Γ-convergence of quadratic functionals with non uniformly elliptic conductivity matrices

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Abstract

We investigate the homogenization through Γ -convergence for the $L^2(\Omega)$ -weak topology of the conductivity functional with a zero-order term where the matrix-valued conductivity is assumed to be non strongly elliptic. Under proper assumptions, we show that the homogenized matrix A^* is provided by the classical homogenization formula. We also give algebraic conditions for two and three dimensional 1-periodic rank-one laminates such that the homogenization result holds. For this class of laminates, an explicit expression of A^* is provided which is a generalization of the classical laminate formula. We construct a two-dimensional counter-example which shows an anomalous asymptotic behaviour of the conductivity functional.

Keywords: quadratic functionals, homogenization, Γ -convergence, two-scale convergence, non-local functional

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1 Introduction

In this paper, for a bounded domain Ω of \mathbb{R}^d , we study the homogenization through Γ -convergence of the conductivity energy with a zero-order term of the type

$$\mathscr{F}_{\varepsilon}(u) := \begin{cases} \int_{\Omega} \left\{ A\left(\frac{x}{\varepsilon}\right) \nabla u \cdot \nabla u + |u|^{2} \right\} dx, & \text{if } u \in H_{0}^{1}(\Omega), \\ \\ \infty, & \text{if } u \in L^{2}(\Omega) \setminus H_{0}^{1}(\Omega). \end{cases}$$

$$\tag{1.1}$$

The conductivity A is a Y_d -periodic, symmetric and non-negative matrix-valued function in $L^{\infty}(\mathbb{R}^d)^{d\times d}$, denoted by $L^{\infty}_{\mathrm{per}}(Y_d)^{d\times d}$, which is not strongly elliptic, *i.e.*

ess-inf
$$\min \left\{ A(y)\xi \cdot \xi : \xi \in \mathbb{R}^d, |\xi| = 1 \right\} \ge 0.$$
 (1.2)

This condition holds true when the conductivity energy density has missing derivatives. This occurs, for example, when the quadratic form associated to A is given by

$$A\xi \cdot \xi := A'\xi' \cdot \xi'$$
 for $\xi = (\xi', \xi_d) \in \mathbb{R}^{d-1} \times \mathbb{R}$,

where $A' \in L^{\infty}_{per}(Y_d)^{(d-1)\times(d-1)}$ is symmetric and non-negative matrix. It is known (see e.g. [13, Chapters 24 and 25]) that the strongly ellipticity of the matrix A, i.e.

ess-inf
$$\min_{y \in Y_d} \left(\min \left\{ A(y)\xi \cdot \xi : \xi \in \mathbb{R}^d, |\xi| = 1 \right\} \right) > 0,$$
 (1.3)

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combined with the boundedness implies a compactness result of the conductivity functional

$$u \in H_0^1(\Omega) \mapsto \int_{\Omega} A\left(\frac{x}{\varepsilon}\right) \nabla u \cdot \nabla u dx$$

for the $L^2(\Omega)$ -strong topology. The Γ -limit is given by

$$\int_{\Omega} A^* \nabla u \cdot \nabla u dx,$$

where the matrix-valued function A^* is defined by the classical homogenization formula

$$A^*\lambda \cdot \lambda := \min \left\{ \int_{Y_d} A(y)(\lambda + \nabla v(y)) \cdot (\lambda + \nabla v(y)) dy : v \in H^1_{per}(Y_d) \right\}. \tag{1.4}$$

The Γ -convergence for the $L^p(\Omega)$ -strong topology, for p > 1, for the class of integral functionals F_{ε} of the form

$$F_{\varepsilon}(u) = \int_{\Omega} f\left(\frac{x}{\varepsilon}, Du\right) dx, \quad \text{for } u \in W^{1,p}(\Omega; \mathbb{R}^m),$$
 (1.5)

where $f: \Omega \times \mathbb{R}^{m \times d} \to \mathbb{R}$ is a Borel function, 1-periodic in the first variable satisfying the standard growth conditions of order p, namely $c_1|M|^p \leq f(x,M) \leq c_2(|M|^p+1)$ for any $x \in \Omega$ and for any real $(m \times d)$ -matrix M, has been widely studied and it is a classical subject (see e.g. [4, Chapter 12] and [13, Chapter 24]). On the contrary, the Γ -convergence of oscillating functionals for the weak topology on bounded sets of $L^p(\Omega)$ has been very few analysed. An example of the study of Γ -convergence for the $L^p(\Omega)$ -weak topology can be found in the paper [6] where, in the context of double-porosity, the authors compare the Γ -limit for non-linear functionals analogous to (1.5) computed with respect to different topologies and in particular with respect to $L^p(\Omega)$ -weak topology.

In this paper, we investigate the Γ -convergence for the weak topology on bounded sets (a metrizable topology) of $L^2(\Omega)$ of the conductivity functional under condition (1.2). In this case, one has no a priori $L^2(\Omega)$ -bound on the sequence of gradients, which implies a loss of coerciveness of the investigated energy. To overcome this difficulty, we add a quadratic zeroth-order term of the form $\|u\|_{L^2(\Omega)}^2$, so that we immediately obtain the coerciveness in the weak topology of $L^2(\Omega)$ of $\mathscr{F}_{\varepsilon}$, namely, for $u \in H_0^1(\Omega)$,

$$\mathscr{F}_{\varepsilon}(u) \ge \int_{\Omega} |u|^2 dx.$$

This estimate guarantees that Γ -limit for the weak topology on bounded sets of $L^2(\Omega)$ is characterized by conditions (i) and (ii) of the Definition 1.1 below (see [13, Proposition 8.10]), as well as, thanks to a compactness result (see [13, Corollary 8.12]), $\mathscr{F}_{\varepsilon}$ Γ -converges for the weak topology of $L^2(\Omega)$, up to subsequences, to some functional. We will show that, under the following assumptions:

- (H1) any two-scale limit $u_0(x, y)$ of a sequence u_{ε} of functions in $L^2(\Omega)$ with bounded energy $\mathscr{F}_{\varepsilon}(u_{\varepsilon})$ does not depend on y (see [1, Theorem 1.2]);
- (H2) the space V defined by

$$V:=\left\{\int_{Y_d}A^{1/2}(y)\Phi(y)dy:\Phi\in L^2_{\rm per}(Y_d;\mathbb{R}^d)\ \text{with }\operatorname{div}\left(A^{1/2}(y)\Phi(y)\right)=0\ \text{in }\ \mathscr{D}'(\mathbb{R}^d)\right\}$$

agrees with the space \mathbb{R}^d ,

the Γ -limit is given by

$$\mathscr{F}_0(u) := \begin{cases} \int_{\Omega} \left\{ A^* \nabla u \cdot \nabla u + |u|^2 \right\} dx, & \text{if } u \in H_0^1(\Omega), \\ \\ \infty, & \text{if } u \in L^2(\Omega) \setminus H_0^1(\Omega), \end{cases}$$
(1.6)

where the homogenized matrix A^* is given through the expected homogenization formula

$$A^*\lambda \cdot \lambda := \inf \left\{ \int_{Y_d} A(y)(\lambda + \nabla v(y)) \cdot (\lambda + \nabla v(y)) dy : v \in H^1_{\text{per}}(Y_d) \right\}. \tag{1.7}$$

We need to make assumption (H1) since for any sequence u_{ε} with bounded energy, *i.e.* $\sup_{\varepsilon>0} \mathscr{F}_{\varepsilon}(u_{\varepsilon}) < \infty$, the sequence ∇u_{ε} in $L^{2}(\Omega; \mathbb{R}^{d})$ is not bounded due to the lack of ellipticity of the matrix-valued conductivity A(y). Assumption (H2) turns out to be equivalent to the positive definiteness of the homogenized matrix (see Proposition 2.2).

In the 2D isotropic elasticity setting of [11], the authors make use of similar conditions as (H1) and (H2) in the proof of the main results (see [11, Theorems 3.3 and 3.4]). They investigate the limit in the sense of Γ -convergence for the $L^2(\Omega)$ -weak topology of the elasticity functional with a zeroth-order term in the case of two-phase isotropic laminate materials where the phase 1 is very strongly elliptic, while the phase 2 is only strongly elliptic. The strong ellipticity of the effective tensor is preserved through a homogenization process expect in the case when the volume fraction of each phase is 1/2, as first evidenced by Gutiérrez [14]. Indeed, Gutiérrez has provided two and three dimensional examples of 1-periodic rank-one laminates such that the homogenized tensor induced by a homogenization process, labelled 1*-convergence, is not strongly elliptic. These examples have been revisited by means of a homogenization process using Γ -convergence in the two-dimensional case of [10] and in the three-dimensional case of [12].

In the present scalar case, we enlighten assumptions (H1) and (H2) which are the key ingredients to obtain the general Γ-convergence result Theorem 2.1. Using Nguetseng-Allaire [1, 16] two-scale convergence, we prove that for any dimension $d \geq 2$, the Γ -limit \mathscr{F}_0 (1.6) for the weak topology of $L^2(\Omega)$ actually agrees with the one obtained for the $L^2(\Omega)$ -strong topology under uniformly ellipticity (1.3), replacing the minimum in (1.4) by the infimum in (1.7). Assumption (H2) implies the coerciveness of the functional \mathscr{F}_0 showing that its domain is $H_0^1(\Omega)$ and that the homogenized matrix A^* is positive definite. More precisely, the positive definiteness of A^* turns out to be equivalent to assumption (H2) (see Proposition 2.2). We also provide two and three dimensional 1-periodic rank-one laminates which satisfy assumptions (H1) and (H2) (see Proposition 3.1 for the two-dimensional case and Proposition 3.2 for the three-dimensional case). Thanks to Theorem 2.1, the corresponding homogenized matrix A^* is positive definite. For this class of laminates, an alternative and independent proof of positive definiteness of A^* is performed using an explicit expression of A^* (see Proposition A.1). This expression generalizes the classical laminate formula for non-degenerate phases (see [17] and also [2, Lemma 1.3.32], [8]) to the case of two-phase rank-one laminates with degenerate and anisotropic phases.

The lack of assumption (H1) may induce a degenerate asymptotic behaviour of the functional $\mathscr{F}_{\varepsilon}$ (1.1). We provide a two-dimensional rank-one laminate with two degenerate phases for which the functional $\mathscr{F}_{\varepsilon}$ does Γ -converge for the $L^2(\Omega)$ -weak topology to a functional \mathscr{F} which differs from the one given by (1.6) (see Proposition 4.1). In this example, any two-scale limit $u_0(x,y)$ of a sequence with bounded energy $\mathscr{F}_{\varepsilon}(u_{\varepsilon})$, depends on the variable y. Moreover, we give two quite different expressions of the Γ -limit \mathscr{F} which seem to be original up to the best of our knowledge. The energy density of the first expression is written with Fourier transform of the target function. The second expression appears as a non-local functional due to the presence of a convolution term. However, we do not know if the Γ -limit \mathscr{F} is a Dirichlet form in the sense of Beurling-Deny [3], since the Markovian property is not stable by the $L^2(\Omega)$ -weak topology (see Remark 4.5).

The paper is organized as follows. In Section 2, we prove a general Γ -convergence result (see Theorem 2.1) for the functional $\mathscr{F}_{\varepsilon}$ (1.1) with any non-uniformly elliptic matrix-valued function A, under assumptions (H1) and (H2). In Section 3 we illustrate the general result of Section 2 by periodic two-phase rank-one laminates with two (possibly) degenerate and anisotropic phases in dimension two and three. We provide algebraic conditions so that assumptions (H1) and (H2) are satisfied (see Propositions 3.1 and 3.2). In Section 4 we exhibit a two-dimensional counter-

example where assumption (H1) fails, which leads us to a degenerate Γ -limit \mathscr{F} involving a convolution term (see Proposition 4.1). Finally, in the Appendix we give an explicit formula for the homogenized matrix A^* for any two-phase rank-one laminates with (possibly) degenerate phases. We also provide an alternative proof of the positive definiteness of A^* using an explicit expression of A^* for the class of two-phase rank-one laminates introduced in Section 3 (see Proposition A.1).

Notation

- For i = 1, ..., d, e_i denotes the *i*-th vector of the canonical basis in \mathbb{R}^d ;
- I_d denotes the unit matrix of $\mathbb{R}^{d \times d}$;
- $H^1_{\text{per}}(Y_d; \mathbb{R}^n)$ (resp. $L^2_{\text{per}}(Y_d; \mathbb{R}^n)$, $C^{\infty}_{\text{per}}(Y_d; \mathbb{R}^n)$) is the space of those functions in $H^1_{\text{loc}}(\mathbb{R}^d; \mathbb{R}^n)$ (resp. $L^2_{\text{loc}}(\mathbb{R}^d; \mathbb{R}^n)$, $C^{\infty}_{\text{loc}}(\mathbb{R}^d; \mathbb{R}^n)$) that are Y_d -periodic;
- Throughout, the variable x will refer to running point in a bounded open domain $\Omega \subset \mathbb{R}^d$, while the variable y will refer to a running point in Y_d (or $k + Y_d$, $k \in \mathbb{Z}^d$);
- We write

$$u_{\varepsilon} \Rightarrow u_0$$

with $u_{\varepsilon} \in L^2(\Omega)$ and $u_0 \in L^2(\Omega \times Y_d)$ if u_{ε} two-scale converges to u^0 in the sense of Nguetseng-Allaire (see [1, 16])

• \mathcal{F}_1 and \mathcal{F}_2 denote the Fourier transform defined on $L^1(\mathbb{R})$ and $L^2(\mathbb{R})$ respectively. For $f \in L^1(\mathbb{R}) \cap L^2(\mathbb{R})$, the Fourier transform \mathcal{F}_1 of f is defined by

$$\mathcal{F}_1(f)(\lambda) := \int_{\mathbb{D}} e^{-2\pi i \lambda x} f(x) dx.$$

Definition 1.1. Let X be a reflexive and separable Banach space endowed with the weak topology $\sigma(X, X')$, and let $\mathscr{F}_{\varepsilon}: X \to \mathbb{R}$ be a ε -indexed sequence of functionals. The sequence $\mathscr{F}_{\varepsilon}$ Γ -converges to the functional $\mathscr{F}_0: X \to \mathbb{R}$ for the weak topology of X, and we write $\mathscr{F}_{\varepsilon} \overset{\Gamma(X) \to w}{\longrightarrow} \mathscr{F}_0$, if for any $u \in X$,

- $i) \quad \forall u_{\varepsilon} \rightharpoonup u, \, \mathscr{F}_0(u) \leq \liminf_{\varepsilon \to 0} \mathscr{F}_{\varepsilon}(u_{\varepsilon}),$
- ii) $\exists \overline{u}_{\varepsilon} \rightharpoonup u \text{ such that } \lim_{\varepsilon \to 0} \mathscr{F}_{\varepsilon}(\overline{u}_{\varepsilon}) = \mathscr{F}_{0}(u).$

Such a sequence $\overline{u}_{\varepsilon}$ is called a recovery sequence.

Recall that the weak topology of $L^2(\Omega)$ is metrizable on bounded sets, *i.e.* there exists a metric d on $L^2(\Omega)$ such that on every norm bounded subset B of $L^2(\Omega)$ the weak topology coincides with the topology induced on B by the metric d (see e.g. [13, Proposition 8.7]).

2 A preliminary general Γ -result

In this section, we will prove the main result of this paper. As previously announced, up to a subsequence, the sequence of functionals $\mathscr{F}_{\varepsilon}$, given by (1.1) with non-uniformly elliptic matrix-valued conductivity A(y), Γ -converges for the weak topology on bounded sets of $L^2(\Omega)$ to some functional. Our aim is to show that Γ -limit is exactly \mathscr{F}_0 when $u \in H^1_0(\Omega)$.

Theorem 2.1. Let $\mathscr{F}_{\varepsilon}$ be functionals given by (1.1) with A(y) a Y_d -periodic, symmetric, nonnegative matrix-valued function in $L^{\infty}(\mathbb{R}^d)^{d\times d}$ satisfying (1.2). Assume the following assumptions

- (H1) any two-scale limit $u_0(x,y)$ of a sequence u_{ε} of functions in $L^2(\Omega)$ with bounded energy $\mathscr{F}_{\varepsilon}(u_{\varepsilon})$ does not depend on y;
- (H2) the space V defined by

$$V := \left\{ \int_{Y_d} A^{1/2}(y) \Phi(y) dy : \Phi \in L^2_{per}(Y_d; \mathbb{R}^d) \text{ with } \operatorname{div}\left(A^{1/2}(y) \Phi(y)\right) = 0 \text{ in } \mathscr{D}'(\mathbb{R}^d) \right\}$$

$$(2.1)$$

agrees with the space \mathbb{R}^d .

Then, $\mathscr{F}_{\varepsilon}$ Γ -converges for the weak topology of $L^2(\Omega)$ to \mathscr{F}_0 , i.e.

$$\mathscr{F}_{\varepsilon}^{\Gamma(L^2)-w}\mathscr{F}_0,$$

where \mathscr{F}_0 is defined by (1.6) and A^* is given by (1.7).

Proof. We split the proof into two steps which are an adaptation of [11, Theorem 3.3] using the sole assumptions (H1) and (H2) in the general setting of conductivity.

Step 1 - Γ -lim inf inequality.

Consider a sequence $\{u_{\varepsilon}\}_{\varepsilon}$ converging weakly in $L^{2}(\Omega)$ to $u \in L^{2}(\Omega)$. We want to prove that

$$\liminf_{\varepsilon \to 0} \mathscr{F}_{\varepsilon}(u_{\varepsilon}) \ge \mathscr{F}_{0}(u).$$
(2.2)

If the lower limit is ∞ then (2.2) is trivial. Up to a subsequence, still indexed by ε , we may assume that $\liminf \mathscr{F}_{\varepsilon}(u_{\varepsilon})$ is a limit and we can also assume henceforth that, for some $0 < C < \infty$,

$$\mathscr{F}_{\varepsilon}(u_{\varepsilon}) \le C.$$
 (2.3)

As u_{ε} is bounded in $L^2(\Omega)$, there exists a subsequence, still indexed by ε , which two-scale converges to a function $u_0(x,y) \in L^2(\Omega \times Y_d)$ (see e.g. [1, Theorem 1.2]). In other words,

$$u_{\varepsilon} \stackrel{>}{=} u_0.$$
 (2.4)

Assumption (H1) ensures that

$$u_0(x,y) = u(x)$$
 is independent of y , (2.5)

where, according to the link between two-scale and weak $L^2(\Omega)$ -convergences (see [1, Proposition 1.6]), u is the weak limit of u_{ε} , *i.e.*

$$u_{\varepsilon} \rightharpoonup u$$
 weakly in $L^2(\Omega)$.

Since all the components of the matrix A(y) are bounded and A(y) is non-negative as a quadratic form, in view of (2.3), for another subsequence (not relabeled), we have

$$A\left(\frac{x}{\varepsilon}\right)\nabla u_{\varepsilon} \Longrightarrow \sigma_0(x,y)$$
 with $\sigma_0 \in L^2(\Omega \times Y_d; \mathbb{R}^d)$,

and also

$$A^{1/2}\left(\frac{x}{\varepsilon}\right)\nabla u_{\varepsilon} \stackrel{\Delta}{=} \Theta_0(x,y) \quad \text{with } \Theta_0 \in L^2(\Omega \times Y_d; \mathbb{R}^d).$$
 (2.6)

In particular

$$\varepsilon A\left(\frac{x}{\varepsilon}\right) \nabla u_{\varepsilon} \rightharpoonup 0. \tag{2.7}$$

Consider $\Phi \in L^2_{\mathrm{per}}(Y_d; \mathbb{R}^d)$ such that

$$\operatorname{div}\left(A^{1/2}(y)\Phi(y)\right) = 0 \quad \text{in } \mathscr{D}'(\mathbb{R}^d), \tag{2.8}$$

or equivalently,

$$\int_{Y_d} A^{1/2}(y)\Phi(y) \cdot \nabla \psi(y) dy = 0 \qquad \forall \psi \in H^1_{\text{per}}(Y_d).$$

Take also $\varphi \in C^{\infty}(\overline{\Omega})$. Since $u_{\varepsilon} \in H_0^1(\Omega)$ and in view of (2.8), an integration by parts yields

$$\int_{\Omega} A^{1/2} \left(\frac{x}{\varepsilon} \right) \nabla u_{\varepsilon} \cdot \Phi \left(\frac{x}{\varepsilon} \right) \varphi(x) dx = -\int_{\Omega} u_{\varepsilon} A^{1/2} \left(\frac{x}{\varepsilon} \right) \Phi \left(\frac{x}{\varepsilon} \right) \cdot \nabla \varphi(x) dx.$$

By using [1, Lemma 5.7], $A^{1/2}(y)\Phi(y)\cdot\nabla\varphi(x)$ is an admissible test function for the two-scale convergence. Then, we can pass to the two-scale limit in the previous expression with the help of the convergences (2.4) and (2.6) along with (2.5), and we obtain

$$\int_{\Omega \times Y_d} \Theta_0(x, y) \cdot \Phi(y) \varphi(x) dx dy = -\int_{\Omega \times Y_d} u(x) A^{1/2}(y) \Phi(y) \cdot \nabla \varphi(x) dx dy. \tag{2.9}$$

We prove that the target function u is in $H^1(\Omega)$. Setting

$$N := \int_{Y_d} A^{1/2}(y)\Phi(y)dy, \tag{2.10}$$

and varying φ in $C_c^{\infty}(\Omega)$, the equality (2.9) reads as

$$\int_{\Omega \times Y_d} \Theta_0(x, y) \cdot \Phi(y) \varphi(x) dx dy = -\int_{\Omega} u(x) N \cdot \nabla \varphi(x) dx$$

Since the integral in the left-hand side is bounded by a constant times $\|\varphi\|_{L^2(\Omega)}$, the right-hand side is a linear and continuous map in $\varphi \in L^2(\Omega)$. By the Riesz representation theorem, there exists $g \in L^2(\Omega)$ such that, for any $\varphi \in C_c^{\infty}(\Omega)$,

$$\int_{\Omega} u(x)N \cdot \nabla \varphi(x) dx = \int_{\Omega} g(x)\varphi(x) dx,$$

which implies that

$$N \cdot \nabla u \in L^2(\Omega). \tag{2.11}$$

In view of assumption (H2), N is an arbitrary vector in \mathbb{R}^d so that we infer from (2.11) that

$$u \in H^1(\Omega). \tag{2.12}$$

This combined with equality (2.9) leads us to

$$\int_{\Omega \times Y_d} \Theta_0(x, y) \cdot \Phi(y) \varphi(x) dx dy = \int_{\Omega \times Y_d} A^{1/2}(y) \nabla u(x) \cdot \Phi(y) \varphi(x) dx dy. \tag{2.13}$$

By density, the last equality holds if the test functions $\Phi(y)\varphi(x)$ are replaced by the set of $\psi(x,y) \in L^2(\Omega; L^2_{\rm per}(Y_d; \mathbb{R}^d))$ such that

$$\operatorname{div}_y\left(A^{1/2}(y)\psi(x,y)\right) = 0$$
 in $\mathscr{D}'(\mathbb{R}^d)$,

or equivalently,

$$\int_{\Omega \times Y_d} \psi(x, y) \cdot A^{1/2}(y) \nabla_y v(x, y) dx dy = 0 \qquad \forall v \in L^2(\Omega; H^1_{\text{per}}(Y_d)).$$

The $L^2(\Omega; L^2_{\mathrm{per}}(Y_d; \mathbb{R}^d))$ -orthogonal to that set is the L^2 -closure of

$$\mathscr{K} := \left\{ A^{1/2}(y) \nabla_y v(x, y) : v \in L^2(\Omega; H^1_{\text{per}}(Y_d)) \right\}.$$

Thus, the equality (2.13) yields

$$\Theta_0(x,y) = A^{1/2}(y)\nabla u(x) + S(x,y)$$

for some S in the closure of \mathcal{K} , i.e. there exists a sequence $v_n \in L^2(\Omega; H^1_{\text{per}}(Y_d))$ such that

$$A^{1/2}(y)\nabla_y v_n(x,y) \to S(x,y)$$
 strongly in $L^2(\Omega; L^2_{per}(Y_d; \mathbb{R}^d))$.

Due to the lower semi-continuity property of two-scale convergence (see [1, Proposition 1.6]), we get

$$\lim_{\varepsilon \to 0} \inf \|A^{1/2}(x/\varepsilon)\nabla u_{\varepsilon}\|_{L^{2}(\Omega;\mathbb{R}^{d})}^{2} \ge \|\Theta_{0}\|_{L^{2}(\Omega \times Y_{d};\mathbb{R}^{d})}^{2}$$

$$= \lim_{n} \|A^{1/2}(y)\left(\nabla_{x}u(x) + \nabla_{y}v_{n}\right)\|_{L^{2}(\Omega \times Y_{d};\mathbb{R}^{d})}^{2}.$$

Then, by the weak L^2 -lower semi-continuity of $||u_{\varepsilon}||_{L^2(\Omega)}$, we have

$$\lim_{\varepsilon \to 0} \inf \mathscr{F}_{\varepsilon}(u_{\varepsilon}) \ge \lim_{n} \int_{\Omega \times Y_{d}} A(y) (\nabla_{x} u(x) + \nabla_{y} v_{n}(x, y)) \cdot (\nabla_{x} u(x) + \nabla_{y} v_{n}(x, y)) dx dy
+ \int_{\Omega} |u|^{2} dx
\ge \int_{\Omega} \inf \left\{ \int_{Y_{d}} A(y) (\nabla_{x} u(x) + \nabla_{y} v(y)) \cdot (\nabla_{x} u(x) + \nabla_{y} v(y)) dy : v \in H^{1}_{per}(Y_{d}) \right\} dx
+ \int_{\Omega} |u|^{2} dx.$$

Recalling the definition (1.7), we immediately conclude that

$$\liminf_{\varepsilon \to 0} \mathscr{F}_{\varepsilon}(u_{\varepsilon}) \ge \int_{\Omega} \left\{ A^* \nabla u \cdot \nabla u + |u|^2 \right\} dx,$$

provided that $u \in H_0^1(\Omega)$.

It remains to prove that the target function u is actually in $H_0^1(\Omega)$, giving a complete characterization of Γ -limit. To this end, take $x_0 \in \partial \Omega$ a Lebesgue point for $u \mid \partial \Omega$ and for $\nu(x_0)$, the exterior normal to Ω at point x_0 . Thanks to (2.12), we know that $u \in H^1(\Omega)$, hence, after an integration by parts of the right-hand side of (2.9), we obtain, for $\varphi \in C^{\infty}(\overline{\Omega})$,

$$\int_{\Omega \times Y_d} \Theta_0(x, y) \cdot \Phi(y) \varphi(x) dx dy = \int_{\Omega} N \cdot \nabla u(x) \varphi(x) dx - \int_{\partial \Omega} N \cdot \nu(x) u(x) \varphi(x) d\mathcal{H}, \quad (2.14)$$

where N is given by (2.10). Varying φ in $C_c^{\infty}(\Omega)$, the first two integrals in (2.14) are equal and bounded by a constant times $\|\varphi\|_{L^2(\Omega)}$. It follows that, for any $\varphi \in C^{\infty}(\overline{\Omega})$,

$$\int_{\partial\Omega} N \cdot \nu(x) u(x) \varphi(x) d\mathcal{H} = 0,$$

which leads to $N \cdot \nu(x)u(x) = 0$ \mathcal{H} -a.e. on $\partial\Omega$. Since x_0 is a Lebesgue point, we have

$$N \cdot \nu(x_0)u(x_0) = 0. \tag{2.15}$$

In view of assumption (H2) and the arbitrariness of N, we can choose N such that $N = \nu(x_0)$ so that from (2.15) we get $u(x_0) = 0$. Hence,

$$u \in H_0^1(\Omega)$$
.

This concludes the proof of the Γ -lim inf inequality.

Step 2 - Γ-lim sup inequality.

We use the same arguments of [12, Theorem 2.4] which can easily extend to the conductivity setting. We just give an idea of the proof, which is based on a perturbation argument. For $\delta > 0$, let A_{δ} be the perturbed matrix of $\mathbb{R}^{d \times d}$ defined by

$$A_{\delta} := A + \delta I_d$$

where I_d is the unit matrix of $\mathbb{R}^{d \times d}$. Since the matrix A is non-negative, A_{δ} turns out to be positive definite, hence, the functional $\mathscr{F}_{\varepsilon}^{\delta}$, defined by (1.1) with A_{δ} in place of A, Γ -converges to the functional \mathscr{F}^{δ} given by

$$\mathscr{F}^{\delta}(u) := \begin{cases} \int_{\Omega} \left\{ A_{\delta}^* \nabla u \cdot \nabla u + |u|^2 \right\} dx, & \text{if} \quad u \in H_0^1(\Omega), \\ \\ \infty, & \text{if} \quad u \in L^2(\Omega) \setminus H_0^1(\Omega), \end{cases}$$

for the strong topology of $L^2(\Omega)$ (see e.g. [13, Corollary 24.5]). Thanks to the compactness result of Γ-convergence (see e.g. [4, Proposition 1.42]), there exists a subsequence ε_j such that $\mathscr{F}_{\varepsilon_j}$ Γ-converges for the $L^2(\Omega)$ -strong topology to some functional F^0 . Let $u \in H^1_0(\Omega)$ and let u_{ε_j} be a recovery sequence for $\mathscr{F}_{\varepsilon_j}$ which converges to u for the $H^1(\Omega)$ -weak topology on bounded sets. Since $\mathscr{F}_{\varepsilon_j} \leq \mathscr{F}_{\varepsilon_j}^{\delta}$ and since u_{ε_j} belongs to some bounded set of $H^1(\Omega)$, from [13, Propositions 6.7 and 8.10] we deduce that

$$F^{0}(u) \leq \mathscr{F}^{\delta}(u)$$

$$\leq \liminf_{\varepsilon_{j} \to 0} \int_{\Omega} \left\{ A_{\delta} \left(\frac{x}{\varepsilon_{j}} \right) \nabla u_{\varepsilon_{j}} \cdot \nabla u_{\varepsilon_{j}} + |u_{\varepsilon_{j}}|^{2} \right\} dx$$

$$\leq \liminf_{\varepsilon_{j} \to 0} \int_{\Omega} \left\{ A \left(\frac{x}{\varepsilon_{j}} \right) \nabla u_{\varepsilon_{j}} \cdot \nabla u_{\varepsilon_{j}} + |u_{\varepsilon_{j}}|^{2} \right\} dx + O(\delta)$$

$$= F^{0}(u) + O(\delta).$$

It follows that \mathscr{F}^{δ} converges to F^0 as $\delta \to 0$. Then, the Γ -limit F^0 of $\mathscr{F}_{\varepsilon_j}$ is independent on the subsequence ε_j . Repeating the same arguments, any subsequence of $\mathscr{F}_{\varepsilon}$ has a further subsequence which Γ -converges for the strong topology of $L^2(\Omega)$ to $F^0 = \lim_{\delta \to 0} \mathscr{F}^{\delta}$. Thanks to the Urysohn property (see *e.g.* [4, Proposition 1.44]), the whole sequence $\mathscr{F}_{\varepsilon}$ Γ -converges to the functional F^0 for the strong topology of $L^2(\Omega)$. On the other hand, in light of the definition (1.7) of A^* , we get that A^*_{δ} converges to A^* as $\delta \to 0$, *i.e.*

$$\lim_{\delta \to 0} A_{\delta}^* = A^*. \tag{2.16}$$

Thanks to the Lebesgue dominated convergence theorem and in view of (2.16), we get that $F^0 = \lim_{\delta \to 0} \mathscr{F}^{\delta}$ is exactly \mathscr{F}_0 given by (1.6). Therefore, $\mathscr{F}_{\varepsilon}$ Γ -converges to \mathscr{F}_0 for the $L^2(\Omega)$ -strong topology.

Now, let us show that $\mathscr{F}_{\varepsilon}$ Γ -converges to \mathscr{F}_0 for the weak topology of $L^2(\Omega)$. Recall that the $L^2(\Omega)$ -weak topology is metrizable on the closed ball of $L^2(\Omega)$. Fix $n \in \mathbb{N}$ and let d_{B_n} be any metric inducing the $L^2(\Omega)$ -weak topology on the ball B_n centered on 0 and of radius n. Let $u \in H^1_0(\Omega)$ and let $\overline{u}_{\varepsilon}$ be a recovery sequence for $\mathscr{F}_{\varepsilon}$ for the $L^2(\Omega)$ -strong topology. Since the topology induced by the metric d_{B_n} on B_n is weaker than the $L^2(\Omega)$ -strong topology, $\overline{u}_{\varepsilon}$ is also a recovery sequence for $\mathscr{F}_{\varepsilon}$ for the $L^2(\Omega)$ -weak topology on B_n . Hence,

$$\lim_{\varepsilon \to 0} \mathscr{F}_{\varepsilon}(\overline{u}_{\varepsilon}) = \mathscr{F}_{0}(u),$$

which proves the Γ -lim sup inequality in B_n . Finally, since any sequence converging weakly in $L^2(\Omega)$ belongs to some ball $B_n \subset L^2(\Omega)$, as well as its limit, it follows that the Γ -lim sup inequality holds true for $\mathscr{F}_{\varepsilon}$ for $L^2(\Omega)$ -weak topology, which concludes the proof.

The next proposition provides a characterization of Assumption (H2) in terms of homogenized matrix A^* .

Proposition 2.2. Assumption (H2) is equivalent to the positive definiteness of A^* , or equivalently,

$$\operatorname{Ker}(A^*) = V^{\perp}.$$

Proof. Consider $\lambda \in \text{Ker}(A^*)$. Define

$$H^1_{\lambda}(Y_d) := \left\{ u \in H^1_{\mathrm{loc}}(\mathbb{R}^d) \, \colon \nabla u \ \text{ is } \ Y_d\text{-periodic and } \ \int_{Y_d} \nabla u(y) dy = \lambda \right\}.$$

Recall that $u \in H^1_{\lambda}(Y_d)$ if and only if there exists $v \in H^1_{per}(Y_d)$ such that $u(y) = v(y) + \lambda \cdot y$ (see e.g. [13, Lemma 25.2]). Since A^* is non-negative and symmetric, from (1.7) it follows that

$$0 = A^* \lambda \cdot \lambda = \inf \left\{ \int_{Y_d} A(y) \nabla u(y) \cdot \nabla u(y) dy : u \in H^1_{\lambda}(Y_d) \right\}.$$

Then, there exists a sequence u_n of functions in $H^1_{\lambda}(Y_d)$ such that

$$\lim_{n \to \infty} \int_{Y_d} A(y) \nabla u_n(y) \cdot \nabla u_n(y) dy = 0,$$

which implies that

$$A^{1/2}\nabla u_n \to 0$$
 strongly in $L^2(Y_d; \mathbb{R}^d)$. (2.17)

Now, take $\Phi \in L^2_{\rm per}(Y_d; \mathbb{R}^d)$ such that $A^{1/2}\Phi$ is a divergence free field in \mathbb{R}^d . Recall that, since $u_n \in H^1_{\lambda}(Y_d)$, we have that $\nabla u_n(y) = \nabla v_n(y) + \lambda$, for some $v_n \in H^1_{\rm per}(Y_d)$. This implies that

$$\int_{Y_d} A^{1/2}(y) \nabla u_n(y) \cdot \Phi(y) dy = \int_{Y_d} \nabla u_n(y) \cdot A^{1/2}(y) \Phi(y) dy
= \lambda \cdot \int_{Y_d} A^{1/2}(y) \Phi(y) dy + \int_{Y_d} \nabla v_n(y) \cdot A^{1/2}(y) \Phi(y) dy
= \lambda \cdot \int_{Y_d} A^{1/2}(y) \Phi(y) dy,$$
(2.18)

where the last equality is obtained by integrating by parts the second integral combined with the fact that $A^{1/2}\Phi$ is a divergence free field in \mathbb{R}^d . In view of convergence (2.17), the integral on the left-hand side of (2.18) converges to 0. Hence, passing to the limit as $n \to \infty$ in (2.18) yields

$$0 = \lambda \cdot \left(\int_{Y_d} A^{1/2}(y) \Phi(y) dy \right),\,$$

for any $\Phi \in L^2_{\rm per}(Y_d; \mathbb{R}^d)$ such that $A^{1/2}\Phi$ is a divergence free field in \mathbb{R}^d . Therefore $\lambda \in V^{\perp}$ which implies that

$$Ker(A^*) \subseteq V^{\perp}$$
.

Conversely, by (2.16) we already know that

$$\lim_{\delta \to 0} A_{\delta}^* = A^*,$$

where A_{δ}^* is the homogenized matrix associated with $A_{\delta} = A + \delta I_d$. Since A_{δ} is strongly elliptic, the homogenized matrix A_{δ}^* is given by

$$A_{\delta}^* \lambda \cdot \lambda = \min \left\{ \int_{Y_d} A_{\delta}(y) \nabla u_{\delta}(y) \cdot \nabla u_{\delta}(y) dy : u_{\delta} \in H_{\lambda}^1(Y_d) \right\}. \tag{2.19}$$

Let \overline{u}_{δ} be the minimizer of problem (2.19). Therefore, there exists a constant C>0 such that

$$A_{\delta}^* \lambda \cdot \lambda = \int_{Y_d} A_{\delta}(y) \nabla \overline{u}_{\delta}(y) \cdot \nabla \overline{u}_{\delta}(y) dy = \int_{Y_d} |A_{\delta}^{1/2}(y) \nabla \overline{u}_{\delta}(y)|^2 dy \le C,$$

which implies that the sequence $\Phi_{\delta}(y) := A_{\delta}^{1/2}(y) \nabla \overline{u}_{\delta}(y)$ is bounded in $L_{\text{per}}^2(Y_d; \mathbb{R}^d)$. Then, up to extract a subsequence, we can assume that Φ_{δ} converges weakly to some Φ in $L_{\text{per}}^2(Y_d; \mathbb{R}^d)$.

Now, we show that $A_{\delta}^{1/2}$ converges strongly to $A^{1/2}$ in $L_{\rm per}^{\infty}(Y_d)^{d\times d}$. Since A(y) is a symmetric matrix, there exists an orthogonal matrix-valued function R in $L_{\rm per}^{\infty}(Y_d)^{d\times d}$ such that

$$A(y) = R(y)D(y)R^{T}(y)$$
 for a.e. $y \in Y_d$,

where D is a diagonal non-negative matrix-valued function in $L_{per}^{\infty}(Y_d)^{d\times d}$ and R^T denotes the transpose of R. It follows that $A_{\delta}(y) = A(y) + \delta I_d = R(y)(D(y) + \delta I_d)R^T(y)$, for a.e. $y \in Y_d$. Hence,

$$A_{\delta}^{1/2}(y) = R(y)(D(y) + \delta I_d)^{1/2}R^T(y)$$
 for a.e. $y \in Y_d$,

which implies that $A_{\delta}^{1/2}$ converges strongly to $A^{1/2} = RD^{1/2}R^T$ in $L_{\rm per}^{\infty}(Y_d)^{d\times d}$. Now, passing to the limit as $\delta\to 0$ in

$$\operatorname{div}(A_{\delta}^{1/2}\Phi_{\delta}) = \operatorname{div}(A_{\delta}\nabla \overline{u}_{\delta}) = 0 \quad \text{in } \mathscr{D}'(\mathbb{R}^d),$$

we have

$$\operatorname{div}(A^{1/2}\Phi) = 0$$
 in $\mathscr{D}'(\mathbb{R}^d)$.

This along with $\Phi \in L^2_{per}(Y_d; \mathbb{R}^d)$ implies that Φ is a test function for the set V given by (2.1). From (2.19) it follows that

$$A_{\delta}^* \lambda = \int_{Y_{\delta}} A_{\delta}(y) \nabla \overline{u}_{\delta}(y) dy = \int_{Y_{\delta}} A_{\delta}^{1/2}(y) \Phi_{\delta}(y) dy.$$

Hence, taking into account the strong convergence of $A_{\delta}^{1/2}$ in $L_{\text{per}}^{\infty}(Y_d)^{d\times d}$ and the weak convergence of Φ_{δ} in $L_{\text{per}}^2(Y_d; \mathbb{R}^d)$, we have

$$A^*\lambda = \lim_{\delta \to 0} A_\delta^*\lambda = \lim_{\delta \to 0} \int_{Y_d} A_\delta^{1/2}(y) \Phi_\delta(y) dy = \int_{Y_d} A^{1/2}(y) \Phi(y) dy,$$

which implies that $A^*\lambda \in V$ since Φ is a suitable test function for the set V. Therefore, for $\lambda \in V^{\perp}$,

$$A^*\lambda \cdot \lambda = 0$$
,

so that, since A^* is a non-negative matrix, we deduce that $\lambda \in \text{Ker}(A^*)$. In other words,

$$V^{\perp} \subseteq \operatorname{Ker}(A^*),$$

which concludes the proof.

3 Two-dimensional and three-dimensional examples

In this section we provide a geometric setting for which assumptions (H1) and (H2) are fulfilled. We focus on a 1-periodic rank-one laminates of direction e_1 with two phases in \mathbb{R}^d , d=2,3. Specifically, we assume the existence of two anisotropic phases Z_1 and Z_2 of Y_d given by

$$Z_1 = (0, \theta) \times (0, 1)^{d-1}$$
 and $Z_2 = (\theta, 1) \times (0, 1)^{d-1}$,

where θ denotes the volume fraction of the phase Z_1 . Let $Z_1^{\#}$ and $Z_2^{\#}$ be the associated subsets of \mathbb{R}^d , *i.e.* the open periodic sets

$$Z_i^{\#} := \operatorname{Int} \left(\bigcup_{k \in \mathbb{Z}^d} \left(\overline{Z_i} + k \right) \right) \quad \text{for } i = 1, 2.$$

Let X_1 and X_2 be unbounded connected components of $Z_1^\#$ and $Z_2^\#$ in \mathbb{R}^d given by

$$X_1 := (0, \theta) \times \mathbb{R}^{d-1}$$
 and $X_2 := (\theta, 1) \times \mathbb{R}^{d-1}$,

and we denote by ∂Z the interface $\{y_1 = 0\}$.

The anisotropic phases are described by two constant, symmetric and non-negative matrices A_1 and A_2 of $\mathbb{R}^{d\times d}$ which are possibly not positive definite. Hence, the conductivity matrix-valued function $A\in L^\infty_{\rm per}(Y_d)^{d\times d}$, given by

$$A(y_1) := \chi(y_1)A_1 + (1 - \chi(y_1))A_2 \quad \text{for } y_1 \in \mathbb{R}, \tag{3.1}$$

where χ is the 1-periodic characteristic function of the phase Z_1 , is not strongly elliptic, *i.e.* (1.2) is satisfied.

3.1 The two-dimensional case with one degenerate phase

We are interested in two-phase mixtures in \mathbb{R}^2 with one degenerate phase. We specialize to the case where the non-negative and symmetric matrices A_1 and A_2 of $\mathbb{R}^{2\times 2}$ are such that

$$A_1 = \xi \otimes \xi$$
 and A_2 is positive definite, (3.2)

for some $\xi \in \mathbb{R}^2$. The next proposition establishes the algebraic conditions which provide assumptions (H1) and (H2) of Theorem 2.1.

Proposition 3.1. Let A_1 and A_2 be the matrices defined by (3.2). Assume that $\xi \cdot e_1 \neq 0$ and the vectors ξ and A_2e_1 are linearly independent in \mathbb{R}^2 . Then, assumptions (H1) and (H2) are satisfied. In particular, the homogenized matrix A^* , given by (1.7), associated to the matrix A defined by (3.1) and (3.2) is positive definite.

From Theorem 2.1, we easily deduce that the energy $\mathscr{F}_{\varepsilon}$ defined by (1.1) with A given by (3.1) and (3.2) Γ -converges to the functional \mathscr{F}_0 given by (1.6) with conductivity matrix A^* defined by (1.7). In the present case, the homogenized matrix A^* has an explicit expression given in Proposition A.1 in the Appendix.

Proof. Firstly, let us prove assumption (H1). We adapt the proof of Step 1 of [11, Theorem 3.3] to two-dimensional laminates. In our context, the algebra involved is different due to the scalar setting.

Denote by u_0^i the restriction of the two-scale limit u_0 in phase Z_i or $Z_i^{\#}$ for i=1,2. In view of (2.7), for any $\Phi(x,y) \in C_c^{\infty}(\Omega \times \mathbb{R}^2; \mathbb{R}^2)$ with compact support in $\Omega \times Z_1^{\#}$, or due to periodicity in $\Omega \times X_1$, we deduce that

$$0 = -\lim_{\varepsilon \to 0} \varepsilon \int_{\Omega} A\left(\frac{x}{\varepsilon}\right) \nabla u_{\varepsilon} \cdot \Phi\left(x, \frac{x}{\varepsilon}\right) dx$$

$$= \lim_{\varepsilon \to 0} \int_{\Omega} u_{\varepsilon} \operatorname{div}_{y}(A_{1}\Phi(x, y)) \left(x, \frac{x}{\varepsilon}\right) dx$$

$$= \int_{\Omega \times Z_{1}^{\#}} u_{0}^{1}(x, y) \operatorname{div}_{y}(A_{1}\Phi(x, y)) dx dy$$

$$= -\int_{\Omega \times Z_{1}^{\#}} A_{1} \nabla_{y} u_{0}^{1}(x, y) \cdot \Phi(x, y) dx dy,$$

so that

$$A_1 \nabla_y u_0^1(x, y) \equiv 0 \quad \text{in } \Omega \times Z_1^{\#}. \tag{3.3}$$

Similarly, taking $\Phi(x,y) \in C_c^{\infty}(\Omega \times \mathbb{R}^2; \mathbb{R}^2)$ with compact support in $\Omega \times Z_2^{\#}$, or equivalently in $\Omega \times X_2$, as test function and repeating the same arguments, we obtain

$$A_2 \nabla_y u_0^2(x, y) \equiv 0 \quad \text{in } \Omega \times Z_2^{\#}. \tag{3.4}$$

Due to (3.3), in phase $Z_1^{\#}$ we have

$$\nabla_y u_0^1 \in \operatorname{Ker}(A_1) = \operatorname{Span}(\xi^{\perp}),$$

where $\xi^{\perp} = (-\xi_2, \xi_1) \in \mathbb{R}^2$ is perpendicular to $\xi = (\xi_1, \xi_2)$. Hence, u_0^1 reads as

$$u_0^1(x,y) = \theta^1(x,\xi^{\perp} \cdot y)$$
 a.e. $(x,y) \in \Omega \times X_1$, (3.5)

for some function $\theta^1 \in L^2(\Omega \times \mathbb{R})$. On the other hand, since the matrix A_2 is positive definite, in phase $Z_2^{\#}$ the relation (3.4) implies that

$$u_0^2(x,y) = \theta^2(x)$$
 a.e. $(x,y) \in \Omega \times X_2$, (3.6)

for some function $\theta^2 \in L^2(\Omega)$. Now, consider a constant vector-valued function Φ defined on Y_2 such that

$$(A_1 - A_2)\Phi \cdot e_1 = 0$$
 on $\partial Z_1^{\#}$. (3.7)

Note that condition (3.7) is necessary for $\operatorname{div}_y(A(y)\Phi)$ to be an admissible test function for two-scale convergence. In view of (2.7) and (3.6), for any $\varphi \in C_c^{\infty}(\Omega; C_{\operatorname{per}}^{\infty}(Y_2))$, we obtain

$$0 = -\lim_{\varepsilon \to 0} \varepsilon \int_{\Omega} A(y) \nabla u_{\varepsilon} \cdot \Phi \varphi \left(x, \frac{x}{\varepsilon} \right) dx$$

$$= \lim_{\varepsilon \to 0} \int_{\Omega} u_{\varepsilon} \operatorname{div}_{y} (A(y) \Phi \varphi(x, y)) \left(x, \frac{x}{\varepsilon} \right) dx$$

$$= \int_{\Omega \times Z_{1}} u_{0}^{1}(x, y) \operatorname{div}_{y} (A_{1} \Phi \varphi(x, y)) dx dy$$

$$+ \int_{\Omega \times Z_{2}} \theta^{2}(x) \operatorname{div}_{y} (A_{2} \Phi \varphi(x, y)) dx dy.$$

Take now $\varphi \in C_c^{\infty}(\Omega \times \mathbb{R}^2)$ and use the periodized function

$$\varphi^{\#}(x,y) := \sum_{k \in \mathbb{Z}^2} \varphi(x,y+k)$$

as new test function. Then, we obtain

$$0 = \int_{\Omega \times Z_{1}} u_{0}^{1}(x, y) \operatorname{div}_{y}(A_{1} \Phi \varphi^{\#}(x, y)) dx dy + \int_{\Omega \times Z_{2}} \theta^{2}(x) \operatorname{div}_{y}(A_{2} \Phi \varphi^{\#}(x, y)) dx dy$$

$$= \sum_{k \in \mathbb{Z}^{2}} \int_{\Omega \times (Z_{1} + k)} u_{0}^{1}(x, y) \operatorname{div}_{y}(A_{1} \Phi \varphi(x, y)) dx dy$$

$$+ \sum_{k \in \mathbb{Z}^{2}} \int_{\Omega \times (Z_{2} + k)} \theta^{2}(x) \operatorname{div}_{y}(A_{2} \Phi \varphi(x, y)) dx dy$$

$$= \int_{\Omega \times Z_{1}^{\#}} u_{0}^{1}(x, y) \operatorname{div}_{y}(A_{1} \Phi \varphi(x, y)) dx dy + \int_{\Omega \times Z_{2}^{\#}} \theta^{2}(x) \operatorname{div}_{y}(A_{2} \Phi \varphi(x, y)) dx dy.$$
(3.8)

Recall that $A_1 = \xi \otimes \xi$, where ξ is such that $\xi \cdot e_1 \neq 0$. This combined with the linear independence of the vectors ξ and A_2e_1 implies that the linear map

$$\Phi \in \mathbb{R}^2 \mapsto (A_1 e_1 \cdot \Phi, A_2 e_1 \cdot \Phi) \in \mathbb{R}^2$$

is one-to-one. Hence, for any $f \in \mathbb{R}$, there exists a unique $\Phi \in \mathbb{R}^2$ such that

$$A_1 \Phi \cdot e_1 = A_2 \Phi \cdot e_1 = f. \tag{3.9}$$

In view of the arbitrariness of f in (3.9), we can choose Φ such that

$$A_1 e_1 \cdot \Phi = A_2 e_1 \cdot \Phi = 1 \quad \text{on } \partial Z_1^{\#}. \tag{3.10}$$

Since $A_1 \nabla_y u_0^1 = 0$ in the distributional sense and $A_1 = \xi \otimes \xi$, we deduce that u_0^1 is constant along the direction ξ . Using Fubini's theorem, we may integrate along straight lines parallel to the vector ξ where integration by parts is allowed. Therefore, performing an integration by parts in (3.8) combined with (3.10), it follows that for any $\varphi \in C_c^{\infty}(\Omega \times \mathbb{R}^2)$,

$$0 = \int_{\Omega \times \partial Z} v_0(x, y) \varphi(x, y) dx d\mathscr{H}_y,$$

where we have set $v_0(x,y) := u_0^1(x,y) - \theta^2(x)$. We conclude that $v_0(x,\cdot)$ has a trace on ∂Z for a.e. $x \in \Omega$ satisfying

$$v_0(x,\cdot) = 0$$
 on ∂Z . (3.11)

Recall that $\partial Z = \{y_1 = 0\}$. Fix $x \in \Omega$. Taking into account (3.5) and (3.6), the equality (3.11) reads as

$$\theta^1(x, \xi_1 y_2) = \theta^2(x)$$
 on ∂Z

Since $\xi \cdot e_1 \neq 0$, it follows that θ^1 only depends on x so that $u_0^1(x,y)$ agrees with $\theta^2(x)$. Finally, we conclude that $u_0(x,y) := \chi(y_1)u_0^1(x,y) + (1-\chi(y_1))u_0^2(x,y)$ is independent of y and hence (H1) is satisfied.

Let us prove assumption (H2). The proof is a variant of the Step 2 of [11, Theorem 3.4]. For arbitrary $\alpha, \beta \in \mathbb{R}$, let Φ be a vector-valued function given by

$$A^{1/2}(y)\Phi(y) := \chi(y_1)\alpha\xi + (1 - \chi(y_1))(\alpha\xi + \beta e_2) \quad \text{for a.e. } y \in \mathbb{R}^2.$$
 (3.12)

Such a vector field Φ does exist, since ξ is in the range of A_1 and thus the right-hand side of (3.12) belongs pointwise to the range of A, or equivalently to the range of $A^{1/2}$. Moreover, the difference of two constant phases in (3.12) is orthogonal to the laminate direction e_1 , so that $A^{1/2}\Phi$ is a laminate divergence free periodic field in \mathbb{R}^2 . Its average value is given by

$$N := \int_{Y_2} A^{1/2}(y)\Phi(y)dy = \alpha\xi + (1 - \theta)\beta e_2.$$

Hence, due to $\xi \cdot e_1 \neq 0$ and the arbitrariness of α, β , the set of the vectors N spans \mathbb{R}^2 , which yields assumption (H2).

From Proposition 2.2, it immediately follows that the homogenized matrix A^* is positive definite. For the reader's convenience, the proof of explicit formula of A^* is postponed to Proposition A.1 in the Appendix.

3.2 The three-dimensional case with both degenerate phases

We are going to deal with three-dimensional laminates where both phases are degenerate. We assume that the symmetric and non-negative matrices A_1 and A_2 of $\mathbb{R}^{3\times3}$ have rank two, hence, there exist $\eta_1, \eta_2 \in \mathbb{R}^3$ such that

$$\operatorname{Ker}(A_i) = \operatorname{Span}(\eta_i) \quad \text{for } i = 1, 2.$$
 (3.13)

The following proposition gives the algebraic conditions so that assumptions required by Theorem 2.1 are satisfied.

Proposition 3.2. Let η_1 and η_2 be the vectors in \mathbb{R}^3 defined by (3.13). Assume that the vectors $\{e_1, \eta_1, \eta_2\}$ as well as $\{A_1e_1, A_2e_1\}$ are linearly independent in \mathbb{R}^3 . Then, assumptions (H1) and (H2) are satisfied. In particular, the homogenized matrix A^* given by (1.7) and associated to the conductivity matrix A given by (3.1) and (3.13) is positive definite.

Invoking again Theorem 2.1, the energy $\mathscr{F}_{\varepsilon}$ defined by (1.1) with A given by (3.1) and (3.13), Γ -converges for the weak topology of $L^2(\Omega)$ to \mathscr{F}_0 where the effective conductivity A^* is given by (1.7). As in two-dimensional laminate materials, A^* has an explicit expression (see Proposition A.1 in the Appendix).

Proof. Let us first check assumption (H1). The proof is an adaptation of the first step of [11, Theorem 3.3]. Same arguments as in the proof of Proposition 3.1 show that

$$A_i \nabla_y u_0^i(x, y) \equiv 0$$
 in $\Omega \times Z_i^{\#}$ for $i = 1, 2$. (3.14)

In view of (3.13) and (3.14), in phase $Z_i^{\#}$, u_0^i reads as

$$u_0^i(x,y) = \theta^i(x,\eta_i \cdot y)$$
 a.e. $(x,y) \in \Omega \times X_i$, (3.15)

for some function $\theta^i \in L^2(\Omega \times \mathbb{R})$ and i = 1, 2. Now, consider a constant vector-valued function Φ on Y_3 such that the transmission condition (3.7) holds. In view of (2.7), for any $\varphi \in C_{\rm c}^{\infty}(\Omega, C_{\rm per}^{\infty}(Y_3))$, we obtain

$$0 = -\lim_{\varepsilon \to 0} \varepsilon \int_{\Omega} A(y) \nabla u_{\varepsilon} \cdot \Phi \varphi \left(x, \frac{x}{\varepsilon} \right) dx$$

$$= \int_{\Omega \times Z_{1}} u_{0}^{1}(x, y) \operatorname{div}_{y} (A_{1} \Phi \varphi(x, y)) dx dy$$

$$+ \int_{\Omega \times Z_{2}} u_{0}^{2}(x, y) \operatorname{div}_{y} (A_{2} \Phi \varphi(x, y)) dx dy.$$
(3.16)

Take $\varphi \in C_c^{\infty}(\Omega \times \mathbb{R}^3)$. Putting the periodized function

$$\varphi^{\#}(x,y) := \sum_{k \in \mathbb{Z}^3} \varphi(x,y+k)$$

as test function in (3.16), we get

$$\int_{\Omega \times Z_1^{\#}} u_0^1(x, y) \operatorname{div}_y(A_1 \Phi \varphi(x, y)) dx dy + \int_{\Omega \times Z_2^{\#}} u_0^2(x, y) \operatorname{div}_y(A_2 \Phi \varphi(x, y)) dx dy = 0.$$
 (3.17)

Since the vectors A_1e_1 and A_2e_1 are independent in \mathbb{R}^3 , the linear map

$$\Phi \in \mathbb{R}^3 \mapsto (A_1 e_1 \cdot \Phi, A_2 e_1 \cdot \Phi) \in \mathbb{R}^2$$

is surjective. In particular, for any $f \in \mathbb{R}$, there exists $\Phi \in \mathbb{R}^3$ such that

$$A_1 \Phi \cdot e_1 = A_2 \Phi \cdot e_1 = f. \tag{3.18}$$

In view of the arbitrariness of f in (3.18), we can choose Φ such that (3.10) is satisfied. Due to (3.14) and (3.13), we deduce that u_0^i is constant along the plane Π_i perpendicular to η_i , for i = 1, 2. This implies that, thanks to Fubini's theorem, we may integrate along the plane Π_i where an integration by part may be performed. Hence, an integration by parts in (3.17) combined with (3.10), yields for any $\varphi \in C_c^{\infty}(\Omega \times \mathbb{R}^3)$,

$$\int_{\Omega \times \partial Z} \left[u_0^1(x, y) - u_0^2(x, y) \right] \varphi(x, y) dx d\mathcal{H}_y = 0,$$

which implies that

$$u_0^1(x,\cdot) = u_0^2(x,\cdot) \qquad \text{on} \quad \partial Z. \tag{3.19}$$

Fix $x \in \Omega$ and recall that $\partial Z = \{y_1 = 0\}$. In view of (3.15), the relation (3.19) reads as

$$\theta^{1}(x, b_{1}y_{2} + c_{1}y_{3}) = \theta^{2}(x, b_{2}y_{2} + c_{2}y_{3}) \quad \text{on} \quad \partial Z,$$
 (3.20)

with $\eta_i = (a_i, b_i, c_i)$ for i = 1, 2. Due to the independence of $\{e_1, \eta_1, \eta_2\}$ in \mathbb{R}^3 , the linear map $(y_2, y_3) \in \mathbb{R}^2 \mapsto (z_1, z_2) \in \mathbb{R}^2$ defined by

$$z_1 := b_1 y_2 + c_1 y_3, \qquad z_2 := b_2 y_2 + c_2 y_3,$$

is a change of variables so that (3.20) becomes

$$\theta^{1}(x, z_{1}) = \theta^{2}(x, z_{2})$$
 a.e. $z_{1}, z_{2} \in \mathbb{R}$.

This implies that θ^1 and θ^2 depend only on x and thus u_0^1 and u_0^2 agree with some function $u \in L^2(\Omega)$. Finally, we conclude that $u_0(x,y) = \chi(y_1)u_0^1(x,y) + (1-\chi(y_1))u_0^2(x,y)$ is independent of y and hence (H1) is satisfied.

It remains to prove assumption (H2). To this end, let E be the subset of $\mathbb{R}^3 \times \mathbb{R}^3$ defined by

$$E := \{ (\xi_1, \xi_2) \in \mathbb{R}^3 \times \mathbb{R}^3 : (\xi_1 - \xi_2) \cdot e_1 = 0, \ \xi_1 \cdot \eta_1 = 0, \ \xi_2 \cdot \eta_2 = 0 \}.$$
 (3.21)

For $(\xi_1, \xi_2) \in E$, let Φ be the vector-valued function defined by

$$A^{1/2}(y)\Phi(y) := \chi(y_1)\xi_1 + (1 - \chi(y_1))\xi_2 \quad \text{a.e. } y \in \mathbb{R}^3.$$
 (3.22)

The existence of such a vector field Φ is guaranteed by the conditions $\xi_i \cdot \eta_i = 0$, for i = 1, 2, which imply that ξ_i belongs to the range of A_i and hence the right-hand side of (3.22) belongs pointwise to the range of A, or equivalently to the range of $A^{1/2}$. Moreover, since the difference of the phases ξ_1 and ξ_2 is orthogonal to the laminate direction e_1 , $A^{1/2}\Phi$ is a laminate divergence free periodic field in \mathbb{R}^3 . Its average value is given by

$$N := \int_{Y_3} A^{1/2}(y)\Phi(y)dy = \theta \xi_1 + (1 - \theta)\xi_2.$$

Note that E is a linear subspace of $\mathbb{R}^3 \times \mathbb{R}^3$ whose dimension is three. Indeed, let f be the linear map defined by

$$(\xi_1, \xi_2) \in \mathbb{R}^3 \times \mathbb{R}^3 \mapsto ((\xi_1 - \xi_2) \cdot e_1, \ \xi_1 \cdot \eta_1, \ \xi_2 \cdot \eta_2) \in \mathbb{R}^3.$$

If we identify the pair $(\xi_1, \xi_2) \in \mathbb{R}^3 \times \mathbb{R}^3$ with the vector $(x_1, y_1, z_1, x_2, y_2, z_2) \in \mathbb{R}^6$, with $\xi_i = (x_i, y_i, z_i)$, for i = 1, 2, the associated matrix $M_f \in \mathbb{R}^{3 \times 6}$ of f is given by

$$M_f := \begin{pmatrix} 1 & 0 & 0 & -1 & 0 & 0 \\ a_1 & b_1 & c_1 & 0 & 0 & 0 \\ 0 & 0 & 0 & a_2 & b_2 & c_2 \end{pmatrix},$$

with $\eta_i = (a_i, b_i, c_i)$, i = 1, 2. In view of the linear independence of $\{e_1, \eta_1, \eta_2\}$, the rank of M_f is three, which implies that the dimension of kernel Ker(f) is also three. Since the kernel Ker(f) agrees with E, we conclude that the dimension of E is three.

Now, let g be the linear map defined by

$$(\xi_1, \xi_2) \in E \mapsto \theta \xi_1 + (1 - \theta) \xi_2 \in \mathbb{R}^3.$$

Let us show that g is invertible. To this end, consider $(\xi_1, \xi_2) \in \text{Ker}(g)$. From the definition of the map g, Ker(g) consists of all vectors $(\xi_1, \xi_2) \in E$ of the form

$$\left(\xi_1, \ \frac{\theta}{\theta - 1}\xi_1\right). \tag{3.23}$$

In view of the definition of E given by (3.21), the vector (3.23) satisfies the conditions

$$\left(\xi_1 - \frac{\theta}{\theta - 1}\xi_1\right) \cdot e_1 = 0, \quad \xi_1 \cdot \eta_1 = 0, \quad \frac{\theta}{\theta - 1}\xi_1 \cdot \eta_2 = 0.$$

This combined with the linear independence of $\{e_1, \eta_1, \eta_2\}$ implies that

$$\xi_1 \in \{e_1, \eta_1, \eta_2\}^{\perp} = \{0\}.$$

Hence, $Ker(g) = \{(0,0)\}$ which implies along with the fact that the dimension of E is three that g is invertible. This proves that all the vectors of \mathbb{R}^3 can be attained through the map g so that assumption (H2) is satisfied.

Thanks to Proposition 2.2, the homogenized matrix A^* turns out to be positive definite. The proof of the explicit expression of A^* is given in Proposition A.1 in the Appendix.

4 A two-dimensional counter-example

In this section we are going to construct a counter-example of two-dimensional laminates with two degenerate phases, where the lack of assumption (H1) provides an anomalous asymptotic behaviour of the functional $\mathscr{F}_{\varepsilon}$ (1.1).

Let $\Omega := (0,1)^2$ and let e_2 be the laminate direction. We assume that the non-negative and symmetric matrices A_1 and A_2 of $\mathbb{R}^{2\times 2}$ are given by

$$A_1 = e_1 \otimes e_1$$
 and $A_2 = ce_1 \otimes e_1$,

for some positive constant c > 1. The presence of $c \neq 1$ is essential to have oscillation in the conductivity matrix A. In the present case, the matrix-valued conductivity A is given by

$$A(y_2) := \chi(y_2)A_1 + (1 - \chi(y_2))A_2 = a(y_2)e_1 \otimes e_1 \quad \text{for } y_2 \in \mathbb{R}, \tag{4.1}$$

with

$$a(y_2) := \chi(y_2) + c(1 - \chi(y_2)) \ge 1. \tag{4.2}$$

Thus, the energy $\mathscr{F}_{\varepsilon}$, defined by (1.1) with A(y) given by (4.1) and (4.2) becomes

$$\mathscr{F}_{\varepsilon}(u) = \begin{cases} \int_{\Omega} \left[a\left(\frac{x_{2}}{\varepsilon}\right) \left(\frac{\partial u}{\partial x_{1}}\right)^{2} + |u|^{2} \right] dx, & \text{if } u \in H_{0}^{1}((0,1)_{x_{1}}; L^{2}(0,1)_{x_{2}}), \\ \\ \infty, & \text{if } u \in L^{2}(\Omega) \setminus H_{0}^{1}((0,1)_{x_{1}}; L^{2}(0,1)_{x_{2}}). \end{cases}$$

$$(4.3)$$

We denote by $*_1$ the convolution with respect to the variable x_1 , *i.e.* for $f \in L^1(\mathbb{R}^2)$ and $g \in L^2(\mathbb{R}^2)$

$$(f *_1 g)(x_1, x_2) = \int_{\mathbb{D}} f(x_1 - t, x_2) g(t, x_2) dt.$$

Throughout this section, c_{θ} denotes the positive constant given by

$$c_{\theta} := c\theta + 1 - \theta,\tag{4.4}$$

where $\theta \in (0,1)$ is the volume fraction of the phase Z_1 in Y_2 . The following result proves the Γ -convergence of $\mathscr{F}_{\varepsilon}$ for the weak topology of $L^2(\Omega)$ and provides two alternative expressions of the Γ -limit, one of that seems nonlocal due to presence of convolution term (see Remark 4.5 below).

Proposition 4.1. Let $\mathscr{F}_{\varepsilon}$ be the functional defined by (4.3). Then, $\mathscr{F}_{\varepsilon}$ Γ -converges for the weak topology of $L^2(\Omega)$ to the functional defined by

$$\mathscr{F}(u) := \begin{cases} \int_0^1 dx_2 \int_{\mathbb{R}} \frac{1}{\hat{k}_0(\lambda_1)} |\mathcal{F}_2(u)(\lambda_1, x_2)|^2 d\lambda_1, & \text{if } u \in H_0^1((0, 1)_{x_1}; L^2(0, 1)_{x_2}), \\ \\ \infty, & \text{if } u \in L^2(\Omega) \setminus H_0^1((0, 1)_{x_1}; L^2(0, 1)_{x_2}), \end{cases}$$

where $\mathcal{F}_2(u)(\lambda_1,\cdot)$ denotes the Fourier transform on $L^2(\mathbb{R})$ of parameter λ_1 with respect to the variable x_1 of the function $x_1 \mapsto u(x_1,\cdot)$ extended by zero outside (0,1) and

$$\hat{k}_0(\lambda_1) := \int_0^1 \frac{1}{4\pi^2 a(y_2)\lambda_1^2 + 1} dy_2. \tag{4.5}$$

The Γ -limit \mathscr{F} can be also expressed as

$$\mathscr{F}(u) := \begin{cases} \int_{0}^{1} dx_{2} \int_{\mathbb{R}} \left\{ \frac{c}{c_{\theta}} \left(\frac{\partial u}{\partial x_{1}} \right)^{2} (x_{1}, x_{2}) + \left[\sqrt{\alpha} u(x_{1}, x_{2}) + (h *_{1} u)(x_{1}, x_{2}) \right]^{2} \right\} dx_{1}, \\ if \ u \in H_{0}^{1}((0, 1)_{x_{1}}; L^{2}(0, 1)_{x_{2}}), \\ \infty, \qquad if \ u \in L^{2}(\Omega) \setminus H_{0}^{1}((0, 1)_{x_{1}}; L^{2}(0, 1)_{x_{2}}), \end{cases}$$

$$\tag{4.6}$$

where c_{θ} is given by (4.4) and h is a real-valued function in $L^{2}(\mathbb{R})$ defined by means of its Fourier transform \mathcal{F}_{2} on $L^{2}(\mathbb{R})$

$$\mathcal{F}_2(h)(\lambda_1) := \sqrt{\alpha + f(\lambda_1)} - \sqrt{\alpha},\tag{4.7}$$

where α and f are given by

$$\alpha := \frac{c^2\theta + 1 - \theta}{c_\theta^2} > 0, \qquad f(\lambda_1) := \frac{(c - 1)^2\theta(\theta - 1)}{c_\theta^2} \frac{1}{c_\theta 4\pi^2 \lambda_1^2 + 1}.$$
 (4.8)

Moreover, any two-scale limit $u_0(x,y)$ of a sequence u_{ε} with bounded energy $\mathscr{F}_{\varepsilon}$ depends on the variable $y_2 \in Y_1$.

Remark 4.2. From (4.8), we can deduce that

$$\alpha + f(\lambda_1) = \frac{1}{c_{\theta}^2(c_{\theta}4\pi^2\lambda_1^2 + 1)} \left\{ (c^2\theta + 1 - \theta)c_{\theta}4\pi^2\lambda_1^2 + [(c - 1)\theta + 1]^2 \right\} > 0 \qquad \forall \lambda_1 \in \mathbb{R},$$

so that the Fourier transform of h is well-defined.

Proof. We divide the proof into three steps.

Step 1 - Γ -lim inf inequality.

Consider a sequence $\{u_{\varepsilon}\}_{\varepsilon}$ converging weakly in $L^{2}(\Omega)$ to $u \in L^{2}(\Omega)$. Our aim is to prove that

$$\liminf_{\varepsilon \to 0} \mathscr{F}_{\varepsilon}(u_{\varepsilon}) \ge \mathscr{F}(u).$$
(4.9)

If the lower limit is ∞ then (4.9) is trivial. Up to a subsequence, still indexed by ε , we may assume that $\lim \inf \mathscr{F}_{\varepsilon}(u_{\varepsilon})$ is a limit and we may assume henceforth that, for some $0 < C < \infty$,

$$\mathscr{F}_{\varepsilon}(u_{\varepsilon}) \le C.$$
 (4.10)

It follows that the sequence u_{ε} is bounded in $L^2(\Omega)$ and according to [1, Theorem 1.2], a subsequence, still indexed by ε , of that sequence two-scale converges to some $u_0(x,y) \in L^2(\Omega \times Y_2)$. In other words,

$$u_{\varepsilon} \stackrel{}{\rightharpoonup} u_0.$$
 (4.11)

In view of (4.2), we know that $a \ge 1$ so that, thanks to (4.10), for another subsequence (not relabeled) we have

$$\frac{\partial u_{\varepsilon}}{\partial x_1} \stackrel{\text{def}}{=} \sigma_0(x, y) \quad \text{with } \sigma_0 \in L^2(\Omega \times Y_2).$$
 (4.12)

In particular,

$$\varepsilon \frac{\partial u_{\varepsilon}}{\partial x_1} \stackrel{\text{def}}{=} 0. \tag{4.13}$$

Take $\varphi \in C_c^{\infty}(\Omega; C_{per}^{\infty}(Y_2))$. By integration by parts, we obtain

$$\varepsilon \int_{\Omega} \frac{\partial u_{\varepsilon}}{\partial x_{1}} \varphi\left(x, \frac{x}{\varepsilon}\right) dx = -\int_{\Omega} u_{\varepsilon} \left(\varepsilon \frac{\partial \varphi}{\partial x_{1}} \left(x, \frac{x}{\varepsilon}\right) + \frac{\partial \varphi}{\partial y_{1}} \left(x, \frac{x}{\varepsilon}\right)\right) dx.$$

Passing to the limit in both terms with the help of (4.11) and (4.13) leads to

$$0 = -\int_{\Omega \times Y_2} u_0(x, y) \frac{\partial \varphi}{\partial y_1}(x, y) dx dy,$$

which implies that

$$u_0(x,y)$$
 is independent of y_1 . (4.14)

Due to the link between two-scale and weak L^2 -convergences (see [1, Proposition 1.6]), we have

$$u_{\varepsilon} \rightharpoonup u(x) = \int_{Y_1} u_0(x, y_2) dy_2$$
 weakly in $L^2(\Omega)$. (4.15)

Now consider $\varphi \in C^{\infty}(\overline{\Omega}; C^{\infty}_{per}(Y_2))$ such that

$$\frac{\partial \varphi}{\partial y_1}(x, y) = 0. \tag{4.16}$$

Since $u_{\varepsilon} \in H_0^1((0,1)_{x_1}; L^2(0,1)_{x_2})$, an integration by parts leads us to

$$\int_{\Omega} \frac{\partial u_{\varepsilon}}{\partial x_{1}} \varphi(x, y) dx = -\int_{\Omega} u_{\varepsilon} \frac{\partial \varphi}{\partial x_{1}} (x, y) dx.$$

In view of the convergences (4.11) and (4.12) together with (4.14), we can pass to the two-scale limit in the previous expression and we obtain

$$\int_{\Omega \times Y_2} \sigma_0(x, y) \varphi(x, y) dx dy = -\int_{\Omega \times Y_2} u_0(x, y_2) \frac{\partial \varphi}{\partial x_1}(x, y) dx dy. \tag{4.17}$$

Varying $\varphi \in C_c^{\infty}(\Omega; C_{\text{per}}^{\infty}(Y_2))$, the left-hand side of (4.17) is bounded by a constant times $\|\varphi\|_{L^2(\Omega \times [0,1))}$ so that the right-hand side is a linear and continuous form in $\varphi \in L^2(\Omega \times Y_2)$. By the Riesz representation theorem, there exists $g \in L^2(\Omega \times Y_2)$ such that, for any $\varphi \in C_c^{\infty}(\Omega; C_{\text{per}}^{\infty}(Y_2))$,

$$\int_{\Omega \times Y_2} u_0(x, y_2) \frac{\partial \varphi}{\partial x_1}(x, y) dx dy = \int_{\Omega \times Y_2} g(x, y) \varphi(x, y) dx dy,$$

which yields

$$\frac{\partial u_0}{\partial x_1}(x, y_2) \in L^2(\Omega \times Y_1). \tag{4.18}$$

Then, an integration by parts with respect to x_1 of the right-hand side of (4.17) yields, for any $\varphi \in C^{\infty}(\overline{\Omega}; C^{\infty}_{per}(Y_2))$ satisfying (4.16),

$$\begin{split} \int_{\Omega \times Y_2} \sigma_0(x,y) \varphi(x,y) dx dy &= \int_{\Omega \times Y_2} \frac{\partial u_0}{\partial x_1}(x,y_2) \varphi(x,y) dx dy \\ &- \int_0^1 dx_2 \int_{Y_2} \left[u_0(1,x_2,y_2) \varphi(1,x_2,y) - u_0(0,x_2,y_2) \varphi(0,x_2,y) \right] dy. \end{split}$$

Since for any $\varphi \in C_c^{\infty}(\Omega; C_{\text{per}}^{\infty}(Y_2))$ the first two integrals are equal and bounded by a constant times $\|\varphi\|_{L^2(\Omega \times [0,1)}$, we conclude that, for any $\varphi \in C^{\infty}(\overline{\Omega}; C_{\text{per}}^{\infty}(Y_2))$ satisfying (4.16),

$$\int_0^1 dx_2 \int_{Y_2} \left[u_0(1, x_2, y_2) \varphi(1, x_2, y) - u_0(0, x_2, y_2) \varphi(0, x_2, y) \right] dy = 0,$$

which implies that

$$u_0(1, x_2, y_2) = u_0(0, x_2, y_2) = 0$$
 a.e. $(x_2, y_2) \in (0, 1) \times Y_1$.

This combined with (4.18) yields

$$u_0(x_1, x_2, y_2) \in H_0^1((0, 1)_{x_1}; L^2((0, 1)_{x_2} \times Y_1)).$$

Finally, an integration by parts with respect to x_1 of the right-hand side of (4.17) implies that, for any $\varphi \in C^{\infty}(\overline{\Omega}; C^{\infty}_{per}(Y_2))$ satisfying (4.16),

$$\int_{\Omega\times Y_2} \left(\sigma_0(x,y) - \frac{\partial u_0}{\partial x_1}(x,y_2)\right) \varphi(x,y) dx dy = 0.$$

Since the orthogonal of divergence-free functions is the gradients, from the previous equality we deduce that there exists $\tilde{u} \in H^1_{\text{per}}(Y_1; L^2(\Omega \times Y_1))$ such that

$$\sigma_0(x,y) = \frac{\partial u_0}{\partial x_1}(x,y_2) + \frac{\partial \tilde{u}}{\partial y_1}(x,y). \tag{4.19}$$

Let us now show that

$$\liminf_{\varepsilon \to 0} \int_{\Omega} a\left(\frac{x_2}{\varepsilon}\right) \left(\frac{\partial u_{\varepsilon}}{\partial x_1}\right)^2 dx \ge \int_{\Omega \times Y_2} a(y_2) \left(\frac{\partial u_0}{\partial x_1}(x, y_2) + \frac{\partial \tilde{u}}{\partial y_1}(x, y)\right)^2 dx dy. \tag{4.20}$$

To this end, set

$$\sigma_{\varepsilon} := \frac{\partial u_{\varepsilon}}{\partial x_1}.$$

Since $a \in L^{\infty}_{per}(Y_1) \subset L^2_{per}(Y_1)$, there exists a sequence a_k of functions in $C^{\infty}_{per}(Y_1)$ such that

$$||a - a_k||_{L^2(Y_1)} \to 0 \quad \text{as } k \to \infty,$$
 (4.21)

hence, by periodicity, we also have

$$\left\| a\left(\frac{x_2}{\varepsilon}\right) - a_k\left(\frac{x_2}{\varepsilon}\right) \right\|_{L^2(\Omega)} \le C\|a - a_k\|_{L^2(Y_1)},\tag{4.22}$$

for some positive constant C > 0. On the other hand, since σ_0 given by (4.19) is in $L^2(\Omega \times Y_2)$, there exists a sequence ψ_n of functions in $C_c^{\infty}(\Omega; C_{per}^{\infty}(Y_2))$ such that

$$\psi_n(x,y) \to \sigma_0(x,y)$$
 strongly in $L^2(\Omega \times Y_2)$. (4.23)

From the inequality

$$\int_{\Omega} a\left(\frac{x_2}{\varepsilon}\right) \left(\sigma_{\varepsilon} - \psi_n\left(x, \frac{x}{\varepsilon}\right)\right)^2 dx \ge 0,$$

we get

$$\int_{\Omega} a\left(\frac{x_{2}}{\varepsilon}\right) \sigma_{\varepsilon}^{2} dx \geq 2 \int_{\Omega} a\left(\frac{x_{2}}{\varepsilon}\right) \sigma_{\varepsilon} \psi_{n}\left(x, \frac{x}{\varepsilon}\right) dx - \int_{\Omega} a\left(\frac{x_{2}}{\varepsilon}\right) \psi_{n}^{2}\left(x, \frac{x}{\varepsilon}\right) dx
= 2 \int_{\Omega} \left(a\left(\frac{x_{2}}{\varepsilon}\right) - a_{k}\left(\frac{x_{2}}{\varepsilon}\right)\right) \sigma_{\varepsilon} \psi_{n}\left(x, \frac{x}{\varepsilon}\right) dx + 2 \int_{\Omega} a_{k}\left(\frac{x_{2}}{\varepsilon}\right) \sigma_{\varepsilon} \psi_{n}\left(x, \frac{x}{\varepsilon}\right) dx
- \int_{\Omega} a\left(\frac{x_{2}}{\varepsilon}\right) \psi_{n}^{2}\left(x, \frac{x}{\varepsilon}\right) dx.$$
(4.24)

In view of (4.22), the first integral on the right-hand side of (4.24) can be estimated as

$$\left| \int_{\Omega} \left(a \left(\frac{x_2}{\varepsilon} \right) - a_k \left(\frac{x_2}{\varepsilon} \right) \right) \sigma_{\varepsilon} \psi_n \left(x, \frac{x}{\varepsilon} \right) dx \right| \le C \|a - a_k\|_{L^2(Y_1)} \|\psi_n\|_{L^{\infty}(\Omega)} \|\sigma_{\varepsilon}\|_{L^2(\Omega)}$$

$$\le C \|a - a_k\|_{L^2(Y_1)}.$$

Hence, passing to the limit as $\varepsilon \to 0$ in (4.24) with the help of (4.12) leads to

$$\begin{split} \liminf_{\varepsilon \to 0} \int_{\Omega} a \left(\frac{x_2}{\varepsilon} \right) \sigma_{\varepsilon}^2 dx &\geq -C \| a - a_k \|_{L^2(Y_1)} + 2 \lim_{\varepsilon \to 0} \int_{\Omega} a_k \left(\frac{x_2}{\varepsilon} \right) \sigma_{\varepsilon} \psi_n \left(x, \frac{x}{\varepsilon} \right) dx \\ &- \lim_{\varepsilon \to 0} \int_{\Omega} a \left(\frac{x_2}{\varepsilon} \right) \psi_n^2 \left(x, \frac{x}{\varepsilon} \right) dx dy \\ &= 2 \int_{\Omega \times Y_2} a_k(y_2) \sigma_0(x, y) \psi_n(x, y) dx dy - C \| a - a_k \|_{L^2(Y_1)} \\ &- \int_{\Omega \times Y_2} a(y_2) \psi_n^2(x, y) dx dy. \end{split}$$

Thanks to (4.21), we take the limit as $k \to \infty$ in the previous inequality and we obtain

$$\liminf_{\varepsilon \to 0} \int_{\Omega} a\left(\frac{x_2}{\varepsilon}\right) \sigma_{\varepsilon}^2 dx \ge 2 \int_{\Omega \times Y_2} a(y_2) \sigma_0(x, y) \psi_n(x, y) dx dy - \int_{\Omega \times Y_2} a(y_2) \psi_n^2(x, y) dx dy = 0$$

so that in view of (4.23), passing to the limit as $n \to \infty$ leads to

$$\liminf_{\varepsilon \to 0} \int_{\Omega} a\left(\frac{x_2}{\varepsilon}\right) \sigma_{\varepsilon}^2 dx \ge \int_{\Omega \times Y_0} a(y_2) \sigma_0^2(x, y) dx dy.$$

This combined with (4.19) proves (4.20).

By (4.14), we already know that u_0 does not depend on y_1 . In view of the periodicity of \tilde{u} with respect to y_1 , an application of Jensen's inequality leads us to

$$\begin{split} \int_{\Omega\times Y_2} a(y_2) \left(\frac{\partial u_0}{\partial x_1}(x,y_2) + \frac{\partial \tilde{u}}{\partial y_1}(x,y) \right)^2 dx dy \\ &= \int_{\Omega} dx \int_{Y_1} a(y_2) dy_2 \int_{Y_1} \left(\frac{\partial u_0}{\partial x_1}(x,y_2) + \frac{\partial \tilde{u}}{\partial y_1}(x,y) \right)^2 dy_1 \\ &\geq \int_{\Omega} dx \int_{Y_1} a(y_2) dy_2 \left(\int_{Y_1} \left[\frac{\partial u_0}{\partial x_1}(x,y_2) + \frac{\partial \tilde{u}}{\partial y_1}(x,y) \right] dy_1 \right)^2 \\ &= \int_{\Omega} dx \int_{Y_1} a(y_2) \left(\frac{\partial u_0}{\partial x_1} \right)^2 (x,y_2) dy_2. \end{split}$$

This combined with (4.20) implies that

$$\liminf_{\varepsilon \to 0} \int_{\Omega} a\left(\frac{x_2}{\varepsilon}\right) \left(\frac{\partial u_{\varepsilon}}{\partial x_1}\right)^2 dx \ge \int_{\Omega} dx \int_{Y_1} a(y_2) \left(\frac{\partial u_0}{\partial x_1}\right)^2 (x, y_2) dy_2. \tag{4.25}$$

Now, we extend the functions in $L^2(\Omega)$ by zero with respect to x_1 outside (0,1) so that functions in $H^1_0((0,1)_{x_1}; L^2(0,1)_{x_2})$ can be regarded as functions in $H^1(\mathbb{R}_{x_1}; L^2(0,1)_{x_2})$. Due to the weak L^2 -lower semi-continuity of $\|u_{\varepsilon}\|_{L^2(\Omega)}$ along with (4.25), we have

$$\liminf_{\varepsilon \to 0} \mathscr{F}_{\varepsilon}(u_{\varepsilon}) \ge \int_{0}^{1} dx_{2} \int_{Y_{1}} dy_{2} \int_{\mathbb{R}} \left[a(y_{2}) \left(\frac{\partial u_{0}}{\partial x_{1}} \right)^{2} (x_{1}, x_{2}, y_{2}) + |u_{0}|^{2} (x_{1}, x_{2}, y_{2}) \right] dx_{1}.$$
(4.26)

We minimize the right-hand side with respect to $u_0(x_1, x_2, y_2) \in H^1(\mathbb{R}_{x_1}; L^2((0, 1)_{x_2} \times Y_1))$ satisfying (4.15) where the weak limit u of u_{ε} in $L^2(\Omega)$ is fixed. The minimizer, still denoted by u_0 , satisfies the Euler equation

$$\int_0^1 dx_2 \int_{Y_1} dy_2 \int_{\mathbb{R}} \left[a(y_2) \frac{\partial u_0}{\partial x_1}(x_1, x_2, y_2) \frac{\partial v}{\partial x_1}(x_1, x_2, y_2) + u_0(x_1, x_2, y_2) v(x_1, x_2, y_2) \right] dx_1 = 0$$

for any $v(x_1, x_2, y_2) \in H^1(\mathbb{R}_{x_1}; L^2((0, 1)_{x_2} \times Y_1))$ such that $\int_{Y_1} v(x, y_2) dy_2 = 0$. Then, there exists $b(x_1, x_2) \in H^{-1}(\mathbb{R}_{x_1}; L^2(\mathbb{R})_{x_2})$ independent of y_2 such that in distributions sense with respect to the variable x_1 ,

$$-a(y_2)\frac{\partial^2 u_0}{\partial x_1^2}(x_1, x_2, y_2) + u_0(x_1, x_2, y_2) = b(x_1, x_2) \quad \text{in } \mathscr{D}'(\mathbb{R}) \quad \text{a.e. } (x_2, y_2) \in (0, 1) \times Y_1. \tag{4.27}$$

Taking the Fourier transform \mathcal{F}_2 on $L^2(\mathbb{R})$ of parameter λ_1 with respect to the variables x_1 , the equation (4.27) becomes

$$\mathcal{F}_2(u_0)(\lambda_1, x_2, y_2) = \frac{\mathcal{F}_2(b)(\lambda_1, x_2)}{4\pi^2 a(y_2)\lambda_1^2 + 1} \quad \text{a.e. } (\lambda_1, x_2, y_2) \in \mathbb{R} \times (0, 1) \times Y_1. \tag{4.28}$$

Note that (4.28) proves in particular that the two-scale limit u_0 does depend on the variable y_2 , since its Fourier transform with respect to the variable x_1 depends on y_2 through the function $a(y_2)$.

In light of the definition (4.5) of \hat{k}_0 and due to (4.15), integrating (4.28) with respect to $y_2 \in Y_1$ yields

$$\mathcal{F}_2(u)(\lambda_1, x_2) = \hat{k}_0(\lambda_1)\mathcal{F}_2(b)(\lambda_1, x_2)$$
 a.e. $(\lambda_1, x_2) \in \mathbb{R} \times (0, 1)$. (4.29)

By using Plancherel's identity with respect to the variable x_1 in the right-hand side of (4.26) and in view of (4.28) and (4.29), we obtain

$$\lim_{\varepsilon \to 0} \inf \mathscr{F}_{\varepsilon}(u_{\varepsilon}) \ge \int_{0}^{1} dx_{2} \int_{Y_{1}} dy_{2} \int_{\mathbb{R}} (4\pi^{2}a(y_{2})\lambda_{1}^{2} + 1) |\mathcal{F}_{2}(u_{0})(\lambda_{1}, x_{2}, y_{2})|^{2} d\lambda_{1}$$

$$= \int_{0}^{1} dx_{2} \int_{\mathbb{R}} \frac{1}{\hat{k}_{0}(\lambda_{1})} |\mathcal{F}_{2}(u)(\lambda_{1}, x_{2})|^{2} d\lambda_{1},$$

which proves the Γ -lim inf inequality.

Step 2- Γ -lim sup inequality.

For the proof of the Γ -lim sup inequality, we need the following lemma whose proof will be given later

Lemma 4.3. Let $u \in C_c^{\infty}(\Omega)$. For fixed $x_2 \in (0,1)$ and $y_2 \in Y_1$, let $b(\cdot, x_2)$ be the distribution (parameterized by x_2) defined by

$$\mathcal{F}_2(b)(\lambda_1, x_2) := \frac{1}{\hat{k}_0(\lambda_1)} \mathcal{F}_2(u)(\lambda_1, x_2), \tag{4.30}$$

where $u(\cdot, x_2)$ is extended by zero outside (0,1). Let $u_0(\cdot, x_2, y_2)$ be the unique solution to problem

$$\begin{cases}
-a(y_2)\frac{\partial^2 u_0}{\partial x_1^2}(x_1, x_2, y_2) + u_0(x_1, x_2, y_2) = b(x_1, x_2), & x_1 \in (0, 1), \\
u_0(0, x_2, y_2) = u_0(1, x_2, y_2) = 0,
\end{cases}$$
(4.31)

with $a(y_2)$ given by (4.2). Then $b(x_1, x_2)$ is in $C([0, 1]_{x_2}; L^2(0, 1)_{x_1})$ and $u_0(x_1, x_2, y_2)$ is in $C^1([0, 1]^2; L^{\infty}_{per}(Y_1))$.

Let $u \in C_c^{\infty}(\Omega)$. Thanks to Lemma 4.3, there exists a unique solution

$$u_0(x_1, x_2, y_2) \in C^1([0, 1]^2; L_{per}^{\infty}(Y_1))$$
 (4.32)

to the problem (4.31). Taking the Fourier transform \mathcal{F}_2 on $L^2(\mathbb{R})$ of parameter λ_1 with respect to x_1 of the equation in (4.31) and taking into account (4.30), we get

$$\mathcal{F}_2(u_0)(\lambda_1, x_2, y_2) = \frac{\mathcal{F}_2(u)(\lambda_1, x_2)}{(4\pi^2 a(y_2)\lambda_1^2 + 1)\hat{k}_0(\lambda_1)} \quad \text{for} \quad (\lambda_1, x_2, y_2) \in \mathbb{R} \times [0, 1] \times Y_1, \quad (4.33)$$

where $u_0(\cdot, x_2, y_2)$ and $u(\cdot, x_2)$ are extended by zero outside (0, 1). Integrating (4.33) over $y_2 \in Y_1$, we obtain

$$u(x_1, x_2) = \int_{Y_1} u_0(x_1, x_2, y_2) dy_2 \quad \text{for } (x_1, x_2) \in \mathbb{R} \times (0, 1).$$
 (4.34)

Let $\{u_{\varepsilon}\}_{\varepsilon}$ be the sequence in $L^{2}(\Omega)$ defined by

$$u_{\varepsilon}(x_1, x_2) := u_0\left(x_1, x_2, \frac{x_2}{\varepsilon}\right).$$

Recall that rapidly oscillating Y_1 -periodic function u_{ε} weakly converges in $L^2(\Omega)$ to the mean value of u_{ε} over Y_1 . This combined with (4.34) implies that u_{ε} weakly converges in $L^2(\Omega)$ to u. In other words,

$$u_{\varepsilon} \rightharpoonup u$$
 weakly in $L^2(\Omega)$.

Due to (4.32), we can apply [1, Lemma 5.5] so that $u_0(x_1, x_2, y_2)$ and $\frac{\partial u_0}{\partial x_1}$ are an admissible test function for the two-scale convergence. Hence,

$$\lim_{\varepsilon \to 0} \mathscr{F}_{\varepsilon}(u_{\varepsilon}) = \lim_{\varepsilon \to 0} \int_{\Omega} \left[a\left(\frac{x_{2}}{\varepsilon}\right) \left(\frac{\partial u_{0}}{\partial x_{1}}\right)^{2} \left(x_{1}, x_{2}, \frac{x_{2}}{\varepsilon}\right) + \left| u_{0}\left(x_{1}, x_{2}, \frac{x_{2}}{\varepsilon}\right) \right|^{2} \right] dx$$

$$= \int_{\Omega} dx \int_{Y_{1}} \left[a(y_{2}) \left(\frac{\partial u_{0}}{\partial x_{1}}\right)^{2} \left(x_{1}, x_{2}, y_{2}\right) + \left| u_{0}(x_{1}, x_{2}, y_{2}) \right|^{2} \right] dy_{2}$$

$$= \int_{0}^{1} dx_{2} \int_{Y_{1}} dy_{2} \int_{\mathbb{R}} \left[a(y_{2}) \left(\frac{\partial u_{0}}{\partial x_{1}}\right)^{2} \left(x_{1}, x_{2}, y_{2}\right) + \left| u_{0}(x_{1}, x_{2}, y_{2}) \right|^{2} \right] dx_{1}, \quad (4.35)$$

where the function $x_1 \mapsto u_0(x_1, \cdot, \cdot)$ is extended by zero outside (0, 1). In view of the definition (4.5) of \hat{k}_0 and due to (4.33), the Plancherel identity with respect to the variable x_1 and the Fubini theorem yield

$$\begin{split} \int_0^1 dx_2 \int_{Y_1} dy_2 \int_{\mathbb{R}} \left[a(y_2) \left(\frac{\partial u_0}{\partial x_1} \right)^2 (x_1, x_2, y_2) + |u_0(x_1, x_2, y_2)|^2 \right] dx_1 \\ &= \int_0^1 dx_2 \int_{Y_1} dy_2 \int_{\mathbb{R}} (4\pi^2 a(y_2) \lambda_1^2 + 1) |\mathcal{F}_2(u_0)(\lambda_1, x_2, y_2)|^2 d\lambda_1 \\ &= \int_0^1 dx_2 \int_{\mathbb{R}} \frac{1}{\hat{k}_0(\lambda_1)} |\mathcal{F}_2(u)(\lambda_1, x_2)|^2 d\lambda_1. \end{split}$$

This together with (4.35) implies that, for $u \in C_c^{\infty}(\Omega)$,

$$\lim_{\varepsilon \to 0} \mathscr{F}_{\varepsilon}(u_{\varepsilon}) = \int_{0}^{1} dx_{2} \int_{\mathbb{R}} \frac{1}{\hat{k}_{0}(\lambda_{1})} |\mathcal{F}_{2}(u)(\lambda_{1}, x_{2})|^{2} d\lambda_{1},$$

which proves the Γ -lim sup inequality on $C_{\rm c}^{\infty}(\Omega)$.

Now, let us extend the previous result to any $u \in H_0^1((0,1)_{x_1}; L^2(0,1)_{x_2})$. To this end, we use a density argument (see e.g. [5, Remark 2.8]). Recall that the weak topology of $L^2(\Omega)$ is metrizable on the closed balls of $L^2(\Omega)$. Fix $n \in \mathbb{N}$ and denote d_{B_n} any metric inducing the $L^2(\Omega)$ -weak topology on the ball B_n centered on 0 and of radius n. Then, $H_0^1((0,1)_{x_1}; L^2(0,1)_{x_2})$ can be regarded as a subspace of $L^2(\Omega)$ endowed with the metric d_{B_n} . On the other hand, $H_0^1((0,1)_{x_1}; L^2(0,1)_{x_2})$ is a Hilbert space endowed with the norm

$$||u||_{H_0^1((0,1)_{x_1};L^2(0,1)_{x_2})} := \left(\left\| \frac{\partial u}{\partial x_1} \right\|_{L^2(\Omega)}^2 + ||u||_{L^2(\Omega)}^2 \right)^{1/2}.$$

The associated metric $d_{H_0^1}$ on $H_0^1((0,1)_{x_1}; L^2(0,1)_{x_2})$ induces a topology which is not weaker than that induced by d_{B_n} , *i.e.*

$$d_{H_0^1}(u_k, u) \to 0$$
 implies $d_{B_n}(u_k, u) \to 0.$ (4.36)

Recall that $C_c^{\infty}(\Omega)$ is a dense subspace of $H_0^1((0,1)_{x_1}; L^2(0,1)_{x_2})$ for the metric $d_{H_0^1}$ and that the Γ -lim sup inequality holds on $C_c^{\infty}(\Omega)$ for the $L^2(\Omega)$ -weak topology, *i.e.* for any $u \in C_c^{\infty}(\Omega)$,

$$\Gamma$$
- $\limsup_{\varepsilon \to 0} \mathscr{F}_{\varepsilon}(u) \le \mathscr{F}(u).$ (4.37)

A direct computation of \hat{k}_0 , given by (4.5), shows that

$$\hat{k}_0(\lambda_1) = \frac{c_\theta 4\pi^2 \lambda_1^2 + 1}{(4\pi^2 \lambda_1^2 + 1)(c4\pi^2 \lambda_1^2 + 1)},$$

which implies that

$$\frac{1}{\hat{k}_0(\lambda_1)} = \frac{c}{c_\theta} 4\pi^2 \lambda_1^2 + f(\lambda_1) + \alpha, \tag{4.38}$$

where $f(\lambda_1)$ and α are given by (4.8). Hence, there exists a positive constant C such that

$$\frac{1}{\hat{k}_0(\lambda_1)} \le C(4\pi^2\lambda_1^2 + 1). \tag{4.39}$$

This combined with the Plancherel identity yields

$$\mathscr{F}(u) \leq C \int_{0}^{1} dx_{2} \int_{\mathbb{R}} (4\pi^{2}\lambda_{1}^{2} + 1) |\mathcal{F}_{2}(u)(\lambda_{1}, x_{2})|^{2} d\lambda_{1}$$

$$= C \int_{0}^{1} dx_{2} \int_{\mathbb{R}} \left[\left(\frac{\partial u}{\partial x_{1}} \right)^{2} (x_{1}, x_{2}) + |u(x_{1}, x_{2})|^{2} \right] dx_{1}$$

$$= C \|u\|_{H_{0}^{1}((0, 1)_{x_{1}}; L^{2}(0, 1)_{x_{2}})}^{2}, \tag{4.40}$$

where $u(\cdot, x_2)$ is extended by zero outside (0,1). Since \mathscr{F} is a non-negative quadratic form, from (4.40) we conclude that \mathscr{F} is continuous with respect to the metric $d_{H_0^1}$.

Now, take $u \in H_0^1((0,1)_{x_1}; L^2(0,1)_{x_2})$. By density, there exists a sequence u_k in $C_c^{\infty}(\Omega)$ such that

$$d_{H_0^1}(u_k, u) \to 0$$
 as $k \to \infty$. (4.41)

In particular, due to (4.36), we also have that $d_{B_n}(u_k, u) \to 0$ as $k \to \infty$. In view of the weakly lower semi-continuity of Γ -lim sup and the continuity of \mathscr{F} , we deduce from (4.37) that

$$\begin{split} \Gamma\text{-}\limsup_{\varepsilon\to 0}\mathscr{F}_\varepsilon(u) &\leq \liminf_{k\to \infty} (\Gamma\text{-}\limsup_{\varepsilon\to 0}\mathscr{F}_\varepsilon(u_k)) \\ &\leq \liminf_{k\to \infty}\mathscr{F}(u_k) \\ &= \mathscr{F}(u), \end{split}$$

which proves the Γ -lim sup inequality in B_n . Since for any $u \in H_0^1((0,1)_{x_1}; L^2(0,1)_{x_2})$ the sequence u_k of functions in $C_c^{\infty}(\Omega)$ satisfying (4.41) belongs to some ball B_n of $L^2(\Omega)$, as well as its limit, the Γ -lim sup property holds true for the sequence $\mathscr{F}_{\varepsilon}$ on $H_0^1((0,1)_{x_1}; L^2(0,1)_{x_2})$, which concludes the proof of Γ -lim sup inequality.

Step 3 - Alternative expression of Γ -limit.

The proof of the equality between the two expressions of the Γ -limit \mathscr{F} relies on the following lemma whose proof will be given later.

Lemma 4.4. Let
$$h \in L^2(\mathbb{R})$$
 and $u \in L^1(\mathbb{R}) \cap L^2(\mathbb{R})$. Then, $h * u \in L^2(\mathbb{R})$ and
$$\mathcal{F}_2(h * u) = \mathcal{F}_2(h)\mathcal{F}_2(u) \quad a.e. \text{ in } \mathbb{R}. \tag{4.42}$$

By applying Plancherel's identity with respect to x_1 , for any $u \in H_0^1(\mathbb{R}_{x_1}; L^2(0,1)_{x_2})$ extended by zero with respect to the variable x_1 outside (0,1), we get

$$\int_{\mathbb{R}} \left| \sqrt{\alpha} u(x_1, x_2) + (h *_1 u)(x_1, x_2) \right|^2 dx_1$$

$$= \int_{\mathbb{R}} \left| \sqrt{\alpha} \mathcal{F}_2(u)(\lambda_1, x_2) + \mathcal{F}_2(h *_1 u)(\lambda_1, x_2) \right|^2 d\lambda_1$$

$$= \int_{\mathbb{R}} \left[\alpha \left| \mathcal{F}_2(u)(\lambda_1, x_2) \right|^2 + 2\sqrt{\alpha} \operatorname{Re} \left(\mathcal{F}_2(u)(\lambda_1, x_2) \overline{\mathcal{F}_2(h *_1 u)}(\lambda_1, x_2) \right) + \left| \mathcal{F}_2(h *_1 u)(\lambda_1, x_2) \right|^2 \right] d\lambda_1.$$
(4.43)

Recall that the Fourier transform of h, given by (4.7), is real. From (4.43), an application of Lemma 4.4 leads us to

$$\int_{\mathbb{R}} \left[\alpha \left| \mathcal{F}_{2}(u)(\lambda_{1}, x_{2}) \right|^{2} + 2\sqrt{\alpha} \operatorname{Re} \left(\mathcal{F}_{2}(u)(\lambda_{1}, x_{2}) \overline{\mathcal{F}_{2}(h *_{1} u)}(\lambda_{1}, x_{2}) \right) + \left| \mathcal{F}_{2}(h *_{1} u)(\lambda_{1}, x_{2}) \right|^{2} \right] d\lambda_{1}$$

$$= \int_{\mathbb{R}} \left[\alpha + 2\sqrt{\alpha} \mathcal{F}_{2}(h)(\lambda_{1}) + \left(\mathcal{F}_{2}(h)(\lambda_{1}) \right)^{2} \right] \left| \mathcal{F}_{2}(u)(\lambda_{1}, x_{2}) \right|^{2} d\lambda_{1}$$

$$= \int_{\mathbb{R}} \left[\sqrt{\alpha} + \mathcal{F}_{2}(h)(\lambda_{1}) \right]^{2} \left| \mathcal{F}_{2}(u)(\lambda_{1}, x_{2}) \right|^{2} d\lambda_{1}$$

$$= \int_{\mathbb{R}} \left[\alpha + f(\lambda_{1}) \right] \left| \mathcal{F}_{2}(u)(\lambda_{1}, x_{2}) \right|^{2} d\lambda_{1}.$$
(4.44)

On the other hand, by applying Plancherel's identity with respect to x_1 , we obtain

$$\int_{\mathbb{R}} \frac{c}{c_{\theta}} 4\pi^2 \lambda_1^2 |\mathcal{F}_2(u)(\lambda_1, x_2)|^2 d\lambda_1 = \int_{\mathbb{R}} \frac{c}{c_{\theta}} \left(\frac{\partial u}{\partial x_1}\right)^2 (x_1, x_2) dx_1.$$

In view of the expansion of $1/\hat{k}_0(\lambda_1)$ given by (4.38), the previous equality combined with (4.43) and (4.44) implies that, for $u \in H_0^1((0,1)_{x_1}; L^2(0,1)_{x_2})$ extended by zero with respect to x_1 outside (0,1),

$$\int_{0}^{1} dx_{2} \int_{\mathbb{R}} \frac{1}{\hat{k}_{0}(\lambda_{1})} |\mathcal{F}_{2}(u)(\lambda_{1}, x_{2})|^{2} d\lambda_{1}$$

$$= \int_{0}^{1} dx_{2} \int_{\mathbb{R}} \left\{ \frac{c}{c_{\theta}} \left(\frac{\partial u}{\partial x_{1}} \right)^{2} (x_{1}, x_{2}) + \left[\sqrt{\alpha} u(x_{1}, x_{2}) + (h *_{1} u)(x_{1}, x_{2}) \right]^{2} \right\} dx_{1},$$

which concludes the proof.

Proof of Lemma 4.3. In view of (4.38), the equality (4.30) becomes

$$\mathcal{F}_{2}(b)(\lambda_{1}, x_{2}) = \left(\frac{c}{c_{\theta}} 4\pi^{2} \lambda_{1}^{2} + \alpha + f(\lambda_{1})\right) \mathcal{F}_{2}(u)(\lambda_{1}, x_{2})$$

$$= \mathcal{F}_{2}\left(-\frac{c}{c_{\theta}} \frac{\partial^{2} u}{\partial x_{1}^{2}} + \alpha u\right) (\lambda_{1}, x_{2}) + f(\lambda_{1}) \mathcal{F}_{2}(u)(\lambda_{1}, x_{2}). \tag{4.45}$$

Since

$$f(\lambda_1) = \frac{(c-1)^2 \theta(\theta-1)}{c_{\theta}^2} \frac{1}{c_{\theta} 4\pi^2 \lambda_1^2 + 1} = O(\lambda_1^{-2}) \in C_0(\mathbb{R}) \cap L^1(\mathbb{R}),$$

the right-hand side of (4.45) belongs to $L^2(\mathbb{R})$ with respect to λ_1 , which implies that

$$\mathcal{F}_2(b)(\cdot,x_2)\in L^2(\mathbb{R}).$$

Applying the Plancherel identity, we obtain that $b(\cdot, x_2) \in L^2(\mathbb{R})$ with respect to x_1 . Since $u(\cdot, x_2)$ is extended by zero outside (0, 1), $b(\cdot, x_2)$ is also equal to zero outside (0, 1) so that

$$b(\cdot, x_2) \in L^2(0, 1). \tag{4.46}$$

Let us show that $b(x_1, \cdot)$ is a continuous function with respect to $x_2 \in [0, 1]$. Recall that the continuity of $x_2 \in [0, 1] \mapsto b(x_1, x_2) \in L^2(0, 1)_{x_1}$ is equivalent to

$$\lim_{t \to 0} ||b(\cdot, x_2 + t) - b(\cdot, x_2)||_{L^2(0,1)_{x_1}} = 0.$$

Thanks to Plancherel's identity, we infer from (4.30) that

$$\begin{aligned} \|b(\cdot, x_2 + t) - b(\cdot, x_2)\|_{L^2(0, 1)_{x_1}}^2 &= \|\mathcal{F}_2(b)(\cdot, x_2 + t) - \mathcal{F}_2(b)(\cdot, x_2)\|_{L^2(\mathbb{R})_{\lambda_1}}^2 \\ &= \int_{\mathbb{R}} \left| \frac{1}{\hat{k}_0(\lambda_1)} \left[\mathcal{F}_2(u)(\lambda_1, x_2 + t) - \mathcal{F}_2(u)(\lambda_1, x_2) \right] \right|^2 d\lambda_1. \end{aligned}$$

In view of (4.39) and thanks to the Plancherel identity, we obtain

$$||b(\cdot, x_{2} + t) - b(\cdot, x_{2})||_{L^{2}(0,1)_{x_{1}}}^{2} \leq C^{2} \int_{\mathbb{R}} \left| (4\pi^{2}\lambda_{1}^{2} + 1)(\mathcal{F}_{2}(u)(\lambda_{1}, x_{2} + t) - \mathcal{F}_{2}(u)(\lambda_{1}, x_{2})) \right|^{2} d\lambda_{1}$$

$$\leq C^{2} \left\| \mathcal{F}_{2} \left(\frac{\partial u}{\partial x_{1}} \right) (\cdot, x_{2} + t) - \mathcal{F}_{2} \left(\frac{\partial u}{\partial x_{1}} \right) (\cdot, x_{2}) \right\|_{L^{2}(0,1)_{\lambda_{1}}}^{2}$$

$$+ C^{2} \|\mathcal{F}_{2}(u)(\cdot, x_{2} + t) - \mathcal{F}_{2}(u)(\cdot, x_{2}) \|_{L^{2}(0,1)_{x_{1}}}^{2}$$

$$= C^{2} \left\| \frac{\partial u}{\partial x_{1}} (\cdot, x_{2} + t) - \frac{\partial u}{\partial x_{1}} (\cdot, x_{2}) \right\|_{L^{2}(0,1)_{x_{1}}}^{2}$$

$$+ C^{2} \|u(\cdot, x_{2} + t) - u(\cdot, x_{2}) \|_{L^{2}(0,1)_{x_{1}}}^{2}.$$

By the Lebesgue dominated convergence theorem and since $u \in C_c^{\infty}([0,1]^2)$, from the previous inequality we conclude that the map $x_2 \in [0,1] \mapsto b(x_1,x_2) \in L^2(0,1)_{x_1}$ is continuous. Hence,

$$b(x_1, x_2) \in C([0, 1]_{x_2}; L^2(0, 1)_{x_1}).$$
 (4.47)

To conclude the proof, it remains to show the regularity of u_0 . Note that (4.31) is a Sturm-Liouville problem with constant coefficient with respect to x_1 , since $x_2 \in (0,1)$ and $y_2 \in Y_1$ play the role of parameters. By (4.46), we already know that $b(\cdot, x_2) \in L^2(0,1)$, so that thanks to a classical regularity result (see e.g. [7] pp. 223-224), the problem (4.31) admits a unique solution $u_0(\cdot, x_2, y_2)$ in $H^2(0,1)$. Since $H^2(0,1)$ is embedding into $C^1([0,1])$, we have

$$u_0(\cdot, x_2, y_2) \in C^1([0, 1])$$
 a.e. $(x_2, y_2) \in (0, 1) \times Y_1$.

On the other hand, the solution $u_0(x_1, x_2, y_2)$ to the Sturm-Liouville problem (4.31) is explicitly given by

$$u_0(x_1, x_2, y_2) := \int_0^1 G_{y_2}(x_1, s)b(s, x_2)ds, \tag{4.48}$$

where $b(x_1, x_2)$ is defined by (4.30) and (4.47) and the kernel $G_{y_2}(x_1, s)$ is given by

$$G_{y_2}(x_1,s) := \frac{1}{\sqrt{a(y_2)}\sinh\left(\frac{1}{\sqrt{a(y_2)}}\right)}\sinh\left(\frac{x_1 \wedge s}{\sqrt{a(y_2)}}\right)\sinh\left(\frac{1 - x_1 \vee s}{\sqrt{a(y_2)}}\right).$$

This combined with (4.47) and (4.48) proves that

$$u_0(x_1, x_2, y_2) \in C^1([0, 1]^2, L_{per}^{\infty}(Y_1)),$$

which concludes the proof.

We prove now the Lemma 4.4 that we used in Step 3 of Proposition 4.1.

Proof of Lemma 4.4. By the convolution property of the Fourier transform on $L^2(\mathbb{R})$, we have

$$h * u = \overline{\mathcal{F}_2}(\mathcal{F}_2(h)) * \overline{\mathcal{F}_2}(\mathcal{F}_2(h)) = \overline{\mathcal{F}_1}(\mathcal{F}_2(h)\mathcal{F}_2(u)), \tag{4.49}$$

where $\overline{\mathcal{F}_i}$ denotes the conjugate Fourier transform for i=1,2. On the other hand, since $u \in L^1(\mathbb{R}) \cap L^2(\mathbb{R})$ and due to Riemann-Lebesgue's lemma, we deduce that $\mathcal{F}_2(u) = \mathcal{F}_1(u) \in C_0(\mathbb{R}) \cap L^2(\mathbb{R})$. This combined with $\mathcal{F}_2(h) \in L^2(\mathbb{R})$ implies that

$$\mathcal{F}_2(h)\mathcal{F}_2(u) = \mathcal{F}_2(h)\mathcal{F}_1(u) \in L^2(\mathbb{R}) \cap L^1(\mathbb{R}).$$

Since $\overline{\mathcal{F}_1} = \overline{\mathcal{F}_2}$ on $L^1(\mathbb{R}) \cap L^2(\mathbb{R})$, from (4.49) we deduce that

$$h * u = \overline{\mathcal{F}_2}(\mathcal{F}_2(h)\mathcal{F}_2(u)) \in L^2(\mathbb{R}),$$

which yields (4.42). This concludes the proof.

Remark 4.5. Thanks to the Beurling-Deny theory of Dirichlet forms [3], Mosco [15, Theorem 4.1.2] has proved that the Γ -limit F of a family of Markovian form for the $L^2(\Omega)$ -strong topology is a Dirichlet form which can be split into a sum of three forms: a strongly local form F_d , a local form and nonlocal one. More precisely, for $u \in L^2(\Omega)$ with $F(u) < \infty$, we have

$$F(u) = F_d(u) + \int_{\Omega} u^2 k(dx) + \int_{(\Omega \times \Omega) \setminus \text{diag}} (u(x) - u(y))^2 j(dx, dy), \tag{4.50}$$

where F_d is called the diffusion part of F, k is a positive Radon measure on Ω , called the killing measure, and j is a positive Radon measure on $(\Omega \times \Omega) \setminus \text{diag}$, called the jumping measure. Recall that a Dirichlet form F is a closed form which satisfies the Markovian property, i.e. for any contraction $T: \mathbb{R} \to \mathbb{R}$, such that

$$T(0) = 0,$$
 and $\forall x, y \in \mathbb{R}, |T(x) - T(y)| \le |x - y|,$

we have $F \circ T \leq F$. A Γ -limit form obtained with the $L^2(\Omega)$ -weak topology does not a priori satisfy the Markovian property, since the $L^2(\Omega)$ -weak convergence does not commute with all contractions T. An example of a sequence of Markovian forms whose Γ -limit for the $L^2(\Omega)$ -weak topology does not satisfy the Markovian property is provided in [9, Theorem 3.1]. Hence, the representation formula (4.50) does not hold in general when the $L^2(\Omega)$ -strong topology is replaced by the $L^2(\Omega)$ -weak topology.

In the present context, we do not know if the Γ -limit \mathscr{F} (4.6) is a Dirichlet form since the presence of the convolution term makes difficult to prove the Markovian property.

A Homogenized formula for a rank-one laminate

We are going to give an explicit expression of the homogenized matrix A^* defined by (1.7), which extends the rank-one laminate formula in the case of a rank-one laminates with degenerate phases. We will recover directly from this expression the positive definiteness of A^* for the class of rank-one laminates introduced in Section 3. Indeed, by virtue of Theorem 2.1 the positive definiteness of A^* also follows from assumption (H2) which is established in Proposition 3.1 and Proposition 3.2.

Set

$$a := (1 - \theta)A_1e_1 \cdot e_1 + \theta A_2e_1 \cdot e_1, \tag{A.1}$$

with $\theta \in (0,1)$ being the volume fraction of phase Z_1 .

Proposition A.1. Let A_1 and A_2 be two symmetric and non-negative matrices of $\mathbb{R}^{d \times d}$, $d \geq 2$. If a given by (A.1) is positive, the homogenized matrix A^* is given by

$$A^* = \theta A_1 + (1 - \theta)A_2 - \frac{\theta(1 - \theta)}{a}(A_2 - A_1)e_1 \otimes (A_2 - A_1)e_1.$$
 (A.2)

If a = 0, the homogenized matrix A^* is the arithmetic average of the matrices A_1 and A_2 , i.e.

$$A^* = \theta A_1 + (1 - \theta) A_2. \tag{A.3}$$

Furthermore, if one of the following conditions is satisfied:

- i) in two dimensions, a > 0 and the matrices A_1 and A_2 are given by (3.2) with $\xi \cdot e_1 \neq 0$,
- ii) in three dimensions, a > 0, the matrices A_1 and A_2 are given by (3.13) and the vectors $\{e_1, \eta_1, \eta_2\}$ are independent in \mathbb{R}^3 ,

then A^* is positive definite.

Remark A.2. The condition a > 0 agrees with the Γ -convergence results of Propositions 3.1 and 3.2. In the two-dimensional framework, the degenerate case a = 0 does not agree with Propositions 3.1. Indeed, a = 0 implies that $A_1e_1 \cdot e_1 = A_2e_1 \cdot e_1 = 0$ in contradiction to positive definiteness of A_2 . Similar in the three-dimensional setting, where the independence of $\{e_1, \eta_1, \eta_2\}$ is not compatible with a = 0. Indeed, a = 0 implies that $A_ie_1 = A_i\eta_i = 0$, for i = 1, 2, which contradicts the fact that A_1 and A_2 have rank two.

Proof. Assume that a > 0. In view of the convergence (2.16), we already know that

$$\lim_{\delta \to 0} A_{\delta}^* = A^*, \tag{A.4}$$

where, for $\delta > 0$, A_{δ}^* is the homogenized matrix associated to conductivity matrix A_{δ} given by

$$A_{\delta}(y_1) = \chi(y_1)A_1^{\delta} + (1 - \chi(y_1))A_2^{\delta}$$
 for $y_1 \in \mathbb{R}$,

with $A_i^{\delta} = A_i + \delta I_d$. Since A_1 and A_2 are non-negative matrices, A_{δ} is positive definite and thus the homogenized matrix A_{δ}^* is given by the lamination formula (see [17] and also [2, Lemma 1.3.32])

$$A_{\delta}^{*} = \theta A_{1}^{\delta} + (1 - \theta) A_{2}^{\delta} - \frac{\theta (1 - \theta)}{(1 - \theta) A_{1}^{\delta} e_{1} \cdot e_{1} + \theta A_{2}^{\delta} e_{1} \cdot e_{1}} (A_{2}^{\delta} - A_{1}^{\delta}) e_{1} \otimes (A_{2}^{\delta} - A_{1}^{\delta}) e_{1}.$$
 (A.5)

If a > 0, we easily infer from the convergence (A.4) combined with the lamination formula (A.5) the expression (A.2) for A^* .

Let us prove that $A^*x \cdot x \geq 0$ for any $x \in \mathbb{R}^d$. From the Cauchy-Schwarz inequality, we deduce that

$$|(A_2 - A_1)e_1 \cdot x| \le |A_2e_1 \cdot x| + |A_1e_1 \cdot x|$$

$$\le (A_2e_1 \cdot e_1)^{1/2} (A_2x \cdot x)^{1/2} + (A_1e_1 \cdot e_1)^{1/2} (A_1x \cdot x)^{1/2}.$$
(A.6)

This combined with the definition (A.2) of A^* implies that, for any $x \in \mathbb{R}^d$,

$$A^*x \cdot x = \theta(A_1x \cdot x) + (1 - \theta)(A_2x \cdot x) - \theta(1 - \theta)a^{-1} |(A_2 - A_1)e_1 \cdot x|^2$$

$$\geq \theta(A_1x \cdot x) + (1 - \theta)(A_2x \cdot x)$$

$$- \theta(1 - \theta)a^{-1}[(A_2e_1 \cdot e_1)^{1/2}(A_2x \cdot x)^{1/2} + (A_1e_1 \cdot e_1)^{1/2}(A_1x \cdot x)^{1/2}]^2$$

$$= a^{-1}[a\theta(A_1x \cdot x) + a(1 - \theta)(A_2x \cdot x) - \theta(1 - \theta)(A_2e_1 \cdot e_1)(A_2x \cdot x)$$

$$- \theta(1 - \theta)(A_1e_1 \cdot e_1)(A_1x \cdot x) - 2\theta(1 - \theta)(A_2e_1 \cdot e_1)^{1/2}(A_2x \cdot x)^{1/2}(A_1e_1 \cdot e_1)^{1/2}(A_1x \cdot x)^{1/2}].$$
(A.7)

In view of definition (A.1) of a, we have that

$$a\theta(A_1x \cdot x) + a(1-\theta)(A_2x \cdot x) = \theta(1-\theta)(A_1e_1 \cdot e_1)(A_1x \cdot x) + \theta^2(A_2e_1 \cdot e_1)(A_1x \cdot x) + (1-\theta)^2(A_1e_1 \cdot e_1)(A_2x \cdot x) + \theta(1-\theta)(A_2e_1 \cdot e_1)(A_2x \cdot x).$$

Plugging this equality in (A.7), we deduce that

$$A^*x \cdot x \ge a^{-1} [\theta^2 (A_2 e_1 \cdot e_1) (A_1 x \cdot x) + (1 - \theta)^2 (A_1 e_1 \cdot e_1) (A_2 x \cdot x) - 2\theta (1 - \theta) (A_2 e_1 \cdot e_1)^{1/2} (A_1 x \cdot x)^{1/2} (A_1 e_1 \cdot e_1)^{1/2} (A_2 x \cdot x)^{1/2}] = a^{-1} [\theta (A_2 e_1 \cdot e_1)^{1/2} (A_1 x \cdot x)^{1/2} - (1 - \theta) (A_1 e_1 \cdot e_1)^{1/2} (A_2 x \cdot x)^{1/2}]^2 \ge 0,$$
 (A.8)

which proves that A^* is a non-negative definite matrix.

Now, assume a=0. Since A_1 and A_2 are non-negative matrices, the condition a=0 implies $A_1e_1 \cdot e_1 = A_2e_1 \cdot e_1 = 0$ or equivalently $A_1e_1 = A_2e_1 = 0$. Hence,

$$(A_2^{\delta} - A_1^{\delta})e_1 = (A_2 - A_1)e_1 = 0,$$

which implies that the lamination formula (A.5) becomes

$$A_{\delta}^* = \theta A_1^{\delta} + (1 - \theta) A_2^{\delta}.$$

This combined with the convergence (A.4) yields to the expression (A.3) for A^* .

To conclude the proof, it remains to prove the positive definiteness of A^* under the above conditions i) and ii).

Case (i): d = 2, a > 0 and A_1, A_2 given by (3.2).

Assume $A^*x \cdot x = 0$. Then, the inequality (A.8) is an equality, which yields in turn equalities in (A.6). In particular, we have

$$|A_2e_1 \cdot x| = (A_2e_1 \cdot e_1)^{1/2} (A_2x \cdot x)^{1/2} = ||A_2^{1/2}e_1|| ||A_2^{1/2}x||.$$
(A.9)

Recall that the Cauchy-Schwarz inequality is an equality if and only if one of vectors is a scalar multiple of the other. This combined with (A.9) leads to $A_2^{1/2}x = \alpha A_2^{1/2}e_1$ for some $\alpha \in \mathbb{R}$, so that, since A_2 is positive definite or equivalently $A_2^{1/2}$, we have

$$x = \alpha e_1$$
 for some $\alpha \in \mathbb{R}$. (A.10)

From the definition (A.2) of A^* and due to the assumption $\xi \cdot e_1 \neq 0$, we get

$$A^*e_1 \cdot e_1 = \frac{1}{a} (A_2 e_1 \cdot e_1)(\xi \cdot e_1)^2 > 0.$$
(A.11)

Recall that $A^*x \cdot x = 0$. This combined with (A.10) and (A.11) implies that x = 0, which proves that A^* is positive definite.

Case (ii): d = 3, a > 0 and A_1, A_2 given by (3.13).

Assume that $A^*x \cdot x = 0$. As in Case (i), we have equalities in (A.6). In other words,

$$|A_1e_1 \cdot x| = (A_1e_1 \cdot e_1)^{1/2} (A_1x \cdot x)^{1/2}, \tag{A.12}$$

$$|A_2e_1 \cdot x| = (A_2e_1 \cdot e_1)^{1/2} (A_2x \cdot x)^{1/2}.$$
(A.13)

Let $p_i(t)$ be the non-negative polynomials of degree 2 defined by

$$p_i(t) := A_i(x + te_1) \cdot (x + te_1)$$
 for $i = 1, 2$.

In view of (A.12), the discriminant of $p_1(t)$ is zero, so that there exists $t_1 \in \mathbb{R}$ such that

$$p_1(t_1) = A_1(x + t_1e_1) \cdot (x + t_1e_1) = 0. \tag{A.14}$$

Recall that $Ker(A_1) = Span(\eta_1)$. Since A_1 is non-negative matrix, we deduce from (A.14) that $x + t_1e_1$ belongs to $Ker(A_1)$, so that

$$x \in \operatorname{Span}(e_1, \eta_1). \tag{A.15}$$

Similarly, recalling that $Ker(A_2) = Span(\eta_2)$ and using (A.13), we have

$$x \in \operatorname{Span}(e_1, \eta_2). \tag{A.16}$$

Since the vectors $\{e_1, \eta_1, \eta_2\}$ are independent in \mathbb{R}^3 , (A.15) and (A.16) imply that

$$x = \alpha e_1$$
 for some $\alpha \in \mathbb{R}$.

In light of definition (A.2) of A^* , we have

$$A^*e_1 \cdot e_1 = \frac{1}{a}(A_1e_1 \cdot e_1)(A_2e_1 \cdot e_1) > 0,$$

which implies that x = 0, since $A^*x \cdot x = 0$. This establishes that A^* is positive definite and concludes the proof.

Note that when d=2 and a>0 the assumption $\xi \cdot e_1 \neq 0$ is essential to obtain that A^* is positive definite. Otherwise, the homogenized matrix A^* is just non-negative definite as shown by the following counter-example. Let A_1 and A_2 be symmetric and non-negative matrices of $\mathbb{R}^{2\times 2}$ defined by

$$A_1 = e_2 \otimes e_2$$
 and $A_2 = I_2$.

Then, it is easy to check that $a = \theta > 0$ and $A^*e_1 \cdot e_1 = 0$.

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