THE OPTIMAL HOLE FOR THE BEST HÖLDER EXTENSION

SAMER DWEIK

ABSTRACT. In this paper, we study the problem of finding the optimal hole among all subsets $A \subset \Omega$ that minimizes the α -Hölder seminorm $[u]_{\alpha}$ among all functions u such that u = 1 on $\partial\Omega$ and u = 0 on A, plus a penalization on the volume of A. For a given set $A \subset \Omega$, we will also characterize the function that minimizes $[u]_{\alpha}$. In addition, we will study the limit when $p \rightarrow \infty$ of the "fractional" version of the Alt-Caffarelli problem.

1. INTRODUCTION

Let Ω be an open bounded domain in \mathbb{R}^N . In [2, 7, 6], the authors considered the problem of minimizing

(1.1)
$$\min\left\{\int_{\Omega} |\nabla u|^p + \lambda |\{u > 0\}| : u \in W^{1,p}(\Omega), \ u \ge 0, \ u = 1 \text{ on } \partial\Omega\right\}$$

where $1 and <math>\lambda > 0$. Problems of this kind (known as Bernoulli-type problems) have several applications in heat flows [1, 3] and electrochemical machining [10].

In [9], the authors studied the limit when $p \to \infty$ of the minimizer u_p to the following problem:

(1.2)
$$\min\left\{\frac{1}{p}\int_{\Omega}\left[\frac{|\nabla u|}{\Lambda}\right]^{p} + \lambda|\{u>0\}| : u \in W^{1,p}(\Omega), \ u=1 \text{ on } \partial\Omega\right\}.$$

More precisely, they show that up to a subsequence, u_p converges uniformly to a function u_{∞} that solves

(1.3)
$$\min\left\{|\{u>0\}| : u \in \operatorname{Lip}(\bar{\Omega}), |\nabla u| \le \Lambda, u = 1 \text{ on } \partial\Omega\right\}.$$

In [5], the authors considered the following free boundary problem (which is the supremal version of the Alt-Caffarelli minimization problem (1.1):

(1.4)
$$\min\{||\nabla u||_{\infty} + \lambda |\{u > 0\}| : u \in \operatorname{Lip}(\bar{\Omega}), \ u \ge 0, \ u = 1 \text{ on } \partial\Omega\}.$$

It is clear that

$$\min(1.4) = \min_{\Lambda>0} [\Lambda + \min(1.3)].$$

Notice that the minimizer u in Problem (1.4) will be constant (i.e. u = 1 on Ω) as soon as the parameter λ is sufficiently small. Otherwise, they show that there is a constant r > 0 such that $u_r := [1 - \frac{d(x,\partial\Omega)}{r}]_+$ is a minimizer (see [5, Theorem 1]).

In this paper, we will consider the fractional version of Problem (1.2), where the L^p norm of ∇u is replaced by the $W^{s,p}$ -seminorm $[u]_{s,p}$ of u:

(1.5)
$$\min\left\{\frac{1}{p\Lambda^{p}}\int_{\Omega\times\Omega}\frac{|u(x)-u(y)|^{p}}{|x-y|^{\alpha p}}+\lambda|\{u>0\}|\,:\,u\in W^{s,p}(\Omega),\,\,u=1\,\text{ on }\,\partial\Omega\right\},$$

where $s = \alpha - \frac{N}{p}$ and

$$W^{s,p}(\Omega) := \left\{ u \in L^{p}(\Omega), \ [u]_{s,p}^{p} := \iint_{\Omega \times \Omega} \frac{|u(x) - u(y)|^{p}}{|x - y|^{N + sp}} < \infty \right\}.$$

In Section 2, we will study the limit of Problem (1.5) as $p \to \infty$. We show that up to a subsequence, the minimizers u_p converge to u_{∞} which turns out to be a solution to the following minimization problem (which is the α -Hölder version of (1.3)):

$$\min\left\{|\{u>0\}| : u \in C^{0,\alpha}(\Omega), \ [u]_{\alpha} \le \Lambda, \ u=1 \text{ on } \partial\Omega\right\}$$

where

$$[u]_{\alpha} := \sup_{x, y \in \Omega, y \neq x} \frac{|u(y) - u(x)|}{|y - x|^{\alpha}}$$

Moreover, we will see that u_{∞} is a viscosity solution to the fractional infinity Laplacian $-L_{\infty}u_{\infty} = 0$ in the positivity set $\{u_{\infty} > 0\}$, where

$$L_{\infty}u := L_{\infty}^{+}u + L_{\infty}^{-}u$$

and

$$L_{\infty}^{+}u(x) := \sup_{y \in \Omega} \frac{u(y) - u(x)}{|y - x|^{\alpha}}, \qquad L_{\infty}^{-}u(x) := \inf_{y \in \Omega} \frac{u(y) - u(x)}{|y - x|^{\alpha}}.$$

We note that the fractional infinity Laplacian has been studied in [4] where the authors prove existence of a solution to $L_{\infty}u = 0$ using an approximation with the fractional *p*-Laplacian when $p \to \infty$.

In Section 3, we consider the problem of finding the best α -Hölder extension (with $0 < \alpha < 1$) of the constant boundary condition (u = 1 on $\partial \Omega$) in the presence of a hole $A \subset \subset \Omega$, i.e. we minimize the α -Hölder seminorm among all functions u that vanish on A while u = 1 on the boundary $\partial \Omega$:

(1.6)
$$\Lambda(A) := \min\{[u]_{\alpha} : u \in C^{0,\alpha}(\overline{\Omega}), u \ge 0, u = 1 \text{ on } \partial\Omega, u = 0 \text{ on } A\}$$

where

$$[u]_{\alpha} = \sup_{x, y \in \bar{\Omega}, x \neq y} \frac{|u(x) - u(y)|}{|x - y|^{\alpha}}$$

The aim of this section is to give an explicit representation of the solution to Problem (1.6). More precisely, we show that the function

$$u(x) = \frac{d(x, A)^{\alpha}}{d(x, A)^{\alpha} + d(x, \partial \Omega)^{\alpha}}$$

minimizes (1.6). Moreover, we will show that this minimizer u solves the fractional infinity Laplacian

(1.7)
$$L_{\infty}u = 0 \quad \text{in } \Omega \backslash A.$$

In Section 4, we consider the α -Hölder version of Problem (1.4). To be more precise, we study the problem of finding the optimal hole A that minimizes the functional $\Lambda(A)$ among all subsets $A \subset \Omega$, i.e. we consider the following shape optimization problem:

(1.8)
$$\min\{\Lambda(A) - \lambda | A| : A \subset \subset \Omega\}.$$

If $\lambda \leq 0$, it is clear that the optimal set A in Problem (1.8) is empty. However, if $\lambda > 0$ the situation becomes much complicated since on one side we need to take A small as much as

possible so that $\Lambda(A)$ will be small too but on the other side |A| is increasing in A. Yet, we will show that there exists a constant $\lambda^* > 0$ such that for all $\lambda \leq \lambda^*$ the optimal set A is empty, while if $\lambda \geq \lambda^*$ the optimal set $A = \{x \in \Omega : d(x, \partial\Omega) \geq r_\lambda\}$, where the constant $r_\lambda > 0$ is such that

$$r_{\lambda}^{\alpha+1} \mathcal{H}^{N-1}(\partial A_{r_{\lambda}}) = \frac{\alpha}{\lambda}.$$

Moreover, λ^{\star} satisfies

$$r^{\alpha}_{\lambda^{\star}} \left| A_{r_{\lambda^{\star}}} \right| = \frac{1}{\lambda^{\star}}.$$

2. The limit of the fractional p-Laplacian free boundary problem

Let Ω be a bounded Lipschitz set in \mathbb{R}^N and λ , $\Lambda > 0$ are fixed. Then, we consider their minimization problem:

(2.1)
$$\min\left\{\frac{1}{p\Lambda^p}\int_{\Omega\times\Omega}\frac{|u(x)-u(y)|^p}{|x-y|^{\alpha p}} + \lambda|\{u>0\}| : u \in W^{s,p}(\Omega), \ u=1 \text{ on } \partial\Omega\right\}.$$

Proposition 2.1. Problem (2.1) has a minimizer u_p . Moreover, we have $L_p u_p = 0$ (in the weak sense) inside the positivity set $\{u_p > 0\}$, where

$$L_p u(x) := -\int_{\Omega} \frac{|u(x) - u(y)|^{p-1}}{|x - y|^{\alpha p}} \frac{u(x) - u(y)}{|u(x) - u(y)|} \, \mathrm{d}y$$

Proof. Let $\{u_n\}_n$ be a minimizing sequence in (2.1). So, there is a constant C (independent of n) such that

$$\frac{1}{p\Lambda^p} \int_{\Omega \times \Omega} \frac{|u_n(x) - u_n(y)|^p}{|x - y|^{\alpha p}} + \lambda |\{u_n > 0\}| \le C, \quad \text{for all } n.$$

Hence,

(2.2)
$$\left(\int_{\Omega\times\Omega} \frac{|u_n(x) - u_n(y)|^p}{|x - y|^{\alpha p}}\right)^{\frac{1}{p}} \le [Cp]^{\frac{1}{p}} \Lambda.$$

Yet, $u_n = 1$ on $\partial \Omega$. By [8, Theorem 8.2], we get

$$||u_n||_{\infty} \le C[u_n]_{s,p} + 1.$$

Thanks to (2.2), this implies that $\{u_n\}_n$ is bounded in $W^{s,p}(\Omega)$. Hence, up to a subsequence, u_n converges uniformly to u_p in $\overline{\Omega}$. Thanks to Fatou's Lemma, we see that

$$\frac{1}{p} \int_{\Omega \times \Omega} \left[\frac{\frac{|u_p(x) - u_p(y)|}{|x - y|^{\alpha}}}{\Lambda} \right]^p + \lambda |\{u_p > 0\}| \le \liminf_n \left[\frac{1}{p} \int_{\Omega \times \Omega} \left[\frac{\frac{|u_n(x) - u_n(y)|}{|x - y|^{\alpha}}}{\Lambda} \right]^p + \lambda |\{u_n > 0\}| \right].$$

In particular, we have $u_p = 1$ on $\partial\Omega$. Hence, u_p is a minimizer. Moreover, it is easy to see that $u_p \ge 0$. Assume this is not the case; consider the truncated function $\tilde{u}_p := \max\{u_p, 0\}$. Then, one has $\{u_p > 0\} = \{\tilde{u}_p > 0\}$ and

$$|\tilde{u}_p(x) - \tilde{u}_p(y)| \le |u_p(x) - u_p(y)|, \quad \text{for all } x, y \in \Omega.$$

Fix $\varphi \in C_0^{\infty}(\Omega)$ such that $\operatorname{spt}(\varphi) \subset \{u_p > 0\}$. Then, we clearly have $u + \varepsilon \varphi \in W^{s,p}(\Omega)$,

 $u + \varepsilon \varphi = 1$ on $\partial \Omega$ and $\{u_p + \varepsilon \varphi > 0\} = \{u_p > 0\}$ for ε small enough. From the optimality of u_p , we have

$$\int_{\Omega \times \Omega} \left[\frac{|u_p(x) - u_p(y)|}{|x - y|^{\alpha}} \right]^p \le \int_{\Omega \times \Omega} \left[\frac{|(u_p + \varepsilon \varphi)(x) - (u_p + \varepsilon \varphi)(y)|}{|x - y|^{\alpha}} \right]^p.$$

Therefore, we get

$$\int_{\Omega \times \Omega} \frac{|u_p(x) - u_p(y)|^{p-1}}{|x - y|^{\alpha p}} \frac{u_p(x) - u_p(y)}{|u_p(x) - u_p(y)|} \left[\varphi(x) - \varphi(y)\right] = 0.$$

Then, we have

 $L_p u_p = 0$ in $\{u_p > 0\}$ (in the weak sense).

Proposition 2.2. Up to a subsequence, $u_p \to u_\infty$ uniformly in Ω . Moreover, u_∞ minimizes the following problem:

$$\min\left\{|\{u>0\}| : u \in C^{0,\alpha}(\Omega), \ [u]_{\alpha} \le \Lambda, \ u=1 \ on \ \partial\Omega\right\}.$$

Proof. From the optimality of u_p in Problem (2.1), we have

$$\frac{1}{p} \int_{\Omega \times \Omega} \left[\frac{\frac{|u_p(x) - u_p(y)|}{|x - y|^{\alpha}}}{\Lambda} \right]^p + \lambda |\{u_p > 0\}| \le \lambda |\Omega|, \quad \text{for all } p$$

Hence,

$$\left[\int_{\Omega\times\Omega} \frac{|u_p(x) - u_p(y)|^p}{|x - y|^{\alpha p}}\right]^{\frac{1}{p}} \le [p\lambda|\Omega|]^{\frac{1}{p}}\Lambda, \quad \text{for all } p.$$

Fix m < p, one has

$$\left[\iint_{\Omega\times\Omega}\frac{|u_p(x)-u_p(y)|^m}{|x-y|^{\alpha m}}\right]^{\frac{1}{m}} \le \left[\iint_{\Omega\times\Omega}\frac{|u_p(x)-u_p(y)|^p}{|x-y|^{\alpha p}}\right]^{\frac{1}{p}}|\Omega|^{2(1-\frac{m}{p})} \le C.$$

Consequently, $(u_p)_p$ is bounded in $W^{s,m}(\Omega)$ (with $s = \alpha - \frac{N}{m}$). If $m > \frac{2N}{\alpha}$, then one has the following estimate

$$||u_p||_{C^{0,\gamma}(\overline{\Omega})} \le C[u_p]_{W^{s,m}(\Omega)},$$

with $\gamma = s - \frac{N}{m} > 0$. Therefore, up to a subsequence, u_p converges uniformly to u_{∞} in $\overline{\Omega}$. Moreover, we have $u_{\infty} \in C^{0,\alpha}(\Omega)$ and

$$[u_{\infty}]_{\alpha} \leq \Lambda$$

Fix $u \in C^{0,\alpha}(\Omega)$ such that $[u]_{\alpha} \leq \Lambda$ and u = 1 on $\partial \Omega$. Thanks again to the optimality of u_p , we have

$$\lambda|\{u_p>0\}| \leq \frac{1}{p} \int_{\Omega\times\Omega} \left[\frac{\frac{|u_p(x)-u_p(y)|}{|x-y|^{\alpha}}}{\Lambda}\right]^p + \lambda|\{u_p>0\}| \leq \frac{|\Omega|^2}{p} + \lambda|\{u>0\}|.$$

Passing to the limit when $p \to \infty$, we get

$$\lambda |\{u_{\infty} > 0\}| \le \lambda \liminf_{p} |\{u_{p} > 0\}| \le \liminf_{p} \frac{|\Omega|^{2}}{p} + \lambda |\{u > 0\}| = \lambda |\{u > 0\}|.$$

In order to show that u_{∞} is a viscosity solution to the fractional infinity Laplacian in the positivity set, we need to introduce first the definition of a viscosity supersolution (resp. subsolution).

Definition 2.1. We say that u is a viscosity supersolution of $-L_p u = 0$ in E if the following holds: for every $x_0 \in E$ and $\phi \in C^1(\Omega) \cap C(\overline{\Omega})$ such that

$$\phi(x_0) = u(x_0)$$
 and $\phi(x) \le u(x)$ for all $x \in \Omega$,

then we have

$$-L_p\phi(x_0) \ge 0.$$

The requirement for a viscosity subsolution is symmetric: the test function is touching from above and the inequality is reversed. Finally, a viscosity solution is defined as being both a viscosity supersolution and a viscosity subsolution.

Proposition 2.3. For all p > 1, u_p is a viscosity solution to $-L_p u_p = 0$ in $\{u_p > 0\}$.

Proof. In order to prove that u_p is a viscosity solution, we will use some technical points from the proof of [4, Proposition 6.4], where more details can be found there. First, we show that u_p is a viscosity subsolution. Assume that there is a function $\varphi \in C^1(\Omega) \cap C(\overline{\Omega})$ touching u_p from above at some point $x_0 \in \{u_p > 0\}$ such that

$$-L_p\varphi(x_0) > 0.$$

First, we claim that one can assume that $u_p < \phi$ in $\Omega \setminus \{x_0\}$. Fix $\delta > 0$ small enough and set $\varphi_{\delta}(x) := \varphi(x) + \delta |x - x_0|^2$, for every $x \in \Omega$. We have

$$|\varphi_{\delta}(x) - \varphi_{\delta}(y)|^{p-2}[\varphi_{\delta}(x) - \varphi_{\delta}(y)] = |\varphi(x) - \varphi(y) + \delta[|x - x_{0}|^{2} - |y - x_{0}|^{2}]|^{p-2}[\varphi(x) - \varphi(y) + \delta[|x - x_{0}|^{2} - |y - x_{0}|^{2}]].$$

Yet,

$$\begin{aligned} \left| |\varphi_{\delta}(x) - \varphi_{\delta}(y)|^{p-2} [\varphi_{\delta}(x) - \varphi_{\delta}(y)] - |\varphi(x) - \varphi(y)|^{p-2} [\varphi(x) - \varphi(y)] \right| \\ &= \left| (p-1) \left(\int_{0}^{1} |\varphi(x) - \varphi(y) + \delta t[|x - x_{0}|^{2} - |y - x_{0}|^{2}]|^{p-2} dt \right) \delta[|x - x_{0}|^{2} - |y - x_{0}|^{2}] \right| \\ &\leq C \delta |x - y|^{p-1}. \end{aligned}$$

Then, we get

$$|L_p\varphi_{\delta}(x) - L_p\varphi(x)| \le C\delta.$$

Therefore, $-L_p \varphi_{\delta}(x_0) > 0$ provided that $\delta > 0$ is small enough. For $\varepsilon > 0$ small enough, we define

$$\varphi_{\varepsilon} := \min\{u_p, \varphi - \varepsilon\} \quad \text{and} \quad \varphi^{\varepsilon} := \max\{u_p, \varphi - \varepsilon\}.$$

Since $0 \leq u_p < \phi$ in $\Omega \setminus \{x_0\}$, $\varphi(x_0) = u_p(x_0) > 0$ and $\varphi \in C(\overline{\Omega})$, then we have $\varphi_{\varepsilon} = u_p$ on $\partial\Omega$ and $\varphi - \varepsilon > 0$ on Ω , for all $\varepsilon > 0$ small enough. Yet, u_p is a minimizer and so, one has

$$(2.3) \qquad \frac{1}{p} \int_{\Omega \times \Omega} \left[\frac{\frac{|u_p(x) - u_p(y)|}{|x - y|^{\alpha}}}{\Lambda} \right]^p + \lambda |\{u_p > 0\}| \le \frac{1}{p} \int_{\Omega \times \Omega} \left[\frac{\frac{|\varphi_{\varepsilon}(x) - \varphi_{\varepsilon}(y)|}{|x - y|^{\alpha}}}{\Lambda} \right]^p + \lambda |\{\varphi_{\varepsilon} > 0\}|.$$

For $p \ge 1$, we have the following convexity inequality (see [11]):

$$|\min\{a,c\} - \min\{b,d\}|^p + |\max\{a,c\} - \max\{b,d\}|^p \le |a-b|^p + |c-d|^p.$$

S. DWEIK

So, we have

$$\int_{\Omega \times \Omega} \frac{|\varphi_{\varepsilon}(x) - \varphi_{\varepsilon}(y)|^p}{|x - y|^{\alpha p}} + \int_{\Omega \times \Omega} \frac{|\varphi^{\varepsilon}(x) - \varphi^{\varepsilon}(y)|^p}{|x - y|^{\alpha p}} \le \int_{\Omega \times \Omega} \frac{|u_p(x) - u_p(y)|^p}{|x - y|^{\alpha p}} + \int_{\Omega \times \Omega} \frac{|\varphi(x) - \varphi(y)|^p}{|x - y|^{\alpha p}}$$

But, it is clear that

$$|\{\varphi_{\varepsilon} > 0\}| = |\{u_p > 0\}|.$$

Recalling (2.3), this yields that

$$\int_{\Omega \times \Omega} \frac{|\varphi^{\varepsilon}(x) - \varphi^{\varepsilon}(y)|^p}{|x - y|^{\alpha p}} \le \int_{\Omega \times \Omega} \frac{|\varphi(x) - \varphi(y)|^p}{|x - y|^{\alpha p}}.$$

Now, set

$$\mathcal{J}(t) := \int_{\Omega \times \Omega} \frac{|(1-t)\varphi(x) + t\varphi^{\varepsilon}(x) - (1-t)\varphi(y) - t\varphi^{\varepsilon}(y)|^p}{|x-y|^{\alpha p}}, \quad \text{for all } t \in [0,1].$$

Yet, we have

$$\mathcal{J}(t) \leq (1-t) \int_{\Omega \times \Omega} \frac{|\varphi(x) - \varphi(y)|^p}{|x - y|^{\alpha p}} + t \int_{\Omega \times \Omega} \frac{|\varphi^{\varepsilon}(x) - \varphi^{\varepsilon}(y)|^p}{|x - y|^{\alpha p}}$$
$$\leq \int_{\Omega \times \Omega} \frac{|\varphi(x) - \varphi(y)|^p}{|x - y|^{\alpha p}} = \mathcal{J}(0).$$

Hence, t = 0 maximizes $\mathcal{J}(t)$. Therefore, $\mathcal{J}'(0) \leq 0$. But, we have

$$\mathcal{J}'(0) = p \int_{\Omega \times \Omega} \frac{|\varphi(x) - \varphi(y)|^{p-1}}{|x - y|^{\alpha p}} \frac{\varphi(x) - \varphi(y)}{|\varphi(x) - \varphi(y)|} [\varphi^{\varepsilon}(x) - \varphi(x) + \varepsilon - (\varphi^{\varepsilon}(y) - \varphi(y) + \varepsilon)] \le 0.$$

So, we get

$$\int_{\Omega} [-L_p \varphi(x)] [\varphi^{\varepsilon}(x) - \varphi(x) + \varepsilon] \le 0,$$

which yields to a contradiction as soon as $\varepsilon > 0$ is small enough. In the same way we prove that u_p is a viscosity supersolution.

Proposition 2.4. The limit function u_{∞} is a viscosity solution to $-L_{\infty}u_{\infty} = 0$ in the positivity set $\{u_{\infty} > 0\}$.

Proof. Fix $x_0 \in \{u_\infty > 0\}$. Let $\phi \in C^1(\Omega) \cap C(\overline{\Omega})$ be such that $u_\infty \ge \phi$ on $\overline{\Omega}$ and $u_\infty(x_0) =$ $\phi(x_0)$. Recall that one can assume that x_0 is the unique minimizer of $u_{\infty} - \phi$. Set $m_p =$ $\min[u_p - \phi]$. So, one has $x_p \to x_0$ with $u_p(x_p) = \phi(x_p) + m_p$. Since u_p is a viscosity solution in $\{u_p > 0\}$, then we have

$$-L_p\phi(x_p) \ge 0.$$

Hence,

$$\int_{\Omega} \frac{[\phi(y) - \phi(x_p)]_{-}^{p-1}}{|x - y|^{\alpha p}} \, \mathrm{d}y \ge \int_{\Omega} \frac{[\phi(y) - \phi(x_p)]_{+}^{p-1}}{|x - y|^{\alpha p}} \, \mathrm{d}y.$$

Letting $p \to \infty$ and thanks to [4, Lemma 6.5], we get the following inequality:

$$-L_{\infty}^{-}\phi(x_0) \ge L_{\infty}^{+}\phi(x_0).$$

Now, let us show that u_{∞} is a viscosity subsolution (so, it is a viscosity solution). Fix $x_0 \in \{u_{\infty} > 0\}$. Let $\phi \in C^1(\Omega) \cap C(\overline{\Omega})$ be such that $u_{\infty} \leq \phi$ on $\overline{\Omega}$ and $u_{\infty}(x_0) = \phi(x_0)$. Assume again that x_0 is the unique minimizer of $u_{\infty} - \phi$. Set $M_p = \max[u_p - \phi]$ and $x_p \in \Omega$ is such that $u_p(x_p) = \phi(x_p) + M_p$. We note again that $x_p \to x_0$. Since u_p is a viscosity solution in $\{u_p > 0\}$, then one has

$$-L_p\phi(x_p) \le 0$$

Hence,

$$-\int_{\Omega} \frac{[\phi(y) - \phi(x_p)]_+^{p-1}}{|x - y|^{\alpha p}} \,\mathrm{d}y + \int_{\Omega} \frac{[\phi(y) - \phi(x_p)]_-^{p-1}}{|x - y|^{\alpha p}} \,\mathrm{d}y \le 0.$$

Then, we get that

$$-L_{\infty}^{+}\phi(x_{0}) - L_{\infty}^{-}\phi(x_{0}) \le 0.$$

3. Characterization of the best Hölder extension

Let Ω be a bounded domain in \mathbb{R}^N . For a subset $A \subset \subset \Omega$, we consider the following minimization problem:

(3.1)
$$\Lambda(A) := \min\{[u]_{\alpha} : u \in C^{0,\alpha}(\overline{\Omega}), u \ge 0, u = 1 \text{ on } \partial\Omega, u = 0 \text{ on } A\}.$$

Proposition 3.1. The following function $u(x) = \frac{d(x,A)^{\alpha}}{d(x,A)^{\alpha} + d(x,\partial\Omega)^{\alpha}}$ minimizes Problem (3.1).

Proof. Clearly, this function u satisfies the boundary conditions u = 0 on A and u = 1 on $\partial \Omega$. Moreover, we have the following:

$$\sup_{y \in \partial \Omega \cup A} \frac{u(y) - u(x)}{|y - x|^{\alpha}} = \sup_{y \in \partial \Omega} \frac{1 - u(x)}{|y - x|^{\alpha}} = \sup_{y \in \partial \Omega} \frac{1 - \frac{d(x, A)^{\alpha}}{d(x, A)^{\alpha} + d(x, \partial \Omega)^{\alpha}}}{|y - x|^{\alpha}}$$
$$= \frac{d(x, \partial \Omega)^{\alpha}}{d(x, A)^{\alpha} + d(x, \partial \Omega)^{\alpha}} \sup_{y \in \partial \Omega} \frac{1}{|y - x|^{\alpha}} = \frac{1}{d(x, A)^{\alpha} + d(x, \partial \Omega)^{\alpha}}$$

and

$$\inf_{y \in \partial \Omega \cup A} \frac{u(y) - u(x)}{|y - x|^{\alpha}} = \inf_{y \in A} \frac{-u(x)}{|y - x|^{\alpha}} = -\sup_{y \in A} \frac{\frac{d(x, A)^{\alpha}}{d(x, A)^{\alpha} + d(x, \partial \Omega)^{\alpha}}}{|y - x|^{\alpha}}$$
$$= -\frac{d(x, A)^{\alpha}}{d(x, A)^{\alpha} + d(x, \partial \Omega)^{\alpha}} \sup_{y \in A} \frac{1}{|y - x|^{\alpha}} = -\frac{1}{d(x, A)^{\alpha} + d(x, \partial \Omega)^{\alpha}}$$

Hence,

$$\sup_{y \in \partial \Omega \cup A} \frac{u(y) - u(x)}{|y - x|^{\alpha}} + \inf_{y \in \partial \Omega \cup A} \frac{u(y) - u(x)}{|y - x|^{\alpha}} = 0.$$

For every $x \in \Omega$, we claim that

$$\sup_{y\in\bar{\Omega},\,y\neq x}\frac{u(y)-u(x)}{|y-x|^{\alpha}}=\sup_{y\in\partial\Omega}\frac{u(y)-u(x)}{|y-x|^{\alpha}}$$

and

$$\inf_{y \in \bar{\Omega}, \, y \neq x} \frac{u(y) - u(x)}{|y - x|^{\alpha}} = \inf_{y \in A} \frac{u(y) - u(x)}{|y - x|^{\alpha}}.$$

Fix $x_1, x_2 \in \Omega$. Assume that $S_{x_1}^+ := \sup_{y \in \partial \Omega} \frac{u(y) - u(x_1)}{|y - x_1|^{\alpha}} \ge \sup_{y \in \partial \Omega} \frac{u(y) - u(x_2)}{|y - x_2|^{\alpha}} := S_{x_2}^+$. Let $y_1^+ \in \partial \Omega$ be such that

$$S_{x_1}^+ = \frac{1 - u(x_1)}{|y_1^+ - x_1|^{\alpha}}.$$

Yet, we have

$$S_{x_2}^+ \ge \frac{1 - u(x_2)}{|y_1^+ - x_2|^{\alpha}}$$

Hence,

$$u(x_1) - u(x_2) \le S_{x_2}^+ |y_1^+ - x_2|^\alpha - S_{x_1}^+ |y_1^+ - x_1|^\alpha \le S_{x_2}^+ |x_2 - x_1|^\alpha.$$

Consequently,

$$\frac{u(x_1) - u(x_2)}{|x_1 - x_2|^{\alpha}} \le S_{x_2}^+ \quad \text{if} \quad S_{x_1}^+ \ge S_{x_2}^+.$$

On the other side, we denote by $S_x^- := \inf_{y \in A} \frac{u(y) - u(x)}{|y - x|^{\alpha}}$. Since $S_{x_1}^+ \ge S_{x_2}^+$ and $S_{x_1}^+ + S_{x_1}^- = S_{x_2}^+ + S_{x_2}^- = 0$ then we have $S_{x_1}^- \le S_{x_2}^- \le 0$. Let $y_1^- \in A$ be such that

$$S_{x_1}^- = -\frac{u(x_1)}{|y_1^- - x_1|^{\alpha}}.$$

One has

$$S_{x_2}^- \le -\frac{u(x_2)}{|y_1^- - x_1|^{\alpha}}.$$

Then, we get

 $u(x_1) - u(x_2) \ge -S_{x_1}^- |y_1^- - x_1|^{\alpha} + S_{x_2}^- |y_1^- - x_2|^{\alpha} \ge S_{x_2}^- [|y_1^- - x_2|^{\alpha} - |y_1^- - x_1|^{\alpha}] \ge S_{x_2}^- |x_2 - x_1|^{\alpha}.$ Therefore,

$$u(x_2) - u(x_1) \le -S_{x_2}^- |x_2 - x_1|^{\alpha} = S_{x_2}^+ |x_2 - x_1|^{\alpha}.$$

Interchanging x_1 and x_2 , we get

$$\frac{u(x_1) - u(x_2)}{|x_1 - x_2|^{\alpha}} \le S_{x_1}^+ \quad \text{if} \quad S_{x_1}^+ \le S_{x_2}^+.$$

Hence,

$$\sup_{x_1 \in \bar{\Omega}, \, x_1 \neq x_2} \frac{u(x_1) - u(x_2)}{|x_1 - x_2|^{\alpha}} \le \sup_{y \in \partial \Omega} \frac{u(y) - u(x_2)}{|y - x_2|^{\alpha}}$$

In the same way, we show that

$$\inf_{y \in \bar{\Omega}, \, y \neq x} \frac{u(y) - u(x)}{|y - x|^{\alpha}} = \inf_{y \in A} \frac{u(y) - u(x)}{|y - x|^{\alpha}}.$$

Thus, we infer that

(3.2)
$$\sup_{y\in\bar{\Omega},\,y\neq x}\frac{u(y)-u(x)}{|y-x|^{\alpha}} + \inf_{y\in\bar{\Omega},\,y\neq x}\frac{u(y)-u(x)}{|y-x|^{\alpha}} = 0.$$

Finally, assume that there is a function $v \in C^{0,\alpha}(\Omega)$ such that v = 0 on A and v = 1 on $\partial \Omega$ with

$$[v]_{\alpha} < [u]_{\alpha}.$$

This implies that there is a point $x_0 \in \Omega$ such that

$$[v]_{\alpha} < \sup_{y \in \bar{\Omega}, \ y \neq x_0} \frac{u(y) - u(x_0)}{|y - x_0|^{\alpha}} = \sup_{y \in \partial\Omega} \frac{u(y) - u(x_0)}{|y - x_0|^{\alpha}} = \sup_{y \in \partial\Omega} \frac{v(y) - u(x_0)}{|y - x_0|^{\alpha}}.$$

If $u(x_0) \ge v(x_0)$, we get that

$$[v]_{\alpha} < \sup_{y \in \partial \Omega} \frac{v(y) - u(x_0)}{|y - x_0|^{\alpha}} \le \sup_{y \in \partial \Omega} \frac{v(y) - v(x_0)}{|y - x_0|^{\alpha}}$$

which is a contradiction. Finally, assume that $u(x_0) < v(x_0)$. Then, thanks to (3.2), we have

$$\begin{split} [v]_{\alpha} < \sup_{y \in \bar{\Omega}, \, y \neq x_0} \frac{u(y) - u(x_0)}{|y - x_0|^{\alpha}} = -\inf_{y \in \bar{\Omega}, \, y \neq x_0} \frac{u(y) - u(x_0)}{|y - x_0|^{\alpha}} = -\inf_{y \in A} \frac{u(y) - u(x_0)}{|y - x_0|^{\alpha}} \\ = -\inf_{y \in A} \frac{v(y) - u(x_0)}{|y - x_0|^{\alpha}} \le -\inf_{y \in A} \frac{v(y) - v(x_0)}{|y - x_0|^{\alpha}}. \end{split}$$

But, this is again a contradiction. \Box

4. Optimal hole

Fix $\lambda > 0$. Then, we consider the problem of minimizing the optimal α -Hölder semi-norm $\Lambda(A)$, among all nonnegative functions u in $C^{0,\alpha}(\overline{\Omega})$ with a prescribed Dirichlet boundary condition u = 1 on $\partial\Omega$ and u = 0 on A, plus a penalization on the volume of the set A. More precisely, we study the following shape optimization problem:

(4.1)
$$\min\{\Lambda(A) - \lambda | A| : A \subset \subset \Omega\},$$

where

$$\Lambda(A) := \min\{[u]_{\alpha} : u \in C^{0,\alpha}(\overline{\Omega}), u \ge 0, u = 1 \text{ on } \partial\Omega, u = 0 \text{ on } A\}.$$

First, we start by proving the existence of a solution to Problem (4.1).

Proposition 4.1. There exists an optimal set A^* that minimizes Problem (4.1).

Proof. Let $\{A_n\}_n$ be a minimizing sequence in Problem (4.1). For every $n \in \mathbb{N}$, we may assume that A_n is closed since it is clear that $\Lambda(\overline{A_n}) = \Lambda(A_n)$ while $|A_n| \leq |\overline{A_n}|$. For all $n \in \mathbb{N}$, let u_n be a minimizer of Problem (3.1), i.e. $\Lambda(A_n) = [u_n]_{\alpha}$. Then, there is a constant $C < \infty$ such that for all $n \in \mathbb{N}$,

$$\Lambda(A_n) - \lambda |A_n| = [u_n]_\alpha - \lambda |A_n| \le C.$$

In particular, $[u_n]_{\alpha} \leq C + \lambda |\Omega|$. Yet, $u_n = 1$ on $\partial \Omega$. Hence, $\{u_n\}_n$ is uniformly bounded since $|u_n(x)| \leq 1 + C \operatorname{diam}(\Omega)^{\alpha}$, for all $x \in \overline{\Omega}$.

So, up to subsequences, $u_n \to u$ uniformly in $\overline{\Omega}$ and A_n converges to A in the Hausdorff distance. Clearly, u = 1 on $\partial\Omega$ and u = 0 on A. But, one has

(4.2)
$$|u_n(x) - u_n(y)| \le [u_n]_\alpha |x - y|^\alpha, \quad \text{for all } x, y \in \Omega.$$

Passing to the limit in (4.2) when $n \to \infty$, this yields that

$$|u(x) - u(y)| \le \liminf_n [u_n]_\alpha \, |x - y|^\alpha, \qquad \text{for all } x, \, y \in \overline{\Omega}$$

Thus,

(4.3)
$$\Lambda(A) \le [u]_{\alpha} \le \liminf_{n} [u_{n}]_{\alpha} = \liminf_{n} \Lambda(A_{n})$$

On the other hand, if $x \in A_n$ for all n large enough then we also have $x \in A$ and so, we get that

(4.4)
$$\limsup_{n} |A_n| \le |A|.$$

Combining (4.3) & (4.4), we get

(4.5)
$$\Lambda(A) - \lambda |A| \le \liminf_{n} [\Lambda(A_n) - \lambda |A_n|].$$

This implies that A is an optimal set. \Box

In the next proposition, we show that we can always find an explicit optimal set to Problem (4.1). Let R_{Ω} be the inradius of Ω (the radius of the largest ball that can be contained in Ω), i.e.

$$R_{\Omega} = \max_{x \in \Omega} d(x, \partial \Omega).$$

Proposition 4.2. For every $\lambda > 0$, at least one of the following two statements holds: $A = \emptyset$ is an optimal set or there exists $r \in (0, R_{\Omega}]$ such that $A_r := \{x : d(x, \partial\Omega) \ge r\}$ is an optimal set. Moreover, the function

$$u_r(x) = \left[1 - \frac{d(x, \partial \Omega)^{\alpha}}{r^{\alpha}}\right]_+$$

minimizes $\Lambda(A_r)$. More precisely, if there is an optimal set A such that $\Lambda(A) < \frac{1}{R_{\Omega}^{\alpha}}$ then $A = \emptyset$, while if $\Lambda(A) \geq \frac{1}{R_{\Omega}^{\alpha}}$ then for $r := \frac{1}{\Lambda(A)^{1/\alpha}} \in (0, R_{\Omega}]$, A_r is an optimal set.

Proof. Let $A \subset \Omega$ and u be a minimizer in Problem (3.1). Let us denote by P(x) any projection point of x onto the boundary. Since u = 1 on $\partial\Omega$, then we have that

$$|u(x) - 1| = |u(x) - u(P(x))| \le [u]_{\alpha} |x - P(x)|^{\alpha} = [u]_{\alpha} d(x, \partial \Omega)^{\alpha}.$$

For every $x \in A$, one has u(x) = 0. Then, we must have

$$d(x,\partial\Omega) \ge \frac{1}{[u]_{\alpha}^{1/\alpha}}$$

This implies that

(4.6)
$$\left\{x : d(x, \partial \Omega) < \frac{1}{[u]_{\alpha}^{1/\alpha}}\right\} \subset \{u > 0\}.$$

If $R_{\Omega} < \frac{1}{\Lambda(A)^{1/\alpha}} = \frac{1}{[u]_{\alpha}^{1/\alpha}}$ then $\{u > 0\} = \Omega$, since for every $x \in \Omega$ one has

$$d(x,\partial\Omega) \le R_{\Omega} < \frac{1}{[u]_{\alpha}^{1/\alpha}}$$

and then, $A = \emptyset$ (so, u = 1).

Finally, assume that $R_{\Omega} \geq \frac{1}{\Lambda(A)^{1/\alpha}} = \frac{1}{[u]_{\alpha}^{1/\alpha}}$. So, there is a $r \in (0, R_{\Omega}]$ such that $[u]_{\alpha} = \frac{1}{r^{\alpha}}$. Now, consider the function u_r . It is clear that $u_r \in C^{0,\alpha}(\bar{\Omega})$ with $[u_r]_{\alpha} = \frac{1}{r^{\alpha}}$. From the definition of A_r , we also have $u_r = 1$ on $\partial\Omega$ and $u_r = 0$ on A_r . Hence, $\Lambda(A) = [u]_{\alpha} = [u_r]_{\alpha}$. Recalling (4.6), one has

(4.7)
$$\Omega \setminus A_r = \left\{ x : d(x, \partial \Omega) < r \right\} \subset \{ u > 0 \}.$$

Yet, u = 0 on A. Hence, $A \subset A_r$. Thus, we have the following:

$$|A| \le |A_r|.$$

From the optimality of A, we infer that

 $\Lambda(A) - \lambda |A| \le \Lambda(A_r) - \lambda |A_r| \le [u_r]_{\alpha} - \lambda |A_r| \le [u_r]_{\alpha} - \lambda |A| = \Lambda(A) - \lambda |A|.$

This yields that A_r is an optimal set in Problem (4.1), u_r is also a minimizer in $\Lambda(A_r)$ and, $A = A_r$ almost everywhere. \Box

Proposition 4.3. Assume Ω is convex. Then, there exists $\lambda^* > 0$ such that for all $\lambda < \lambda^*$, $A = \emptyset$ is the unique optimal set. For $\lambda = \lambda^*$, there exists a unique $r_{\lambda^*} \in (0, R_{\Omega})$ such that $A_{r_{\lambda^*}}$ is an optimal set (while $A = \emptyset$ is always optimal). And for $\lambda > \lambda^*$, there is a $r_{\lambda} \in (0, R_{\Omega})$ such that $A_{r_{\lambda}}$ is optimal. Moreover, we have the following characterization:

$$r_{\lambda}^{\alpha+1} \mathcal{H}^{N-1}(\partial A_{r_{\lambda}}) = \frac{\alpha}{\lambda}, \quad \text{for all } \lambda \ge \lambda^{\star}$$

and

$$r^{\alpha}_{\lambda^{\star}} \left| A_{r_{\lambda^{\star}}} \right| = \frac{1}{\lambda^{\star}}.$$

Proof. First, we define

$$f_{\lambda}(r) := \Lambda(A_r) - \lambda |A_r|.$$

Thanks to Proposition 4.2, we have

$$f_{\Lambda}(r) = [u_r]_{\alpha} + \lambda |\Omega \setminus A_r| - \lambda |\Omega|, \quad \text{for all } r \in (0, R_{\Omega}].$$

Hence, one has

$$f_{\Lambda}(r) = \frac{1}{r^{\alpha}} + \lambda |\{x : d(x, \partial \Omega) < r\}| - \lambda |\Omega|.$$

Using the coarea formula, we have

$$f_{\lambda}(r) = \frac{1}{r^{\alpha}} + \lambda \int_{o}^{r} \mathcal{H}^{N-1}(\{x : d(x, \partial \Omega) = t\}) \,\mathrm{d}t - \lambda |\Omega|.$$

Then,

$$f_{\lambda}'(r) = -\frac{\alpha}{r^{\alpha+1}} + \lambda \mathcal{H}^{N-1}(\{x : d(x, \partial \Omega) = r\}).$$

So,

$$f_{\lambda}'(r) \leq 0 \Longleftrightarrow \frac{\alpha}{r^{\alpha+1}} \geq \lambda \,\mathcal{H}^{N-1}(\partial A_r) \Longleftrightarrow \frac{\alpha^{\frac{1}{N-1}}}{r^{\frac{\alpha+1}{N-1}}} \geq \lambda^{\frac{1}{N-1}} \,\mathcal{H}^{N-1}(\partial A_r)^{\frac{1}{N-1}}.$$

For simplicity of notation, we set

$$\Psi(r) = \mathcal{H}^{N-1}(\partial A_r)^{\frac{1}{N-1}} \quad \text{and} \quad G(r) = \frac{\alpha^{\frac{N-1}{N-1}}}{r^{\frac{\alpha+1}{N-1}}}$$

1

Since Ω is convex, thanks to the Brunn-Minkowski inequality, Ψ is decreasing and concave. However, G is decreasing and strictly convex. Moreover, one has $\lim_{r\to 0^+} G(r) = +\infty$. First, assume that $\Psi(R_{\Omega}) = 0$ (we note that this is not the case in general; consider the case when Ω is a stadium or simply a rectangle). Then, thanks to these properties on G and Ψ , it is clear that there is a constant λ_i such that the following statements hold:

•
$$G(r) > \lambda^{\frac{1}{N-1}} \Psi(r)$$
 on $[0, R_{\Omega}]$, for all $\lambda < \lambda_i$.

S. DWEIK

- There exists $r_i \in (0, R_{\Omega}]$ such that $G(r_i) = \lambda_i^{\frac{1}{N-1}} \Psi(r_i)$ and $G(r) > \lambda_i^{\frac{1}{N-1}} \Psi(r)$ for all $r \neq r_i$.
 - There exist $r_{\lambda}, R_{\lambda} \in (0, R_{\Omega}]$ such that $G(r_{\lambda}) = \lambda^{\frac{1}{N-1}} \Psi(r_{\lambda}), G(R_{\lambda}) = \lambda^{\frac{1}{N-1}} \Psi(R_{\lambda})$ and,

$$G(r) < \lambda^{\frac{1}{N-1}} \Psi(r) \Longleftrightarrow r_{\lambda} < r < R_{\lambda}$$

For all $\lambda < \lambda_i$, we have $f'_{\lambda}(r) < 0$ for every $0 < r \leq R_{\Omega}$. Hence, we get the following:

$$\min_{r \in (0,R_{\Omega}]} f_{\lambda}(r) = f_{\lambda}(R_{\Omega}) = \frac{1}{R_{\Omega}^{\alpha}} > 0.$$

Then,

$$\Lambda(A_r) - \lambda |A_r| > 0, \quad \text{for all } r \in (0, R_{\Omega}].$$

Recalling Proposition 4.2, this implies that for any optimal set A, we must have $\Lambda(A) < \frac{1}{R_{\Omega}^{\alpha}}$ and so, $A = \emptyset$. If $\lambda = \lambda_i$, $f'_{\lambda}(r) \leq 0$ and so, we get again that

$$\min_{r \in (0,R_{\Omega}]} f_{\lambda}(r) = f_{\lambda}(R_{\Omega}) = \frac{1}{R_{\Omega}^{\alpha}} > 0$$

and so, $A = \emptyset$ is the unique minimizer.

Now, assume $\lambda > \lambda_i$. Then, one has

$$\min_{r \in (0,R_{\Omega}]} f_{\lambda}(r) = \min\{f_{\lambda}(r_{\Lambda}), f_{\lambda}(R_{\Omega})\} = \min\left\{f_{\lambda}(r_{\lambda}), \frac{1}{R_{\Omega}^{\alpha}}\right\}.$$

Yet, $\min_{r \in (0,R_{\Omega}]} f_0(r) = \frac{1}{R_{\Omega}^{\alpha}} > 0$ while $\min_{r \in (0,R_{\Omega}]} f_{\lambda}(r) < 0$ for $\lambda > \lambda_i$ sufficiently large. Moreover, it is easy to see that $\lambda \mapsto \min_{r \in (0,R_{\Omega}]} f_{\lambda}(r)$ is continuous and decreasing. Hence, there is a unique $\lambda^* > \lambda_i$ such that $\min_{r \in (0,R_{\Omega}]} f_{\lambda^*}(r) = 0$. Thus, $f_{\lambda^*}(r_{\lambda^*}) = 0$ for some $r_{\lambda^*} \in (0,R_{\Omega}]$ and so, we get that

$$\Lambda(A_{r_{\lambda^{\star}}}) - \lambda^{\star} |A_{r_{\lambda^{\star}}}| = 0 < \Lambda(A_r) - \lambda^{\star} |A_r|, \qquad r \neq r_{\lambda^{\star}}.$$

This implies that $A_{r_{\lambda^{\star}}}$ is an optimal set (while $A = \emptyset$ is always optimal). If $\lambda > \lambda^{\star}$, then there exists r_{λ} such that $f_{\lambda}(r_{\lambda}) = \min_{r \in (0,R_{\Omega}]} f_{\lambda}(r_{\lambda}) < 0$. Hence, $A_{r_{\Lambda}}$ is a minimizer.

Finally, we note that if $\lambda_i < \lambda < \lambda^*$ then we have

$$\min_{r\in(0,R_{\Omega}]}f_{\lambda}(r)=\min\left\{f_{\lambda}(r_{\lambda}),\frac{1}{R_{\Omega}^{\alpha}}\right\}>0.$$

Hence,

$$\Lambda(A_r) - \lambda |A_r| > 0, \quad \text{for all } r \in (0, R_\Omega].$$

So, $A = \emptyset$ is again the unique minimizer.

In the same way, we treat the case when $\Psi(R_{\Omega}) > 0$; the only difference now is that for λ large there exists a unique $r_{\lambda} \in (0, R_{\Omega}]$ such that $G(r_{\lambda}) = \lambda^{\frac{1}{N-1}} \Psi(r_{\lambda})$ and $G(r) < \lambda^{\frac{1}{N-1}} \Psi(r)$ when $r > r_{\lambda}$. This yields that $\min_{r \in (0, R_{\Omega}]} f_{\lambda}(r) = f_{\lambda}(r_{\lambda}) < 0$ and so, $A_{r_{\lambda}}$ is an optimal set. \Box

References

- [1] ACKER A., Heat flow inequalities with applications to heat flow optimization problems, SIAM J. Math. Anal. 4, 604-618 (1977).
- [2] H. W. ALT AND L. A. CAFFARELLI, Existence and regularity for a minimum problem with free boundary, J. Reine Angew. Math. 325 (1981), 105-144.
- BEURLING A., On free-boundary problems for the Laplace equation, Seminars on analytic functions, vol. I, pp. 248-263.
- [4] CHAMBOLLE A., LINDGREN E., MONNEAU R., A Hölder infinity Laplacian, ESAIM: Control, Optimisation and Calculus of Variations 18.3 (2012): 799-835.
- [5] G. CRASTA AND I. FRAGALÀ, On the supremal version of the Alt-Caffarelli minimization problem, Advances in Calculus of Variations, vol. 14, no. 3, 2021, pp. 327-341.
- [6] D. DANERS AND B. KAWOHL, An isoperimetric inequality related to a Bernoulli problem, Calc. Var. Partial Differential Equations 39 (2010), no. 3-4, 547-555.
- [7] D. DANIELLI AND A. PETROSYAN, A minimum problem with free boundary for a degenerate quasilinear operator, *Calc. Var. Partial Differential Equations* 23 (2005), no. 1, 97-124.
- [8] DI NEZZA E., PALATUCCI G., VALDINOCI E.: Hitchhikers guide to the fractional Sobolev spaces, Bull. Sci. Math. 136(5), 521-573 (2012).
- B. KAWOHL AND H. SHAHGHOLIAN, Gamma limits in some Bernoulli free boundary problem, Arch. Math. (Basel) 84 (2005), no. 1, 79-87.
- [10] LACEY, A. A., SHILLOR M., Electrochemical and electro-discharge machining with a threshold current. IMA J. Appl. Math. 39(2), 121-142 (1987).
- [11] K. MUROTA, Discrete convex analysis. SIAM Monographs on Discrete Mathematics and Applications, Society for Industrial and Applied Mathematics (SIAM), Philadelphia, PA (2003).

DEPARTMENT OF MATHEMATICS AND STATISTICS, COLLEGE OF ARTS AND SCIENCES, QATAR UNIVERSITY, 2713, DOHA, QATAR.

Email address: sdweik@qu.edu.qa