

# THE MICHOR–MUMFORD CONJECTURE IN HILBERTIAN H-TYPE GROUPS

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ABSTRACT. We introduce infinite dimensional Hilbertian H-type groups equipped with weak, graded, left invariant Riemannian metrics. For these Lie groups, we show that the vanishing of the geodesic distance and the local unboundedness of the sectional curvature coexist. The result validates a deep phenomenon conjectured in an influential 2005 paper by Michor and Mumford, namely, the vanishing of the geodesic distance is linked to the local unboundedness of the sectional curvature. We prove that degenerate geodesic distances appear for a large class of weak, left invariant Riemannian metrics. Their vanishing is rather surprisingly related to the infinite dimensional sub-Riemannian structure of Hilbertian H-type groups. The same class of weak Riemannian metrics yields the nonexistence of the Levi-Civita covariant derivative.

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## 1. INTRODUCTION

The study of infinite dimensional manifolds is a vast and fascinating area of Mathematics which, for instance, embraces Differential Geometry, Lie group theory, and PDEs. A recent introduction to these topics can be found in the monograph [30] and the lecture notes [8, 23]. Some foundational works are [12, 19], and more specific information on infinite dimensional Lie groups can be found for instance in [29, 17] and in the surveys [27, 28, 11].

We begin by highlighting Riemannian Hilbert manifolds, that constitute a class of infinite dimensional manifolds modeled on a Hilbert space. Their Riemannian metrics induce the manifold topology on tangent spaces, hence they are called *strong Riemannian metrics* and their geodesic distance is a distance function, that separates points. While the local geometry

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of Riemannian Hilbert manifolds shares some analogies with the finite dimensional case, for instance the Levi-Civita connection always exists, certain global properties fail to hold. For more information, we refer the reader to the interesting survey [7] and the references therein.

Only for infinite dimensional manifolds, the so-called *weak Riemannian metrics* may induce on tangent spaces weaker topologies than the manifold topology, [1, 8, 23, 30]. If the manifold is not modeled on a Hilbert space, then the Riemannian metric must be weak. We focus our attention on Lie groups modeled on a Hilbert space, where both weak and strong Riemannian metrics can be defined. Therefore, we use the terminology “*strictly weak Riemannian metric*” to emphasize the cases where the weak Riemannian metric is not strong.

For strictly weak Riemannian metrics, a striking phenomenon can occur, resulting in the vanishing of the geodesic distance between distinct points. We say that such geodesic distance is *degenerate*. First examples of such surprising fact were discovered in different classes of Fréchet manifolds [10], [25], [26]. Simple examples of degenerate geodesic distances are also available in Hilbert manifolds, [21, 22], see also [5, 6] for more information.

In the 2005 paper [25], P. Michor and D. Mumford conjectured a relationship between the vanishing of the geodesic distance and the local unboundedness of the sectional curvature. They proposed a fascinating interpretation behind this phenomenon: some parts of the infinite dimensional manifold “wrap up on themselves” allowing to find curves connecting two distinct points and having shorter and shorter length, up to reaching vanishing infimum, see [25] and [5, Section 1.2]. In Mathematical terms, we may rephrase this phenomenon as follows: whenever a weak Riemannian metric admits a degenerate geodesic distance, then the sectional curvature must be unbounded on some special sequences of planes that stay in a neighborhood of some point. For infinite dimensional Lie groups, the homogeneity by translations allows this point to be the unit element.

We point out that when a specific choice of strictly weak Riemannian metric on the infinite dimensional Heisenberg group is considered, then the following phenomenon appears: the blow-up of the sectional curvature occurs along some planes that are related to the shrinking curves which connect the distinct points, where the geodesic distance vanishes, [22]. If we take into account the above comments and the subsequent Theorem 1.1, then we may interpret the Michor–Mumford conjecture in infinite dimensional Lie groups as follows. Considering an infinite dimensional Lie group, equipped with a weak, left invariant Riemannian metric and a degenerate geodesic distance, *then we expect that the sectional curvature at the unit element is positively unbounded.*

In the present paper, we introduce *Hilbertian H-type groups*, whose geometry validates the previous version of the conjecture, with respect to a large class of strictly weak, left invariant Riemannian metrics. Hilbertian H-type groups include the infinite dimensional Heisenberg group of [22] and in the finite dimensional case they exactly coincide with the well known H-type groups, that were discovered by A. Kaplan, [14, 15, 16], see also [13]. We notice that Kaplan’s definition perfectly works also through the infinite dimensional interpretation. On the other hand, the effective existence of infinite dimensional H-type groups needs to be verified. In Section 2, we provide an infinite dimensional construction, from which one may notice that there are infinitely many infinite dimensional Hilbertian H-type Lie groups, see Remark 2.3.

We focus our attention on the “natural” *weak Riemannian metrics* on Hilbertian H-type groups, that are left invariant and make the subspaces  $\mathbb{V}$  and  $\mathbb{W}$  orthogonal. Borrowing the terminology from the finite dimensional case, we say that such metrics are *graded*. For instance, the Cameron-Martin subgroup of [9] is a two step, infinite dimensional Lie group equipped

with a strong and graded Riemannian metric. Thus, the next statement validates our interpretation of the Michor–Mumford conjecture in Hilbertian H-type groups.

**Theorem 1.1.** *Let  $\sigma$  be a weak, graded Riemannian metric on a Hilbertian H-type group. If the metric  $\sigma$  yields a degenerate geodesic distance, then the sectional curvature at the unit element exists on a sequence of planes and it is positively unbounded.*

The starting point of the proof is that the degenerate geodesic distance forces the graded Riemannian metric to be strictly weak. Then we prove that for strictly weak, graded Riemannian metrics the blow-up of the sectional curvature always occurs. Extending Theorem 1.1 to more general classes of infinite dimensional Lie groups seems an interesting open question.

It is also important to understand whether, and in which cases, the geodesic distance in a Hilbertian H-type group is actually degenerate. Here a rather striking fact appears, since infinite dimensional sub-Riemannian (sub-Finsler) Geometry enters the proof of Theorem 1.1. More generally, for *any* strictly weak, left invariant sub-Finsler metric on a Hilbertian H-type group, the sub-Finsler distance is *degenerate*, see Theorem 4.1. The idea behind the proof of this theorem is to use a sequence of vectors, where the weak and the strong topology differ. Then we use the map  $J$  associated with the structure of H-type group, which allows for the same “shrinking-space effect” that was first observed in [22]. As a consequence, we have the following result, corresponding to Theorem 4.4.

**Theorem 1.2** (Characterization of points with vanishing distance). *Let  $F$  be a strictly weak, left invariant Finsler metric on a Hilbertian H-type group  $\mathbb{M} = \mathbb{W} \oplus \mathbb{W}$  and let us fix  $x, y \in \mathbb{W}$ ,  $z_1, z_2 \in \mathbb{W}$ . Then we have*

$$d_F(x + z_1, y + z_2) = 0 \quad \text{if and only if} \quad x = y,$$

where  $d_F$  is the Finsler distance associated with  $F$ .

The subclass of strictly weak, graded Riemannian metrics on a Hilbertian H-type group gives rise to another singular phenomenon, i.e. the lack of the Levi-Civita covariant derivative.

**Theorem 1.3.** *If  $\sigma$  is a strictly weak, graded Riemannian metric on a Hilbertian H-type group, then it does not admit the Levi-Civita covariant derivative.*

The proof of the previous theorem is given in Section 5. An example of nonexistence of the Levi-Civita connection was provided in [3]. We also notice that in [23, Example 2.26] the model of [21] is extended to a family of weak Riemannian metrics which do not possess Christoffel symbols, hence their associated Levi-Civita covariant derivative cannot exist.

Despite Theorem 1.3, we observe that through the classical Arnold’s formula [2] it is still possible to compute the sectional curvature of some planes in a Hilbertian H-type group. However, we cannot claim that the formula works for all planes. In fact, there are also planes for which the Arnold’s formula does not apply, as it is shown for instance in [21, Remark 4.1].

The next theorem proves that in a Hilbertian H-type group equipped with a strictly weak, graded Riemannian metric, we can always find sequences of planes in  $T_0\mathbb{M}$  where the sectional curvature is well defined, and also unbounded.

**Theorem 1.4** (Unboundedness of the sectional curvature). *Let  $\mathbb{M}$  be a Hilbertian H-type group. If  $\sigma$  is a strictly weak, graded Riemannian metric on  $\mathbb{M}$ , then there exist two sequences of planes  $\{P_n\}_{n \in \mathbb{N}}, \{Q_n\}_{n \in \mathbb{N}} \subset T_0\mathbb{M}$  whose sectional curvatures  $K_\sigma(P_n)$  and  $K_\sigma(Q_n)$  are well defined through the Arnold’s formula and we have*

$$\lim_{n \rightarrow \infty} K_\sigma(P_n) = -\infty \quad \text{and} \quad \lim_{n \rightarrow \infty} K_\sigma(Q_n) = +\infty.$$

This theorem is a version of Theorem 6.6, where we provide an explicit form for the planes:

$$P_n = \text{span}\{w_n, J_z w_n\} \quad \text{and} \quad Q_n = \text{span}\{z, J_{A_z} w_n\}.$$

We believe that there is a connection between these planes and the sequence of curves that progressively decrease their length, while connecting the fixed distinct points. In fact, we point out that the projection on  $\mathbb{W}$  of these *horizontal curves* has the form

$$\gamma_1^n(t) = tc \sqrt{n} w_n + \frac{t^2 c}{2} \frac{1}{\sqrt{n}} J_z(w_n)$$

for  $c \in \mathbb{R}$ , see the proof of Theorem 6.6. In this sense, we surmise that the planes  $P_n$  and  $Q_n$  should be somehow related to the parts of the space where the curves  $\gamma^n$  "move", when their length reduces up to converging to zero. However, the precise relationship between the planes of the blow-up and the shrinking curves remains unclear to us.

We observe that Theorem 1.4 immediately gives Theorem 1.1, since the vanishing of the geodesic distance implies that the graded Riemannian metric is strictly weak. We hopefully expect that our remarks in Hilbertian H-type groups provide more insights to understand the Michor–Mumford phenomenon in other classes of infinite dimensional manifolds.

## 2. INFINITE DIMENSIONAL H-TYPE GROUPS

The approach of [20] can be used to construct specific classes of infinite dimensional Banach nilpotent Lie groups, starting from an infinite dimensional nilpotent Lie algebra. Indeed, the group operation is immediately provided by the Baker–Campbell–Hausdorff formula, which we abbreviate as “BCH formula”. We will see that this simple viewpoint allows us to get the notion of a possibly infinite dimensional H-type group.

We fix some notions that we will use throughout the paper. Let  $\mathbb{M}$  be a Hilbert space, consider a continuous Lie product  $[\cdot, \cdot] : \mathbb{M} \times \mathbb{M} \rightarrow \mathbb{M}$  and two orthogonal and nontrivial closed subspaces  $\mathbb{V}$  and  $\mathbb{W}$  such that  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$ , with  $\dim(\mathbb{W}) < +\infty$ . We denote the scalar product on  $\mathbb{M}$  by  $\langle \cdot, \cdot \rangle$  and the associated norm by  $|\cdot|$ . The space of all linear continuous endomorphisms of a Banach space  $X$  is denoted by  $\text{End}(X)$ .

We say that  $\mathbb{M}$  is a *Hilbertian H-type group*, or simply an *H-type group*, if the following conditions hold.

(I)  $[\mathbb{M}, \mathbb{M}] \subset \mathbb{W}$  and  $[\mathbb{M}, \mathbb{W}] = \{0\}$ ,

(II) the unique linear and continuous operator  $J : \mathbb{W} \rightarrow \text{End}(\mathbb{W})$  defined by the formula

$$(1) \quad \langle J_z x, y \rangle = \langle z, [x, y] \rangle$$

for  $z \in \mathbb{W}$ ,  $x, y \in \mathbb{W}$ , satisfies the additional condition

$$(2) \quad J_z^2 = -|z|^2 \text{Id}_{\mathbb{W}},$$

where  $\text{Id}_{\mathbb{W}} : \mathbb{W} \rightarrow \mathbb{W}$  is the identity mapping.

Notice that the existence of the linear and continuous operator  $J$  is a consequence of both the Riesz representation theorem applied on  $\mathbb{W}$  and the continuity of the bilinear mapping  $[\cdot, \cdot]$ . Thus, (1) immediately follows.

The group operation is automatically obtained by the BCH formula:

$$(3) \quad x \cdot y = x + y + \frac{1}{2}[x, y].$$

From the defining formula (1), we immediately notice that the adjoint operator  $J_z^*$  satisfies

$$(4) \quad J_z^* = -J_z.$$

As a consequence, using also (2), we may write

$$|J_z x|^2 = -\langle x, J_z^2 x \rangle = |z|^2 |x|^2,$$

that gives

$$(5) \quad |J_z x| = |z| |x|.$$

Therefore, using also the defining formula (1), we have

$$(6) \quad |z|^2 |x|^2 = |J_z x|^2 = \langle z, [x, J_z x] \rangle.$$

For every  $w \in \mathbb{W}$ , we also notice that (5) implies

$$|\langle w, [x, y] \rangle| = |\langle J_w x, y \rangle| \leq |w| |x| |y|,$$

therefore in any H-type group we have

$$(7) \quad |[x, y]| \leq |x| |y|.$$

For  $x, z \neq 0$ , it follows that

$$(8) \quad \left| \frac{[x, J_z x]}{|x|^2 |z|} \right| \leq 1$$

and in addition (6) gives

$$(9) \quad \left\langle \frac{z}{|z|}, \frac{[x, J_z x]}{|x|^2 |z|} \right\rangle = 1.$$

Combining (7) and (9), we have proved that

$$(10) \quad [x, J_z x] = |x|^2 z.$$

Notice that  $[\mathbb{M}, \mathbb{W}] = \{0\}$  implies that  $\mathbb{W}$  is contained in the center of  $\mathbb{M}$ , where we regard  $\mathbb{M}$  as a Lie algebra. However, it is easy to notice that condition (10) shows that  $\mathbb{W}$  exactly coincides with the center of  $\mathbb{M}$ .

**Remark 2.1.** Notice that in the case  $\dim(\mathbb{W}) < +\infty$ , the Hilbertian H-type group coincides with the well known (finite dimensional) H-type group, [14], hence motivating our terminology.

Next, we construct examples of (infinite dimensional) Hilbertian H-type groups. We fix an H-type group  $\mathfrak{n} = \nu \oplus \zeta$ , where  $\nu$  and  $\zeta$  are finite dimensional orthogonal subspaces of the Hilbert space  $\mathfrak{n}$ . We denote by  $\langle \cdot, \cdot \rangle_{\mathfrak{n}}$  the scalar product of  $\mathfrak{n}$  and by  $|\cdot|_{\mathfrak{n}}$  its associated norm.

The endomorphism  $J^{\mathfrak{n}} : \zeta \rightarrow \text{End}(\nu)$  defines the H-type structure on  $\mathfrak{n}$ . We denote by  $\mathbb{N}^+$  the set of positive integers and consider the space of square-summable sequences

$$(11) \quad \mathbb{P}_{\nu} = \left\{ (x_k)_k : x_k \in \nu, k \in \mathbb{N}^+, \sum_{k=1}^{\infty} |x_k|_{\mathfrak{n}}^2 < +\infty \right\}.$$

We set  $\mathbb{M} = \mathbb{P}_{\nu} \times \zeta$  and identifying  $\mathbb{P}_{\nu}$  and  $\zeta$  with  $\mathbb{P}_{\nu} \times \{0\}$  and  $\{0\} \times \zeta$ , respectively, we can also write

$$\mathbb{M} = \mathbb{P}_{\nu} \oplus \zeta.$$

For  $(x, z), (x', z') \in \mathbb{M}$ , we define the scalar product

$$(12) \quad \langle (x, z), (x', z') \rangle = \langle ((x_k)_k, z), ((x'_k)_k, z') \rangle = \langle z, z' \rangle_{\mathfrak{n}} + \sum_{k=1}^{\infty} \langle x_k, x'_k \rangle_{\mathfrak{n}}$$

that makes  $\mathbb{M}$  a Hilbert space, where  $\mathbb{P}_\nu$  and  $\zeta$  are orthogonal closed subspaces. We denote by  $|\cdot|$  the associated norm on  $\mathbb{M}$ . For  $x = (x_k)_k \in \mathbb{P}_\nu$  and  $z \in \zeta$ , we define

$$(13) \quad J_z(x) = (J_z^n x_k)_k.$$

Thus, observing that

$$(14) \quad \sum_{k=1}^{\infty} |J_z^n x_k|_{\mathfrak{n}}^2 = |z|_{\mathfrak{n}}^2 \sum_{k=1}^{\infty} |x_k|_{\mathfrak{n}}^2 < +\infty,$$

the mapping  $J_z : \mathbb{P}_\nu \rightarrow \mathbb{P}_\nu$  is well defined and

$$(15) \quad J_z^2 = -|z|_{\mathfrak{n}}^2 \text{Id}_{\mathbb{P}_\nu},$$

since  $(J_z^n)^2 = -|z|_{\mathfrak{n}}^2 \text{Id}_\nu$ . The Lie product of  $\xi + \eta, \xi' + \eta' \in \mathfrak{n} = \nu \oplus \zeta$  is given by a skew-symmetric continuous bilinear mapping

$$\beta : \nu \times \nu \rightarrow \zeta$$

such that

$$[\xi + \eta, \xi' + \eta'] = \beta(\xi, \xi').$$

By the property (7) for H-type groups, we get

$$(16) \quad |\beta(\xi, \xi')| = |[\xi, \xi']| \leq |\xi|_{\mathfrak{n}} |\xi'|_{\mathfrak{n}}$$

for all  $\xi, \xi' \in \nu$ , therefore the Lie product

$$(17) \quad [(x, z), (x', z')] = \left( 0, \sum_{k=1}^{+\infty} \beta(x_k, x'_k) \right),$$

is well defined for all  $(x, z), (x', z') \in \mathbb{M}$ . Cauchy–Schwarz inequality yields

$$(18) \quad |[(x, z), (x', z')]| \leq \sum_{k=1}^{+\infty} |\beta(x_k, x'_k)| \leq \sum_{k=1}^{\infty} |x_k|_{\mathfrak{n}} |x'_k|_{\mathfrak{n}} \leq |x| |x'|,$$

hence the Lie product  $[\cdot, \cdot]$  is continuous on  $\mathbb{M}$ . Finally, from definition (13) of  $J_z : \mathbb{P}_\nu \rightarrow \mathbb{P}_\nu$ , we obtain

$$\langle J_z x, y \rangle = \sum_{k=1}^{\infty} \langle J_z^n x_k, y_k \rangle_{\mathfrak{n}} = \sum_{k=1}^{\infty} \langle z, [x_k, y_k] \rangle_{\mathfrak{n}} = \sum_{k=1}^{\infty} \langle z, \beta(x_k, y_k) \rangle_{\mathfrak{n}} = \langle z, [x, y] \rangle$$

for all  $x, y \in \mathbb{P}_\nu$  and  $z \in \zeta$ . We have proved the following result.

**Theorem 2.2.** *The linear space  $\mathbb{M} = \mathbb{P}_\nu \oplus \zeta$  equipped with scalar product (12), Lie product (17) and linear operator (13) is an infinite dimensional H-type group.*

**Remark 2.3.** By [14, Corollary 1], there exist infinitely many finite dimensional H-type groups, where there are no isomorphic couples. Indeed, these groups can be chosen to have centers of different dimensions. As a result, Theorem 2.2 also shows that there are infinitely many infinite dimensional H-type groups.

**Remark 2.4.** We point out that, when the finite dimensional H-type group  $\mathfrak{n}$  coincides with the 3-dimensional Heisenberg group, in the construction of  $\mathbb{M}$ , then Theorem 2.2 yields the infinite dimensional Heisenberg group studied in [22].

## 3. WEAK METRICS ON HILBERTIAN H-TYPE GROUPS

In the sequel,  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$  always denotes a Hilbertian H-type group, equipped with a scalar product  $\langle \cdot, \cdot \rangle$  and its Hilbertian norm  $|\cdot|$ . This section presents various notions of weak metrics on  $\mathbb{M}$ . They include weak Finsler metrics and weak Riemannian metrics. Indeed, both of these metrics may induce a topology which is strictly weaker than the manifold topology. We will also follow the convention of identifying the tangent space  $T_q\mathbb{M}$  with the group itself  $\mathbb{M}$ ,  $q \in \mathbb{M}$ , due to the linear structure of  $\mathbb{M}$ .

For every  $p \in \mathbb{M}$ , the *left multiplication by  $p$*  is denoted by  $L_p : \mathbb{M} \rightarrow \mathbb{M}$ , with

$$L_p(q) = p \cdot q = p + q + \frac{1}{2}[p, q]$$

for all  $q \in \mathbb{M}$ . We define the skew-symmetric bilinear function  $\beta : \mathbb{V} \times \mathbb{V} \rightarrow \mathbb{W}$  such that

$$[x, y] = \beta(x, y)$$

for every  $x, y \in \mathbb{V}$ . By definition of  $\mathbb{M}$ , we have two canonical projections  $\pi_1 : \mathbb{M} \rightarrow \mathbb{V}$  and  $\pi_2 : \mathbb{M} \rightarrow \mathbb{W}$  such that every  $p \in \mathbb{M}$  can be written in a unique way as

$$p = \pi_1(p) + \pi_2(p)$$

where  $\pi_1(p)$  and  $\pi_2(p)$  are also orthogonal. We obviously have the isometric isomorphism

$$\mathbb{M} \rightarrow \mathbb{V} \times \mathbb{W}, \quad p \rightarrow (\pi_1(p), \pi_2(p))$$

with respect to the Hilbert structure of  $\mathbb{M}$ . We use the simplified notation  $p_i = \pi_i(p)$  for  $p \in \mathbb{M}$ , so that we can write  $p = p_1 + p_2$  with  $p_1 \in \mathbb{V}$  and  $p_2 \in \mathbb{W}$ . Then the group operation (3) gives a simple formula for the differential of  $L_p$  at a point  $q \in \mathbb{M}$  along  $v = v_1 + v_2 \in \mathbb{M}$ :

$$(19) \quad (dL_p)_q(v) = \left. \frac{d}{dt} L_p(q + tv) \right|_{t=0} = v + \frac{1}{2}[p, v] = v_1 + v_2 + \frac{\beta(p_1, v_1)}{2}.$$

Indeed, the linear structure of  $\mathbb{M}$  allows us to identify  $T_q\mathbb{M}$  with  $\mathbb{M}$ .

**3.0.1. Weak Finsler metrics and Finsler distances.** We fix a norm  $F_0 : \mathbb{M} \rightarrow [0, +\infty)$  with respect to the linear structure of  $\mathbb{M}$ , which also yields a Finsler metric on  $T\mathbb{M}$ . We always assume that  $F_0$  is continuous, namely  $F_0(v) \leq c_1|v|$  for some  $c_1 > 0$  and for all  $v \in \mathbb{M}$ , where  $|\cdot|$  is the fixed scalar product on  $\mathbb{M}$ . It is also natural to assume that the decomposition  $\mathbb{V} \oplus \mathbb{W}$  is compatible with the Finsler norm, namely  $\pi_1 : \mathbb{M} \rightarrow \mathbb{V}$  and  $\pi_2 : \mathbb{M} \rightarrow \mathbb{W}$  are continuous with respect to  $F_0$ . In other words, there exists  $C > 0$  such that

$$F_0(\pi_1(x)) \leq CF_0(x) \quad \text{and} \quad F_0(\pi_2(x)) \leq CF_0(x).$$

Thus, for each  $p \in \mathbb{M}$ , we set

$$F_p(v) = F_0((dL_{-p})_p(v))$$

for every  $v \in T_p\mathbb{M}$ . We say that the map  $F$  on  $T\mathbb{M}$  arising from the norms  $F_p$  is a *weak, left invariant Finsler metric* on  $T\mathbb{M}$ . We say that  $F$  is a *strong, left invariant Finsler metric* if the topology induced by  $F_0$  on  $\mathbb{M}$  coincides with the already given Hilbert topology of  $\mathbb{M}$ . In different terms, there exist  $\tilde{c}_1 > 0$  such that  $F_0(v) \geq \tilde{c}_1|v|$  for all  $v \in \mathbb{M}$ . If a weak, left invariant Finsler metric  $F$  on  $\mathbb{M}$  is not strong, then we say that  $F$  is a *strictly weak, left invariant Finsler metric* on  $\mathbb{M}$ .

**Example 3.1.** Let us consider the infinite dimensional Heisenberg group  $\mathbb{H} = \ell^2 \times \ell^2 \times \mathbb{R}$  equipped with the product of the associated Hilbert structure and the group operation as defined

in [22]. We have  $\mathbb{H} = \mathbb{W} \oplus \mathbb{W}$ , where  $\mathbb{W} = \ell^2 \times \ell^2 \times \{0\}$  and  $\mathbb{W} = \{0\} \times \{0\} \times \mathbb{R}$ . We fix  $p > 2$  and for an element  $(h, k, t) \in \mathbb{M}$ , we define the norm

$$F_0(h, k, t) = \|h\|_p + \|k\|_p + |t|,$$

where  $\|x\|_p = (\sum_{k=1}^{\infty} |x_k|^p)^{1/p} \leq \|x\|_2 < +\infty$  for every  $x \in \ell^2$ . Clearly  $F_0$  gives an example of strictly weak, left invariant Finsler metric. Indeed, it is also obvious that the projections  $\pi_1$  and  $\pi_2$  on  $\mathbb{W}$  and  $\mathbb{W}$  are  $F_0$ -continuous, respectively.

The length of a continuous, piecewise smooth curve  $\gamma : [0, 1] \rightarrow \mathbb{M}$  is defined by the integral

$$(20) \quad \ell_F(\gamma) = \int_0^1 F_{\gamma(t)}(\dot{\gamma}(t)) dt = \int_0^1 F_0((dL_{-\gamma(t)})_{\gamma(t)} \dot{\gamma}(t)) dt.$$

Then we can immediately define the associated *Finsler distance*

$$(21) \quad d_F(p, q) = \inf\{\ell_F(\gamma) : \gamma \text{ is continuous, piecewise smooth, } \gamma(0) = p \text{ and } \gamma(1) = q\}$$

for every  $p, q \in \mathbb{M}$ , hence  $d_F : \mathbb{M} \times \mathbb{M} \rightarrow [0, +\infty)$ . Clearly  $d_F$  is left invariant, symmetric and satisfies the triangle inequality.

**Remark 3.2.** Let us consider a weak, left invariant Finsler metric  $F$  on  $\mathbb{M}$ , and let  $d_F$  be the associated geodesic distance. We will prove that for  $p, q \in \mathbb{M}$  with  $\pi_1(p) = x \neq y = \pi_1(q)$ , we have  $C d_F(p, q) \geq F_0(x - y) > 0$ . Indeed, for every continuous, piecewise smooth curve  $\gamma : [0, 1] \rightarrow \mathbb{M}$  joining  $p$  to  $q$ , we get

$$\ell_F(\gamma) = \int_0^1 F_0((dL_{-\gamma(t)})_{\gamma(t)}(\dot{\gamma}(t))) dt \geq \frac{1}{C} \int_0^1 F_0(\dot{\gamma}_1(t)) dt$$

in view of (25) and taking into account the  $F$ -continuity of the projections. Thus, if we consider the projected curve  $\gamma_1 : [0, 1] \rightarrow \mathbb{W}$ , we can piecewise integrate  $\dot{\gamma}_1$  on the intervals where it is continuous. Then we apply [12, Theorem 2.1.1 (ii)] and [12, Theorem 2.2.2] and the triangle inequality on a partition  $t_0 = 0 < t_1 < \dots < t_k = 1$ . It follows that

$$\begin{aligned} \ell_F(\gamma) &\geq \frac{1}{C} \int_0^1 F_0(\dot{\gamma}_1(t)) dt \geq \frac{1}{C} \sum_{j=0}^{k-1} F_0\left(\int_{t_j}^{t_{j+1}} \dot{\gamma}_1(t)\right) = \frac{1}{C} \sum_{j=0}^{k-1} F_0(\gamma_1(t_{j+1}) - \gamma_1(t_j)) \\ &\geq \frac{F_0(x - y)}{C} > 0. \end{aligned}$$

**3.0.2. Weak sub-Finsler metrics.** Identifying  $\mathbb{W} \oplus \mathbb{W}$  with  $T_0(\mathbb{W} \oplus \mathbb{W})$ , the subspace  $\mathbb{W}$  can be seen as a closed subspace of  $T_0\mathbb{M}$ , that we denote by  $H_0\mathbb{M}$  and we may introduce the *left invariant horizontal subbundle*, denoted by  $H\mathbb{M}$ , with fibers

$$H_p\mathbb{M} = (dL_p)_0(H_0\mathbb{M}) \subset T_p\mathbb{M}$$

for every  $p \in \mathbb{M}$ . For each  $p \in \mathbb{M}$ , on the horizontal fiber  $H_p\mathbb{M}$  of  $H\mathbb{M}$  we can fix a norm, which turns out to be continuous and left invariant. Precisely, a *weak, left invariant sub-Finsler metric*  $S$  on  $H\mathbb{M}$  is defined by a norm

$$(22) \quad S_0 : \mathbb{W} \rightarrow [0, +\infty)$$

satisfying for some  $c_0 > 0$  and for all  $x \in \mathbb{W}$  the inequality

$$(23) \quad S_0(x) \leq c_0|x|.$$



The previous condition immediately yields the continuity of  $S_0$  with respect to the fixed Hilbert topology on  $\mathbb{M}$ . Notice that the closed subspace  $\mathbb{W}$  inherits a Hilbert structure from  $\mathbb{M}$ . With the previous identifications, for every  $p \in \mathbb{M}$  and  $v \in H_p\mathbb{M}$ , we introduce the norm

$$(24) \quad S_p(v) = S_0\left((dL_{-p})_p(v)\right)$$

on the fiber  $H_p\mathbb{M}$ . If the topology defined by the norm  $S_0$  on  $\mathbb{W}$  coincides with the Hilbert one of  $\mathbb{W}$ , we say that  $S_0$  defines a *strong, left invariant sub-Finsler metric*. This is equivalent to the existence of a constant  $\tilde{c} > 0$  such that  $\tilde{c}|x| \leq S_0(x)$  for all  $x \in \mathbb{W}$ . If this is not the case, we say that  $S_0$  defines a *strictly weak, left invariant sub-Finsler metric*.

**Example 3.3.** Let us consider the infinite dimensional Heisenberg group  $\mathbb{H} = \ell^2 \times \ell^2 \times \mathbb{R}$  equipped with the product of the associated Hilbert structure and the group operation as defined in [22]. We have  $\mathbb{H} = \mathbb{V} \oplus \mathbb{W}$ , where  $\mathbb{V} = \ell^2 \times \ell^2 \times \{0\}$  and  $\mathbb{W} = \{0\} \times \{0\} \times \mathbb{R}$ . We fix  $p > 2$  and for an element  $(h, k, 0) \in \mathbb{W}$ , we define the norm

$$S_0(h, k) = \|h\|_p + \|k\|_p,$$

where  $\|x\|_p = (\sum_{k=1}^{\infty} |x_j|^p)^{1/p} \leq \|x\|_2 < +\infty$  for every  $x \in \ell^2$ . Clearly  $S_0$  gives an example of strictly weak, left invariant sub-Finsler metric.

**3.0.3. Horizontal curves and sub-Finsler distances.** We notice that the expression of the differential of translations (19) proves that  $v \in H_p\mathbb{M}$  if and only if

$$(25) \quad (dL_{-p})_p(v) = v - \frac{1}{2}[p, v] = v_1 + v_2 - \frac{\beta(p_1, v_1)}{2} \in H_0\mathbb{M}$$

and the previous condition corresponds to the equality

$$(26) \quad v_2 = \frac{\beta(p_1, v_1)}{2}.$$

Thus, we have a precise formula to define the *horizontal curves* associated with  $HH$ . They are continuous and piecewise smooth curves  $\gamma : [0, 1] \rightarrow \mathbb{M}$  of the form  $\gamma = \gamma_1 + \gamma_2 \in \mathbb{M}$ , such that for almost every  $t \in [0, 1]$  we have

$$\dot{\gamma}_2(t) = \frac{\beta(\gamma_1(t), \dot{\gamma}_1(t))}{2}.$$

The previous differential constraint means that  $\dot{\gamma}(t) \in H_{\gamma(t)}\mathbb{M}$ . The length of a horizontal curve  $\gamma : [0, 1] \rightarrow \mathbb{M}$  is defined by  $\ell_S(\gamma) = \int_0^1 S_{\gamma(t)}(\dot{\gamma}(t)) dt$ , therefore

$$\ell_S(\gamma) = \int_0^1 S_0\left((dL_{-\gamma(t)})_{\gamma(t)}\dot{\gamma}(t)\right) dt = \int_0^1 S_0(\dot{\gamma}_1(t)) dt.$$

It is not difficult to observe that all couple of points in  $\mathbb{M}$  can be connected by horizontal curves. As a result, the *sub-Finsler distance*

$$\rho_S(p, q) = \inf\{\ell_S(\gamma) : \gamma \text{ is a horizontal curve with } \gamma(0) = p, \gamma(1) = q\}$$

is finite for every  $p, q \in \mathbb{M}$ , hence  $\rho_F : \mathbb{M} \times \mathbb{M} \rightarrow [0, +\infty)$ . The fact that  $\rho_F$  is left invariant, symmetric and satisfies the triangle inequality is straightforward.

**Remark 3.4.** Let us consider a weak, left invariant sub-Finsler metric  $S$  on  $\mathbb{M}$ , and a weak, left invariant Finsler metric  $F$  on  $\mathbb{M}$  such that  $F_0|_{\mathbb{W}} = S_0$ . We define  $\rho_S$  and  $d_F$  to be the associated sub-Finsler distance and Finsler distance, respectively. Taking into account (20), (25) and (26) we observe that  $\ell_F(\gamma) = \ell_S(\gamma)$  for every horizontal curve. Then we immediately get

$$\rho_S(p, q) \geq d_F(p, q)$$

for every  $p, q \in \mathbb{IM}$ . Taking into account Remark 3.2 we also have  $\rho_S(p, q) \geq d_F(p, q) > 0$  whenever  $\pi_1(p) \neq \pi_1(q)$ . Notice that for any fixed weak sub-Finsler metric  $S_0$  on  $\mathbb{IM}$ , we can always find a weak Finsler metric  $F_0$  such that  $F_0|_{\mathbb{W}} = S_0$ . It suffices to choose any Hilbert norm  $|\cdot|$  on  $\mathbb{W}$ , defining

$$F_0(x + z) = S_0(x) + |z|$$

for every  $x \in \mathbb{W}$  and  $z \in \mathbb{W}$ .

**3.0.4. Weak Riemannian metrics and Riemannian distances.** Following Section 2, we consider a Hilbertian H-type group  $\mathbb{IM} = \mathbb{V} \oplus \mathbb{W}$  equipped with a Hilbert product  $\langle \cdot, \cdot \rangle$  and the mapping  $J_z, z \in \mathbb{W}$ . We fix a continuous scalar product  $\sigma_0$  on  $\mathbb{IM}$ , namely

$$(27) \quad \|v\|_{\sigma_0} \leq c_0|v|$$

for some  $c_0 > 0$  and every  $v \in \mathbb{IM}$ , where  $\|\cdot\|_{\sigma_0}$  is the norm arising from  $\sigma_0$ . We also require that the canonical projections  $\pi_1 : \mathbb{IM} \rightarrow \mathbb{V}$  and  $\pi_2 : \mathbb{IM} \rightarrow \mathbb{W}$  are  $\sigma_0$ -continuous, that is

$$\|\pi_1(v)\|_{\sigma_0} \leq C\|v\|_{\sigma_0} \quad \text{and} \quad \|\pi_2(v)\|_{\sigma_0} \leq C\|v\|_{\sigma_0}$$

for all  $v \in \mathbb{IM}$  and some  $C > 0$ . Thus,  $\sigma_0$  gives a scalar product

$$(28) \quad \sigma_p(v, w) = \sigma_0((dL_{p^{-1}})_p v, (dL_{p^{-1}})_p w) = \sigma_0((dL_{-p})_p v, (dL_{-p})_p w)$$

for each  $p \in \mathbb{IM}$  and  $v, w \in T_p \mathbb{IM}$ . The corresponding Riemannian metric  $\sigma$  on  $T\mathbb{IM}$  is called *weak, left invariant Riemannian metric*. Notice that the Riemannian norm  $\|\cdot\|_{\sigma_0}$  on  $\mathbb{IM}$  is also Finsler metric, see Section 3.0.1.

Let us consider the topology defined by  $\sigma_0$  on  $\mathbb{IM}$ . When it coincides with the topology determined by the Hilbert structure of  $\mathbb{IM}$ , we say that  $\sigma$  is a *strong, left invariant Riemannian metric*. We say that  $\sigma$  is a *strictly weak, left invariant Riemannian metric* if it is not strong. Finally, a (strictly) weak, left invariant Riemannian metric  $\sigma$  on  $\mathbb{IM}$  such that  $\mathbb{V}$  and  $\mathbb{W}$  are  $\sigma_0$ -orthogonal is called *(strictly) weak, graded Riemannian metric*.

For a fixed weak, left invariant Riemannian metric  $\sigma$  on  $\mathbb{IM}$ , we consider the linear and continuous operator  $A : \mathbb{IM} \rightarrow \mathbb{IM}$  such that for all  $v, w \in \mathbb{IM}$  we have  $\sigma_0(v, w) = \langle v, Aw \rangle$ , where  $\langle \cdot, \cdot \rangle$  denotes the Hilbert product on  $\mathbb{IM}$ . The operator  $A$  exists by the classical Riesz representation theorem and it is automatically self-adjoint and positive.

We denote by  $A_{\mathbb{V}}$  its restriction to  $\mathbb{V}$  and by  $A_{\mathbb{W}}$  its restriction to  $\mathbb{W}$ . When  $\sigma_0$  is graded, it is easy to notice that  $A_{\mathbb{V}}(\mathbb{V}) \subset \mathbb{V}$  and  $A_{\mathbb{W}}(\mathbb{W}) \subset \mathbb{W}$ . Then we can consider the linear and continuous operators  $A_{\mathbb{V}} : \mathbb{V} \rightarrow \mathbb{V}$  and  $A_{\mathbb{W}} : \mathbb{W} \rightarrow \mathbb{W}$ .

The following proposition is also standard.

**Proposition 3.5.** *If  $\sigma$  is a weak, left invariant Riemannian metric on  $\mathbb{IM}$ , then the subspace  $A(\mathbb{IM})$  is dense in  $\mathbb{IM}$ . Furthermore,  $\sigma$  is strong if and only if  $A$  is surjective.*

For any continuous and piecewise smooth curve  $\gamma : [0, 1] \rightarrow \mathbb{IM}$  its Riemannian length with respect to the weak Riemannian metric  $\sigma$  is defined as

$$\ell_{\sigma}(\gamma) = \int_0^1 \|\dot{\gamma}(t)\|_{\sigma} dt.$$

The *geodesic distance* associated with  $\sigma$  is the function  $d_{\sigma} : \mathbb{IM} \times \mathbb{IM} \rightarrow [0, +\infty)$  defined as

$$d_{\sigma}(p, q) = \inf\{\ell_{\sigma}(\gamma) : \gamma \text{ is a continuous and piecewise smooth curve with } \gamma(0) = p, \gamma(1) = q\}.$$

Clearly  $d_{\sigma}$  is left invariant, symmetric and it satisfies the triangle inequality.

## 4. DEGENERATE GEODESIC DISTANCES

The next theorem proves the existence of degenerate sub-Finsler distances in any Hilbertian H-type group equipped with a strictly weak, left invariant sub-Finsler metric.

**Theorem 4.1** (Vanishing of sub-Finsler distances). *Let  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$  be an infinite dimensional H-type group equipped with the canonical projections  $\pi_1 : \mathbb{M} \rightarrow \mathbb{V}$  and  $\pi_2 : \mathbb{M} \rightarrow \mathbb{W}$ . Let  $\rho_S$  be the sub-Finsler distance arising from any strictly weak, left invariant sub-Finsler metric  $S$  on  $\mathbb{M}$ . Then for every  $p, q \in \mathbb{M}$  with  $\pi_1(p) = \pi_1(q)$ , we have  $\rho_S(p, q) = 0$ .*

*Proof.* It suffices to prove that for all  $c \in \mathbb{R}$  and all  $z \in \mathbb{W}$  with  $|z| = 1$ , we have

$$(29) \quad \rho_S\left(0, \frac{c^2}{3}z\right) = 0.$$

Since the norm  $S_0$  of (22) does not define the Hilbert topology of  $\mathbb{W}$ , there exists a sequence  $\{w^n\}_n$  in  $\mathbb{W}$  such that  $|w^n| = 1$  and  $S_0(w^n) \leq \frac{1}{n}$  for all  $n \in \mathbb{N}^+$ . We choose  $z \in \mathbb{W}$  with  $|z| = 1$ , and for each  $n \in \mathbb{N}$ , define

$$\gamma_1^n(t) = tc \sqrt{n}w_n + \frac{t^2c}{2} \frac{1}{\sqrt{n}} J_z(w_n).$$

Consider now the curve  $\gamma^n = (\gamma_1^n, \gamma_2^n)$ , where

$$\gamma_2^n(t) = \frac{1}{2} \int_0^t \beta(\gamma_1^n(s), \dot{\gamma}_1^n(s)) ds \in \mathbb{W}.$$

By construction, the curve  $\gamma^n$  is horizontal, therefore  $\ell_S(\gamma^n) = \int_0^1 S_0(\dot{\gamma}_1^n(t)) dt$ . Let us consider the following estimates

$$(30) \quad \begin{aligned} \ell_S(\gamma^n) &= \int_0^1 S_0(\dot{\gamma}_1^n(t)) dt = \int_0^1 S_0\left(c \sqrt{n}w_n + \frac{ct}{\sqrt{n}} J_z(w_n)\right) dt \\ &\leq c \sqrt{n} S_0(w_n) + \frac{c}{\sqrt{n}} S_0(J_z(w_n)) \leq \frac{c}{\sqrt{n}} + \frac{cc_0}{\sqrt{n}} |J_z(w_n)| = \frac{c}{\sqrt{n}} + \frac{cc_0}{\sqrt{n}} \cdot |z|. \end{aligned}$$

It follows that

$$\lim_{n \rightarrow \infty} \ell_S(\gamma^n) = 0.$$

For each  $n$ , the endpoint of  $\gamma^n$  is

$$\gamma^n(1) = c \sqrt{n}w_n + \frac{c}{2} \frac{1}{\sqrt{n}} J_z(w_n) + \frac{c^2}{12} z.$$

Now, we define the curve  $\alpha_1^n : [0, 1] \rightarrow \mathbb{W}$  as

$$\alpha_1^n(t) = c \sqrt{n}(1-t)w_n + \frac{c(1-t^2)}{2} \frac{1}{\sqrt{n}} J_z(w_n)$$

and consider the lifting  $\alpha^n = \alpha_1^n + \alpha_2^n$ , where

$$\alpha_2^n(t) = \gamma_2^n(1) + \frac{1}{2} \int_0^t \beta(\alpha_1^n(s), \dot{\alpha}_1^n(s)) ds \in \mathbb{W}$$

By construction,  $\alpha^n$  is also horizontal and  $\alpha^n(0) = \gamma^n(1)$ , therefore the curve  $\alpha^n \star \gamma^n$  obtained by joining  $\gamma^n$  and  $\alpha^n$  is also horizontal. For each  $n \in \mathbb{N}$ , the curve  $\alpha^n \star \gamma^n$  connects the origin  $0 \in \mathbb{M}$  to the point  $\frac{c^2 z}{6} \in \mathbb{W}$ . We finally observe that

$$\ell_S(\alpha^n) = \int_0^1 S_0(\dot{\alpha}_1^n(t)) dt = \int_0^1 S_0\left(c \sqrt{n}w_n + \frac{ct}{\sqrt{n}} J_z(w_n)\right) dt = \ell_S(\gamma^n) \rightarrow 0.$$

Therefore,  $\ell_S(\alpha_n \star \gamma_n) = \ell_S(\gamma_n) + \ell_S(\alpha_n) \rightarrow 0$ . We have proved that (29) holds for every  $c \in \mathbb{R}$  and  $z \in \mathbb{W}$ . To conclude the proof, we consider  $z_1, z_2 \in \mathbb{W}$ ,  $z_1 \neq z_2$  and  $x \in \mathbb{W}$ . We notice that the left invariance of the sub-Finsler distance function yields

$$\rho_S(x + z_1, x + z_2) = \rho_S(xz_1, xz_2) = \rho_S(z_1, z_2) = \rho_S(0, z_2 - z_1).$$

Clearly, we can find  $c \neq 0$  and  $z \in \mathbb{W} \setminus \{0\}$  such that  $z_2 - z_1 = c^2z/6$ , hence

$$\rho_S(x + z_1, x + z_2) = \rho_S(0, c^2z/6) = 0,$$

concluding the proof.  $\square$

**Corollary 4.2.** *Let us fix a strictly weak, left invariant sub-Finsler metric  $S$  on a Hilbertian  $H$ -type group  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$ . Then for  $x, y \in \mathbb{V}$  and  $z_1, z_2 \in \mathbb{W}$ , we have*

$$\rho_S(x + z_1, y + z_2) = 0 \quad \text{if and only if} \quad x = y,$$

where  $\rho_S$  is the sub-Finsler distance associated with  $S$ .

The main implication of this corollary follows by Theorem 4.1. The full characterization of the two conditions is obtained by showing that points with different projections on  $\mathbb{W}$  must have positive Finsler distances. This is a consequence of combining Remark 3.2 and Remark 3.4.

**Lemma 4.3.** *If  $F$  be a strictly weak, left invariant Finsler metric  $F$  on a Hilbertian  $H$ -type group  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$ . Then there exists a sequence  $\{h_n\}_{n \in \mathbb{N}} \subset \mathbb{V}$  such that  $F_0(h_n) \rightarrow 0$  and  $|h_n| = 1$  for all  $n \in \mathbb{N}$ .*

*Proof.* The topology defined by  $F_0$  on  $\mathbb{M}$  is not the Hilbert one, therefore there exists a sequence  $u_n$  in  $\mathbb{M}$  such that  $|u_n| = 1$  for all  $n$  and  $F_0(u_n) \rightarrow 0$ . We can write

$$u_n = v_n + w_n = \pi_1(u_n) + \pi_2(u_n),$$

where  $v_n \in \mathbb{V}$  and  $w_n \in \mathbb{W}$ . By the continuity of the projections,  $CF_0(u_n) \geq F_0(w_n)$  therefore  $F_0(w_n) \rightarrow 0$ . Since  $\mathbb{W}$  is finite dimensional, we also have  $|w_n| \rightarrow 0$ , therefore  $|v_n| \rightarrow 1$ . Again the continuity of the projections yields  $F_0(v_n) \rightarrow 0$ . To conclude the proof, we consider a subsequence  $v_n$  of nonzero vectors, and we observe that the renormalized sequence  $h_n = \frac{v_n}{|v_n|}$  satisfies our claim.  $\square$

**Theorem 4.4.** *Let  $F$  be a strictly weak, left invariant Finsler metric on a Hilbertian  $H$ -type group  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$ . Then for every  $x, y \in \mathbb{V}$  and  $z_1, z_2 \in \mathbb{W}$ , we have  $d_F((x, z_1), (y, z_2)) = 0$  if and only if  $x = y$ .*

*Proof.* The restriction of  $F_0$  to  $\mathbb{W}$  defines a weak sub-Finsler metric  $S_0 : \mathbb{W} \rightarrow [0, +\infty)$ . By Lemma 4.3, the corresponding left invariant sub-Finsler metric  $S$  is strictly weak. In view of Remark 3.4, we have  $\rho_S \geq d_F$ , so we can apply Theorem 4.1, obtaining that  $d_F(p, q) = 0$ , whenever  $\pi_1(p) = \pi_1(q)$ . By Remark 3.2, the proof is complete.  $\square$

**Corollary 4.5.** *Let  $\sigma$  be a strictly weak, left invariant Riemannian metric on a Hilbertian  $H$ -type group  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$ . Then for every  $x, y \in \mathbb{V}$  and  $z_1, z_2 \in \mathbb{W}$ , we have  $d_\sigma((x, z_1), (y, z_2)) = 0$  if and only if  $x = y$ .*

The previous corollary follows by observing that a strictly weak, left invariant Riemannian metric also yields a strictly weak, left invariant Finsler metric.

## 5. NON-EXISTENCE OF THE LEVI-CIVITA COVARIANT DERIVATIVE

In this section, we fix a Hilbertian H-type group  $\mathbb{M}$  with its Lie product  $[\cdot, \cdot]$ . We consider the Lie algebra  $\text{Lie } \mathbb{M}$  of left invariant vector fields on  $\mathbb{M}$ . The associated Lie product is the skew-symmetric bilinear mapping  $[\cdot, \cdot] : \text{Lie } \mathbb{M} \times \text{Lie } \mathbb{M} \rightarrow \text{Lie } \mathbb{M}$  its Lie product. In our setting, the linear structure of  $\mathbb{M}$  allows us also consider the "identification"  $\mathfrak{I} : \mathbb{M} \rightarrow \text{Lie } \mathbb{M}$ , where  $\mathfrak{I}(v) = X_v$  is the unique left invariant vector field of  $\text{Lie}(\mathbb{M})$  such that  $X_v(0) = v$ . In fact, there is the already mentioned identification between  $T_0\mathbb{M}$  and  $\mathbb{M}$ . Throughout the section, the continuous linear and self-adjoint operator  $A : \mathbb{M} \rightarrow \mathbb{M}$  is defined by the weak metric  $\sigma_0(v, w) = \langle v, Aw \rangle$  for  $v, w \in \mathbb{M}$ .

The first result of this section is to prove that the Lie algebra  $\text{Lie}(\mathbb{M})$  is actually isomorphic to the starting Lie algebra  $\mathbb{M}$ , and the isomorphism is given by the map  $\mathfrak{I}$ .

**Proposition 5.1.** *Let  $\mathbb{M}$  be an H-type group. Then the map  $\mathfrak{I}$  is a Lie algebra isomorphism, that is, for every  $x, y \in \mathbb{M}$  we have  $\mathfrak{I}_{[x,y]} = [\mathfrak{I}_x, \mathfrak{I}_y]$ .*

The proof of the previous proposition can be obtained by standard arguments, taking into account that the group operation in  $\mathbb{M}$  is given by the BCH formula and the Lie product on  $\mathbb{M}$ . Actually, it holds in general Banach nilpotent Lie groups, [20, Proposition 2.1].

**Theorem 5.2.** *Let  $\sigma$  be a weak, graded Riemannian metric on a Hilbertian H-type group  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$ . If  $\sigma$  admits the Levi-Civita covariant derivative  $\nabla$ , then for every  $x = x_1 + x_2 \in \mathbb{M}$  with  $x_1 \in \mathbb{V}$  and  $x_2 \in \mathbb{W}$  we have*

$$(31) \quad J_{Ax_2}x_1 \in \text{Im } A \quad \text{and} \quad \nabla_{\mathfrak{I}_x}\mathfrak{I}_x(0) = -A^{-1}(J_{Ax_2}x_1).$$

*Proof.* Suppose that  $\nabla$  is the Levi-Civita covariant derivative. Since  $\nabla$  is torsion-free, we have  $[\mathfrak{I}_x, \mathfrak{I}_y] = \nabla_{\mathfrak{I}_x}\mathfrak{I}_y - \nabla_{\mathfrak{I}_y}\mathfrak{I}_x$  for  $x, y \in \mathbb{M}$ . By the left invariance of  $\mathfrak{I}_x$  and  $\mathfrak{I}_y$ , the function  $\mathbb{M} \ni p \rightarrow \sigma_p(\mathfrak{I}_x(p), \mathfrak{I}_y(p))$  is constantly equal to  $\sigma_0(x, y)$ , by the identification of  $\mathbb{M}$  with  $T_0\mathbb{M}$ . The key property of the Levi-Civita covariant derivative yields

$$(32) \quad 0 = Z\sigma(\mathfrak{I}_x, \mathfrak{I}_y) = \sigma(\nabla_Z\mathfrak{I}_x, \mathfrak{I}_y) + \sigma(\mathfrak{I}_x, \nabla_Z\mathfrak{I}_y)$$

for every  $Z$  vector field on  $\mathbb{M}$ . Notice that the previous equations for  $x = y$  yield

$$\sigma(\mathfrak{I}_x, \nabla_Z\mathfrak{I}_x) = 0.$$

As a consequence, using again (32), we get

$$\begin{aligned} \sigma([\mathfrak{I}_x, \mathfrak{I}_y], \mathfrak{I}_x) &= \sigma(\nabla_{\mathfrak{I}_x}\mathfrak{I}_y, \mathfrak{I}_x) - \sigma(\nabla_{\mathfrak{I}_y}\mathfrak{I}_x, \mathfrak{I}_x) = \sigma(\nabla_{\mathfrak{I}_x}\mathfrak{I}_y, \mathfrak{I}_x) \\ &= -\sigma(\mathfrak{I}_y, \nabla_{\mathfrak{I}_x}\mathfrak{I}_x) = -\sigma_0(y, \nabla_{\mathfrak{I}_x}\mathfrak{I}_x(0)). \end{aligned}$$

By Proposition 5.1, it follows that

$$\sigma([\mathfrak{I}_x, \mathfrak{I}_y], \mathfrak{I}_x) = \sigma(\mathfrak{I}_{[x,y]}, \mathfrak{I}_x) = \sigma_0(\mathfrak{I}_{[x,y]}(0), \mathfrak{I}_x(0)) = \sigma_0([x, y], x).$$

Therefore, we have proved that

$$(33) \quad \sigma_0(y, \nabla_{\mathfrak{I}_x}\mathfrak{I}_x(0)) = -\sigma_0([x, y], x),$$

which immediately leads us to the following equalities

$$(34) \quad \langle y, A\nabla_{\mathfrak{I}_x}\mathfrak{I}_x(0) \rangle = -\langle [x, y], Ax \rangle = -\langle [x_1, y_1], Ax_2 \rangle = -\langle y_1, J_{Ax_2}x_1 \rangle.$$

In particular, formula (34) holds true for all  $y \in \mathbb{W}$ , hence  $A\nabla_{\mathfrak{I}_x}\mathfrak{I}_x(0) \in \mathbb{W}$ . Now, taking  $y \in \mathbb{W}$  in formula (34) we get

$$A\nabla_{\mathfrak{I}_x}\mathfrak{I}_x(0) = -J_{Ax_2}x_1,$$

which proves our claim.  $\square$

**Theorem 5.3.** *Let  $\sigma$  be a weak, graded Riemannian metric on an H-type group  $\mathbb{M}$ . If  $\sigma$  is strictly weak, then it does not admit the Levi-Civita covariant derivative.*

*Proof.* If  $\sigma$  is strictly weak, then its associated operator  $A$  is not surjective, by Proposition 3.5. Since  $\mathbb{W}$  is finite dimensional and  $A_{\mathbb{W}}$  is injective, then  $A_{\mathbb{W}}$  is also surjective. As a consequence,  $A_{\mathbb{W}}$  cannot be surjective, hence we can choose  $v \in \mathbb{W}$  such that  $v \notin A_{\mathbb{W}}(\mathbb{W})$ . We consider  $x_2 \in \mathbb{W}$ ,  $x_2 \neq 0$  and we define  $x = J_{Ax_2}v + x_2$ ,  $x_1 = J_{Ax_2}v$ . By (2) we have

$$J_{Ax_2}x_1 = J_{Ax_2}(J_{Ax_2}v) = -|Ax_2|^2v \notin \text{Im } A.$$

Hence, by Theorem 5.2 we get a contradiction, therefore the Levi-Civita covariant derivative does not exist for  $\sigma$ .  $\square$

Since strong Riemannian metrics always admit the Levi-Civita covariant derivative, the next corollary is straightforward.

**Corollary 5.4.** *Let  $\sigma$  be a weak, graded Riemannian metric on an H-type group  $\mathbb{M}$ . Then,  $\sigma$  admits the Levi-Civita covariant derivative if and only if it is a strong Riemannian metric.*

## 6. BLOW-UP OF THE SECTIONAL CURVATURE

We consider a Hilbertian H-type group  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$ , endowed with a weak, graded Riemannian metric  $\sigma$ . If  $\sigma$  is strong, then the sectional curvature can be computed using the Riemann tensor and the Levi-Civita covariant derivative, [18]. This approach in general does not apply when  $\sigma$  is strictly weak, as a consequence of Theorem 5.3. We will also show how the Arnold's formula allows us to compute the sectional curvature for a special family of planes. Finally, we find a sequence of planes where the sectional curvatures blow-up.

**6.1. The B-adjoint vector.** We consider the adjoint representation  $\text{ad} : \mathbb{M} \rightarrow \text{End}(\mathbb{M})$ , where the endomorphism  $\text{ad}_x(y) = [x, y]$  is defined by the Lie product of  $\mathbb{M}$ . For a fixed couple of vectors  $x, y \in \mathbb{M}$ , we consider (in case it exists) the unique vector  $B_{\sigma_0}(y, x) \in \mathbb{M}$  which satisfies the formula

$$(35) \quad \langle z, B_{\sigma_0}(y, x) \rangle_{\sigma_0} = \langle [x, z], y \rangle_{\sigma_0}$$

for every  $z \in \mathbb{M}$ . We say that  $B_{\sigma_0}(y, x)$  is the *B-adjoint vector of  $(y, x)$  with respect to  $\sigma_0$* . When this vector exists, it automatically satisfies

$$B_{\sigma_0}(ty, sx) = ts B_{\sigma_0}(y, x)$$

for every  $t, s \in \mathbb{R}$ . And also  $B_{\sigma_0}(ty, sx)$  exists for some  $t, s \neq 0$  if and only if  $B_{\sigma_0}(y, x)$  exists. If  $\sigma_0$  is a strong metric, then the classical Riesz representation theorem yields the existence of  $B_{\sigma}(y, x)$  for all  $x, y \in \mathbb{M}$ . Precisely, in this case,

$$B_{\sigma_0}(y, x) = \text{ad}_x^{\top}(y),$$

where  $\text{ad}_x^{\top} : \mathbb{M} \rightarrow \mathbb{M}$  is the adjoint operator of  $\text{ad}_x$  with respect to  $\sigma_0$ . For a strictly weak Riemannian metric, the existence of  $B_{\sigma}(y, x) \in \mathbb{M}$  for fixed  $x, y \in \mathbb{M}$  does not necessarily hold. A simple example can be found for instance in [22].

**6.2. Arnold's formula.** To compute the sectional curvature of planes in a Hilbertian H-type group  $\mathbb{M}$ , we use the Arnold's formula [2, Theorem 5], see also [24], [4] and [3].

Let us consider two  $\sigma_0$ -orthonormal vectors  $x, y \in \mathbb{M}$ , such that the  $B$ -adjoint vectors

$$B_{\sigma_0}(y, x), B_{\sigma_0}(x, y), B_{\sigma_0}(x, x), B_{\sigma_0}(y, y) \in \mathbb{M}$$

all exist. We introduce the notation  $\Pi_{x,y}$  to denote the vector subspace spanned by  $x$  and  $y$ . The sectional curvature of  $\Pi_{x,y}$  can be obtained by

$$(36) \quad K_{\sigma}(\Pi_{x,y}) = \langle \delta, \delta \rangle_{\sigma_0} + 2 \langle \alpha, \beta \rangle_{\sigma_0} - 3 \langle \alpha, \alpha \rangle_{\sigma_0} - 4 \langle B_x, B_y \rangle_{\sigma_0}.$$

In the previous formula we have defined

$$(37) \quad \delta = \frac{1}{2} (B_{\sigma_0}(x, y) + B_{\sigma_0}(y, x)), \quad \beta = \frac{1}{2} (B_{\sigma_0}(x, y) - B_{\sigma_0}(y, x)), \quad \alpha = \frac{1}{2} [x, y]$$

$$(38) \quad B_x = \frac{1}{2} B_{\sigma_0}(x, x) \quad \text{and} \quad B_y = \frac{1}{2} B_{\sigma_0}(y, y).$$

It is a simple computation to verify that the sectional curvature of a plane defined through this formula does not depend on the choice of the  $\sigma_0$ -orthonormal basis for that plane.

First of all, we provide a condition for which the vector  $B_{\sigma}(y, x)$  exists with  $x, y \in \mathbb{M}$  fixed, see the following proposition.

**Proposition 6.1** (Existence of the  $B$ -adjoint vector). *Let  $\sigma_0$  be a weak, graded Riemannian metric on a Hilbertian H-type group  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$  and let  $x = x_1 + x_2, y = y_1 + y_2 \in \mathbb{M}$ , with  $x_1, y_1 \in \mathbb{V}$  and  $x_2, y_2 \in \mathbb{W}$ . It follows that*

$$(39) \quad \text{there exists } B_{\sigma_0}(y, x) \in \mathbb{M} \text{ if and only if } J_{A_{y_2}} x_1 \in A_{\mathbb{W}}(\mathbb{W}).$$

If one of the previous conditions holds, then

$$(40) \quad B_{\sigma_0}(y, x) = A^{-1}(J_{A_{y_2}} x_1).$$

*Proof.* Assume that  $J_{A_{y_2}} x_1 \in A_{\mathbb{W}}(\mathbb{W})$ . Thus, for all  $z \in \mathbb{M}$  we have

$$\langle z, A^{-1}(J_{A_{y_2}} x_1) \rangle_{\sigma_0} = \langle z, J_{A_{y_2}} x_1 \rangle = \langle [x, z], A_{y_2} \rangle = \langle [x, z], y \rangle_{\sigma_0},$$

hence there exists  $B_{\sigma_0}(y, x) = A^{-1}(J_{A_{y_2}} x_1)$ . If  $B_{\sigma_0}(y, x) \in \mathbb{M}$  exists, then for all  $z \in \mathbb{M}$  we have

$$\langle z, A(B_{\sigma_0}(y, x)) \rangle = \langle z, B_{\sigma_0}(y, x) \rangle_{\sigma_0} = \langle [x, z], y \rangle_{\sigma_0} = \langle [x_1, z], A_{y_2} \rangle = \langle J_{A_{y_2}} x_1, z \rangle.$$

Therefore,  $A(B_{\sigma_0}(y, x)) = J_{A_{y_2}} x_1$ , concluding the proof.  $\square$

From (39) and (40) we get directly (1). From (39), (40) and (2) we get directly (2).

**Remark 6.2.** As a consequence of Proposition 6.1, precisely of (39), (40), for all

$$(y, x) \in (\mathbb{V} \times \mathbb{M}) \cup (\mathbb{M} \times \mathbb{W})$$

we have  $J_{A_{y_2}} x_1 = 0$ , hence the  $B$ -adjoint vector  $B_{\sigma_0}(y, x)$  exists and it vanishes.

**Remark 6.3.** For all  $z \in \mathbb{W}$  and  $x \in \mathbb{V}$ , we notice that

$$J_{A_z}(J_{A_z}(Ax)) = -|A_z|^2 Ax \in A_{\mathbb{W}}(\mathbb{W}),$$

hence (39) yields the existence of the  $B$ -adjoint vector  $B_{\sigma_0}(z, J_{A_z}(Ax))$  and (40) gives

$$(41) \quad B_{\sigma_0}(z, J_{A_z}(Ax)) = -|A_z|^2 x.$$

We use Proposition 6.1 and the previous remarks to compute the sectional curvatures of specific planes, according to the following lemma.

**Lemma 6.4.** *Let  $\sigma$  be a weak graded Riemannian metric on  $\mathbb{M}$ .*

(1) *If  $x, y \in \mathbb{W}$  are  $\sigma_0$ -orthonormal, then the sectional curvature  $K_\sigma(\Pi_{x,y})$  exists and*

$$K_\sigma(\Pi_{x,y}) = -\frac{3}{4} \|[x, y]\|_{\sigma_0}^2.$$

(2) *For all  $z \in \mathbb{W} \setminus \{0\}$  and  $x \in \mathbb{W} \setminus \{0\}$ , the vectors  $J_{Az}(Ax)$  and  $z$  are orthogonal and*

$$K_\sigma(\Pi_{J_{Az}(Ax), z}) = \frac{1}{4} \frac{|Az|^4}{\|J_{Az}(Ax)\|_{\sigma_0}^2 \|z\|_{\sigma_0}^2} \|x\|_{\sigma_0}^2.$$

*Proof.* Due to Remark 6.2,  $B_\sigma(x, x)$ ,  $B_\sigma(y, y)$ ,  $B_\sigma(y, x)$ ,  $B_\sigma(x, y)$  all exist and are null. Thus, (36) immediately gives the claim (1). The term  $\alpha$  of (36) obviously vanishes, and again Remark 6.2 gives the existence and the vanishing of  $B_{J_{Az}(Ax)}$ ,  $B_z$ , and  $B_{\sigma_0}(J_{Az}(Ax), z)$  in the corresponding Arnold's formula for the sectional curvature. From the property of the mapping  $J_Z$ ,  $Z \in \mathbb{W}$ , of a Hilbertian H-type group, it is easy to notice that  $z$  and  $J_{Az}(Ax)$  are  $\sigma_0$ -orthogonal.

Thus, by (36) applied to the  $\sigma_0$ -orthonormal basis  $z/\|z\|_{\sigma_0}$  and  $J_{Ay}(Ax)/\|J_{Ay}(Ax)\|_{\sigma_0}$ , we get

$$\begin{aligned} K_\sigma(\Pi_{J_{Az}(Ax), z}) &= \|\delta\|_{\sigma_0}^2 = \frac{1}{4} \left\| B_{\sigma_0} \left( \frac{z}{\|z\|_{\sigma_0}}, \frac{J_{Az}(Ax)}{\|J_{Az}(Ax)\|_{\sigma_0}} \right) \right\|_{\sigma_0}^2 \\ &= \frac{1}{4 \|z\|_{\sigma_0}^2 \|J_{Az}(Ax)\|_{\sigma_0}^2} \|B_{\sigma_0}(z, J_{Az}(Ax))\|_{\sigma_0}^2 \\ &= \frac{1}{4 \|z\|_{\sigma_0}^2 \|J_{Az}(Ax)\|_{\sigma_0}^2} \|[Az]^2 x\|_{\sigma_0}^2, \end{aligned}$$

where the last equality also relied on (41) and immediately gives the claim (2).  $\square$

**Lemma 6.5.** *Let  $\sigma$  be a strictly weak graded Riemannian metric on a Hilbertian H-type group  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$ . Then there exists  $w_n \in A_{\mathbb{W}}(\mathbb{W})$  such that  $|w_n| = 1$  and  $\|w_n\|_{\sigma_0} \rightarrow 0$  as  $n \rightarrow +\infty$ .*

*Proof.* We consider the sequence  $h_n$  given by Lemma 4.3, hence  $\|h_n\|_{\sigma_0} \rightarrow 0$  and  $|h_n| = 1$ . The image  $A_{\mathbb{W}}(\mathbb{W})$  is dense in  $\mathbb{W}$ , as a consequence of Proposition 3.5. Therefore, for each  $n \in \mathbb{N} \setminus \{0\}$  we may choose  $v_n \in A_{\mathbb{W}}(\mathbb{W})$  such that  $|v_n - h_n| \leq \frac{1}{2n}$ , and therefore  $|v_n| \rightarrow 1$ . We define the unit vectors  $w_n = \frac{v_n}{|v_n|}$  and consider

$$\|v_n\|_{\sigma_0} \leq \|h_n\|_{\sigma_0} + \|h_n - v_n\|_{\sigma_0} \leq \|h_n\|_{\sigma_0} + c_0 |v_n - h_n| \leq \|h_n\|_{\sigma_0} + \frac{c_0}{2n} \rightarrow 0,$$

concluding the proof.  $\square$

**Theorem 6.6.** *Let  $\sigma$  be a strictly weak, graded Riemannian metric on a Hilbertian H-type group  $\mathbb{M} = \mathbb{V} \oplus \mathbb{W}$ . Then there exists a sequence  $w_n \in \mathbb{W}$  such that for every  $z \in \mathbb{W} \setminus \{0\}$  the following limits hold*

$$(42) \quad \lim_{n \rightarrow \infty} K_\sigma(\Pi_{w_n, J_z w_n}) = -\infty \quad \text{and} \quad \lim_{n \rightarrow \infty} K_\sigma(\Pi_{z, J_{Az} w_n}) = +\infty.$$

*Proof.* We consider the sequence  $w_n \in A_{\mathbb{W}}(\mathbb{W}) \subset \mathbb{W}$  of Lemma 6.5 and define the vector

$$\xi_n = J_z w_n - \frac{w_n}{\|w_n\|_{\sigma_0}} \left\langle J_z w_n, \frac{w_n}{\|w_n\|_{\sigma_0}} \right\rangle_{\sigma_0} \in \mathbb{W}.$$



By construction of  $\xi_n$ , the vectors  $w_n / \|w_n\|_{\sigma_0}$  and  $\xi_n / \|\xi_n\|_{\sigma_0}$  are  $\sigma_0$ -orthonormal and span the 2-dimensional subspace  $\Pi_{w_n, J_z w_n}$ . By Lemma 6.4 and (10), we have

$$K_{\sigma}(\Pi_{w_n, J_z w_n}) = -\frac{3}{4} \left\| \left\| \frac{w_n}{\|w_n\|_{\sigma_0}}, \frac{\xi_n}{\|\xi_n\|_{\sigma_0}} \right\|_{\sigma_0} \right\|^2 = -\frac{3}{4} \frac{\|z\|_{\sigma_0}^2}{\|w_n\|_{\sigma_0}^2 \left\| J_z w_n - \frac{w_n}{\|w_n\|_{\sigma_0}^2} \langle J_z w_n, w_n \rangle_{\sigma_0} \right\|_{\sigma_0}^2}.$$

We consider the estimates

$$\begin{aligned} \left\| J_z w_n - \frac{w_n}{\|w_n\|_{\sigma_0}^2} \langle J_z w_n, w_n \rangle_{\sigma_0} \right\|_{\sigma_0}^2 &\leq 2 \left( \|J_z w_n\|_{\sigma_0}^2 + \frac{\langle J_z w_n, w_n \rangle_{\sigma_0}^2}{\|w_n\|_{\sigma_0}^2} \right) \\ &\leq 4 \|J_z w_n\|_{\sigma_0}^2 \leq 4c_0^2 |J_z w_n|^2 \\ &\leq 4c_0^2 |z|^2, \end{aligned}$$

where we have applied both (27) and (5). It follows that

$$\left\| \left\| \frac{w_n}{\|w_n\|_{\sigma_0}}, \frac{\xi_n}{\|\xi_n\|_{\sigma_0}} \right\|_{\sigma_0} \right\|^2 \geq \frac{1}{4c_0^2 |z|^2} \frac{\|z\|_{\sigma_0}^2}{\|w_n\|_{\sigma_0}^2} \rightarrow +\infty,$$

proving the first limit of (42). To establish the second limit of (42), we consider the same previous sequence  $w_n \in A_{\mathbb{W}}(\mathbb{W})$ , along with  $v_n \in \mathbb{W}$  such that  $A v_n = w_n$ . By Lemma 6.4 we have

$$(43) \quad K_{\sigma}(\Pi_{z, J_{A_z}(A v_n)}) = \frac{1}{4} \frac{|A z|^4}{\|J_{A_z}(A v_n)\|_{\sigma_0}^2 \|z\|_{\sigma_0}^2} \|v_n\|_{\sigma_0}^2.$$

Again (27) and (5) give the inequalities

$$\frac{1}{\|J_{A_z}(A v_n)\|_{\sigma_0}} \geq \frac{1}{c_0 |J_{A_z}(A v_n)|} = \frac{1}{c_0 |A z| |A v_n|} = \frac{1}{c_0 |A z|} > 0,$$

where we have also use the condition  $|w_n| = |A v_n| = 1$ . By Cauchy-Schwarz inequality, we get

$$\|v_n\|_{\sigma_0} \geq \left\langle v_n, \frac{w_n}{\|w_n\|_{\sigma_0}} \right\rangle_{\sigma_0} = \langle A v_n, w_n \rangle \frac{1}{\|w_n\|_{\sigma_0}} = \frac{1}{\|w_n\|_{\sigma_0}} \rightarrow +\infty,$$

that immediately yields  $K_{\sigma}(\Pi_{z, J_{A_z} w_n}) \rightarrow +\infty$ , concluding the proof.  $\square$

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