THE DIRICHLET PROBLEM FOR A FAMILY OF TOTALLY DEGENERATE DIFFERENTIAL OPERATORS

MARIA MANFREDINI, MIRCO PICCININI, AND SERGIO POLIDORO

ABSTRACT. In the framework of Potential Theory we prove existence for the Perron-Weiner-Brelot-Bauer solution to the Dirichlet problem related to a family of totally degenerate, in the sense of Bony, differential operators. We also state and prove a Wiener-type criterium and an exterior cone condition for the regularity of a boundary point. Our results apply to a wide family of strongly degenerate operators that includes the following example $\mathcal{L} = t^2 \Delta_x + \langle x, \nabla_y \rangle - \partial_t$, for $(x, y, t) \in \mathbb{R}^N \times \mathbb{R}$.

1. INTRODUCTION

We consider second-order partial differential operators of the form

(1.1)
$$\mathcal{L} := t^{2\vartheta} \sum_{i=1}^{m} \partial_{x_i}^2 + \sum_{i,j=1}^{N} b_{ij} x_j \partial_{x_i} - \partial_t,$$

where $z = (x, t) \in \mathbb{R}^{N+1}$, m, N and ϑ are non-negative integers with $1 \le m \le N$. Moreover, b_{ij} is a real constant for every i, j = 1, ..., N. The standing assumption of this article is:

[H.1] The matrix $B := (b_{ij})_{i,j=1,\dots,N}$ has the form

	0	0		0	0
	B_1	0		0	0
B =	0	B_2		0	0
	:	÷	·	÷	:
	0	0		B_{κ}	0

where every block B_j is a $m_j \times m_{j-1}$ matrix of rank m_j with $j = 1, 2, ..., \kappa$. Moreover, every m_j is a positive integer such that

$$m_0 \ge m_1 \ge \ldots \ge m_{\kappa} \ge 1$$
, and $m_0 + m_1 + \ldots + m_{\kappa} = N$.

We agree to let $m_0 := m$ to have a consistent notation, moreover every 0 denotes a block matrix whose entries are zeros.

As we will see in the following Proposition 2.2, the condition [H.1] implies that the operator \mathcal{L} is *hypoelliptic*. This means that, for every open set $U \subseteq \mathbb{R}^{N+1}$, every function $u \in L^1_{loc}(U)$, which solves the equation $\mathcal{L}u = f$ in the distributional sense, belongs to $C^{\infty}(U)$ whenever $f \in C^{\infty}(U)$. In particular, u is a classical solution to $\mathcal{L}u = f$.

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In the framework of Potential Theory, we address the boundary value problem

(1.2)
$$\begin{cases} \mathcal{L}u = 0 & \text{ in } U, \\ u = \phi & \text{ in } \partial U, \end{cases}$$

where U is any open subset of \mathbb{R}^{N+1} and $\phi \in C_c(\partial U)^1$. The Perron-Weiner-Brelot-Bauer method provides us with a function H^U_{ϕ} which is a classical solution to $\mathcal{L}H^U_{\phi} = 0$ in U.

Theorem 1.1. Every open set $U \subseteq \mathbb{R}^{N+1}$ is resolutive, i.e. for every $\phi \in C_c(\partial U)$ it is defined the Perron-Weiner-Brelot-Bauer solution H^U_{ϕ} to the problem (1.2). Moreover $H^U_{\phi} \in C^{\infty}(U)$ is a classical solution to $\mathcal{L}H^U_{\phi} = 0$.

Concerning the boundary value datum, it is well known that solution H^U_{ϕ} to (1.2) does not attain the prescribed boundary datum at every point of ∂U . We say that a point $z_o \in \partial U$ is \mathcal{L} -regular if $H^U_{\phi}(z) \to \phi(z_o)$ as $z \to z_o$, for every $\phi \in C_c(\partial U)$. The second main result of this article is a Wiener criterium for the regularity of a boundary point $z_o \in \partial U$. Its statement requires some notation. For any fixed $\lambda \in (0, 1)$ and for every $n \in \mathbb{N}$ we consider the following set

(1.3)
$$U_n^c(z_0) := \left\{ z \in \mathbb{R}^{N+1} \setminus U : \lambda^{-n \log n} \le \Gamma(z_0; z) \le \lambda^{-(n+1) \log(n+1)} \right\} \cup \{ z_0 \}.$$

Here Γ is the fundamental solution of \mathcal{L} , whose explicit expression is given in (2.13). Moreover, we denote with $\widehat{\mathcal{R}}^1_{U_n^c(z_o)}$ the *balayage* of the constant function 1 on the set $U_n^c(z_o)$; see forthcoming Definition 3.20. With this bit notation we have

Theorem 1.2. Let $U \subset \mathbb{R}^{N+1}$ be an open set and let $z_0 = (x_0, 0) \in \partial U$. Then z_0 is an \mathcal{L} -regular point, if and only if

$$\sum_{n=1}^{\infty} \widehat{\mathcal{R}}^{1}_{U_{n}^{c}(z_{\mathrm{o}})}(z_{\mathrm{o}}) = +\infty.$$

The proof of Theorem 1.2 is based on the explicit expression of the fundamental solution Γ of \mathcal{L} and follows the lines of the work [14] of Kogoj, Lanconelli and Tralli, where the regularity of Kolmogorov operator (1.1) with $\vartheta = 0$ is studied. In particular the article [14] extends to degenerate Kolmogorov equations the Wiener-Landis test for the heat equation [10], and a regularity criterion proved by Landis in [18], which again holds for the heat equation.

Finally we give a Zaremba-type criterion for the regularity of boundary points $z_{\rm o} = (x_{\rm o}, 0)$, which is a sufficient geometric condition relying on the definition of *cone* $C(z_{\rm o})$ with vertex at $z_{\rm o}$; see Definition 2.1 below.

Proposition 1.3. Let $U \subset \mathbb{R}^{N+1}$ be an open set and let $z_0 = (x_0, 0) \in \partial U$. If there exists an exterior cone $\mathcal{C}(z_0)$ with vertex at z_0 , then z_0 is \mathcal{L} -regular.

Note that Proposition 1.3 extends the analogous result proved by Manfredini [21] for the case $\vartheta = 0$. The requirement that the time coordinate of z_0 is $t_0 = 0$ both in Theorem 1.2 and in Proposition 1.3 is needed because the definition of the cone $\mathcal{C}(z_0)$ requires a dilation-invariance property of \mathcal{L} which, in the case $\vartheta > 0$, is granted only for $t_0 = 0$ (see (2.4) below) as well as to use the particular invariance properties of the fundamental solution Γ of \mathcal{L} . On the other hand, the exterior cone criterion proved by Manfredini [21, Theorem 6.3] as well as the equivalent characterization of the regularity of boundary points in [17, Theorem 5.4] do apply to every boundary point $z_0 = (x_0, t_0)$ with $t_0 \neq 0$.

¹We indicate with $C_c(\partial U)$ the family of continuous functions on ∂U with compact support

Let us briefly discuss Proposition 1.3 in the simplest case of m = N, $\vartheta = 1$ and B = 0, that is

(1.4)
$$\mathcal{L} = t^2 \Delta_x - \partial_t$$

In this setting, for any $(x,t) \in \mathbb{R}^{N+1}$ and any r > 0, the group of dilations is defined as

$$\delta_r(x,t) := (r^3 x, r^2 t),$$

and following Definition 2.1 the cone of vertex $z_0 := (x_0, 0)$, height T > 0 and base $K \subset \mathbb{R}^N$ is given by

$$\mathcal{C}(z_{o}) := \left\{ (x_{o} + r^{3}x, -r^{2}T) : x \in K, 0 \le r \le 1 \right\}.$$

Note that (1.4) can be reduced to the heat equation by the change of the time-scale $u(x,t) := v(x,t^3/3)$. The classical parabolic cone

$$\widetilde{\mathcal{C}}(z_{\mathrm{o}}) := \left\{ (x_{\mathrm{o}} + rx, -r^{2}\widetilde{T}) : x \in \widetilde{K}, 0 \le r \le 1 \right\},\$$

introduced in [9] by Effros and Kazdan, guarantees the regularity of boundary point z_o for the solution v to problem (1.2) relevant to the heat operator. Inverting the time-scale change of variables defined above $\tilde{\mathcal{C}}(z_o)$ does coincide with $\mathcal{C}(z_o)$. However, this simple argument does not apply to ultraparabolic operators of the type (1.1). Hence, the result stated in Proposition 1.3 can not be proved trivially with a time-scale change of variables in the general setting we are dealing with.

We next give some comments about our main results. The first one concerns the uniqueness of the solution to the Dirichlet problem (1.2). A first simple answer to the uniqueness problem plainly follows from the maximum principle (see Corollary 3.15 below). In particular, it implies that if u and v belong to $C(\overline{U})$, for some bounded open set U, u and v are both classical solutions to (1.2), and attain the same values on ∂U , then necessarily agree. This result is however unsatisfactory. Indeed, it is well known that, if we consider the Cauchy-Dirichlet problem for the heat equation in a cylinder, then the solution is uniquely defined by the boundary condition on the *parabolic boundary* of the cylinder. For this reason, we would expect that only the regular boundary points need to be considered in order to have the uniqueness of the solution to (1.2). Unfortunately, this fact is not true even in the case of the heat equation. Indeed, Lukeš proves in Example 3.2 (D) of [19] that there exist bounded open sets that admit different solutions that agree at every regular boundary point.

The classical Perron method for the Laplace equation relies on the Poisson kernel, which provides us with the solution to the Dirichlet problem on any ball of the Euclidean space. In the more general setting of the abstract Potential Theory the Euclidean balls are replaced by the resolutive sets, that are sets such that the Perron-Weiner-Brelot-Bauer solution is defined. Specifically, it is assumed that there exists a family of resolutive open sets $\{U_i\}_{i \in I}$, such that $\{U_i\}_{i \in I}$ is a basis for the topology of the space. Note that, unlike in the case of the Laplace equation, it is not required that all the boundary points of a resolutive set are regular.

The development of Potential Theory is simpler in the case of the existence of a basis of regular sets, which are resolutive sets whose all the boundary points are regular. For this reason, even in the case of the heat operator, an effort has be done in order to build a basis of regular sets for the space \mathbb{R}^{N+1} . In particular, Bauer first pointed out in [4] that the cones defined for $(x_0, t_0) \in \mathbb{R}^{N+1}$, and r > 0 as

$$K_r(x_{\rm o}, t_{\rm o}) = \{ (x, t) \in \mathbb{R}^{N+1} : |x - x_{\rm o}| < t_{\rm o} - t < r \},\$$

have this property. Later Effros and Kazdan introduce in [9] regular sets that are build as follows. Every set is the union of the cylinder

$$\widetilde{Q}_{r}(x_{o}, t_{o}) = \{(x, t) \in \mathbb{R}^{N+1} : |x - x_{o}| < r, t_{o} - 2r < t \le t_{o} - r\},\$$

and the cone $K_r(x_0, t_0)$. The regularity of the boundary points for the above families of sets is proved by a simple barrier argument, which relies on the fact that, for every point of the lateral boundary of the cone, the spatial component ν_x of the outer normal $\nu = (\nu_x, \nu_t) \in \mathbb{R}^{N+1}$ is non zero.

Bony considers in [5] the boundary value problem (1.2) for degenerate operators in the form

(1.5)
$$\mathcal{L} = \sum_{j=1}^{m} X_j^2 + Y,$$

where X_1, \ldots, X_m and Y are vector fields defined in a domain $\Omega \subset \mathbb{R}^{N+1}$, with smooth coefficients, satisfying Hörmander's condition [11]

(1.6)
$$\operatorname{Lie}(X_1, \dots, X_m, Y)(z) = \mathbb{R}^{N+1}, \quad \text{for every } z \in \Omega$$

We recall that $\text{Lie}(X_1, \ldots, X_m, Y)$ is the Lie algebra generated by the vector fields X_1, \ldots, X_m and Y, that is the vector space generated by X_1, \ldots, X_m, Y and their commutators. The commutator of two given vector fields W and Z is the vector field defined as:

$$[W, Z] := W Z - Z W.$$

In his work, Bony restricts his study to non totally degenerate operators. This means that, for every $z \in \mathbb{R}^{N+1}$, at least one of the vector fields $X_1(z), \ldots, X_m(z)$ is non zero. The non total degeneracy of the operator \mathcal{L} allows Bony to build a family of bounded open regular sets by a general method that relies on a barrier argument. Note that for $\vartheta = 0$ the Bony's theory applies to the operator \mathcal{L} . We refer the reader to [7], [13], [16] and [21] for the study of the relevant Dirichlet problem.

We remark that the non total degeneracy of the operator \mathcal{L} is a mild requirement. Indeed, from the very definition of commutator it follows that

$$W(z) = 0$$
 and $Z(z) = 0 \Rightarrow [W, Z](z) = 0$,

thus

$$X_1(z) = 0, \dots, X_m(z) = 0, Y(z) = 0 \quad \Rightarrow \quad \text{Lie}(X_1, \dots, X_m, Y)(z) = \{0\}.$$

In particular, if \mathcal{L} satisfies Hörmander's condition, then at least one of the vector fields X_1, \ldots, X_m, Y is different from zero. Concerning the operator \mathcal{L} , it can be written in the form (1.5) with

$$X_j := t^{\vartheta} \partial_{x_j}, \quad j = 1, \dots, m, \qquad Y := \langle Bx, D \rangle - \partial_t$$

and, as we say in Proposition 2.2, the assumption [H.1] is equivalent to Hörmander's condition, even though \mathcal{L} is totally degenerate at t = 0, for $\vartheta \ge 1$.

In this work we rely on the construction of the Perron-Weiner-Brelot-Bauer solution to the Dirichlet problem (1.2) based on the existence of a family of *resolutive sets*, as explained in the monograph [8] by Constantinescu and Cornea. We recall that a family of resolutive sets for operators in the form (1.1) satisfying the assumption [H.1] has been built by Montanari in [22]. We point out that in the particular case of the heat operator, these resolutive sets agree with the standard cylinders.

Outline of the article. In Section 2 we specify the notation adopted throughout the rest of the article and recall some known results about the operator \mathcal{L} . Moreover, we also give a detailed proof of the hypoellipticity of \mathcal{L} . In Section 3 we recall all the notions and results from Potential Theory that we need. We also give a characterization of boundary regularity in the abstract setting of Potential Theory; see forthcoming Theorem 3.30. In Section 4 we construct the Perron-Weiner-Brelot-Bauer solution of the problem (1.2) and prove Theorem 1.1. In Section 5 we prove Theorem 1.2 and Proposition 1.3.

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2. Preliminaries

In this section we specify the notation adopted throughout the rest of the paper and provide some known results about the family of operators we are dealing with. We also give a detailed proof of the hypoellipticity of \mathcal{L} and of the existence of its fundamental solution.

We denote with c a positive universal constant greater than one, which may change from line to line. For the sake of readability, dependencies of the constants will be often omitted within the chains of estimates, therefore stated after the estimate. Relevant dependencies on parameters will be emphasized by using parentheses.

For any $U \subset \mathbb{R}^{N+1}$ we denote with |U| the Lebesgue measure of U. As customary, for any r > 0 and any $y_o \in \mathbb{R}^{N+1}$ we denote by $B_r(y_o) \equiv B(y_o; r) := \{y \in \mathbb{R}^{N+1} : |y - y_o| < r\}$, the open ball with radius r and center y_o . Here and in the following of this note we write the operator \mathcal{L} in Hörmander's form

$$\mathcal{L} = \sum_{j=1}^{m} (t^{\vartheta} \partial_{x_j})^2 + \langle Bx, \nabla \rangle - \partial_t = \sum_{j=1}^{m} X_j^2 + Y,$$

with

$$X_j := t^{\vartheta} \partial_{x_j}, \qquad Y := \langle Bx, \nabla \rangle - \partial_t,$$

for j = 1, ..., m. As usual in the theory of Hörmander's operators, we identify any vector field X with the vector valued function whose entries are the coefficients of X, specifically

$$X = \sum_{j=1}^{N} c_j(x,t) \partial_{x_j} + c_0(x,t) \partial_t \simeq (c_1(x,t), \dots, c_N(x,t), c_0(x,t)).$$

We denote by A and e^{-sB} the $N \times N$ matrices defined as

(2.1)
$$A := \begin{bmatrix} I_{m_0} & 0\\ 0 & 0 \end{bmatrix} \qquad e^{-sB} := \sum_{n=0}^{\infty} \frac{(-1)^n s^n}{n!} B^n \,,$$

where I_{m_0} is the $m_0 \times m_0$ identity matrix and s is any real number. For every $t, \tau \in \mathbb{R}$ we eventually define the matrix

(2.2)
$$C(\tau,t) := \int_0^{t-\tau} (t-s)^{2\vartheta} e^{-sB} A e^{-sB^T} \mathrm{d}s.$$

We spend few words about some geometric aspects related to the operator \mathcal{L} . In the article [16] the composition law

(2.3)
$$(x,t) \circ (\xi,\tau) = (\xi + e^{-\tau B}x, t+\tau) \quad (x,t), (\xi,\tau) \in \mathbb{R}^{N+1}$$

was introduced and it was proved that $\mathbb{K} := (\mathbb{R}^{N+1}, \circ)$ is a non-commutative Lie group with zero element (0, 0) and inverse element given by

$$(x,t)^{-1} = (-e^{tB}x,-t) \quad \forall (x,t) \in \mathbb{R}^{N+1}$$

Moreover, the operator \mathcal{L} with $\vartheta = 0$ is invariant with respect to the left translation (2.3). We refer the reader to the monograph [3] for a general presentation of the theory of Lie groups and to [1,2] for a survey of results on the operator \mathcal{L} . However, the operator \mathcal{L} is not translation invariant as $\vartheta \geq 1$; see Proposition 1.2.13 in [3]. Nevertheless, the matrix (2.1) will be used also for $\vartheta \geq 1$ in order to define a basis of resolutive sets and to state a Harnack inequality.

For every r > 0, we denote with $\delta_r : \mathbb{R}^{N+1} \to \mathbb{R}^{N+1}$ the family of automorphisms on \mathbb{R}^{N+1} making \mathcal{L} homogeneous of degree two

(2.4)
$$\mathcal{L} \circ \delta_r = r^2 \delta_r \circ \mathcal{L} \qquad \forall r > 0.$$

and whose explicitly expression is given by

(2.5)
$$\delta_r(x,t) := \delta_r(x^{(m_0)}, x^{(m_1)}, \dots, x^{(m_\kappa)}, t) := (r^{2\vartheta+1}x^{(m_0)}, r^{2\vartheta+2}x^{(m_1)}, \dots, r^{2(\vartheta+\kappa)+1}x^{(m_\kappa)}, r^2t),$$

where $x^{(m_j)} \in \mathbb{R}^{m_j}$ for $j = 0, ..., \kappa$ and for r > 0. Throughout the sequel we indicate with $Q + 2 := (2\vartheta + 1)m_0 + (2\vartheta + 2)m_1 + \cdots (2\vartheta + 2\kappa + 1)m_{\kappa} + 2$ the homogeneous dimension of \mathbb{R}^{N+1} with respect to $(\delta_r)_{r>0}$. The number Q will be the homogeneous dimension of \mathbb{R}^N with respect to the family of automorphisms $(D_r)_{r>0}$ given by

(2.6)
$$D_r: \mathbb{R}^N \to \mathbb{R}^N, \quad D_r(x) := \left(r^{2\vartheta+1}x^{(m_0)}, \dots, r^{2(\vartheta+\kappa)+1}x^{(m_\kappa)}\right)$$

Throughout the paper, we will denote with $|\cdot|$ the Euclidean norm on \mathbb{R}^N , \mathbb{R}^{m_j} (for $j = 0, \ldots, \kappa$) or \mathbb{R} . For any $x \in \mathbb{R}^N$ we denote with

(2.7)
$$|x|_C^2 := \frac{1}{4} \langle C^{-1}(-1,0)x, x \rangle.$$

Denoting with $4\sigma_C^2$ the smallest eigenvalue of the positive definite matrix

$$e^{-B^T}C^{-1}(-1,0)e^{-B}$$
,

we have

$$(2.8) |e^{-B}x|_C^2 \ge \sigma_C^2 |x|^2$$

Moreover, we recall that a homogeneous norm $\|\cdot\|:\mathbb{R}^N\to\mathbb{R}_+$ is a D_r -homogeneous function of degree 1 defined as follows

$$||x|| := \sum_{j=0}^{\kappa} \left| x^{(m_j)} \right|^{\frac{1}{2(j+\vartheta)+1}}$$

We call homogeneous cylinder of radius r > 0 and centered in $z_0 = (x_0, 0)$ the set

(2.9)
$$\mathcal{Q}_r(z_0) := \left\{ z = (x,t) \in \mathbb{R}^{N+1} : \|x - e^{-tB}x_0\| < r, \ -r^2 < t \le 0 \right\}.$$

The norms $\|\cdot\|$ and $|\cdot|$ can be compared as follows

$$\sigma \min\left\{ |x|^{\frac{1}{1+2\vartheta}}, |x|^{\frac{1}{2(\kappa+\vartheta)+1}} \right\}$$

(2.10)
$$\leq \|x\| \leq (\kappa+1) \max\left\{ |x|^{\frac{1}{1+2\vartheta}}, |x|^{\frac{1}{2(\kappa+\vartheta)+1}} \right\} \quad \forall x \in \mathbb{R}^N,$$

where $\sigma = \min_{|x|=1} ||x||$. Indeed, on one side we simply have

$$\|x\| \le \sum_{j=0}^{\kappa} |x|^{\frac{1}{2(j+\vartheta)+1}} \le (\kappa+1) \max\left\{ |x|^{\frac{1}{1+2\vartheta}}, |x|^{\frac{1}{2(\kappa+\vartheta)+1}} \right\} \quad \forall x \in \mathbb{R}^{N}.$$

On the other hand, for any $x \neq 0$, we get

$$\frac{\|x\|}{\min\left\{|x|^{\frac{1}{1+2\vartheta}}, |x|^{\frac{1}{2(\kappa+\vartheta)+1}}\right\}} \ge \sum_{j=0}^{\kappa} \frac{|x^{(m_j)}|^{\frac{1}{2(j+\vartheta)+1}}}{|x|^{\frac{1}{2(j+\vartheta)+1}}} = \sum_{j=0}^{\kappa} \left| \left(\frac{x}{|x|}\right)^{(m_j)} \right|^{\frac{1}{2(j+\vartheta)+1}} = \left\|\frac{x}{|x|}\right\| \ge \sigma.$$

Let us give the definition of \mathcal{L} -cone.

Definition 2.1. For any T > 0, R > 0 and any compact subset K of \mathbb{R}^N with positive Lebesgue measure we call \mathcal{L} -cone of vertex $z_0 := (x_0, 0)$, base K and height T, the set

$$\mathcal{C}(z_{o}) := \left\{ (D_{r}x + x_{o}, -r^{2}T) : x \in K, 0 \le r \le R \right\},\$$

where D_r is defined in (2.6).

Given an open subset U of \mathbb{R}^{N+1} and $z_o = (x_o, 0) \in \partial U$ we say that there exists an exterior cone with vertex in z_o if there exists an \mathcal{L} -cone $\mathcal{C}(z_o)$ such that $\mathcal{C}(z_o) \subseteq \mathbb{R}^{N+1} \setminus U$.

We recall some known facts about the operator \mathcal{L} in the case $\vartheta = 0$, which will be useful for the study of the case when $\vartheta \ge 1$.

If $\vartheta = 0$, specifically when

$$\mathcal{L} := \sum_{j=1}^{m} \partial_{x_j}^2 + \langle Bx, \nabla \rangle - \partial_t,$$

the following statements are equivalent to the condition [H.1]:

- (i) (Hörmander's condition): rank Lie $(X_1, \ldots, X_m, Y)(x, t) = N + 1$ for every $(x, t) \in \mathbb{R}^{N+1}$;
- (ii) $\operatorname{Ker}(A)$ does not contain non-trivial subspaces which are invariant for B^T ;
- (iii) $C(\tau, t) > 0$ for every $t > \tau$;
- (iv) (Kalman's rank condition): rank $(A, BA, \dots, B^{N-1}A) = N$.

The equivalence between (i) and (ii) was first proved by Hörmander in [11]. A detailed proof of the equivalence between (i), (ii), (iii) and [H.1] can be found in [16] (see Proposition A.1, and Proposition 2.1). The equivalence between (iii) and (iv) was pointed out by Lunardi in [20]. We next prove that the above result also holds in the case $\vartheta \geq 1$.

Proposition 2.2. The following statements are equivalent to the condition [H.1]:

- (i) (Hörmander's condition): rank Lie $(X_1, \ldots, X_m, Y)(x, t) = N + 1$ for every $(x, t) \in \mathbb{R}^{N+1}$;
- (ii) $\operatorname{Ker}(A)$ does not contain non-trivial subspaces which are invariant for B^T ;
- (iii) $C(\tau, t) > 0$ for every $t > \tau$;
- (iv) Kalman's rank condition): rank $(A, BA, \dots, B^{N-1}A) = N$.

Proof. As said above, the assertion is known to be true in the case $\vartheta = 0$. Moreover, the constant ϑ does not appear in [**H.1**], (*ii*) and (*iv*), hence the equivalence between [**H.1**], (*ii*) and (*iv*) trivially follows from the case $\vartheta = 0$.

We next prove that [H.1] is equivalent to (ii) for every $\vartheta \geq 1$. With this aim, we compare condition (ii) with $\vartheta = 0$ and condition (ii) with $\vartheta \ge 1$. In order to distinguish the two cases we set, for $j = 1, \ldots, m$,

$$\widetilde{X}_j^0 := \partial_{x_j}, \qquad \widetilde{X}_j^k := [\widetilde{X}_j^{k-1}, Y], \qquad k = 1, \dots, \kappa.$$

Moreover, we let

$$V_k := \operatorname{span}\left\{\widetilde{X}_1^k, \dots, \widetilde{X}_m^k\right\}, \qquad k = 0, \dots, \kappa.$$

and we set, for $j = 1, \ldots, m$,

$$X_j^0 := t^\vartheta \partial_{x_j}, \qquad X_j^k := [X_j^{k-1}, Y], \qquad k = 1, \dots, \kappa.$$

A direct computation shows that

$$[t^{\vartheta}\partial_{x_j}, Y] = t^{\vartheta}[\partial_{x_j}, Y] + \vartheta t^{\vartheta - 1}\partial_{x_j}, \qquad j = 1, \dots, m,$$

that can be written as follows

$$X_j^1 = t^\vartheta \widetilde{X}_j^1 + \vartheta t^{\vartheta - 1} \widetilde{X}_j^0, \qquad j = 1, \dots, m.$$

By iterating the same argument, we find

(2.11)
$$X_j^2 = t^{\vartheta} \widetilde{X}_j^2 + 2\vartheta t^{\vartheta - 1} \widetilde{X}_j^1 + \vartheta(\vartheta - 1) t^{\vartheta - 2} \widetilde{X}_j^0, \qquad j = 1, \dots, m$$

and, for k = 3, ..., and j = 1, ..., m,

(2.12)
$$X_j^k = t^{\vartheta} \widetilde{X}_j^k + k \vartheta t^{\vartheta - 1} \widetilde{X}_j^{k-1} + \dots + \vartheta (\vartheta - 1) \dots (\vartheta - k + 1) t^{\vartheta - k} \widetilde{X}_j^0.$$

Note that the last coefficient vanishes whenever $k > \vartheta$.

We are now ready to show that Hörmander's condition (ii) is satisfied by the system of vector fields $\{X_1^k, \ldots, X_m^k, Y\}$ in the set $\{t \neq 0\}$. Indeed, we easily see that, in this case,

$$\operatorname{span}\left\{\widetilde{X}_{1}^{0},\ldots,\widetilde{X}_{m}^{0}\right\}=\operatorname{span}\left\{X_{1}^{0},\ldots,X_{m}^{0}\right\}.$$

Moreover (2.11) implies that

$$\operatorname{span}\left\{\widetilde{X}_{1}^{0},\ldots,\widetilde{X}_{m}^{0},\widetilde{X}_{1}^{1},\ldots,\widetilde{X}_{m_{1}}^{1}\right\}=\operatorname{span}\left\{X_{1}^{1},\ldots,X_{m_{1}}^{1}\right\},$$

for every $t \neq 0$. By the same reason, using the above assertions and (2.12), we conclude that Lie $\{X_1^k, \ldots, X_m^k, Y\}$ agrees with Lie $\{\widetilde{X}_1^k, \ldots, \widetilde{X}_m^k, Y\}$ whenever $t \neq 0$. We are left with the set $\{t = 0\}$. In this case we use (2.12) with $k = \vartheta$ and we find

$$X_j^{\vartheta}(x,0) = \vartheta! X_j^0, \qquad j = 1, \dots, m,$$

for every $x \in \mathbb{R}^N$. This means that \widetilde{X}_i^0 belongs to $\text{Lie}\{X_1^k, \ldots, X_m^k, Y\}$ computed at t = 0. Hence, $\text{Lie}\{X_1^k, \ldots, X_m^k, Y\}$ contains $\text{Lie}\{\widetilde{X}_1^k, \ldots, \widetilde{X}_m^k, Y\}$ and Hörmander's condition (1.6) is satisfied also in the set $\{t = 0\}$. This concludes the proof of the equivalence between [H.1] and (ii).

We next prove that (ii) is equivalent to (iii). We follow Hörmander's argument. We first note that the matrix Ae^{-sB^T} is non negative, for every $s \in \mathbb{R}$. Then $C(\tau, t) \geq 0$ whenever $t \geq \tau$. Moreover, the function $t \mapsto \langle C(\tau, t)\xi, \xi \rangle$ is non-decreasing. We claim that the following assertions are equivalent:

- (1) there exists a $t_{\rm o} > \tau$ such that $\langle C(\tau, t_{\rm o})\xi, \xi \rangle = 0$;
- (2) $\langle C(\tau, t)\xi, \xi \rangle = 0$ fo every $t > \tau$;
- (3) $A(B^T)^k \xi = 0$, for every non-negative integer k.

We first prove that 1. implies 3. Assume that there exists a $t_o > \tau$ and a vector $\xi \in \mathbb{R}^N$ such that $\langle C(\tau, t_o)\xi, \xi \rangle = 0$. Then $\langle C(\tau, t)\xi, \xi \rangle = 0$ for every $t \in [\tau, t_o]$. From the definition of $C(\tau, t)$ (2.2), it follows that

$$s^{2\vartheta} \langle A e^{-sB^T} \xi, e^{-sB^T} \xi \rangle = 0, \quad \text{for every} \quad s \in [\tau, t_o],$$

then

$$\left(\sum_{k=0}^{+\infty} \frac{(-1)^k}{k!} s^{k+2\vartheta} A(B^T)^k\right) \xi = 0, \quad \text{for every} \quad s \in [\tau, t_o],$$

which implies the assertion 3. The implications $3. \Rightarrow 2. \Rightarrow 1$. are trivial and are omitted.

The proof of the equivalence between (ii) and (iii) is a direct consequence of the fact that

$$V := \left\{ \xi \in \mathbb{R}^N : A(B^T)^k \xi = 0 \text{ fo every non-negative integer } k \right\}$$

is the greatest subspace of Ker(A) which is B^T -invariant. This completes the proof of Proposition 2.2.

We emphasize that the condition *(iii)* of Proposition 2.2 is very important in our setting. Indeed, by using the Fourier transform we find the explicit expression of the fundamental solution of \mathcal{L} . Indeed, for every $z = (x, t), \zeta = (\xi, \tau) \in \mathbb{R}^{N+1}$ we have

(2.13)
$$\Gamma(z;\zeta) := \begin{cases} \frac{(4\pi)^{-N/2}}{\sqrt{\det C(\tau,t)}} e^{-\frac{1}{4}\langle C^{-1}(\tau,t)(x-e^{-(t-\tau)B}\xi), x-e^{-(t-\tau)B}\xi \rangle} & \text{if } t > \tau \\ 0 & \text{if } t \le \tau \end{cases}$$

The expression (2.13) was first obtained by Kuptsov under a condition equivalent to (iv), and used by Montanari in [22]. We also recall the scaling property of the fundamental solution Γ with respect to the automorphism (2.5); see [22, Lemma 2.1].

Lemma 2.3. The following properties of the fundamental solution Γ in (2.13) hold true: (i) For any $(x, t), (\xi, \tau) \in \mathbb{R}^{N+1}$

$$\Gamma(x,t;\xi,\tau) = \Gamma(x - e^{-(t-\tau)B}y,t;\xi-y,\tau) \quad \forall y \in \mathbb{R}^N.$$

(ii) For any $(x,t), (\xi,\tau) \in \mathbb{R}^{N+1}$ and any r > 0 it holds

$$\Gamma(x,t;\xi,\tau) = r^Q \Gamma(D_r x, r^2 t; D_r \xi, r^2 \tau).$$

The following properties of the fundamental solution Γ in will the a key tool in the subsequent proof of the sufficient condition in Theorem 1.2.

We start by recalling the following identity, whose proof can be found in [16, Remark 2.1]

(2.14)
$$e^{-r^2sB}D_r = D_r e^{-sB} \qquad \forall r > 0, \, \forall s \in \mathbb{R}.$$

We will need the following lemma.

Lemma 2.4. For $0 > t > \tau$ we have the following matrix inequality

$$e^{-tB^{T}}C^{-1}(\tau,t)e^{-tB} \ge C^{-1}(\tau,0)$$

Proof. Let us begin noticing that for symmetric positive definite matrices we have

$$M_1 \le M_2 \quad \Rightarrow \quad M_1^{-1} \ge M_2^{-1}$$

(see [12, Corollary 7.7.4]) and recalling that $(e^{-tB}) = e^{tB}$, it is enough to show that

(2.15)
$$e^{tB}C(\tau,t)e^{tB^T} \le C(\tau,0).$$

From the very definition of the matrix C we get

$$e^{tB}C(\tau,t)e^{tB^{T}} = e^{tB}\left(\int_{0}^{t-\tau} (t-s)^{2\vartheta}e^{-sB}Ae^{-sB^{T}} ds\right)e^{tB^{T}}$$
$$= \int_{0}^{t-\tau} (t-s)^{2\vartheta}e^{(t-s)B}Ae^{(t-s)B^{T}} ds$$
$$= \int_{-t}^{-\tau} \sigma^{2\vartheta}e^{-\sigma B}Ae^{-\sigma B^{T}} d\sigma.$$

Since $-\tau > -t > 0$ and A is nonnegative definite, we have

$$\int_{-t}^{-\tau} \sigma^{2\vartheta} e^{-\sigma B} A e^{-\sigma B^{T}} \, \mathrm{d}\sigma \le \int_{0}^{-\tau} \sigma^{2\vartheta} e^{-\sigma B} A e^{-\sigma B^{T}} \, \mathrm{d}\sigma = C(\tau, 0)$$

,

which proves (2.15) and the lemma.

Let us now prove an estimate of the ratio $\frac{\Gamma(z,\zeta)}{\Gamma(z_{0},\zeta)}$, for $z_{0} = (x_{0},0)$, z = (x,t) and $\zeta = (\xi,\tau)$ with $0 > t > \tau$. Let us denote with

(2.16)

$$\mu := \frac{-t}{-\tau} \in (0,1),$$

$$M(z_{o},z) := \left| D_{\frac{1}{\sqrt{-t}}} (x - e^{-tB} x_{o}) \right|,$$
and
$$M(z_{o},\zeta) := \left| D_{\frac{1}{\sqrt{-\tau}}} (\xi - e^{-\tau B} x_{o}) \right|$$

Lemma 2.5. Fix $z_0 = (x_0, 0) \in \mathbb{R}^{N+1}$. There exists a positive constant c such that, for any $z = (x, t), \zeta = (\xi, \tau)$ with $0 > t > \tau$ and $\mu \leq \min\{\frac{1}{2}, \frac{\sigma^2}{(\kappa+1)^2}\}$, we have

$$\frac{\Gamma(z,\zeta)}{\Gamma(z_{\rm o},\zeta)} \le \left(\frac{1}{1-\mu}\right)^{\frac{Q}{2}} e^{c\sqrt{\mu}M(z_{\rm o},z)M(z_{\rm o},\zeta)}.$$

where μ and $M(\cdot)$ are both defined in (2.16).

Proof. Applying the transformation in Lemma 2.3 we obtain that

$$\begin{split} \Gamma(z,\zeta) &= (t-\tau)^{-\frac{Q}{2}} \Gamma(D_{\frac{1}{\sqrt{t-\tau}}}(x-e^{-(t-\tau)B}\xi), \frac{t}{t-\tau}; 0, \frac{\tau}{t-\tau}) \\ &= \frac{c(t-\tau)^{-\frac{Q}{2}}}{\sqrt{\det C(\frac{\tau}{t-\tau}, \frac{t}{t-\tau})}} e^{-\frac{1}{4}\langle C^{-1}(\tau,t)(x-e^{-(t-\tau)B}\xi), x-e^{-(t-\tau)B}\xi\rangle} \\ &= \frac{c(t-\tau)^{-\frac{Q}{2}}}{\sqrt{\det C(-\frac{1}{1-\mu}, -\frac{\mu}{1-\mu})}} e^{-\frac{1}{4}\langle C^{-1}(\tau,t)(x-e^{-(t-\tau)B}\xi), x-e^{-(t-\tau)B}\xi\rangle} \end{split}$$

and, similarly, we have

$$\Gamma(z_{\rm o},\zeta) = \frac{c(-\tau)^{-\frac{Q}{2}}}{\sqrt{\det C(-1,0)}} e^{-\left|D_{\frac{1}{\sqrt{-\tau}}}(x_{\rm o}-e^{\tau B}\xi)\right|_{C}^{2}},$$

recalling the definition of $|\cdot|_C$ in (2.7).

Then, since

$$\frac{(t-\tau)^{-\frac{Q}{2}}\sqrt{\det C(-1,0)}}{(-\tau)^{-\frac{Q}{2}}\sqrt{\det C(-\frac{1}{1-\mu},-\frac{\mu}{1-\mu})}} = \left(\frac{1}{1-\mu}\right)^{\frac{Q}{2}},$$

the only thing we need to control is the exponential term. For this, start noticing that

(2.17)

$$\begin{aligned}
x - e^{-(t-\tau)B}\xi &= x - e^{-(t-\tau)B}(\xi - e^{-\tau B}x_{o} + e^{-\tau B}x_{o}) \\
&= x - e^{-(t-\tau)B}e^{-\tau B}x_{o} - e^{-(t-\tau)B}(\xi - e^{-\tau B}x_{o}) \\
&= x - e^{-tB}x_{o} - e^{-(t-\tau)B}(\xi - e^{-\tau B}x_{o}),
\end{aligned}$$

where we have used that $(e^{-tB})^{-1} = e^{tB}$. Then, by (2.17) we obtain

$$(2.18) \begin{aligned} -\frac{1}{4} \langle C^{-1}(\tau,t)(x-e^{-(t-\tau)B}\xi), x-e^{-(t-\tau)B}\xi \rangle \\ &= -\frac{1}{4} \langle C^{-1}(\tau,t)(x-e^{-tB}x_{0}), x-e^{-tB}x_{0} \rangle \\ &-\frac{1}{4} \langle C^{-1}(\tau,t)e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{0}), e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{0}) \rangle \\ &+\frac{1}{2} \left(\langle C^{-1}(\tau,t)(x-e^{-tB}x_{0}), x-e^{-tB}x_{0} \rangle \right)^{\frac{1}{2}} \\ &\times \left(\langle C^{-1}(\tau,t)e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{0}), e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{0}) \rangle \right)^{\frac{1}{2}} \\ \leq -\frac{1}{4} \langle C^{-1}(\tau,t)e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{0}), e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{0}) \rangle \\ &+\frac{1}{2} \left(\langle C^{-1}(\tau,t)(x-e^{-tB}x_{0}), x-e^{-tB}x_{0} \rangle \right)^{\frac{1}{2}} \\ &\times \left(\langle C^{-1}(\tau,t)e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{0}), e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{0}) \rangle \right)^{\frac{1}{2}} \\ &\times \left(\langle C^{-1}(\tau,t)e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{0}), e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{0}) \rangle \right)^{\frac{1}{2}} \\ \end{aligned}$$

since $C^{-1}(\cdot, \cdot)$ is a positive definite matrix. Moreover, Lemma 2.4 yields that for any $y \in \mathbb{R}^N$

$$\left\langle C^{-1}(\tau,0)e^{\tau B}y,e^{\tau B}y\right\rangle - \left\langle C^{-1}(\tau,t)e^{-(t-\tau)B}y,e^{-(t-\tau)B}y\right\rangle \le 0.$$

By using this and (2.18) we get

$$\left| D_{\frac{1}{\sqrt{-\tau}}} \left(x_{o} - e^{\tau B} \xi \right) \right|_{C}^{2} - \frac{1}{4} \langle C^{-1}(\tau, t) (x - e^{-(t-\tau)B} \xi), x - e^{-(t-\tau)B} \xi \rangle$$

$$\leq \frac{1}{4} \langle C^{-1}(\tau, 0) e^{\tau B} \left(\xi - e^{-\tau B} x_{o} \right), e^{\tau B} \left(\xi - e^{-\tau B} x_{o} \right) \rangle$$

$$- \frac{1}{4} \langle C^{-1}(\tau, t) e^{-(t-\tau)B} (\xi - e^{-\tau B} x_{o}), e^{-(t-\tau)B} (\xi - e^{-\tau B} x_{o}) \right)$$

$$+ \frac{1}{2} \left(\langle C^{-1}(\tau, t) (x - e^{-tB} x_{o}), x - e^{-tB} x_{o} \rangle \right)^{\frac{1}{2}}$$

$$\times \left(\langle C^{-1}(\tau, t) e^{-(t-\tau)B} (\xi - e^{-\tau B} x_{o}), e^{-(t-\tau)B} (\xi - e^{-\tau B} x_{o}) \rangle \right)^{\frac{1}{2}}$$

$$\leq \frac{1}{2} \left(\langle C^{-1}(\tau, t) (x - e^{-tB} x_{o}), x - e^{-tB} x_{o} \rangle \right)^{\frac{1}{2}}$$

$$\times \left(\langle C^{-1}(\tau, t) e^{-(t-\tau)B} (\xi - e^{-\tau B} x_{o}), e^{-(t-\tau)B} (\xi - e^{-\tau B} x_{o}) \rangle \right)^{\frac{1}{2}}$$

We are going to bound all the above terms in (2.19) separately. We first have

$$\langle C^{-1}(\tau,t)(x-e^{-tB}x_{o}), x-e^{-tB}x_{o} \rangle$$

$$= \left\langle C^{-1}\left(-\frac{1}{\mu},-1\right) D_{\frac{1}{\sqrt{-t}}}(x-e^{-tB}x_{o}), D_{\frac{1}{\sqrt{-t}}}(x-e^{-tB}x_{o}) \right\rangle.$$

Now, let us denote with ||A|| the operator norm of a matrix A (i.e. its biggest eigenvalue for symmetric matrices). By (2.10), for any vector v with |v| = 1 we get

$$\begin{split} \min\left\{ \left| D_{\sqrt{\mu}} v \right|^{\frac{1}{1+2\vartheta}}, \left| D_{\sqrt{\mu}} v \right|^{\frac{1}{2(\kappa+\vartheta)+1}} \right\} &\leq \frac{1}{\sigma} \sqrt{\mu} \left\| v \right\| &\leq \frac{\kappa+1}{\sigma} \sqrt{\mu} \max\left\{ |v|^{\frac{1}{2\vartheta+1}}, |v|^{\frac{1}{2(\kappa+\vartheta)+1}} \right\} \\ &= \frac{\kappa+1}{\sigma} \sqrt{\mu}. \end{split}$$

From $\mu \leq \frac{\sigma^2}{(\kappa+1)^2}$ we then deduce $|D_{\sqrt{\mu}}v| \leq \left(\frac{\kappa+1}{\sigma}\right)^{2\vartheta+1}\mu^{\frac{1}{2}(2\vartheta+1)} \leq \left(\frac{\kappa+1}{\sigma}\right)^{2\vartheta+1}\sqrt{\mu}$ since $\mu \in (0,1)$. Hence, since by definition μ is also less than $\frac{1}{2}$, for any |v| = 1 we obtain that

$$\left\langle C^{-1}\left(-\frac{1}{\mu},-1\right)v,v\right\rangle = \left\langle C^{-1}(-1,-\mu)D_{\sqrt{\mu}}v,D_{\sqrt{\mu}}v\right\rangle$$

$$\leq \left\|C^{-1}(-1,-\mu)\right\| \left|D_{\sqrt{\mu}}v\right|^{2}$$

$$\leq \left(\frac{\kappa+1}{\sigma}\right)^{4\vartheta+2} \left\|C^{-1}\left(-1,-\mu\right)\right\| \mu$$

$$\leq \left(\frac{\kappa+1}{\sigma}\right)^{4\vartheta+2} \left\|C^{-1}\left(-1,-\frac{1}{2}\right)\right\| \mu$$
recalling (2.16)

which gives recalling (2.16)

$$\left\langle C^{-1}(\tau,t)(x-e^{-tB}x_{\mathrm{o}}), x-e^{-tB}x_{\mathrm{o}} \right\rangle$$
$$\leq \left(\frac{\kappa+1}{\sigma}\right)^{4\vartheta+2} \left\| C^{-1}\left(-1,-\frac{1}{2}\right) \right\| \mu M(z_{\mathrm{o}},z)^{2}.$$

On the other hand, by the commutation property (2.14), we get

$$\begin{split} \left\langle C^{-1}(\tau,t)e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{o}), e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{o}) \right\rangle \\ &= \left\langle C^{-1}(-1,-\mu)D_{\frac{1}{\sqrt{-\tau}}}e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{o}), D_{\frac{1}{\sqrt{-\tau}}}e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{o}) \right\rangle \\ &\leq \left\| C^{-1}(-1,-\mu) \right\| \left\| D_{\frac{1}{\sqrt{-\tau}}}e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{o}) \right\|^{2} \\ &= \left\| C^{-1}(-1,-\mu) \right\| \left\| e^{-(1-\mu)B}D_{\frac{1}{\sqrt{-\tau}}}(\xi-e^{-\tau B}x_{o}) \right\|^{2} \\ &\leq \left\| C^{-1}(-1,-\mu) \right\| \left\| e^{-(1-\mu)(B+B^{T})} \right\| \left\| D_{\frac{1}{\sqrt{-\tau}}}(\xi-e^{-\tau B}x_{o}) \right\|^{2} \\ &\leq \left\| C^{-1}\left(-1,-\frac{1}{2}\right) \right\| \left\| e^{-(1-\mu)(B+B^{T})} \right\| \left\| D_{\frac{1}{\sqrt{-\tau}}}(\xi-e^{-\tau B}x_{o}) \right\|^{2}. \end{split}$$

Since $0 < \mu \leq \frac{1}{2}$, the term $\left\| e^{-(1-\mu)(B+B^T)} \right\|$ is bounded from above by a universal constant c_0^2 . Thus we have

$$\left\langle C^{-1}(\tau,t)e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{\rm o}),e^{-(t-\tau)B}(\xi-e^{-\tau B}x_{\rm o})\right\rangle$$

$$\leq c_0^2 \left\| C^{-1} \left(-1, -\frac{1}{2} \right) \right\| M(z_0, \xi)^2.$$

Therefore

$$\frac{\Gamma(z,\zeta)}{\Gamma(z_{\mathrm{o}},\zeta)} \leq \left(\frac{1}{1-\mu}\right)^{\frac{Q}{2}} e^{c\sqrt{\mu}M(z_{\mathrm{o}},z)M(z_{\mathrm{o}},\xi)} \,,$$

which gives the thesis.

Now, we are now in position to introduce the *cylindrical* sets with basis at $z_0 = (x_0, t_0) \in \mathbb{R}^{N+1}$ previously used in [22]. For every $T > t_0$ and r > 0, we let

(2.20)
$$Q_{r,T}(z_{o}) := \left\{ z \in \mathbb{R}^{N+1} : t_{o} < t < T, \left| D_{\frac{1}{\sqrt{r}}}(e^{tB}x - e^{t_{o}B}x_{o}) \right| < 1 \right\},$$

and we denote by $\partial_P Q_{r,T}(z_0)$ its parabolic boundary

$$\partial_P Q_{r,T}(z_{\mathrm{o}}) = \partial Q_{r,T}(z_{\mathrm{o}}) \setminus \left\{ z = (x,T) \in \mathbb{R}^{N+1} : \left| D_{\frac{1}{\sqrt{r}}}(e^{TB}x - e^{t_{\mathrm{o}}B}x_{\mathrm{o}}) \right| < 1 \right\}.$$

Here $\partial Q_{r,T}(z_{o})$ is the topological boundary of $Q_{r,T}(z_{o})$. It has been shown by Montanari, in [22], that, for every $Q_{r,T}(z_{o})$ and for every $\phi \in C(\partial Q_{r,T}(z_{o}))$, there exists a unique solution $u \in C^{\infty}(Q_{r,T}(z_{o}))$ to the problem

(2.21)
$$\begin{cases} \mathcal{L}u = 0 & \text{ in } Q_{r,T}(z_{o}), \\ u = \phi & \text{ in } \partial_{P}Q_{r,T}(z_{o}). \end{cases}$$

Moreover, again in [22, Theorem 3.1] a Harnack inequality for positive solution to $\mathcal{L}u = 0$ has been proved.

We introduce some further notation. For every $\beta \in \mathbb{R}$, $0 < \alpha < \gamma < 1$ and $\nu \in (0, \nu_{o})$, with $\nu_{o} > 0$ depending on α and of the coefficients of the matrix B, and for every $\xi \in \mathbb{R}^{N}$ let us define the following sets

$$\begin{aligned} Q^+ &:= Q_{\nu r, (\beta+1)r}(\xi, (\beta-1)r) \cap \{\beta - \gamma \le t/r \le \beta - \alpha\}, \\ Q^- &:= Q_{\nu r, (\beta+1)r}(\xi, (\beta-1)r) \cap \{\beta + \alpha \le t/r \le \beta + \gamma\}. \end{aligned}$$

We state the following Harnack inequality.

Theorem 2.6. There exists a non-negative constant $c \equiv c(\alpha, \gamma, \beta, \nu) < \infty$ such that for all r > 0

$$\max_{a} u \le c \min_{a} u,$$

for all non-negative $u \in C^{\infty}(\overline{Q}_{\nu r,(\beta+1)r}(\xi,(\beta-1)r)$ satisfying

$$\mathcal{L}u = 0 \quad in \ Q_{\nu r,(\beta+1)r}(\xi, (\beta-1)r).$$

3. REVIEW OF ABSTRACT POTENTIAL THEORY

We begin recalling some definitions and results from Potential Theory. We adopt the notation of the monograph [8] by Constantinescu and Cornea. Let us indicate with $(\mathcal{E}, d_{\mathcal{E}})$ a metric space, locally connected and locally compact. Moreover, denoting with $\tau_{\mathcal{E}}$ the topology generated by the metric $d_{\mathcal{E}}$ on \mathcal{E} , we assume that $(\mathcal{E}, \tau_{\mathcal{E}})$ has a countable basis of open sets.

Definition 3.1. Suppose we are given, for every open set $U \in \tau_{\mathcal{E}}$, a family $\mathcal{H}(U)$ of extended real valued functions $u: U \to [-\infty, \infty]$. We say that the map

$$\mathcal{H}: U \longmapsto \mathcal{H}(U),$$

is a sheaf of functions on \mathcal{E} if the following properties hold:

- (i) If $U_1, U_2 \in \tau_{\mathcal{E}}$ with $U_1 \subseteq U_2$ and $u \in \mathcal{H}(U_2)$ then $u_{|U_1|} \in \mathcal{H}(U_1)$.
- (ii) if $(U_i)_{i\in I} \in \tau_{\mathcal{E}}$ and $u: \bigcup_{i\in I} U_i \to [-\infty,\infty]$ is such that $u_{|U_i|} \in \mathcal{H}(U_i)$ for all $i \in I$, then $u \in \mathcal{H}(\bigcup_{i\in I} U_i)$.

A sheaf of functions \mathcal{H} on \mathcal{E} will be called harmonic if, for every $U \in \tau_{\mathcal{E}}$, $\mathcal{H}(U)$ is a linear subspace of C(U). A sheaf of functions \mathcal{U} on \mathcal{E} will be said hyperharmonic if, for any $U \in \tau_{\mathcal{E}}$, the family $\mathcal{U}(U)$ is a convex cone of lower semi-continuous, lower finite functions.

Note that if \mathcal{U} is a hyperharmonic sheaf on \mathcal{E} , then the map

$$\mathcal{H}_{\mathcal{U}}: U \longmapsto \mathcal{U}(U) \cap (-\mathcal{U}(U)) \quad \forall U \in \tau_{\mathcal{E}},$$

is a harmonic sheaf on \mathcal{E} .

Throughout the sequel we indicate with \mathcal{H} (resp. \mathcal{U}) a harmonic (resp. hyperharmonic) sheaf on \mathcal{E} and $\mathcal{H}_{\mathcal{U}}$ -functions (resp. \mathcal{U} -functions) will be called *harmonic* (resp. *hyperharmonic*). Moreover, a function $u \in (-\mathcal{U})$ will be called *hypoharmonic*.

Let $U \subseteq \mathcal{E}$ be an open set and let $\phi : U \to (-\infty, +\infty]$ be a lower semi-continuous function. Then, for any open set $V \subset U$, with compact closure and non-empty boundary, and for any non-negative Radon measure μ on ∂V we define

(3.1)
$$\int_{\partial V} \phi \, \mathrm{d}\mu := \sup \left\{ \int_{\partial V} g \, \mathrm{d}\mu : g \in C(\partial V), \ g \le \phi \text{ on } \partial V \right\}.$$

Since ϕ is lower finite and ∂V is compact, ϕ is bounded from below on ∂V . Hence the set on the righthand side in (3.1) is not empty. Thus, we can give the following definition.

Definition 3.2. Let $V \subset \mathcal{E}$ be open, with compact closure and non-empty boundary. Let us consider a family $\mu^V = \{\mu_x^V\}_{x \in V}$ of non-negative Radon measures on ∂V . The family μ^V will be called a sweeping on V. For any lower semi-continuous function $\phi : \partial V \to (-\infty, +\infty]$ we will denote with μ_{ϕ}^V the function

$$\begin{split} \mu^V_\phi &: V \to (-\infty, +\infty], \\ x \longmapsto \mu^V_\phi(x) &:= \int_{\partial V} \phi \, \mathrm{d} \mu^V_x \end{split}$$

If \mathcal{H} is a harmonic sheaf on \mathcal{E} , then the sweeping μ^V will be called \mathcal{H} -sweeping if:

- (i) $\forall \phi \in C(\partial V)$ the function μ_{ϕ}^{V} is a \mathcal{H} -function;
- (ii) for any \mathcal{H} -function h defined on an open neighbourhood of \overline{V} we have $\mu_h^V = h$ on V.

We will say that the family

(3.2)
$$\Omega := \left\{ \mu^{V_i} = \{ \mu_x^{V_i} \}_{x \in V_i} : i \in I \right\},$$

is a sweeping system on \mathcal{E} if $\{V_i : i \in I\}$ is a basis for \mathcal{E} of relatively compact sets with non-empty boundary and for any $i \in I \ \mu^{V_i}$ is a sweeping on V_i .

If \mathcal{H} is a harmonic sheaf on E, then a sweeping system Ω is called \mathcal{H} -sweeping system on E if μ^{V_i} is a \mathcal{H} -sweeping on V_i , for every $i \in I$.

A hyperharmonic sheaf can be defined starting from a sweeping systems. Indeed, let us consider on \mathcal{E} a sweeping system Ω as defined in (3.2) and give the following definition.

Definition 3.3. Let $U \subseteq \mathcal{E}$. A lower semicontinuous function $u: U \to (-\infty, +\infty]$ will be said Ω -hyperharmonic if for any $i \in I$ such that $V_i \subseteq U$ we have that $\mu_u^{V_i} \leq u$ on V_i , *i.e.*

$$u(x) \ge \int_{\partial V_i} u \, \mathrm{d}\mu_x^{V_i}, \qquad \forall x \in V_i.$$

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The function u will be said locally Ω -hyperharmonic if there exists an open covering $\{W_j\}_{j \in J}$ of U such that, $\forall j \in J$, $u_{|W_j}$ is Ω -hyperharmonic on W_j .

Let Ω be a sweeping system on the space \mathcal{E} . We call hyperharmonic sheaf generated by Ω the map \mathcal{U} defined as follows

 $\mathcal{U}: \tau_{\mathcal{E}} \ni U \longmapsto \mathcal{U}(U) := \{ u : u \text{ is locally } \Omega \text{-hyperharmonic on } U \}.$

Given the hyperharmonic sheaf \mathcal{U} generated by the sweeping system Ω , we call harmonic sheaf generated by Ω the harmonic sheaf given by

$$\mathcal{H}_{\mathcal{U}}: U \longmapsto \mathcal{U}(U) \cap (-\mathcal{U}(U)) \quad \forall U \in \tau_{\mathcal{E}}.$$

3.1. Resolutive sets. Throughout the rest of this section \mathcal{U} will denote a given hyperharmonic sheaf on the space \mathcal{E} . Let us give the following definition.

Definition 3.4. An open set $U \subseteq \mathcal{E}$ will be called a minimum principle set, in short a MPset, if every \mathcal{U} -function u which is non-negative outside the intersection with U of a compact set $K \subseteq \mathcal{E}$ and

$$\liminf_{x \to y} u(x) \ge 0 \quad \forall y \in \partial U,$$

is non-negative on U.

Remark 3.5. We point out that, if in the previous definition we are considering an open set U with compact closure, we drop the condition that a \mathcal{U} -function u is non-negative outside the intersection with U of a compact set $K \subseteq \mathcal{E}$.

Let \mathcal{U} be the hyperharmonic sheaf on \mathcal{E} , $U \subseteq \mathcal{E}$ be a MP-set and let $\phi : \partial U \to [-\infty, +\infty]$. Let us consider the set

$$\overline{\mathcal{U}}_{\phi}^{U} := \bigg\{ u \in \mathcal{U}(U) : \overline{\{u < 0\}} \text{ is a compact, possibly empty, subset of } U \\ \liminf_{U \ni x \to y} u(x) \ge \phi(y) \; \forall y \in \partial U \bigg\}.$$

The sets $\overline{\mathcal{U}}_{\phi}^{U}$ and $\underline{\mathcal{U}}_{\phi}^{U} = -\overline{\mathcal{U}}_{-\phi}^{U}$ will be called respectively the set of *upper-functions* and the set of *lower-function*. We will call *upper-solution* and *lower-solution* the functions:

$$\overline{H}^U_\phi := \inf \overline{\mathcal{U}}^U_\phi, \qquad \underline{H}^U_\phi := \sup \underline{\mathcal{U}}^U_\phi.$$

The next proposition is a straightforward consequence of the definition of upper and lower solution.

Proposition 3.6. Let $\phi_1, \phi_2 : \partial U \to \overline{\mathbb{R}}, \alpha \in \mathbb{R}, \alpha > 0$. Then:

 $\begin{aligned} &(i) \ \phi_1 \le \phi_2 \Rightarrow \overline{H}^U_{\phi_1} \le \overline{H}^U_{\phi_2}, \underline{H}^U_{\phi_1} \le \underline{H}^U_{\phi_2}, \\ &(ii) \ \overline{H}^U_{\phi_1 + \phi_2} \le \overline{H}^U_{\phi_1} + \overline{H}^U_{\phi_2}, \underline{H}^U_{\phi_1 + \phi_2} \ge \underline{H}^U_{\phi_1} + \underline{H}^U_{\phi_2}, whenever the sums are defined. \\ &(iii) \ \underline{H}^U_{\alpha\phi_1} = \alpha \underline{H}^U_{\phi_1}, \overline{H}^U_{\alpha\phi_1} = \alpha \overline{H}^U_{\phi_1}, \overline{H}^U_{-\alpha\phi_1} = -\alpha \underline{H}^U_{\phi_2}, \\ &(iv) \ \phi_1 \ge 0 \Rightarrow \overline{H}^U_{\phi_1}, \underline{H}^U_{\phi_1} \ge 0. \end{aligned}$

Let us given now a crucial definition.

Definition 3.7. A function $\phi : \partial U \to [-\infty, \infty]$ is called resolutive if the functions $\overline{H}_{\phi}^{U}, \underline{H}_{\phi}^{U}$ are \mathcal{H}_{U} -functions and coincide. In this case we set $H_{\phi}^{U} := \overline{H}_{\phi}^{U} = \underline{H}_{\phi}^{U}$ and we say that H_{ϕ}^{U} is the generalized solution in the sense of Perron-Weiner (in short PW solution).

An open set U of \mathcal{E} , with non-empty boundary, is said to be a resolutive set (with respect to U) if every $\phi \in C_c(\partial U)$ is resolutive.

If U is a resolutive set, for any $x \in U$, the map

$$C_c(\partial U) \ni \phi \longmapsto H^U_\phi(x) \in \mathbb{R},$$

is a linear and non-negative functional, hence by the Riesz Theorem, for every $x \in U$, there exists a suitable Radon measure μ_x^U on ∂U such that

$$H^U_{\phi}(x) = \int_{\partial U} \phi(y) \,\mathrm{d}\mu^U_x(y).$$

The measure μ_x^U is called the \mathcal{H}_u -harmonic measure related to U and x. Clearly the family $\mu^U := {\{\mu_x^U\}_{x \in U} \text{ is a sweeping on } U \text{ and, if } \overline{U} \text{ is compact, the family } \mu^U \text{ is a } \mathcal{H}_u\text{-sweeping on } U.$

3.2. Harmonic spaces and \mathfrak{P} -harmonic spaces. Let us begin defining a harmonic space.

Definition 3.8. The couple $(\mathcal{E}, \mathcal{U})$, where \mathcal{U} is a hyperharmonic sheaf on \mathcal{E} , is called a harmonic space if the following axioms are satisfied:

- (i) (A1)(Positivity): For every $x \in \mathcal{E}$ there exists a $\mathcal{H}_{\mathcal{U}}$ -function, defined in a neighbourhood of x, that does not vanish at x.
- (ii) (A2)(Bauer convergence property): Let $\{u_n\}_{n\in\mathbb{N}}$ be a monotone increasing sequence of $\mathcal{H}_{\mathcal{U}}$ -functions on an open set U of \mathcal{E} . Then

$$u := \lim_{n \to +\infty} u_n,$$

is a $\mathcal{H}_{\mathcal{U}}$ -function whenever it is locally bounded.

- (iii) (A3)(Resolutivity): The resolutive sets (with respect to \mathcal{U}) form a basis for the topology $\tau_{\mathcal{E}}$ on \mathcal{E} .
- (iv) (A4)(Completeness): A lower semi-continuous, lower finite function u on an open set U of \mathcal{E} belongs to $\mathcal{U}(U)$ if, for any relatively compact with non-empty boundary resolutive set V (with respect to \mathcal{U}) such that $\overline{V} \subset U$, we have $\mu_u^V \leq u$ on V, that is

$$u(x) \ge \int_{\partial V} u \, \mathrm{d}\mu_x^V, \qquad \forall x \in V,$$

where μ^V is given by the sweeping constructed with the basis of resolutive sets.

Remark 3.9. In the particular case the hyperharmonic sheaf \mathcal{U} is generated by a sweeping system Ω (see Definition 3.3), the axiom (A4) of Completeness, is trivially satisfied.

In our setting, by using the Harnack inequality for the non-negative solutions to $\mathcal{L}u = 0$ given in Theorem 2.6, we will prove the following property which, in turn, implies the Bauer convergence property (A2).

(iv) (A2)'(Doob convergence property): If $\{u_n\}_{n\in\mathbb{N}}$ is a monotone increasing sequence of $\mathcal{H}_{\mathcal{U}}$ -functions on an open set $U \subset \mathcal{E}$ such that the set

$$\left\{ x \in U | \sup_{n \in \mathbb{N}} u_n(x) < \infty \right\},\$$

is dense in U, then

$$u := \lim_{n \to \infty} u_n,$$

is a $\mathcal{H}_{\mathcal{U}}$ -function on U.

Throughout the sequel we indicate with $(\mathcal{E}, \mathcal{U})$ a harmonic space.

Definition 3.10. A hyperharmonic function u on a harmonic space $(\mathcal{E}, \mathcal{U})$ is called superharmonic if, for any relatively compact resolutive set V, the function μ_u^V is harmonic. A hypoharmonic function u will be said subharmonic if -u is superharmonic. **Remark 3.11.** Every superharmonic function u is finite on a dense subset of its domain. Moreover, if the harmonic sheaf \mathcal{H}_{u} has the Doob convergence property (A2)', then hyperharmonic functions, which are finite on a dense set, are superharmonic.

Definition 3.12. A non-negative superharmonic function p for which any non-negative harmonic minorant vanishes identically is called a potential.

We refer to [8] for some properties of superharmonic functions and potentials. Let us give the following definition.

Definition 3.13. A harmonic space $(\mathcal{E}, \mathcal{U})$ will be called \mathfrak{P} -harmonic space if for any $x \in \mathcal{E}$ there exists a potential p on \mathcal{E} such that p(x) > 0.

The following result holds (see [8, Proposition 2.3.2]).

Proposition 3.14. Let $(\mathcal{E}, \mathcal{U})$ be a harmonic space. The following conditions are equivalent:

- (i) \mathcal{E} is a \mathfrak{P} -harmonic space;
- (ii) the set \mathcal{P}_c of finite continuous potentials on \mathcal{E} such that any $p \in \mathcal{P}_c$ is harmonic outside a compact set, separates the points of \mathcal{E} ;
- (iii) the set of non-negative superharmonic functions on \mathcal{E} separates the points of \mathcal{E} ;
- (iv) for any relatively compact, resolutive set V and for any $x \in V$, there exists a nonnegative, finite, continuous superharmonic function u on \mathcal{E} such that

$$\int_{\partial V} u \, \mathrm{d} \mu_x^V < u(x).$$

As a consequence of the proposition above we have the following corollary [8, Corollary 2.3.3].

Corollary 3.15. Every open set of a \mathfrak{P} -harmonic space is an MP-set, according to Definition 3.4.

 \mathfrak{P} -harmonic spaces are really important since the following result holds true [8, Theorem 2.4.2].

Theorem 3.16. Any open set of a \mathfrak{P} -harmonic space with non-empty boundary is resolutive.

The consequence of Theorem 3.16 is that given an open set U of a \mathfrak{P} -harmonic space the $\mathcal{H}_{\mathcal{U}}$ -Dirichlet problem

(3.3)
$$\begin{cases} u \in \mathcal{H}_{\mathcal{U}}(U), \\ u = \phi \quad \text{on } \partial U, \ \forall \phi \in C_c(\partial U). \end{cases}$$

admits a solution H_{ϕ}^{U} in the sense of Perron-Weiner-Brelot-Bauer.

In general, we cannot expect a good behaviour of H^U_{ϕ} at the boundary points of U. In the following section we describe the conditions under which the boundary datum ϕ in (3.3) is attained by the generalized solution H^U_{ϕ} .

3.3. Boundary regularity. Let us give the following definitions.

Definition 3.17. Let $(\mathcal{E}, \mathcal{U})$ be a \mathfrak{P} -harmonic space and let U be an open subset of \mathcal{E} with non-empty boundary. A point $x_0 \in \partial U$ is said $\mathcal{H}_{\mathcal{U}}$ -regular if

$$\lim_{x \to x_{o}} H^{U}_{\phi}(x) = \phi(x_{o}), \qquad \forall \phi \in C_{c}(\partial U).$$

A point $x_0 \in \partial U$ which is not regular is called \mathcal{H}_U -irregular.

Definition 3.18. Let $(\mathcal{E}, \mathcal{U})$ be a \mathfrak{P} -harmonic space and let U be an open set of \mathcal{E} with nonempty boundary, $x_0 \in \partial U$ and let V be an open neighbourhood of x_0 . We say that a function $\omega \in \mathcal{U}(V \cap U)$ is a barrier at x_0 if:

(i) $\omega > 0$ on $U \cap V$; (ii) $\lim_{x \to x_0} \omega(x) = 0.$

The first condition for a boundary point to be regular is having a barrier function [8, Proposition 2.4.7].

Proposition 3.19. Let U be a resolutive subset of a \mathfrak{P} -harmonic space $(\mathcal{E}, \mathcal{U})$. Then, any boundary point x_0 which possesses a barrier is regular.

In order to state some geometrical characterization of regular point we need some further notation. The following notion was introduced by Brelot ([6]).

Definition 3.20. Let $(\mathcal{E}, \mathcal{U})$ be a \mathfrak{P} -harmonic space. For any non-negative function u on \mathcal{E} and any subset A of \mathcal{E} denote

$$\Phi^u_A := \{ v \in \mathcal{U}(\mathcal{E}) : v \ge 0 \text{ on } \mathcal{E} \text{ and } v \ge u \text{ on } A \}.$$

We call the reduit of u on A the following function

$$\mathcal{R}^u_A := \inf \left\{ v : v \in \Phi^u_A \right\}.$$

We call balayage of u on A the lower semi-continuous regularization of the reduit function of u on A, that is

$$\widehat{\mathcal{R}}^{u}_{A}(x) := \liminf_{y \to x} \mathcal{R}^{u}_{A}(y) \quad \forall x \in \mathcal{E}.$$

We list some useful properties of the balayage and the reduit function which will turn out to be helpful in the following parts of the paper.

Proposition 3.21. For any subsets A and B of \mathcal{E} and for every non-negative function u and v on \mathcal{E} the following properties hold

- (i) $\mathcal{R}^u_A = u$ on A;
- (ii) if $A \subseteq B$ and $u \leq v$ we have $\mathcal{R}_A^u \leq \mathcal{R}_B^v$;
- (iii) $\mathcal{R}^{u}_{A} = \mathcal{R}^{u}_{A}$ if A is open;
- (iv) $\widehat{\mathcal{R}}_{A\cup B}^{i} + \widehat{\mathcal{R}}_{A\cap B}^{i} \leq \widehat{\mathcal{R}}_{A}^{i} + \widehat{\mathcal{R}}_{B}^{u}$, and $\mathcal{R}_{A\cup B}^{u} + \mathcal{R}_{A\cap B}^{u} \leq \mathcal{R}_{A}^{u} + \mathcal{R}_{B}^{u}$.

For a proof of the last property in the proposition above we refer to [8, Theorem 4.2.2].

Proposition 3.22. Let $(\mathcal{E}, \mathcal{U})$ be a \mathfrak{P} -harmonic space and let u be a non-negative superharmonic function on \mathcal{E} and $A \subset \mathcal{E}$. Then, \mathcal{R}^{u}_{A} is harmonic on $\mathcal{E} \setminus \overline{A}$ and \mathcal{R}^{u}_{A} and $\widehat{\mathcal{R}}^{u}_{A}$ coincide on $\mathcal{E} \setminus \overline{A}$.

Proposition 3.23. Let $(\mathcal{E}, \mathcal{U})$ be a \mathfrak{P} -harmonic space. The balayage of any non-negative superharmonic function on \mathcal{E} , on any compact subset of \mathcal{E} , is a potential.

For a proof of the previous propositions we refer to [8, Proposition 5.3.1 and Proposition 5.3.5].

Definition 3.24. Let $(\mathcal{E}, \mathcal{U})$ be a \mathfrak{P} -harmonic space and let \mathcal{U} be an open set of \mathcal{E} . A set P is said polar set in \mathcal{U} if there exists a non-negative superharmonic function p on \mathcal{U} which is equal $+\infty$ at least on $\mathcal{U} \cap P$. In this case, we say that the function p is associated to P.

Even though most of the results stated below are proved in [6], we give here their proofs, since our axiomatic setting is slightly different than the one adopted by the author of [6].

Proposition 3.25. Let $(\mathcal{E}, \mathcal{U})$ be a \mathfrak{P} -harmonic space, P a polar set in \mathcal{E} and u a nonnegative function on \mathcal{E} . Then, the reduit \mathcal{R}_P^u is zero on a dense subset of \mathcal{E} . Moreover, $\widehat{\mathcal{R}}_P^u \equiv 0$.

Proof. Suppose that P is a polar set and consider its associated function p. Then, $p = +\infty$ on P. Choose any point x_0 where $p(x_0) < +\infty$. We have that $\lambda p \ge u$ on P, for every $\lambda > 0$, moreover $p \ge 0$ outside P. Then,

(3.4)
$$\lambda p \ge \mathcal{R}_P^u \quad \forall \lambda > 0.$$

Since (3.4) holds also in x_o and $p(x_o)$ is finite, taking the infimum on $\lambda > 0$ we get that $\mathcal{R}_P^u(x_o) = 0$. By the previous argument we have that \mathcal{R}_P^u is zero on every point in which p is finite. Since p is a superharmonic function, it is finite on a dense subset of \mathcal{E} (see Remark 3.11). Then $\mathcal{R}_P^u = 0$ on a dense subset of \mathcal{E} . Form this fact it follows that $\widehat{\mathcal{R}_P^u} \equiv 0$.

As an immediate consequence of Proposition 3.25 and 3.21 we have

Corollary 3.26. Let $(\mathcal{E}, \mathcal{U})$ be a \mathfrak{P} -harmonic space. If P is a polar set of \mathcal{E} , then $\widehat{\mathcal{R}}^{u}_{A\cup P} = \widehat{\mathcal{R}}^{u}_{A}$, for any subset A of \mathcal{E} and for any non-negative function u on \mathcal{E} .

The following definition will be used to give a further characterization of regular points.

Definition 3.27. Let A be a subset of a \mathfrak{P} -harmonic space $(\mathcal{E}, \mathcal{U})$ and let us consider a point $x_o \notin A$. We say that A is thin at x_o if either $x_o \notin \overline{A}$ or $x_o \in \overline{A}$ and there exists a non-negative superharmonic function u on \mathcal{E} such that

$$u(x_{o}) < \liminf_{A \ni x \to x_{o}} u(x).$$

Let us consider a point $x_o \in A$. We say that A is thin at its point x_o if $\{x_o\}$ is a polar set in \mathcal{E} (according to Definition 3.24) and $A \setminus \{x_o\}$ is thin at x_o .

Let us remark that we will call a set $K \subset \mathcal{E}$ a G_{δ} -set if K is the countable intersection of open sets of \mathcal{E} . The following Proposition holds.

Proposition 3.28. Let $(\mathcal{E}, \mathcal{U})$ be a \mathfrak{P} -harmonic space, let A be any subset of \mathcal{E} , $x_o \notin A$ and let w > 0 be a superharmonic function on \mathcal{E} , finite and continuous at x_o . Then, A is thin in x_o if and only if there exists an open neighborhood V of x_o such that

(3.5)
$$\mathcal{R}^w_{A \cap V}(x_o) < w(x_o) \quad and \quad \mathcal{R}^w_{A \cap V}(x_o) < w(x_o).$$

Proof. Let us begin noticing that if A is thin at x_0 , then by [6, Theorem 29], the first condition in (3.5) holds true. Then, the second one follows using the definition of balayage function as well as the continuity of w in x_0 .

Let us prove the vice versa. Since $\mathcal{R}_{A\cap V}^w \geq \widehat{\mathcal{R}}_{A\cap V}^w$, it is enough to show that the second condition in (3.5) implies that A is thin in x_0 . First of all, let us note that $\{x_0\}$ is a G_{δ} -set, since in \mathcal{E} the singleton $\{x_0\}$ is the zero level set of the distance function which is a G_{δ} -set. With no loss of generality let us assume $x_0 \in \overline{A}$, otherwise there is nothing to prove. We endow \mathcal{E} of the *fine topology*, which is the coarsest topology on \mathcal{E} which is finer than $\tau_{\mathcal{E}}$ and for which any hyperharmonic function on any open set is continuous. By [8, Corollary 5.3.2] since $\{x_0\}$ is a G_{δ} -set, for any $\varepsilon > 0$ such that

(3.6)
$$\mathcal{R}^{w}_{A \cap V}(x_{o}) + \varepsilon < w(x_{o}),$$

there exists a positive superharmonic function u on \mathcal{E} such that $u \equiv w$ on A and

(3.7)
$$u(x_{o}) \leq \widehat{\mathcal{R}}^{w}_{A \cap V}(x_{o}) + \varepsilon.$$

Moreover, $\mathcal{R}^{w}_{A\cap V}(x_{o}) = \widehat{\mathcal{R}}^{w}_{A\cap V}(x_{o})$. Then, by the continuity of w in x_{o} , combined with (3.6) and (3.7), we have that

$$u(x_{o}) < w(x_{o}) = \lim_{A \ni x \to x_{o}} w(x) \le \liminf_{A \ni x \to x_{o}} u(x).$$

Thus A is thin at $\{x_0\}$.

The following theorem holds true; see [8, Theorem 6.3.3].

Theorem 3.29. Let U be an open subset of a \mathfrak{P} -harmonic space (E, U) and $x_0 \in \partial U$. Hence, x_0 is \mathcal{H}_U -regular if and only if $E \setminus U$ is not thin at x_0 .

We conclude this section recalling a well known result in potential theory that links the regularity of the boundary points of an open set U with the balayage on the complementary of $\mathcal{E} \setminus U$. The forthcoming result is proven in [23, Theorem 14]; see also [17, Theorem 4.6].

Theorem 3.30. Let $(\mathcal{E}, \mathcal{U})$ be a \mathfrak{P} -harmonic space, \mathcal{U} be an open subset of \mathcal{E} and $x_o \in \partial \mathcal{U}$ such that $\{x_o\}$ is a polar set in \mathcal{E} , according to Definition 3.24. Then, x_o is a $\mathcal{H}_{\mathcal{U}}$ -irregular point if and only if

$$\inf_{K} \widehat{\mathcal{R}}^{1}_{(\mathcal{E} \setminus U) \cap K}(x_{\mathrm{o}}) = 0,$$

where the infimum is taken on the family of compact neighborhoods K of x_o ordered by inclusion.

4. The Perron-Weiner-Brelot-Bauer solution for \mathcal{L}

We consider the Dirichlet problem

(4.1)
$$\begin{cases} \mathcal{L}u = 0 & \text{ in } U, \\ u = \phi & \text{ in } \partial U \end{cases}$$

where U is an open subset of \mathbb{R}^{N+1} , $\phi \in C_c(\partial U)$ and \mathcal{L} is the operator defined in (1.1) satisfying hypothesis **[H.1]**. As we are interested in classical solution to $\mathcal{L}u = 0$, throughout the sequel of this article we denote with \mathcal{H} the harmonic sheaf defined as

(4.2)
$$U \longmapsto \mathcal{H}(U) := \left\{ u \in C^{\infty}(U) : \mathcal{L}u = 0 \text{ in } U \right\},$$

for every open set U of \mathbb{R}^{N+1} and we say that a function u is harmonic in an open set U if $u \in \mathcal{H}(U)$.

We next discuss the main steps of the procedure that provides us with the unique solution u to the boundary value problem (4.1).

4.1. Definition of the sweeping system. We construct the Perron-Weiner-Brelot-Bauer solution to problem (4.1). With this aim we consider, for any $z_o = (x_o, t_o) \in \mathbb{R}^{N+1}, T > t_o$ and r > 0, the cylinder $Q_{r,T}(z_o)$ defined in (2.20), and the relevant Dirichlet problem (2.21). Note that, in the simplest case of the heat operator $\mathcal{L} = \Delta - \partial_t$, we are considering the usual Cauchy-Dirichlet problem on the parabolic cylinder

$$(4.3) Q_r(z_o) := B_r(x_o) \times (t_o, T).$$

As already recalled in Section 2, there exists a unique classical solution $u \in C^{\infty}(Q_{r,T}(z_{o}))$ to the Dirichlet problem (2.21), which attains the boundary data on $\partial_{P}Q_{r}(z_{o})$. By Riesz's Theorem we have that there exists a Radon measure $\mu_{z}^{Q_{r,T}(z_{o})}$, supported on $\partial_{P}Q_{r,T}(z_{o})$, such that

$$u(z) := \int_{\partial_P Q_{r,T}(z_o)} \phi(\zeta) \mathrm{d} \mu_z^{Q_{r,T}(z_o)}(\zeta), \quad \forall z \in Q_{r,T}(z_o).$$

Thus, the family

(4.4)
$$\Omega := \left\{ \mu^{Q_{r,T}(z_{o})} := \{ \mu_{z}^{Q_{r,T}(z_{o})} \}_{z \in Q_{r,T}(z_{o})} : z_{o} \in \mathbb{R}^{N+1}, r \in \mathbb{R}^{+}, T > t_{o} \right\},$$

is a sweeping system on \mathbb{R}^{N+1} .

4.2. The hyperharmonic sheaf \mathcal{U} and the \mathfrak{P} -harmonic space $(\mathbb{R}^{N+1}, \mathcal{U})$. We now consider the hyperharmonic sheaf \mathcal{U} generated by Ω in accordance with the Definition 3.3, and we prove that $(\mathbb{R}^{N+1}, \mathcal{U})$ is a \mathfrak{P} -harmonic space, according to Definition 3.13.

We first prove that $(\mathbb{R}^{N+1}, \mathcal{U})$ is a harmonic space in the sense of Definition 3.8. We postpone the proof of axiom (A2), since it is the most involved. The axiom (A1) holds because the constant functions are $\mathcal{H}_{\mathcal{U}}$ -functions. The validity of the axiom (A3) is a direct consequence of the fact that

$$\mathcal{Q} := \left\{ Q_{r,T}(z_{o}) : z_{o} = (x_{o}, t_{o}) \in \mathbb{R}^{N+1}, T > t_{o}, r > 0 \right\},\$$

is a basis of resolutive sets for the Euclidean topology on \mathbb{R}^{N+1} . The axiom (A4) follows from the fact that \mathcal{U} is the hyperharmonic sheaf generated by Ω .

Let us focus our attention to the proof of axiom (A2). We show that $(\mathbb{R}^{N+1}, \mathcal{U})$ has the Doob convergence property (axiom (A2)'). With this aim, we consider a monotone increasing sequence of $\mathcal{H}_{\mathcal{U}}$ -functions $\{u_n\}_{n\in\mathbb{N}}$ in an open set $U \subset \mathbb{R}^{N+1}$ such that the set

$$V := \bigg\{ z \in U | \sup_{n \in \mathbb{N}} u_n(z) < \infty \bigg\},\$$

is dense in U. We plan to prove that

$$(4.5) u := \lim_{n \to +\infty} u_n,$$

is a $\mathcal{H}_{\mathcal{U}}$ -function in U. We first prove that $\{u_n\}_{n\in\mathbb{N}}$ converges uniformly on every compact subsets K of U. For every $z \in K$, we choose a point $(\xi, \tau) \in \mathbb{R}^{N+1}$, and two positive constants T and r such that

$$Q_{r,T}(\xi,\tau) \Subset U$$
 and $z \in Q^-$.

Note that, for every $p \in \mathbb{N}$, $\{u_{n+p} - u_n\}_{n \in \mathbb{N}}$ is a sequence of non-negative $\mathcal{H}_{\mathcal{U}}$ -functions. Then, by the Harnack inequality stated in Theorem 2.6, we obtain

$$0 \le (u_{n+p}(z) - u_n(z)) \le \max_{\overline{Q^-}} (u_{n+p} - u_n)$$
$$\le c \min_{\overline{Q^+}} (u_{n+p} - u_n)$$
$$\le c(u_{n+p}(\zeta) - u_n(\zeta)) \xrightarrow{n \to \infty} 0.$$

In the last inequality we have used the fact that there exists a point $\zeta \in Q^+ \cap V$ such that

$$\min_{\overline{Q^+}}(u_{n+p}-u_n) \le c(u_{n+p}(\zeta)-u_n(\zeta)),$$

since V is dense in U. From the compactness of K it follows that there exists a finite family of cylinders $\{Q_i\}_{i=1}^{\bar{m}}$, contained in U, such that $K \subset \bigcup_{i=1}^{\bar{m}} Q_i^-$. This proves that $\{u_n\}_{n \in \mathbb{N}}$ converges uniformly on K.

We next show that u in (4.5) is a $\mathcal{H}_{\mathcal{U}}$ -function. Indeed, fixed $Q_{r,T}(z_0) \subseteq U$, we have that

$$u_n(z) = \int_{\partial_P Q_{r,T}(z_o)} u_n(\zeta) \mathrm{d}\mu_z^{Q_{r,T}(z_o)}(\zeta), \qquad \forall z \in Q_{r,T}(z_o), \, \forall n \in \mathbb{N}.$$

From the uniform convergence, it follows that the limit function u satisfies the same identity. Then, $u \in \mathcal{H}_{\mathcal{U}}(Q_{r,T}(z_{o}))$ and the Doob convergence property follows. This completes the proof of (A2), and thus, that $(\mathbb{R}^{N+1}, \mathcal{U})$ is a harmonic space.

In order to show that $(\mathbb{R}^{N+1}, \mathcal{U})$ is a \mathfrak{P} -harmonic space we show that \mathcal{U} separates the points, so that we can rely on Proposition 3.14. Let us consider two points $z_1 \neq z_2$. There exists T > 0 such that $z_1, z_2 \in \mathcal{U} = \mathbb{R}^N \times [-T, T]$. If $t_1 \neq t_2$, then we set $u_1(z) = e^t$. If otherwise $t_1 = t_2 = \tilde{t}$ we choose $\gamma \in \mathbb{R}^N$ so that $\langle x_1 - x_2, e^{tB} \gamma \rangle \neq 0$ and c > 0 so that

$$u_2(z) = c - \langle x, e^{tB} \gamma \rangle > 0, \qquad \forall z \in U.$$

By definition u_2 satisfies

$$\mathcal{L}u_2(z) = \langle Bx, \nabla u_2(z) \rangle - \partial_t u_2(z) = -\langle Bx, e^{tB}\gamma \rangle + \langle Bx, e^{tB}\gamma \rangle = 0.$$

Hence, $u_{1,2}(z_1) \neq u_{1,2}(z_2)$ and u_1, u_2 are both non-negative superharmonic functions. Then, by Proposition 3.14 it follows that $(\mathbb{R}^{N+1}, \mathcal{U})$ is a \mathfrak{P} -harmonic space.

4.3. Conclusions. Thanks to Theorem 3.16, we conclude that there exists a generalized solution $H^U_{\phi} \in \mathcal{H}_{\mathcal{U}}(U)$ to the problem

(4.6)
$$\begin{cases} u \in \mathcal{H}_{\mathcal{U}}(U), \\ u = \phi, \quad \text{in } \partial U, \ \forall \phi \in C_c(\partial U) \end{cases}$$

We next show that the generalized solution H_{ϕ}^U to (4.6) is also a classical solution to the equation $\mathcal{L}H_{\phi}^U = 0$, then it is a solution to problem (4.1). This fact is the main consequence of the following

Proposition 4.1. The sweeping system Ω , defined above, is a *H*-sweeping system, with respect to the sheaf *H* defined in (4.2).

Proof. We show that $\mu^{Q_{r,T}(z_o)}$ is a \mathcal{H} -sweeping, according to Definition 3.2. Clearly fixed $\phi \in C_c(\partial_P Q_{r,T}(z_o))$ the function (recall that $\mu_z^{Q_{r,T}}$ is supported on $\partial_P Q_{r,T}$)

$$\begin{aligned} \mu_{\phi}^{Q_{r,T}(z_{\mathrm{o}})} \colon Q_{r,T}(z_{\mathrm{o}}) \to (-\infty, +\infty], \\ z \longmapsto \mu_{\phi}^{Q_{r,T}(z_{\mathrm{o}})}(z) \coloneqq \int_{\partial Q_{r,T}(z_{\mathrm{o}})} \phi(\zeta) \mathrm{d}\mu_{z}^{Q_{r,T}(z_{\mathrm{o}})}(\zeta), \end{aligned}$$

is a \mathcal{H} -function, because it is the solution $H^{Q_{r,T}(z_o)}_{\phi}$ of the Dirichlet problem (2.21) with boundary data ϕ . Consider $u \in \mathcal{H}(U)$, and let $Q_{r,T}(z_o) \in U$ be any cylinder. Since u is the solution to (2.21) with boundary data $\phi = u$, we have that

$$\mu_{u}^{Q_{r,T}(z_{o})}(z) := \int_{\partial_{P}Q_{r,T}(z_{o})} u(\zeta) \mathrm{d}\mu_{z}^{Q_{r,T}(z_{o})}(\zeta) = u(z), \qquad \forall z \in Q_{r,T}(z_{o}).$$

Hence, $\mu_u^{Q_{r,T}(z_o)} = u$ on $Q_{r,T}(z_o)$ and the thesis follows.

The main consequence of the above Proposition is that $U \subseteq \mathbb{R}^{N+1} \mathcal{H}_{\mathcal{U}}(U) \equiv \mathcal{H}(U)$ for every open set. We are now ready to give the

Proof of Theorem 1.1. Consider the sweeping system Ω defined in (4.4) and the hyperharmonic sheaf \mathcal{U} generated by Ω . We have that $(\mathbb{R}^{N+1}, \mathcal{U})$ is a \mathfrak{P} -harmonic space, according to Definition 3.13, then Theorem 3.16 provides us with the existence of the Perron-Weiner-Brelot-Bauer solution H_{ϕ}^U to (4.6). Moreover, Proposition 4.1 implies that H_{ϕ}^U to (4.6) is also a classical solution to the equation $\mathcal{L}H_{\phi}^U = 0$, then it is a solution to problem (4.1). \Box

5. The Wiener-type test and the cone condition at $\{t = 0\}$

In Section 4 we have shown that there exists the generalized solution H_{ϕ}^{U} to the Dirichlet problem for the operator \mathcal{L} defined in (1.1) in an arbitrary open set U

$$\begin{cases} \mathcal{L}u = 0, & \text{in } U, \\ u = \phi, & \text{in } \partial U, \ \forall \phi \in C_c(\partial U) \end{cases}$$

In this section we describe the conditions under which the boundary datum ϕ is attained by the generalized solution H_{ϕ}^{U} . In particular, we prove Theorem 1.2 and Proposition 1.3.

5.1. Boundary regularity, \mathcal{L} -potential and \mathcal{L} -capacity. In order to use the abstract Theorem 3.30 we begin showing that every singleton $\{z_0\}$ is a polar set in \mathbb{R}^{N+1} . Our proof follows the same line as [17, Lemma 4.5].

Let us consider the fundamental solution Γ of the operator \mathcal{L} , defined in (2.13). In order to make Γ a lower semi-continuous function on \mathbb{R}^{N+1} we agree to let $\Gamma(\zeta; \zeta) = 0$, so that

(5.1)
$$\Gamma(\zeta;\zeta) = \liminf_{z \to \zeta} \Gamma(z;\zeta), \quad \forall \zeta \in \mathbb{R}^{N+1}.$$

The following lemma holds.

Lemma 5.1. Let $\zeta_{o} := (\xi_{o}, \tau_{o}) \in \mathbb{R}^{N+1}$ be fixed and let u be the function defined as follows (5.2) $u(z) := \Gamma(z; \zeta_{o}) \quad z \in \mathbb{R}^{N+1}.$

Then, u is a non-negative U-function on \mathbb{R}^{N+1} .

Proof. The non-negativity and the lower semi-continuity of u follow form the properties of the fundamental solution Γ and from (5.1). Let us prove that, fixed a cylinder $Q_{r,T} \equiv Q_{r,T}(z_{\rm o})$, u satisfies the inequality

$$u(z) \ge \int_{\partial Q_{r,T}} u(\zeta) \,\mathrm{d}\mu_z^{Q_{r,T}}(\zeta) \quad \forall z \in Q_{r,T}.$$

Let us consider a function $\phi \in C(\partial Q_{r,T})$ such that $\phi \leq u$ on $\partial Q_{r,T}$.

Assume that $\zeta_{0} \notin Q_{r,T}$ and indicate with $H_{\phi}^{Q_{r,T}}$ the generalized solution to the Dirichlet problem in $Q_{r,T}$ with boundary datum ϕ . For any $\delta > 0$, let us apply the strong maximum principle in [17, Proposition 3.1] on $Q_{r,T} \cap \{t \leq T - \delta\}$. In particular, let us note that $\partial Q_{r,T} \cap \{t \leq T - \delta\} = \partial_P Q_{r,T} \cap \{t \leq T - \delta\}$. Then, since every boundary points of $\partial_P Q_{r,T}$ is \mathcal{L} -regular (see for instance Proposition A.1 in [22]), form the harmonicity of u in $Q_{r,T}$ and the lower-semicontinuity of u, we get that

(5.3)
$$\liminf_{z \to \zeta} (u(z) - H_{\phi}^{Q_{r,T}}(z)) \ge u(\zeta) - \phi(\zeta) \ge 0 \quad \forall \zeta \in \partial Q_{r,T} \cap \{t \le T - \delta\}.$$

Hence, [17, Proposition 3.10] we have that $u \ge H_{\phi}^{Q_{r,T}}$ on $Q_{r,T} \cap \{t \le T - \delta\}$

(5.4)
$$u(z) \ge H_{\phi}^{Q_{r,T}}(z) := \int_{\partial Q_{r,T}} \phi \,\mathrm{d}\mu_{z}^{Q_{r,T}} \quad \forall z \in Q_{r,T} \cap \{t \le T - \delta\}$$

Since for any interior point $z = (x, t) \in Q_{r,T}$ we can find $\delta > 0$ such that $t_0 < t \le T - \delta < T$, we have that (5.4) holds true for any $z \in Q_{r,T}$. Then, passing to the supremum of every $\phi \le u$ on $\partial Q_{r,T}$ we obtain the desired inequality (5.2).

On the other hand, let us suppose that $\zeta_{o} \in Q_{r,T}$. Since $u \equiv 0$ on the set $\{t \leq \tau_{o}\}$ we have that $\phi \leq 0$ on $\partial Q_{r,T} \cap \{t \leq \tau_{o}\}$, so that by [17, Proposition 3.10] we obtain $H_{\phi}^{Q_{r,T}} \leq 0$ on $Q_{r,T} \cap \{t \leq \tau_{o}\}$. In particular, $H_{\phi}^{Q_{r,T}}(\zeta_{o}) \leq 0$. Let us consider $\widetilde{Q}_{r,T} := Q_{r,T} \setminus \{\zeta_{o}\}$.

Then, by proceeding as in the previous case we can prove (5.3) in $\widetilde{Q}_{r,T}$, which yields that $u \geq H_{\phi}^{Q_{r,T}}$ on $\widetilde{Q}_{r,T} \cap \{t \leq T - \delta\}$. Moreover in ζ_0 we have that $u(\zeta_0) = 0 \geq H_{\phi}^{Q_{r,T}}(\zeta_0)$. Hence, $u \geq H_{\phi}^{Q_{r,T}}$ on $Q_{r,T} \cap \{t \leq T - \delta\}$ and (5.4), and in turn (5.2), follows exactly as for the case $\zeta_0 \notin Q_{r,T}$.

Proposition 5.2. Every singleton $\{z_o\}$, $z_o \in \mathbb{R}^{N+1}$, is a polar set in \mathbb{R}^{N+1} .

Proof. Let $z_0 := (x_0, t_0) \in \mathbb{R}^{N+1}$ and we use the fundamental solution Γ to built a function p which satisfies the condition of Definition 3.24.

For any $\varepsilon > 0$ let us consider the family of points

$$\zeta_{\varepsilon} := (\xi_{\varepsilon}, \tau_{\varepsilon}) = (e^{\varepsilon B} x_{o}, t_{o} - \varepsilon).$$

By the definition (2.13) of fundamental solution we obtain that

$$\Gamma(z_{\rm o};\zeta_{\varepsilon}) := \frac{(4\pi)^{N/2}}{\sqrt{\det C(t_{\rm o} - \varepsilon, t_{\rm o})}} \xrightarrow{\varepsilon \to 0^+} +\infty.$$

Then, there exists a decreasing sequence $\{\varepsilon_n\}_{n\in\mathbb{N}}$ such that

(5.5)
$$\Gamma(z_{o}; \zeta_{\varepsilon_{n}}) \ge 4^{n}, \quad \forall n \in \mathbb{N}$$

Let us consider the function p defined as follows

$$p(z) := \sum_{n=1}^{\infty} \frac{\Gamma(z; \zeta_{\varepsilon_n})}{2^n}$$

and show that p satisfies the condition of Definition 3.24. By assumption (5.5) we have

$$p(z_{o}) = \sum_{n=1}^{\infty} \frac{\Gamma(z_{o}; \zeta_{\varepsilon_{n}})}{2^{n}} \ge \sum_{n=1}^{\infty} 2^{n} = +\infty.$$

Let $z \neq z_0$. Then, there exists a positive r such that

$$\overline{B}_r(z)\times\overline{B}_r(z_{\mathrm{o}})\cap\{(w,\zeta)\in\mathbb{R}^{N+1}\times\mathbb{R}^{N+1}:w=\zeta\}=\emptyset$$

Since Γ is continuous in $\{(w, \zeta) \in \mathbb{R}^{N+1} \times \mathbb{R}^{N+1} : w \neq \zeta\}$, we have

$$M := \max_{\substack{(y,s)\in\overline{B}_{r}(z)\\(\eta,\sigma)\in\overline{B}_{r}(z_{0})}} \Gamma(y,s;\eta,\sigma) < +\infty.$$

Moreover, since $\zeta_{\varepsilon_n} \to z_0$ as $n \to +\infty$, there exists an index $\bar{n} > 0$ such that, for any $n > \bar{n}$, $\zeta_{\varepsilon_n} \in \overline{B}_r(z_0)$. We show that p converges uniformly on $\overline{B}_r(z)$. Indeed,

$$\sum_{n=\bar{n}}^{\infty} \frac{\sup_{w\in\overline{B}_r(z)} |\Gamma(w;\zeta_{\varepsilon_n})|}{2^n} \le M \sum_{n=1}^{\infty} \frac{1}{2^n} = M.$$

Hence, it follows that p converges uniformly on $\overline{B}_r(z)$. From Lemma 5.1 it then follows that p is a \mathcal{U} - function on \mathbb{R}^{N+1} , finite for any $z \neq z_0$. Moreover, since the harmonic space $(\mathbb{R}^{N+1}, \mathcal{U})$ has the Doob convergence property, by Remark 3.11, p is superharmonic. Hence, $\{z_0\}$ is a polar set in \mathbb{R}^{N+1} , according to Definition 3.24, with associated function p. \Box

Now we apply the results presented in the last part of Chapter 3 to discuss the regularity of boundary points. Since the sweeping system Ω , defined in (4.4), is a \mathcal{H} -sweeping (see Proposition 4.1), the definition of \mathcal{L} -regular point and $\mathcal{H}_{\mathcal{U}}$ -regular point coincide. Indicating with U an open subset of \mathbb{R}^{N+1} with non-empty boundary let us consider, for any r > 0 and $z_o \in \partial U$, the set $\mathcal{Q}_r(x_o, 0)$ defined in (2.9) and let

(5.6)
$$G_r := \{ (x,t) \in \mathbb{R}^{N+1} \setminus U : -r^2 < t \le 0, \ \|x - e^{-tB}x_0\| \le r \}.$$

As consequence of Theorem 3.30 and Proposition 5.2 we characterize the regularity of boundary points as follows.

Corollary 5.3. Let $U \subseteq \mathbb{R}^{N+1}$ be an open set and let $z_o \in \partial U$. Then, being G_r the set defined in (5.6), we have that z_o is a \mathcal{L} -regular point if and only if

$$\lim_{r \to 0^+} \mathcal{R}^1_{G_r}(z_{\rm o}) > 0.$$

Before proceeding with the proof of our regularity criteria we still need few more definitions. Let us denote with $\mathcal{M}(\mathbb{R}^{N+1})$ the collection of all nonnegative Radon measure on \mathbb{R}^{N+1} and call

$$\Gamma_{\mu}(z) := \int_{\mathbb{R}^{N+1}} \Gamma(z,\zeta) \, \mathrm{d}\mu(\zeta), \qquad z \in \mathbb{R}^{N+1},$$

the \mathcal{L} -potential of μ .

If F is a compact set of \mathbb{R}^{N+1} and $\mathcal{M}(F)$ is the collection of all nonnegative Radon measure on \mathbb{R}^{N+1} with support in F, the \mathcal{L} -capacity of F is defined as

$$\operatorname{cap}(F) := \sup\{\mu(F) \mid \mu \in \mathcal{M}(F), \ \Gamma_{\mu} \le 1 \text{ on } \mathbb{R}^{N+1}\}$$

We list some properties of the \mathcal{L} -capacities. For every F, F_1 and F_2 compact subsets of \mathbb{R}^{N+1} , we have:

(i) $\operatorname{cap}(F) < \infty;$ (ii) if $F_1 \subseteq F_2$, then $\operatorname{cap}(F_1) \leq \operatorname{cap}(F_2);$ (iii) $\operatorname{cap}(F_1 \cup F_2) \leq \operatorname{cap}(F_1) + \operatorname{cap}(F_2);$ (iv) $\operatorname{cap}(\delta_r(F)) = r^Q \operatorname{cap}(F)$ for every r > 0.

The properties (i) - (iv) are quite standard, and they follow from the features of Γ . Following the same lines of the proof of [15, Teorema 1.1], we have the existence of a unique measure $\mu_F \in \mathcal{M}(F)$ such that

$$\widehat{\mathcal{R}}_{F}^{1}(z) = \Gamma_{\mu_{F}}(z) = \int_{\mathbb{R}^{N+1}} \Gamma(z,\zeta) \,\mathrm{d}\mu_{F}(\zeta) \quad \forall z \in \mathbb{R}^{N+1},$$

and

$$\mu_F(\mathbb{R}^{N+1}) = \operatorname{cap}(F).$$

The proof of this fact relies on the good behavior of Γ , a representation formula of Riesz-type for superharmonic functions proved in [7, Theorem 5.1], and a Maximum Principle for \mathcal{L} .

5.2. Wiener-type criterium. We begin proving Theorem 1.2. We extend to our contest the same approach used in [14]. We will use the lemma below; see [14, Lemma 5.1].

Lemma 5.4. For every $n \in \mathbb{N}$, let us split the set G_r in (5.6) as follows

$$G_r = G_r^n \cup G_r^{*n},$$

where, for any $\lambda \in (0,1)$, we write

$$G_r^n = \{ z \in G_r : \Gamma(z_0; z) \ge \lambda^{-n \log n} \} \cup \{ z_0 \}$$

and
$$G_r^{*n} = \{ z \in G_r : \Gamma(z_0; z) \le \lambda^{-n \log n} \}.$$

Then,

$$\lim_{r \to 0^+} \widehat{\mathcal{R}}^1_{G_r}(z_0) = \lim_{r \to 0^+} \widehat{\mathcal{R}}^1_{G_r^n}(z_0).$$

Proof of the necessary condition in Theorem 1.2. We prove the implication

(5.7)
$$z_{\rm o} \text{ is } \mathcal{L}\text{-regular} \Rightarrow \sum_{n=1}^{\infty} \widehat{\mathcal{R}}^1_{U^c_n(z_{\rm o})}(z_{\rm o}) = +\infty,$$

By the hypothesis it follows from Corollary 5.3 that

(5.8)
$$\lim_{r \to 0^+} \widehat{\mathcal{R}}^1_{G_r}(z_0) > 0$$

Let us assume by contradiction that

(5.9)
$$\sum_{n=1}^{\infty} \widehat{\mathcal{R}}^1_{U_n^c(z_o)}(z_o) < +\infty,$$

where $U_n^c(z_0)$ is the set defined in (1.3). We are going to prove that the assumption (5.9) is in contradiction with (5.8).

By hypothesis (5.9), for every $\varepsilon > 0$, there exists $n_{\varepsilon} := n(\varepsilon) \in \mathbb{N}$ such that

$$\sum_{n=n_{\varepsilon}}^{\infty} \widehat{\mathcal{R}}^{1}_{U_{n}^{c}(z_{\mathrm{o}})}(z_{\mathrm{o}}) < \varepsilon.$$

On the other hand, following the notation of Lemma 5.4, for any positive radius r > 0, we have

$$G_r^{n_{\varepsilon}} \subseteq \bigcup_{n=n_{\varepsilon}}^{\infty} U_n^c(z_{\mathrm{o}}).$$

Then, by Proposition 3.21, we get

$$\widehat{\mathcal{R}}^{1}_{G_{r}^{n_{\varepsilon}}}(z_{o}) \leq \sum_{n=n_{\varepsilon}}^{\infty} \widehat{\mathcal{R}}^{1}_{U_{n}^{c}(z_{o})}(z_{o}) < \varepsilon.$$

By Lemma 5.4, we get

$$\lim_{r \to 0^+} \widehat{\mathcal{R}}^1_{G_r}(z_{\rm o}) = 0,$$

which is in contradiction with (5.8). This prove the necessary condition (5.7).

We now prove the sufficient condition of Theorem 1.2. This will require three lemmas. The first follows by a similar path as in [14, Lemma 6.1] by relying on Corollary 3.15

Lemma 5.5. Suppose we have a sequence of compact sets $\{F_n\}_{n\in\mathbb{N}}$ in \mathbb{R}^{N+1} such that

$$\begin{cases} F_n \cap F_k = \emptyset & \text{if } n \neq k, \\ \forall r > 0 \ \exists \ \bar{n} \quad such \ that \ \ F_n \subseteq G_r & \text{for } n \geq \bar{n}. \end{cases}$$

 $Suppose \ also \ that \ the \ following \ two \ conditions \ hold \ true:$

(i)

$$\sum_{n=1}^{+\infty}\widehat{\mathcal{R}}_{F_k}^1(z_0) = +\infty;$$

(ii)

$$\sup_{n \neq k} \sup \left\{ \frac{\Gamma(z,\zeta)}{\Gamma(z_0,\zeta)} : z \in F_n, \, \zeta \in F_k \right\} \le M_0.$$

Then we have $\widehat{\mathcal{R}}^1_{G_r}(z_0) \geq \frac{1}{2M_0}$ for every positive r.

Now, for any fixed $\lambda \in (0,1)$, we recall that the definition of the set $U_n^c(z_0) \equiv U_n^c(x_0,0)$ given in (1.3) and, setting $\alpha(n) = n \log n$, let us denote

$$T_n := \max_{(x,t)\in U_n^c(x_0,0)} -t = \left(c_N \lambda^{\alpha(n)}\right)^{\overline{\alpha}},$$

where Q is the homogeneous dimension associated to $(D_r)_{r>0}$ and c_N is a given dimensional constant. Fix $q \in \mathbb{N}$ such that

(5.10)
$$q \ge q_0 := 4 + \frac{m}{\log\left(\frac{1}{\lambda}\right)}, \text{ where } m = \max\left\{2, \frac{2Q}{\log 6}, \frac{2\sigma_C^2}{\log 6}, \frac{Q\log 2}{\log 8}, \frac{2Q\log\left(\frac{\kappa+1}{\sigma}\right)}{\log 8}\right\},$$

and σ_C, σ are the constants in (2.8) and (2.10). Moreover, let us also denote by

(5.11)
$$p = 1 + \left\lfloor \frac{q}{2} \right\rfloor := 1 + \text{the integer part of } \frac{q}{2}$$

So $\frac{q}{2} \leq p \leq 1 + \frac{q}{2} < q - 1$. For any $n \in \mathbb{N}$ consider the sets

$$U_{nq}^{c}(x_{o},0) = \left(U_{nq}^{c}(x_{o},0) \cap \{t \ge -T_{nq+p}\}\right) \cup \left(U_{nq}^{c}(x_{o},0) \cap \{t \le -T_{nq+p}\}\right)$$

:= $F_{n}^{(o)} \cup F_{n}$.

Moreover, notice that, since nq + p < q(n + 1), then

(5.12)
$$\min_{(x,t)\in F_m} t = -T_{mq} > -T_{nq+p} = \max_{(\xi,\tau)\in F_n} \tau \qquad \forall n,m\in\mathbb{N}, \ m>n.$$

Let us prove the following lemma.

Lemma 5.6. With the notation above, we have that

$$\sum_{n=1}^{+\infty} \widehat{\mathcal{R}}_{F_n^{(o)}}^1(z_0) < +\infty.$$

Proof. We are going to prove that $F_n^{(o)}$ is contained in a homogeneous cylinder \mathcal{Q}_{r_n} so that

(5.13)
$$\sum_{n=1}^{+\infty} \left(\frac{1}{\lambda}\right)^{\alpha(nq+1)} r_n^Q < +\infty.$$

This is enough to prove the statement since

$$\widehat{\mathcal{R}}^{1}_{F_{n}^{(\mathrm{o})}}(z_{\mathrm{o}}) = \int_{F_{n}^{(\mathrm{o})}} \Gamma(z_{\mathrm{o}};\zeta) \,\mathrm{d}\mu_{\mathrm{F}_{n}^{(\mathrm{o})}}(\zeta) \leq \left(\frac{1}{\lambda}\right)^{\alpha(nq+1)} \operatorname{cap}(F_{n}^{(\mathrm{o})}),$$

and by monotonicity and homogeneity we have

$$\operatorname{cap}(F_n^{(\mathrm{o})}) \le \operatorname{cap}(\mathcal{Q}_{r_n}) = \operatorname{cap}(\mathcal{Q}_1)r_n^Q.$$

In order to prove (5.13), we have to find a good bound for r_n . Fix $z = (x, t) \in F_n^{(o)}$. Since in particular $z \in U_{nq}^c(x_0, 0)$, we have that by definition of $|\cdot|_C$ in (2.7)

$$\begin{aligned} \left| e^{-B} D_{\frac{1}{\sqrt{-t}}}(x - e^{-tB} x_{o}) \right|_{C} &= \left. \frac{1}{4} \langle C^{-1} \left(-1, 0 \right) e^{-B} D_{\frac{1}{\sqrt{-t}}}(x - e^{-tB} x_{o}), e^{-B} D_{\frac{1}{\sqrt{-t}}}(x - e^{-tB} x_{o}) \rangle \\ &\leq \left. \log \left(\frac{c \lambda^{\alpha(nq)}}{(-t)^{\frac{Q}{2}}} \right), \end{aligned}$$

while, on the other hand, by (2.8), we get

$$\left| e^{-B} D_{\frac{1}{\sqrt{-t}}} (x - e^{-tB} x_{0}) \right|_{C}^{2} \ge \sigma_{C}^{2} \left| D_{\frac{1}{\sqrt{-t}}} (x - e^{-tB} x_{0}) \right|^{2},$$

so then

(5.14)
$$\left| D_{\frac{1}{\sqrt{-t}}}(x - e^{-tB}x_{\mathrm{o}}) \right|^2 \le \frac{1}{\sigma_C^2} \log\left(\frac{c_N \lambda^{\alpha(nq)}}{(-t)^{\frac{Q}{2}}}\right)$$

Therefore, from (2.10), we deduce

$$\begin{split} &\frac{1}{\sqrt{-t}} \left\| x - e^{-tB} x_{o} \right\| \\ &= \left\| D_{\frac{1}{\sqrt{-t}}} (x - e^{-tB} x_{o}) \right\| \\ &\leq (\kappa + 1) \max\left\{ \left| D_{\frac{1}{\sqrt{-t}}} (x - e^{-tB} x_{o}) \right|^{\frac{1}{2\vartheta + 1}}, \left| D_{\frac{1}{\sqrt{-t}}} (x - e^{-tB} x_{o}) \right|^{\frac{1}{2(\kappa + \vartheta) + 1}} \right\} \\ &\leq (\kappa + 1) \max\left\{ \frac{1}{\sigma_{C}^{\frac{1}{2\vartheta + 1}}} \log^{\frac{1}{2(2\vartheta + 1)}} \left(\frac{c\lambda^{\alpha(nq)}}{(-t)^{\frac{Q}{2}}} \right), \frac{1}{\sigma_{C}^{\frac{1}{2(\kappa + \vartheta) + 1}}} \log^{\frac{1}{2(2(\kappa + \vartheta) + 1)}} \left(\frac{c\lambda^{\alpha(nq)}}{(-t)^{\frac{Q}{2}}} \right) \right\}. \end{split}$$

Let us note that from our choice of $\alpha(n) = n \log n$ we can check that the sequence $n \mapsto \alpha(nq+p) - \alpha(nq)$ is monotone increasing. In particular, by the choice of p in (5.11), this yields that

$$\begin{aligned} \alpha(nq+p) - \alpha(nq) &\geq & \alpha(q+p) - \alpha(q) \\ &\geq & \alpha\left(\frac{3}{2}q\right) - \alpha(q) \geq \frac{1}{2}q\log\left(\frac{3}{2}q\right) \geq \frac{1}{2}q\log 6. \end{aligned}$$

By our choice of q (5.10), we have that $\alpha(nq+p) - \alpha(nq) \ge \frac{Q}{2\log(\frac{1}{\lambda})}$ and so, for any $n \in \mathbb{N}$, it holds

$$T_{nq+p}^{\frac{Q}{2}} \le c\lambda^{\alpha(nq)}e^{-\frac{Q}{2}}.$$

This and the fact that the functions $s \mapsto s \log^{\beta} \frac{\theta}{s^{Q}}$ are increasing in the interval $(0, e^{-\beta} \theta^{\frac{1}{Q}}]$ allow to bound the term $||x - e^{-tB}x_{0}||$ further. Indeed, having $0 < -t \leq T_{nq+p}$, we get

$$\begin{aligned} \left\| x - e^{-tB} x_{o} \right\| &\leq \frac{(\kappa+1)}{\sigma_{C}} \sqrt{-t} \log^{\frac{1}{2}} \left(\frac{c \lambda^{\alpha(nq)}}{(-t)^{\frac{Q}{2}}} \right) \\ &\leq \frac{(\kappa+1)}{\sigma_{C}} \sqrt{T_{nq+p}} \log^{\frac{1}{2}} \left(\frac{c_{N} \lambda^{\alpha(kq)}}{T_{nq+p}^{\frac{Q}{2}}} \right), \end{aligned}$$

since given that $\frac{1}{2}q\log 6 \geq \frac{\sigma_C^2}{\log(\frac{1}{\lambda})}$ we have also $T_{nq+p}^{\frac{Q}{2}} \leq c\lambda^{\alpha(nq)}e^{-\sigma_C^2}$, which says

$$\log^{\frac{1}{2}} \left(\frac{c \lambda^{\alpha(nq)}}{T_{nq+p}^{\frac{Q}{2}}} \right) \geq \sigma_C.$$

Summing up, we have just proved that

$$(x,t) \in F_k^{(\mathrm{o})} \qquad \Longrightarrow \quad \begin{cases} \left\| x - e^{-tB} x_{\mathrm{o}} \right\| \le \frac{(\kappa+1)}{\sigma_C} \sqrt{T_{nq+p}} \log^{\frac{1}{2}} \left(\frac{c\lambda^{\alpha(nq)}}{T_{nq+p}^2} \right) =: r_n \\ 0 < -t \le T_{nq+p} \le (\kappa+1)^2 T_{nq+p} < r_n^2, \end{cases}$$

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namely, recalling the definition of $Q_r(x_0, 0)$ in (2.9) yields that

$$F_k^{(\mathrm{o})} \subseteq \mathcal{Q}_{r_n}(x_{\mathrm{o}}, 0).$$

Moreover, by the choice of $p \ge \frac{q}{2} > 1 + \frac{1}{\log(\frac{1}{\lambda})}$, we obtain that (5.13) is verified by the same argument as in [14, Lemma 6.2].

Lemma 5.7. Let $z_0 := (x_0, 0)$. There exists a positive constant M_0 such that

$$\frac{\Gamma(z;\zeta)}{\Gamma(z_{\rm o};\zeta)} \le M_0 \quad \forall \, z \in F_m, \, \forall \, \zeta \in F_n, \quad \forall \, m, n \in \mathbb{N}, \, m \neq n.$$

Proof. Fix any $m, n \in \mathbb{N}$ with $m \neq n$. If $m \leq n-1$, then F_m lies below F_n implying that $\Gamma(z; \zeta) = 0$ by definition of Γ . Thus, the thesis follows. Hence, with no loss of generality we can assume $m \geq n+1$. For every $z = (x, t) \in F_m$ and $\zeta = (\xi, \tau) \in F_n$, by (5.12) we have that

$$\mu = \frac{-t}{-\tau} \le \frac{-\min_{(x,t)\in F_m} t}{-\max_{(\xi,\tau)\in F_n} \tau} = \frac{T_{mq}}{T_{nq+p}} = \left(\frac{\lambda^{\alpha(mq)}}{\lambda^{\alpha(nq+p)}}\right)^{\frac{2}{Q}} = \left(\frac{1}{\lambda}\right)^{\frac{2}{Q}\left(\alpha(nq+p) - \alpha(mq)\right)}$$

Moreover, since $nq+p < q(n+1) \le mq$, by monotonicity of the map $n \mapsto \alpha(nq+q) - \alpha(nq+p)$ and by the choice of p in (5.11), we have

$$\begin{aligned} \alpha(mq) - \alpha(nq+p) &\geq & \alpha(nq+q) - \alpha(nq+p) \\ &\geq & \alpha(2q) - \alpha(q+p) \\ &\geq & \alpha(2q) - \alpha\left(\frac{3}{2}q+1\right) \geq \left(\frac{q}{2}-1\right)\log\left(2q\right). \end{aligned}$$

Furthermore, by our choice of q (5.10) we have that

$$\alpha(mq) - \alpha(nq+p) \ge \left(\frac{q}{2} - 1\right)\log\left(8\right) \ge \frac{Q}{2} \frac{\max\left\{\log 2, \log\left(\frac{\kappa+1}{\sigma}\right)^2\right\}}{\log\left(\frac{1}{\lambda}\right)}$$

which, in turn, implies $\mu \leq \min \{\frac{1}{2}, \frac{\sigma^2}{(\kappa+1)^2}\}$. Hence, by Lemma 2.5 we get

$$\frac{\Gamma(z,\zeta)}{\Gamma(z_{\mathrm{o}},\zeta)} \leq \left(\frac{1}{1-\mu}\right)^{\frac{Q}{2}} e^{C\sqrt{\mu}M(z_{\mathrm{o}},z)M(z_{\mathrm{o}},\zeta)} \leq 2^{\frac{Q}{2}} e^{C\sqrt{\mu}M(z_{\mathrm{o}},z)M(z_{\mathrm{o}},\zeta)} ,$$

recalling the notation in (2.16).

To finish the proof we need to show that the exponential is uniformly bounded for $z \in F_m$ and $\zeta \in F_n$. By estimating as in (5.14) we have

$$\begin{split} \left| D_{\frac{1}{\sqrt{-\tau}}}(\xi - e^{-\tau B} x_{o}) \right|^{2} &\leq \frac{1}{\sigma_{C}^{2}} \log \left(\frac{c \lambda^{\alpha(nq)}}{(-\tau)^{\frac{Q}{2}}} \right) \\ &\leq \frac{1}{\sigma_{C}^{2}} \log \left(\frac{c \lambda^{\alpha(nq)}}{T_{nq+p}^{\frac{Q}{2}}} \right) \\ &= \frac{1}{\sigma_{C}^{2}} \log \left(\frac{1}{\lambda} \right) (\alpha(nq+p) - \alpha(nq)) \,, \end{split}$$

and in a similar way

$$\left| D_{\frac{1}{\sqrt{-t}}}(x - e^{-tB}x_{o}) \right|^{2} \leq \frac{1}{\sigma_{C}^{2}} \log\left(\frac{1}{\lambda}\right) (\alpha(mq + p) - \alpha(mq)),$$

so that now the proof follows as in [14, Lemma 6.3].

Proof of the sufficient condition in Theorem 1.2. The proof now follows by a similar argument as in [14, Theorem 1.1] by using the above lemmas. \Box

5.3. **Proof of Proposition 1.3.** We prove that $\mathbb{R}^{N+1} \setminus U$ is not thin in z_o , according to Definition 3.27. Then, by Theorem 3.29, z_o is a \mathcal{L} -regular point. Since $z_o \in \mathbb{R}^{N+1} \setminus U$ we show that $(\mathbb{R}^{N+1} \setminus U) \setminus \{z_o\}$ is not thin in $\{z_o\}$. Thanks to Proposition 3.28 it is enough to prove that, for any open neighborhood V of z_o

(5.15)
$$\mathcal{R}^{1}_{(\mathbb{R}^{N+1}\setminus U)\cap (V\setminus\{z_{o}\})}(z_{o}) = 1,$$

For any r > 0 let us consider the neighborhoods G_r defined in (5.6). By Proposition 3.21 we have that

$$\mathcal{R}^1_{G_r}(z_o) \leq \mathcal{R}^1_{G_r \setminus \{z_o\}}(z_o) + \mathcal{R}^1_{\{z_o\}}(z_o).$$

Form (5.15) it follows that it is enough to show that

(5.16)
$$\mathcal{R}^{1}_{G_{r} \setminus \{z_{o}\}}(z_{o}) \geq \mathcal{R}^{1}_{G_{r}}(z_{o}) - \mathcal{R}^{1}_{\{z_{o}\}}(z_{o}) \geq 1.$$

Now, let us adopt the following notation

$$C_r(z_0) = (x_0 + D_r K) \times \{-r^2 T\} =: K_r(x_0) \times \{-r^2 T\}.$$

For any $\theta > 1$ and any $n \in \mathbb{N}$ let us denote with

$$F_n^{(\theta)} := \left\{ z = (x, t) \in \mathbb{R}^{N+1} : \frac{1}{\lambda^{n \log n}} < \Gamma(x_0, 0; x, t) \le \frac{\theta}{\lambda^{n \log n}} \right\}$$

There exists $\bar{n} \in \mathbb{N}$ such that

(5.17)
$$F_n^{(\theta)} \cap \mathcal{C}_r(z_0) \subset U_n^c(z_0) \quad \forall n \ge \bar{n}.$$

We claim that there exist $\bar{n}_1 \geq \bar{n}$ and a non-empty open set $B \subset \mathbb{R}^{N+1}$ such that

$$(5.18) B \subseteq F_n^{(\theta)} \cap \mathcal{C}_r(z_0) \forall n \ge \bar{n}_1$$

Indeed, take $\bar{n}_1 \geq \bar{n}$ such that, for any fixed $r \in (0, R)$, it holds

$$\sup_{\xi \in \operatorname{int}(K_r(x_0))} \Gamma(x_0, 0; \xi, -r^2 T) < \frac{1}{\lambda^{n \log n}} \quad \forall n \ge \bar{n}_1.$$

Consider

$$A := \left\{ \xi \in \operatorname{int}(K_r(x_0)), \, \frac{1}{\theta} \Gamma(x_0, 0; \xi, -r^2 T) < \frac{1}{\lambda^{n \log n}} < \Gamma(x_0, 0; \xi, -r^2 T) \right\},$$

which is open, and non-empty since $\operatorname{int}(K_r(x_0)) \neq \emptyset$ and $\theta > 1$. Moreover $A \times \{-r^2T\} \subset F_n^{(\theta)}$ by construction, and $A \times \{-r^2T\} \subset C_r(z_0)$ for $r \in (0, R)$. Now, note that for sufficiently small r > 0 we have that

(5.19)
$$\mathcal{Q}_r(z_0) \setminus U \supseteq K_r(x_0) \times \{-r^2T\}.$$

Thus, by Definition 3.20 of reduit function it holds $\mathcal{R}_{G_r}^1(z_0) = 1$ and by

$$\int_{K_r(x_0)} \Gamma(x_0, 0; \xi, -r^2 T) \,\mathrm{d}\xi \le 1,$$

keeping in mind (5.17) and (5.18), we obtain that for $n \ge \bar{n}_1$

$$\begin{aligned} \mathcal{R}^{1}_{G_{r} \setminus \{z_{o}\}}(z_{o}) &\geq \mathcal{R}^{1}_{G_{r}}(z_{o}) - \mathcal{R}^{1}_{\{z_{o}\}}(z_{o}) \\ &\geq \int_{K_{r}(x_{o})} \Gamma(x_{o}, 0; \xi, -r^{2}T) \,\mathrm{d}\xi - \mathcal{R}^{1}_{\{z_{o}\}}(z_{o}) \geq \frac{|A|}{\lambda^{n \log n}} - \mathcal{R}^{1}_{\{z_{o}\}}(z_{o}) \geq 1 \,, \end{aligned}$$

up to choosing a sufficiently small λ such that $\lambda^{n \log n} \leq (1 + \mathcal{R}^1_{\{z_o\}})/|A|$. Then, condition (5.16) is satisfied and the thesis follows.

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(M. Manfredini) DIPARTIMENTO DI SCIENZE FISICHE, INFORMATICHE E MATEMATICHE, UNIVERSITÀ DEGLI STUDI DI MODENA E REGGIO EMILIA VIA G. CAMPI 213/B, 41121 MODENA, ITALY Email address: maria.manfredini@unimore.it

(M. Piccinini) DIPARTIMENTO DI MATEMATICA,
UNIVERSITÀ DI PISA,
L.GO B. PONTECORVO 5, 56127, PISA, ITALY
Email address: mirco.piccinini@dm.unipi.it

(S. Polidoro) DIPARTIMENTO DI SCIENZE FISICHE, INFORMATICHE E MATEMATICHE, UNIVERSITÀ DEGLI STUDI DI MODENA E REGGIO EMILIA, VIA G. CAMPI 213/B, 41121 MODENA, ITALY *Email address*: sergio.polidoro@unimore.it