

TWO RIGIDITY RESULTS FOR STABLE MINIMAL HYPERSURFACES

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ABSTRACT. The aim of this paper is to prove two results concerning the rigidity of complete, immersed, orientable, stable minimal hypersurfaces: we show that they are hyperplane in \mathbb{R}^4 , while they do not exist in positively curved closed Riemannian $(n + 1)$ -manifold when $n \leq 5$; in particular, there are no stable minimal hypersurfaces in \mathbb{S}^{n+1} when $n \leq 5$. The first result was recently proved also by Chodosh and Li, and the second is a consequence of a more general result concerning minimal surfaces with finite index. Both theorems rely on a conformal method, inspired by a classical work of Fischer-Colbrie.

Key Words: stable minimal hypersurface, rigidity

AMS subject classification: 53C42, 53C21

1. INTRODUCTION

In this paper we consider smooth, complete, connected, orientable, isometrically immersed hypersurfaces $M^n \hookrightarrow (X^{n+1}, h)$, $n \geq 2$, where (X^{n+1}, h) is a (complete) Riemannian manifold of dimension $n + 1$ endowed with metric h . We denote with g the induced metric on M and with H the mean curvature of M ; M is *minimal* if $H \equiv 0$ on M . In this latter case we say that M is *stable* if

$$\int_M [|A|^2 + \text{Ric}_h(\nu, \nu)] f^2 dV_g \leq \int_M |\nabla f|^2 dV_g \quad \forall f \in C_0^\infty(M), \quad (1.1)$$

where $A = A_M$ is the second fundamental form of M^n , ν is a unit normal vector to M in X and dV_g is the volume form of g . It is well known that minimal hypersurfaces arise as critical points of the area functional and stability is related to the non-negativity of the second variation or, equivalently, the non-negativity of the Jacobi operator

$$L_M := \Delta + |A|^2 + \text{Ric}_h(\nu, \nu).$$

Our goal is to prove two results concerning the rigidity of a stable minimal hypersurface $M^n \hookrightarrow (X^{n+1}, h)$ when (X^{n+1}, h) is either the flat space \mathbb{R}^{n+1} or a closed (compact without boundary) Riemannian manifold with non-negative sectional curvature and positive Ricci curvature. The study of minimal (in particular stable or in general with finite index) hypersurfaces immersed into a Riemannian manifolds is a very active field and has attracted a lot of interest in the last decades.

Our first result is the following:

Theorem 1.1. *A complete, orientable, immersed, stable minimal hypersurface $M^3 \hookrightarrow \mathbb{R}^4$ is a hyperplane.*

This theorem has been recently proved by Chodosh and Li in [1, Theorem 1] (see also [2]). Here we provide a completely different proof based on a conformal method, a comparison result and integral estimates. We refer to [1, 2] and references therein for previous and related results.

Our second result concerns minimal hypersurfaces with *finite index*. We recall that a minimal immersion $M^n \hookrightarrow (X^{n+1}, h)$ has finite index if the number of negative eigenvalues (counted with multiplicity) of the Jacobi operator L_M on every compact domain in M with Dirichlet boundary conditions is finite. In particular stability implies finite (equal zero) index. In this paper we prove the following:

Theorem 1.2. *If (X^{n+1}, h) is a closed $(n+1)$ -dimensional, $n \leq 5$, manifold with non-negative sectional curvature and positive Ricci curvature, then every complete, orientable, immersed, minimal hypersurface $M^n \hookrightarrow (X^{n+1}, h)$ with finite index must be compact.*

As a byproduct we have the following

Corollary 1.3. *If (X^{n+1}, h) is a closed $(n+1)$ -dimensional, $n \leq 5$, manifold with non-negative sectional curvature and positive Ricci curvature, then there is no complete, orientable, immersed, stable minimal hypersurface $M^n \hookrightarrow (X^{n+1}, h)$.*

In particular, there is no complete, orientable, immersed, stable minimal hypersurface of the round spheres $M^n \hookrightarrow (\mathbb{S}^{n+1}, g_{\text{std}})$, provided $n \leq 5$. In dimension $n = 2$ this follows from a more general result proved in [6], while, in dimension $n = 3$, it was recently proved in [3, Corollary 1.5]. As far as we know, Corollary 1.3 is new in the cases $n = 4, 5$. We do not know if Theorem 1.2 and Corollary 1.3 hold also in dimension greater than five.

2. PROOF FOR THEOREM 1.1

In this section we give an alternative proof of [1, Theorem 1] (see Theorem 1.1). The main idea is to use a weighted volume comparison for a suitable conformal metric \tilde{g} together with a new weighted integral estimate inspired by [7]. Let $M^n \hookrightarrow \mathbb{R}^{n+1}$ be a complete, connected, orientable, isometrically immersed, stable minimal hypersurface.

2.1. Conformal change. It is well known (see e.g. [5, Proposition 1]) that, since $M^n \hookrightarrow \mathbb{R}^{n+1}$ is stable, then there exists a positive function $0 < u \in C^\infty(M)$ satisfying

$$-\Delta_g u = |A|_g^2 u \quad \text{on } M. \quad (2.1)$$

Following the line in [5] (see also [4]), let $k > 0$ and consider the conformal metric

$$\tilde{g} = u^{2k} g.$$

where $g = \iota^* h$ is the induced metric on M (and ι denotes the inclusion). First of all we prove the following lower bound for a modified Bakry-Emery-Ricci curvature of \tilde{g} . In particular, this implies the non-negativity of the 2-Bakry-Emery-Ricci curvature of \tilde{g} for a suitable k .

Lemma 2.1. *Let $f := k(n-2) \log u$. Then the Ricci tensor of the metric $\tilde{g} = u^{2k} g$ satisfies*

$$\text{Ric}_{\tilde{g}} + \nabla_{\tilde{g}}^2 f - \frac{1 - k(n-2)}{k(n-2)^2} df \otimes df \geq \left(k - \frac{n-1}{n} \right) |A|_g^2 g$$

in the sense of quadratic forms. In particular, if $n = 3$ and $k = \frac{2}{3}$, then the 2-Bakry-Emery-Ricci tensor $\text{Ric}_{\tilde{g}}^{2,f} := \text{Ric}_{\tilde{g}} + \nabla_{\tilde{g}}^2 f - \frac{1}{2} df \otimes df$ satisfies

$$\text{Ric}_{\tilde{g}}^{2,f} \geq 0.$$

Proof. Since $f = k(n-2) \log u$, we have

$$df = k(n-2) \frac{du}{u}$$

and

$$\nabla_g^2 f = k(n-2) \left(\frac{\nabla_g^2 u}{u} - \frac{du \otimes du}{u^2} \right),$$

which implies

$$\Delta_g f = k(n-2) \left(\frac{\Delta_g u}{u} - \frac{|\nabla_g u|_g^2}{u^2} \right).$$

On the other hand, from the standard formulas for a conformal change of the metric $\tilde{g} = e^{2\varphi}g$, $\varphi \in C^\infty(M)$, $\varphi > 0$ we get

$$\text{Ric}_{\tilde{g}} = \text{Ric}_g - (n-2) (\nabla_g^2 \varphi - d\varphi \otimes d\varphi) - \left[\Delta_g \varphi + (n-2) |\nabla_g \varphi|_g^2 \right] g$$

and

$$\nabla_{\tilde{g}}^2 f = \nabla_g^2 f - (df \otimes d\varphi + d\varphi \otimes df) + g(\nabla f, \nabla \varphi).$$

Note that, in our case, $\varphi = k \log u$; now we exploit the facts that u is a solution of equation (2.1) to write

$$\begin{aligned} \text{Ric}_{\tilde{g}} + \nabla_{\tilde{g}}^2 f &= \text{Ric}_g - k^2(n-2) \frac{du \otimes du}{u^2} + k|A|_g^2 g + k \frac{|\nabla_g u|_g^2}{u^2} g \\ &= \text{Ric}_g - \frac{df \otimes df}{n-2} + k|A|_g^2 g + \frac{|\nabla_g f|_g^2}{k(n-2)^2} g. \end{aligned}$$

From the Cauchy-Schwarz inequality we have

$$|\nabla_g f|_g^2 g \geq df \otimes df,$$

thus

$$\text{Ric}_{\tilde{g}} + \nabla_{\tilde{g}}^2 f \geq \text{Ric}_g + \frac{1-k(n-2)}{k(n-2)^2} df \otimes df + k|A|_g^2 g;$$

from Gauss equations in the minimal case we get $\text{Ric}_g = -A^2$; since A is traceless we have the inequality

$$A^2 \leq \frac{n-1}{n} |A|_g^2 g,$$

and substituting in the previous relation we conclude

$$\text{Ric}_{\tilde{g}} + \nabla_{\tilde{g}}^2 f - \frac{1-k(n-2)}{k(n-2)^2} df \otimes df \geq \left(k - \frac{n-1}{n} \right) |A|_g^2 g.$$

□

2.2. Completeness. From now on we take

$$n = 3, \quad k = \frac{2}{3}$$

and $u \in C^\infty(M)$ a positive solution to (2.1). In the following we prove the completeness of the conformal metric $\tilde{g} = u^{\frac{4}{3}}g$, following the strategy in [5, Theorem 1] and using some computations in [4].

Lemma 2.2. *The metric $\tilde{g} = u^{\frac{4}{3}}g$ is complete.*

Proof. As shown in [5, Theorem 1] we can construct a minimizing geodesic in the metric $\tilde{g} = u^{2k}g$, $\gamma = \gamma(s)$, where s is the arclength in the metric g . As observed in [5, Theorem 1] the completeness of \tilde{g} is equivalent to prove that γ has infinite \tilde{g} length, i.e.

$$\int_0^{+\infty} u^k(\gamma(s)) ds = +\infty.$$

Since γ is minimizing, by the second variation formula, following the computation in the proof of Theorem 1 (with $H = 0$) in [4], we obtain

$$\begin{aligned} (n-1) \int_0^{+\infty} (\varphi_s)^2 u^{-k} ds &\geq \int_0^{+\infty} \varphi^2 u^{-k} \left(k|A|^2 - A_{11}^2 - \sum_{j=2}^n A_{1j}^2 \right) ds \\ &\quad - k(n-2) \int_0^{+\infty} \varphi^2 u^{-k} (\log u)_{ss} ds + k \int_0^{+\infty} \varphi^2 u^{-k} \frac{|\nabla u|^2}{u^2} ds \end{aligned}$$

for every smooth function φ with compact support in $(0, +\infty)$ and for every $k > 0$. Since A is trace-free, we have

$$|A|^2 \geq A_{11}^2 + A_{22}^2 + \dots + A_{nn}^2 + 2 \sum_{j=2}^n A_{1j}^2 \geq \frac{n}{n-1} A_{11}^2 + 2 \sum_{j=2}^n A_{1j}^2,$$

thus

$$k|A|^2 - A_{11}^2 - \sum_{j=2}^n A_{1j}^2 \geq \left(\frac{kn}{n-1} - 1 \right) A_{11}^2 + (2k-1) \sum_{j=2}^n A_{1j}^2.$$

In particular, if

$$k \geq \frac{n-1}{n} \tag{2.2}$$

we have

$$\int_0^{+\infty} \varphi^2 u^{-k} \left(k|A|^2 - A_{11}^2 - \sum_{j=2}^n A_{1j}^2 \right) ds \geq 0.$$

Using this estimate, the fact that $|\nabla u|^2 \geq (u_s)^2$ and integrating by parts, we obtain

$$\begin{aligned} (n-1) \int_0^{+\infty} (\varphi_s)^2 u^{-k} ds &\geq 2k(n-2) \int_0^{+\infty} \varphi \varphi_s u^{-k-1} u_s ds \\ &\quad + k[1 - k(n-2)] \int_0^{+\infty} \varphi^2 u^{-k-2} (u_s)^2 ds. \end{aligned}$$

Let now $\varphi = u^k \psi$, with ψ smooth with compact support in $(0, +\infty)$. We have

$$\begin{aligned} \varphi^2 u^{-k} &= u^k \psi^2, \\ \varphi_s &= k\psi u^{k-1} u_s + u^k \psi_s, \\ (\varphi_s)^2 u^{-k} &= k^2 \psi^2 u^{k-2} (u_s)^2 + u^k (\psi_s)^2 + 2k\psi \psi_s u^{k-1} u_s, \end{aligned}$$

and substituting in the previous relation we get

$$(n-1) \int_0^{+\infty} u^k (\psi_s)^2 ds \geq -2k \int_0^{+\infty} \psi \psi_s u^{k-1} u_s ds + k(1-k) \int_0^{+\infty} \psi^2 u^{k-2} (u_s)^2 ds. \tag{2.3}$$

Let

$$I := \int_0^{+\infty} \psi \psi_s u^{k-1} u_s ds;$$

thus we have

$$I = \frac{1}{k} \int_0^{+\infty} \psi \psi_s (u^k)_s ds = -\frac{1}{k} \int_0^{+\infty} u^k (\psi_s)^2 ds - \frac{1}{k} \int_0^{+\infty} \psi \psi_{ss} u^k ds.$$

Moreover, for every $t > 1$ and using Young's inequality for every $\varepsilon > 0$, we have

$$\begin{aligned} 2kI &= 2ktI + 2k(1-t)I \\ &= -2t \int_0^{+\infty} u^k (\psi_s)^2 ds - 2t \int_0^{+\infty} \psi \psi_{ss} u^k ds + 2k(1-t) \int_0^{+\infty} \psi \psi_s u^{k-1} u_s ds \\ &\leq -2t \int_0^{+\infty} u^k (\psi_s)^2 ds - 2t \int_0^{+\infty} \psi \psi_{ss} u^k ds \\ &\quad + k(t-1)\varepsilon \int_0^{+\infty} \psi^2 u^{k-2} (u_s)^2 ds + \frac{k(t-1)}{\varepsilon} \int_0^{+\infty} u^k (\psi_s)^2 ds. \end{aligned}$$

Assuming

$$k < 1 \tag{2.4}$$

and choosing

$$\varepsilon := \frac{1-k}{t-1}$$

we obtain

$$2kI \leq -2t \int_0^{+\infty} \psi \psi_{ss} u^k ds + k(1-k) \int_0^{+\infty} \psi^2 u^{k-2} (u_s)^2 ds + \left[\frac{k(t-1)^2}{1-k} - 2t \right] \int_0^{+\infty} u^k (\psi_s)^2 ds.$$

From (2.3) we get

$$0 \leq \left[\frac{k(t-1)^2}{1-k} - 2t + (n-1) \right] \int_0^{+\infty} u^k (\psi_s)^2 ds - 2t \int_0^{+\infty} \psi \psi_{ss} u^k ds$$

for every $t > 1$ and every k satisfying (2.2) and (2.4). Let

$$P(t) := \frac{k(t-1)^2}{1-k} - 2t + (n-1)$$

and choose $k = \frac{n-1}{n}$. It is easy to see that $P(t)$ is negative for some $t > 1$ if $n = 3$: indeed

$$P(t) = (n-1)t^2 - 2nt + 2(n-1) = 2t^2 - 6t + 4 = -2(t-1)(2-t).$$

Therefore, if $n = 3$, $k = \frac{2}{3}$ and $t = \frac{3}{2}$, we deduce

$$0 \leq - \int_0^{+\infty} u^{\frac{2}{3}} (\psi_s)^2 ds - 6 \int_0^{+\infty} u^{\frac{2}{3}} \psi \psi_{ss} ds$$

for every ψ smooth with compact support in $(0, +\infty)$. Now we choose $\psi = s\eta$ with η smooth with compact support in $(0, +\infty)$: thus

$$\psi_s = \eta + s\eta_s, \quad \psi_{ss} = 2\eta_s + s\eta_{ss},$$

and we get

$$\int_0^{+\infty} u^{\frac{2}{3}} \eta^2 ds \leq \int_0^{+\infty} u^{\frac{2}{3}} (-14s\eta\eta_s - 6s^2\eta\eta_{ss} - s^2(\eta_s)^2) ds.$$

Choose η so that $\eta \equiv 1$ on $[0, R]$, $\eta \equiv 0$ on $[2R, +\infty)$ and with $|\eta_s|$ and $|\eta_{ss}|$ bounded by C/R and C/R^2 respectively for $R \leq s \leq 2R$. Then

$$\int_0^R u^{\frac{2}{3}} ds \leq \int_0^{+\infty} u^{\frac{2}{3}} \eta^2 ds \leq C \int_R^{+\infty} u^{\frac{2}{3}} ds$$

for some $C > 0$ independent of R . We conclude that

$$\int_0^{+\infty} u^{\frac{2}{3}} ds = +\infty,$$

i.e. $\tilde{g} = u^{\frac{4}{3}}g$ is complete. \square

2.3. Weighted integral estimates. From lemma 2.1 and lemma 2.2 we have that the metric $\tilde{g} = u^{\frac{4}{3}}g$ is complete and it has non-negative 2-Bakry-Emery-Ricci curvature. Using well known comparison results (see [8, Theorem A.1]) we immediately obtain the following weighted Bishop-Gromov volume estimate for a geodesic ball $B_R^{\tilde{g}}(x_0)$ centered at $x_0 \in M$, of radius R , with respect to the metric \tilde{g} .

Corollary 2.3. *Let $x_0 \in M^3$. Then, for every $R > 0$, there exists $C > 0$ such that the f -volume*

$$\text{Vol}_f B_R^{\tilde{g}}(x_0) := \int_{B_R^{\tilde{g}}(x_0)} e^{-f} dV_{\tilde{g}} \leq CR^5,$$

where $f = \frac{2}{3} \log u$. Equivalently, in terms of u and the volume form of g ,

$$\int_{B_R^{\tilde{g}}(x_0)} u^{\frac{4}{3}} dV_g \leq CR^5.$$

The last ingredient that we need in the proof of Theorem 1.1 is the following weighted integral inequality in the spirit of [7, Theorem 1].

Lemma 2.4. *For every $0 < \delta < \frac{1}{100}$, there exists $C > 0$ such that*

$$\int_M |A|^{5+\delta} u^{-2-\frac{2\delta}{3}} \psi^{5+\delta} dV_g \leq C \int_M u^{-2-\frac{2\delta}{3}} |\nabla \psi|^{5+\delta} dV_g \quad \forall \psi \in C_0^\infty(M).$$

Proof. We do part of the computations for every n . From [7, Formulas (2.1)-(2.3)] we get

$$\int_M |A|^p f^2 \leq C \int_M |A|^{p-2} |\nabla f|^2 \quad \forall f \in C_0^\infty(M), \quad (2.5)$$

for every $p \in [4, 4 + \sqrt{8/n}]$ and for some $C > 0$. Take $f = u^\alpha \psi$, with ψ smooth with compact support, u the solution of (2.1) and $\alpha < 0$. Since, from Cauchy-Schwarz and Young's inequalities,

$$|\nabla(u^\alpha \psi)|^2 \leq 2\psi^2 |\nabla(u^\alpha)|^2 + 2u^{2\alpha} |\nabla \psi|^2, \quad (2.6)$$

then (2.5) becomes

$$\int_M |A|^p u^{2\alpha} \psi^2 \leq 2C \left[\int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 + \int_M |A|^{p-2} u^{2\alpha} |\nabla \psi|^2 \right] \quad \forall \psi \in C_0^\infty(M). \quad (2.7)$$

Now we tackle the first integral on the right-hand side of (2.7) firstly integrating by parts

$$\begin{aligned} \int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 &= - \int_M |A|^{p-2} \psi^2 u^\alpha \Delta u^\alpha - \int_M u^\alpha \psi^2 \langle \nabla u^\alpha, \nabla |A|^{p-2} \rangle \\ &\quad - 2 \int_M |A|^{p-2} u^\alpha \psi \langle \nabla u^\alpha, \nabla \psi \rangle, \end{aligned}$$

secondly we use the fact that

$$\Delta u^\alpha = \alpha u^{\alpha-1} \Delta u + \alpha(\alpha-1) u^{\alpha-2} |\nabla u|^2 \quad \text{and} \quad |\nabla u^\alpha|^2 = \alpha^2 u^{2\alpha-2} |\nabla u|^2,$$

together with Cauchy-Schwarz and Young's inequalities to get

$$\begin{aligned} \int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 &\leq -\alpha \int_M |A|^{p-2} u^{2\alpha-1} \psi^2 \Delta u - \frac{\alpha-1}{\alpha} \int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 \\ &\quad - \int_M u^\alpha \psi^2 \langle \nabla u^\alpha, \nabla |A|^{p-2} \rangle + \varepsilon \int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 + \frac{1}{\varepsilon} \int_M |A|^{p-2} u^{2\alpha} |\nabla \psi|^2, \end{aligned}$$

for all $\varepsilon > 0$. From (2.1) we find

$$\begin{aligned} \int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 &\leq \alpha \int_M |A|^p u^{2\alpha} \psi^2 - \frac{\alpha-1}{\alpha} \int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 \\ &- \int_M u^\alpha \psi^2 \langle \nabla u^\alpha, \nabla |A|^{p-2} \rangle + \varepsilon \int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 + \frac{1}{\varepsilon} \int_M |A|^{p-2} u^{2\alpha} |\nabla \psi|^2, \end{aligned}$$

i.e.

$$\begin{aligned} \left(1 - \varepsilon + \frac{\alpha-1}{\alpha}\right) \int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 &\leq \alpha \int_M |A|^p u^{2\alpha} \psi^2 \\ &- \int_M u^\alpha \psi^2 \langle \nabla u^\alpha, \nabla |A|^{p-2} \rangle + \frac{1}{\varepsilon} \int_M |A|^{p-2} u^{2\alpha} |\nabla \psi|^2, \end{aligned}$$

Now, since

$$\nabla |A|^{p-2} = (p-2) |A|^{p-3} \nabla |A| = (p-2) |A|^{\frac{p-2}{2}} |A|^{\frac{p-4}{2}} \nabla |A|,$$

then, from Cauchy-Schwarz and Young's inequalities we obtain

$$\begin{aligned} \left(1 - \varepsilon + \frac{\alpha-1}{\alpha} - \frac{p-2}{2t_1}\right) \int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 &\leq \alpha \int_M |A|^p u^{2\alpha} \psi^2 \\ &+ \frac{(p-2)t_1}{2} \int_M |A|^{p-4} \psi^2 u^{2\alpha} |\nabla |A||^2 + \frac{1}{\varepsilon} \int_M |A|^{p-2} u^{2\alpha} |\nabla \psi|^2, \end{aligned} \quad (2.8)$$

for every $t_1 > 0$. Now we use Simon's identity and the improved Kato's inequality as in [7, Equation (1.34)] to obtain

$$|A| |\Delta |A|| + |A|^4 \geq \frac{2}{n} |\nabla |A||^2.$$

Multiplying by $|A|^{p-4} f^2$, integrating by parts and using Young's inequality we obtain

$$\int_M |A|^p f^2 \geq \left(\frac{2}{n} + p - 3 - t_2\right) \int_M |A|^{p-4} |\nabla |A||^2 f^2 - \frac{1}{t_2} \int_M |A|^{p-2} |\nabla f|^2$$

for every $t_2 > 0$. Choosing $f = u^\alpha \psi$ we obtain

$$\begin{aligned} \int_M |A|^p u^{2\alpha} \psi^2 &\geq \left(\frac{2}{n} + p - 3 - t_2\right) \int_M |A|^{p-4} |\nabla |A||^2 u^{2\alpha} \psi^2 \\ &- \left(\frac{1}{t_2} + \varepsilon\right) \int_M |A|^{p-2} \psi^2 |\nabla u^\alpha|^2 - \frac{1}{t_2} \left(1 + \frac{1}{t_2 \varepsilon}\right) \int_M |A|^{p-2} u^{2\alpha} |\nabla \psi|^2 \end{aligned} \quad (2.9)$$

for every $\varepsilon > 0$, since

$$|\nabla(u^\alpha \psi)|^2 \leq (1 + t_2 \varepsilon) \psi^2 |\nabla(u^\alpha)|^2 + \left(1 + \frac{1}{t_2 \varepsilon}\right) u^{2\alpha} |\nabla \psi|^2.$$

Now let $\delta > 0$. Using (2.9) in (2.8) with

$$\alpha = -1 - \frac{\delta}{3} \leq -1$$

we obtain

$$\begin{aligned} \left(1 + \frac{2 + \frac{\delta}{3}}{1 + \frac{\delta}{3}} - 2\varepsilon - \frac{p-2}{2t_1} - \frac{1}{t_2}\right) \int_M |A|^{p-2} \psi^2 |\nabla u^{-1-\frac{\delta}{3}}|^2 &\leq \left[\frac{1}{\varepsilon} + \frac{1}{t_2} \left(1 + \frac{1}{t_2 \varepsilon}\right)\right] \int_M |A|^{p-2} u^{-2-\frac{2\delta}{3}} |\nabla \psi|^2 \\ &+ \left[\frac{(p-2)t_1}{2} - \frac{2}{n} - p + 3 + t_2\right] \int_M |A|^{p-4} \psi^2 u^{-2-\frac{2\delta}{3}} |\nabla |A||^2, \end{aligned}$$

for all $\varepsilon, t_1, t_2 > 0$. Let

$$n = 3, \quad p = 5 + \delta, \quad t_1 = \frac{2(5 + 3\delta)}{3(3 + \delta)}, \quad t_2 = 1$$

we obtain

$$\frac{(p-2)t_1}{2} - \frac{2}{n} - p + 3 + t_2 = 0$$

and

$$1 + \frac{2 + \frac{\delta}{3}}{1 + \frac{\delta}{3}} - \frac{p-2}{2t_1} - \frac{1}{t_2} = \frac{39 + 11\delta - 15\delta^2 - 3\delta^3}{60 + 56\delta + 12\delta^2}.$$

Thus

$$\left(\frac{39 + 11\delta - 15\delta^2 - 3\delta^3}{60 + 56\delta + 12\delta^2} - 2\varepsilon \right) \int_M |A|^{3+\delta} \psi^2 |\nabla u^{-1-\frac{\delta}{3}}|^2 \leq \left(1 + \frac{2}{\varepsilon} \right) \int_M |A|^{3+\delta} u^{-2-\frac{2\delta}{3}} |\nabla \psi|^2,$$

for all $\varepsilon > 0$. Choosing $0 < \delta < 1/100$ and ε small enough we obtain

$$\int_M |A|^{3+\delta} \psi^2 |\nabla u^{-1-\frac{\delta}{3}}|^2 \leq C \int_M |A|^{3+\delta} u^{-2-\frac{2\delta}{3}} |\nabla \psi|^2,$$

for some $C > 0$. From (2.7) and Young's inequality we get

$$\begin{aligned} \int_M |A|^{5+\delta} u^{-2-\frac{2\delta}{3}} \psi^2 &\leq C \int_M |A|^{3+\delta} u^{-2-\frac{2\delta}{3}} |\nabla \psi|^2 \\ &\leq \varepsilon' \int_M |A|^{5+\delta} u^{-2-\frac{2\delta}{3}} \psi^2 + \frac{C}{\varepsilon'} \int_M u^{-2-\frac{2\delta}{3}} |\nabla \psi|^{5+\delta} \psi^{-(3+\delta)} \end{aligned}$$

for all $\varepsilon' > 0$ and $\psi \in C_0^\infty(M)$. Therefore

$$\begin{aligned} \int_M |A|^{5+\delta} u^{-2-\frac{2\delta}{3}} \psi^2 &\leq C \int_M u^{-2-\frac{2\delta}{3}} |\nabla \psi|^{5+\delta} \psi^{-(3+\delta)} \\ &= C \int_M u^{-2-\frac{2\delta}{3}} |\nabla \psi|^{\frac{2}{5+\delta}} |^{5+\delta}. \end{aligned}$$

The conclusion now follows immediately by replacing ψ with $\psi^{\frac{2}{5+\delta}}$. \square

2.4. Final estimate. Combining Lemma 2.4 with Corollary 2.3 we can conclude the proof of Theorem 1.1. More precisely, let $x_0 \in M$ and let \tilde{r} the distance function from x_0 with respect to the metric $\tilde{g} = u^{\frac{4}{3}}g$. We choose $\psi := \eta(\tilde{r})$ with $0 \leq \eta \leq 1$, $\eta \equiv 1$ on $[0, R]$, $\eta \equiv 0$ on $[2R, +\infty)$ and $|\eta'| \leq C/R$ on $[R, 2R]$, for some $C > 0$ and $R > 0$. From Lemma 2.4, for some $0 < \delta < 1/100$, we have

$$\begin{aligned} \int_M |A|^{5+\delta} u^{-2-\frac{2\delta}{3}} \eta^{5+\delta} dV_g &\leq C \int_M u^{-2-\frac{2\delta}{3}} |\nabla \eta|_g^{5+\delta} dV_g \\ &= C \int_M u^{-2-\frac{2\delta}{3} + \frac{2(5+\delta)}{3}} |\nabla \eta|_{\tilde{g}}^{5+\delta} dV_g \\ &\leq \frac{C}{R^{5+\delta}} \int_{B_{2R}^{\tilde{g}}(x_0)} u^{\frac{4}{3}} dV_g \\ &\leq \frac{C}{R^\delta}, \end{aligned}$$

where we used the fact that $|\nabla \tilde{r}|_{\tilde{g}} \equiv 1$ and Corollary 2.3. Since $\delta > 0$, letting $R \rightarrow +\infty$ we get

$$|A| \equiv 0 \quad \text{on } M^3$$

and this concludes the proof of Theorem 1.1.

3. CLOSED AMBIENT SPACE: PROOF OF THEOREM 1.2

Proof of Theorem 1.2. Let (X^{n+1}, h) be a closed n -dimensional, $n \leq 5$, manifold with non-negative sectional curvature and positive Ricci curvature and consider an orientable, immersed, minimal hypersurface $M^n \rightarrow (X^{n+1}, h)$ with finite index. Suppose, by contradiction, that M is non-compact. It is well known (see [5, Proposition 1]) that there exist $0 < u \in C^\infty(M)$ and a compact subset $K \subset M$ such that u solves

$$-\Delta u = [|A|^2 + \text{Ric}_h(\nu, \nu)] u \quad \text{on } M \setminus K.$$

Let $k > 0$ and consider the conformal metric

$$\tilde{g} = u^{2k} g.$$

where g is the induced metric on M . Let s be the arc length with respect to the metric g . Following the construction in [5, Theorem 1], we can construct a minimizing geodesic $\tilde{\gamma}(s) : [0, +\infty) \rightarrow M \setminus K$ in the metric \tilde{g} which has infinite length in the metric g . Now we can argue exactly as in the proof of estimate (6) in [4], using $H \equiv 0$, obtaining

$$\begin{aligned} (n-1) \int_0^a (\varphi_s)^2 ds &\geq k(n-3) \int_0^a \varphi \varphi_s \frac{u_s}{u} ds + \frac{k[4-k(n-1)]}{4} \int_0^a \varphi^2 \left(\frac{u_s}{u}\right)^2 ds \\ &\quad + \int_0^a \varphi^2 \left(k \text{Ric}_h(\nu, \nu) + \sum_{j=2}^n R_{1j1j}^h \right) ds \\ &\quad + \int_0^a \varphi^2 \left(k|A|^2 - A_{11}^2 - \sum_{j=2}^n A_{1j}^2 \right) ds, \end{aligned}$$

for every smooth function φ such that $\varphi(0) = \varphi(a) = 0$ and for every $k > 0$. Since (N^{n+1}, h) is closed with non-negative sectional curvature and positive Ricci curvature, we have $R_{1j1j}^h \geq 0$ for every $j = 2, \dots, n$ and

$$\text{Ric}_h(\nu, \nu) \geq R_0 > 0.$$

Theoreme

$$\begin{aligned} (n-1) \int_0^a (\varphi_s)^2 ds &\geq k(n-3) \int_0^a \varphi \varphi_s \frac{u_s}{u} ds + \frac{k[4-k(n-1)]}{4} \int_0^a \varphi^2 \left(\frac{u_s}{u}\right)^2 ds \\ &\quad + \int_0^a \varphi^2 \left(kR_0 + k|A|^2 - A_{11}^2 - \sum_{j=2}^n A_{1j}^2 \right) ds. \end{aligned}$$

Since A is trace-free, we have

$$|A|^2 \geq A_{11}^2 + A_{22}^2 + \dots + A_{nn}^2 + 2 \sum_{j=2}^n A_{1j}^2 \geq \frac{n}{n-1} A_{11}^2 + 2 \sum_{j=2}^n A_{1j}^2,$$

thus

$$k|A|^2 - A_{11}^2 - \sum_{j=2}^n A_{1j}^2 \geq \left(\frac{kn}{n-1} - 1 \right) A_{11}^2 + (2k-1) \sum_{j=2}^n A_{1j}^2.$$

Choose

$$k = \frac{n-1}{n}.$$

We get

$$\int_0^a (\varphi_s)^2 ds \geq \frac{n-3}{n} \int_0^a \varphi \varphi_s \frac{u_s}{u} ds + \frac{6n-n^2-1}{4n^2} \int_0^a \varphi^2 \left(\frac{u_s}{u}\right)^2 ds + \frac{R_0}{n} \int_0^a \varphi^2 ds.$$

If $n \leq 5$, we have

$$\frac{6n - n^2 - 1}{4n^2} \geq \delta_0 > 0.$$

Moreover, there exists $C > 0$, such that

$$\frac{n-3}{n} \varphi \varphi_s \frac{u_s}{u} \geq -\delta_0 \varphi^2 \left(\frac{u_s}{u} \right)^2 - C(\varphi_s)^2.$$

Therefore, there exists $C > 0$, such that

$$C \int_0^a (\varphi_s)^2 ds \geq \frac{R_0}{n} \int_0^a \varphi^2 ds$$

for every smooth function φ such that $\varphi(0) = \varphi(a) = 0$. Integrating by parts we obtain

$$\int_0^a (\varphi \varphi_{ss} + CR_0 \varphi^2) ds \leq 0.$$

Choosing $\varphi(s) = \sin(\pi s a^{-1})$, $s \in [0, a]$ one has

$$\left(CR_0 - \frac{\pi^2}{a^2} \right) \int_0^a \sin^2(\pi s a^{-1}) ds \leq 0$$

i.e.

$$a^2 \leq \frac{\pi^2}{CR_0}.$$

We conclude that the length (in the metric g) of the geodesic $\tilde{\gamma}(s)$ is finite and this gives a contradiction. Therefore (M^n, g) must be compact and this concludes the proof of Theorem 1.2. \square

Proof of Corollary 1.3. If M is stable, by Theorem 1.2 it must be compact. Moreover there exists $u > 0$ satisfying

$$-\Delta u = [|A|^2 + \text{Ric}_h(\nu, \nu)] u \quad \text{on } M.$$

Integrating over M we get a contradiction, since $\text{Ric}_h > 0$ on M . Equivalently, one can use $f \equiv 1$ in the stability inequality (1.1) to get a contradiction. \square

Acknowledgments. *The first and the second authors are members of the GNSAGA, Gruppo Nazionale per le Strutture Algebriche, Geometriche e le loro Applicazioni of INdAM. The third author is member of GNAMPA, Gruppo Nazionale per l'Analisi Matematica, la Probabilità e le loro Applicazioni of INdAM.*

Data availability statement

Data sharing not applicable to this article as no datasets were generated or analysed during the current study.

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