FAILURE OF CURVATURE-DIMENSION CONDITIONS ON SUB-RIEMANNIAN MANIFOLDS VIA TANGENT ISOMETRIES

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ABSTRACT. We prove that, on any sub-Riemannian manifold endowed with a positive smooth measure, the Bakry–Émery inequality for the corresponding sub-Laplacian,

$$\frac{1}{2}\Delta(\|\nabla u\|^2) \ge g(\nabla u, \nabla \Delta u) + K \|\nabla u\|^2, \quad K \in \mathbb{R},$$

implies the existence of enough Killing vector fields on the tangent cone to force the latter to be Euclidean at each point, yielding the failure of the curvature-dimension condition in full generality. Our approach does not apply to non-strictly-positive measures. In fact, we prove that the weighted Grushin plane does not satisfy any curvature-dimension condition, but, nevertheless, does admit an a.e. pointwise version of the Bakry–Émery inequality. As recently observed by Pan and Montgomery, one half of the weighted Grushin plane satisfies the $\mathsf{RCD}(0, N)$ condition, yielding a counterexample to gluing theorems in the RCD setting.

1. INTRODUCTION AND STATEMENTS

In the last twenty years, there has been an impressive effort in extending the concept of 'Ricci curvature lower bound' to non-Riemannian structures, and even to general metric spaces equipped with a measure (metric-measure spaces, for short). We refer the reader to the ICM notes [3] for a survey of this line of research.

There are two distinct points of view on the matter, traditionally known as the *Lagrangian* and *Eulerian* approaches, respectively.

The Lagrangian point of view is the one adopted by Lott–Villani and Sturm [36, 48, 49]. In this formulation, Ricci curvature lower bounds are encoded by convexity-type inequalities for entropy functionals on the Wasserstein space. Such inequalities are called *curvature-dimension* conditions, CD(K, N) for short, where $K \in \mathbb{R}$ represents the lower bound on the curvature and $N \in [1, \infty]$ stands for an upper bound on the dimension.

The Eulerian point of view, instead, employs the metric-measure structure to define an energy form and, in turn, an associated diffusion operator. The notion of Ricci curvature lower bound is therefore encoded in the so-called *Bakry–Émery inequality*, $\mathsf{BE}(K, N)$ for short, for the diffusion operator, which can be expressed in terms of a suitable *Gamma calculus*, see the monograph [10].

Thanks to several key contributions [4, 6, 7, 24], the Lagrangian and the Eulerian approaches are now known to be essentially equivalent. In particular, CD(K, N) always

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implies $\mathsf{BE}(K, N)$ in *infinitesimal Hilbertian* metric-measure spaces, as introduced in [25], while the converse implication requires further technical assumptions.

Such synthetic theory of curvature-dimension conditions, besides being consistent with the classical notions of Ricci curvature and dimension on smooth Riemannian manifolds, is stable under pointed-measure Gromov–Hausdorff convergence. Furthermore, it yields a comprehensive approach for establishing all results typically associated with Ricci curvature lower bounds, like Poincaré, Sobolev, log-Sobolev and Gaussian isoperimetric inequalities, as well as Brunn–Minkowski, Bishop–Gromov and Bonnet–Myers inequalities.

1.1. The sub-Riemannian framework. Although the aforementioned synthetic curvature-dimension conditions embed a large variety of metric-measure spaces, a relevant and widely-studied class of smooth structures is left out—the family of *sub-Riemannian manifolds*. A sub-Riemannian structure is a natural generalization of a Riemannian one, in the sense that its distance is induced by a scalar product that is defined only on a smooth sub-bundle of the tangent bundle, whose rank possibly varies along the manifold. See the monographs [2, 40, 45] for a detailed presentation.

The first result in this direction was obtained by Driver–Melcher [23], who proved that an integrated version of the $\mathsf{BE}(K,\infty)$, the so-called *pointwise gradient estimate* for the heat flow, is false for the three-dimensional *Heisenberg group*.

In [31], Juillet proved the failure of the $CD(K, \infty)$ property for all Heisenberg groups (and even for the strictly related *Grushin plane*, see [32]). Later, Juillet [33] extended his result to any sub-Riemannian manifold endowed with a possibly rank-varying distribution of rank *strictly* smaller than the manifold's dimension, and with any positive smooth measure, by exploiting the notion of *ample curves* introduced in [1]. The idea of [31,33] is to construct a counterexample to the *Brunn–Minkowski inequality*.

The 'no-CD theorem' of [31] was extended to all *Carnot groups* by Ambrosio and the second-named author in [8, Prop. 3.6] with a completely different technique, namely, by exploiting the optimal version of the *reverse Poincaré inequality* obtained in [16].

In the case of sub-Riemannian manifolds endowed with an *equiregular distribution* and a positive smooth measure, Huang–Sun [29] proved the failure of the CD(K, N) condition for all values of $K \in \mathbb{R}$ and $N \in (1, \infty)$ contradicting a bi-Lipschitz embedding result.

Very recently, in order to address the structures left out in [33], Magnabosco–Rossi [37] recently extended the 'no-CD theorem' to *almost-Riemannian manifolds M* of dimension 2 or *strongly regular*. The approach of [37] relies on the localization technique developed by Cavalletti–Mondino [19] in metric-measure spaces.

To complete the picture, we mention that several replacements for the Lott–Sturm– Villani curvature-dimension property have been proposed and studied in the sub-Riemannian framework in recent years. Far from being complete, we refer the reader to [11–15,38] for an account on the Lagrangian approach, to [17] concerning the Eulerian one, and finally to [47] for a first link between entropic inequalities and contraction properties of the heat flow in the special setting of metric-measure groups.

Main aim. At the present stage, a 'no-CD theorem' for sub-Riemannian structures in full generality is missing, since the aforementioned approaches [8, 23, 29, 31, 33, 37] either require the ambient space to satisfy some structural assumptions, or leave out the infinite dimensional case $N = \infty$.

The main aim of the present paper is to fill this gap by showing that (possibly rankvarying) sub-Riemannian manifolds do not satisfy any curvature bound in the sense of Lott–Sturm–Villani or Bakry–Émery when equipped with a positive smooth measure, i.e., a Radon measure whose density in local charts with respect to the Lebesgue measure is a strictly positive smooth function.

1.2. Failure of the Bakry–Émery inequality. The starting point of our strategy is the weakest curvature-dimension condition, as we now define.

Definition 1.1 (Bakry-Émery inequality). We say that a sub-Riemannian manifold (M, d) endowed with a positive smooth measure **m** satisfies the *Bakry-Émery* $\mathsf{BE}(K, \infty)$ inequality, for $K \in \mathbb{R}$, if

$$\frac{1}{2}\Delta(\|\nabla u\|^2) \ge g(\nabla u, \nabla \Delta u) + K \|\nabla u\|^2 \quad \text{for all } u \in C^{\infty}(M), \tag{1.1}$$

where Δ is the corresponding sub-Laplacian, and ∇ the sub-Riemannian gradient.

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Our first main result is the following rigidity property for sub-Riemannian structures supporting the Bakry–Émery inequality (1.1).

Theorem 1.2 (no-BE). Let (M, d) be a complete sub-Riemannian manifold endowed with a positive smooth measure m. If (M, d, m) satisfies the $BE(K, \infty)$ inequality for some $K \in \mathbb{R}$, then rank $\mathscr{D}_x = \dim M$ at each $x \in M$, so that (M, d) is Riemannian.

The idea behind our proof of Theorem 1.2 is to show that the *metric tangent cone* in the sense of Gromov [26] at each point of (M, d) is Euclidean. This line of thought is somehow reminiscent of the deep structural result for $\mathsf{RCD}(K, N)$ spaces, with $K \in \mathbb{R}$ and $N \in (1, \infty)$, proved by Mondino–Naber [39]. However, differently from [39], Theorem 1.2 provides information about the metric tangent cone at *each* point of the manifold. Showing that the distribution \mathscr{D} is Riemannian at *almost every* point in fact would not be enough, as this would not rule out almost-Riemannian structures.

Starting from (1.1), we first blow-up the sub-Riemannian structure and pass to its metric-measure tangent cone, showing that (1.1) is preserved with K = 0. Note that, in this blow-up procedure, the positivity of the density of **m** is crucial, since otherwise the resulting metric tangent cone would be endowed with the null measure.

The resulting blown-up sub-Riemannian space is isometric to a homogeneous space of the form G/H, where $G = \exp \mathfrak{g}$ is the Carnot group associated to the underlying (finite-dimensional and stratified) Lie algebra \mathfrak{g} of bracket-generating vector fields, and $H = \exp \mathfrak{h}$ is its subgroup corresponding to the Lie subalgebra \mathfrak{h} of vector fields vanishing at the origin, see [18]. Of course, the most difficult case is when H is non-trivial, that is, the tangent cone is not a Carnot group.

At this point, the key idea is to show that the Bakry-Émery inequality $\mathsf{BE}(K,\infty)$ implies the existence of special isometries on the tangent cone.

Definition 1.3 (Sub-Riemannian isometries). Let M be a sub-Riemannian manifold, with distribution \mathscr{D} and metric g. A diffeomorphism $\phi: M \to M$ is an *isometry* if

$$(\phi_*\mathscr{D})|_x = \mathscr{D}_{\phi(x)} \quad \text{for all } x \in M,$$
 (1.2)

and, furthermore, ϕ_* is an orthogonal map with respect to g. We say that a smooth vector field V is *Killing* if its flow ϕ_t^V is an isometry for all $t \in \mathbb{R}$.

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For precise definitions of \mathfrak{g} and \mathfrak{h} in the next statement, we refer to Section 2.4.

Theorem 1.4 (Existence of Killing fields). Let (M, d) be a complete sub-Riemannian manifold equipped with a positive smooth measure m If (M, d, m) satisfies the $BE(K, \infty)$ inequality for some $K \in \mathbb{R}$, then, for the nilpotent approximation at any given point, there exists a vector space $i \subset g^1$ such that

$$\mathfrak{g}^1 = \mathfrak{i} \oplus \mathfrak{h}^1 \tag{1.3}$$

and every $Y \in \mathfrak{i}$ is a Killing vector field.

The existence of the space of isometries i forces the Lie algebra \mathfrak{g} to be commutative and of maximal rank, thus implying that the original manifold (M, d) was in fact Riemannian.

Theorem 1.5 (Killing implies commutativity). If there exists a subspace $\mathfrak{i} \subset \mathfrak{g}^1$ of Killing vector fields such that $\mathfrak{g}^1 = \mathfrak{i} \oplus \mathfrak{h}^1$, then \mathfrak{g} is commutative.

Theorem 1.5 states that, if a Carnot group contains enough *horizontal symmetries*, then it must be commutative. As it will be evident from its proof, Theorem 1.5 holds simply assuming that, for each $V \in \mathbf{i}$, the flow ϕ_t^V is pointwise distribution-preserving, namely it satisfies (1.2), without being necessarily isometries.

1.3. Infinitesimal Hilbertianity. The Bakry–Émery inequality $\mathsf{BE}(K, \infty)$ in (1.1) is a consequence of the $\mathsf{CD}(K, \infty)$ condition as soon as the ambient metric-measure space is infinitesimal Hilbertian as defined in [25].

Let (X, d) be a complete separable metric space, m be a locally bounded Borel measure, and $q \in [1, \infty)$. We let $|\mathsf{D}u|_{w,q} \in L^q(X, \mathsf{m})$ be the *minimal q-upper gradient* of a measurable function $u: X \to \mathbb{R}$, see [5, Sec. 4.4]. We define the Banach space

$$W^{1,q}(X,\mathsf{d},\mathsf{m}) = \{ u \in L^q(X,\mathsf{m}) : |\mathsf{D}u|_{w,q} \in L^q(X,\mathsf{m}) \}$$

with the norm

$$||u||_{\mathbf{W}^{1,q}(X,\mathsf{d},\mathsf{m})} = \left(||u||_{\mathbf{L}^{q}(X,\mathsf{m})}^{q} + |||\mathsf{D}u|_{w,q}||_{\mathbf{L}^{q}(X,\mathsf{m})}^{q}\right)^{1/q}.$$

Definition 1.6 (Infinitesimal Hilbertianity). A metric measure space $(X, \mathsf{d}, \mathsf{m})$ is *in-finitesimally Hilbertian* if $W^{1,2}(X, \mathsf{d}, \mathsf{m})$ is a Hilbert space.

The infinitesimal Hilbertianity of sub-Riemannian structures has been recently proved in [35], with respect to any Radon measure. In particular, Theorem 1.2 immediately yields the following 'no-CD theorem' for sub-Riemannian manifolds, thus extending all the aforementioned results [8, 23, 29, 31, 33, 37].

Corollary 1.7 (no-CD). Let (M, d) be a complete sub-Riemannian manifold endowed with a positive smooth measure m. If (M, d, m) satisfies the $CD(K, \infty)$ condition for some $K \in \mathbb{R}$, then (M, d) is Riemannian.

However, since the measure in Corollary 1.7 is positive and smooth, we can avoid to rely on the general result of [35], instead providing a simpler and self-contained proof of the infinitesimal Hilbertianity property. In particular, we prove the following result, which actually refines [35, Th. 5.6] in the case of smooth measures. In the following, $HW^{1,q}(M, \mathbf{m})$ denotes the sub-Riemannian Sobolev spaces (see Section 2.2).

Theorem 1.8 (Infinitesimal Hilbertianity). Let $q \in (1, \infty)$. Let (M, d) be a complete sub-Riemannian manifold equipped with a positive smooth measure m. The following hold.

- (i) $W^{1,q}(M, \mathsf{d}, \mathsf{m}) = HW^{1,q}(M, \mathsf{m})$, with $|\mathsf{D}u|_{w,q} = ||\nabla u||$ m-a.e. on M for all $u \in W^{1,q}(M, \mathsf{d}, \mathsf{m})$. In particular, taking q = 2, $(M, \mathsf{d}, \mathsf{m})$ is infinitesimally Hilbertian.
- (ii) If $(M, \mathsf{d}, \mathsf{m})$ satisfies the $\mathsf{CD}(K, \infty)$ condition for some $K \in \mathbb{R}$, then the Bakry-Émery $\mathsf{BE}(K, \infty)$ inequality (1.1) holds on M.

Note that Theorem 1.8 holds for less regular measures, see Remark 3.6.

Remark 1.9 (The case of a.e. smooth measures). Theorem 1.8 can be adapted also to the case of a Borel and locally finite measure **m** which is smooth and positive only on $\overline{\Omega}$, where $\Omega \subset M$ is an open set with $\mathsf{m}(\partial\Omega) = 0$. In this case, we obtain $\mathrm{HW}^{1,q}(\Omega,\mathsf{m}) =$ $\mathrm{W}^{1,q}(\overline{\Omega},\mathsf{d},\mathsf{m})$, with $|\mathsf{D}u|_{w,q} = ||\nabla u||$ m-a.e. on Ω for all $u \in \mathrm{W}^{1,q}(\overline{\Omega},\mathsf{d},\mathsf{m})$. In particular, if **m** is smooth and positive out of a closed set \mathcal{Z} , with $\mathsf{m}(\mathcal{Z}) = 0$, an elementary approximation argument proves that $(M,\mathsf{d},\mathsf{m})$ is infinitesimally Hilbertian and, if $(M,\mathsf{d},\mathsf{m})$ satisfies the $\mathsf{CD}(K,\infty)$ condition for $K \in \mathbb{R}$, then the Bakry-Émery $\mathsf{BE}(K,\infty)$ inequality (1.1) holds on $M \setminus \mathcal{Z}$. This is the case, for example, of the Grushin planes and half-planes with weighted measures of Section 1.5. The proof follows the same argument of the one of Theorem 1.8, exploiting the locality of the q-upper gradient, see for example [5, Sec. 8.2] and [25, Prop. 2.6], and similar properties for the distributional derivative.

1.4. An alternative approach to the 'no-CD theorem'. We mention an alternative proof of the 'no-CD theorem' for almost-Riemannian structures (i.e., sub-Riemannian structures that are Riemannian outside a closed nowhere dense singular set). The strategy relies on the Gromov-Hausdorff continuity of the metric tangent at interior points of geodesics in $\mathsf{RCD}(K, N)$ spaces, with $N < \infty$, proved by Deng in [22],

For example, consider the standard Grushin plane (introduced in Section 1.5) equipped with a smooth positive measure. The curve $\gamma(t) = (t, 0), t \in \mathbb{R}$, is a geodesic between any two of its point. The metric tangent at $\gamma(t)$ is (isometric to) the Euclidean plane for every $t \neq 0$, while it is (isometric to) the Grushin plane itself for t = 0. Since the Grushin plane cannot be bi-Lipschitz embedded into the Euclidean plane, the two spaces are at positive Gromov-Hausdorff distance, contradicting the continuity result.

This strategy has a few drawbacks. On the one hand, it relies on the (non-trivial) machinery developed in [22]. Consequently, this argument does not work in the case $N = \infty$. On the other hand, the formalization of this strategy for general almost-Riemannian structures requires certain quantitative bi-Lipschitz non-embedding results for almost-Riemannian structures into Euclidean spaces, which we are able to prove only under the same assumptions of [37].

1.5. Weighted Grushin structures. When the density of the smooth measure is allowed to vanish, the 'no-CD theorem' breaks down. In fact, in this situation, the following two interesting phenomena occur:

- (A) the Bakry-Émery $\mathsf{BE}(K,\infty)$ inequality no longer implies the $\mathsf{CD}(K,\infty)$ condition;
- (B) there exist almost-Riemannian structures with boundary satisfying the CD(0, N) condition for $N \in [1, \infty]$.

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We provide examples of both phenomena on the so-called *weighted Grushin plane*. This is the sub-Riemannian structure on \mathbb{R}^2 induced by the family $\mathscr{F} = \{X, Y\}$, where

$$X = \partial_x, \quad Y = x \,\partial_y, \quad (x, y) \in \mathbb{R}^2.$$
 (1.4)

The induced distribution $\mathscr{D} = \operatorname{span}\{X, Y\}$ has maximal rank outside the singular region $S = \{x = 0\}$ and rank 1 on S. Since $[X, Y] = \partial_y$ on \mathbb{R}^2 , the resulting sub-Riemannian metric space $(\mathbb{R}^2, \mathsf{d})$ is Polish and geodesic. It is *almost-Riemannian* in the sense that, out of S, the metric is locally equivalent to the Riemannian one given by the metric tensor

$$g = dx \otimes dx + \frac{1}{x^2} dy \otimes dy, \quad x \neq 0.$$
(1.5)

We endow the metric space $(\mathbb{R}^2, \mathsf{d})$ with the weighted Lebesgue measure

$$\mathsf{m}_p = |x|^p \,\mathrm{d}x \,\mathrm{d}y,$$

where $p \in \mathbb{R}$ is a parameter. The choice p = -1 corresponds to the Riemannian density

$$\operatorname{vol}_{g} = \frac{1}{|x|} \, \mathrm{d}x \, \mathrm{d}y, \quad x \neq 0, \tag{1.6}$$

so that

$$\mathbf{m}_p = e^{-V} \operatorname{vol}_g, \quad V(x) = -(p+1) \log |x|, \quad x \neq 0.$$
 (1.7)

We call the metric-measure space $\mathbb{G}_p = (\mathbb{R}^2, \mathsf{d}, \mathsf{m}_p)$ the *(p-)weighted Grushin plane*.

We can now state the following result, illustrating phenomenon (A).

Theorem 1.10. Let $p \in \mathbb{R}$ and let $\mathbb{G}_p = (\mathbb{R}^2, \mathsf{d}, \mathsf{m}_p)$ be the weighted Grushin plane.

- (i) If $p \ge 0$, then \mathbb{G}_p does not satisfy the $\mathsf{CD}(K, \infty)$ property for all $K \in \mathbb{R}$.
- (ii) If $p \ge 1$, then \mathbb{G}_p satisfies the $\mathsf{BE}(0,\infty)$ inequality (1.1) almost everywhere.

To prove (i), we show that the corresponding Brunn–Minkowski inequality is violated. In fact, the case p = 0 is due to Juillet [32], while the case p > 0 can be achieved via a simple argument which was pointed out to us by J. Pan. Claim (ii), instead, is obtained by direct computations.

Somewhat surprisingly, the weighted Grushin half-plane \mathbb{G}_p^+ —obtained by restricting the metric-measure structure of \mathbb{G}_p to the (closed) half-plane $[0, \infty) \times \mathbb{R}$ —does satisfy the $\mathsf{CD}(0, N)$ condition for sufficiently large $N \in [1, \infty]$. Precisely, we can prove the following result, illustrating phenomenon (B).

Theorem 1.11. Let $p \ge 1$. The weighted Grushin half-plane \mathbb{G}_p^+ satisfies the $\mathsf{CD}(0, N)$ condition if and only if $N \ge N_p$, where $N_p \in (2, \infty]$ is given by

$$N_p = \frac{(p+1)^2}{p-1} + 2, \tag{1.8}$$

with the convention that $N_1 = \infty$. Furthermore, \mathbb{G}_p^+ is infinitesimally Hilbertian, and it is thus an $\mathsf{RCD}(0, N)$ space for $N \ge N_p$.

While we were completing this work, Pan and Montgomery [41] observed that the spaces built in [20, 42] as *Ricci limits* are actually the weighted Grushin half-spaces presented above. Our construction and method of proof are more direct with respect to the approach of [20, 42], and easily yield sharp dimensional bounds. 1.6. Counterexample to gluing theorems. We end this introduction with an interesting by-product of our analysis, in in connection with the so-called *gluing theorems*.

Perelman's Doubling Theorem [43, Sect. 5.2] states that a finite dimensional Alexandrov space with a curvature lower bound can be doubled along its boundary yielding an Alexandrov space with *same* curvature lower bound and dimension. This result has been extended by Petrunin [44, Th. 2.1] to the gluing of Alexandrov spaces.

It is interesting to understand whether these classical results hold true for general metric-measure spaces satisfying synthetic Ricci curvature lower bounds in the sense of Lott–Sturm–Villani. In [34], the gluing theorem was proved for CD(K, N) spaces with Alexandrov curvature bounded from below (while it is false for MCP spaces, see [46]).

Here we obtain that, in general, the assumption of Alexandrov curvature bounded from below cannot be removed from the results in [34]. More precisely, Theorems 1.10 and 1.11, and the fact that the metric-measure double of the Grushin half-plane \mathbb{G}_p^+ is \mathbb{G}_p (see [46, Prop. 6]) yield the following corollary.

Corollary 1.12 (Counterexample to gluing in RCD spaces). For all $N \ge 10$, there exists a geodesically convex $\mathsf{RCD}(0, N)$ metric-measure space with boundary such that its metric-measure double does not satisfy the $\mathsf{CD}(K, \infty)$ condition for any $K \in \mathbb{R}$.

In [34, Conj. 1.6], the authors conjecture the validity of the gluing theorem for noncollapsed $\mathsf{RCD}(K, N)$, with N the Hausdorff dimension of the metric-measure space. As introduced in [21], a non-collapsed $\mathsf{RCD}(K, N)$ space is an infinitesimally Hilbertian $\mathsf{CD}(K, N)$ space with $\mathsf{m} = \mathscr{H}^N$, where \mathscr{H}^N denotes the N-dimensional Hausdorff measure of (X, d) . Since the weighted half-Grushin spaces are indeed collapsed, Corollary 1.12 also shows that the non-collapsing assumption cannot be removed from [34, Conj. 1.6].

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2. Preliminaries

In this section, we introduce some notation and recall some results about sub-Riemannian manifolds and curvature-dimension conditions.

2.1. Sub-Riemannian structures. For $L \in \mathbb{N}$, we let $\mathscr{F} = \{X_1, \ldots, X_L\}$ be a family of smooth vector fields globally defined on a smooth *n*-dimensional manifold $M, n \geq 2$. The (generalized) sub-Riemannian distribution induced by the family \mathscr{F} is defined by

$$\mathscr{D} = \bigsqcup_{x \in M} \mathscr{D}_x, \quad \mathscr{D}_x = \operatorname{span}\{X_1|_x, \dots, X_L|_x\} \subset T_x M, \quad x \in M.$$
(2.1)

Note that we do not require the dimension of \mathscr{D}_x to be constant as $x \in M$ varies, that is, we may consider *rank-varying* distributions. With a standard abuse of notation, we let

$$\Gamma(\mathscr{D}) = C^{\infty}$$
-module generated by \mathscr{F} .

Notice that, for any smooth vector field V, it holds

$$V \in \Gamma(\mathscr{D}) \implies V_x \in \mathscr{D}_x \text{ for all } x \in M,$$

but the converse is false in general. We let

$$||V||_x = \min\left\{|u|: u \in \mathbb{R}^L \text{ such that } V = \sum_{i=1}^L u_i X_i|_x, \ X_i \in \mathscr{F}\right\}$$
(2.2)

whenever $V \in \mathscr{D}$ and $x \in M$. The norm $\|\cdot\|_x$ induced by the family \mathscr{F} satisfies the parallelogram law and, consequently, it is induced by a scalar product

$$g_x \colon \mathscr{D}_x \times \mathscr{D}_x \to \mathbb{R}$$

An admissible curve is a locally Lipschitz in charts path $\gamma \colon [0,1] \to M$ such that there exists a control $u \in L^{\infty}([0,1]; \mathbb{R}^L)$ such that

$$\dot{\gamma}(t) = \sum_{i=1}^{L} u_i(t) X_i|_{\gamma(t)}$$
 for a.e. $t \in [0, 1]$.

The *length* of an admissible curve γ is defined via the norm (2.2) as

$$\operatorname{length}(\gamma) = \int_0^1 \|\dot{\gamma}(t)\|_{\gamma(t)} \,\mathrm{d}t$$

and the Carnot-Carathéodory (or sub-Riemannian) distance between $x, y \in M$ is

 $\mathsf{d}(x,y) = \inf\{ \operatorname{length}(\gamma) : \gamma \text{ admissible with } \gamma(0) = x, \ \gamma(1) = y \}.$

We assume that the family \mathscr{F} satisfies the bracket-generating condition

$$T_x M = \{X|_x : X \in \operatorname{Lie}(\mathscr{F})\} \quad \text{for all } x \in M,$$
(2.3)

where $\text{Lie}(\mathscr{F})$ is the smallest Lie subalgebra of vector fields on M containing \mathscr{F} , namely,

$$\operatorname{Lie}(\mathscr{F}) = \operatorname{span}\left\{ [X_{i_1}, \dots, [X_{i_{j-1}}, X_{i_j}]] : X_{i_\ell} \in \mathscr{F}, \ j \in \mathbb{N} \right\}$$

Under the assumption (2.3), the Chow–Rashevskii Theorem implies that d is a well-defined finite distance on M inducing the same topology of the ambient manifold.

2.2. Gradient, sub-Laplacian and Sobolev spaces. The gradient of a function $u \in C^{\infty}(M)$ is the unique vector field $\nabla u \in \Gamma(\mathscr{D})$ such that

$$g(\nabla u, V) = du(V)$$
 for all $V \in \Gamma(\mathscr{D})$. (2.4)

One can check that ∇u can be globally represented as

$$\nabla u = \sum_{i=1}^{L} X_i u X_i, \quad \text{with} \quad \|\nabla u\|^2 = \sum_{i=1}^{L} (X_i u)^2, \tag{2.5}$$

even if the family \mathscr{F} is not linearly independent, see Corollary A.2 for a proof.

We equip the manifold M with a *positive smooth* measure \mathbf{m} . The *sub-Laplacian* of a function $u \in C^{\infty}(M)$ is the unique function $\Delta u \in C^{\infty}(M)$ such that

$$\int_{M} g(\nabla u, \nabla v) \, \mathrm{d}\mathbf{m} = -\int_{M} v \, \Delta u \, \mathrm{d}\mathbf{m}$$
(2.6)

for all $v \in C_c^{\infty}(M)$. On can check that Δu can be globally represented as

$$\Delta u = \sum_{i=1}^{L} \left(X_i^2 u + X_i u \operatorname{div}_{\mathsf{m}}(X_i) \right), \qquad (2.7)$$

see Corollary A.2 for a proof. In (2.7), $\operatorname{div}_{\mathsf{m}}V$ is the divergence of the vector field V computed with respect to m , that is,

$$\int_{M} v \operatorname{div}_{\mathsf{m}}(V) \operatorname{d} \mathsf{m} = -\int_{M} \operatorname{g}(\nabla v, V) \operatorname{d} \mathsf{m} \quad \text{for all } v \in C_{c}^{\infty}(M).$$

For $q \in [1, \infty)$, we say that $u \in L^1_{loc}(M, \mathsf{m})$ has q-integrable distributional X_i -derivative if there exists a function $X_i u \in L^q(M, \mathsf{m})$ such that

$$\int_{M} v X_{i} u \, \mathrm{d}\mathbf{m} = \int_{M} u X_{i}^{*} v \, \mathrm{d}\mathbf{m} \quad \text{for all } v \in C_{c}^{\infty}(M)$$

where $X_i^* v = -X_i v - v \operatorname{div}_{\mathsf{m}}(X_i)$ denotes the adjoint action of X_i . We thus let

$$\mathrm{HW}^{1,q}(M,\mathsf{m}) = \{ u \in \mathrm{L}^q(M,\mathsf{m}) : X_i u \in \mathrm{L}^q(M,\mathsf{m}), \ i = 1, \dots, L \}$$

be the usual *horizontal* $W^{1,q}$ Sobolev space induced by the family \mathscr{F} and the measure **m** on M, endowed with the natural norm

$$\|u\|_{\mathrm{HW}^{1,q}(M,\mathsf{m})} = \left(\|u\|_{\mathrm{L}^{q}(M,\mathsf{m})}^{q} + \|\nabla u\|_{\mathrm{L}^{q}(M,\mathsf{m})}^{q}\right)^{1/q}$$

for all $u \in HW^{1,q}(M, \mathbf{m})$, where $\nabla u = \sum_{i=1}^{L} X_i u X_i$ in accordance with (2.5) and

$$\|\nabla u\|_{\mathrm{L}^{q}(M,\mathsf{m})}^{q} = \int_{M} \|\nabla u\|^{q} \,\mathrm{d}\mathsf{m}.$$

2.3. **Privileged coordinates.** Following [18, 30], we introduce *privileged coordinates*, a fundamental tool in the description of the tangent cone of sub-Riemannian manifolds.

Given a multi-index $I \in \{1, \ldots, L\}^{\times i}$, $i \in \mathbb{N}$, we let |I| = i be its *length* and we set

$$X_I = [X_{I_1}, [\dots, [X_{I_{i-1}}, X_{I_i}]]]]$$

Accordingly, we define

$$\mathscr{D}_x^i = \operatorname{span}\{X_I|_x : |I| \le i\}$$
(2.8)

and

$$k_i(x) = \dim \mathscr{D}_x^i$$

for all $x \in M$ and $i \in \mathbb{N}$. In particular, $\mathscr{D}_x^0 = \{0\}$ and $\mathscr{D}_x^1 = \mathscr{D}_x$ as in (2.1) for all $x \in M$. The spaces defined in (2.8) naturally yield the filtration

$$\{0\} = \mathscr{D}_x^0 \subset \mathscr{D}_x^1 \subset \cdots \subset \mathscr{D}_x^{s(x)} = T_x M$$

for all $x \in M$, where $s = s(x) \in \mathbb{N}$ is the *step* of the sub-Riemannian structure at the point x. We say that $x \in M$ is a *regular* point if the dimension of each space \mathscr{D}_y^i remains constant as $y \in M$ varies in an open neighborhood of x, otherwise x is a *singular* point.

Definition 2.1 (Adapted and privileged coordinates). Let $o \in M$ and let $U \subset M$ be an open neighborhood of o. We say that the local coordinates given by a diffeomorphism $z: U \to \mathbb{R}^n$ are adapted at o if they are centered at o, i.e. z(o) = 0, and $\partial_{z_1}|_{0,\ldots,\partial_{z_{k_i}}}|_0$ form a basis for \mathscr{D}_o^i in these coordinates for all $i = 1, \ldots, s(o)$. We say that the adapted coordinate z_i has weight $w_i = j$ if $\partial_{z_i}|_0 \in \mathscr{D}_o^j \setminus \mathscr{D}_o^{j-1}$. Furthermore, we say that the coordinates z are privileged at o if they are adapted at o and, in addition, $z_i(x) = O(\mathsf{d}(x, o)^{w_i})$ for all $x \in U$ and $i = 1, \ldots, n$.

Privileged coordinates exist in a neighborhood of any point, see [18, Th. 4.15].

2.4. Nilpotent approximation. From now on, we fix a set of privileged coordinates $z: U \to \mathbb{R}^n$ around a point $o \in M$ in the sense of Definition 2.1. Without loss of generality, we identify the coordinate domain $U \subset M$ with \mathbb{R}^n and the base point $o \in M$ with the origin $0 \in \mathbb{R}^n$. Similarly, the vector fields in \mathscr{F} defined on U are identified with vector fields on \mathbb{R}^n , and the restriction of the sub-Riemannian distance **d** to U is identified with a distance function on \mathbb{R}^n , which is induced by the family \mathscr{F} , for which we keep the same notation.

On $(\mathbb{R}^n, \mathscr{F})$, we define a family of *dilations*, for $\lambda \geq 0$, by letting

$$\operatorname{dil}_{\lambda} \colon \mathbb{R}^n \to \mathbb{R}^n, \quad \operatorname{dil}_{\lambda}(z_1, \dots, z_n) = (\lambda^{w_1} z_1, \dots, \lambda^{w_n} z_n)$$

for all $z = (z_1, \ldots, z_n) \in \mathbb{R}^n$, where the w_i 's are the weights given by Definition 2.1. We say that a differential operator P is homogeneous of degree $-d \in \mathbb{Z}$ if

$$P(f \circ \operatorname{dil}_{\lambda}) = \lambda^{-d}(Pf) \circ \operatorname{dil}_{\lambda} \quad \text{for all } \lambda > 0 \text{ and } f \in C^{\infty}(\mathbb{R}^{n}).$$
(2.9)

Note that the monomial z_i is homogeneous of degree w_i , while the vector field ∂_{z_i} is homogeneous of degree $-w_i$, for i = 1, ..., n. As a consequence, the differential operator

$$z_1^{\mu_1} \cdot \dots \cdot z_n^{\mu_n} \frac{\partial^{|\nu|}}{\partial z_1^{\nu_1} \cdots \partial z_n^{\nu_n}}, \qquad \nu_i, \mu_j \in \mathbb{N} \cup \{0\}$$

is homogeneous of degree $\sum_{i=1}^{n} w_i(\mu_i - \nu_i)$. For more details, see [18, Sec. 5].

We can now introduce the new family

$$\widehat{\mathscr{F}} = \left\{ \widehat{X}_1, \dots, \widehat{X}_L \right\}$$

by defining

$$\widehat{X}_{i} = \lim_{\varepsilon \to 0} X_{i}^{\varepsilon}, \quad X_{i}^{\varepsilon} = \varepsilon \, (\operatorname{dil}_{1/\varepsilon})_{*} X_{i}, \tag{2.10}$$

for all $i = 1, \ldots, L$, where $(\operatorname{dil}_{1/\varepsilon})_*$ stands for the usual push-forward via the differential of the dilation map $dil_{1/\varepsilon}$, see [18, Sec. 5.3]. The convergence in (2.10) can be actually made more precise, in the sense that

$$X_i^{\varepsilon} = \widehat{X}_i + \mathscr{R}_i^{\varepsilon}, \quad i = 1, \dots, L,$$

where $\mathscr{R}_i^{\varepsilon}$ locally uniformly converges to zero as $\varepsilon \to 0$, see [18, Th. 5.19]. The family $\widehat{\mathscr{F}}$ is a set of complete vector fields on \mathbb{R}^n , homogeneous of degree -1, with polynomial coefficients, and can be understood as the 'principal part' of \mathscr{F} upon blow-up by dilations. Since \mathscr{F} satisfies the bracket-generating condition (2.3), also the new family $\widehat{\mathscr{F}}$ is bracket-generating at all points of \mathbb{R}^n , and thus induces a finite sub-Riemannian distance \hat{d} , see [18, Prop. 5.17]. The resulting *n*-dimensional sub-Riemannian structure $(\mathbb{R}^n, \widehat{\mathscr{F}})$ is called *nilpotent approximation* of $(\mathbb{R}^n, \mathscr{F})$ at $0 \in \mathbb{R}^n$.

The family $\widehat{\mathscr{F}} = \left\{ \widehat{X}_1, \dots, \widehat{X}_L \right\}$ generates a finite-dimensional stratified Lie algebra

$$\mathfrak{g} = \operatorname{Lie}(\mathscr{F}) = \mathfrak{g}^1 \oplus \cdots \oplus \mathfrak{g}^s$$

of step $s = s(0) \in \mathbb{N}$, where the grading is given by the degree of the vector fields, according to the definition in (2.9), that is, the layer \mathfrak{g}^i corresponds to vector fields homogeneous of degree -i with respect to dilations, see [18, Sec. 5.4]. In particular, $\mathfrak{g}^1 = \operatorname{span}\{\widehat{X}_1, \ldots, \widehat{X}_L\}$, so that \mathfrak{g} is generated by its first stratum, namely,

$$\mathbf{g}^{j+1} = [\mathbf{g}^1, \mathbf{g}^j], \qquad \forall j = 1, \dots, s-1.$$
(2.11)

Finally, define the Lie subalgebra of vector fields vanishing at 0,

$$\mathfrak{h} = \left\{ \widehat{X} \in \mathfrak{g} : \widehat{X}|_0 = 0 \right\} = \mathfrak{h}^1 \oplus \cdots \oplus \mathfrak{h}^s,$$

which inherits the grading from the one of \mathfrak{g} ,

$$\mathfrak{h}^{j+1} = [\mathfrak{h}^1, \mathfrak{h}^j], \qquad \forall j = 1, \dots, s-1.$$
(2.12)

It is a fundamental fact [18, Th. 5.21] that the nilpotent approximation $(\mathbb{R}^n, \widehat{\mathscr{F}})$ is diffeomorphic to the homogeneous sub-Riemannian space G/H, where G is the Carnot group $G = \exp \mathfrak{g}$ (explicitly realized as the subgroup of the flows of the vector fields of \mathfrak{g} acting on \mathbb{R}^n from the right) and $H = \exp \mathfrak{h}$ is the Carnot subgroup induced by \mathfrak{h} .

In particular, if $0 \in \mathbb{R}^n$ is a regular point, then $H = \{0\}$, and so the nilpotent approximation $(\mathbb{R}^n, \widehat{\mathscr{F}})$ is diffeomorphic to the Carnot group G, see [18, Prop. 5.22].

Recall that the smooth measure **m** on the original manifold M can be identified with a smooth measure on $U \simeq \mathbb{R}^n$, for which we keep the same notation. In particular, **m** is absolutely continuous with respect to the *n*-dimensional Lebesgue measure \mathscr{L}^n on \mathbb{R}^n , with $\mathbf{m} = \rho \mathscr{L}^n$ for some positive smooth function $\rho \colon \mathbb{R}^n \to (0, \infty)$. The corresponding blow-up measure on the nilpotent approximation is naturally given by

$$\widehat{\mathsf{m}} = \lim_{\varepsilon \to 0} \mathsf{m}^{\varepsilon} = \rho(0) \, \mathscr{L}^n, \quad \mathsf{m}^{\varepsilon} = \varepsilon^Q \, (\mathrm{dil}_{1/\varepsilon})_{\#} \mathsf{m},$$

in the sense of weak^{*} convergence of measures in \mathbb{R}^n , where

$$Q = \sum_{i=1}^{n} i \, w_i \in \mathbb{N}$$

is the so-called homogeneous dimension of $(\mathbb{R}^n, \widehat{\mathscr{F}})$ and $(\operatorname{dil}_{1/\varepsilon})_{\#}$ stands for the pushforward in the measure-theoretic sense via the dilation map $\operatorname{dil}_{1/\varepsilon}$. Consequently, without loss of generality, we can assume that $\rho(0) = 1$, thus endowing $(\mathbb{R}^n, \widehat{\mathscr{F}})$ with the *n*dimensional Lebesgue measure. Notice that $\operatorname{div}_{\mathscr{L}^n} \widehat{X}_i = 0$, for all $i = 1, \ldots, L$, since each \widehat{X}_i is homogeneous of degree -1. Hence, by (2.7), the sub-Laplacian of a function $u \in C^{\infty}(\mathbb{R}^n)$ can be globally represented as

$$\widehat{\Delta}u = \sum_{i=1}^{L} \widehat{X}_i^2 u. \tag{2.13}$$

It is worth noticing that the metric space $(\mathbb{R}^n, \widehat{\mathbf{d}})$ induced by the nilpotent approximation $(\mathbb{R}^n, \widehat{\mathscr{F}})$ actually coincides with the *metric tangent cone* at $o \in M$ of the metric space (M, \mathbf{d}) in the sense of Gromov [26], see [18, Th. 7.36] for the precise statement. In fact, the sub-Riemmanian distance d^{ε} induced by the vector fields X_i^{ε} , i = 1, ..., L, defined in (2.10) is uniformly converging to the distance \hat{d} on compact sets as $\varepsilon \to 0$.

It is not difficult to check that the family $\{(\mathbb{R}^n, \mathsf{d}^{\varepsilon}, \mathsf{m}^{\varepsilon}, 0)\}_{\varepsilon>0}$ of pointed metric-measure spaces converge to the pointed metric-measure space $(\mathbb{R}^n, \widehat{\mathsf{d}}, \mathscr{L}^n, 0)$ as $\varepsilon \to 0$ in the *pointed* measure Gromov-Hausdorff topology, see [13, Sec. 10.3] for details.

2.5. The curvature-dimension condition. We end this section by recalling the definition of curvature-dimension conditions of introduced in [36, 48, 49].

On a Polish (i.e., separable and complete) metric space (X, d) , we let $\mathscr{P}(X)$ be the set of probability Borel measures on X and define the Wasserstein (extended) distance W_2

$$\mathsf{W}_2^2(\mu,\nu) = \inf\left\{\int_{X\times X} \mathsf{d}^2(x,y)\,\mathrm{d}\pi: \pi\in\mathsf{Plan}(\mu,\nu)\right\}\in[0,\infty],$$

for $\mu, \nu \in \mathscr{P}(X)$, where

$$\mathsf{Plan}(\mu,\nu) = \{ \pi \in \mathscr{P}(X \times X) : (p_1)_{\#}\pi = \mu, \ (p_2)_{\#}\pi = \nu \},\$$

where $p_i: X \times X \to X$, i = 1, 2, are the projections on each component and $T_{\#}\mu \in \mathscr{P}(Y)$ denotes the push-forward measure given by any μ -measurable map $T: X \to X$. The function W_2 is a distance on the *Wasserstein space*

$$\mathscr{P}_2(X) = \left\{ \mu \in \mathscr{P}(X) : \int_X \mathsf{d}^2(x, x_0) \, \mathrm{d}\mu(x) < \infty \text{ for some, and thus any, } x_0 \in X \right\}.$$

Note that $(\mathscr{P}_2(X), \mathsf{W}_2)$ is a Polish metric space which is geodesic as soon as (X, d) is. In addition, letting $\operatorname{Geo}(X)$ be the set of geodesics of (X, d) , namely, curves $\gamma \colon [0, 1] \to X$ such that $\mathsf{d}(\gamma_s, \gamma_t) = |s-t| \, \mathsf{d}(\gamma_0, \gamma_1)$, for all $s, t \in [0, 1]$, any W_2 -geodesic $\mu \colon [0, 1] \to \mathscr{P}_2(X)$ can be (possibly non-uniquely) represented as $\mu_t = (e_t)_{\sharp} \nu$ for some $\nu \in \mathscr{P}(\operatorname{Geo}(X))$, where $e_t \colon \operatorname{Geo}(X) \to X$ is the evaluation map at time $t \in [0, 1]$.

We endow the metric space (X, d) with a non-negative Borel measure **m** such that

m is finite on bounded sets and $supp(\mathbf{m}) = X$.

We define the *(relative) entropy* functional $\mathsf{Ent}_{\mathsf{m}} \colon \mathscr{P}_2(X) \to [-\infty, +\infty]$ by letting

$$\operatorname{Ent}_{\mathsf{m}}(\mu) = \int_{X} \rho \log \rho \, \mathrm{d}\mathsf{m}$$

if $\mu = \rho \mathbf{m}$ and $\rho \log \rho \in L^1(X, \mathbf{m})$, while we set $\mathsf{Ent}_{\mathbf{m}}(\mu) = +\infty$ otherwise.

Definition 2.2 (CD(K, ∞) property). We say that a metric-measure space $(X, \mathsf{d}, \mathsf{m})$ satisfies the CD(K, ∞) property if, for any $\mu_0, \mu_1 \in \mathscr{P}_2(X)$ with $\mathsf{Ent}_{\mathsf{m}}(\mu_i) < +\infty, i = 0, 1$, there exists a W_2 -geodesic $[0, 1] \ni s \mapsto \mu_s \in \mathscr{P}_2(X)$ joining them such that

$$\mathsf{Ent}_{\mathsf{m}}(\mu_s) \le (1-s)\,\mathsf{Ent}_{\mathsf{m}}(\mu_0) + s\,\mathsf{Ent}_{\mathsf{m}}(\mu_1) - \frac{K}{2}\,s(1-s)\,\mathsf{W}_2^2(\mu_0,\mu_1) \tag{2.14}$$

for every $s \in [0, 1]$.

The geodesic K-convexity of $\mathsf{Ent}_{\mathsf{m}}$ in (2.14) can be reinforced to additionally encode an upper bound on the dimension on the space, as recalled below. For $N \in (1, \infty)$, we let

$$S_N(\mu, \mathbf{m}) = -\int_X \rho^{-1/N} d\mu, \qquad \mu = \rho \mathbf{m} + \mu^{\perp}$$

be the *N*-*Rényi entropy* of $\mu \in \mathscr{P}_2(X)$ with respect to **m**, where $\mu = \rho \mathbf{m} + \mu^{\perp}$ denotes the Radon–Nikodym decomposition of μ with respect to **m**.

Definition 2.3 (CD(K, N) property). We say that a metric-measure space $(X, \mathsf{d}, \mathsf{m})$ satisfies the CD(K, N) property for some $N \in [1, \infty)$ if, for any $\mu_0, \mu_1 \in \mathscr{P}_2(X)$ with $\mu_i = \rho_i \mathsf{m}, i = 0, 1$, there exists a W_2 -geodesic $[0, 1] \ni s \mapsto \mu_s \in \mathscr{P}_2(X)$ joining them, with $\mu_s = (e_s)_{\sharp} \nu$ for some $\nu \in \mathscr{P}(\text{Geo}(X))$ such that

$$S_{N'}(\mu_s, \mathsf{m}) \le -\int_{\text{Geo}(X)} \left[\tau_{K,N'}^{(1-s)}(\mathsf{d}(\gamma_0, \gamma_1)) \rho_0^{-1/N'}(\gamma_0) + \tau_{K,N'}^{(s)}(\mathsf{d}(\gamma_0, \gamma_1)) \rho_1^{-1/N'}(\gamma_1) \right] d\nu(\gamma)$$

for every $s \in [0, 1], N' \ge N$. Here $\tau_{K,N}^{(s)}$ is the model distortion coefficient, see [49, p. 137].

Remark 2.4. The CD(0, N) corresponds to the convexity of the N'-Rényi entropy

$$S_{N'}(\mu_s, \mathsf{m}) \le (1-s)S_{N'}(\mu_0, \mathsf{m}) + sS_{N'}(\mu_1, \mathsf{m})$$

for every $s \in [0,1]$ and $N' \ge N$, with $\mu_0, \mu_1 \in \mathscr{P}_2(X)$ as in Definition 2.3.

Remark 2.5. For a CD(K, N) metric-measure space, K and N represent a lower bound on the Ricci tensor and an upper bond on the dimension, respectively, and we have

$$\mathsf{CD}(K, N) \implies \mathsf{CD}(K, N') \quad \text{for all } N' \ge N, \ N, N' \in [1, \infty],$$

 $\mathsf{CD}(K, N) \implies \mathsf{CD}(K', N) \quad \text{for all } K' \le K, \ K, K' \in \mathbb{R}.$

In particular, the $CD(K, \infty)$ condition (2.14) is the weakest of all the curvature-dimension conditions for fixed $K \in \mathbb{R}$.

3. Proofs

We first deal with Theorems 1.4 and 1.5, from which Theorem 1.2 immediately follows.

3.1. Proof of Theorem 1.4. We divide the proof in four steps.

Step 1: passing to the nilpotent approximation via blow-up. Let $(\mathbb{R}^n, \widehat{\mathscr{F}})$ be the nilpotent approximation of (M, \mathscr{F}) at some fixed point $o \in M$ as explained in Section 2.4. Let $u \in C_c^{\infty}(M)$ and, without loss of generality, let us assume that $\sup u$ is contained in the domain of the privileged coordinates at $o \in M$. In particular, we identify u with a C_c^{∞} function on \mathbb{R}^n . We now apply (1.1) to the dilated function

$$u_{\varepsilon} = u \circ \operatorname{dil}_{1/\varepsilon} \in C_c^{\infty}(\mathbb{R}^n), \quad \text{for } \varepsilon > 0,$$

and evaluate this expression at the point $\operatorname{dil}_{\varepsilon}(x) \in \mathbb{R}^n$. Exploiting the expressions in Corollary A.2, we get that

$$\sum_{i,j=1}^{L} X_{i}^{\varepsilon} u \left(X_{ijj}^{\varepsilon} u - X_{jji}^{\varepsilon} u \right) - (X_{ij}^{\varepsilon} u)^{2} + \mathscr{R}_{i,j}^{\varepsilon} u \le 0,$$
(3.1)

where X_i^{ε} is as in (2.10), $X_{ijk} = X_i X_j X_k$ whenever $i, j, k \in \{1, \ldots, L\}$, and $\mathscr{R}_{i,j}^{\varepsilon}$ is a reminder locally uniformly vanishing as $\varepsilon \to 0$. Therefore, letting $\varepsilon \to 0$ in (3.1), by the convergence in (2.10) we get

$$\sum_{i,j=1}^{L} \widehat{X}_{i} u \left(\widehat{X}_{ijj} u - \widehat{X}_{jji} u \right) - \left(\widehat{X}_{ij} u \right)^{2} \leq 0, \qquad (3.2)$$

which is (1.1) with K = 0 for the nilpotent approximation $(\mathbb{R}^n, \widehat{\mathscr{F}})$.

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Step 2: improvement via homogeneous structure. We now show that (3.2) implies a stronger identity, see (3.4) below, obtained from (3.2) by removing the squared term and replacing the inequality with an equality. Recall, in particular, the definition of weight of (privileged) coordinates in Definition 2.1. We take $u \in C^{\infty}(\mathbb{R}^n)$ of the form

$$u = \alpha + \gamma$$

where α and γ are homogeneous polynomial of weighted degree 1 and at least 3, respectively. Since $X_I \alpha = 0$ as soon as the multi-index satisfies $|I| \ge 2$ (see [18, Prop. 4.10]), we can take the terms with lowest homogeneous degree in (3.2) to get

$$\sum_{i,j=1}^{L} \widehat{X}_{i} \alpha \left(\widehat{X}_{ijj} \gamma - \widehat{X}_{jji} \gamma \right) = \sum_{i=1}^{L} \widehat{X}_{i} \alpha \left[\widehat{X}_{i}, \widehat{\Delta} \right](\gamma) \le 0$$

for all such α and γ . In the second equality, we used the fact that the sub-Laplacian Δ is a sum of squares as in (2.13). Since α can be replaced with $-\alpha$, we must have that

$$\sum_{i=1}^{L} \widehat{X}_{i} \alpha \left[\widehat{X}_{i}, \widehat{\Delta} \right] (\gamma) = 0.$$
(3.3)

Observing that $\widehat{X}_i \alpha$ is homogeneous of degree 0, and thus a constant function, we can rewrite (3.3) as

$$\left[\sum_{i=1}^{L} \widehat{X}_{i} \alpha \, \widehat{X}_{i}, \widehat{\Delta}\right](\gamma) = 0, \qquad (3.4)$$

which is the seeked improvement of (3.2).

Step 3: construction of the space $\mathfrak{i} \subset \mathfrak{g}^1$. Let \mathbb{P}_1^n be the vector space of homogeneous polynomials of weighted degree 1 on \mathbb{R}^n . Notice that

$$\mathbb{P}_1^n = \operatorname{span}\{z_i \mid i = 1, \dots, k_1\}, \quad k_1 = \dim \mathscr{D}|_0$$

that is, \mathbb{P}_1^n is generated by the monomials given by the coordinates of lowest weight. We now define a linear map $\phi \colon \mathbb{P}_1^n \to \mathfrak{g}^1$ by letting

$$\phi[\alpha] = \widehat{\nabla}\alpha = \sum_{i=1}^{L} \widehat{X}_i \alpha \, \widehat{X}_i$$

for all $\alpha \in \mathbb{P}_1^n$ (recall Corollary A.2). We claim that ϕ is injective. Indeed, if $\phi[\alpha] = 0$ for some $\alpha \in \mathbb{P}_1^n$, then, by applying the operator $\phi[\alpha]$ to the polynomial α , we get

$$0 = \phi\alpha = \left(\sum_{i=1}^{L} \widehat{X}_i \alpha \, \widehat{X}_i\right)(\alpha) = \sum_{i=1}^{L} (\widehat{X}_i \alpha)^2.$$

Thus $\widehat{X}_i \alpha = 0$ for all i = 1, ..., L. Hence α must have weighted degree at least 2. However, since α is homogeneous of weighted degree 1, we conclude that $\alpha = 0$, proving that ker $\phi = \{0\}$. We can thus define the subspace

$$\mathfrak{i} = \phi[\mathbb{P}_1^n] \subset \mathfrak{g}^1.$$

By (3.4), any $\widehat{X} \in \mathfrak{i}$ is such that $[\widehat{X}, \widehat{\Delta}](\gamma) = 0$ for any homogeneous polynomial γ of degree at least 3. Exploiting the definitions given in Section 2.4, we observe that a differential operator P, homogeneous of weighted degree $-d \in \mathbb{Z}$, has the form

$$P = \sum_{\mu,\nu} a_{\mu,\nu} z^{\mu} \frac{\partial^{|\nu|}}{\partial z^{\nu}}, \qquad (3.5)$$

where $\mu = (\mu_1, \ldots, \mu_n), \nu = (\nu_1, \ldots, \nu_n), \mu_i, \nu_j \in \mathbb{N} \cup \{0\}, a_{\mu,\nu} \in \mathbb{R}$, and the weighted degree of every addend in (3.5) is equal to -d, namely, $\sum_{i=1}^n (\mu_i - \nu_i) w_i = -d$.

Thus, since \widehat{X} and $\widehat{\Delta}$ are homogeneous differential operators of order -1 and -2, respectively, then $[\widehat{X}, \widehat{\Delta}]$ has order -3, see [18, Prop. 5.16]. It follows that $[\widehat{X}, \widehat{\Delta}] = 0$ as differential operator acting on $C^{\infty}(\mathbb{R}^n)$.

We now show (1.3). Let us first observe that $\mathbf{i} \cap \mathbf{h} = \{0\}$. Indeed, if $\phi[\alpha] \in \mathbf{h}$ for some $\alpha \in \mathbb{P}_1^n$, that is, $\phi[\alpha]|_0 = 0$, then $\widehat{X}_i \alpha|_0 = 0$ for all $i = 1, \ldots, L$. Since $\widehat{X}_i \alpha$ is a constant function, this implies $\phi[\alpha] = 0$, as claimed. Therefore, since dim $\mathbf{i} = \dim \mathbb{P}_1^n = k_1$, we must have $\mathfrak{g}^1 = \mathbf{i} \oplus \mathfrak{h}^1$ thanks to Lemma 3.1 below.

Lemma 3.1. With the same notation of Section 2.4, if $\mathfrak{g}^1 = \mathfrak{v} \oplus \mathfrak{h}^1$, then dim $\mathfrak{v} = k_1$.

Proof. We claim that the dimension of \mathfrak{v} is preserved by evaluation at zero, that is, dim $\mathfrak{v}|_0 = \dim \mathfrak{v}$, where dim $\mathfrak{v}|_0$ is the dimension of $\mathfrak{v}|_0$ as a subspace of $T_0\mathbb{R}^n$, while dim \mathfrak{v} is the dimension of \mathfrak{v} as a subspace of \mathfrak{g} . Indeed, we have the trivial inequality dim $\mathfrak{v}|_0 \leq \dim \mathfrak{v}$. On the other hand, if strict inequality holds, then \mathfrak{v} must contain nonzero vector fields vanishing at zero, contradicting the fact that $\mathfrak{v} \cap \mathfrak{h} = \{0\}$. Therefore, since dim $\mathfrak{g}^1|_0 = k_1$ and dim $\mathfrak{h}^1|_0 = 0$, we get dim $\mathfrak{v} = \dim \mathfrak{v}|_0 = k_1$ as desired. \Box

Step 4: proof of the Killing property. We have so far proved the existence of \mathfrak{i} such that $\mathfrak{g}^1 = \mathfrak{i} \oplus \mathfrak{h}^1$, and such that any element $Y \in \mathfrak{i}$ commutes with the sub-Laplacian $\widehat{\Delta}$. We now show that all such Y is a Killing vector field.

Let $Y \in \mathfrak{i}$. Since $[Y, \widehat{\Delta}] = 0$, the induced flow ϕ_s^Y , for $s \in \mathbb{R}$, commutes with $\widehat{\Delta}$ when acting on smooth functions, that is,

$$\widehat{\Delta}(u \circ \phi_s^Y) = (\widehat{\Delta}u) \circ \phi_s^Y \tag{3.6}$$

for all $u \in C^{\infty}(\mathbb{R}^n)$ and $s \in \mathbb{R}$. Recall the sub-Riemannian Hamiltonian $\widehat{H}: T^*\mathbb{R}^n \to \mathbb{R}$,

$$\widehat{H}(\lambda) = \frac{1}{2} \sum_{i=1}^{L} \langle \lambda, \widehat{X}_i \rangle^2, \qquad (3.7)$$

for all $\lambda \in T^* \mathbb{R}^n$. By (2.13), \widehat{H} is the principal symbol of $\widehat{\Delta}$. Thus, from (3.6) it follows

$$\widehat{H} \circ \left(\phi_s^Y \right)^* = \widehat{H}$$

for all $s \in \mathbb{R}$, where the star denotes the pull-back, and thus $(\phi_s^Y)^*$ is a diffeomorphism on $T^*\mathbb{R}^n$. This means that ϕ_s^Y is an isometry, as we now show. Indeed, for any given $x \in \mathbb{R}^n$, the restriction $\widehat{H}|_{T^*_x\mathbb{R}^n}$ is a quadratic form on $T^*_x\mathbb{R}^n$, so $(\phi_s^Y)^*$ must preserve its kernel, that is,

$$(\phi_s^Y)^* \ker \widehat{H}|_{T^*_{\phi_s^Y(x)} \mathbb{R}^n} = \ker \widehat{H}|_{T^*_x \mathbb{R}^n}$$
(3.8)

for all $x \in \mathbb{R}^n$. By (3.7), it holds $\ker \widehat{H}|_{T^*_x \mathbb{R}^n} = \widehat{\mathscr{D}}_x^{\perp}$, where \perp denotes the annihilator of a vector space. By duality, from (3.8) we obtain that $(\phi_s^Y)_* \widehat{\mathscr{D}}_x = \widehat{\mathscr{D}}_{\phi_s^Y(x)}$ for all $x \in \mathbb{R}^n$ as required by (1.2). Finally, for $\lambda \in T^*_x M$, let $\lambda^{\#} \in \mathscr{D}_x$ be uniquely defined by $g_x(\lambda^{\#}, V) = \langle \lambda, V \rangle_x$ for all $V \in \mathscr{D}_x$, and notice that the map $\lambda \mapsto \lambda^{\#}$ is surjective on \mathscr{D}_x . Then it holds $\|\lambda^{\#}\|_x^2 = 2\widehat{H}(\lambda)$, see Lemma A.1. Thus, since $(\phi_s^Y)^*$ preserves \widehat{H} , the map $(\phi_s^Y)_*$ preserves the sub-Riemannian norm, and thus g. This means that ϕ_s^Y is an isometry, concluding the proof of Theorem 1.4.

3.2. Proof of Theorem 1.5. We claim that

$$\mathfrak{g}^j = \mathfrak{h}^j \quad \text{for all } j \ge 2.$$
 (3.9)

Note that (3.9) is enough to conclude the proof of Theorem 1.5, since, from (3.9) combined with (2.11) and (2.12), we immediately get that

$$\mathfrak{g} = \mathfrak{g}^1 \oplus \mathfrak{h}^2 \oplus \cdots \oplus \mathfrak{h}^s.$$

In particular, we deduce that $\mathfrak{g}|_0 = \mathfrak{g}^1|_0$, which in turn implies that \mathfrak{g} must be commutative, otherwise the bracket-generating condition would fail. To prove (3.9), we proceed by induction on $j \ge 2$ as follows.

Proof of the base case j = 2. We begin by proving the base case j = 2 in (3.9). To this aim, let $\widehat{X} \in \mathfrak{i}$ and $\widehat{Y} \in \mathfrak{g}^1$. By definition of Lie bracket, we can write

$$\left(\phi_{-s}^{\widehat{X}}\right)_{*}\widehat{Y} = s\left[\widehat{X},\widehat{Y}\right] + o(s) \text{ as } s \to 0,$$

where $\phi_s^{\widehat{X}}$, for $s \in \mathbb{R}$, is the flow of \widehat{X} . Since $\mathfrak{g}^1|_x = \widehat{\mathscr{D}}|_x$ for all $x \in \mathbb{R}^n$, and since \widehat{X} is Killing (in particular (1.2) holds for its flow), we have that $[\widehat{X}, \widehat{Y}]|_x \in \widehat{\mathscr{D}}|_x$ for all $x \in \mathbb{R}^n$. Since $[\widehat{X}, \widehat{Y}] \in \mathfrak{g}^2$ and so, in particular, $[\widehat{X}, \widehat{Y}]$ is homogeneous of degree -2, we have

$$[\widehat{X}, \widehat{Y}]|_0 = \sum_{j: w_j=2} a_j \,\partial_{z_j}|_0,$$

for some constants $a_i \in \mathbb{R}$. But we also must have that $[\widehat{X}, \widehat{Y}]|_0 \in \widehat{\mathscr{D}}|_0$ and so, since

$$\widehat{\mathscr{D}}|_0 = \operatorname{span}\left\{\partial_{z_j} : w_j = 1\right\}$$

according to Definition 2.1, $[\widehat{X}, \widehat{Y}]|_0 = 0$, that is, $[\widehat{X}, \widehat{Y}] \in \mathfrak{h}$. We thus have proved that $[\mathfrak{i}, \mathfrak{g}^1] \subset \mathfrak{h}^2$. In particular, since $\mathfrak{g}^1 = \mathfrak{i} \oplus \mathfrak{h}^1$, we get

$$[\mathbf{i},\mathbf{i}] \subset \mathfrak{h}^2 \quad \text{and} \quad [\mathbf{i},\mathfrak{h}^1] \subset \mathfrak{h}^2,$$
 (3.10)

from which we readily deduce (3.9) for j = 2.

Proof of the induction step. Let us assume that (3.9) holds for some $j \in \mathbb{N}$, $j \geq 2$. Since $\mathfrak{g}^1 = \mathfrak{i} \oplus \mathfrak{h}^1$, by the induction hypothesis we can write

$$\mathfrak{g}^{j+1} = [\mathfrak{g}^1, \mathfrak{g}^j] = [\mathfrak{g}^1, \mathfrak{h}^j] = [\mathfrak{i}, \mathfrak{h}^j] + [\mathfrak{h}^1, \mathfrak{h}^j] = [\mathfrak{i}, \mathfrak{h}^j] + \mathfrak{h}^{j+1}.$$

We thus just need to show that $[i, b^j] \subset b^{j+1}$ for all $j \in \mathbb{N}$ with $j \geq 2$. Note that we actually already proved the case j = 1 in (3.10). Again arguing by induction (taking j = 1 as base case), by the Jacobi identity and (3.10) we have

$$[\mathfrak{i},\mathfrak{h}^{j+1}] = [\mathfrak{i},[\mathfrak{h}^1,\mathfrak{h}^j]] = [\mathfrak{h}^1,[\mathfrak{h}^j,\mathfrak{i}]] + [\mathfrak{h}^j,[\mathfrak{i},\mathfrak{h}^1]] \subset [\mathfrak{h}^1,\mathfrak{h}^{j+1}] + [\mathfrak{h}^j,\mathfrak{h}^2] = \mathfrak{h}^{j+2}$$

as desired, concluding the proof of the induction step.

Remark 3.2 (Proof of Theorem 1.5 in the case $\mathfrak{h} = \{0\}$). The proof of Theorem 1.5 is much simpler if the nilpotent approximation $(\mathbb{R}^n, \widehat{\mathscr{F}})$ is a Carnot group, i.e., $\mathfrak{h} = \{0\}$. Indeed, in this case, the base case j = 2 in (3.9) immediately implies that $\mathfrak{g}^2 = \mathfrak{h}^2 = \{0\}$, which in turn gives $\mathfrak{g} = \mathfrak{g}^1$, so that \mathfrak{g} is commutative.

3.3. **Proof of Theorem 1.8.** In the following, we assume that the reader is familiar with the notions of *upper gradient* and of *q-upper gradient*, see [5] for the precise definitions. The next two lemmas are proved in [27] for sub-Riemannians structures on \mathbb{R}^n equipped with the Lebesgue measure, and are immediately extended to the weighted case.

Lemma 3.3. Let $(M, \mathsf{d}, \mathsf{m})$ be as in Theorem 1.8. If $u \in C(M)$ and $0 \leq g \in L^1_{\text{loc}}(M, \mathsf{m})$ be an upper gradient of u, then $u \in HW^{1,1}_{\text{loc}}(M, \mathsf{m})$ with $\|\nabla u\| \leq g$ m-a.e. In particular, if $u \in \text{Lip}(M, \mathsf{d})$, then $\|\nabla u\| \leq \text{Lip}(u)$.

Proof. Without loss of generality we may assume that $M = \Omega \subset \mathbb{R}^n$ is a bounded open set, the sub-Riemannian structure is induced by a family of smooth bracket-generating vector fields $\mathscr{F} = \{X_1, \ldots, X_L\}$ on Ω and $\mathbf{m} = \theta \mathscr{L}^n$, where $\theta \colon \Omega \to [0, \infty)$ is smooth and satisfies $0 < \inf_{\Omega} \theta \leq \sup_{\Omega} \theta < \infty$. Hence, $L^1(\Omega, \theta \mathscr{L}^n) = L^1(\Omega, \mathscr{L}^n)$ as sets, with equivalent norms, so that $0 \leq g \in L^1_{loc}(\Omega, \mathscr{L}^n)$ is an upper gradient of $u \in C(\Omega)$. Hence, by [27, Th. 11.7], we get that $u \in HW^{1,1}_{loc}(\Omega, \mathscr{L}^n)$, with $\|\nabla u\| \leq g \mathscr{L}^n$ -a.e., and thus $\theta \mathscr{L}^n$ -a.e., on Ω . By definition of distributional derivative, we can write

$$\int_{\Omega} v X_i u \, \mathrm{d}x = \int_{\Omega} u \left[-X_i v + \operatorname{div}(X_i) v \right] \, \mathrm{d}x, \quad \forall v \in C_c^1(\Omega), \ i = 1, \dots, L,$$

where div denotes the Euclidean divergence. We apply the above formula with test function $v = \theta w$, for any $w \in C_c^1(\Omega)$, getting

$$\int_{\Omega} w X_i u \,\theta \,\mathrm{d}x = \int_{\Omega} u \left[-X_i w + \operatorname{div}(X_i) w + \frac{X_i \theta}{\theta} w \right] \theta \,\mathrm{d}x, \quad \forall w \in C_c^1(\Omega), \ i = 1, \dots, L.$$

The function within square brackets is the adjoint $X_i^* w$ with respect to the measure $\theta \mathscr{L}^n$. It follows that $\mathrm{HW}^{1,q}(\Omega, \theta \mathscr{L}^n) = \mathrm{HW}^{1,q}(\Omega, \mathscr{L}^n)$ as sets, with equivalent norms. In particular, $u \in \mathrm{W}^{1,1}_{\mathscr{D},\mathrm{loc}}(\Omega, \theta \mathscr{L}^n)$ as desired.

Lemma 3.4 (Meyers–Serrin). Let $(M, \mathsf{d}, \mathsf{m})$ be as in Theorem 1.8 and let $q \in [1, \infty)$. Then $\mathrm{HW}^{1,q}(M, \mathsf{m}) \cap C^{\infty}(M)$ is dense in $\mathrm{HW}^{1,q}(M, \mathsf{m})$.

Proof. Up to a partition of unity and exhaustion argument, we can reduce to the case $M = \Omega \subset \mathbb{R}^n$ is a bounded open set and $\mathbf{m} = \theta \mathscr{L}^n$, where $\theta \colon \Omega \to [0, \infty)$ is as in the previous proof, so that $\mathrm{HW}^{1,q}(\Omega, \mathscr{L}^n) = \mathrm{HW}^{1,q}(\Omega, \theta \mathscr{L}^n)$ as sets, with equivalent norms. In particular, we can assume that $\theta \equiv 1$. This case is proved in [27, Th. 11.9]. \Box

Lemma 3.5. Let $(M, \mathsf{d}, \mathsf{m})$ be as in Theorem 1.8 and let $q \in [1, \infty)$. If $u \in \mathrm{HW}^{1,q}(M, \mathsf{m})$, then $\|\nabla u\|$ is the minimal q-upper gradient of u.

Proof. Let us first prove that $\|\nabla u\|$ is a q-upper gradient of u. Indeed, by Lemma 3.4, we can find $(u_k)_{k\in\mathbb{N}}\subset \mathrm{HW}^{1,q}(M,\mathsf{m})\cap C^{\infty}(M)$ such that $u_k\to u$ in $\mathrm{HW}^{1,q}(M,\mathsf{m})$ as $k\to\infty$.

It is well-known that the sub-Riemannian norm of the gradient of a smooth function is an upper gradient, see [27, Prop. 11.6]. Thus, for u_k it holds

$$|u_k(\gamma(1)) - u_k(\gamma(0))| \le \int_{\gamma} \|\nabla u_k\| \,\mathrm{d}s.$$

Arguing as in [28, p. 179], using Fuglede's lemma (see [28, Lem. 7.5 and Sec. 10]), we pass to the limit for $k \to \infty$ in the previous equality, outside a *q*-exceptional family of curves. This proves that any Borel representative of $\|\nabla u\|$ is a *q*-upper gradient of *u*.

We now prove that $\|\nabla u\|$ is indeed minimal. Let $0 \leq g \in L^q(M, \mathsf{m})$ be any q-upper gradient of u. Arguing as in [28, p. 194], we can find a sequence $(g_k)_{k\in\mathbb{N}} \subset L^q(M, \mathsf{m})$ of upper gradients of u such that $g_k \geq g$ for all $k \in \mathbb{N}$ and $g_k \to g$ both pointwise m -a.e. on M and in $L^q(M, \mathsf{m})$ as $k \to \infty$. By Lemma 3.3, we thus must have that $\|\nabla u\| \leq g_k$ m -a.e. on M for all $k \in \mathbb{N}$. Hence, passing to the limit, we conclude that $\|\nabla u\| \leq g$ m -a.e. on M for any q-upper gradient g, concluding the proof. \Box

We are now ready to deal with the proof of Theorem 1.8.

Proof of (i). Recall that, here, q > 1. We begin by claiming that

$$W^{1,q}(M,\mathsf{d},\mathsf{m}) \subset HW^{1,q}(M,\mathsf{m})$$
(3.11)

isometrically, with $\|\nabla u\| = |\mathsf{D}u|_{w,q}$. Indeed, let $u \in W^{1,q}(M,\mathsf{d},\mathsf{m})$. By a well-known approximation argument, combining [5, Prop. 4.3, Th. 5.3 and Th. 7.4], we find $(u_k)_{k\in\mathbb{N}} \subset \operatorname{Lip}(M,\mathsf{d}) \cap W^{1,q}(M,\mathsf{d},\mathsf{m})$ such that

$$u_k \to u \quad \text{and} \quad |\mathsf{D}u_k|_{w,q} \to |\mathsf{D}u|_{w,q} \quad \text{in } \mathsf{L}^q(M,\mathsf{m}).$$
 (3.12)

Since $u_k \in \text{Lip}(M, \mathsf{d})$, by Lemma 3.3 we know that $u_k \in \text{HW}^{1,q}(M, \mathsf{m})$. Hence, by Lemma 3.5, $|\mathsf{D}u_k|_{w,q} = ||\nabla u_k||$, and we immediately get that

$$\sup_{k\in\mathbb{N}}\int_M \|\nabla u_k\|^q \,\mathrm{d}\mathbf{m} < \infty.$$

Therefore, up to passing to a subsequence, $(X_i u_k)_{k \in \mathbb{N}}$ is weakly convergent in $L^q(M, \mathbf{m})$, say $X_i u_k \rightharpoonup \alpha_i \in L^q(M, \mathbf{m})$, for all $i = 1, \ldots, L$. We thus get that $u \in HW^{1,q}(M, \mathbf{m})$ with $X_i u = \alpha_i$ and thus $\nabla u = \sum_{i=1}^L \alpha_i X_i$. By stability of q-upper gradients, [5, Th. 5.3 and Thm. 7.4], $\|\nabla u\|$ is a q-upper gradient of u. By semi-continuity of the norm, we obtain

$$\int_{M} \|\nabla u\|^{q} \,\mathrm{d}\mathbf{m} \leq \liminf_{k \to \infty} \int_{M} \|\nabla u_{k}\|^{q} \,\mathrm{d}\mathbf{m} = \int_{M} |\mathsf{D}u|_{w,q}^{q} \,\mathrm{d}\mathbf{m},$$

where we used (3.12). By definition of minimal q-upper gradient we thus get that $\|\nabla u\| = |\mathsf{D}u|_{w,q}$ m-a.e., and the claimed inclusion in (3.11) immediately follows.

We now observe that it also holds

$$\mathrm{HW}^{1,q}(M,\mathsf{m}) \cap C^{\infty}(M) \subset \mathrm{W}^{1,q}(M,\mathsf{d},\mathsf{m}), \tag{3.13}$$

with $\|\nabla u\| = |\mathsf{D}u|_{w,q}$. We just need to notice that, if $u \in C^{\infty}(M)$, then $\|\nabla u\|$ is an upper gradient of u, see [27, Prop. 11.6]. Therefore, by Lemma 3.3, $\|\nabla u\|$ must coincide with the minimal q-upper gradient of u, i.e., $\|\nabla u\| = |\mathsf{D}u|_w$ m-a.e., and (3.13) readily follows. In view of the isometric inclusions (3.11) and (3.13), and of the density provided by Lemma 3.4, this concludes the proof of (i).

Proof of (ii). Let us assume that $(M, \mathsf{d}, \mathsf{m})$ satisfies the $\mathsf{CD}(K, \infty)$ property for some $K \in \mathbb{R}$. By the previous point (i), we know that $(M, \mathsf{d}, \mathsf{m})$ satisfies the $\mathsf{RCD}(K, \infty)$ property. Consequently, since clearly $C_c^{\infty}(M) \subset W^{1,2}(M, \mathsf{d}, \mathsf{m})$ by (3.13), [6, Rem. 6.3] (even if the measure m is σ -finite, see [4, Sec. 7] for a discussion) implies that

$$\frac{1}{2} \int_{M} \Delta v \, \|\nabla u\|^2 \, \mathrm{d}\mathbf{m} - \int_{M} v \, \operatorname{g}(\nabla u, \nabla \Delta u) \, \mathrm{d}\mathbf{m} \ge K \int_{M} v \, \|\nabla u\|^2 \, \mathrm{d}\mathbf{m}$$

for all $u, v \in C_c^{\infty}(M)$ with $v \ge 0$ on M, from which we readily deduce (1.1).

Remark 3.6. The above proofs work for more general measures \mathbf{m} . Namely, we can assume that, locally on any bounded coordinate neighborhood $\Omega \subset \mathbb{R}^n$, $\mathbf{m} = \theta \mathscr{L}^n$ with $\theta \in \mathrm{W}^{1,1}(\Omega, \mathscr{L}^n) \cap \mathrm{L}^{\infty}(\Omega, \mathscr{L}^n)$. In this case, the positivity of \mathbf{m} corresponds to the requirement that θ is locally essentially bounded from below away from zero, in charts.

3.4. Proof of Theorem 1.10. We prove the two points in the statement separately.

Proof of (i). The case p = 0 has been already considered by Juillet in [32]. For p > 0, we can argue as follows. Let $A_0 = [-\ell - 1, -\ell] \times [0, 1]$ and $A_1 = [\ell, \ell + 1] \times [0, 1]$ for $\ell > 0$. We will shortly prove that the *midpoint set*

$$A_{1/2} = \left\{ q \in \mathbb{R}^2 : \exists q_0 \in A_0, \ \exists q_1 \in A_1 \text{ with } \mathsf{d}(q, q_0) = \mathsf{d}(q, q_1) = \frac{1}{2} \,\mathsf{d}(q_0, q_1) \right\}$$

satisfies

$$A_{1/2} \subset \left[-1 - \varepsilon_{\ell}, 1 + \varepsilon_{\ell}\right] \times \left[0, 1\right] \tag{3.14}$$

for some $\varepsilon_{\ell} > 0$, with $\varepsilon_{\ell} \downarrow 0$ as $\ell \to \infty$. Since $\mathsf{m}_p(A_0) = \mathsf{m}_p(A_1) \sim \ell^p$ as $\ell \to \infty$, we get

$$\sqrt{\mathsf{m}_p(A_0)\,\mathsf{m}_p(A_1)} > \mathsf{m}_p(A_{1/2})$$

for large $\ell > 0$. This contradicts the logarithmic Brunn–Minkowski $BM(0, \infty)$ inequality, which is a consequence of the $CD(0, \infty)$ condition, see [50, Th. 30.7].

To prove (3.14), let $q_i \in A_i$, $q_i = (x_i, y_i)$, and let $\gamma(t) = (x(t), y(t))$, $t \in [0, 1]$, be a geodesic such that $\gamma(i) = q_i$, with i = 0, 1. We first note that

$$\min\{y_0, y_1\} \le y(t) \le \max\{y_0, y_1\} \quad \text{for all } t \in [0, 1], \tag{3.15}$$

since any curve that violates (3.15) can be replaced by a strictly shorter one satisfying (3.15). In particular, we get that $A_{1/2} \subset \mathbb{R} \times [0, 1]$. Let us now observe that

$$|x_a - x_b| \le \mathsf{d}(a, b) \le |x_a - x_b| + \frac{|y_a - y_b|}{\max\{|x_a|, |x_b|\}}$$

for all $a = (x_a, y_a)$ and $b = (x_b, y_b)$ with $x_a, x_b \neq 0$. Therefore, if $q = (x, y) \in A_{1/2}$, then

$$|x - x_0| \le \mathsf{d}(q, q_0) = \frac{1}{2} \mathsf{d}(q_0, q_1) \le \ell + 1 + O(1/\ell)$$

and, similarly, $|x - x_1| \leq \ell + 1 + O(1/\ell)$. Since $x_0 \in [-\ell - 1, -\ell]$ and $x_1 \in [\ell, \ell + 1]$, we deduce that $|x| \leq 1 + O(1/\ell)$, concluding the proof of the claimed (3.14).

Proof of (ii). Out of the negligible set $\{x = 0\}$, the metric g on \mathbb{G}_p given by (1.5) is locally Riemannian. Recalling (1.6) and (1.7), the $\mathsf{BE}(K,\infty)$ inequality (1.1) is implied by the lower bound $\operatorname{Ric}_{\infty,V} \geq K$ via Bochner's formula, where $\operatorname{Ric}_{\infty,V}$ is the ∞ -Bakry-Émery Ricci tensor of $(\mathbb{R}^2, g, e^{-V} \operatorname{vol}_g)$, see [50, Ch. 14, Eqs. (14.36) – (14.51)]. By Lemma 3.7 below, we have $\operatorname{Ric}_{\infty,V} \geq 0$ for all $p \geq 1$, concluding the proof.

Lemma 3.7. Let $p \in \mathbb{R}$ and N > 2. The N-Bakry-Émery Ricci tensor of the Grushin metric (1.5), with weighted measure $\mathbf{m}_p = |x|^p \, \mathrm{d}x \, \mathrm{d}y$, for all $x \neq 0$ is

$$\operatorname{Ric}_{N,V} = \frac{p-1}{x^2} \operatorname{g} - \frac{(p+1)^2}{N-2} \frac{\mathrm{d}x \otimes \mathrm{d}x}{x^2},$$

with the convention that $1/\infty = 0$.

Proof. The N-Bakry–Émery Ricci tensor of a n-dimensional weighted Riemannian structure $(g, e^{-V} \operatorname{vol}_g)$, for N > n, is given by

$$\operatorname{Ric}_{N,V} = \operatorname{Ric}_{g} + \operatorname{Hess}_{g} V - \frac{\mathrm{d}V \otimes \mathrm{d}V}{N-n}, \qquad (3.16)$$

see [50, Eq. (14.36)]. In terms of the frame (1.4), the Levi-Civita connection is given by

$$\nabla_X X = \nabla_X Y = 0, \quad \nabla_Y X = -\frac{1}{x} Y, \quad \nabla_Y Y = \frac{1}{x} X,$$

whenever $x \neq 0$. Recalling that, from (1.7), $V(x) = -(p+1)\log|x|$, for $x \neq 0$, we obtain

$$\operatorname{Ric}_{g} = -\frac{2}{x^{2}} g, \quad \operatorname{Hess}_{g} V = \frac{(p+1)}{x^{2}} g, \quad \mathrm{d} V = -\frac{p+1}{x} \,\mathrm{d} x,$$
 (3.17)

whenever $x \neq 0$. The conclusion thus follows by inserting (3.17) into (3.16).

3.5. **Proof of Theorem 1.11.** The statement is a consequence of the geodesic convexity of \mathbb{G}_p^+ and the computation of the *N*-Bakry–Émery curvature in Lemma 3.7. Since the proof uses quite standard arguments, we simply sketch its main steps.

The interior of \mathbb{G}_p^+ , i.e., the open half-plane, can be regarded as a (non-complete) weighted Riemannian manifold with metric g as in (1.5) and weighted volume as in (1.7). Let $\mu_0, \mu_1 \in \mathscr{P}_2(\mathbb{G}_p^+), \mu_0, \mu_1 \ll \mathsf{m}_p$, with bounded support contained in the Riemannian region $\{x > \varepsilon\}$, for some $\varepsilon \ge 0$.

Let $(\mu_s)_{s \in [0,1]}$ be a W_2 -geodesic joining μ_0 and μ_1 . By a well-known representation theorem (see [50, Cor. 7.22]), there exists $\nu \in \mathscr{P}(\text{Geo}(\mathbb{G}_p^+))$, supported on the set $\Gamma = (e_0 \times e_1)^{-1}(\text{supp }\mu_0 \times \text{supp }\mu_1)$, such that $\mu_s = (e_s)_{\sharp}\nu$ for all $s \in [0,1]$. Since the set $\{x \ge \varepsilon\}$ is a geodesically convex subset of the full Grushin plane \mathbb{G}_p (by the same argument of [46, Prop. 5]), any $\gamma \in \Gamma$ is contained for all times in the region $\{x > 0\}$. Therefore, Γ is a set of Riemannian geodesics contained in the weighted Riemannian structure ($\{x > 0\}, g, e^{-V} \operatorname{vol}_g$). By Lemma 3.7, we have $\operatorname{Ric}_{N,V} \ge 0$ for all $N \ge N_p$, where N_p is as in (1.8). At this point, a standard argument shows that the Rényi entropy is convex along Wasserstein geodesics joining μ_0 with μ_1 , see the proof of [49, Th. 1.7] for example.

The extension to $\mu_0, \mu_1 \in \mathscr{P}_2(\mathbb{G}_p^+)$, with $\mu_0, \mu_1 \ll \mathsf{m}_p$ and compact support possibly touching the singular region $\{x = 0\}$, is achieved via a standard approximation argument. More precisely, one reduces to the previous case and exploits the stability of optimal transport [50, Th. 28.9] and the lower semi-continuity of the Rényi entropy [50, Th. 29.20]. Finally, the extension to general $\mu_0, \mu_1 \in \mathscr{P}_2(\mathbb{G}_p^+)$ follows the routine argument outlined in [9, Rem. 2.12], which works when $\mu_s = (e_s)_{\sharp}\nu$, $s \in [0, 1]$, and ν is concentrated on a set of non-branching geodesics. This proves the 'if' part of the statement.

The 'only if' part is also standard. The $\mathsf{CD}(0, N)$ condition for N > 2 implies that, on the Riemannian region $\{x > 0\}$, $\operatorname{Ric}_{N,V} \ge 0$, but this is false for $N < N_p$.

The fact that \mathbb{G}_p^+ is infinitesimally Hilbertian follows from Remark 1.9, by noting that m_p is positive and smooth out of the closed set $\{x = 0\}$, which has zero measure. An alternative proof follows from the observation that \mathbb{G}_p^+ is a Ricci limit, see [42].

APPENDIX A. GRADIENT AND LAPLACIAN REPRESENTATIONS FORMULAS

For the reader's convenience, in this appendix we provide a short proof of the representation formulas (2.5) and (2.7), in the rank-varying case.

Lemma A.1. For $\lambda \in T^*M$, let $\lambda^{\#} \in \mathscr{D}$ be uniquely defined by

$$g(\lambda^{\#}, V) = \langle \lambda, V \rangle$$

for all $V \in \mathscr{D}$, where $\langle \cdot, \cdot \rangle$ denotes the action of covectors on vectors. Then

$$\|\lambda^{\#}\|^{2} = \sum_{i=1}^{L} \left\langle \lambda^{\#}, X_{i} \right\rangle^{2}.$$
 (A.1)

As a consequence, if $\lambda, \mu \in T^*M$, then

$$g(\lambda^{\#}, \mu^{\#}) = \sum_{i=1}^{L} \langle \lambda, X_i \rangle \langle \mu, X_i \rangle.$$
(A.2)

Proof. Given $u \in \mathbb{R}^L$, we set $X_u = \sum_{i=1}^L u_i X_i$ and define

$$u^* \in \operatorname{argmin} \{ v \mapsto |v| : v \in \mathbb{R}^L, \ X_v = X_u \}.$$

In other words, for $X_u \in \mathscr{D}$, u^* is the element of minimal Euclidean norm such that $X_{u^*} = X_u$. Note that, by definition, it holds $||X_u|| = |u^*|$. We thus have

$$\|\lambda^{\#}\| = \sup \{ g(\lambda^{\#}, X) : \|X\| = 1, \ X \in \mathscr{D} \} = \sup \{ g(\lambda^{\#}, X_u) : |u^*| = 1, \ u \in \mathbb{R}^L \}.$$

We now claim that

$$\sup \{ g(\lambda^{\#}, X_u) : |u^*| = 1, \ u \in \mathbb{R}^L \} = \sup \{ g(\lambda^{\#}, X_u) : |u| = 1, \ u \in \mathbb{R}^L \}.$$
(A.3)

Indeed, the inequality \leq in (A.3) is obtained by observing that $X_u = X_{u^*}$ for any $u \in \mathbb{R}^L$. To prove the inequality \geq in (A.3), we observe that, if $u \in \mathbb{R}^L$ is such that |u| = 1 and $0 < |u^*| < 1$, then $v = u/|u^*|$ satisfies $|v^*| = 1$ and gives

$$g(\lambda^{\#}, X_v) > g(\lambda^{\#}, X_v) |u^*| = g(\lambda^{\#}, X_u).$$
 (A.4)

Furthermore, if |u| = 1 and $u^* = 0$, then $X_u = 0$ so also in this case we find $v \in \mathbb{R}^n$ with $v^* = 1$ such that (A.4) holds. This ends the proof of the claimed (A.3). Hence, since

$$g(\lambda^{\#}, X_u) = \sum_{i=1}^{L} g(\lambda^{\#}, X_i) u_i,$$

we easily conclude that

$$\|\lambda^{\#}\| = \sup \{ g(\lambda^{\#}, X_u) : |u| = 1, \ u \in \mathbb{R}^L \} = \sqrt{\sum_{i=1}^L g(\lambda^{\#}, X_i)^2},$$

proving (A.1). Equality (A.2) then follows by polarization.

Corollary A.2. The following formulas hold:

$$\nabla u = \sum_{i=1}^{L} X_i u \, X_i,\tag{A.5}$$

$$\Delta u = \sum_{i=1}^{L} \left(X_i^2 u + X_i u \operatorname{div}_{\mathsf{m}}(X_i) \right), \tag{A.6}$$

$$g(\nabla u, \nabla v) = \sum_{i=1}^{L} X_i u X_i v, \qquad (A.7)$$

for all $u, v \in C^{\infty}(M)$. In particular, $\|\nabla u\| = \sum_{i=1}^{L} (X_i u)^2$ for all $u \in C^{\infty}(M)$.

Proof. We prove each formula separately.

Proof of (A.5). Recalling the definition in (2.4), we can pick $\lambda = du$ in (A.2) to get

$$\left\langle du, \mu^{\#} \right\rangle = g(\nabla u, \mu^{\#}) = \sum_{i=1}^{L} \left\langle du, X_{i} \right\rangle \left\langle \mu, X_{i} \right\rangle$$
$$= \sum_{i=1}^{L} X_{i} u \left\langle \mu, X_{i} \right\rangle = g\left(\mu^{\#}, \sum_{i=1}^{L} X_{i} u X_{i} \right)$$

whenever $\mu \in T_x^*M$. Since the map $\#: T_x^*M \to \mathscr{D}_x$ is surjective, we immediately get (A.5).

Proof of (A.6). Recall that

$$\operatorname{div}_{\mathsf{m}}(fX) = Xf + f\operatorname{div}_{\mathsf{m}}(X)$$

for any $f \in C^{\infty}(M)$ and $X \in \Gamma(TM)$. Hence, from the definition in (2.6), we can compute

$$\Delta u = \operatorname{div}_{\mathsf{m}}(\nabla u) = \sum_{i=1}^{L} \operatorname{div}_{\mathsf{m}}(X_{i}u X_{i}) = \sum_{i=1}^{L} \left(X_{i}^{2}u X_{i} + X_{i}u \operatorname{div}_{\mathsf{m}}(X_{i}) \right),$$

which is the desired (A.6).

Proof of (A.7). Choosing $\lambda = du$ and $\mu = dv$ in (A.2), we can compute

$$g(\nabla u, \nabla v) = \sum_{i=1}^{L} \langle du, X_i \rangle \langle dv, X_i \rangle = \sum_{i=1}^{L} X_i u X_i v$$

and the proof is complete.

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