

OPTIMAL REGULARITY OF ISOPERIMETRIC SETS WITH HÖLDER DENSITIES

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ABSTRACT. We establish a regularity result for optimal sets of the isoperimetric problem with double density under mild Hölder regularity assumptions on the density functions. Our main Theorem improves some previous results and allows to reach the optimal regularity class $C^{1, \frac{\alpha}{2-\alpha}}$ in any dimension.

1. INTRODUCTION

In this paper we are concerned with the regularity of isoperimetric sets in \mathbb{R}^n with densities, for arbitrary dimensions $n \geq 2$ and with an emphasis on the situation of very low regularity assumptions on the density functions. Isoperimetric sets are defined as solutions of the isoperimetric problem in \mathbb{R}^n with densities, which can be formulated as follows: Given two lower semi-continuous functions $f, h: \mathbb{R}^n \rightarrow (0, +\infty)$, the so-called *densities*, and an arbitrary measurable set $E \subset \mathbb{R}^n$, we introduce its (weighted) volume $V_f(E)$ via

$$V_f(E) := \int_E f(x) dx$$

and its (weighted) perimeter $P_h(E)$ via

$$P_h(E) := \int_{\partial^* E} h(x) d\mathcal{H}^{n-1}(x),$$

whenever E is of locally finite perimeter (and with $\partial^* E$ denoting the reduced boundary of E), while we set $P_h(E) := \infty$ otherwise. For some positive number m , we then look for a set of minimal weighted perimeter among all sets of fixed weighted volume m , i.e., we look for minimizers of

$$\inf \{P_h(E): E \subset \mathbb{R}^n \text{ with } V_f(E) = m\}.$$

The classical isoperimetric problem dating back to ancient Greece corresponds to constant density functions $h = f \equiv 1$, for which the weighted volume and perimeter reduce to the Euclidean volume V_{Eucl} and Euclidean perimeter P_{Eucl} , and in this case it is well known that the isoperimetric sets relative to a constant m are precisely all balls of radius R such that the equality

$$V_{\text{Eucl}}(B_R) = \frac{\pi^{n/2}}{\Gamma(1 + n/2)} R^n = m$$

is satisfied.

In the interesting case of non-constant densities, existence of isoperimetric sets is still guaranteed under quite general assumptions on the density function (see [12, 15, 26, 28]). These sets are in general not unique, even not in the equivalence class of spatial translates. (Notice, however, that in certain geometries, uniqueness of the isoperimetric set is obtained only *thanks* to the weight.) In general, if the weight functions are not globally bounded, the isoperimetric sets are not necessarily bounded. The complementary, however, is true as proved in [12, Theorem 1.1] and [28, Theorem B].

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In this paper, we focus on the regularity of the isoperimetric sets, or more precisely, on the regularity of their boundaries. (Optimal) regularity has been investigated for many years in dependency on the regularity of the density functions.

A classical (and optimal) result in this regard for the case of a single density (i.e., $f = h$), under the assumption of quite high regularity, which in particular allows to take advantage of the Euler–Lagrange formulation of the problem, is the following statement ([23, Proposition 3.5 and Corollary 3.8]).

Theorem A ([23]). *Let $f = h$ be of class $C^{k,\alpha}(\mathbb{R}^n, \mathbb{R}^+)$ for some $k \geq 1$ and $\alpha \in (0, 1]$. Then the boundary of any isoperimetric set is of class $C^{k+1,\alpha}$, except for a singular set of Hausdorff dimension at most $n - 8$.*

When the densities are assumed to be just Hölder functions, one cannot even write down the associated Euler–Lagrange equation. This case of poorly regular densities was addressed only recently. More specifically, in Theorem 5.7 of [12] a first regularity result for the case of a single density $f = h$, which is Hölder continuous of order α , was established in any dimension (with a Hölder exponent depending on α and on the dimension). A second result improved the above regularity result in the 2-dimensional case, see Theorem A in [13]. Here is the precise combined statement.

Theorem B ([12, 13]). *Let $f = h$ be of class $C^{0,\alpha}(\mathbb{R}^n, \mathbb{R}^+)$ for some $\alpha \in (0, 1]$. Then, if E is an isoperimetric set, we have that $\partial E = \partial^* E$ up to \mathcal{H}^{n-1} -negligible sets, and $\partial^* E \in C^{1,\alpha/(2n(1-\alpha)+2\alpha)}$. If $n = 2$, we have that $\partial^* E \in C^{1,\alpha/(3-2\alpha)}$.*

More recently, in Theorem C of [29] the regularity result in dimension n was generalized to the case of two different densities. As it is clear from the proof of this result, the Hölder regularity of an optimal set only depends on the Hölder regularity of the density h (weighting the perimeter), while no regularity is needed on f .

Theorem C ([29]). *Let h be a density of class $C^{0,\alpha}(\mathbb{R}^n, \mathbb{R}^+)$ for some $\alpha \in (0, 1]$ and f be a locally bounded function. Then, if E is an isoperimetric set, we have that $\partial E = \partial^* E$ up to \mathcal{H}^{n-1} -negligible sets, and $\partial^* E \in C^{1,\alpha/(2n(1-\alpha)+2\alpha)}$.*

We will later build up on these regularity results and we will thus refer to $C^{1,\sigma}$ with $\sigma = \alpha/(2n(1-\alpha) + 2\alpha)$ as the *initial regularity*.

The proof of the regularity result in any dimension (for both the case of single and double density) consists in showing that if E is an isoperimetric set with an α -Hölder density h , then it is an ω -minimal set (or almost-minimal set) for a certain modulus of continuity $\omega(r) = r^{2\sigma}$. Hence, standard regularity theory for ω -minimal sets applies and allows to obtain $C^{1,\sigma}$ regularity of ∂E .

We observe that using this approach, which relies on ω -minimality, the order σ that one can reach tends to $1/2$ when $\alpha \rightarrow 1$. In the 2-dimensional result of Theorem B, the exponent $\frac{\alpha}{3-2\alpha}$ is still not-optimal but tends to 1 for $\alpha \rightarrow 1$.

The crucial ingredient in the proof of both Theorems B and C is the so-called $\varepsilon - \varepsilon^\beta$ property, first established in [12, Theorem B] for the case of a single density, and then generalized to the case of double density in [29]. Roughly speaking this property says that it is possible to modify a set E by changing its volume of an amount ε and increasing its perimeter of an amount proportional to at most ε^β . In the case of a Lipschitz density the exponent β can be chosen to be 1 , while for a Hölder density it must be chosen depending on the Hölder regularity of the density. In the case of double density, as mentioned before, only the density on the perimeter is needed to be Hölder continuous.

The aim of the present paper is to improve these regularity results in the setting of Hölder continuous densities and in general dimensions. More specifically, we prove the following:

Theorem 1.1. *Let h be density of class $C^{0,\alpha}(\mathbb{R}^n, \mathbb{R}^+)$ and f be a density of class $C^{0,\gamma}(\mathbb{R}^n, \mathbb{R}^+)$ for some α and $\gamma \in (0, 1)$. Then the boundary of any isoperimetric set is of class $C^{1,\alpha/(2-\alpha)}$, except for a singular set of Hausdorff dimension at most $n - 8$.*

As we will see in Example 1.2 below, the Hölder exponent $\frac{\alpha}{2-\alpha}$ is optimal. Moreover, it does not depend on the dimension and it indeed improves on the regularity results established before because

$$\frac{\alpha}{2-\alpha} > \begin{cases} \frac{\alpha}{2n(1-\alpha)+2\alpha} & \text{for } n \geq 2, \\ \frac{\alpha}{3-2\alpha} & \text{for } n = 2 \text{ and } f = h, \end{cases}$$

for each $\alpha \in (0, 1)$. In particular, the expected asymptotic behavior $\alpha/(2 - \alpha) \rightarrow 1$ as $\alpha \nearrow 1$ is now achieved for all dimensions $n \geq 2$.

At first glance, the loss in the order of the Hölder semi-norm from α in the differentiable setting of Theorem A to $\frac{\alpha}{2-\alpha}$ in the continuous setting in Theorem 1.1 seems surprising. This feature is, however, well-known from classical regularity theory for the minimization of variational functionals of the form $\mathcal{F}[w] = \int_{\Omega} F(x, w, Dw) dx$ among Sobolev functions in a given Dirichlet class, in the specific situation that merely an α -Hölder continuity assumption is imposed on the maps $u \mapsto F(x, u, z)$ and $(x, u) \mapsto D_z F(x, u, z)$ which does not allow for the passage to an Euler–Lagrange equation. In this case, the optimal regularity of minimizers is precisely $C^{1,\alpha/(2-\alpha)}$, see [27].

The hypothesis that the volume density f being Hölder continuous seems to be an artifact of our method of proof and we actually do not believe that it is a necessary assumption. Indeed, our optimal regularity result is independent of the Hölder exponent γ , and the suboptimal results from Theorem C hold true also without any continuity requirement. Unfortunately, we do currently not see how to remove this hypothesis.

Finally, the optimal bound on the dimension of the singular set follows from the standard regularity theory for ω -minimal sets, established by Tamanini in [30]. Indeed, as commented above, in [12] and [29] it is proved that an isoperimetric set with density is ω -minimal for a certain modulus of continuity $\omega(r) = r^{2\sigma}$, and hence Tamanini’s regularity result applies.

We conclude this introduction by discussing the strategy of the proof of our main result.

Thanks to the already known regularity result of Theorem C, we can work with a local representation of the reduced boundary of isoperimetric sets (at some given regular point) in terms of the graph of a C^1 -functions. More precisely, in order to study the local regularity of isoperimetric sets, this amounts to considering minimizers u of the functional

$$w \mapsto \int_{B_R(0)} h(x', w) (1 + |Dw|^2)^{\frac{1}{2}} dx' \quad (1.1)$$

among all functions w satisfying the constraint

$$\int_{B_R(0)} \int_0^{w(x')} f(x', t) dt dx' = m \quad (1.2)$$

for a given constant m and with prescribed boundary values on $\partial B_R(0)$. Notice that here, $B_R(0)$ denotes an open ball in \mathbb{R}^{n-1} that we have centered at the origin for convenience and we may choose $R \leq R_0 \leq 1$.

Our method for establishing (optimal) Hölder regularity is based on the so-called direct approach from classical regularity theory for minimization problems, see e.g. [17, 18] for the original theory without integral constraints, and [6, 8] for more recent text books. To this end, we define in Section 3 a suitable comparison problem by keeping the original density only for the volume constraint, and by freezing it for the perimeter. Via a combination of the initial regularity result for the minimizer of the comparison problem, suitable estimates on the Lagrange multiplier (coming from the volume constraint), and classical Schauder theory (applied to the associated Euler–Lagrange equation which does now indeed exist), the minimizer is then shown to have

optimal decay estimates. Finally, in Section 5 the decay estimates of this comparison function are then carried over to the minimizer of the original constrained minimization problem, thus completing the proof of Theorem 1.1, via the Campanato characterization of Hölder continuous functions.

We finally want to give an example that shows the optimality of the Hölder exponent $\frac{\alpha}{2-\alpha}$ that we find in this paper.

Example 1.2. *For simplicity, we consider the two-dimensional problem and suppose that the volume density is constant, say $f \equiv 1$. Let us moreover consider the perimeter density $h(x_1, x_2) = 1/(1 + |x_1|^\alpha + |x_2|^\alpha)$, which is α -Hölder continuous. We suppose furthermore that the boundary of the isoperimetric set can be locally written as the graph of a function w over the interval $(0, \ell)$ and we suppose that $w > 0$ inside the interval and $w(0) = w(\ell) = 0$. Then, according to (1.1) and (1.2), w minimizes the functional*

$$w \mapsto \int_0^\ell \frac{\sqrt{1 + (w'(z))^2}}{1 + |z|^\alpha + w(z)^\alpha} dz,$$

among all w satisfying the constraint

$$\int_0^\ell w(z) dz = m.$$

In this scenario, we may compute the Euler–Lagrange equation inside the interval and find that

$$\left(\frac{1}{1 + |z|^\alpha + w^\alpha} \frac{w'}{\sqrt{1 + (w')^2}} \right)' + \frac{\alpha w^{\alpha-1}}{(1 + |z|^\alpha + w^\alpha)^2} \sqrt{1 + (w')^2} = \lambda,$$

where $\lambda \in \mathbb{R}$ is the Lagrange multiplier. In view of the assumption $w(0) = 0$ and knowing that w is a $C^{1,\sigma}$ function, it must hold that $w(z) \approx z^{1+\sigma}$ near $z = 0$. Plugging this Ansatz into the Euler–Lagrange equation, we see that the first term is of the order $O(z^{\sigma-1})$, while the second one is $O(z^{(\alpha-1)(1+\sigma)})$. The singularity of both terms enforces that both exponents are identical, $\sigma - 1 = (\alpha - 1)(1 + \sigma)$, which yields $\sigma = \frac{\alpha}{2-\alpha}$.

The paper is organized as follows:

- Section 2 is devoted to introduce some notations and preliminaries;
- in Section 3, we introduce the comparison problem and prove some crucial preliminary Lemmas that relate, in a quantitative way, the Lagrange multiplier λ with the L^2 -distance between the gradient of the comparison function and the gradient of the solution of our original weighted problem;
- Section 4, which is the core of the paper, deals with decay estimates for the comparison function v ;
- finally, in Section 5, we transfer these decay estimates from v to the solution of our original problem u and deduce our regularity result.

2. NOTATION AND PRELIMINARIES

We start by introducing some notation. In the following, we will denote by $x = (x', x_n)$ a point in $\mathbb{R}^n = \mathbb{R}^{n-1} \times \mathbb{R}$. Given $r > 0$ and $x'_0 \in \mathbb{R}^{n-1}$, we denote by $B_r(x'_0)$ the ball in \mathbb{R}^{n-1} centered at x'_0 and with radius r , and we write $B_r := B_r(0)$ for simplicity.

Given a function w defined on \mathbb{R}^{n-1} , we denote its mean integral on a certain measurable set $A \subset \mathbb{R}^{n-1}$ by

$$(w)_A := \frac{1}{|A|} \int_A w(x') dx',$$

where $|A|$ stands for the Lebesgue measure of A . In the particular case in which $A = B_r(x'_0)$ and it is clear from the context what is the center x'_0 , we simply use the abbreviation $(w)_r$ instead of $(w)_{B_r(x'_0)}$.

As mentioned above, we will rely on Campanato's characterization of Hölder continuity, which we recall here. See also Section 3.1 in [6].

Proposition D ([11], Teorema I.2). *Let B_R be a ball in \mathbb{R}^{n-1} , $\beta \in (0, 1]$ and $p \in [1, \infty)$. A function $w \in L^1(B_R)$ is (up to the choice of a suitable representative) Hölder continuous with exponent β , i.e., $w \in C^{0,\beta}(\overline{B_R})$, if and only if there exists a constant C such that for each ball $B_\rho(y')$ centered in some point $y' \in B_R$ there holds*

$$\int_{B_R \cap B_\rho(y')} |w - (w)_{B_R \cap B_\rho(y')}|^p dx' \leq C \rho^{n-1+p\beta}.$$

Apparently, the oscillation on the left-hand side is a monotone function of ρ because for any measurable set $A \subset \mathbb{R}^{n-1}$ the mapping

$$c \mapsto \int_A (w - c)^p dx'$$

is minimized at $c = (w)_A$. The following iteration lemma is thus well-suited for oscillations and it is an elementary though fundamental tool in elliptic regularity theory as it allows to pass from ρ^{α_2} to r^{α_2} and to drop an additive non-decaying term (the one that involves ε) at the expense of lowering the order of decay. See also Lemma 3.13 in [6].

Lemma E ([16], Lemma III.2.1). *Assume that $\phi(\rho)$ is a non-negative, real-valued, non-decreasing function defined on the interval $[0, R_0]$ which satisfies*

$$\phi(r) \leq C_1 \left[\left(\frac{r}{\rho} \right)^{\alpha_1} + \varepsilon \right] \phi(\rho) + C_2 \rho^{\alpha_2}$$

for all $r \leq \rho \leq \rho_0$, some non-negative constants C_1, C_2 , and positive exponents $\alpha_1 > \alpha_2$. Then there exists a positive number $\varepsilon_0 = \varepsilon_0(C_1, \alpha_1, \alpha_2)$ such that for $\varepsilon \leq \varepsilon_0$ and all $r \leq \rho \leq \rho_0$ we have

$$\phi(r) \leq c(C_1, \alpha_1, \alpha_2) \left[\left(\frac{r}{\rho} \right)^{\alpha_2} \phi(\rho) + C_2 r^{\alpha_2} \right].$$

Notice that if the quantity ϕ in the lemma is indeed the oscillation, the statement implies Hölder regularity of the order $(\alpha_2 - n + 1)/p$ via Proposition D.

We now collect at one spot for the reader's convenience the Hölder regularity of the density functions:

$$\begin{aligned} h &\in C^{0,\alpha} && \text{regularity of perimeter density,} \\ f &\in C^{0,\gamma} && \text{regularity of volume density.} \end{aligned}$$

Since our final statement in Theorem 1.1 is independent of γ , we may without loss of generality suppose that γ is small, for instance,

$$\gamma < \min \left\{ \frac{\alpha}{2}, \frac{2(1-\alpha)}{2-\alpha} \right\}. \quad (2.1)$$

This choice will slightly simplify our notation later on.

Finally, we conclude this section with a comment on local bounds for the density functions. Since we are assuming that the densities f and h are positive continuous functions, they are in particular locally bounded both from above and away from zero. In particular, for any $T > 0$, there exists a constant $M > 0$ that can be chosen independently from our localization scale $R \leq R_0$ introduced in (1.1) and (1.2) such that

$$\frac{1}{M} \leq f(x', t) \leq M \quad \text{and} \quad \frac{1}{M} \leq h(x', t) \leq M \quad \text{for any } (x', t) \in B_R \times (-T, T). \quad (2.2)$$

We will always choose T large enough so that $\|u\|_{L^\infty(B_R)} \leq T$ uniformly in $R \leq R_0$, which allows for choosing $t = u(x')$. Moreover, as a consequence of the initial regularity statement of Theorem C, the gradient of the constrained minimizer of the weighted surface area functional is locally bounded by a constant $K \geq 1$ that is independent of $R \leq R_0$, i.e.,

$$\|Du\|_{L^\infty(B_R)} \leq K. \quad (2.3)$$

In the rest of the paper, when we write $A \lesssim B$, we mean that there exists a constant c which depends only on $n, K, M, [f]_{C^{0,\gamma}}$ and $[h]_{C^{0,\alpha}}$ (hence, in particular, it is independent of R), such that $A \leq cB$.

3. THE COMPARISON PROBLEM AND BOUNDS ON THE LAGRANGE MULTIPLIER

As outlined in the introduction, we will study the regularity of the boundary of an isoperimetric set with density E by means of classical regularity estimates for the (volume-constrained) minimizer of the weighted surface area functional

$$w \mapsto \int_{B_R} h(x', w) a(Dw) dx',$$

where, for notational convenience, we have used the abbreviation $a(z) := (1 + |z|^2)^{\frac{1}{2}}$ and B_R stands, as before, for an $n - 1$ dimensional Euclidean ball of radius R (that we assume to be centered at 0). The derivation of this functional as the graph representation of the boundary is fairly standard in the context of isoperimetric and minimal surfaces problems, we omit the details. In the following discussion, the minimizer will be denoted by u .

The proof of our main regularity result is based on the derivation of regularity estimates for a comparison problem, in which the density $h(x', w)$ in the surface area functional is frozen to a constant (and thus removed) in order to allow for the application of elliptic regularity arguments in the now computable Euler–Lagrange equations.

A further simplification is achieved by modifying the surface function $a(z)$ for large values of z . In fact, by (2.3), we have that the variational problem remains unchanged if we substitute $a(z)$ by an increasing smooth and strongly convex function $a_K \geq a$ such that

$$a_K(z) = \begin{cases} (1 + |z|^2)^{\frac{1}{2}} & \text{if } |z| \leq K, \\ c_K(1 + |z|^2) & \text{if } |z| \geq 2K, \end{cases}$$

for some constant c_K . Notice that by strong convexity, we mean that there exists a constant $\mu > 0$ such that

$$a_K(z_2) \geq a_K(z_1) + D_z a_K(z_1) \cdot (z_2 - z_1) + \frac{\mu}{2} |z_2 - z_1|^2, \quad (3.1)$$

for any $z_1, z_2 \in \mathbb{R}^{n-1}$. This statement is equivalent to the ellipticity condition

$$\xi \cdot D_z^2 a_K(z) \xi \geq \mu |\xi|^2, \quad (3.2)$$

for any $\xi \in \mathbb{R}^{n-1}$.

Our *comparison problem* is thus the following: We study the problem of minimizing the (Euclidean) perimeter (still in the graph representation)

$$w \mapsto \int_{B_R} a_K(Dw) dx' \quad (3.3)$$

among all functions w with $w = u$ on the boundary ∂B_R which satisfy the weighted volume constraint

$$\int_{B_R} \int_0^{w(x')} f(x', t) dt dx' = \int_{B_R} \int_0^{u(x')} f(x', t) dt dx'. \quad (3.4)$$

With standard compactness arguments, we obtain existence of minimizers of the comparison problem.

Lemma 3.1 (Euler–Lagrange equations). *In the above setting, a minimizer $v \in u + W_0^{1,2}(B_R)$ to the functional (3.3) under the constraint (3.4) always exists. Moreover, every minimizer v satisfies an Euler–Lagrange equation with Lagrange multiplier $\lambda \in \mathbb{R}$: for every $\varphi \in W_0^{1,2}(B_R)$, there holds*

$$\int_{B_R} D_z a_K(Dv(x')) \cdot D\varphi(x') dx' + \lambda \int_{B_R} f(x', v)\varphi(x') dx' = 0. \quad (3.5)$$

Proof. Because $a_K(z)$ has quadratic growth, the direct method yields the existence of a minimizer of the comparison problem (3.3), under the volume constraint (3.4). Moreover, since $a_K(z)$ is differentiable and the constraint is of isoperimetric type, there exists a Lagrange multiplier $\lambda \in \mathbb{R}$ such that (3.5) holds. \square

The following remark shows that the minimizer of the comparison problem reduces locally the Euclidean perimeter.

Remark 3.2 (Energy estimate). *By minimality of v for the comparison problem (3.3) with the volume constraint (3.4), we have, via choice of $a_K \geq a$ and $\|Du\|_{L^\infty} \leq K$*

$$\int_{B_R} a(Dv) dx' \leq \int_{B_R} a_K(Dv) dx' \leq \int_{B_R} a_K(Du) dx' = \int_{B_R} a(Du) dx'.$$

Therefore, in what follows, all estimates can be written in terms of the original minimizer u only. For example, we have for every $p \in [1, 2]$ that $|z|^p \leq c(K)a_K(z)$, and thus

$$\int_{B_R} |Dv|^p dx \leq c(K, n)R^{n-1}.$$

We now derive two elementary estimates for solutions to the Euler–Lagrange equations

$$\operatorname{div} D_z a_K(Dv) = \lambda f(x', v) \quad \text{in } B_R, \quad v = u \quad \text{on } \partial B_R$$

cf. (3.5). Our first is on the Lagrange multiplier.

Lemma 3.3 (First bound on λ). *There exists a constant $R_* = R_*(n, f)$ such that if $R \leq R_0 \leq R_*$ then we have the following estimate for the Lagrange multiplier λ :*

$$|\lambda| \lesssim R^{-1}.$$

In what follows, we will tacitly assume that $R_0 \leq R_*$, so that the statement of Lemma 3.3 is always true.

Proof. This bound could be obtained easily by testing the weak formulation of the Euler–Lagrange equation (3.5) with a suitable cut-off function, if we knew already that the minimizer is bounded uniformly in $R \leq R_0$ in the sense that $\|v\|_{L^\infty(B_R)} \leq T$ for some T , see the discussion after (2.2). Because we know this to be true for original u only, we have to control their difference: Using the Hölder regularity of f , Jensen’s inequality and the Poincaré inequality, we observe that

$$\begin{aligned} \int_{B_R} |f(x', v) - f(x', u)| dx' &\leq [f]_{C^{0,\gamma}} \int_{B_R} |v - u|^\gamma dx' \\ &\leq c(n)[f]_{C^{0,\gamma}} R^{(n-1)\frac{2-\gamma}{2}} \left(\int_{B_R} (v - u)^2 dx' \right)^{\gamma/2} \\ &\leq c(n, [f]_{C^{0,\gamma}}) R^{(n-1)\frac{2-\gamma}{2} + \gamma} \left(\int_{B_R} |Du - Dv|^2 dx' \right)^{\gamma/2}. \end{aligned}$$

Now, thanks to Remark 3.2 and the Lipschitz bound (2.3), the latter leads to

$$\int_{B_R} |f(x', v) - f(x', u)| dx' \leq c(n, [f]_{C^{0,\gamma}}, K) R^{n-1+\gamma}.$$

We finally consider a cut-off function $\eta \in C_0^\infty(B_{3R/4}, [0, 1])$ of radial structure satisfying $\eta \equiv 1$ in $B_{R/2}$ and $|D\eta| \lesssim R^{-1}$. In this way, we find

$$\begin{aligned} |\lambda| &\leq c(n, M)R^{1-n} \left| \lambda \int_{B_{3R/4}} f(x', u)\eta \, dx' \right| \\ &\leq c(n, M)R^{1-n} \left| \int_{B_{3R/4}} D_z a_K(Dv) \cdot D\eta \, dx' \right| + c(n, [f]_{C^{0,\gamma}}, K)|\lambda|R^\gamma, \end{aligned}$$

by the virtue of (2.2), the Euler–Lagrange equations (3.5) and the previous error estimate. Hence if $R \leq R_0$ is sufficiently small so that $c(n, [f]_{C^{0,\gamma}}, K)R_0^\gamma \leq 1/2$ and using $|D_z a_K(z)| \lesssim |z|$ together with Remark 3.2, we conclude that

$$\begin{aligned} |\lambda| &\lesssim R^{1-n} \left| \int_{B_R} D_z a_K(Dv) \cdot D\eta \, dx' \right| \\ &\lesssim R^{1-n} \int_{B_R} |D_z a_K(Dv)| R^{-1} \, dx' \lesssim R^{-1}, \end{aligned} \tag{3.6}$$

which is the desired estimate. \square

The following lemma allows to improve the bound on the Lagrange multiplier from the previous lemma if additional error estimates are available.

Lemma 3.4 (Improved bound on λ). *Suppose that u is $C^{1,\sigma}(B_R)$ and that*

$$\int_{B_R} |Du - Dv|^2 \, dx \lesssim R^{n-1+2\theta} \tag{3.7}$$

for some σ and $\theta \in [0, 1)$, then

$$|\lambda| \lesssim R^{\theta-1} + R^{\sigma-1}.$$

Proof. We take a smooth cut-off function $\eta \in C_0^\infty(B_R, [0, 1])$ satisfying $\eta \equiv 1$ in $B_{R/2}$ and $\|D\eta\|_{L^\infty} \lesssim R^{-1}$. We may choose this function as a test function in the Euler–Lagrange equation (3.5) and find, analogously to (3.6) in the previous proof, that

$$|\lambda|R^{n-1} \lesssim \left| \int_{B_R} D_z a_K(Dv) \cdot D\eta \, dx' \right|.$$

We now use the fact that η is compactly supported to observe that $\int_{B_R} \xi \cdot D\eta \, dx = 0$ for any $\xi \in \mathbb{R}^{n-1}$. In particular, for $\xi = D_z a_K((Du)_R)$, we find that

$$\begin{aligned} |\lambda|R^{n-1} &\lesssim \left| \int_{B_R} (D_z a_K(Dv) - D_z a_K((Du)_R)) \cdot D\eta \, dx' \right| \\ &\lesssim R^{-1} \int_{B_R} |D_z a_K(Dv) - D_z a_K((Du)_R)| \, dx'. \end{aligned}$$

It is easily seen that $D_z a_K$ is Lipschitz with a Lipschitz constant depending just on K . Using in addition the triangle inequality, we thus obtain

$$|\lambda|R^n \lesssim \int_{B_R} |Dv - Du| \, dx' + \int_{B_R} |Du - (Du)_R| \, dx'.$$

For the first term, we use Jensen’s inequality and the hypothesis (3.7) to bound

$$\int_{B_R} |Dv - Du| \, dx \lesssim R^{n-1+\theta}.$$

For the second term, we use the fact that Du is known to be a σ -Hölder function, and thus

$$\int_{B_R} |Du - (Du)_R| dx \lesssim R^{n-1+\sigma}.$$

A combination of the previous bounds yields the statement of the lemma. \square

Our next result is somehow complementary to the previous lemma.

Lemma 3.5 (First error estimate). *Suppose that there exists $\delta \in [0, 1)$ such that*

$$|\lambda| \lesssim R^{\delta-1}.$$

Then,

$$\int_{B_R} |Du - Dv|^2 dx' \lesssim R^{n-1+\frac{2\alpha}{2-\alpha}} + R^{n-1+\frac{2}{1-\gamma}(\gamma+\delta)}. \quad (3.8)$$

Proof. Making use of the strong convexity of a_K , cf. (3.1), and the Euler–Lagrange equation (3.5) for v (tested with $\varphi = u - v$), we find

$$\frac{\mu}{2} \int_{B_R} |Du - Dv|^2 dx' \leq \int_{B_R} (a_K(Du) - a_K(Dv)) dx' + \lambda \int_{B_R} f(x', v(x'))(u(x') - v(x')) dx'. \quad (3.9)$$

Now we estimate the two integrals appearing on the right-hand side separately. We start by noticing that the first integral is nonnegative due to the fact that v is a minimizer. Hence, using in addition the Lipschitz bound on u , the definition of a_K and the lower bound on h , we observe that

$$\begin{aligned} \frac{1}{M} \int_{B_R} (a_K(Du) - a_K(Dv)) dx' &\leq h(0', u(0')) \int_{B_R} (a(Du) - a(Dv)) dx' \\ &= \int_{B_R} (h(0', u(0')) - h(x', u(x')))(a(Du) - a(Dv)) dx' \\ &\quad + \int_{B_R} (h(x', u(x'))a(Du) - h(x', v(x'))a(Dv)) dx' \\ &\quad + \int_{B_R} (h(x', v(x')) - h(x', u(x'))a(Dv)) dx'. \end{aligned}$$

The second term on the right-hand side is non-positive because u is a minimizer for the initial full weighted problem and v is an admissible competitor. Using now that h is Hölder of order α , u is Lipschitz with constant K and a is Lipschitz with constant 1, we can further estimate

$$\begin{aligned} \frac{1}{M} \int_{B_R} (a_K(Du) - a_K(Dv)) dx' \\ \leq (1 + K^\alpha) [h]_{C^{0,\alpha}} \int_{B_R} |x'|^\alpha |Du - Dv| dx' + [h]_{C^{0,\alpha}} \int_{B_R} |v - u|^\alpha a(Dv) dx'. \end{aligned}$$

We estimate with the help of Young's inequality:

$$\begin{aligned} \frac{1}{M} \int_{B_R} (a_K(Du) - a_K(Dv)) dx' \\ \leq \varepsilon \int_{B_R} (|Du - Dv|^2 + R^{-2}|u - v|^2) dx' + C \left(\int_{B_R} |x'|^{2\alpha} dx' + R^{\frac{2\alpha}{2-\alpha}} \int_{B_R} a(Dv)^{\frac{2}{2-\alpha}} dx' \right), \end{aligned}$$

where ε is some small but finite constant that we will fix later and $C = C(\varepsilon, K, \alpha, M, [h]_{C^{0,\alpha}}, n)$ is a constant that may (from here on) change from line to line. Clearly, the second term on the right-hand side is of the order $R^{n-1+2\alpha}$. Moreover, because $a(z)^p \leq C(K)a_K(z)$ for any $p \in [1, 2]$ and thanks to the minimality of v and the Lipschitz bound on u , we have for the third

term that

$$\int_{B_R} a(Dv)^{\frac{2}{2-\alpha}} dx' \lesssim \int_{B_R} a_K(Dv) dx' \leq \int_{B_R} a_K(Du) dx' \leq CR^{n-1}.$$

For $R \leq 1$, we conclude that

$$\frac{1}{M} \int_{B_R} (a_K(Du) - a_K(Dv)) dx' \leq \varepsilon \int_{B_R} (|Du - Dv|^2 + R^{-2}|u - v|^2) dx' + CR^{n-1+\frac{2\alpha}{2-\alpha}}.$$

It remains to estimate the volume constraint term in (3.9). Using the assumption on the Lagrange multiplier, and the fact that u and v satisfy the same volume constraint, we estimate

$$\begin{aligned} |\lambda| & \left| \int_{B_R} f(x', v(x'))(u(x') - v(x')) dx' \right| \\ & \lesssim R^{\delta-1} \left| \int_{B_R} \int_0^{u(x')} f(x', v(x')) dt dx' - \int_{B_R} \int_0^{v(x')} f(x', v(x')) dt dx' \right| \\ & = R^{\delta-1} \left| \int_{B_R} \int_{v(x')}^{u(x')} (f(x', v(x')) - f(x', t)) dt dx' \right|. \end{aligned}$$

We use the γ -Hölder regularity of f and Young's inequality to get

$$\begin{aligned} |\lambda| \left| \int_{B_R} f(x', v(x'))(u(x') - v(x')) dx' \right| & \leq CR^{\delta-1} \int_{B_R} |u(x') - v(x')|^{1+\gamma} dx' \\ & \leq \varepsilon \int_{B_R} R^{-2}|u - v|^2 dx' + CR^{n-1+\frac{2}{1-\gamma}(\gamma+\delta)}. \end{aligned}$$

We have now a bound on both terms appearing on the right-hand side of (3.9). Therefore,

$$\frac{\mu}{2} \int_{B_R} |Du - Dv|^2 dx' \leq 2\varepsilon \int_{B_R} (|Du - Dv|^2 + R^{-2}|u - v|^2) dx' + CR^{n-1+\frac{2\alpha}{2-\alpha}} + CR^{n-1+\frac{2}{1-\gamma}(\gamma+\delta)}.$$

Hence, via Poincaré's inequality and a suitable (small) choice of ε , we end up with (3.8). \square

Iterating Lemma 3.5 and 3.4, we get the following

Corollary 3.6 (Improved error estimate). *Let $u \in C^{1,\sigma}(B_R)$ with $\sigma \leq \frac{\alpha}{2-\alpha}$, then we have that*

$$|\lambda| \lesssim R^{\sigma-1} \tag{3.10}$$

and

$$\int_{B_R} |Du - Dv|^2 dx' \lesssim R^{n-1+\frac{2\alpha}{2-\alpha}} + R^{n-1+\frac{2}{1-\gamma}(\gamma+\sigma)}. \tag{3.11}$$

Proof. By Lemma 3.3 we know that $|\lambda| \lesssim R^{-1}$, hence we can apply Lemma 3.5 with $\delta = 0$ and deduce that

$$\int_{B_R} |Du - Dv|^2 \lesssim R^{n-1+\frac{2\alpha}{2-\alpha}} + R^{n-1+\frac{2\gamma}{1-\gamma}}.$$

Under the assumption (2.1), the second term on the right-hand side is the leading order term for $R \leq 1$. Hence, applying Lemma 3.4 (with $\theta = \frac{\gamma}{1-\gamma}$), we deduce that

$$|\lambda| \lesssim R^{\sigma-1} + R^{\frac{\gamma}{1-\gamma}-1}.$$

If $\frac{\gamma}{1-\gamma} \geq \sigma$, the first bound (3.10) is proved and (3.11) follows directly from Lemma 3.5. Otherwise, we can iterate the above procedure and after a finite number of steps we will reach the estimate

$$|\lambda| \lesssim R^{\sigma-1},$$

which, again, will imply, by using Lemma 3.5, the desired estimate (3.11). \square

4. DECAY ESTIMATES FOR THE COMPARISON PROBLEM

In this section, we establish decay estimates for the solution v of the comparison problem. In getting such estimates, the bound on the Lagrange multiplier λ obtained in the previous section will play a crucial role.

We start, however, with first (suboptimal) Hölder estimates for the minimizer of the comparison problem.

Lemma 4.1. *Let $v \in u + W_0^{1,2}(B_R)$ be a minimizer for the functional (3.3) under the constraint (3.4) in the above setting. Then $v \in W_{loc}^{2,q}(B_R)$ for any $q \in (1, \infty)$, and thus, in particular, it holds $v \in C^{1,\omega}(B_{\frac{R}{2}})$ for any $\omega \in (0, 1)$. Moreover, there are the estimates*

$$\|Dv\|_{L^\infty(B_{\frac{R}{2}})} \lesssim 1 \quad \text{and} \quad [Dv]_{C^{0,\omega}(B_{\frac{R}{2}})} \lesssim R^{-\omega}.$$

The proof of the statement follows from standard elliptic theory. We provide it for the convenience of the reader.

Proof. We start by rewriting the Euler–Lagrange equation as

$$-D_z^2 a_K(Dv) : D^2 v + \lambda f(x', v) = 0 \quad \text{in } B_R,$$

and we recall that $A := D_z^2 a_K(Dv)$ is a uniformly elliptic matrix by the virtue of (3.2). By rescaling

$$x' = R\hat{x}', \quad v(x') = R\hat{v}(\hat{x}'), \quad \lambda = R^{-1}\hat{\lambda}, \quad f(x', v) = \hat{f}(\hat{x}', \hat{v}), \quad A(x') = \hat{A}(\hat{x}'),$$

observing that $[\hat{f}]_{C^{0,\gamma}} = R^\gamma [f]_{C^{0,\gamma}} \lesssim 1$ because $R \leq 1$, and invoking Remarks 3.2 and 3.3, it is enough to consider the case $R = 1$.

We introduce a cut-off function η whose support is compactly contained in B_1 . Smuggling this function into the elliptic equation leads to considering

$$-A : D^2 w + w = -2A : D\eta \otimes Dv - A : (D^2 \eta)v + \eta v - \lambda \eta f(\cdot, v) \quad \text{in } \mathbb{R}^n. \quad (4.1)$$

By the assumptions of the lemma and recalling that f is Hölder continuous, arguing similarly as in the proof of Lemma 3.3, we see that the right-hand side belongs to $L^2(\mathbb{R}^n)$, and thus, by standard theory for elliptic equations, e.g., Theorem 5.1.1 in [22], there exists a unique solution w , which must coincide with ηv by construction, and that solution belongs to $W^{2,2}(\mathbb{R}^n)$. Moreover, thanks to Remarks 3.2 and 3.3 and Poincaré’s inequality, we have the estimate

$$\|D^2 w\|_{L^2} + \|w\|_{L^2} \lesssim 1,$$

by inspection of the right-hand side. Invoking the Sobolev embedding theorem and recalling that w is compactly supported, we deduce that $w \in W^{1,q}(\mathbb{R}^n)$ for any $q \in [1, \frac{2n}{n-2})$ for $n \geq 3$ and any $q \in [1, \infty)$ for $n = 2$, and thus, the right-hand side of (4.1) must be in $L^q(\mathbb{R}^n)$ with norm estimate

$$\|Dw\|_{L^q} + \|w\|_{L^q} \lesssim 1.$$

This procedure can be repeated and we deduce that $w \in W^{2,q}(\mathbb{R}^n)$ for any $q \in (1, \infty)$ eventually. We finally make use of the Sobolev embedding into Hölder spaces to conclude that $w \in C^{1,\omega}(\mathbb{R}^n)$ for any $\omega \in (0, 1)$. Choosing η appropriately gives the statement of the lemma. \square

The following Proposition is the main result of this Section: it establishes decay estimates for the oscillation of $\partial_i v$, being v the solution of the comparison problem introduced in the previous Section.

Proposition 4.2. *Let $u \in C^{1,\sigma}(B_R)$ with $\sigma \leq \frac{\alpha}{2-\alpha}$ and let $v \in u + W_0^{1,2}(B_R)$ be a solution of (3.5), under the volume constraint (3.4). Then there exists $\rho_0 > 0$ of the form $\rho_0 = \varepsilon_0 R$ (with ε_0 depending only on $n, K, M, \alpha, \gamma, [f]_{C^{0,\gamma}}$ and $[h]_{C^{0,\alpha}}$) such that $B_{\rho_0}(x'_0) \subset B_{R/4}$, and for all*

$0 < r < \rho \leq \rho_0$, we have

$$\int_{B_r(x'_0)} |\partial_i v - (\partial_i v)_r|^2 dx' \lesssim \left(\frac{r}{\rho}\right)^{n-1+2(\gamma+\sigma)} \int_{B_\rho(x'_0)} |\partial_i v - (\partial_i v)_\rho|^2 dx' + r^{n-1+2(\gamma+\sigma)},$$

for any $i = 1, \dots, n-1$.

In order to prove the previous result, we will consider the equation satisfied by the derivatives of v (in the weak sense):

$$\operatorname{div} (D_z^2 a_K(Dv) D \partial_i v) = \lambda \partial_i (f(x', v))$$

for every $i \in \{1, \dots, n-1\}$. Thus, each of the functions $\partial_i v$ solves an equation with measurable, elliptic (cf. (3.2)) and bounded coefficients (given by $D_z^2 a_K(Dv)$), where the inhomogeneity is the "derivative" of a function in $L^2(B_R)$. In order to get the desired decay estimates for $\partial_i v$, we need some intermediate decay estimates for the solutions to an associate problem with constant coefficients.

Let $\rho > 0$ be such that $B_\rho(x'_0) \subset B_{R/4}$ and let $A(Dv)$ denote the matrix $D_z^2 a_K(Dv)$ and A_0 the constant matrix obtained by freezing the coefficients in $B_\rho(x'_0)$, more precisely, $A_0 = A((Dv)_{B_\rho(x'_0)})$. Moreover, set $f_0 = f(x'_0, (v)_{B_\rho(x'_0)})$. With these notations, we have the following result.

Lemma 4.3. *Let $u \in C^{1,\sigma}(B_R)$ with $\sigma \leq \frac{\alpha}{2-\alpha}$ and let $w \in \partial_i v + W_0^{1,2}(B_\rho(x'_0))$ be a weak solution of the linear elliptic Dirichlet problem*

$$-\operatorname{div}(A_0 D w) = -\lambda \partial_i (f(x, v) - f_0) \quad \text{in } B_\rho(x'_0).$$

Then, for any $0 < r < \rho$ we have:

$$\int_{B_r(x'_0)} |D w|^2 dx' \lesssim \left(\frac{r}{\rho}\right)^{n-1} \int_{B_\rho(x'_0)} |D w|^2 dx' + R^{2(\sigma-1)} \rho^{n-1+2\gamma}.$$

Proof. For ease of notation, we do not write explicitly the center of the balls. Hence in the following computations B_ρ and B_r stand for $B_\rho(x'_0)$ and $B_r(x'_0)$, respectively.

We write $w = \psi + \phi$ where ψ is the weak solution of the corresponding homogeneous problem

$$\begin{cases} -\operatorname{div}(A_0 D \psi) = 0 & \text{in } B_\rho, \\ \psi = \partial_i v & \text{on } \partial B_\rho, \end{cases}$$

and ϕ satisfies the non-homogeneous problem

$$\begin{cases} -\operatorname{div}(A_0 D \phi) = \lambda \partial_i (f(x, v) - f_0) & \text{in } B_\rho, \\ \phi = 0 & \text{on } \partial B_\rho. \end{cases}$$

By standard decay estimates for the homogeneous equation with constant coefficients (see, e.g., Lemma 2.17 in [6]), we have

$$\int_{B_r} |D \psi|^2 dx' \lesssim \left(\frac{r}{\rho}\right)^{n-1} \int_{B_\rho} |D \psi|^2 dx', \quad (4.2)$$

for any $0 < r < \rho$.

We consider now the nonhomogeneous problem satisfied by ϕ and test it with ϕ itself, to get

$$\begin{aligned} \int_{B_\rho} |D \phi|^2 dx' &\lesssim \lambda^2 \int_{B_\rho} |f(x, v) - f(x_0, (v)_\rho)|^2 dx' \\ &\lesssim R^{2(\sigma-1)} \int_{B_\rho} (|x' - x'_0|^{2\gamma} + |v - (v)_\rho|^{2\gamma}) dx' \\ &\lesssim R^{2(\sigma-1)} \rho^{n-1+2\gamma}, \end{aligned} \quad (4.3)$$

where we have exploited the ellipticity of A_0 in (3.2), used that $f \in C^{0,\gamma}$, that v is Lipschitz with a Lipschitz constant that does not depend on R , see Lemma 4.1, and applied the bound on λ given in Corollary 3.6.

Finally, we combine (4.2) and (4.3), to get

$$\begin{aligned} \int_{B_r} |Dw|^2 dx' &\lesssim \int_{B_r} |D\psi|^2 dx' + \int_{B_r} |D\phi|^2 dx' \\ &\lesssim \left(\frac{r}{\rho}\right)^{n-1} \int_{B_\rho} |D\psi|^2 dx' + R^{2(\sigma-1)} \rho^{n-1+2\gamma} \\ &\lesssim \left(\frac{r}{\rho}\right)^{n-1} \int_{B_\rho} |Dw|^2 dx' + \left(\frac{r}{\rho}\right)^{n-1} \int_{B_\rho} |D\phi|^2 dx' + R^{2(\sigma-1)} \rho^{n-1+2\gamma} \\ &\lesssim \left(\frac{r}{\rho}\right)^{n-1} \int_{B_\rho} |Dw|^2 dx' + R^{2(\sigma-1)} \rho^{n-1+2\gamma}. \end{aligned}$$

This is the stated estimate. \square

We can now give the proof of the decay estimates for our comparison problem.

Proof of Proposition 4.2. Let ρ be such that $B_\rho(x'_0) \subset B_{R/4}$. We shall again neglect the actual center of the ball for notational convenience, that is, $B_r = B_r(x'_0)$ for any $r \leq \rho$ in the following. Let w be as in Lemma 4.3, then we have that the function $\partial_i v - w$ is a weak solution of the following problem:

$$\begin{cases} -\operatorname{div}(A_0 D(\partial_i v - w)) = -\operatorname{div}((A_0 - A(Dv))D\partial_i v) & \text{in } B_\rho, \\ \partial_i v - w = 0 & \text{on } \partial B_\rho. \end{cases}$$

We now test the above equation with $\partial_i v - w$ itself, to get

$$\int_{B_\rho} |D(\partial_i v - w)|^2 dx' \lesssim \int_{B_\rho} |A_0 - A(Dv)|^2 |D\partial_i v|^2 dx' \lesssim \left(\frac{\rho}{R}\right)^{2\omega} \int_{B_\rho} |D\partial_i v|^2 dx', \quad (4.4)$$

where we have used that A_0 is elliptic (3.2), A is Lipschitz and Dv is ω -Hölder continuous with $[Dv]_{C^{0,\omega}} \lesssim R^{-\omega}$ by Lemma 4.1. Thus, we have

$$\begin{aligned} \int_{B_r} |D\partial_i v|^2 dx' &\lesssim \int_{B_r} |Dw|^2 dx' + \int_{B_r} |D(\partial_i v - w)|^2 dx' \\ &\lesssim \left(\frac{r}{\rho}\right)^{n-1} \int_{B_\rho} |Dw|^2 dx' + \int_{B_\rho} |D(\partial_i v - w)|^2 dx' + R^{2(\sigma-1)} \rho^{n-1+2\gamma} \\ &\lesssim \left(\frac{r}{\rho}\right)^{n-1} \int_{B_\rho} |D\partial_i v|^2 dx' + \int_{B_\rho} |D(\partial_i v - w)|^2 dx' + R^{2(\sigma-1)} \rho^{n-1+2\gamma} \\ &\lesssim \left(\left(\frac{r}{\rho}\right)^{n-1} + \left(\frac{\rho}{R}\right)^{2\omega} \right) \int_{B_\rho} |D\partial_i v|^2 dx' + R^{2(\sigma-1)} \rho^{n-1+2\gamma}, \end{aligned}$$

where we have used Lemma 4.3 for the second inequality and estimate (4.4) for the last one. Applying now the Poincaré inequality on the left-hand side, we deduce

$$\begin{aligned} \int_{B_r} |\partial_i v - (\partial_i v)_r|^2 dx' &\lesssim r^2 \int_{B_r} |D\partial_i v|^2 dx' \\ &\lesssim r^2 \left(\left(\frac{r}{\rho} \right)^{n-1} + \left(\frac{\rho}{R} \right)^{2\omega} \right) \int_{B_\rho} |D\partial_i v|^2 dx' + r^2 R^{2(\sigma-1)} \rho^{n-1+2\gamma} \quad (4.5) \\ &\lesssim r^2 \left(\left(\frac{r}{\rho} \right)^{n-1} + \left(\frac{\rho}{R} \right)^{2\omega} \right) \int_{B_\rho} |D\partial_i v|^2 + \left(\frac{\rho}{R} \right)^{2(1-\sigma)} \rho^{n-1+2(\gamma+\sigma)}. \end{aligned}$$

We now use a Caccioppoli-type estimate for the equation satisfied by $\partial_i v$ in order to replace the quantity $|D\partial_i v|^2$ on the right-hand side of the previous inequality by the oscillation $|\partial_i v - (\partial_i v)_\rho|^2$. We derive such a Caccioppoli estimate in a standard way, by testing the equation

$$-\operatorname{div}(A(Dv)D\partial_i v) = -\lambda\partial_i(f - f_0)$$

with $\eta^2(\partial_i v - (\partial_i v)_{2\rho})$, where $\eta \in C_0^\infty(B_{2\rho}, [0, 1])$ is a standard cut-off function satisfying $\eta \equiv 1$ in B_ρ and $\|D\eta\|_{L^\infty} \lesssim \rho^{-1}$. In this way we obtain

$$\begin{aligned} \int_{B_\rho} |D\partial_i v|^2 dx' &\leq \int_{B_{2\rho}} \eta^2 |D\partial_i v|^2 dx' \\ &\lesssim \int_{B_{2\rho}} |D\eta|^2 |\partial_i v - (\partial_i v)_{2\rho}|^2 dx' + \lambda^2 \int_{B_{2\rho}} |f - f_0|^2 dx' \quad (4.6) \\ &\lesssim \rho^{-2} \int_{B_{2\rho}} |\partial_i v - (\partial_i v)_{2\rho}|^2 dx' + R^{2(\sigma-1)} \rho^{n-1+2\gamma}, \end{aligned}$$

where we have used an estimate that is almost identical to (4.3) to control the inhomogeneity. (Here, we need that $B_\rho \subset B_{R/4}$.) Plugging (4.6) into (4.5), we conclude the following decay estimate for the oscillation of $\partial_i v$:

$$\begin{aligned} \int_{B_r} |\partial_i v - (\partial_i v)_r|^2 dx' &\lesssim \left(\frac{r}{\rho} \right)^2 \left(\left(\frac{r}{\rho} \right)^{n-1} + \left(\frac{\rho}{R} \right)^{2\omega} \right) \int_{B_{2\rho}} |\partial_i v - (\partial_i v)_{2\rho}|^2 dx' + \left(\frac{\rho}{R} \right)^{2(1-\sigma)} \rho^{n-1+2(\gamma+\sigma)} \\ &\lesssim \left(\left(\frac{r}{\rho} \right)^{n+1} + \left(\frac{\rho}{R} \right)^{2\omega} \right) \int_{B_{2\rho}} |\partial_i v - (\partial_i v)_{2\rho}|^2 dx' + \rho^{n-1+2(\gamma+\sigma)}, \end{aligned}$$

for any $0 < r < \rho$ with $B_\rho(x'_0) \subset B_{R/4}$. Observe that the previous estimate extends trivially to $r \in (\rho, 2\rho)$ thanks to the monotonicity of the oscillation discussed right after Proposition D. Hence, the estimate is valid for any $r < 2\rho$.

For $\varepsilon > 0$ given as in Lemma E, let now ρ_0 be such that $B_{\rho_0}(x'_0) \subset B_{R/4}$ and satisfying

$$\left(\frac{\rho_0}{R} \right)^{2\omega} \leq \varepsilon.$$

It follows that

$$\int_{B_r} |\partial_i v - (\partial_i v)_r|^2 dx' \lesssim \left(\left(\frac{r}{\rho} \right)^{n+1} + \varepsilon \right) \int_{B_\rho} |\partial_i v - (\partial_i v)_\rho|^2 dx' + \rho^{n-1+2(\gamma+\sigma)},$$

holds for any $r < \rho \leq \rho_0$. Finally, we can apply the iteration Lemma E, to deduce the desired decay estimate for $\partial_i v$ and conclude the proof of the proposition. \square

5. PROOF OF THE REGULARITY RESULT

We are now ready to prove our main result. The idea consists in transferring the oscillation decay estimate from Proposition 4.2 for the comparison function v to our minimizer u , by making use of the error estimate from Lemma 3.5.

Proof of Theorem 1.1. As already discussed in the introduction, the optimal bound on the dimension of the singular set follows by the classical regularity theory for ω -minimal sets established in [30]. Indeed, in [12, 29], it was proved that, under our assumption, any isoperimetric set is ω -minimal with $\omega(r) = r^{2\sigma}$, being $\sigma = \alpha/(2n(1-\alpha) + 2\alpha)$. It remains, thus, to show the optimal regularity of the reduced boundary.

Let u be the local representation of ∂^*E , i.e., the solution of our weighted minimization problem (1.1) under the weighted volume constraint (1.2), which initially enjoys the regularity $u \in C^{1,\sigma}(B_R)$ with $\sigma = \alpha/(2n(1-\alpha) + 2\alpha)$ according to Theorem C, and let v be the comparison function studied in the previous section. Using Proposition 4.2, and Corollary 3.6, we deduce that

$$\begin{aligned} & \int_{B_r} |\partial_i u - (\partial_i u)_r|^2 dx' \\ & \lesssim \int_{B_r} |\partial_i v - (\partial_i v)_r|^2 dx' + \int_{B_R} |Du - Dv|^2 dx' \\ & \lesssim \left(\frac{r}{\rho}\right)^{n-1+2(\gamma+\sigma)} \int_{B_\rho} |\partial_i v - (\partial_i v)_\rho|^2 dx' + r^{n-1+2(\gamma+\sigma)} + R^{n-1+\frac{2\alpha}{2-\alpha}} + R^{n-1+\frac{2}{1-\gamma}(\gamma+\sigma)}, \end{aligned} \quad (5.1)$$

for any $0 < r < \rho \leq \rho_0 = \varepsilon_0 R$.

Via another application of Corollary 3.6 and using that $r \leq R \leq 1$, this implies the following oscillation decay for $\partial_i u$:

$$\begin{aligned} & \int_{B_r} |\partial_i u - (\partial_i u)_r|^2 dx' \\ & \lesssim \left(\frac{r}{\rho}\right)^{n-1+2(\gamma+\sigma)} \int_{B_\rho} |\partial_i u - (\partial_i u)_\rho|^2 dx' + R^{n-1+2\min\{\gamma+\sigma, \frac{\alpha}{2-\alpha}\}}, \end{aligned}$$

for any $0 < r < \rho \leq \rho_0$. We choose now $\rho = \rho_0 = \varepsilon_0 R$, and deduce that

$$\begin{aligned} & \int_{B_r} |\partial_i u - (\partial_i u)_r|^2 dx' \\ & \lesssim \left(\frac{r}{R}\right)^{n-1+2(\gamma+\sigma)} \int_{B_{\varepsilon_0 R}} |\partial_i u - (\partial_i u)_{\varepsilon_0 R}|^2 dx' + R^{n-1+2\min\{\gamma+\sigma, \frac{\alpha}{2-\alpha}\}} \\ & \lesssim \left(\frac{r}{R}\right)^{n-1+2(\gamma+\sigma)} \int_{B_R} |\partial_i u - (\partial_i u)_R|^2 dx' + R^{n-1+2\min\{\omega, \frac{\alpha}{2-\alpha}\}}, \end{aligned}$$

for any $0 < r \leq \varepsilon_0 R$, where $\omega = \gamma + \sigma - \delta > \sigma$ for any $\delta \in (0, 1)$ small. We may choose $\omega = \frac{\gamma}{2} + \sigma$. The same estimate trivially extends to $r \in (\varepsilon_0 R, R)$ and thus holds for any $0 < r < R$.

We can now apply again the iteration Lemma E, to get

$$\int_{B_r(x'_0)} |\partial_i u - (\partial_i u)_r|^2 dx' \lesssim \left(\frac{r}{R}\right)^{n-1+2\min\{\omega, \frac{\alpha}{2-\alpha}\}} \int_{B_R} |\partial_i u - (\partial_i u)_r|^2 dx' + r^{n-1+2\min\{\omega, \frac{\alpha}{2-\alpha}\}}.$$

Finally, by Proposition D, we deduce that $u \in C^{1, \min\{\frac{\alpha}{2-\alpha}, \omega\}}$. If $\omega = \frac{\gamma}{2} + \sigma \geq \frac{\alpha}{2-\alpha}$ the proof is completed. Otherwise we can iterate the above reasoning: setting $\sigma_j := \sigma + \frac{j\gamma}{2}$, we can iteratively apply Proposition 4.2 and Corollary 3.6, with $u \in C^{1, \sigma_j}$ and plug the new improved estimate (3.11) (with $\sigma_j > \sigma$ in place of σ) into (5.1). After a finite number N of steps (in

particular when $N\gamma/2 + \sigma \geq \frac{\alpha}{2-\alpha}$) we reach the exponent $\frac{\alpha}{2-\alpha}$. This concludes the proof of Theorem 1.1. \square

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