

GENERATION OF BALANCED VISCOSITY SOLUTIONS TO RATE-INDEPENDENT SYSTEMS VIA VARIATIONAL CONVERGENCE

GIOVANNI A. BONASCHI AND RICCARDA ROSSI

ABSTRACT. In this paper we investigate the origin of the Balanced Viscosity solution concept for rate-independent evolution, in the setting of a finite-dimensional space. Namely, given a family of dissipation potentials $(\Psi_n)_{n \in \mathbb{N}}$ with superlinear growth at infinity and suitably converging to a 1-positively homogeneous potential Ψ_0 , and a smooth energy functional \mathcal{E} , we provide sufficient conditions on them ensuring that the solutions of the associated *(generalized) gradient systems* (Ψ_n, \mathcal{E}) converge as $n \rightarrow \infty$ to a Balanced Viscosity solution of the *rate-independent system* driven by Ψ_0 and \mathcal{E} . In specific cases, we also obtain results on the reverse approximation of Balanced Viscosity solutions by means of solutions to gradient systems.

Our approach is based on the key observation that solutions to gradient systems/that Balanced Viscosity solutions to rate-independent systems can be characterized as (null-)minimizers of suitable trajectory functionals, for which we indeed prove MOSCO-convergence.

As particular cases, our analysis encompasses both the *vanishing-viscosity* approximation of rate-independent systems from [MRS12, MRS16], and their *stochastic* derivation developed in [BP16].

Key words: Gradient Systems, Rate-Independent Systems, Balanced Viscosity solutions, Vanishing Viscosity, Large Deviations, Variational Convergence.

1. INTRODUCTION

Over the last years, rate-independent systems have been the object of intensive mathematical investigations. This is undoubtedly due to their vast range of applicability. Indeed, this kind of processes seems to be ubiquitous in continuum mechanics, ranging from shape memory alloys to crack propagation, from elastoplasticity to damage and delamination. They also occur in fields such as ferromagnetism and ferroelectricity. We refer to [Mie05, MR15] for a thorough survey of all these problems.

Besides its applicative relevance, though, rate-independent evolution has an own, intrinsic, mathematical interest. This is apparent already in the context of a *finite-dimensional* rate-independent system, to which we shall confine the analysis developed within this paper. In general, such a system is driven by a *dissipation potential* $\Psi_0 : \mathbb{R}^d \rightarrow [0, +\infty)$ (non-degenerate), convex, and positively homogeneous of degree 1, and an *energy functional* $\mathcal{E} : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}$; in particular, throughout the paper, we will consider a smooth energy \mathcal{E} such that the power function $\partial_t \mathcal{E}$ is controlled by \mathcal{E} itself, namely

$$\mathcal{E} \in C^1([0, T] \times \mathbb{R}^d) \quad \text{and} \quad \exists C_1, C_2 > 0 \quad \forall (t, u) \in [0, T] \times \mathbb{R}^d : \quad |\partial_t \mathcal{E}(t, u)| \leq C_1 \mathcal{E}(t, u) + C_2. \quad (\text{E})$$

The pair (Ψ_0, \mathcal{E}) give rise to the simplest example of rate-independent evolution, namely the gradient system

$$\partial \Psi_0(u'(t)) + D\mathcal{E}(t, u(t)) \ni 0 \quad \text{for a.a. } t \in (0, T), \quad (1.1)$$

where $\partial \Psi_0 : \mathbb{R}^d \rightrightarrows \mathbb{R}^d$ is the subdifferential of Ψ_0 in the sense of convex analysis, whereas $D\mathcal{E}$ is the differential of the map $u \mapsto \mathcal{E}(t, u)$. Due to the 0-homogeneity of $\partial \Psi_0$, (1.1) is invariant for time rescalings, i.e. it is rate-independent. Now, it is well known that, even in the case of a *smooth* energy \mathcal{E} , if $u \mapsto \mathcal{E}(t, u)$ fails to be strictly convex, then absolutely continuous solutions to (1.1) need not exist. In the last two decades, this has

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motivated the development of various weak solvability concepts for (1.1) and, in general, for rate-independent systems in infinite-dimensional Banach spaces, or even topological spaces.

While referring to [Mie11] and [MR15] for a survey of all weak notions of rate-independent evolution, in the following lines we shall focus on the concepts of *Energetic* and *Balanced Viscosity* solutions. The study of these notions poses several interesting problems already in the finite-dimensional context and motivates the analysis developed in this paper.

Energetic and Balanced Viscosity solutions to rate-independent systems. The concept of *Energetic solution* was first proposed in [MT99] and fully analyzed in [MT04]; an analogous notion, referred to as *quasistatic evolution*, was in parallel developed within the realm of brittle fracture, cf. [FM98] and [DMT02]. It consists of the *global stability* condition, holding at every $t \in [0, T]$,

$$\mathcal{E}(t, u(t)) \leq \mathcal{E}(t, z) + \Psi_0(z - u(t)) \quad \text{for every } z \in \mathbb{R}^d, \quad (\text{S})$$

and of the (Ψ_0, \mathcal{E}) -*energy-dissipation balance*

$$\mathcal{E}(t, u(t)) + \text{Var}_{\Psi_0}(u; [0, t]) = \mathcal{E}(0, u(0)) + \int_0^t \partial_t \mathcal{E}(s, u(s)) \, ds \quad \text{for every } t \in [0, T]. \quad (\text{E}_{\Psi_0, \mathcal{E}})$$

Indeed, $(\text{E}_{\Psi_0, \mathcal{E}})$ involves the dissipated energy $\text{Var}_{\Psi_0}(u; [0, t])$ (where Var_{Ψ_0} denotes the notion of total variation induced by Ψ_0), the stored energy $\mathcal{E}(t, u(t))$ at the process time t , the initial energy $\mathcal{E}(0, u(0))$, and the work of the external forces. Since the Energetic formulation (S)– $(\text{E}_{\Psi_0, \mathcal{E}})$ only features the (assumedly smooth) power of the external forces $\partial_t \mathcal{E}$, and no other derivatives, it is particularly suited to solutions with discontinuities in time. It is also considerably flexible and can be indeed given for rate-independent processes in general topological spaces, cf. [MM05]. That is why, it has been exploited in a great variety of applicative contexts, ranging from fracture, damage, and delamination to plasticity, shape-memory alloys, ferro-electricity, to name a few; we refer to [MR15] for a comprehensive survey.

Nonetheless, over the years it has become apparent that, in the very case of a *nonconvex* dependence $u \mapsto \mathcal{E}(t, u)$, the *global stability* (S) fails provide a truthful description of the system behaviour at jumps, leading to solutions jumping ‘too early’ and ‘too long’ (i.e. into very far-apart energetic configurations), as shown for instance by the example [Mie03, Ex. 6.1], and by the characterization of Energetic solutions to (one-dimensional) rate-independent systems in [RS13].

This circumstance has led to the introduction of *alternative* weak solvability concepts for (1.1) and its generalizations. In particular, [EM06] first set forth the vanishing-viscosity regularization of the rate-independent system as a selection criterion for mechanically feasible weak solutions. The vanishing-viscosity approach has in fact proved to be a robust method in diverse applications, ranging from plasticity (cf., e.g., [DMDMM08, DDS11, BFM12]), to fracture (cf., e.g., [TZ09, KMZ08, LT11]), and to damage (cf., e.g., [KRZ13, CL16]) models. The solution concept obtained through this approach has been codified under the name of *Balanced Viscosity* solution in [MRS12, MRS16]. We also refer to [Neg14] for an alternative derivation of Balanced Viscosity solutions via time discretization, and to [MN16], where the notion was recovered with the so-called “Epsilon-neighborhood” method.

Let us briefly illustrate the vanishing-viscosity approach: We “augment by viscosity” the dissipation potential Ψ_0 and thus introduce

$$\Psi_\varepsilon(v) := \Psi_0(v) + \frac{\varepsilon}{2} \|v\|^2, \quad (1.2)$$

with $\|\cdot\|$ a second norm on \mathbb{R}^d , which may or may not coincide with the norm associated with Ψ_0 . The corresponding (*generalized*) *gradient system* $(\Psi_\varepsilon, \mathcal{E})$, namely the doubly nonlinear differential inclusion

$$\partial \Psi_\varepsilon(u'(t)) + D\mathcal{E}(t, u(t)) \ni 0 \quad \text{for a.a. } t \in (0, T), \quad (1.3)$$

thus provides an approximation of the rate-independent system (1.1). Since Ψ_ε has superlinear growth at infinity, (1.3) does admit absolutely continuous solutions. It is to be expected that, as the viscosity parameter ε vanishes, solutions $(u_\varepsilon)_\varepsilon$ to (1.3) will converge to a suitable weak solution to the rate-independent system

(1.1). In [MRS12] it was indeed shown that any limit curve $u \in \text{BV}([0, T]; \mathbb{R}^d)$ of the functions $(u_\varepsilon)_\varepsilon$ complies with the stability condition

$$-D\mathcal{E}(t, u(t)) \in K^* := \partial\Psi_0(0) \quad \text{for a.a. } t \in (0, T), \quad (\text{S}_{\text{loc}})$$

and with the energy-dissipation balance

$$\text{Var}_{\Psi_0, \mathfrak{p}, \varepsilon}(u; [0, t]) + \mathcal{E}(t, u(t)) = \mathcal{E}(0, u(0)) + \int_0^t \partial_t \mathcal{E}(s, u(s)) \, ds \quad \text{for all } t \in [0, T], \quad (\text{E}_{\Psi_0, \mathfrak{p}, \varepsilon})$$

which individuate the notion of *Balanced Viscosity* solution to the rate-independent system (S). Although (S_{loc}) & $(\text{E}_{\Psi_0, \mathfrak{p}, \varepsilon})$ look similar to (S) & $(\text{E}_{\Psi_0, \varepsilon})$, they are in fact significantly different. First of all, (S_{loc}) is in fact a *local* version of the global stability (S). Secondly, $(\text{E}_{\Psi_0, \mathfrak{p}, \varepsilon})$ shares the same structure with the energy-dissipation balance $(\text{E}_{\Psi_0, \varepsilon})$, but it features a novel type of total variation functional, $\text{Var}_{\Psi_0, \mathfrak{p}, \varepsilon}$. While referring to Section 3 for its precise definition (cf. (3.23) ahead), we may mention here that, in addition to the dissipation potential Ψ_0 , $\text{Var}_{\Psi_0, \mathfrak{p}, \varepsilon}$ involves the *vanishing-viscosity contact potential*

$$\mathfrak{p}(v, \xi) := \inf_{\varepsilon > 0} (\Psi_\varepsilon(v) + \Psi_\varepsilon^*(\xi)) = \Psi_0(v) + \|v\| \min_{\zeta \in K^*} \|\xi - \zeta\|_*, \quad (1.4)$$

which indeed lies at the core of the Balanced Viscosity concept. The second equality in (1.4) ensues from a direct calculation; K^* is the *stable set* from (S_{loc}) and $\|\cdot\|_*$ the dual norm of the “viscosity-related” norm $\|\cdot\|$. As we will see in Sec. 3 with more detail, the functional \mathfrak{p} thus encodes how viscosity, neglected in the vanishing-viscosity limit, pops back into the description of the solution behaviour at jumps, whereas in the continuous (‘sliding’) regime, the system is only governed by the 1-homogeneous dissipation Ψ_0 .

A characterization of Balanced Viscosity solutions, again for one-dimensional systems, has been provided in [RS13], showing that they model jumps more accurately than Energetic solutions. On the other hand, as evident from (1.4), this notion seems to be strongly reminiscent of the vanishing-viscosity approximation (1.3).

It is thus natural to wonder if there are ways, *alternative* to the vanishing-viscosity [MRS12, MRS16] and to the time-discretization [Neg14] (cf. also [MN16]) approaches, to generate Balanced Viscosity solutions. The present paper aims to contribute in this direction.

The stochastic origin of Balanced Viscosity solutions. Recently, this question has been answered affirmatively in [BP16], investigating the role of stochasticity in the origin of rate independence, in the context of *one-dimensional* rate-independent systems (i.e., with (1.1) set in the ambient space \mathbb{R}). The motivation for the analysis carried out in [BP16] stems from the argument that rate independence may arise through the interplay between thermal noise and a rough energy landscape, cf. [Bas59, Bec25, KE75, Oro40]. The approach to rate-independent evolution developed in [BP16] is akin to that in [ADPZ11, ADPZ13], where a connection has been established between the evolution of a class of many-particle systems and Wasserstein gradient flows, through a large-deviations principle. We also refer to [MPR14, LMPR17], where deeper insight has been gained into the principles underlying this connection within the more general context of (generalized) gradient structures; in this mainstream, [BP16] has however been the first paper investigating *rate-independent*, in place of rate-dependent, evolution.

More specifically, [BP16] has focused on a continuous-time Markov jump process $t \mapsto X_t^h$ on a one-dimensional lattice, with lattice spacing $\frac{1}{h}$, $h \in \mathbb{N}$. While referring to Section 2 for more details, we may mention here that this process models the evolution of a Brownian particle in a wiggly energy landscape, involving the energy \mathcal{E} , in the following way. If the particle is at the position x at time t , then it jumps in continuous time to its neighbours $x \pm \frac{1}{h}$ with rates $hr^\pm(x)$, where $r^\pm(x) = \alpha \exp(\mp\beta D\mathcal{E}(t, x))$. Here, α and β are positive parameters, the former characterizing the rate of jumps, and thus the global time scale of the process, and the latter related to noise.

First of all, in [BP16] it was shown that the deterministic limit, in a ‘large-deviations’ sense, as $h \rightarrow \infty$ and for α and β fixed, of this stochastic process solves

$$u'(t) = 2\alpha \sinh(-\beta D\mathcal{E}(t, u(t))) \quad \text{for a.a. } t \in (0, T).$$

Observe that the latter equation is a reformulation of the (generalized) gradient system

$$\partial\Psi_{\alpha,\beta}(u'(t)) + D\mathcal{E}(t, u(t)) \ni 0 \quad \text{for a.a. } t \in (0, T), \quad (1.5)$$

where the convex dissipation potential $\Psi_{\alpha,\beta}$ is such that its Fenchel-Moreau convex conjugate fulfills $\partial\Psi_{\alpha,\beta}^{-1}(\xi) = \partial\Psi_{\alpha,\beta}^*(\xi) = \{D\Psi_{\alpha,\beta}^*(\xi)\} = \{2\alpha \sinh(\beta\xi)\}$. More precisely, in [BP16] it was proved that the process X^h satisfies a *large-deviations principle* (cf. Sec. 2), with rate function given by the functional of trajectories $\tilde{\mathcal{J}}_{\Psi_{\alpha,\beta},\varepsilon} : \text{BV}([0, T]; \mathbb{R}^d) \rightarrow [0, +\infty]$ defined by

$$\tilde{\mathcal{J}}_{\Psi_{\alpha,\beta},\varepsilon}(u) := \beta \left(\int_0^T (\Psi_{\alpha,\beta}(u'(t)) + \Psi_{\alpha,\beta}^*(-D\mathcal{E}(t, u(t)))) dt + \mathcal{E}(T, u(T)) - \mathcal{E}(0, u(0)) - \int_0^T \partial_t \mathcal{E}(t, u(t)) dt \right)$$

if $u \in \text{AC}([0, T]; \mathbb{R}^d)$, and $+\infty$ else. In fact, the null-minimizers of $\tilde{\mathcal{J}}_{\Psi_{\alpha,\beta},\varepsilon}$ are solutions to the gradient system (1.5), as shown in Lemma 3.1 ahead. Let us mention that this kind of argument, relating solutions of evolutionary equations to the (null-)minimization of functionals of entire trajectories, can be traced back to the seminal BRÉZIS-EKELAND-NAYROLES principle [BE76b, BE76a, Nay76], cf. also [Ste08], and the monograph [Gho09] for a comprehensive overview.

Secondly, the *variational* limits of the functionals $\tilde{\mathcal{J}}_{\Psi_{\alpha,\beta},\varepsilon}$ have been addressed in [BP16] under different scalings of the parameters α and β , leading to gradient flow or rate-independent evolution. To illustrate the result in the latter case, here and throughout the paper we will confine the discussion to the following choice of parameters: $\alpha = \alpha_n := \frac{e^{-nA}}{2}$ and $\beta := \beta_n = n$, with $n \in \mathbb{N}$. In this case, the associated dissipation potentials are given by

$$\Psi_n(v) := \Psi_{\alpha_n, \beta_n}(v) = \frac{v}{n} \log \left(\frac{v + \sqrt{v^2 + e^{-2nA}}}{e^{-nA}} \right) - \frac{1}{n} \sqrt{v^2 + e^{-2nA}} + \frac{e^{-nA}}{n}. \quad (1.6)$$

In [BP16, Thm. 4.2] it was proved that that the functionals of trajectories $\mathcal{J}_{\Psi_n, \varepsilon} := \frac{1}{n} \tilde{\mathcal{J}}_{\Psi_n, \varepsilon}$ converge in the sense of MOSCO with respect to the *weak-strict* topology in $\text{BV}([0, T]; \mathbb{R}^d)$, to the functional $\mathcal{J}_{\Psi_0, \mathbf{p}, \varepsilon} : \text{BV}([0, T]; \mathbb{R}^d) \rightarrow [0, +\infty]$ defined by

$$\begin{aligned} \mathcal{J}_{\Psi_0, \mathbf{p}, \varepsilon}(u) := & \text{Var}_{\Psi_0, \mathbf{p}, \varepsilon}(u; [0, T]) + \int_0^T I_{K^*}(-D\mathcal{E}(t, u(t))) dt \\ & + \mathcal{E}(T, u(T)) - \mathcal{E}(0, u(0)) - \int_0^T \partial_t \mathcal{E}(s, u(s)) ds, \end{aligned} \quad (1.7)$$

with $\Psi_0(v) = A|v|$, \mathbf{p} given by (1.4) and the associated total variation functional $\text{Var}_{\Psi_0, \mathbf{p}, \varepsilon}$ defined in (3.23) ahead, and with I_{K^*} denoting the indicator function of the set stable set $K^* = \partial\Psi_0(0) = [-A, A]$. While postponing the precise definition of MOSCO-convergence in $\text{BV}([0, T]; \mathbb{R}^d)$ to (3.17) ahead, let us only mention that $\text{BV}([0, T]; \mathbb{R}^d)$ is the appropriate space for the solutions to rate-independent systems, liable to jump as functions of time.

The Mosco-convergence result in [BP16, Thm. 4.2] establishes a deep connection between the generalized gradient system (1.5) and the one-dimensional rate-independent system driven by $\Psi_0(v) = A|v|$ and \mathcal{E} . In fact, (null-)minimizers of $\mathcal{J}_{\Psi_0, \mathbf{p}, \varepsilon}$ are Balanced Viscosity solutions of the rate-independent system driven by Ψ_0 and \mathcal{E} (cf. Proposition 3.7 ahead). Therefore, on the one hand the Γ -lim inf-estimate verified within Mosco-convergence, joint with the observation that (null-)minimizers of $\mathcal{J}_{\Psi_n, \varepsilon}$, are solutions to the gradient system (1.5), ensures the convergence of the latter to Balanced Viscosity solutions of the rate-independent system. On the other hand, the Γ -lim sup-estimate yields a reverse approximation result.

Therefore, [BP16, Thm. 4.2] ultimately reveals the connection between the jump process X^h and the (one-dimensional) rate-independent system (1.1), understood in a Balanced Viscosity sense. Furthermore, observe that the functionals Ψ_n from (1.6) are not of the form (1.2). Hence, this result provides a way, alternative to the vanishing viscosity approach, to generate Balanced Viscosity solutions.

1.1. **Our results.** Our first motivation for this work was to extend the ‘stochastic generation’ of Balanced Viscosity solutions unraveled in [BP16], to the *multi-dimensional* rate-independent system (1.1), where now

$$\Psi_0(v) := A\|v\|_1 \quad \text{for all } v \in \mathbb{R}^d, \quad \text{with } \|v\|_1 := \sum_{i=1}^d |v_i|. \quad (1.8)$$

The first, obvious difference between the one- and the multi-dimensional contexts is that, even conjecturing that the viscosity contact potential defining the limiting Balanced Viscosity solution notion is of the form (1.4), in this multi-dimensional context it is no longer obvious which choice of the viscous norm $\|\cdot\|$ should enter into (1.4). With **our main results, Theorem 5.2** (lim inf-estimate) and **Thm. 5.9** (lim sup-estimate), we have shown that the multi-dimensional analogues of the functionals $(\mathcal{J}_{\Psi_n, \varepsilon})_n$ MOSCO-converge, with respect to the weak-strict topology of $BV([0, T]; \mathbb{R}^d)$, to the functional $\mathcal{J}_{\Psi_0, \mathbf{p}, \varepsilon}$ featuring the total variation functional associated with the contact potential

$$\mathbf{p}(v, \xi) := \|v\|_1(A \vee \|\xi\|_\infty) \quad \text{with } \|\xi\|_\infty := \max_{i=1, \dots, d} |\xi_i|. \quad (1.9)$$

It can be checked that \mathbf{p} from (1.9) is indeed of the form (1.4). In this case, however, the ‘viscous’ norm $\|\cdot\|$ in fact coincides with that associated with Ψ_0 from (1.8), i.e. $\|v\| = \|v\|_1$. Therefore, the notion of Balanced Viscosity solution arising from the stochastic approximation coincides with the one in which the 1-homogeneous dissipation potential Ψ_0 is perturbed by a (superlinear) function of Ψ_0 itself. Referring to this case, we shall speak of *vanishing Ψ_0 -viscosity*, cf. Example 5.5 ahead.

Our Γ -lim inf **Theorem 5.2** has in fact a broader and deeper scope, and indeed contributes to understanding the origin of rate-independent evolution in a Balanced Viscosity sense. More precisely, in this paper

- (1) We will introduce an ‘extended’ notion of Balanced Viscosity solution, induced by a class of *viscosity contact potential* $\mathbf{p} : [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0 + \infty]$, $\mathbf{p} = \mathbf{p}(\tau, v, \xi)$, cf. Def. 3.2 ahead, in place of the vanishing-viscosity contact potential \mathbf{p} from, e.g., (1.4). We may understand the functional \mathbf{p} as obtained by augmenting \mathbf{p} with the time variable, in that the contact potentials $\mathbf{p}(v, \xi)$ from (1.4), for instance, stem from setting $\tau = 0$ in (specific choices of) \mathbf{p} , i.e. $\mathbf{p}(0, v, \xi) = \mathbf{p}(v, \xi)$.
- (2) We will provide a series of conditions under which a sequence $(\Psi_n)_n$ of *general* dissipation potentials with superlinear growth at infinity, not necessarily of the form (1.2) (vanishing-viscosity) or (1.6) (stochastic approximation), give rise to a viscosity contact potential. Such conditions will amount to requiring that the bipotentials $b_{\Psi_n} : [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0 + \infty]$, associated with the functionals Ψ_n , and defined by

$$b_{\Psi_n}(\tau, v, \xi) := \tau \Psi_n\left(\frac{v}{\tau}\right) + \tau \Psi_n^*(\xi) \quad \text{for } \tau > 0 \quad (1.10)$$

(cf. (4.1) ahead), converge in a suitable *variational sense* to \mathbf{p} , as $n \rightarrow \infty$. As we will see, such conditions are *for instance* verified in the case of the vanishing-viscosity and of the stochastic approximations.

- (3) It will turn out (cf. Theorem 5.2), that under this condition on the bipotentials b_{Ψ_n} , jointly with a suitable uniform coercivity requirement for the functionals $(\Psi_n)_n$, a Γ -lim inf estimate for the associated trajectory functionals $(\mathcal{J}_{\Psi_n, \varepsilon})_n$ holds, with respect to the weak topology in $BV([0, T]; \mathbb{R}^d)$.

Like previously illustrated for the Γ -lim inf result in [BP16], our Thm. 5.2 has the following outcome in terms of evolutionary systems: it implies that limit curves $u \in BV([0, T]; \mathbb{R}^d)$ of sequences of solutions $(u_n)_n$ to the gradient systems (Ψ_n, \mathcal{E}) (where $(\Psi_n)_n$ are dissipation potentials with superlinear growth at infinity that give rise to a viscosity contact potential \mathbf{p} in the aforementioned sense), are Balanced Viscosity solutions to the rate-independent system $(\Psi_0, \mathbf{p}, \mathcal{E})$, cf. **Theorem 5.3** ahead for a precise statement. In other words, we conclude that the gradient systems $(\Psi_n, \mathcal{E})_n$ *Evolutionary Γ -converge* to the rate-independent system $(\Psi_0, \mathbf{p}, \mathcal{E})$, using a terminology recently popularized in [Mie16] (cf. also, e.g., [MRS08, SS04, Ste08, Ser11, Vis13, Bra14] for limit passages in gradient systems driven by Γ -converging energy functionals and dissipation potentials).

The proof of the lim sup-estimate in **Theorem 5.9** focuses on the *specific* cases of the *vanishing-viscosity* and the *stochastic approximations*. It could be generalized in some directions, cf. Remarks 5.10 and 6.2 ahead.

Nonetheless, we have preferred to confine the discussion to the vanishing-viscosity and the stochastic cases, in order to make the calculations more explicit.

Let us however mention that in [BP16] the Γ -lim sup result was obtained in a much larger generality, for a broader class of dissipation potentials Ψ_n that encompass those considered here, with calculations tailored to the one-dimensional context therein. It is not clear to us how to fully extend such calculations in the frame of the approach we have adopted in our multi-dimensional setup, which, differently from [BP16], is based on careful computations involving the bipotentials \mathbf{b}_{Ψ_n} from (1.10). All the more, the proof of the lim sup-estimate in the *fully general* case, i.e. under the sole condition that the bipotentials b_{Ψ_n} from (1.10) variationally converge to \mathbf{p} , remains an open problem.

Still, we believe Thm. 5.9 to be relevant. Again, the key observation is that (null-)minimizers of the involved functionals of trajectories are solutions of the associated evolutionary problems. Hence, Thm. 5.9 yields a *reverse approximation* result, [Theorem 5.12](#) ahead, of Balanced Viscosity solutions of the limiting rate-independent system, by means of solutions of the approximating gradient systems. Such a result (i) extends what was proved in [BP16] to the multi-dimensional case; (ii) is, to our knowledge, new in the case of the vanishing-viscosity approximation.

Plan of the paper. In [Section 2](#) we present the multi-dimensional analogue of the stochastic model considered in [BP16] and (formally) derive the associated dissipation potential Ψ_n and the induced trajectory functional $\mathcal{I}_{\Psi_n, \varepsilon}$.

[Section 3](#) revolves around an *extended* notion of Balanced Viscosity solution to a rate-independent system, based on the concept of viscosity contact potential \mathbf{p} introduced in [Definition 3.2](#). This concept of solution is defined in [Definition 3.5](#); its properties are illustrated thereafter.

In [Section 4](#) we address the generation of a viscosity contact potential \mathbf{p} starting from a family $(\Psi_n)_n$ of dissipation potentials with superlinear growth at infinity, such that the associated bipotentials \mathbf{b}_{Ψ_n} from (1.10) variationally converge to \mathbf{p} .

Our main results, [Theorems 5.2](#) and [5.9](#), along with their consequences [Thms. 5.3](#) and [5.12](#), are stated in [Section 5](#) and proved throughout [Section 6](#).

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2. THE STOCHASTIC ORIGIN OF RATE-INDEPENDENT SYSTEMS

In this section we briefly describe the multi-dimensional extension of the one-dimensional stochastic model for rate-independent evolution considered in [BP16].

We consider a jump process $t \mapsto X^h(t)$ on a d -dimensional lattice, with lattice spacing $\frac{1}{h}$. The evolution of the process can be described as follows: Fix the origin as initial point. If the process is at the position x at time t , then it jumps in continuous time to its neighbours $(x \pm \frac{1}{m} \mathbf{e}_i)$ with rate mr_i^\pm , for $i = 1, \dots, d$, where $(\mathbf{e}_1, \dots, \mathbf{e}_d)$ is the basis of \mathbb{R}^d , cf. [Figure 1](#). The jump rates depend on two parameters α and β , and on the partial derivatives $D_i \mathcal{E} := D_{x_i} \mathcal{E}$ of a smooth energy functional $\mathcal{E} : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}$, namely

$$r_i^+(x, t) = \alpha e^{-\beta D_i \mathcal{E}(x, t)}, \quad r_i^-(x, t) = \alpha e^{\beta D_i \mathcal{E}(x, t)} \quad \text{for } i = 1, \dots, d. \quad (2.1)$$

The choice of the stochastic process (and thus of the jump rates r_i^\pm) reflects Kramers' formula [Kra40, Ber13, BP16]. Given a particle evolving in a wiggly energy landscape with noise, this formula provides an estimate of the rate of jumps from one energy well to the next one.

We are interested in the continuum limit as $h \rightarrow \infty$. With this aim, we apply the method developed by FENG & KURTZ, cf. [FK06], to prove large-deviations principles for Markov processes.

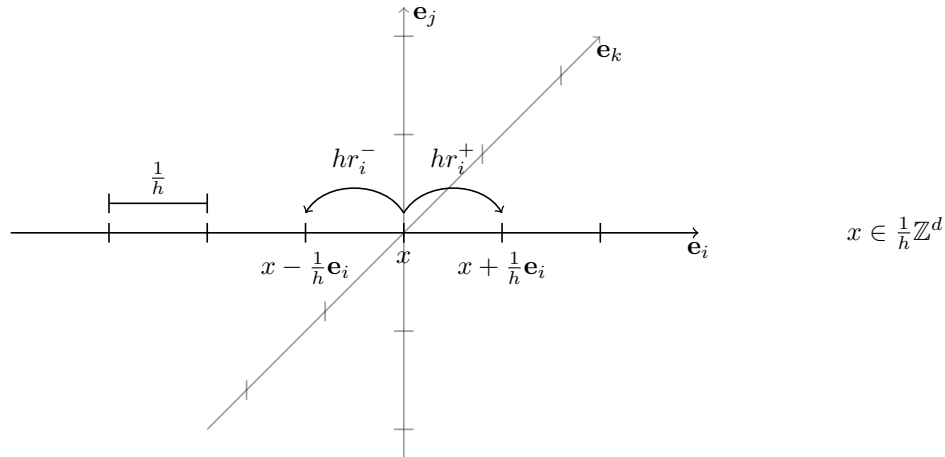


FIGURE 1. A sketch of the jump-process on the lattice.

As in [BP16, Sec. 2.5], we will provisionally assume that the jump rates r^\pm are constant in space and time, and thus derive the expression of the rate function, and then formally substitute (2.1) into it. Following [FK06], we consider the generator

$$\Omega_h f(x) := \sum_{i=1}^d \left[hr_i^+ \left(f\left(x + \frac{1}{h} \mathbf{e}_i\right) - f(x) \right) + hr_i^- \left(f\left(x - \frac{1}{h} \mathbf{e}_i\right) - f(x) \right) \right]$$

of the continuous time Markov process X^h , and the nonlinear generator

$$\begin{aligned} (\mathbf{H}_h f)(x) &:= \frac{1}{h} e^{-hf(x)} (\Omega_h e^{hf})(x) \\ &= \sum_{i=1}^d \left[r_i^+ \left(\exp \left(h \left(f\left(x + \frac{1}{h} \mathbf{e}_i\right) - f(x) \right) \right) - 1 \right) + r_i^- \left(\exp \left(h \left(f\left(x - \frac{1}{h} \mathbf{e}_i\right) - f(x) \right) \right) - 1 \right) \right]. \end{aligned}$$

According to the FENG-KURTZ method, if \mathbf{H}_h converges to some \mathbf{H} in a suitable sense, and if the limiting operator $\mathbf{H}f$ depends locally on Df , we can then define the *Hamiltonian* $H = H(x, \xi)$ through

$$(\mathbf{H}f)(x) =: H(x, Df(x)),$$

and the *Lagrangian* as the Legendre transform of H , namely

$$L(x, v) := \sup_{\xi \in \mathbb{R}^d} (\langle \xi, v \rangle - H(x, \xi)).$$

Then, the Markov process satisfies a large-deviations principle, with rate function

$$\mathcal{I}(u) := \begin{cases} \int_0^T L(u(t), u'(t)) dt & \text{if } u \in \text{AC}([0, T]; \mathbb{R}^d), \\ +\infty & \text{otherwise.} \end{cases} \quad (2.2)$$

We may roughly state this principle in the following form:

$$\text{Prob}(\{X^h \cong x\}) \approx \exp(-h \mathcal{I}(x)) \quad \text{as } h \rightarrow \infty. \quad (2.3)$$

Namely, the probability of finding X^h close to some x is close, in a suitable sense, to $\exp(-h \mathcal{I}(x))$ as $h \rightarrow \infty$; in particular, large values of $\mathcal{I}(x)$ imply small probability. The purposefully vague notations \cong and \approx featuring in (2.3) are made precise in [BP16, Definition 2]. Let us also mention that (2.3) has to be understood as a relation holding in the Skorokhod space $D([0, T])$, namely the space of *cadlag* functions (right continuous and with limit from left). The FENG-KURTZ method applied in [BP16] to prove the large-deviations principle for the one-dimensional stochastic model, extends to the present multi-dimensional setting.

In our context, it can be seen that

$$H(x, \xi) = \sum_{i=1}^d r_i^+(e^{\xi_i} - 1) + r_i^-(e^{-\xi_i} - 1).$$

Then, L is given by

$$L(x, v) = \sum_{i=1}^d \left[v_i \log \left(\frac{v_i + \sqrt{v_i^2 + 4r_i^+ r_i^-}}{2r_i^+} \right) - \sqrt{v_i^2 + 4r_i^+ r_i^-} + r_i^+ + r_i^- \right]. \quad (2.4)$$

Substituting in (2.4) the expression (2.1) for the jump rates, and choosing the parameters

$$\alpha = \frac{e^{-nA}}{2} \quad \text{and} \quad \beta = n, \quad n \in \mathbb{N},$$

we obtain

$$L(x, v) = n (\Psi_n(v) + \Psi_n^*(-D\mathcal{E}(t, x)) - \langle -D\mathcal{E}(t, x), v \rangle), \quad (2.5)$$

where $\langle \cdot, \cdot \rangle$ denotes the inner product in \mathbb{R}^d , and $\Psi_n : \mathbb{R}^d \rightarrow [0, +\infty)$ is given by

$$\Psi_n(v) = \sum_{i=1}^d \psi_n(v_i) = \sum_{i=1}^d \frac{v_i}{n} \log \left(\frac{v_i + \sqrt{v_i^2 + e^{-2nA}}}{e^{-nA}} \right) - \frac{1}{n} \sqrt{v_i^2 + e^{-2nA}} + \frac{e^{-nA}}{n}, \quad (2.6)$$

and Ψ_n^* the Legendre transform of Ψ_n . It can be easily checked that the structure $\Psi_n(v) = \sum_{i=1}^d \psi_n(v_i)$ transfers to the conjugate, hence

$$\Psi_n^*(\xi) = \sum_{i=1}^d \psi_n^*(\xi_i) = \sum_{i=1}^d \frac{e^{-nA}}{n} (\cosh(n\xi_i) - 1). \quad (2.7)$$

In view of Lemma 3.1 ahead, we can see that, with the choice (2.5) for L , the (positive) functional \mathcal{J} from (2.2) is minimized by the solutions of the generalized gradient system

$$D\Psi_n(u'(t)) + D\mathcal{E}(t, u(t)) = 0 \quad \text{for a.a. } t \in (0, T).$$

Taking into account that $D\Psi_n^* = (D\Psi_n)^{-1}$, the latter rewrites as the ODE system

$$u_i'(t) = -D\psi_n^*(-D_i\mathcal{E}(t, u_i(t))) \quad \text{for a.a. } t \in (0, T), \text{ for all } i = 1, \dots, d.$$

3. VISCOSITY CONTACT POTENTIALS AND BALANCED VISCOSITY SOLUTIONS TO RATE-INDEPENDENT SYSTEMS

The central objective of this section is to introduce and illustrate the main properties of the notion of Balanced Viscosity solution to a rate-independent system induced by a general viscosity potential. Therefore, Definition 3.5 ahead shall (slightly) extend the definition given in [MRS12], which was based on the concept of vanishing-viscosity contact potential.

3.1. Preliminaries. Before introducing the notion of *Balanced Viscosity* solution to a rate-independent system and fixing its main properties, we recall some properties of dissipation potentials, and provide some basics of the theory of functions of bounded variation; for a more comprehensive tractation, the reader is referred to, e.g., [AFP05, Mor88].

Dissipation potentials. Hereafter, we will call *dissipation potential* any function

$$\Psi : \mathbb{R}^d \rightarrow [0, +\infty) \text{ convex and such that } \Psi(0) = 0. \quad (3.1)$$

It follows from the above conditions that the Fenchel-Moreau conjugate Ψ^* then fulfills $\Psi^*(0) = 0 \leq \Psi^*(\xi)$ for all $\xi \in \mathbb{R}^d$. We will distinguish two cases:

Dissipation potentials with superlinear growth at infinity: Namely, Ψ fulfills

$$\lim_{\|v\| \rightarrow +\infty} \frac{\Psi(v)}{\|v\|} = +\infty \quad (3.2)$$

for some norm $\|\cdot\|$ on \mathbb{R}^d . For later use, we point out here that, as a consequence of (3.2) one has

$$\lim_{\tau \downarrow 0} \tau \Psi \left(\frac{v}{\tau} \right) = +\infty \quad \text{for all } v \in \mathbb{R}^d \setminus \{0\}. \quad (3.3)$$

1-homogeneous dissipation potentials: In what follows, we will denote by Ψ_0 a dissipation potential

$$\Psi_0 : \mathbb{R}^d \rightarrow [0, +\infty) \text{ convex, 1-positively homogenous, and non-degenerate, viz. } \Psi_0(v) > 0 \text{ if } v \neq 0. \quad (3.4)$$

Thus, for any norm $\|\cdot\|$ on \mathbb{R}^d

$$\exists \eta > 0 \forall v \in \mathbb{R}^d : \eta^{-1} \|v\| \leq \Psi_0(v) \leq \eta \|v\|. \quad (3.5)$$

Its convex-analysis subdifferential $\partial\Psi_0 : \mathbb{R}^d \rightrightarrows \mathbb{R}^d$ at $v \in \mathbb{R}^d$ can be characterized by

$$\zeta \in \partial\Psi_0(v) \Leftrightarrow \begin{cases} \langle \zeta, w \rangle \leq \Psi_0(w) \text{ for all } w \in \mathbb{R}^d, \\ \langle \zeta, v \rangle = \Psi_0(v). \end{cases} \quad (3.6)$$

Throughout, we will use the notation

$$K^* \text{ for the stable set } \partial\Psi_0(0). \quad (3.7)$$

Recall that $\partial\Psi_0(v) \subset K^*$ for all $v \in \mathbb{R}^d$ and that, indeed, Ψ_0 is the *support function* of K^* , namely

$$\Psi_0(v) = \sup_{\zeta \in K^*} \langle \zeta, v \rangle, \quad \text{whence } \Psi_0^*(\xi) = I_{K^*}(\xi). \quad (3.8)$$

We conclude with the following Lemma 3.1, that fixes the observation that, in the case of a dissipation potential Ψ with superlinear growth, the solutions of the generalized gradient system (Ψ, \mathcal{E}) , i.e.

$$\partial\Psi(u'(t)) + D\mathcal{E}(t, u(t)) \ni 0 \quad \text{for a.a. } t \in (0, T), \quad (3.9)$$

can be characterized as the (null-)minimizers of the functional of trajectories $\mathcal{J}_{\Psi, \mathcal{E}} : \text{AC}([0, T]; \mathbb{R}^d) \rightarrow [0, +\infty)$ given by

$$\mathcal{J}_{\Psi, \mathcal{E}}(u) := \int_0^T (\Psi(\dot{u}(s)) + \Psi^*(-D\mathcal{E}(s, u(s)))) \, ds + \mathcal{E}(T, u(T)) - \mathcal{E}(0, u(0)) - \int_0^T \partial_t \mathcal{E}(s, u(s)) \, ds.$$

Lemma 3.1. *Let Ψ have superlinear growth at infinity. Then, a curve $u \in \text{AC}([0, T]; \mathbb{R}^d)$ is a solution to (3.9) if and only if*

$$0 = \mathcal{J}_{\Psi, \mathcal{E}}(u) \leq \mathcal{J}_{\Psi, \mathcal{E}}(v) \quad \text{for all } v \in \text{AC}([0, T]; \mathbb{R}^d).$$

Proof. First of all, the positivity of $\mathcal{J}_{\Psi, \mathcal{E}}$ is due to

$$\begin{aligned} \int_0^T (\Psi(\dot{v}(s)) + \Psi^*(-D\mathcal{E}(s, v(s)))) \, ds &\geq - \int_0^T \langle D\mathcal{E}(s, v(s)), \dot{v}(s) \rangle \, ds \\ &= \mathcal{E}(0, v(0)) - \mathcal{E}(T, v(T)) + \int_0^T \partial_t \mathcal{E}(s, v(s)) \, ds, \end{aligned}$$

where the first inequality follows from the elementary convex analysis inequality $\Psi(v) + \Psi^*(\xi) \geq \langle \xi, v \rangle$, and the last equality by the chain rule. Suppose now that $\mathcal{J}_{\Psi, \varepsilon}(u) = 0$. Then, again using the chain rule we conclude that

$$\int_0^T (\Psi(\dot{u}(s)) + \Psi^*(-D\mathcal{E}(s, u(s))) - \langle -D\mathcal{E}(s, u(s)), \dot{u}(s) \rangle) ds = 0.$$

Since the integrand is positive, we infer that

$$\Psi(\dot{u}(t)) + \Psi^*(-D\mathcal{E}(t, u(t))) - \langle -D\mathcal{E}(t, u(t)), \dot{u}(t) \rangle = 0 \quad \text{for a.a. } t \in (0, T),$$

which ultimately yields, again by convex analysis, that u solves (3.9). The very same arguments yield that a solution u of (3.9) fulfills $\mathcal{J}_{\Psi, \varepsilon}(u) = 0$. \square

BV functions. Throughout, we will work with functions of bounded variation *pointwise defined at every point* $t \in [0, T]$. We recall that a function u in $BV([0, T]; \mathbb{R}^d)$ admits left and right limits at every $t \in [0, T]$:

$$u(t_-) := \lim_{s \uparrow t} u(s), \quad u(t_+) := \lim_{s \downarrow t} u(s), \quad \text{with the convention } u(0_-) := u(0), \quad u(T_+) := u(T), \quad (3.10)$$

and its *pointwise* jump set J_u is the at most countable set defined by

$$J_u := \{t \in [0, T] : u(t_-) \neq u(t) \text{ or } u(t) \neq u(t_+)\} \supset \text{ess-}J_u := \{t \in [0, T] : u(t_-) \neq u(t_+)\}. \quad (3.11)$$

We also recall that the distributional derivative u' of u is a Radon vector measure that can be decomposed (cf. [AFP05]) into the sum of the three mutually singular measures

$$u' = u'_{\mathcal{L}} + u'_C + u'_J, \quad u'_{\mathcal{L}} = \dot{u} \mathcal{L}^1, \quad u'_{\text{co}} := u'_{\mathcal{L}} + u'_C. \quad (3.12)$$

Here, $u'_{\mathcal{L}}$ is the absolutely continuous part with respect to the Lebesgue measure \mathcal{L}^1 , whose Lebesgue density \dot{u} is the pointwise (and \mathcal{L}^1 -a.e. defined) derivative of u , u'_J is a discrete measure concentrated on $\text{ess-}J_u \subset J_u$, and u'_C is the so-called Cantor part. We will use the notation $u'_{\text{co}} := u'_{\mathcal{L}} + u'_C$ for the diffuse part of the measure, which does not charge J_u .

Given a (non-degenerate) 1-homogeneous dissipation potential Ψ_0 , it induces a notion of (pointwise) total variation for a curve $u \in BV([0, T]; \mathbb{R}^d)$ via

$$\text{Var}_{\Psi_0}(u; [a, b]) := \sup \left\{ \sum_{m=1}^M \Psi_0(u(t_m) - u(t_{m-1})) : a = t_0 < t_1 < \dots < t_{M-1} < t_M = b \right\} \quad (3.13)$$

for any $[a, b] \subset [0, T]$. Therefore, with any $u \in BV([0, T]; \mathbb{R}^d)$ we can associate the non-decreasing function $V_{\Psi_0} : \mathbb{R} \rightarrow [0, +\infty)$ defined by

$$V_{\Psi_0}(t) := \begin{cases} 0 & \text{if } t \leq 0, \\ \text{Var}_{\Psi_0}(u; [0, t]) & \text{if } t \in (0, T), \\ \text{Var}_{\Psi_0}(u; [0, T]) & \text{if } t \geq T. \end{cases}$$

Its distributional derivative μ_{Ψ_0} is in turn a Radon measure that can be decomposed into a jump part $\mu_{\Psi_0, J}$, concentrated on J_u and given by

$$\mu_{\Psi_0, J}(\{t\}) = \Psi_0(u(t) - u(t_-)) + \Psi_0(u(t_+) - u(t)),$$

and a diffuse part

$$\mu_{\Psi_0, \text{co}} = \mu_{\Psi_0, \mathcal{L}} + \mu_{\Psi_0, C} \quad \text{with} \quad \mu_{\Psi_0, \mathcal{L}} = \Psi_0(\dot{u}) \mathcal{L}^1 \quad (3.14)$$

and \mathcal{L}^1 the 1-dimensional Lebesgue measure. There holds

$$\text{Var}_{\Psi_0}(u; [a, b]) = \mu_{\Psi_0, \text{co}}([a, b]) + \text{Jmp}_{\Psi_0}(u; [a, b]) = \int_a^b \Psi_0(\dot{u}) dt + \mu_{\Psi_0, C}([a, b]) + \text{Jmp}_{\Psi_0}(u; [a, b]), \quad (3.15)$$

with the jump contribution $\text{Jump}_{\Psi_0}(u; [a, b])$ given by

$$\begin{aligned} \text{Jump}_{\Psi_0}(u; [a, b]) &:= \Psi_0(u(a_+) - u(a)) + \mu_{\Psi_0, \mathfrak{J}}((a, b)) + \Psi_0(u(b_+) - u(b)) \\ &= \Psi_0(u(a_+) - u(a)) + \sum_{t \in \mathfrak{J}_u \cap (a, b)} \left(\Psi_0(u(t) - u(t_-)) + \Psi_0(u(t_+) - u(t)) \right) + \Psi_0(u(b_+) - u(b)). \end{aligned} \quad (3.16)$$

Finally, for later use we recall that a sequence $(u_n)_n$ *weakly* converges in $\text{BV}([0, T]; \mathbb{R}^d)$ to a curve u (we will write $u_n \rightharpoonup u$) if $u_n(t) \rightarrow u(t)$ as $n \rightarrow \infty$ for every $t \in [0, T]$ and $\sup_n \text{Var}(u_n; [0, T]) \leq C < \infty$ (in what follows, we shall denote by $\text{Var}(u; [0, T])$ the total variation of a curve u induced by a generic norm $\|\cdot\|$ on \mathbb{R}^d), whereas $(u_n)_n$ *strictly* converges in $\text{BV}([0, T]; \mathbb{R}^d)$ to u ($u_n \rightarrow u$) if $u_n \rightharpoonup u$ and $\text{Var}(u_n; [0, T]) \rightarrow \text{Var}(u; [0, T])$. Finally, a sequence of functionals $\mathcal{G}_n : \text{BV}([0, T]; \mathbb{R}^d) \rightarrow \mathbb{R}$ MOSCO-converge to a functional $\mathcal{G} : \text{BV}([0, T]; \mathbb{R}^d) \rightarrow \mathbb{R}$ with respect to the weak-strict topology in $\text{BV}([0, T]; \mathbb{R}^d)$ if

$$\begin{aligned} (i) \quad u_n \rightharpoonup u \text{ weakly in } \text{BV}([0, T]; \mathbb{R}^d) &\Rightarrow \liminf_{n \rightarrow \infty} \mathcal{G}_n(u_n) \geq \mathcal{G}(u), \\ (ii) \quad \forall u \in \text{BV}([0, T]; \mathbb{R}^d) \exists (u_n)_n \subset \text{BV}([0, T]; \mathbb{R}^d) \text{ s.t. } &\begin{cases} u_n \rightarrow u \text{ strictly in } \text{BV}([0, T]; \mathbb{R}^d), \\ \limsup_{n \rightarrow \infty} \mathcal{G}_n(u_n) \leq \mathcal{G}(u). \end{cases} \end{aligned} \quad (3.17)$$

We refer to [Att84] for more details on MOSCO-convergence.

Viscosity contact potentials. The notion we are going to introduce now lies at the core of the definition of *Balanced Viscosity* solution to a rate-independent system, driven by an energy functional \mathcal{E} complying with (E). Indeed, the concept of *viscosity contact potential* encodes how viscosity enters into the description of the solution behavior at jumps, cf. (3.26) ahead. It is an extension of the notion of *vanishing-viscosity contact potential* introduced in [MRS12], in that we are augmenting the contact potential defined therein by the time variable. That is why, we have used two different notations, \mathfrak{p} and \mathbf{p} , respectively, to distinguish the contact potential from [MRS12] from that introduced here. Furthermore, in referring to the contact potential \mathbf{p} , we will drop the word ‘vanishing’ in order to highlight that Balanced Viscosity solutions do not necessarily arise from a vanishing-viscosity approximation, cf. Sec. 5.2.

Definition 3.2. *We call a lower semicontinuous function $\mathbf{p} : [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0, +\infty]$ a (viscosity) contact potential if it satisfies the following properties:*

- (1) *for every $\tau \geq 0$ there holds $\mathbf{p}(\tau, v, \xi) \geq \langle v, \xi \rangle$ for all $(v, \xi) \in \mathbb{R}^d \times \mathbb{R}^d$;*
- (2) *for every $\xi \in \mathbb{R}^d$ the map $(\tau, v) \mapsto \mathbf{p}(\tau, v, \xi)$ is convex and positively 1-homogeneous.*
- (3) *for every $\tau > 0$ and $v \in \mathbb{R}^d$, the map $\xi \mapsto \mathbf{p}(\tau, v, \xi)$ is convex.*

Moreover, we say that \mathbf{p} is non-degenerate if

- (4) *for every $\tau \geq 0$ there holds $\mathbf{p}(\tau, v, \xi) > 0$ if $v \neq 0$.*

Finally, given a (non-degenerate) 1-homogeneous dissipation potential Ψ_0 as in (3.4), we say that \mathbf{p} is Ψ_0 -non degenerate if

- (5) *for all $(v, \xi) \in \mathbb{R}^d \times \mathbb{R}^d$ there holds $\mathbf{p}(0, v, \xi) \geq \Psi_0(v)$.*

A crucial object related to a (viscosity) contact potential \mathbf{p} is the set where the inequality in (1) holds as an equality. We will call it *contact set* and denote it by

$$\Lambda_{\mathbf{p}} := \{(\tau, v, \xi) \in [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d : \mathbf{p}(\tau, v, \xi) = \langle v, \xi \rangle\}, \quad (3.18)$$

whereas we will use the notation

$$\Lambda_{\mathbf{p}, 0} := \Lambda_{\mathbf{p}} \cap \{0\} \times \mathbb{R}^d \times \mathbb{R}^d = \{(v, \xi) \in \mathbb{R}^d \times \mathbb{R}^d : \mathbf{p}(0, v, \xi) = \langle v, \xi \rangle\}. \quad (3.19)$$

Let us point out a first important consequence of the properties defining a contact potential:

Lemma 3.3. *For fixed $(\tau, \xi) \in [0, +\infty) \times \mathbb{R}^d$, denote by $\partial_v \mathbf{p}(\tau, \cdot, \xi)(v)$ the (convex analysis) subdifferential at v of the functional $v \mapsto \mathbf{p}(\tau, v, \xi)$. Then,*

$$(\tau, v, \xi) \in \Lambda_{\mathbf{p}} \Leftrightarrow \xi \in \partial_v \mathbf{p}(\tau, \cdot, \xi)(v) \quad (3.20)$$

Proof. Since $v \mapsto \mathfrak{p}(\tau, v, \xi)$ is convex and positively homogeneous of degree 1, we have (cf. (3.6)),

$$\xi \in \partial_v \mathfrak{p}(\tau, \cdot, \xi)(v) \quad \text{iff} \quad \begin{cases} \langle \xi, \tilde{v} \rangle \leq \mathfrak{p}(\tau, \tilde{v}, \xi) & \text{for all } \tilde{v} \in \mathbb{R}^d, \\ \langle \xi, v \rangle = \mathfrak{p}(\tau, v, \xi), \end{cases}$$

and the thesis follows. \square

Remark 3.4. Observe that, for fixed $\tau \in [0, +\infty)$, the function $\mathfrak{p}(\tau, \cdot, \cdot) : \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0, +\infty)$ enjoys some of the properties of the notion of *bipotential* (cf., e.g., [BdV08]), which is by definition a functional $\mathfrak{b} : \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0, +\infty]$ convex and lower semicontinuous w.r.t. *both* variables, separately, and fulfilling $\mathfrak{b}(v, \xi) \geq \langle v, \xi \rangle$ for all $(v, \xi) \in \mathbb{R}^d \times \mathbb{R}^d$, as well as a stronger version of (3.20), namely

$$(v, \xi) \in \Lambda_{\mathfrak{b}} \Leftrightarrow \xi \in \partial_v \mathfrak{b}(\cdot, \xi)(v) \Leftrightarrow v \in \partial_{\xi} \mathfrak{b}(v, \cdot)(\xi),$$

where the contact set $\Lambda_{\mathfrak{b}}$ is defined similarly as in (3.18).

As discussed in [MRS12], the conditions defining the notion of bipotential however seem to be too restrictive for the contact potentials arising in the vanishing-viscosity limit of viscous systems approximating rate-independent evolution. Nonetheless, in Sec. 4 we will see how *viscosity contact potentials* can in fact be generated, via Γ -convergence, by bipotentials (in the sense of [BdV08]) associated with families of dissipation potentials.

3.2. BV solutions to rate-independent systems. We are now in a position to recall the preliminary definitions at the basis of the concept of *Balanced Viscosity* solution; notice that all of them involve the *reduced* contact potential $\mathfrak{p}(0, \cdot, \cdot)$ and the energy functional $\mathcal{E} \in C^1([0, T] \times \mathbb{R}^d)$.

First of all, we introduce the (possibly asymmetric) Finsler distance coming into play in the description of the energetic behaviour of a rate-independent system at a jump time: For a fixed $t \in [0, T]$, the Finsler distance induced by \mathfrak{p} and \mathcal{E} at the time t is defined for every $u_0, u_1 \in \mathbb{R}^d$ by

$$\Delta_{\mathfrak{p}, \mathcal{E}}(t; u_0, u_1) := \inf \left\{ \int_{r_0}^{r_1} \mathfrak{p}(0, \dot{\theta}(r), -D\mathcal{E}(t, \theta(r))) \, dr : \theta \in \text{AC}([r_0, r_1]; \mathbb{R}^d), \theta(r_0) = u_0, \theta(r_1) = u_1 \right\}. \quad (3.21)$$

Observe that, if \mathfrak{p} is a Ψ_0 -non degenerate contact potential for some 1-positively homogeneous potential Ψ_0 , we clearly have $\Delta_{\mathfrak{p}, \mathcal{E}}(t; u_0, u_1) \geq \Delta_{\Psi_0}(u_0, u_1) := \Psi_0(u_1 - u_0)$. Mimicking the notion (3.13) of Ψ_0 -total variation, moving from (3.21) we introduce a notion of total variation that measures the dissipation of a BV-curve at its jump points. Indeed, along the footsteps of [MRS12, Def. 3.4] and in analogy with (3.16), for a given curve $u \in \text{BV}([0, T]; \mathbb{R}^d)$ with jump set J_u , we define the *jump variation* of u induced by $(\mathfrak{p}, \mathcal{E})$ on an interval $[a, b] \subset [0, T]$ by

$$\begin{aligned} \text{Jmp}_{\mathfrak{p}, \mathcal{E}}(u; [a, b]) &:= \Delta_{\mathfrak{p}, \mathcal{E}}(a; u(a), u(a_+)) \\ &+ \sum_{t \in J_u \cap (a, b)} \left(\Delta_{\mathfrak{p}, \mathcal{E}}(t; u(t_-), u(t)) + \Delta_{\mathfrak{p}, \mathcal{E}}(t; u(t), u(t_+)) \right) + \Delta_{\mathfrak{p}, \mathcal{E}}(b; u(b_-), u(b)). \end{aligned} \quad (3.22)$$

Finally, given a (non-degenerate) 1-positively homogeneous dissipation potential Ψ_0 and a contact viscosity potential \mathfrak{p} , the (pseudo-)total variation of a curve $u \in \text{BV}([0, T]; \mathbb{R}^d)$ induced by $(\Psi_0, \mathfrak{p}, \mathcal{E})$ is defined by (cf. (3.15))

$$\text{Var}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(u; [a, b]) := \mu_{\Psi_0, \text{co}}([a, b]) + \text{Jmp}_{\mathfrak{p}, \mathcal{E}}(u; [a, b]) \quad \text{for any } [a, b] \subset [0, T], \quad (3.23)$$

with $\mu_{\Psi_0, \text{co}}$ from (3.14) the diffuse part of the total variation measure of the map $t \mapsto \text{Var}_{\Psi_0}(u; [0, t])$. Let us mention that the notation $\text{Var}_{\Psi_0, \mathfrak{p}, \mathcal{E}}$ is used here with slight abuse, since $\text{Var}_{\Psi_0, \mathfrak{p}, \mathcal{E}}$ does not enjoy all of the standard properties of total variation functionals, see [MRS12, Rmk. 3.6] for further details. Also observe that, if \mathfrak{p} is Ψ_0 -non degenerate, then we have $\text{Var}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(u; [a, b]) \geq \text{Var}_{\Psi_0}(u; [a, b])$.

We are finally in a position to introduce the concept of *Balanced Viscosity* solution to the rate-independent system individuated by the triple $(\Psi_0, \mathfrak{p}, \mathcal{E})$. This definition extends [MRS12, Def. 4.1].

Definition 3.5 (Balanced Viscosity solution). *Given a (non-degenerate) 1-homogeneous dissipation potential Ψ_0 and a (non-degenerate) viscosity contact potential \mathbf{p} , we say that a curve $u \in \text{BV}([0, T]; \mathbb{R}^d)$ is a Balanced Viscosity (BV) solution to the rate-independent system $(\Psi_0, \mathbf{p}, \mathcal{E})$ if it fulfills the local stability (S_{loc}) and the $(E_{\Psi_0, \mathbf{p}, \mathcal{E}})$ -energy-dissipation balance*

$$-D\mathcal{E}(t, u(t)) \in K^* \quad \text{for all } t \in [0, T] \setminus J_u, \quad (S_{\text{loc}})$$

$$\text{Var}_{\Psi_0, \mathbf{p}, \mathcal{E}}(u; [0, t]) + \mathcal{E}(t, u(t)) = \mathcal{E}(0, u(0)) + \int_0^t \partial_t \mathcal{E}(s, u(s)) \, ds \quad \text{for all } t \in [0, T] \quad (E_{\Psi_0, \mathbf{p}, \mathcal{E}})$$

with $K^* = \partial\Psi_0(0)$.

While referring to [MRS12, Sec. 4] and [MRS16, Sec. 3] for a detailed survey of the properties of BV solutions, let us only mention here a few. Firstly, by the analogue of [MRS12, Prop. 4.2], for a BV solution the energy-dissipation balance $(E_{\Psi_0, \mathbf{p}, \mathcal{E}})$ indeed holds on every sub-interval $[s, t] \subset [0, T]$, i.e.

$$\text{Var}_{\Psi_0, \mathbf{p}, \mathcal{E}}(u; [s, t]) + \mathcal{E}(t, u(t)) = \mathcal{E}(s, u(s)) + \int_s^t \partial_t \mathcal{E}(r, u(r)) \, dr \quad \text{for all } [s, t] \subset [0, T]. \quad (E_{\Psi_0, \mathbf{p}, \mathcal{E}})$$

Furthermore, the concept of BV solution yields a thorough description of the energetic behavior of the solution at jumps through the concept of *optimal jump transition*. For fixed $t \in [0, T]$ and $u_-, u_+ \in \mathbb{R}^d$, we call a curve $\theta \in \text{AC}([0, 1]; \mathbb{R}^d)$ (up to a rescaling, we may indeed suppose the curves in (3.21) to be defined on $[0, 1]$), with $\theta(0) = u_-$ and $\theta(1) = u_+$, a $(\mathbf{p}, \mathcal{E}_t)$ -optimal transition between u_- and u_+ if it has constant Finsler velocity $\mathbf{p}(0, \dot{\theta}(\cdot), -D\mathcal{E}(t, \theta(\cdot)))$ and there holds

$$\mathcal{E}(t, u_-) - \mathcal{E}(t, u_+) = \Delta_{\mathbf{p}, \mathcal{E}}(t; u_-, u_+) = \mathbf{p}(0, \dot{\theta}(r), -D\mathcal{E}(t, \theta(r))) > 0 \quad \text{for a.a. } r \in (0, 1). \quad (3.24)$$

The following result subsumes [MRS12, Prop. 4.6, Thm. 4.7].

Proposition 3.6. *Let $u \in \text{BV}([0, T]; \mathbb{R}^d)$ be a Balanced Viscosity solution to the rate-independent system $(\Psi_0, \mathbf{p}, \mathcal{E})$. Then, at every jump time $t \in J_u$ there exists a $(\mathbf{p}, \mathcal{E}_t)$ -optimal transition θ^t between the left and right-limits $u_-(t)$ and $u_+(t)$, such that $\theta^t(r) = u(t)$ for some $r \in [0, 1]$. Moreover, any optimal jump transition θ^t between $u_-(t)$ and $u_+(t)$ complies with the contact condition*

$$(\dot{\theta}^t(r), -D\mathcal{E}(t, \theta^t(r))) \in \Lambda_{\mathbf{p}, 0} \quad \text{for a.a. } r \in (0, 1), \quad (3.25)$$

with the contact set $\Lambda_{\mathbf{p}, 0}$ from (3.19).

A crucial consequence of (3.25) and of (3.20) from Lemma 3.3 is that any optimal jump transition θ^t complies with the subdifferential inclusion

$$-D\mathcal{E}(t, \theta^t(r)) \in \partial_v \mathbf{p}(0, \cdot, -D\mathcal{E}(t, \theta^t(r))) (\dot{\theta}^t(r)) \quad \text{for a.a. } r \in (0, 1). \quad (3.26)$$

The validity of this flow rule explicitly shows how the contact potential \mathbf{p} enters into the description of the solution behavior at jumps.

With the last result of this section we reformulate the BV solution concept in terms of the null-minimization of a functional defined on BV-trajectories; this will be crucial for the variational convergence analysis developed in Sec. 5. Namely, given a rate-independent system $(\Psi_0, \mathbf{p}, \mathcal{E})$, we define the trajectory functional $\mathcal{J}_{\Psi_0, \mathbf{p}, \mathcal{E}} : \text{BV}([0, T]; \mathbb{R}^d) \rightarrow (-\infty, +\infty]$ by

$$\begin{aligned} \mathcal{J}_{\Psi_0, \mathbf{p}, \mathcal{E}}(u) &:= \text{Var}_{\Psi_0, \mathbf{p}, \mathcal{E}}(u; [0, T]) + \int_0^T \Psi_0^*(-D\mathcal{E}(t, u(t))) \, dt + \mathcal{E}(T, u(T)) - \mathcal{E}(0, u(0)) - \int_0^T \partial_t \mathcal{E}(s, u(s)) \, ds \\ &= \int_0^T \left(\Psi_0(\dot{u}(s)) + \Psi_0^*(-D\mathcal{E}(s, u(s))) \right) \, ds + \mu_{\Psi_0, \mathbf{p}, \mathcal{E}}([0, T]) + \text{Jmp}_{\mathbf{p}, \mathcal{E}}(u; [0, T]) \\ &\quad + \mathcal{E}(T, u(T)) - \mathcal{E}(0, u(0)) - \int_0^T \partial_t \mathcal{E}(s, u(s)) \, ds, \end{aligned} \quad (3.27)$$

where the second identity follows from (3.15), with \dot{u} the density of the absolutely continuous part of u' w.r.t. the Lebesgue measure \mathcal{L}^1 . We then have the following

Proposition 3.7. *A curve $u \in \text{BV}([0, T]; \mathbb{R}^d)$ is a Balanced Viscosity solution to the rate-independent system $(\Psi_0, \mathfrak{p}, \mathcal{E})$ if and only if*

$$0 = \mathcal{J}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(u) \leq \mathcal{J}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(v) \quad \text{for all } v \in \text{BV}([0, T]; \mathbb{R}^d) \quad (3.28)$$

Proof. First of all, observe that conditions $(S_{\text{loc}}) - (\mathbf{E}_{\Psi_0, \mathfrak{p}, \mathcal{E}})$ are indeed equivalent to $(S'_{\text{loc}}) - (\mathbf{E}_{\Psi_0, \mathfrak{p}, \mathcal{E}})$, with

$$-D\mathcal{E}(t, u(t)) \in K^* \quad \text{for } \mathcal{L}^1 - \text{a.a. } t \in (0, T). \quad (S'_{\text{loc}})$$

Indeed, if (S'_{loc}) holds, with a continuity argument one deduces $-D\mathcal{E}(t, u(t)) \in K^*$ at all $t \in [0, T] \setminus J_u$.

Clearly, $(S'_{\text{loc}}) - (\mathbf{E}_{\Psi_0, \mathfrak{p}, \mathcal{E}})$ are then equivalent to

$$\mathcal{J}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(u) = 0. \quad (3.29)$$

Now, with an argument based on the chain rule for \mathcal{E} , one sees (cf. the proof of [MRS16, Cor. 3.4] and of Lemma 3.1) that along a given curve $v \in \text{BV}([0, T]; \mathbb{R}^d)$ the map $\mathcal{J}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(v) \geq 0$, so that (3.29) holds if and only if $\mathcal{J}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(u) \leq 0$, i.e. $u \in \text{Argmin}_{v \in \text{BV}([0, T]; \mathbb{R}^d)} \mathcal{J}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(v)$. This concludes the proof. \square

4. GENERATION OF VISCOSITY CONTACT POTENTIALS VIA Γ -CONVERGENCE

In this section we provide a possible procedure to generate a viscosity contact potential via a Γ -convergence procedure, starting from a family $(\Psi_n)_n$ of dissipation potentials with *superlinear growth at infinity* (cf. (3.2)).

Preliminarily, given a convex dissipation potential Ψ , we define the *bipotential* $\mathbf{b}_\Psi : [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0, +\infty]$ induced by Ψ via

$$\mathbf{b}_\Psi(\tau, v, \xi) := \begin{cases} \tau\Psi\left(\frac{v}{\tau}\right) + \tau\Psi^*(\xi) & \text{for } \tau > 0, \\ 0 & \text{for } \tau = 0, v = 0, \\ +\infty & \text{for } \tau = 0 \text{ and } v \neq 0, \end{cases} = \begin{cases} \tau\Psi\left(\frac{v}{\tau}\right) + \tau\Psi^*(\xi) & \text{for } \tau > 0, \\ I_{\{0\}}(v) & \text{for } \tau = 0. \end{cases} \quad (4.1)$$

It is immediate to check that

- (1) for every $(v, \xi) \in \mathbb{R}^d \times \mathbb{R}^d$ the map $\tau \mapsto \mathbf{b}_\Psi(\tau, v, \xi)$ is convex;
- (2) for every $\tau \geq 0$ the functional $(v, \xi) \mapsto \mathbf{b}_\Psi(\tau, v, \xi)$ is a bipotential in the sense of [BdV08] (cf. Remark 3.4);
- (3) for every $v \neq 0$ and $\xi \in \mathbb{R}^d$ with $\Psi^*(\xi) \neq 0$, the set $\text{Argmin}_{\tau > 0} \mathbf{b}_\Psi(\tau, v, \xi)$ is non-empty,

where the latter property is due to the fact that $\lim_{\tau \downarrow 0} \mathbf{b}_\Psi(\tau, v, \xi) = +\infty$ due to the superlinear growth of Ψ , and $\lim_{\tau \uparrow +\infty} \mathbf{b}_\Psi(\tau, v, \xi) = +\infty$.

Let us now be given a sequence $(\Psi_n)_n$ of dissipation potentials, and let $(\mathbf{b}_{\Psi_n})_n$ be the associated bipotentials. We assume the following.

Hypothesis 4.1. Let $\mathfrak{p} : [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0, +\infty]$ be defined by

$$\mathfrak{p} = \Gamma\text{-}\liminf_n \mathbf{b}_{\Psi_n} \quad \text{i.e.} \quad \mathfrak{p}(\tau, v, \xi) := \inf_{n \rightarrow \infty} \{ \liminf \mathbf{b}_{\Psi_n}(\tau_n, v_n, \xi_n) : \tau_n \rightarrow \tau, v_n \rightarrow v, \xi_n \rightarrow \xi \}. \quad (4.2)$$

Then,

for every $\xi \in \mathbb{R}^d$ there exists $(\xi_n)_n \subset \mathbb{R}^d$ with $\xi_n \rightarrow \xi$ and $\mathfrak{p}(\cdot, \cdot, \xi) = \Gamma\text{-}\limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}(\cdot, \cdot, \xi_n)$ i.e.

$$\mathfrak{p}(\tau, v, \xi) = \inf_{(\xi_n)_n \subset \mathbb{R}^d, \xi_n \rightarrow \xi} \left\{ \limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}(\tau_n, v_n, \xi_n) : \tau_n \rightarrow \tau, v_n \rightarrow v \right\}. \quad (4.3)$$

In Section 5.2 ahead, we will exhibit two classes of dissipations potentials $(\Psi_n)_n$, with superlinear growth at infinity, and associated functionals \mathbf{p} , complying with Hypothesis 4.1.

Observe that with (4.3) we are imposing a stronger condition than $\mathbf{p} = \Gamma\text{-lim sup}_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}$, namely we are asking that

$$\forall \xi \in \mathbb{R}^d \exists (\xi_n)_n \subset \mathbb{R}^d : \xi_n \rightarrow \xi \text{ and}$$

$$\forall (\tau, v) \in [0, +\infty) \times \mathbb{R}^d \exists (\tau_n, v_n)_n : \begin{cases} \tau_n \rightarrow \tau, \\ v_n \rightarrow v, \\ \limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}(\tau_n, v_n, \xi_n) \leq \mathbf{p}(\tau, v, \xi). \end{cases} \quad (4.4)$$

This property will play a key role in the proof of Lemma 4.3 below.

The main result of this section, Theorem 4.2 below, ensures that the functional \mathbf{p} generated via (4.2)–(4.3) is a contact potential in the sense of Definition 3.2.

Theorem 4.2. *Let $(\Psi_n)_n$ be a sequence of dissipation potentials on \mathbb{R}^d complying with Hypothesis 4.1. Then, \mathbf{p} is a viscosity contact potential according to Def. 3.2, and there exists a 1-homogeneous dissipation potential Ψ_0 such that*

$$\mathbf{p}(\tau, v, \xi) \geq \Psi_0(v) \quad \text{for all } (\tau, v, \xi) \in [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d. \quad (4.5)$$

Moreover, if the dissipation potentials $(\Psi_n)_n$ fulfill the uniform coercivity condition

$$\exists M > 0, (M_n)_n \subset (0, +\infty) \text{ s.t. } M_n \rightarrow 0 \text{ and } \forall n \in \mathbb{N} \quad \forall v \in \mathbb{R}^d \text{ there holds } \Psi_n(v) \geq M\|v\| - M_n, \quad (4.6)$$

with $\|\cdot\|$ any norm in \mathbb{R}^d , then Ψ_0 is non-degenerate and \mathbf{p} is Ψ_0 -non degenerate.

We postpone the proof of Theorem 4.2 to the end of this section, after obtaining a series of preliminary lemmas on the structure that the functional \mathbf{p} defined by Hypothesis 4.1 inherits from the potentials Ψ_n .

Lemma 4.3. *Assume Hypothesis 4.1. Then, for every $(\tau, v, \xi) \in [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d$ there holds*

- (1) $\mathbf{p}(\tau, v, \xi) \geq \langle v, \xi \rangle$;
- (2) the map $(\tau, v) \mapsto \mathbf{p}(\tau, v, \xi)$ is convex and positively homogeneous of degree 1.

Proof. Property (1) is an immediate consequence of (4.2), using that for every $n \in \mathbb{N}$ there holds $\mathbf{b}_{\Psi_n}(\tau, v, \xi) \geq \langle v, \xi \rangle$ for every $(\tau, v, \xi) \in [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d$.

In order to show that the mapping $\mathbf{p}(\cdot, \cdot, \xi)$ is convex for fixed ξ , let $(\xi_n)_n$ with $\xi_n \rightarrow \xi$ fulfill (4.3). For fixed (τ_0, v_0) and (τ_1, v_1) let $(\tau_n^i, v_n^i)_n$, $i = 1, 2$, be two associated recovery sequences for $\mathbf{b}_{\Psi_n}(\cdot, \cdot, \xi_n)$ as in (4.4). Then, for every $\lambda \in [0, 1]$ there holds

$$\begin{aligned} \mathbf{p}((1-\lambda)\tau_0 + \lambda\tau_1, (1-\lambda)v_0 + \lambda v_1, \xi) &\stackrel{(1)}{\leq} \liminf_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}((1-\lambda)\tau_n^0 + \lambda\tau_n^1, (1-\lambda)v_n^0 + \lambda v_n^1, \xi_n) \\ &\stackrel{(2)}{\leq} \limsup_{n \rightarrow \infty} (1-\lambda)\mathbf{b}_{\Psi_n}(\tau_n^0, v_n^0, \xi_n) + \lambda\mathbf{b}_{\Psi_n}(\tau_n^1, v_n^1, \xi_n) \\ &\stackrel{(3)}{\leq} (1-\lambda)\mathbf{p}(\tau_0, v_0, \xi) + \lambda\mathbf{p}(\tau_1, v_1, \xi), \end{aligned}$$

where (1) follows from (4.2), (2) from the convexity of the maps $\mathbf{b}_{\Psi_n}(\cdot, \cdot, \xi_n)$, and (3) from (4.3).

With an analogous argument one proves that $\mathbf{p}(\cdot, \cdot, \xi)$ is 1-positively homogeneous. \square

We now show that, for $\tau > 0$ the functional $\mathbf{p}(\tau, \cdot, \cdot)$ has the same form (4.1) as $\mathbf{b}_{\Psi_n}(\tau, \cdot, \cdot)$, cf. (4.8).

Lemma 4.4. *Assume Hypothesis 4.1. Let $\Psi_0 : \mathbb{R}^d \rightarrow [0, +\infty)$ be defined by*

$$\Psi_0(v) := \mathbf{p}(1, v, 0). \quad (4.7)$$

Then, Ψ_0 is a 1-positively homogeneous dissipation potential, the sequence $(\Psi_n)_n$ Γ -converges to Ψ_0 , and thus $(\Psi_n^*)_n$ Γ -converges to Ψ_0^* . Furthermore,

$$\mathfrak{p}(\tau, v, \xi) = \tau \Psi_0\left(\frac{v}{\tau}\right) + \tau \Psi_0^*(\xi) \quad \text{for all } \tau > 0 \text{ and all } (v, \xi) \in \mathbb{R}^d \times \mathbb{R}^d. \quad (4.8)$$

Proof. Observe that Ψ_0 from (4.7) is convex and 1-homogeneous thanks to item (2) in the statement Lemma 4.3, which obviously yields the convexity of $v \mapsto \mathfrak{p}(1, v, 0)$,

It follows from (4.2), applied with the choices $\tau = 1$ and $\xi = 0$ and with the sequences $\tau_n \equiv 1$ and $\xi_n \equiv 1$, that $\Psi_0 \leq \Gamma\text{-lim inf}_{n \rightarrow \infty} \Psi_n$. Conversely, applying (4.3) we deduce that $\Gamma\text{-lim sup}_{n \rightarrow \infty} \Psi_n \leq \Psi_0$. In fact, we use (4.4) with $\tau = 1$ and $\xi = 0$ to find a sequence $\xi_n \rightarrow 0$ and sequences $\tau_n \rightarrow 1$ (we may indeed suppose that $\tau_n \uparrow 1$) and $v_n \rightarrow v$ such that

$$\limsup_{n \rightarrow \infty} \left(\tau_n \Psi_n\left(\frac{v_n}{\tau_n}\right) + \tau_n \Psi_n^*(\xi_n) \right) \leq \mathfrak{p}(1, v, 0).$$

In turn, $\limsup_{n \rightarrow \infty} \left(\tau_n \Psi_n\left(\frac{v_n}{\tau_n}\right) + \tau_n \Psi_n^*(\xi_n) \right) \geq \limsup_{n \rightarrow \infty} \tau_n \Psi_n\left(\frac{v_n}{\tau_n}\right) \geq \limsup_{n \rightarrow \infty} \Psi_n(v_n)$, where the latter inequality ensues from the fact that, for any dissipation potential Ψ , the map $\tau \mapsto \Psi\left(\frac{v}{\tau}\right)$ is non-increasing for all $v \in \mathbb{R}^d$. Combining these two estimates yields $\Gamma\text{-lim sup}_{n \rightarrow \infty} \Psi_n \leq \Psi_0$. All in all, we conclude that $\Psi_0 = \Gamma\text{-lim}_{n \rightarrow \infty} \Psi_n$. Then, $(\Psi_n^*)_n$ Γ -converges to Ψ_0^* by [Att84, Thm. 2.18, p. 495]. As a consequence of these convergences and of (4.1), we have (4.8). \square

Our next two results address the characterization of \mathfrak{p} for $\tau = 0$, providing a formula for $\mathfrak{p}(0, v, w)$ in the two cases $\Psi_0^*(\xi) < +\infty$ and $\Psi_0^*(\xi) = +\infty$.

Lemma 4.5. *Assume Hypothesis 4.1. If $\Psi_0^*(\xi) < +\infty$, then*

$$\mathfrak{p}(0, v, \xi) = \liminf_{\tau \rightarrow 0} \tau \Psi_0\left(\frac{v}{\tau}\right) = \Psi_0(v) \quad \text{for all } v \in \mathbb{R}^d. \quad (4.9)$$

Proof. It follows from (4.8) and the fact that $\Psi_0^*(\xi) < +\infty$ that

$$\mathfrak{p}(0, v, \xi) \leq \liminf_{\tau \rightarrow 0} \mathfrak{p}(\tau, v, \xi) \leq \liminf_{\tau \rightarrow 0} \tau \Psi_0\left(\frac{v}{\tau}\right). \quad (4.10)$$

To prove the converse inequality, we again use that the map $\tau \mapsto \Psi\left(\frac{v}{\tau}\right)$ is non-increasing for every $v \in \mathbb{R}^d$. Therefore for all $0 < \tau < \sigma < 1$ we have

$$\tau \Psi\left(\frac{v}{\tau}\right) \geq \sigma \Psi\left(\frac{v}{\sigma}\right). \quad (4.11)$$

Now, let us fix a sequence $\xi_n \rightarrow \xi$ for which (4.3) holds, and accordingly a sequence $(\tau_n, v_n) \rightarrow (0, v)$ such that $\mathfrak{p}(0, v, \xi) = \liminf_{n \rightarrow \infty} (\tau_n \Psi_n(v_n/\tau_n) + \tau_n \Psi_n^*(\xi_n))$. It follows from inequality (4.11) applied to the functionals Ψ_n that for every $\sigma \in (0, 1)$

$$\liminf_{n \rightarrow \infty} \left(\tau_n \Psi_n\left(\frac{v_n}{\tau_n}\right) + \tau_n \Psi_n^*(\xi_n) \right) \geq \liminf_{n \rightarrow \infty} \left(\sigma \Psi_n\left(\frac{v_n}{\sigma}\right) \right) = \sigma \Psi_0\left(\frac{v}{\sigma}\right),$$

where we have also exploited the positivity of the functionals Ψ_n^* . Therefore, in view of (4.3) we find

$$\mathfrak{p}(0, v, \xi) \geq \sigma \Psi_0\left(\frac{v}{\sigma}\right)$$

and conclude the converse of (4.10) passing to the limit as $\sigma \rightarrow 0$. \square

Lemma 4.6. *Assume Hypothesis 4.1. If $\Psi_0^*(\xi) = +\infty$, then*

$$\mathfrak{p}(0, v, \xi) = \Gamma\text{-lim inf}_{n \rightarrow \infty} \inf_{\tau > 0} \mathfrak{b}_{\Psi_n}(\tau, v, \xi) \quad \text{for all } v \in \mathbb{R}^d. \quad (4.12)$$

Proof. Inequality \geq follows from the definition of \mathbf{p} . To prove the converse one, we may suppose that $v \neq 0$, since $\mathbf{p}(0, 0, \xi) = 0$. Take $(v_n, \xi_n) \rightarrow (v, \xi)$ that attains $\Gamma\text{-lim inf}_{n \rightarrow \infty} \inf_{\tau > 0} \mathbf{b}_{\Psi_n}(\tau, v, \xi)$, i.e. $\inf_{\tau > 0} \mathbf{b}_{\Psi_n}(\tau, v_n, \xi_n) \rightarrow \Gamma\text{-lim inf}_{n \rightarrow \infty} \inf_{\tau > 0} \mathbf{b}_{\Psi_n}(\tau, v, \xi)$. In particular, $\liminf_{n \rightarrow \infty} \Psi_n^*(\xi_n) = +\infty$. Therefore, we may choose $\bar{\tau}_n$ as

$$\bar{\tau}_n \in \text{Argmin}_{\tau > 0} \left(\tau \Psi_n \left(\frac{v_n}{\tau} \right) + \tau \Psi_n^*(\xi_n) \right).$$

Since $\liminf_{n \rightarrow \infty} \Psi_n^*(\xi_n) = +\infty$, it is clear that $\bar{\tau}_n \rightarrow 0$, hence

$$\Gamma\text{-lim inf}_{n \rightarrow \infty} \inf_{\tau > 0} \mathbf{b}_{\Psi_n}(\tau, v, \xi) = \lim_{n \rightarrow \infty} \left(\bar{\tau}_n \Psi_n \left(\frac{v_n}{\bar{\tau}_n} \right) + \bar{\tau}_n \Psi_n^*(\xi_n) \right) \geq \mathbf{p}(0, v, \xi)$$

thanks to (4.2). \square

We now prove a pseudo-monotonicity result for \mathbf{p} .

Lemma 4.7. *Assume Hypothesis 4.1. Then, for every $\tau, \bar{\tau} \in [0, +\infty)$, $v, \bar{v} \in \mathbb{R}^d$ and $\xi, \bar{\xi} \in \mathbb{R}^d$ we have that*

$$\left(\mathbf{p}(\tau, v, \xi) - \mathbf{p}(\tau, v, \bar{\xi}) \right) \left(\mathbf{p}(\bar{\tau}, \bar{v}, \xi) - \mathbf{p}(\bar{\tau}, \bar{v}, \bar{\xi}) \right) \geq 0. \quad (4.13)$$

Proof. Observe that (4.13) holds for the bipotentials \mathbf{b}_{Ψ_n} : indeed, in that case it reduces to $\tau \bar{\tau} (\Psi_n^*(\xi) - \Psi_n^*(\bar{\xi}))^2 \geq 0$.

Assume that $\mathbf{p}(\tau, v, \xi) > \mathbf{p}(\tau, v, \bar{\xi})$ and choose $\bar{\xi}_n$ as in (4.3) with (τ_n, v_n) such that

$$(\tau_n, v_n, \bar{\xi}_n) \rightarrow (\tau, v, \bar{\xi}), \quad \mathbf{b}_{\Psi_n}(\tau_n, v_n, \bar{\xi}_n) \rightarrow \mathbf{p}(\tau, v, \bar{\xi}). \quad (4.14)$$

It follows from the definition (4.2) of \mathbf{p} that $\mathbf{p}(\tau, v, \xi) \leq \liminf_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}(\tau_n, v_n, \xi_n)$ for every sequence $\xi_n \rightarrow \xi$ in \mathbb{R}^d , and for (τ_n, v_n) as in (4.14). Then

$$0 < \mathbf{p}(\tau, v, \xi) - \mathbf{p}(\tau, v, \bar{\xi}) \leq \liminf_{n \rightarrow \infty} \left(\mathbf{b}_{\Psi_n}(\tau_n, v_n, \xi_n) - \mathbf{b}_{\Psi_n}(\tau_n, v_n, \bar{\xi}_n) \right). \quad (4.15)$$

Therefore, for sufficiently big n we have that

$$\mathbf{b}_{\Psi_n}(\tau_n, v_n, \xi_n) - \mathbf{b}_{\Psi_n}(\tau_n, v_n, \bar{\xi}_n) \geq 0. \quad (4.16)$$

Now, again in view of (4.3), choose $\xi_n \rightarrow \xi$ (notice that (4.15) holds for *any* sequence ξ_n converging to ξ) and $\bar{\tau}_n \rightarrow \bar{\tau}$, $\bar{v}_n \rightarrow \bar{v}$ such that $\limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}(\bar{\tau}_n, \bar{v}_n, \xi_n) \leq \mathbf{p}(\bar{\tau}, \bar{v}, \xi)$. Since $\liminf_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}(\bar{\tau}_n, \bar{v}_n, \bar{\xi}_n) \geq \mathbf{p}(\bar{\tau}, \bar{v}, \bar{\xi})$ by (4.2), we conclude that

$$\mathbf{p}(\bar{\tau}, \bar{v}, \xi) - \mathbf{p}(\bar{\tau}, \bar{v}, \bar{\xi}) \geq \limsup_{n \rightarrow \infty} \left(\mathbf{b}_{\Psi_n}(\bar{\tau}_n, \bar{v}_n, \xi_n) - \mathbf{b}_{\Psi_n}(\bar{\tau}_n, \bar{v}_n, \bar{\xi}_n) \right) \geq 0,$$

taking into account that $\mathbf{b}_{\Psi_n}(\bar{\tau}_n, \bar{v}_n, \xi_n) - \mathbf{b}_{\Psi_n}(\bar{\tau}_n, \bar{v}_n, \bar{\xi}_n) \geq 0$ for sufficiently big n thanks to (4.16) and the previously observed monotonicity property (4.13) for \mathbf{b}_{Ψ_n} . Thus, (4.13) follows. \square

Finally, let us consider contact sets associated with the bipotentials \mathbf{b}_{Ψ_n} , i.e.

$$\Lambda_{\mathbf{b}_{\Psi_n}} := \left\{ (\tau, v, \xi) \in [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d : \langle v, \xi \rangle = \mathbf{b}_{\Psi_n}(\tau, v, \xi) \right\}.$$

Observe that for every $n \in \mathbb{N}$

- (1) $\Lambda_{\mathbf{b}_{\Psi_n}} \cap \{0\} \times \mathbb{R}^d \times \mathbb{R}^d = \{0\} \times \{0\} \times \mathbb{R}^d$;
- (2) for $\tau > 0$, if $(\tau, v, \xi) \in \Lambda_{\mathbf{b}_{\Psi_n}}$, then $\tau \in \text{Argmin}_{\sigma \in (0, +\infty)} (\sigma \Psi_n(\frac{v}{\sigma}) + \sigma \Psi_n^*(\xi))$.

The following closedness property may be easily derived from (4.2).

Lemma 4.8. *Assume Hypothesis 4.1. Then,*

$$\begin{cases} (\tau_n, v_n, \xi_n) \in \Lambda_{\mathbf{b}_{\Psi_n}}, \\ (\tau_n, v_n, \xi_n) \rightarrow (\tau, v, \xi) \end{cases} \Rightarrow (\tau, v, \xi) \in \Lambda_{\mathbf{p}}. \quad (4.17)$$

We are now in a position to carry out the **proof of Theorem 4.2** by verifying that \mathbf{p} complies with properties (1)–(5) from Definition 3.2.

Properties (1)&(2) are guaranteed by Lemma 4.3, whereas (3) ensues from (4.8) in Lemma 4.4. Concerning property (5), observe that (4.5) ensues from (4.8) for $\tau > 0$. For $\tau = 0$, it directly follows from (4.9) in the case $\Psi_0^*(\xi) < +\infty$, whereas for $\Psi_0^*(\xi) = +\infty$ we use the monotonicity property (4.13), giving

$$(\mathbf{p}(1, v, \xi) - \mathbf{p}(1, v, 0))(\mathbf{p}(0, v, \xi) - \mathbf{p}(0, v, 0)) \geq 0.$$

Now, $\mathbf{p}(1, v, \xi) = \Psi_0(v) + \Psi_0^*(\xi) = +\infty$, hence we deduce that $\mathbf{p}(0, v, \xi) \geq \mathbf{p}(0, v, 0) \geq \Psi_0(v)$ (here we have used that $\Psi_0^*(0) = 0$).

Under the additional (4.6), it is immediate to check that Ψ_0 given by (4.7) is non-degenerate, whence the validity of property (4). This concludes the proof of Thm. 4.2. \square

5. MAIN RESULTS

Let us consider a sequence $(\Psi_n)_n$ of dissipation potentials on \mathbb{R}^d with *superlinear growth at infinity*, namely fulfilling (3.2) for every $n \in \mathbb{N}$. A straightforward extension of the by now classical results by COLLI&VISINTIN for doubly nonlinear evolution equations (cf. [CV90, Col92]) yields that for every $n \in \mathbb{N}$ there exists at least a solution $u \in AC([0, T]; \mathbb{R}^d)$ of (the Cauchy problem for) the generalized gradient system (Ψ_n, \mathcal{E}) , with \mathcal{E} complying with (E). Namely, u solves the doubly nonlinear differential inclusion

$$\partial\Psi_n(\dot{u}(t)) + D\mathcal{E}(t, u(t)) \ni 0 \quad \text{for a.a. } t \in (0, T). \quad (5.1)$$

As we have seen with Lemma 3.1, the solutions to (5.1) coincide with the null-minimizers for the (positive) functional of trajectories $\mathcal{J}_{\Psi_n, \mathcal{E}} : AC([0, T]; \mathbb{R}^d) \rightarrow [0, +\infty)$ defined by

$$\mathcal{J}_{\Psi_n, \mathcal{E}}(u) := \int_0^T (\Psi_n(\dot{u}(s)) + \Psi_n^*(-D\mathcal{E}(s, u(s)))) ds + \mathcal{E}(T, u(T)) - \mathcal{E}(0, u(0)) - \int_0^T \partial_t \mathcal{E}(s, u(s)) ds. \quad (5.2)$$

The **main results of this paper**, **Theorems 5.2 and 5.9** ahead, concern the MOSCO-convergence to the functional $\mathcal{J}_{\Psi_0, \mathbf{p}, \mathcal{E}}$ from (3.27), with respect to the weak-strict topology of $BV([0, T]; \mathbb{R}^d)$ (cf. (3.17)), of a family of functionals $(\mathcal{J}_{\Psi_n, \mathcal{E}})_n$ extending $\mathcal{J}_{\Psi_n, \mathcal{E}}$ to $BV([0, T]; \mathbb{R}^d)$. Namely, we define

$$\mathcal{J}_{\Psi_n, \mathcal{E}} : BV([0, T]; \mathbb{R}^d) \rightarrow [0, +\infty] \quad \text{by} \quad \mathcal{J}_{\Psi_n, \mathcal{E}}(u) := \begin{cases} \mathcal{J}_{\Psi_n, \mathcal{E}}(u) & \text{if } u \in AC([0, T]; \mathbb{R}^d), \\ +\infty & \text{otherwise.} \end{cases} \quad (5.3)$$

More precisely, Section 5.1 below is centered around the Γ -lim inf result, Thm. 5.2, which implies (cf. Thm. 5.3) the Evolutionary Γ -convergence of the gradient systems (5.1) to a limiting rate-independent system (understood in the Balanced Viscosity sense). Thms. 5.2 and 5.3 are valid under the condition that the bipotentials $(\mathbf{b}_{\Psi_n})_n$ associated with the functionals $(\Psi_n)_n$ comply with Hypothesis 4.1. In Section 5.2 we show that Hyp. 4.1 is, in particular, verified by two classes of dissipation potentials approximating a 1-homogeneous one, namely for ‘vanishing-viscosity’ approximations and for the ‘stochastic’ approximation advanced in [BP16]. For these two cases (the vanishing-viscosity one further particularized), in Section 5.3 we state our Γ -lim sup result, Thm. 5.9, along with the reverse approximation Thm. 5.12.

With the exception of Proposition 5.8, the proofs of all the upcoming results in this section shall be carried out throughout Section 6.

5.1. The Γ -liminf result. First of all, let us fix the compactness properties of a sequence $(u_n)_n \subset BV([0, T]; \mathbb{R}^d)$ with $\sup_n \mathcal{J}_{\Psi_n, \mathcal{E}}(u_n) \leq C$, assuming that the potentials Ψ_n comply with a suitable coercivity property.

Proposition 5.1. *Let $(\Psi_n)_n$ be a family of dissipation potentials with superlinear growth at infinity and assume that*

$$\exists M_1, M_2 > 0 \quad \forall n \in \mathbb{N} \quad \forall v \in \mathbb{R}^d : \quad \Psi_n(v) \geq M_1 \|v\| - M_2 \quad (5.4)$$

for some norm $\|\cdot\|$ on \mathbb{R}^d . Let $(u_n)_n \subset \text{BV}([0, T]; \mathbb{R}^d)$ fulfill $\|u_n(0)\| + \mathcal{J}_{\Psi_n, \varepsilon}(u_n) \leq C$ for some constant $C > 0$, uniform w.r.t. $n \in \mathbb{N}$. Then, there exist a subsequence $k \mapsto n_k$ and a curve u such that $u_{n_k} \rightharpoonup u$ in $\text{BV}([0, T]; \mathbb{R}^d)$.

We are now in a position to state the Γ -lim inf result for the sequence $(\mathcal{J}_{\Psi_n, \varepsilon})_n$.

Theorem 5.2. *Let $(\Psi_n)_n$ be a family of dissipation potentials with superlinear growth at infinity such that the associated bipotentials $(\mathbf{b}_{\Psi_n})_n$ comply with Hypothesis 4.1, with limiting viscosity contact potential \mathbf{p} . Let Ψ_0 be the 1-positively homogeneous dissipation potential defined by $\Psi_0(v) := \mathbf{p}(1, v, 0)$, and suppose that Ψ_0 is non-degenerate.*

Then, for every $(u_n)_n, u \in \text{BV}([0, T]; \mathbb{R}^d)$ we have that

$$u_n \rightharpoonup u \text{ in } \text{BV}([0, T]; \mathbb{R}^d) \Rightarrow \liminf_{n \rightarrow \infty} \mathcal{J}_{\Psi_n, \varepsilon}(u_n) \geq \mathcal{J}_{\Psi_0, \mathbf{p}, \varepsilon}(u). \quad (5.5)$$

More precisely, we have as $n \rightarrow \infty$

$$\mathcal{E}(t, u_n(t)) \rightarrow \mathcal{E}(t, u(t)) \text{ and } \int_0^t \partial_t \mathcal{E}(r, u_n(r)) \, dr \rightarrow \int_0^t \partial_t \mathcal{E}(r, u(r)) \, dr \text{ for every } t \in [0, T], \quad (5.6)$$

$$\liminf_{n \rightarrow \infty} \int_s^t (\Psi_n(\dot{u}_n(r)) + \Psi_n^*(-D\mathcal{E}(r, u_n(r)))) \, dr \geq \text{Var}_{\Psi_0, \mathbf{p}, \varepsilon}(u; [s, t]) + \int_s^t \Psi_0^*(-D\mathcal{E}(t, u(r))) \, dr \quad (5.7)$$

for every $0 \leq s \leq t \leq T$.

A straightforward consequence of Thm. 5.2 is the following result.

Theorem 5.3. *Under the assumptions of Theorem 5.2, let $(u_n)_n \subset \text{AC}([0, T]; \mathbb{R}^d)$ fulfill $\mathcal{J}_{\Psi_n}(u_n) \leq \varepsilon_n$ for every $n \in \mathbb{N}$, for some vanishing sequence $(\varepsilon_n)_n$.*

Then, any limit point u of $(u_n)_n$ with respect to the weak-BV $([0, T]; \mathbb{R}^d)$ -topology is a Balanced Viscosity solution to the rate-independent system $(\Psi_0, \mathbf{p}, \varepsilon)$, and, up to a subsequence, convergences (5.6) and

$$\lim_{n \rightarrow \infty} \int_s^t (\Psi_n(\dot{u}_n(r)) + \Psi_n^*(-D\mathcal{E}(r, u_n(r)))) \, dr = \text{Var}_{\Psi_0, \mathbf{p}, \varepsilon}(u; [s, t]) + \int_s^t \Psi_0^*(-D\mathcal{E}(t, u(r))) \, dr \quad (5.8)$$

hold for all $0 \leq s \leq t \leq T$.

Remark 5.4. By virtue of Proposition 5.1, under the uniform coercivity condition (5.4) the set of the limit points of the sequence $(u_n)_n$ in the statement of Theorem 5.3 is non-empty (if, in addition, $\sup_{n \in \mathbb{N}} \|u_n(0)\| \leq C$). If (5.4) is strengthened to (4.6), we also have that the limiting dissipation potential Ψ_0 is non-degenerate.

5.2. Examples. We now focus on two classes of dissipation potentials $(\Psi_n)_n$, with superlinear growth at infinity, approximating a 1-positively homogeneous dissipation potential Ψ_0 . In the first case, the dissipation potentials Ψ_n are obtained by rescaling from a given dissipation potential Ψ with superlinear growth at infinity, and suitably converge to a 1-homogeneous potential Ψ_0 . In the second case, we consider the stochastic model introduced in Section 2 and the associated potentials Ψ_n given by (2.6): the limiting potential is $\Psi_0(v) = A\|v\|_1$, where $\|\cdot\|_1$ denotes the L^1 -norm on \mathbb{R}^d

$$\|v\|_1 := \sum_{i=1}^d |v_i|.$$

We will show that in both cases Hypothesis 4.1 is fulfilled.

The vanishing-viscosity approximation. We consider the dissipation potentials

$$\Psi_n(v) = \frac{1}{\varepsilon_n} \Psi(\varepsilon_n v) \quad \text{for all } v \in \mathbb{R}^d, \text{ with } \varepsilon_n \downarrow 0, \quad (5.9a)$$

with $\Psi : \mathbb{R}^d \rightarrow [0, +\infty)$ a fixed potential with superlinear growth at infinity. We suppose that there exists a 1-homogeneous dissipation potential Ψ_0 such that

$$\Psi_0(v) = \lim_{n \rightarrow \infty} \Psi_n(v) = \lim_{n \rightarrow \infty} \frac{1}{\varepsilon_n} \Psi(\varepsilon_n v) \quad \text{for all } v \in \mathbb{R}^d. \quad (5.9b)$$

Example 5.5. In particular, we focus on these two cases (cf. [MRS12, Ex. 2.3]):

- (1) **Ψ_0 -viscosity:** the superlinear dissipation potential Ψ is obtained augmenting Ψ_0 by a superlinear function of Ψ_0 itself. Namely, given a convex superlinear function $F_V : [0, +\infty) \rightarrow [0, +\infty)$, we set

$$\Psi(v) := \Psi_0(v) + F_V(\Psi_0(v)), \quad \text{whence } \Psi_n(v) = \Psi_0(v) + \frac{1}{\varepsilon_n} F_V(\varepsilon_n \Psi_0(v)) \quad \text{for all } v \in \mathbb{R}^d. \quad (5.10)$$

To fix ideas, we may think of $\Psi_0(v) = A\|v\|_1$ and $F_V(\rho) = \frac{1}{2}\rho^2$, giving rise to

$$\Psi_n(v) = A\|v\|_1 + \frac{\varepsilon_n}{2} A^2 \|v\|_1^2. \quad (5.11)$$

- (2) **2-norm vanishing-viscosity:** Let us now consider a norm $\|\cdot\|$ on \mathbb{R}^d , different from that associated with Ψ_0 . We set

$$\Psi(v) := \Psi_0(v) + F_V(\|v\|), \quad \text{whence } \Psi_n(v) = \Psi_0(v) + \frac{1}{\varepsilon_n} F_V(\varepsilon_n \|v\|) \quad \text{for all } v \in \mathbb{R}^d, \quad (5.12)$$

with again $F_V : [0, +\infty) \rightarrow [0, +\infty)$ convex and superlinear. In this way we generate, for example, the dissipation potentials

$$\Psi_n(v) = A\|v\|_1 + \frac{\varepsilon_n}{2} \|v\|_2^2, \quad (5.13)$$

with $\|v\|_2 := \left(\sum_{i=1}^d |v_i|^2\right)^{1/2}$ and, more in general,

$$\Psi_n(v) = A\|v\|_1 + \frac{\varepsilon_n^{p-1}}{p} \|v\|_p^p \quad \text{with } \|v\|_p := \left(\sum_{i=1}^d |v_i|^p\right)^{1/p}. \quad (5.14)$$

This family of dissipation potentials comply with the hypotheses of Thm. 5.2, as shown by the following result.

Proposition 5.6. *The dissipation potentials from (5.9) comply with (4.6) and with Hypothesis 4.1, where*

$$\mathfrak{p} : [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0, +\infty] \quad \text{is given by } \mathfrak{p}(\tau, v, \xi) := \begin{cases} \Psi_0(v) + I_{K^*}(\xi) & \text{if } \tau > 0, \\ \inf_{\varepsilon_n > 0} (\Psi_n(v) + \Psi_n^*(\xi)) & \text{if } \tau = 0. \end{cases} \quad (5.15)$$

The *proof* can be straightforwardly retrieved from the argument for [MRS12, Lemma 6.1].

Example 5.7 (Example 5.5 continued). Following [MRS12, Rem. 3.1], we explicitly calculate $\mathfrak{p}(0, v, \xi)$, using formula (5.15), in the two cases of Example 5.5:

- (1) **Ψ_0 -viscosity:** We have

$$\mathfrak{p}(0, v, \xi) := \begin{cases} \Psi_0(v) & \text{if } \xi \in K^*, \\ \Psi_0(v) \sup_{v \neq 0} \frac{\langle \xi, v \rangle}{\Psi_0(v)} & \text{if } \xi \notin K^*. \end{cases}$$

Therefore, in the particular case $\Psi_0(v) = A\|v\|_1$, taking into account that

$$K^* = \overline{B}_A^\infty(0) := \{\xi \in \mathbb{R}^d : \|\xi\|_\infty \leq A\} \quad \text{with } \|v\|_\infty := \max_{i=1, \dots, d} |v_i|,$$

we retrieve the formula

$$\mathfrak{p}(0, v, \xi) = \|v\|_1 (A \vee \|\xi\|_\infty) \quad (5.16)$$

(here and in what follows, we use the notation $a \vee b$ for $\max\{a, b\}$).

(2) **2-norm vanishing-viscosity:** In this case, we have

$$\mathfrak{p}(0, v, \xi) = \Psi_0(v) + \|v\| \min_{\zeta \in K^*} \|\xi - \zeta\|_*, \quad (5.17)$$

where we have used the notation $\|\zeta\|_* := \sup_{v \neq 0} \frac{\langle \zeta, v \rangle}{\|v\|}$.

The stochastic approximation. We now consider the dissipation potentials Ψ_n from (2.6), i.e.

$$\begin{aligned} \Psi_n(v) &= \sum_{i=1}^d \psi_n(v_i) = \sum_{i=1}^d \frac{v_i}{n} \log \left(\frac{v_i + \sqrt{v_i^2 + e^{-2nA}}}{e^{-nA}} \right) - \frac{1}{n} \sqrt{v_i^2 + e^{-2nA}} + \frac{e^{-nA}}{n}, \\ &\text{with } \Psi_n^*(\xi) = \sum_{i=1}^d \psi_n^*(\xi_i) = \sum_{i=1}^d \frac{e^{-nA}}{n} (\cosh(n\xi_i) - 1). \end{aligned} \quad (5.18)$$

Preliminarily, we observe that

$$\begin{cases} \Psi_n(v) \rightarrow \Psi_0(v) = A\|v\|_1 & \text{for all } v \in \mathbb{R}^d, \text{ and } \Gamma\text{-}\lim_{n \rightarrow \infty} \Psi_n = \Psi_0, \\ \Psi_n^*(\xi) \rightarrow I_{K^*}(\xi) \text{ with } K^* = \overline{B}_A^\infty(0) & \text{for all } \xi \in \mathbb{R}^d, \text{ and } \Gamma\text{-}\lim_{n \rightarrow \infty} \Psi_n^* = \Psi_0^*. \end{cases} \quad (5.19)$$

In order to check the above statement, e.g. for $\Psi_n(v)$, it is sufficient to recall that $\Psi_n(v) = \sum_{i=1}^d \psi_n(v_i)$, and that the real functions $(\psi_n)_n$ pointwise and Γ -converge to the 1-positively homogeneous potential $\psi_0 : \mathbb{R} \rightarrow \mathbb{R}$ given by $\psi_0(v) = A|v|$. We will now prove that the analogue of Proposition 5.6 holds for the potentials from (5.18).

Proposition 5.8. *The dissipation potentials from (5.18) comply with (4.6) and with Hypothesis 4.1, with limiting viscosity contact potential*

$$\mathfrak{p} : [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0, +\infty] \text{ given by } \mathfrak{p}(\tau, v, \xi) := \begin{cases} \Psi_0(v) + I_{K^*}(\xi) & \text{if } \tau > 0, \\ \|v\|_1 (A \vee \|\xi\|_\infty) & \text{if } \tau = 0. \end{cases} \quad (5.20)$$

Proof. We will split the proof in several claims.

Claim 1: (5.20) **holds for** $\tau > 0$. It follows from the Γ -convergence properties in (5.19) that $\mathfrak{p} = \Gamma\text{-}\liminf_{n \rightarrow \infty} \mathfrak{b}_{\Psi_n}$ fulfills $\mathfrak{p}(\tau, v, \xi) \geq \Psi_0(v) + I_{K^*}(\xi)$ for all $(v, \xi) \in \mathbb{R}^d \times \mathbb{R}^d$, if $\tau > 0$. For the converse inequality, for every $\xi \in \mathbb{R}^d$ we take the constant sequence $\xi_n \equiv \xi$ and again choose for fixed $(\tau, v) \in (0, +\infty) \times \mathbb{R}^d$ the sequences $\tau_n \equiv \tau$ and $v_n \equiv v$. The pointwise convergences from (5.19) ensure that

$$\mathfrak{p}(\tau, v, \xi) \leq \limsup_{n \rightarrow \infty} \mathfrak{b}_{\Psi_n}(\tau, v, \xi) = \tau \Psi_0\left(\frac{v}{\tau}\right) + \tau I_{K^*}(\xi) = \Psi_0(v) + I_{K^*}(\xi).$$

Hence we conclude that $\mathfrak{p}(\tau, v, \xi) = \Psi_0(v) + I_{K^*}(\xi)$, i.e. the validity of (5.20) for $\tau > 0$.

Claim 2: (5.20) **holds for** $\tau = 0$ **and** $v = 0$. In this case we have to check that $\mathfrak{p}(0, 0, \xi) = 0$, which is equivalent to showing that $\mathfrak{p}(0, 0, \xi) \leq 0$ as the functional \mathfrak{p} is positive. To this aim, for every fixed $\xi \in \mathbb{R}^d$ we observe that for any null sequence $\tau_n \downarrow 0$

$$\mathfrak{p}(0, 0, \xi) \leq \limsup_{n \rightarrow \infty} \mathfrak{b}_{\Psi_n}(\tau_n, 0, \xi) = \limsup_{n \rightarrow \infty} \tau_n \Psi_n^*(\xi),$$

and then we choose $(\tau_n)_n$ vanishing fast enough in such a way that the lim sup on the right-hand side equals zero.

Claim 3: (5.20) **holds for** $\tau = 0$ **and** $v \neq 0$. We will split the proof in several (sub-)claims. In the following calculations, taking into account that $\Psi_n = \sum_{i=1}^d \psi_n$ and $\Psi_n^* = \sum_{i=1}^d \psi_n^*$ with $\psi_n : \mathbb{R} \rightarrow \mathbb{R}$ and $\psi_n^* : \mathbb{R} \rightarrow \mathbb{R}$

even functions, we will often confine the discussion to the case in which $v = (v_1, \dots, v_d)$ fulfills $v_i \geq 0$ for all $i = 1, \dots, d$, and analogously for $\xi = (\xi_1, \dots, \xi_d)$.

Moreover, we will need to work with the perturbed bipotentials $\mathbf{b}_{\Psi_n}^\delta : [0, +\infty) \times \mathbb{R}^d \times \mathbb{R}^d \rightarrow [0, +\infty]$ given by

$$\mathbf{b}_{\Psi_n}^\delta(\tau, v, \xi) := \begin{cases} \tau \Psi_n\left(\frac{v}{\tau}\right) + \tau \Psi_n^*(\xi) + \tau \delta & \text{for } \tau > 0, \\ 0 & \text{for } \tau = 0, v = 0, \\ +\infty & \text{for } \tau = 0 \text{ and } v \neq 0 \end{cases} \quad (5.21)$$

with $\delta > 0$ fixed. We remark that $\text{Argmin}_{\tau > 0} \mathbf{b}_{\Psi_n}^\delta(\tau, v, \xi) \neq \emptyset$. Indeed, for every fixed $(v, \xi) \in \mathbb{R}^d \times \mathbb{R}^d$ the functional $\tau \mapsto \mathbf{b}_{\Psi_n}^\delta(\tau, v, \xi)$ is convex on $(0, \infty)$ and, since $v \neq 0$, it fulfills $\lim_{\tau \downarrow 0} \mathbf{b}_{\Psi_n}^\delta(\tau, v, \xi) = \lim_{\tau \uparrow \infty} \mathbf{b}_{\Psi_n}^\delta(\tau, v, \xi) = +\infty$ by the superlinear growth property of the functionals Ψ_n , cf. also (3.3). A straightforward calculation also shows that for every $\xi \in \mathbb{R}^d$ the map $v \mapsto \min_{\tau > 0} \mathbf{b}_{\Psi_n}^\delta(\tau, v, \xi)$ is 1-positively homogeneous. Therefore, there exists a closed convex set $K_{n,\delta}^*(\xi)$ such that

$$\min_{\tau > 0} \mathbf{b}_{\Psi_n}^\delta(\tau, v, \xi) = \sup \{ \langle v, w \rangle : w \in K_{n,\delta}^*(\xi) \}. \quad (5.22a)$$

Indeed, it turns out (cf. [MRS12, Thm. A.17]) that

$$K_{n,\delta}^*(\xi) = \{ w \in \mathbb{R}^d : \Psi_n^*(w) \leq \Psi_n^*(\xi) + \delta \}. \quad (5.22b)$$

We need an intermediate estimate before proving the \geq -inequality in (5.20), i.e. (5.24) below.

Claim 3.1: there holds

$$\mathfrak{p}(0, v, \xi) \geq \inf \{ \liminf_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}^\delta(\bar{\tau}_n^\delta, v_n, \xi_n) : v_n \rightarrow v, \xi_n \rightarrow \xi \}, \quad \text{where } \bar{\tau}_n^\delta \in \text{Argmin}_{\tau > 0} \mathbf{b}_{\Psi_n}^\delta(\tau, v_n, \xi_n). \quad (5.23)$$

This follows from

$$\begin{aligned} \mathfrak{p}(0, v, \xi) &= \inf \{ \liminf_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}(\tau_n, v_n, \xi_n) : \tau_n \rightarrow 0, v_n \rightarrow v, \xi_n \rightarrow \xi \} \\ &= \inf \{ \liminf_{n \rightarrow \infty} (\mathbf{b}_{\Psi_n}^\delta(\tau_n, v_n, \xi_n)) - \delta \tau_n : \tau_n \rightarrow 0, v_n \rightarrow v, \xi_n \rightarrow \xi \} \\ &\stackrel{(2)}{\geq} \inf \{ \liminf_{n \rightarrow \infty} \min_{\tau > 0} \mathbf{b}_{\Psi_n}^\delta(\tau, v_n, \xi_n) : v_n \rightarrow v, \xi_n \rightarrow \xi \}, \end{aligned}$$

where (2) follows from the fact that $\lim_{n \rightarrow \infty} \delta \tau_n = 0$ for every vanishing sequence (τ_n) .

Claim 3.2: there holds

$$\mathfrak{p}(0, v, \xi) \geq \|v\|_1 (A \vee \|\xi\|_\infty). \quad (5.24)$$

In view of (5.23), it is sufficient to prove that

$$\inf \{ \liminf_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}^\delta(\bar{\tau}_n^\delta, v_n, \xi_n) : v_n \rightarrow v, \xi_n \rightarrow \xi \} \geq \|v\|_1 (A \vee \|\xi\|_\infty). \quad (5.25)$$

Hence, we fix a sequence $(v_n, \xi_n) \rightarrow (v, \xi)$ and, for n sufficiently big such that $\frac{1}{n} \log d < A$, define $w_n \in \mathbb{R}^d$ by

$$w_n := \left((A \vee \|\xi_n\|_\infty) - \frac{1}{n} \log d, \dots, (A \vee \|\xi_n\|_\infty) - \frac{1}{n} \log d \right).$$

Taking into account the form (2.7) of Ψ_n^* , we estimate

$$\Psi_n^*(w_n) = d \frac{e^{-nA}}{n} (\cosh(n\|w_n\|_\infty) - 1)$$

distinguishing the two cases $\|\xi_n\|_\infty \leq A$ and $\|\xi_n\|_\infty > A$. In the former situation, it is sufficient to observe that $\|w_n\|_\infty \leq A$, so that

$$\Psi_n^*(w_n) \leq d \frac{e^{-nA}}{n} (\cosh(nA) - 1) = \frac{d}{n} \left(\frac{1 + e^{-2nA} - 2e^{-nA}}{2} \right) \leq \frac{d}{n} \leq \delta \quad (5.26a)$$

for n sufficiently big. In the case $\|\xi_n\|_\infty > A$, we use that

$$\begin{aligned}\Psi_n^*(w_n) &= d \frac{e^{-nA}}{n} (\cosh(n\|\xi_n\|_\infty - \log(d)) - 1) \\ &= d \frac{e^{-nA}}{2n} \left(e^{n\|\xi_n\|_\infty - \log d} + e^{-n\|\xi_n\|_\infty + \log d} - 2 \right) \\ &= \frac{e^{-nA}}{2n} \left(e^{n\|\xi_n\|_\infty} + d^2 e^{-n\|\xi_n\|_\infty} - 2d \right) \\ &= \frac{e^{-nA}}{2n} \left(e^{n\|\xi_n\|_\infty} + e^{-n\|\xi_n\|_\infty} - 2d \right) + \frac{e^{-nA}}{2n} (d^2 - 1) e^{-n\|\xi_n\|_\infty} \leq \Psi_n^*(\xi_n) + \delta\end{aligned}\tag{5.26b}$$

for n sufficiently big such that $\frac{d^2-1}{2n} \leq \delta$. All in all, (5.26) gives that

$$\Psi_n^*(w_n) \leq \Psi_n^*(\xi_n) + \delta,$$

which implies that $w_n \in K_{n,\delta}^*(\xi_n)$, for all n sufficiently big. Now, using the representation formula (5.22a) for $\mathbf{b}_{\Psi_n}^\delta(\bar{\tau}_n^\delta, \cdot, \cdot)$, we find

$$\mathbf{b}_{\Psi_n}^\delta(\bar{\tau}_n^\delta, v_n, \xi_n) \geq \langle v_n, w_n \rangle = \|v_n\|_1 (A \vee \|\xi_n\|_\infty) - \frac{1}{n} \log d \|v_n\|_1,$$

where the last equality follows from the fact that $v_n = (v_n^1, \dots, v_n^d)$ fulfills $v_n^i \geq 0$ for all $i = 1, \dots, d$. Hence $\liminf_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}^\delta(\bar{\tau}_n^\delta, v_n, \xi_n) \geq \|v\|_1 (A \vee \|\xi\|_\infty)$ and, since the sequences $(v_n)_n$ and $(\xi_n)_n$ are arbitrary, we conclude (5.25), and thus (5.24).

In order to prove the converse of inequality (5.24), and thus conclude (5.20), we preliminarily need to investigate the properties of the sets $K_{n,\delta}^*$.

Claim 3.3: there holds

$$\forall \delta > 0 \quad \exists n_\delta \in \mathbb{N} \quad \forall n \geq n_\delta \quad \forall \xi \in \mathbb{R}^d \quad \forall w \in K_{n,\delta}^*(\xi) : \quad \|w\|_\infty \leq A \vee \|\xi\|_\infty + \frac{1}{n} \log(2en\delta).\tag{5.27}$$

Indeed, every $w \in K_{n,\delta}^*(\xi)$ fulfills $\Psi_n^*(w) \leq \Psi_n^*(\xi) + \delta$. Using the explicit formula for Ψ_n^* we obtain that

$$\frac{e^{-nA}}{n} \cosh(n\|w\|_\infty) \leq \frac{de^{-nA}}{n} \cosh(n\|\xi\|_\infty) + \delta,$$

whereby

$$\frac{e^{-nA}}{2n} e^{n\|w\|_\infty} \leq \frac{de^{-nA}}{2n} e^{n\|\xi\|_\infty} + \frac{de^{-nA}}{2n} + \delta \leq \frac{de^{-nA}}{n} e^{n\|\xi\|_\infty} + \delta,$$

and thus

$$\|w\|_\infty \leq \frac{1}{n} \log \left(2n\delta e^{nA} + 2de^{n\|\xi\|_\infty} \right).$$

Now, doing some algebraic manipulations on the logarithmic term on the right-hand side we find

$$\begin{aligned}\log \left(2n\delta e^{nA} + 2de^{n\|\xi\|_\infty} \right) &= \log \left(e^{nA + \log n\delta} \left(1 + e^{n(\|\xi\|_\infty - A) + \log d - \log n\delta} \right) \right) + \log 2 \\ &\stackrel{(1)}{\leq} \log \left(1 + e^{n(\|\xi\|_\infty - A)_+} \right) + nA + \log n\delta + \log 2 \\ &\stackrel{(2)}{\leq} n(A \vee \|\xi\|_\infty) + 1 + \log 2n\delta,\end{aligned}$$

where for (1) we have used that $n\delta > d$ for n sufficiently big and for (2) we have estimated $\log(1 + e^{n(\|\xi\|_\infty - A)_+}) = \log(e^{n(\|\xi\|_\infty - A)_+}) + \log(e^{-n(\|\xi\|_\infty - A)_+} + 1) \leq \log(e^{n(\|\xi\|_\infty - A)_+}) + 1$. Then, (5.27) ensues.

Claim 3.4: for every $(v, \xi) \in \mathbb{R}^d \times \mathbb{R}^d$ and all sequences $(v_n)_n, (\xi_n)_n$ with $v_n \rightarrow v$ and $\xi_n \rightarrow \xi$, for every $\bar{\tau}_n^\delta \in \text{Argmin } \mathbf{b}_{\Psi_n}^\delta(\cdot, v_n, \xi_n)$ there holds

$$\lim_{n \rightarrow \infty} \bar{\tau}_n^\delta = 0.\tag{5.28}$$

We distinguish two cases: (1) $\Psi_0^*(\xi) = +\infty$ and (2) $\Psi_0^*(\xi) = 0$.

- (1) In the first case, we have $\liminf_{n \rightarrow \infty} \Psi_n^*(\xi_n) = +\infty$. Then $\bar{\tau}_n^\delta$ must be vanishing to “cancel” the $\tau \Psi_n^*$ -contribution, cf. also the proof of Lemma 4.6.
- (2) In the second case, to show (5.28) we will provide an estimate from above for $\bar{\tau}_n^\delta$ by exploiting the Euler-Lagrange equation for the minimization problem $\min_{\tau > 0} \mathbf{b}_{\Psi_n}^\delta(\tau, v, \xi)$. Namely, observe that $\bar{\tau}_n^\delta$ complies with

$$0 \in \partial_\tau \mathbf{b}_{\Psi_n}^\delta(\cdot, v_n, \xi_n)(\bar{\tau}_n^\delta) = \Psi_n \left(\frac{v_n}{\bar{\tau}_n^\delta} \right) - \left\langle \mathbf{D}\Psi_n \left(\frac{v_n}{\bar{\tau}_n^\delta} \right), \frac{v_n}{\bar{\tau}_n^\delta} \right\rangle + \Psi_n^*(\xi_n) + \delta. \quad (5.29)$$

Using the explicit formula (5.18) for Ψ_n we find

$$\Psi_n \left(\frac{v_n}{\bar{\tau}_n^\delta} \right) - \left\langle \mathbf{D}\Psi_n \left(\frac{v_n}{\bar{\tau}_n^\delta} \right), \frac{v_n}{\bar{\tau}_n^\delta} \right\rangle = \frac{de^{-nA}}{n} - \sum_i \frac{1}{n} \sqrt{\frac{(v_n^i)^2}{(\bar{\tau}_n^\delta)^2} + e^{-2nA}}.$$

Therefore, (5.29) yields

$$n\delta + de^{-nA} + n\Psi_n^*(\xi_n) = \sum_i \sqrt{\frac{(v_n^i)^2}{(\bar{\tau}_n^\delta)^2} + e^{-2nA}} \leq d \sqrt{\frac{\|v_n\|_\infty^2}{(\bar{\tau}_n^\delta)^2} + e^{-2nA}},$$

$$\text{whence } (\bar{\tau}_n^\delta)^2 \leq \frac{d^2 \|v_n\|_\infty^2}{n^2 \delta^2 + n^2 (\Psi_n^*(\xi_n))^2} \rightarrow 0 \quad \text{for } n \rightarrow \infty. \quad (5.30)$$

We are now in a position to conclude the proof of (5.20).

Claim 3.5: there holds

$$\mathbf{p}(0, v, \xi) \leq \|v\|_1 (A \vee \|\xi\|_\infty). \quad (5.31)$$

We will in fact prove that

$$\forall \xi \in \mathbb{R}^d \quad \exists (\xi_n)_n \subset \mathbb{R}^d : \xi_n \rightarrow \xi \quad \text{and}$$

$$\forall v \in \mathbb{R}^d \quad \exists (\tau_n, v_n)_n \text{ s.t. } \begin{cases} \tau_n \rightarrow 0, \\ v_n \rightarrow v, \\ \limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}(\tau_n, v_n, \xi_n) \leq \|v\|_1 (A \vee \|\xi\|_\infty). \end{cases} \quad (5.32)$$

Taking into account that $\mathbf{p} = \Gamma\text{-lim inf}_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}$, we will then conclude (5.31). To check (5.32), let us choose the constant recovery sequences $\xi_n \equiv \xi$ and $v_n \equiv v$, and let $\tau_n := \bar{\tau}_n^\delta \in \text{Argmin}_{\tau > 0} \mathbf{b}_{\Psi_n}^\delta(\tau, v, \xi)$. By the previous Claim 3.4, we have that $\tau_n \downarrow 0$. Now, in view of the representation formula (5.22a) for $\min_{\tau > 0} \mathbf{b}_{\Psi_n}^\delta(\tau, v, \xi)$, we can construct a sequence $\{\tilde{\xi}_n\} \subset K_{n,\delta}^*(\xi)$ such that

$$\mathbf{b}_{\Psi_n}^\delta(\bar{\tau}_n^\delta, v, \xi) \leq \langle v, \tilde{\xi}_n \rangle + \frac{1}{n} \leq \|v\|_1 (A \vee \|\xi\|_\infty) + \frac{\|v\|_1}{n} \log(2en\delta) + \frac{1}{n},$$

where the second estimate ensues from (5.27). Therefore $\limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}^\delta(\bar{\tau}_n^\delta, v, \xi) \leq \|v\|_1 (A \vee \|\xi\|_\infty)$. Since $\limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}^\delta(\bar{\tau}_n^\delta, v, \xi) = \limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}(\bar{\tau}_n^\delta, v, \xi)$ as the sequence $(\bar{\tau}_n^\delta)_n$ is vanishing, we conclude the desired claim (5.32), and thus (5.31).

This finishes the proof of Proposition 5.8. \square

5.3. The Γ -limsup result. For the Γ -limsup counterpart to Theorem 5.2, where we now consider the *strict* topology in $\text{BV}([0, T]; \mathbb{R}^d)$, we will focus on the 1-positively homogeneous potential

$$\Psi_0(v) = A\|v\|_1 \quad \text{with } A > 0,$$

and the two following *specific* approximations of Ψ_0 :

vanishing viscosity: the dissipation potentials Ψ_n are obtained by augmenting Ψ_0 by a quadratic term involving a (possibly) different norm $\|\cdot\|$ (cf. 5.12), i.e.

$$\Psi_n(v) = A\|v\|_1 + \frac{\varepsilon_n}{2}\|v\|^2 \text{ with } \varepsilon_n \downarrow 0, \quad (5.33)$$

$$\text{with limiting viscosity contact potential } \mathfrak{p}(\tau, v, \xi) = \begin{cases} \Psi_0(v) + I_{K^*}(\xi) & \text{if } \tau > 0, \\ \Psi_0(v) + \|v\| \min_{\zeta \in K^*} \|\xi - \zeta\|_* & \text{if } \tau = 0; \end{cases} \quad (5.33)$$

stochastic approximation: the dissipation potentials Ψ_n are given by (5.18), with viscosity contact potential

$$\mathfrak{p}(\tau, v, \xi) = \begin{cases} \Psi_0(v) + I_{K^*}(\xi) & \text{if } \tau > 0, \\ \|v\|_1 (A \vee \|\xi\|_\infty) & \text{if } \tau = 0. \end{cases} \quad (5.34)$$

Finally, let us mention in advance that, like in [BP16], for the limsup-result we will need to impose some enhanced regularity for $\mathcal{E}(t, \cdot)$, namely

$$\begin{aligned} \exists C_E > 0 \quad \forall (t, u) \in [0, T] \times \mathbb{R}^d : \|\mathrm{D}\mathcal{E}(t, u)\| \leq C_E \quad \text{and } \mathrm{D}\mathcal{E}(\cdot, u) \text{ is uniformly Lipschitz continuous, i.e.} \\ \exists L_E > 0 \quad \forall t_1, t_2 \in [0, T] \quad \forall u \in \mathbb{R}^d : \quad \|\mathrm{D}\mathcal{E}(t_1, u) - \mathrm{D}\mathcal{E}(t_2, u)\| \leq L_E |t_1 - t_2|. \end{aligned} \quad (5.35)$$

Theorem 5.9. *Let \mathcal{E} comply with (E) and with (5.35), and let the dissipation potentials $(\Psi_n)_n$ be given either by (5.33) or by (5.18), with associated limiting bipotential \mathfrak{p} from (5.33) or (5.34), respectively.*

Then, for every $u \in \mathrm{BV}([0, T]; \mathbb{R}^d)$ there exists a sequence $(u_n)_n \subset \mathrm{AC}([0, T]; \mathbb{R}^d)$, converging to u in the strict topology of $\mathrm{BV}([0, T]; \mathbb{R}^d)$, such that

$$\limsup_{n \rightarrow \infty} \mathcal{J}_{\Psi_n, \mathcal{E}}(u_n) \leq \mathcal{J}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(u). \quad (5.36)$$

Remark 5.10. In [BP16], which focused on *one-dimensional* rate-independent systems, the Γ -lim sup result was obtained in a much larger generality, for a class of dissipation potentials Ψ_n fulfilling suitable growth conditions and other properties. Such properties are satisfied in the two abovementioned particular cases (5.18) & (5.33).

We believe that, to some extent, the results in [BP16] could be extended to the present multi-dimensional context. Still, we have preferred to confine the discussion to the vanishing-viscosity and the stochastic approximations, in order to develop more explicit calculations than those in the proof of [BP16, Thm. 4.2], significantly exploiting the specific structure of these examples.

Nonetheless, we will briefly comment in Remark 6.2 ahead how the Γ -lim sup result in the vanishing-viscosity case in fact extends to the broader class of dissipation potentials

$$\Psi_n(v) = A\|v\|_1 + \frac{\varepsilon_n^{p-1}}{p}\|v\|^p \text{ with } \varepsilon_n \downarrow 0, \quad p \in (1, +\infty), \quad (5.37)$$

which still have the limiting viscosity contact potential \mathfrak{p} from (5.33).

Clearly, Theorems 5.2 and 5.9 yield the *Mosco-convergence* of the functionals $(\mathcal{J}_{\Psi_n, \mathcal{E}})_n$ to $\mathcal{J}_{\Psi_0, \mathfrak{p}, \mathcal{E}}$, in the vanishing-viscosity and stochastic cases.

Corollary 5.11. *Let \mathcal{E} comply with (E) and with (5.35), and let the dissipation potentials $(\Psi_n)_n$ be given either by (5.18), or by (5.33).*

Then, the functionals $(\mathcal{J}_{\Psi_n, \mathcal{E}})_n$ MOSCO-converge to $\mathcal{J}_{\Psi_0, \mathfrak{p}, \mathcal{E}}$ with respect to the weak-strict topology of $\mathrm{BV}([0, T]; \mathbb{R}^d)$.

In the spirit of Theorem 5.3 we also have the following straightforward consequence of Theorem 5.9, of Lemma 3.1, and of Proposition 3.7. Theorem 5.12, whose proof is omitted, is a *reverse approximation* result.

Theorem 5.12. *Let \mathcal{E} comply with (E) and with (5.35). Consider the 1-homogeneous potential $\Psi_0(v) = A\|v\|_1$.*

Consider the viscosity contact potential \mathfrak{p} from (5.33). Then, for every Balanced Viscosity solution $u \in \mathrm{BV}([0, T]; \mathbb{R}^d)$ to the rate-independent system $(\Psi_0, \mathfrak{p}, \mathcal{E})$ there exists a sequence $(u_n)_n \subset \mathrm{AC}([0, T]; \mathbb{R}^d)$ of solutions to the gradient systems (Ψ_n, \mathcal{E}) , with the dissipation potentials $(\Psi_n)_n$ given by $\Psi_n(v) = A\|v\|_1 + \frac{\varepsilon_n}{2}\|v\|^2$

for all $n \in \mathbb{N}$, where $(\varepsilon_n)_n \subset (0, +\infty)$ is any vanishing sequence as $n \rightarrow \infty$, such that $u_n \rightarrow u$ as $n \rightarrow \infty$ strictly in $\text{BV}([0, T]; \mathbb{R}^d)$.

A completely analogous statement holds with the viscosity contact potential \mathbf{p} from (5.34), and the dissipation potentials $(\Psi_n)_n$ from (5.18).

6. PROOFS

In what follows, we will denote by C a generic positive constant independent of n , whose meaning may vary even within the same line.

We will just outline the argument for the proof of **Proposition 5.1**, referring to the argument for [MRS12, Thm. 4.1] (see also [BP16, Thm. 4.2]) for all details. Combining the information that $\mathcal{J}_{\Psi_n, \mathcal{E}}(u_n) \leq C$ with the power control condition from (E), we find that

$$\int_0^T (\Psi_n(\dot{u}(s)) + \Psi_n^*(-D\mathcal{E}(s, u(s)))) \, ds + \mathcal{E}(T, u_n(T)) \leq C + \int_0^T C_1 |\mathcal{E}(s, u_n(s))| \, ds,$$

where we have also used that $\|u_n(0)\| \leq C$, and thus $\sup_n |\mathcal{E}(0, u_n(0))| \leq C$. Taking into account that both Ψ_n and Ψ_n^* are positive, via the Gronwall Lemma we deduce from the above inequality that $\sup_{t \in [0, T]} |\mathcal{E}(t, u_n(t))| \leq C$, whence $\sup_{t \in [0, T]} |\partial_t \mathcal{E}(t, u_n(t))| \leq C$. Hence

$$\int_0^T (\Psi_n(\dot{u}_n(s)) + \Psi_n^*(-D\mathcal{E}(s, u(s)))) \, ds \leq C,$$

which implies, thanks to the coercivity (5.4), that $\text{Var}(u_n; [0, T]) \leq C$. Then, the thesis readily follows from the Helly theorem. \square

Before developing the proof of Theorem 5.2, we preliminarily give the following lower semicontinuity result, in the spirit of [MRS12, Lemma 4.3]).

Lemma 6.1. *Let $m, d \geq 1$ and $\mathfrak{F}_n, \mathfrak{F}_\infty : \mathbb{R}^m \times \mathbb{R}^d \rightarrow [0, +\infty)$ be normal integrands (i.e., for $n \in \mathbb{N} \cup \{\infty\}$ the functionals \mathfrak{F}_n are measurable, and for every $v \in \mathbb{R}^m$ the mappings $\xi \mapsto \mathfrak{F}_n(v, \xi)$ are lower semicontinuous) such that*

- (1) *for fixed $\xi \in \mathbb{R}^d$ the functionals $\mathfrak{F}_n(\cdot, \xi)$ are convex for every $n \in \mathbb{N} \cup \{\infty\}$,*
- (2) *there holds*

$$\Gamma\text{-}\liminf_{n \rightarrow \infty} \mathfrak{F}_n \geq \mathfrak{F}_\infty \quad \text{in } \mathbb{R}^m \times \mathbb{R}^d. \quad (6.1)$$

Let I be a bounded interval in \mathbb{R} and let $w_n, w : I \rightarrow \mathbb{R}^m$ fulfill $w_n \rightarrow w$ in $L^1(I; \mathbb{R}^m)$, and $\xi_n, \xi : I \rightarrow \mathbb{R}^d$ fulfill $\xi_n(s) \rightarrow \xi(s)$ for almost all $s \in I$. Then

$$\liminf_{n \rightarrow \infty} \int_I \mathfrak{F}_n(w_n(s), \xi_n(s)) \, ds \geq \int_I \mathfrak{F}_\infty(w(s), \xi(s)) \, ds. \quad (6.2)$$

Proof. We introduce the functional

$$\bar{\mathfrak{F}} : \mathbb{N} \cup \{\infty\} \times \mathbb{R}^m \times \mathbb{R}^d, \quad \bar{\mathfrak{F}}(n, w, \xi) := \begin{cases} \mathfrak{F}_n(w, \xi) & \text{for } n \in \mathbb{N}, \\ \mathfrak{F}_\infty(w, \xi) & \text{for } n = \infty. \end{cases}$$

It follows from (6.1) that $\bar{\mathfrak{F}}$ is lower semicontinuous on $\mathbb{N} \cup \{\infty\} \times \mathbb{R}^m \times \mathbb{R}^d$, hence it is a positive normal integrand. Then, (6.2) follows from the Ioffe Theorem, cf. [Iof77] and also, e.g., [Val90, Thm. 21]. \square

Proof of Theorem 5.2. Let $(u_n)_n \subset \text{BV}([0, T]; \mathbb{R}^d)$ be a sequence weakly converging to $u \in \text{BV}([0, T], \mathbb{R}^d)$. We may suppose that $\liminf_{n \rightarrow \infty} \mathcal{J}_{\Psi_n, \mathcal{E}}(u_n) < +\infty$, as otherwise there is nothing to prove. Therefore, up to a subsequence we have $\mathcal{J}_{\Psi_n, \mathcal{E}}(u_n) \leq C$, in particular yielding that $u_n \in \text{AC}([0, T]; \mathbb{R}^d)$ for every $n \in \mathbb{N}$. With the very same arguments as in the proof of Prop. 5.1, also based on the power control (E), we see that each contribution to $\mathcal{J}_{\Psi_n, \mathcal{E}}(u_n)$ is itself bounded. Convergences (5.6) follow from the pointwise convergence of $(u_n)_n$, the fact that $\mathcal{E} \in C^1([0, T] \times \mathbb{R}^d)$, and the Lebesgue dominated convergence theorem, recalling that $(u_n)_n$ is bounded in $L^\infty(0, T; \mathbb{R}^d)$. Moreover, we have that $\text{D}\mathcal{E}(t, u_n(t)) \rightarrow \text{D}\mathcal{E}(t, u(t))$ for every $t \in [0, T]$. Then, taking into account that the functionals $(\Psi_n^*)_n$ Γ -converge to Ψ_0^* , we can apply Lemma 6.1 to the functionals $\mathfrak{F}_n(w, \xi) := \Psi_n^*(\xi)$ and $\mathfrak{F}(w, \xi) := \Psi_0^*(\xi)$ to obtain

$$\liminf_{n \rightarrow \infty} \int_0^T \Psi_n^*(-\text{D}\mathcal{E}(t, u_n(t))) dt \geq \int_0^T \Psi_0^*(-\text{D}\mathcal{E}(t, u(t))) dt, \quad (6.3)$$

whence $-\text{D}\mathcal{E}(t, u(t)) \in K^*$ for a.a. $t \in (0, T)$.

Define the non-negative finite measures on $[0, T]$

$$\nu_n := \Psi_n(\dot{u}_n(\cdot)) \mathcal{L}^1 + \Psi_n^*(-\text{D}\mathcal{E}(\cdot, u_n(\cdot))) \mathcal{L}^1 \doteq \mu_n + \eta_n.$$

Up to extracting a subsequence, we can suppose that they weakly* converge in duality with $C^0([0, T])$ to a positive measure

$$\nu = \mu + \eta \quad \text{with } \eta \geq \Psi_0^*(-\text{D}\mathcal{E}(\cdot, u(\cdot))) \mathcal{L}^1.$$

Let us now preliminarily show that

$$\nu \geq \Psi_0(\dot{u}) \mathcal{L}^1 + \mu_{\Psi_0, C}. \quad (6.4)$$

For this, we shall in fact observe that $\mu \geq \Psi_0(\dot{u}) \mathcal{L}^1 + \mu_{\Psi_0, C}$. This will follow upon proving that

$$\mu([\alpha, \beta]) = \lim_{n \rightarrow \infty} \int_\alpha^\beta \Psi_n(\dot{u}_n(t)) dt \geq \text{Var}_{\Psi_0}(u; [\alpha, \beta]) \quad \text{for every } [\alpha, \beta] \subset [0, T]. \quad (6.5)$$

Indeed, let us fix a partition $t_0 = \alpha < t_1 < \dots < t_k = \beta$ of $[\alpha, \beta]$ and notice that

$$\begin{aligned} \lim_{n \rightarrow \infty} \int_\alpha^\beta \Psi_n(\dot{u}_n(t)) dt &= \lim_{n \rightarrow \infty} \sum_{m=1}^k \int_{t_{m-1}}^{t_m} \Psi_n(\dot{u}_n(t)) dt \stackrel{(1)}{\geq} \liminf_{n \rightarrow \infty} \sum_{m=1}^k (t_m - t_{m-1}) \Psi_n \left(\frac{\int_{t_{m-1}}^{t_m} \dot{u}_n(t) dt}{t_m - t_{m-1}} \right) \\ &= \liminf_{n \rightarrow \infty} \sum_{m=1}^k (t_m - t_{m-1}) \Psi_n \left(\frac{u_n(t_m) - u_n(t_{m-1})}{t_m - t_{m-1}} \right) \\ &\stackrel{(2)}{\geq} \sum_{m=1}^k (t_m - t_{m-1}) \Psi_0 \left(\frac{u(t_m) - u(t_{m-1})}{t_m - t_{m-1}} \right) \\ &\stackrel{(3)}{=} \sum_{m=1}^k \Psi_0(u(t_m) - u(t_{m-1})), \end{aligned}$$

where (1) follows from the Jensen inequality, (2) from the fact that the potentials $(\Psi_n)_n$ Γ -converge to Ψ_0 (cf. Lemma 4.4), and (3) from the 1-positive homogeneity of Ψ_0 . Since the partition of $[\alpha, \beta]$ is arbitrary, we conclude (6.5).

However, we need to improve (6.4) by obtaining a finer characterization for the jump part of ν . We will in fact prove that

$$\nu(\{t\}) \geq \Delta_{p, \mathcal{E}}(t; u(t_-), u(t_+)) \quad \text{for every } t \in \text{J}_u \quad (6.6)$$

by adapting the argument in the proof of [MRS16, Prop. 7.3]. To this end, for fixed $t \in \text{J}_u$ let us pick two sequences $h_n^- \uparrow t$ and $h_n^+ \downarrow t$ such that $u_n(h_n^-) \rightarrow u(t_-)$ and $u_n(h_n^+) \rightarrow u(t_+)$. Define $s_n : [h_n^-, h_n^+] \rightarrow \mathbb{R}$ by

$$s_n(h) := c_n \left(h - h_n^- + \int_{h_n^-}^h (\Psi_n(\dot{u}_n(t)) + \Psi_n^*(-\text{D}\mathcal{E}(t, u_n(t)))) dt \right), \quad h \in [h_n^-, h_n^+], \quad (6.7)$$

where the normalization constant c_n is chosen in such a way that $\mathfrak{s}_n(h_n^+) = 1$. Therefore, \mathfrak{s}_n takes values in $[0, 1]$. Observe that for every n the function \mathfrak{s}_n is strictly increasing and thus invertible, and let

$$\mathfrak{t}_n := \mathfrak{s}_n^{-1} : [0, 1] \rightarrow [h_n^-, h_n^+] \quad \text{and} \quad \vartheta_n := u_n \circ \mathfrak{t}_n.$$

There holds

$$\dot{\mathfrak{t}}_n(s) + \|\dot{\vartheta}_n\|_1(s) = \frac{1 + \|\dot{u}_n\|_1(\mathfrak{t}_n(s))}{c_n (1 + \Psi_n(\dot{u}_n(\mathfrak{t}_n(s))) + \Psi_n^*(-D\mathcal{E}(\mathfrak{t}_n(s), u_n(\mathfrak{t}_n(s)))))} \leq C \quad \text{for a.a. } s \in (0, 1). \quad (6.8)$$

Now, by the upper semicontinuity property of the weak*-convergence of measures on closed sets we have

$$\begin{aligned} \nu(\{t\}) &\geq \limsup_{n \rightarrow \infty} \nu_n([h_n^-, h_n^+]) \geq \liminf_{n \rightarrow \infty} \int_{h_n^-}^{h_n^+} (\Psi_n(\dot{u}_n(t)) + \Psi_n^*(-D\mathcal{E}(t, u_n(t)))) dt \\ &\stackrel{(1)}{=} \liminf_{n \rightarrow \infty} \int_0^1 (\Psi_n(\dot{u}_n(\mathfrak{t}_n(s))) + \Psi_n^*(-D\mathcal{E}(\mathfrak{t}_n(s), u_n(\mathfrak{t}_n(s)))) \dot{\mathfrak{t}}_n(s) ds \\ &\stackrel{(2)}{=} \liminf_{n \rightarrow \infty} \int_0^1 \mathfrak{b}_{\Psi_n}(\dot{\mathfrak{t}}_n(s), \dot{\vartheta}_n(s), -D\mathcal{E}(\mathfrak{t}_n(s), \vartheta_n(s))) ds \end{aligned} \quad (6.9)$$

where (1) follows from a change of variables, and (2) from the very definition (4.1) of \mathfrak{b}_{Ψ_n} . Now, it follows from (6.8) and from the fact that the range of \mathfrak{t}_n is $[h_n^-, h_n^+]$ that there exists $(\mathfrak{t}, \vartheta) \in C_{\text{lip}}^0([0, 1]; [0, T] \times \mathbb{R}^d)$ such that, up to a not relabeled subsequence,

$$\begin{aligned} \mathfrak{t}_n(s) \rightarrow \mathfrak{t}(s) \equiv t, \quad \vartheta_n(s) \rightarrow \vartheta(s) \quad \text{for all } s \in [0, 1], \quad \dot{\mathfrak{t}}_n \rightharpoonup^* 0 \text{ in } L^\infty(0, 1), \quad \dot{\vartheta}_n \rightharpoonup^* \dot{\vartheta} \text{ in } L^\infty(0, 1; \mathbb{R}^d), \\ \text{so that } \vartheta(0) = \lim_{n \rightarrow \infty} u_n(h_n^-) = u(t_-) \text{ and } \vartheta(1) = \lim_{n \rightarrow \infty} u_n(h_n^+) = u(t_+). \end{aligned} \quad (6.10)$$

Therefore, applying Lemma 6.1 above with the choices $m = d + 1$ and, for $w = (\tau, v) \in \mathbb{R} \times \mathbb{R}^d$, with $\mathfrak{F}_n(w, \xi) = \mathfrak{F}_n(\tau, v, \xi) := \mathfrak{b}_{\Psi_n}(\tau, v, \xi)$ and $\mathfrak{F}_\infty(w, \xi) := \mathfrak{p}(\tau, v, \xi)$ (where we still denote by \mathfrak{b}_{Ψ_n} and by \mathfrak{p} their extensions to $\mathbb{R} \times \mathbb{R}^d \times \mathbb{R}^d$ by infinity), and taking into account (4.2) from Hyp. 4.1, which ensures the validity of condition (6.1) in Lemma 6.1, we conclude

$$\liminf_{n \rightarrow \infty} \int_0^1 \mathfrak{b}_{\Psi_n}(\dot{\mathfrak{t}}_n(s), \dot{\vartheta}_n(s), -D\mathcal{E}(\mathfrak{t}_n(s), \vartheta_n(s))) ds \geq \int_0^1 \mathfrak{p}(0, \dot{\vartheta}(s), -D\mathcal{E}(t, \vartheta(s))) ds \geq \Delta_{\mathfrak{p}, \mathcal{E}}(t; u(t_-), u(t_+)).$$

Similarly, we prove that

$$\limsup_{n \rightarrow \infty} \nu_n([h_n^-, t]) \geq \Delta_{\mathfrak{p}, \mathcal{E}}(t; u(t_-), u(t)), \quad \limsup_{n \rightarrow \infty} \nu_n([t, h_n^+]) \geq \Delta_{\mathfrak{p}, \mathcal{E}}(t; u(t), u(t_+)).$$

Repeating the very same arguments as in the proof of [MRS16, Prop. 7.3], we ultimately find that

$$\liminf_{n \rightarrow \infty} \int_s^t (\Psi_n(\dot{u}_n(r)) + \Psi_n^*(-D\mathcal{E}(r, u_n(r)))) dr \geq \text{Var}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(u; [s, t]) \quad \text{for every } 0 \leq s \leq t \leq T,$$

whence (5.7) also in view of (6.3). This concludes the proof. \square

Proof of Theorem 5.3. Let $u \in \text{BV}([0, T]; \mathbb{R}^d)$ be a limit point of the sequence $(u_n)_n \subset \text{AC}([0, T]; \mathbb{R}^d)$. It follows from the lower-semicontinuity property (5.5) that $\mathcal{J}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(u) = 0$, hence by Prop. 3.7 u is a Balanced Viscosity solution to $(\Psi_0, \mathfrak{p}, \mathcal{E})$. Moreover, for every $0 \leq s \leq t \leq T$ we have that

$$\begin{aligned} &\limsup_{n \rightarrow \infty} \int_s^t (\Psi_n(\dot{u}_n(r)) + \Psi_n^*(-D\mathcal{E}(r, u_n(r)))) dr \\ &\stackrel{(1)}{\leq} \limsup_{n \rightarrow \infty} \left(\mathcal{E}(s, u_n(s)) - \mathcal{E}(t, u_n(t)) + \int_s^t \partial_t \mathcal{E}(r, u_n(r)) dr + \varepsilon_n \right) \\ &\stackrel{(2)}{=} \mathcal{E}(s, u(s)) - \mathcal{E}(t, u(t)) + \int_s^t \partial_t \mathcal{E}(r, u(r)) dr \\ &\stackrel{(3)}{=} \text{Var}_{\Psi_0, \mathfrak{p}, \mathcal{E}}(u; [s, t]) + \int_s^t \Psi_0^*(-D\mathcal{E}(t, u(r))) dr \end{aligned}$$

where (1) follows from $\mathcal{J}_{\Psi_n}(u_n) \leq \varepsilon_n$, (2) from convergences (5.6), and (3) from the fact that $\mathcal{J}_{\Psi_0, \mathbf{p}, \mathcal{E}}(u) = 0$. Combining this with (5.7), we conclude the enhanced convergence properties (5.8). \square

Proof of Theorem 5.9. Given $u \in \text{BV}([0, T], \mathbb{R}^d)$, we will construct a sequence $(u_n)_n \subset \text{AC}([0, T]; \mathbb{R}^d)$ such that $u_n \rightarrow u$ strictly in $\text{BV}([0, T]; \mathbb{R}^d)$ and

$$\limsup_{n \rightarrow \infty} \mathcal{J}_{\Psi_n, \mathcal{E}}(u_n) \leq \mathcal{J}_{\Psi_0, \mathbf{p}, \mathcal{E}}(u). \quad (6.11)$$

We split the proof of in several steps; for Steps 1–4, we suitably adapt the arguments from the proof of [BP16, Thm. 4.2].

Step 1: reparameterization. First we reparameterize the curve u , in terms of a new time-like parameter s on a domain $[0, S]$. The aim is to expand the jumps in u into smooth connections. Following [MRS12, Prop. 6.9], we define

$$\mathbf{s}(t) := t + \text{Var}_{\Psi_0, \mathbf{p}, \mathcal{E}}(u; [0, t]).$$

Then there exists a Lipschitz parameterization $(\mathbf{t}, \mathbf{u}) : [0, S] \rightarrow [0, T] \times \mathbb{R}$ such that \mathbf{t} is non-decreasing,

$$\mathbf{t}(\mathbf{s}(t)) = t \quad \text{and} \quad \mathbf{u}(\mathbf{s}(t)) = u(t) \quad \text{for every } t \in [0, T], \quad (6.12)$$

and such that

$$\int_0^S \mathbf{p}(\dot{\mathbf{t}}(s), \dot{\mathbf{u}}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) ds = \text{Var}_{\Psi_0, \mathbf{p}, \mathcal{E}}(u; [0, T]) + \int_0^T \Psi_0^*(-D\mathcal{E}(t, u(t))) dt. \quad (6.13)$$

Moreover, it also holds that

$$\text{Var}_{\Psi_0}(\mathbf{u}; [0, S]) = \text{Var}_{\Psi_0}(u; [0, T]). \quad (6.14)$$

Step 2: preliminary remarks. Since we will construct a sequence $(u_n)_n$ strictly (and in particular pointwise) converging to u in $\text{BV}([0, T]; \mathbb{R}^d)$, thanks to the smoothness of \mathcal{E} (cf. (E)), we will have for the first three contributions to $\mathcal{J}_{\Psi_n, \mathcal{E}}(u_n)$

$$\mathcal{E}(T, u_n(T)) - \mathcal{E}(0, u_n(0)) - \int_0^T \partial_t \mathcal{E}(t, u_n(t)) dt \rightarrow \mathcal{E}(T, u(T)) - \mathcal{E}(0, u(0)) - \int_0^T \partial_t \mathcal{E}(t, u(t)) dt$$

as $n \rightarrow \infty$. Therefore, in order to prove (6.11) it will be sufficient to focus on the other terms in $\mathcal{J}_{\Psi_n, \mathcal{E}}$ and $\mathcal{J}_{\Psi_0, \mathbf{p}, \mathcal{E}}$. In view of (6.13), it will be sufficient to prove that

$$\limsup_{n \rightarrow \infty} \int_0^T [\Psi_n(\dot{u}_n(t)) + \Psi_n^*(D\mathcal{E}(t, u_n(t)))] dt \leq \int_0^S \mathbf{p}(\dot{\mathbf{t}}(s), \dot{\mathbf{u}}(s), D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) ds. \quad (6.15)$$

Step 3: definition of the new time \mathbf{t}_n and of the recovery sequence u_n . For the sake of simplicity, in what follows we construct a recovery sequence for a curve u with jumps only at 0 and T , postponing to the end of the proof (cf. Step 7), the discussion of the case of a curve with countably many jumps. We define u_n by first perturbing the time variable \mathbf{t} : we fix $\delta > 0$ and consider a selection

$$\tau_n^\delta(s) \in \underset{\tau > 0}{\text{Argmin}} \mathbf{b}_{\Psi_n}^\delta(\tau, \dot{\mathbf{u}}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \quad (6.16)$$

with $\mathbf{b}_{\Psi_n}^\delta$ given by (5.21). We define $\mathbf{t}_n : [0, S] \rightarrow [0, T_n]$ as the solution of the differential equation

$$\mathbf{t}_n(0) = 0, \quad \dot{\mathbf{t}}_n(s) = \dot{\mathbf{t}}(s) \vee \tau_n^\delta(s). \quad (6.17)$$

Observe that $\dot{\mathbf{t}}(s) = 0$ in $[0, \mathbf{s}(0^+)] \cup [\mathbf{s}(T^-), S]$, but we can assume that $|\dot{\mathbf{u}}(s)| > 0$ on $[0, \mathbf{s}(0^+)] \cup [\mathbf{s}(T^-), S]$. This will be sufficient to guarantee that $\underset{\tau > 0}{\text{Argmin}} \mathbf{b}_{\Psi_n}^\delta(\tau, \dot{\mathbf{u}}(s), D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \neq \emptyset$ for $s \in [0, \mathbf{s}(0^+)] \cup [\mathbf{s}(T^-), S]$. Thus, τ_n^δ shall be well defined on the latter set. On the other hand, for $s \in [\mathbf{s}(0^+), \mathbf{s}(T^-)]$, we

have $\dot{\mathbf{t}}(s) = \frac{1}{\dot{\mathbf{s}}(t)} \Big|_{t=\mathbf{t}(s)} > 0$. All in all, $\dot{\mathbf{t}}_n(s) > 0$ for all $s \in [0, S]$. The range of \mathbf{t}_n is $[0, T_n]$, with $T_n \geq T$; since the recovery sequence u_n has to be defined on the interval $[0, T]$, we rescale \mathbf{t}_n by

$$\lambda_n := \frac{T_n}{T} \geq 1, \quad (6.18)$$

and define our recovery sequence as follows:

$$u_n(t) := \mathbf{u}(\mathbf{t}_n^{-1}(t\lambda_n)), \quad \text{so that} \quad \dot{u}_n(t) = \frac{\dot{\mathbf{u}}}{\dot{\mathbf{t}}_n}(\mathbf{t}_n^{-1}(t\lambda_n)) \lambda_n. \quad (6.19)$$

Now we substitute the explicit formula for u_n , we perform a change of variable and obtain

$$\begin{aligned} & \int_0^T \left(\Psi_n(\dot{u}_n(t)) + \Psi_n^*(t, -D\mathcal{E}(t, u_n(t))) \right) dt \\ &= \int_0^T \left(\Psi_n \left(\frac{\dot{\mathbf{u}}}{\dot{\mathbf{t}}_n}(\mathbf{t}_n^{-1}(t\lambda_n)) \lambda_n \right) + \Psi_n^* \left(-D\mathcal{E}(t, \mathbf{u}(\mathbf{t}_n^{-1}(t\lambda_n))) \right) \right) dt \\ &= \int_0^S \left(\Psi_n \left(\frac{\dot{\mathbf{u}}(s)}{\dot{\mathbf{t}}_n(s)} \lambda_n \right) + \Psi_n^* \left(-D\mathcal{E}(\mathbf{t}_n(s)\lambda_n^{-1}, \mathbf{u}(s)) \right) \right) \frac{\dot{\mathbf{t}}_n(s)}{\lambda_n} ds, \end{aligned}$$

so that

$$\int_0^T \left(\Psi_n(\dot{u}_n(t)) + \Psi_n^*(t, -D\mathcal{E}(t, u_n(t))) \right) dt = \int_0^S \mathbf{b}_{\Psi_n}(\lambda_n^{-1}\dot{\mathbf{t}}_n(s), \dot{\mathbf{u}}(s), -D\mathcal{E}(\mathbf{t}_n(s)\lambda_n^{-1}, \mathbf{u}(s))) ds.$$

Step 4: Strict convergence of $(u_n)_n$. Recall that we need to prove the pointwise convergence $u_n(t) \rightarrow u(t)$ for all $t \in [0, T]$ and the convergence of the variations. For this, it will be crucial to have the following property, that shall be verified (even uniformly w.r.t. $s \in [0, S]$) both in the stochastic (cf. (6.24)), and in the vanishing-viscosity cases (cf. (6.39)):

$$\tau_n^\delta(s) \rightarrow 0 \quad \text{as } n \rightarrow \infty \quad \text{for a.a. } s \in (0, S). \quad (6.20)$$

This shall imply that $\dot{\mathbf{t}}_n(s) \rightarrow \dot{\mathbf{t}}(s)$ for almost all $s \in (0, S)$, and then it will hold

$$\mathbf{t}_n(s) \rightarrow \mathbf{t}(s) \quad \text{for every } s \in [0, S] \quad \implies \quad \lambda_n \rightarrow 1, \quad \mathbf{t}_n^{-1}(t\lambda_n) \rightarrow \mathbf{s}(t) \quad \text{for every } t \in [0, T].$$

Moreover, $\dot{\mathbf{t}}_n(s) > 0$ implies that $\mathbf{t}_n^{-1}(0) = 0$ and $\mathbf{t}_n^{-1}(T_n) = S$, and so we will have the desired pointwise convergence

$$u_n(t) = \mathbf{u}(\mathbf{t}_n^{-1}(t\lambda_n)) \rightarrow \mathbf{u}(\mathbf{s}(t)) \stackrel{(6.12)}{=} u(t) \quad \text{for every } t \in [0, T].$$

The convergence of the variations will be automatic, since by definition of u_n we will have

$$\int_0^T A \|\dot{u}_n(t)\|_1 dt = \int_0^S A \|\dot{\mathbf{u}}(s)\|_1 ds = \text{Var}_{\Psi_0}(\mathbf{u}; [0, S]) \stackrel{(6.14)}{=} \text{Var}_{\Psi_0}(u; [0, T]).$$

In view of the above observations, from now on we can concentrate on the proof of the lim sup estimate (6.15).

Step 5: strategy for (6.15). First of all, we will show the following *pointwise* lim sup-inequality

$$\limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}(\lambda_n^{-1}\dot{\mathbf{t}}_n(s), \dot{\mathbf{u}}(s), -D\mathcal{E}(\mathbf{t}_n(s)\lambda_n^{-1}, \mathbf{u}(s))) \leq \mathbf{p}(\dot{\mathbf{t}}(s), \dot{\mathbf{u}}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \quad \text{for a.a. } s \in (0, S). \quad (6.21)$$

Secondly, we will apply the following version of the Fatou Lemma

$$\left. \begin{aligned} \limsup_{n \rightarrow \infty} f_n(s) &\leq f(s) \quad \text{for a.a. } s \in (0, S), \\ f_n(s) &\leq g_n(s) \quad \text{for a.a. } s \in (0, S), \\ g_n &\rightarrow g \quad \text{in } L^1(0, S), \end{aligned} \right\} \implies \limsup_{n \rightarrow \infty} \int_0^S f_n(s) ds \leq \int_0^S f(s) ds, \quad (6.22)$$

for measurable functions $(f_n)_n$ and f , in order to conclude that

$$\limsup_{n \rightarrow \infty} \int_0^S \mathbf{b}_{\Psi_n}(\lambda_n^{-1}\dot{\mathbf{t}}_n(s), \dot{\mathbf{u}}(s), -D\mathcal{E}(\mathbf{t}_n(s)\lambda_n^{-1}, \mathbf{u}(s))) ds \leq \int_0^S \mathbf{p}(\dot{\mathbf{t}}(s), \dot{\mathbf{u}}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) ds, \quad (6.23)$$

whence (6.15) and ultimately (6.11). For the proof of (6.21) and (6.23), we will distinguish the *stochastic* and the *vanishing-viscosity* cases.

Step 6a: proof of (6.21) and (6.23) for Ψ_n given by (5.18) (stochastic approximation). Preliminarily, we observe that, with the very same calculations as for (5.30) (cf. Claim 3.4 in the proof of Proposition 5.8), one has

$$\begin{aligned} \tau_n^\delta(s) &\leq \sqrt{\frac{d^2 \|\dot{u}(s)\|_\infty^2}{n^2 \delta^2 + n^2 (\Psi_n^*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))))^2}} \rightarrow 0 \quad \text{for almost all } s \in (0, S), \quad \text{and thus} \\ \sup_{s \in [0, S]} \tau_n^\delta(s) &\leq \frac{C}{\delta n} \rightarrow 0 \quad \text{as } n \rightarrow \infty, \end{aligned} \quad (6.24)$$

(with a slight abuse of notation, we use the symbol \sup also for an essential supremum) where we have exploited the Lipschitz continuity of u . In order to prove the pointwise estimate (6.21), we start with the following algebraic manipulation

$$\begin{aligned} \mathbf{b}_{\Psi_n}(\lambda_n^{-1} \dot{\mathbf{t}}_n(s), \dot{u}(s), -D\mathcal{E}(\mathbf{t}_n(s) \lambda_n^{-1}, \mathbf{u}(s))) &= \mathbf{b}_{\Psi_n}^\delta(\tau_n^\delta(s), \dot{u}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{t}(s))) - \tau_n^\delta(s) \delta \\ &\quad + \dot{\mathbf{t}}_n(s) \Psi_n^*(-D\mathcal{E}(\mathbf{t}_n(s) \lambda_n^{-1}, \mathbf{u}(s))) - \tau_n^\delta(s) \Psi_n^*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \\ &\quad + \frac{\dot{\mathbf{t}}_n(s)}{\lambda_n} \Psi_n \left(\frac{\dot{u}(s)}{\dot{\mathbf{t}}_n(s)} \lambda_n \right) - \tau_n^\delta(s) \Psi_n \left(\frac{\dot{u}(s)}{\tau_n^\delta(s)} \right) \end{aligned} \quad (6.25)$$

and prove the following three claims for the terms on the right-hand side.

Claim 6.a.1: there holds

$$\limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}^\delta(\tau_n^\delta(s), \dot{u}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) - \tau_n^\delta(s) \delta \leq \mathbf{p}(\dot{\mathbf{t}}(s), \dot{u}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \quad \text{for a.a. } s \in (0, S), \quad (6.26)$$

with \mathbf{p} given by (5.20).

Indeed, the representation formula (5.22) for $\min_{\tau > 0} \mathbf{b}_{\Psi_n}^\delta(\tau_n^\delta(s), \dot{u}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)))$ and estimate (5.27) (cf. Claim 3.3 in the proof of Prop. 5.8) yield

$$\begin{aligned} \mathbf{b}_{\Psi_n}^\delta(\tau_n^\delta(s), \dot{u}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) &= \sup \{ \langle \xi, \dot{u}(s) \rangle \mid \xi \in K_{n, \delta}^*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \} \\ &\leq \sup \{ \|\dot{u}(s)\|_1 \|\xi\|_\infty \mid \xi \in K_{n, \delta}^*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \} \\ &\leq \|\dot{u}(s)\|_1 (A \vee \|D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))\|_\infty) + \frac{1}{n} \|\dot{u}(s)\|_1 \log(2en\delta), \end{aligned} \quad (6.27)$$

and we conclude sending $n \rightarrow \infty$. Furthermore, we observe that $\tau_n^\delta(s) \delta \rightarrow 0$ as $n \rightarrow \infty$ thanks to the previously proved (6.24).

Claim 6.a.2: there holds

$$\limsup_{n \rightarrow \infty} (\dot{\mathbf{t}}_n(s) \Psi_n^*(-D\mathcal{E}(\mathbf{t}_n(s) \lambda_n^{-1}, \mathbf{u}(s))) - \tau_n^\delta(s) \Psi_n^*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)))) \leq 0 \quad \text{for a.a. } s \in (0, S). \quad (6.28)$$

Indeed, from the assumed uniform Lipschitz continuity of $D\mathcal{E}(\cdot, u)$ (cf. (5.35)), we gather that

$$\begin{aligned} |D_i \mathcal{E}(\mathbf{t}_n(s) \lambda_n^{-1}, \mathbf{u}(s))| - |D_i \mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))| &\leq |D_i \mathcal{E}(\mathbf{t}_n(s) \lambda_n^{-1}, \mathbf{u}(s)) - D_i \mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))| \\ &\leq L_E |\mathbf{t}_n(s) \lambda_n^{-1} - \mathbf{t}(s)| \end{aligned} \quad (6.29)$$

for all $s \in [0, S]$ and all $i = 1, \dots, d$. We now observe that

$$\begin{aligned} |\mathbf{t}_n(s) \lambda_n^{-1} - \mathbf{t}(s)| &\leq |\mathbf{t}_n(s) \lambda_n^{-1} - \mathbf{t}(s) \lambda_n^{-1} + \mathbf{t}(s) \lambda_n^{-1} - \mathbf{t}(s)| \\ &\leq \mathbf{t}(s) (1 - \lambda_n^{-1}) + \lambda_n^{-1} |\mathbf{t}_n(s) - \mathbf{t}(s)| \\ &\leq T \left(1 - \frac{1}{\lambda_n} \right) + \lambda_n^{-1} \int_0^s ((\dot{\mathbf{t}}(r) \vee \tau_n^\delta(r)) - \dot{\mathbf{t}}(r)) \, dr \\ &\leq T \left(1 - \frac{1}{\lambda_n} \right) + \int_0^s \tau_n^\delta(r) \, dr \end{aligned} \quad (6.30)$$

where we have used the fact that $\lambda_n \geq 1$ and the definition of \mathbf{t}_n from (6.17). We also have

$$\begin{aligned} T(1 - \lambda_n^{-1}) &= \frac{T}{T_n}(T_n - T) \leq \left(\int_0^{\mathfrak{s}(0^+)} \tau_n^\delta(r) \, dr + \int_{\mathfrak{s}(0^+)}^{\mathfrak{s}(T^-)} ((\dot{\mathbf{t}}(r) \vee \tau_n^\delta(r)) - \dot{\mathbf{t}}(r)) \, dr + \int_{\mathfrak{s}(T^-)}^S \tau_n^\delta(r) \, dr \right) \\ &\leq \left(\int_0^S \tau_n^\delta(r) \, dr \right) \leq \left(\sup_{s \in [0, S]} \tau_n^\delta(s) \right) S \end{aligned} \quad (6.31)$$

again using the definition (6.17) of \mathbf{t}_n . Hence, combining estimate (6.29) with (6.30) and (6.31), we gather that

$$\begin{aligned} |\mathbf{D}_i \mathcal{E}(\mathbf{t}_n(s) \lambda_n^{-1}, \mathbf{u}(s))| - |\mathbf{D}_i \mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))| &\leq C \sup_{s \in [0, S]} \tau_n^\delta(s) \doteq \bar{C}(n) \quad \text{for all } s \in [0, S], \quad \text{with} \\ \sup_{n \in \mathbb{N}} n \bar{C}(n) &\doteq \bar{C} < \infty, \end{aligned} \quad (6.32)$$

the latter estimate due to (6.24). Therefore, using now the explicit formula (2.7) for Ψ_n^* we get for almost all $s \in (0, S)$ that

$$\begin{aligned} &\dot{\mathbf{t}}_n(s) \Psi_n^*(-\mathbf{D}\mathcal{E}(\mathbf{t}_n(s) \lambda_n^{-1}, \mathbf{u}(s))) - \tau_n^\delta(s) \Psi_n^*(-\mathbf{D}\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \\ &\stackrel{(1)}{\leq} \frac{\dot{\mathbf{t}}_n(s)}{n} e^{-nA} \sum_{i=1}^d \cosh(n |\mathbf{D}_i \mathcal{E}(\mathbf{t}_n(s) \lambda_n^{-1}, \mathbf{u}(s))|) \\ &\stackrel{(2)}{\leq} \frac{\dot{\mathbf{t}}_n(s)}{n} e^{-nA} \sum_{i=1}^d \cosh(n |\mathbf{D}_i \mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))| + n \bar{C}(n)) \\ &\stackrel{(3)}{\leq} \frac{d \dot{\mathbf{t}}_n(s) e^{-nA}}{2n} + \frac{\dot{\mathbf{t}}_n(s)}{2n} e^{\bar{C}} e^{-nA} \sum_{i=1}^d e^{n |\mathbf{D}_i \mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))|} \\ &\stackrel{(4)}{\leq} \begin{cases} \frac{d}{n} \dot{\mathbf{t}}_n(s) (1 + e^{\bar{C}}) \doteq \frac{C_1}{n} & \text{for } s \in [\mathfrak{s}(0^+), \mathfrak{s}(T^-)], \\ C_2 \left(\frac{1}{n} + \sup_{s \in [0, S]} \tau_n^\delta(s) \Psi_n^*(-\mathbf{D}\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \right) & \text{for } s \in [0, \mathfrak{s}(0^+)) \cup (\mathfrak{s}(T^-), S], \end{cases} \end{aligned} \quad (6.33)$$

where (1) follows from the positivity of Ψ_n^* and from the trivial inequality $\cosh(nx) - 1 \leq \cosh(n|x|)$, (2) from (6.29), (3) from (6.32) and using the estimate $\cosh(x) \leq \frac{e^x + 1}{2}$ for all $x \geq 0$, and (4) is due to the fact that $\|\mathbf{D}\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))\|_\infty \leq A$ for $s \in [\mathfrak{s}(0^+), \mathfrak{s}(T^-)]$, and to an elementary inequality on $[0, \mathfrak{s}(0^+)) \cup (\mathfrak{s}(T^-), S]$. Clearly, $\frac{C_1}{n} \rightarrow 0$; on the other hand, it follows again from (6.24) and the Lipschitz continuity of u that

$$\sup_{s \in [0, S]} \tau_n^\delta(s) \Psi_n^*(-\mathbf{D}\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \leq \sup_{s \in [0, S]} \frac{d \|\dot{\mathbf{u}}(s)\|_\infty \Psi_n^*(-\mathbf{D}\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)))}{n (\Psi_n^*(-\mathbf{D}\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))))} \leq \frac{C_3}{n} \rightarrow 0 \quad \text{as } n \rightarrow \infty. \quad (6.34)$$

Therefore, (6.28) ensues.

Claim 6.a.3: there holds

$$\limsup_{n \rightarrow \infty} \left(\frac{\dot{\mathbf{t}}_n(s)}{\lambda_n} \Psi_n \left(\frac{\dot{\mathbf{u}}(s)}{\dot{\mathbf{t}}_n(s)} \lambda_n \right) - \tau_n^\delta(s) \Psi_n \left(\frac{\dot{\mathbf{u}}(s)}{\tau_n^\delta(s)} \right) \right) \leq 0 \quad \text{for a.a. } s \in (0, S). \quad (6.35)$$

We use the explicit formula (5.18) for Ψ_n , obtaining

$$\begin{aligned}
& \frac{\dot{t}_n(s)}{\lambda_n} \Psi_n \left(\frac{\dot{u}(s)}{\dot{t}_n(s)} \lambda_n \right) \\
& \leq \frac{\dot{t}_n \geq \tau_n^\delta}{\tau_n^\delta} \frac{\tau_n^\delta(s)}{\lambda_n} \Psi_n \left(\frac{\dot{u}(s)}{\tau_n^\delta(s)} \lambda_n \right) \\
& \leq \frac{d \tau_n^\delta(s) e^{-nA}}{n} + \sum_{i=1}^d \left[\frac{\dot{u}_i(s)}{n} \log \left(\lambda_n \frac{\frac{\dot{u}_i(s)}{\tau_n^\delta(s)} + \sqrt{\left(\frac{\dot{u}_i(s)}{\tau_n^\delta(s)}\right)^2 + \frac{e^{-2nA}}{\lambda_n^2}}}{e^{-nA}} \right) - \frac{1}{n} \sqrt{\dot{u}_i(s)^2 + \left(\frac{\tau_n^\delta(s) e^{-nA}}{\lambda_n}\right)^2} \right] \\
& \stackrel{\lambda_n \geq 1}{\leq} \tau_n^\delta(s) \Psi_n \left(\frac{\dot{u}(s)}{\tau_n^\delta(s)} \right) + \sum_{i=1}^d \left[\frac{\dot{u}_i(s)}{n} \log(\lambda_n) - \frac{1}{n} \sqrt{\dot{u}_i(s)^2 + \left(\frac{\tau_n^\delta(s) e^{-nA}}{\lambda_n}\right)^2} + \frac{1}{n} \sqrt{\dot{u}_i(s)^2 + (\tau_n^\delta(s) e^{-nA})^2} \right],
\end{aligned}$$

for almost all $s \in (0, S)$, whence

$$\begin{aligned}
& \dot{t}_n(s) \frac{1}{\lambda_n} \Psi_n \left(\frac{\dot{u}(s)}{\dot{t}_n(s)} \lambda_n \right) - \tau_n^\delta(s) \Psi_n \left(\frac{\dot{u}(s)}{\tau_n^\delta(s)} \right) \\
& \leq \sum_{i=1}^d \left(\frac{\dot{u}_i(s)}{n} \log(\lambda_n) - \frac{1}{n} \sqrt{(\dot{u}_i(s))^2 + \left(\frac{\tau_n^\delta(s) e^{-nA}}{\lambda_n}\right)^2} + \frac{1}{n} \sqrt{(\dot{u}_i(s))^2 + (\tau_n^\delta(s) e^{-nA})^2} \right). \tag{6.36}
\end{aligned}$$

Observe that the right-hand side of (6.36) tends to zero as $n \rightarrow \infty$ taking into account that $\sup_{s \in [0, S]} \|\dot{u}(s)\|_\infty \leq C$, that $\lambda_n \rightarrow 1$, and that $\sup_{s \in [0, S]} \tau_n^\delta(s) \rightarrow 0$ by (6.24). This yields (6.35) and, ultimately, (6.21).

Finally, we conclude the integrated lim sup-estimate (6.23) by observing that the Fatou Lemma (cf. (6.22)) applies: this can be checked combining (6.24), (6.25), (6.27) (taking into account that $\sup_{s \in [0, S]} \|\dot{u}(s)\|_1 \leq C$), (6.33), (6.34), and (6.36).

Step 6b: proof of (6.21) and (6.23) for Ψ_n given by (5.33) (vanishing-viscosity approximation). To simplify the notation, in what follows we shall focus on the particular case in which the sequence $(\varepsilon_n)_n$ is given by

$$\varepsilon_n = \frac{1}{n}.$$

Preliminarily, we recall that, in the case (5.33),

$$\Psi_n^*(\xi) = \frac{1}{2\varepsilon_n} (\min_{\zeta \in K^*} \|\xi - \zeta\|_*)^2 = \frac{n}{2} d_*(\xi, K^*)^2, \tag{6.37}$$

where $\|\cdot\|_*$ is the dual norm to $\|\cdot\|$, and $d_*(\cdot, K^*)$ denotes the induced distance from the set K^* . Taking into account (6.37), we provide a bound for the parameter τ_n^δ from (6.16) again resorting to the Euler-Lagrange equation (5.29). In the present case, it rewrites as

$$A \left\| \frac{\dot{u}(s)}{\tau_n^\delta(s)} \right\|_1 - \frac{1}{2n} \left\| \frac{\dot{u}(s)}{\tau_n^\delta(s)} \right\|^2 - \langle \partial \Psi_0 \left(\frac{\dot{u}(s)}{\tau_n^\delta(s)} \right), \frac{\dot{u}(s)}{\tau_n^\delta(s)} \rangle + \frac{n}{2} d_*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)), K^*)^2 + \delta = 0, \tag{6.38}$$

where we have formally written $\partial \Psi_0$ as a single-valued mapping. Taking into account that $\langle \partial \Psi_0(\zeta), \zeta \rangle = \Psi_0(\zeta)$ for all $\zeta \in \mathbb{R}^d$, we ultimately conclude that

$$\tau_n^\delta(s) = \frac{\|\dot{u}(s)\|}{\sqrt{2n\delta + n^2 d_*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)), K^*)^2}} \leq \frac{\|\dot{u}(s)\|}{\sqrt{2n\delta}} \quad \text{for a.a. } s \in (0, S). \tag{6.39}$$

In what follows we will take

$$\delta = \delta_n \quad \text{such that} \quad \delta_n \rightarrow \infty \quad \text{and} \quad \delta_n \frac{1}{n} \rightarrow 0 \quad \text{as } n \rightarrow \infty, \tag{6.40}$$

but we will continue to write δ in place of δ_n for shorter notation.

In order to show (6.21), we start from the very same algebraic manipulation as in (6.25) and prove that the terms on the right-hand side converge to the desired limit. We observe that

$$\begin{aligned}
\mathbf{b}_{\Psi_n}^\delta(\tau_n^\delta(s), \dot{\mathbf{u}}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) &= \tau_n^\delta(s) \Psi_n \left(\frac{\dot{\mathbf{u}}(s)}{\tau_n^\delta(s)} \right) + \tau_n^\delta(s) \Psi_n^*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) + \tau_n^\delta(s) \delta \\
&\stackrel{(6.39)}{=} \Psi_0(\dot{\mathbf{u}}(s)) + \frac{\|\dot{\mathbf{u}}(s)\|}{2n} \sqrt{2n\delta + n^2 d_*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)), K^*)^2} \\
&\quad + \frac{n \|\dot{\mathbf{u}}(s)\| d_*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)), K^*)^2}{2\sqrt{2n\delta + n^2 d_*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)), K^*)^2}} + \tau_n^\delta(s) \delta \\
&\stackrel{n \rightarrow \infty}{\rightarrow} \Psi_0(\dot{\mathbf{u}}(s)) + \|\dot{\mathbf{u}}(s)\| d_*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)), K^*) \\
&\leq \mathbf{p}(\dot{\mathbf{t}}(s), \dot{\mathbf{u}}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))),
\end{aligned} \tag{6.41}$$

where the last inequality follows from the fact that $D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)) \in K^*$ when $\dot{\mathbf{t}}(s) > 0$. Thus we conclude the analogue of (6.26). Moreover, observe that, as a consequence of estimate (6.39) and of the scaling for δ_n from (6.40), we have

$$\delta \sup_{s \in [0, S]} \tau_n^\delta(s) \rightarrow 0 \quad \text{as } n \rightarrow \infty. \tag{6.42}$$

We then proceed to show the counterpart to (6.28). The very same calculations as in (6.29) (cf. also (6.31)), and again (6.39) give for every $s \in [0, S]$ and all $i = 1, \dots, d$

$$|D_i \mathcal{E}(\mathbf{t}_n(s) \lambda_n^{-1}, \mathbf{u}(s)) - D_i \mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))| \leq C \sup_{s \in [0, S]} \tau_n^\delta(s) \leq \frac{C}{\sqrt{n\delta}}. \tag{6.43}$$

Resorting now to the explicit formula (6.37) for Ψ_n^* (and using $\xi_n(s)$ and $\xi(s)$ as place-holders for $-D\mathcal{E}(\mathbf{t}_n(s) \lambda_n^{-1}, \mathbf{u}(s))$ and $-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))$, respectively, to avoid overburdening notation), we get

$$\begin{aligned}
\dot{\mathbf{t}}_n(s) \Psi_n^*(\xi_n(s)) - \tau_n^\delta(s) \Psi_n^*(\xi(s)) &\stackrel{(1)}{=} \dot{\mathbf{t}}_n(s) \frac{n}{2} d_*(\xi_n(s), K^*)^2 \\
&\stackrel{(2)}{\leq} \dot{\mathbf{t}}_n(s) \frac{n}{2} \|\xi_n(s) - \xi(s)\|_*^2 \\
&\stackrel{(3)}{\leq} \frac{C}{\delta} \quad \text{for a.a. } s \in (s(0^+), s(T^-)).
\end{aligned} \tag{6.44}$$

In (6.44), (1) and (2) are due to the fact that $D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)) \in K^*$ for almost all $s \in (s(0^+), s(T^-))$, so that $\Psi_n^*(\xi(s)) = 0$, and (3) follows from estimate (6.43). To prove the analogue of (6.28), we will first treat the case in which $s \in [0, s(0^+)) \cup (s(T^-), S]$ (where $\dot{\mathbf{t}}_n(s) = \tau_n^\delta(s)$). Here, we use the Lipschitz estimate (6.43) and the explicit formula for Ψ_n^* . Thus, we find

$$\begin{aligned}
&\tau_n^\delta(s) (\Psi_n^*(\xi_n(s)) - \Psi_n^*(\xi(s))) \\
&= \frac{n}{2} \tau_n^\delta(s) (d_*(\xi_n(s), K^*)^2 - d_*(\xi(s), K^*)^2) \\
&\leq \frac{n}{2} \tau_n^\delta(s) \left((d_*(\xi_n(s), \xi(s)) + d_*(\xi(s), K^*))^2 - d_*(\xi(s), K^*)^2 \right) \\
&\leq \frac{n}{2} \tau_n^\delta(s) (d_*(\xi_n(s), \xi(s))^2 + 2d_*(\xi(s), K^*) d_*(\xi_n(s), \xi(s))) \\
&\stackrel{(6.43)}{\leq} n \tau_n^\delta(s) \left(\frac{C}{n\delta} + \frac{C}{\sqrt{n\delta}} \right) \quad \text{for all } s \in [0, s(0^+)) \cup (s(T^-), S]
\end{aligned} \tag{6.45}$$

Combining (6.44) and (6.45) we infer (6.28), since $\delta = \delta_n \rightarrow \infty$ and $\frac{\delta_n}{n} \rightarrow 0$ as $n \rightarrow \infty$. In order to prove the analogue of (6.35), we use the explicit formula (5.33) of Ψ_n , obtaining

$$\begin{aligned}
\frac{\dot{\mathbf{t}}_n(s)}{\lambda_n} \Psi_n \left(\frac{\dot{\mathbf{u}}(s)}{\dot{\mathbf{t}}_n(s)} \lambda_n \right) &\stackrel{\dot{\mathbf{t}}_n \geq \tau_n^\delta}{\leq} \frac{\tau_n^\delta(s)}{\lambda_n} \Psi_n \left(\frac{\dot{\mathbf{u}}(s)}{\tau_n^\delta(s)} \lambda_n \right) = \Psi_0(\dot{\mathbf{u}}(s)) + \frac{\lambda_n}{2n\tau_n^\delta(s)} \|\dot{\mathbf{u}}(s)\|^2 \\
&= \tau_n^\delta(s) \Psi_n \left(\frac{\dot{\mathbf{u}}(s)}{\tau_n^\delta(s)} \right) + (\lambda_n - 1) \frac{\|\dot{\mathbf{u}}(s)\|^2}{2n\tau_n^\delta(s)}.
\end{aligned}$$

It follows from (6.39) and (6.40) that, for n sufficiently big,

$$n\tau_n^\delta(s) \geq \frac{\|\dot{\mathbf{u}}(s)\|}{1 + d_*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s)), K^*)},$$

hence we deduce that

$$\frac{\dot{\mathbf{t}}_n(s)}{\lambda_n} \Psi_n \left(\frac{\dot{\mathbf{u}}(s)}{\dot{\mathbf{t}}_n(s)} \lambda_n \right) - \tau_n^\delta(s) \Psi_n \left(\frac{\dot{\mathbf{u}}(s)}{\tau_n^\delta(s)} \right) \leq (\lambda_n - 1)C \quad \text{for a.a. } s \in (0, S). \quad (6.46)$$

Then, (6.35), and ultimately (6.21), ensue, since $\lambda_n \rightarrow 1$.

It remains to verify the integrated inequality (6.23). For this, we apply the Fatou Lemma by checking the validity of conditions (6.22). They can be verified using (6.25) and resorting to the *uniform* (w.r.t. $s \in (0, S)$) estimates (6.42), (6.44), (6.45), and (6.46), as well as to the following estimate

$$\begin{aligned} \mathbf{b}_{\Psi_n}(\tau_n^\delta(s), \dot{\mathbf{u}}(s), -D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) &= \sup \{ \langle \xi, \dot{\mathbf{u}}(s) \rangle \mid \xi \in K_{n,\delta}^*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \} \\ &\leq \sup \{ \|\dot{\mathbf{u}}(s)\|_1 \|\xi\|_\infty \mid \xi \in K_{n,\delta}^*(-D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))) \} \\ &\leq C \|\dot{\mathbf{u}}(s)\|_1 \left(\|D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))\|_\infty + \sqrt{\frac{\delta}{n}} \right), \end{aligned}$$

again by the general representation formula (5.22). We then conclude (6.22) by taking into account the boundedness of $\|\dot{\mathbf{u}}(s)\|_1, \|D\mathcal{E}(\mathbf{t}(s), \mathbf{u}(s))\|_\infty$ and sending $n \rightarrow \infty$. Thus, (6.23) is proven.

Step 7: recovery sequence for a general curve u and conclusion of the proof. Now we construct a recovery sequence for a curve with countably many jumps, following the argument from the proof of [BP16, Thm. 4.2]. Given the jump set J_u , fix $\varepsilon > 0$, consider a countable set $\{t^i\}_{i \in I} \subseteq J_u \cup \{0, T\}$ (with $t^i < t^{i+1}$ for all $i \in I$) such that

$$\text{Jmp}_{p,\varepsilon}(u; [0, T] \setminus \{t^i\}) < \varepsilon, \quad (6.47)$$

(recall the definition (3.22) of $\text{Jmp}_{p,\varepsilon}$), and such that the interval $[0, T]$ can be written as the union of disjoint subintervals

$$[0, T] = \bigcup_{i \in I} \Sigma^i \quad \text{where } \Sigma^i = [t^i, t^{i+1}].$$

Then, we let $t_n^i = \mathbf{t}_n(s(t^i))$, and set

$$\lambda_n^i := \frac{t_n^{i+1} - t_n^i}{t^{i+1} - t^i}.$$

We define the recovery sequence by

$$u_n(t) := \mathbf{u}(\mathbf{t}_n^{-1}(\lambda_n^i(t - t^i) + t_n^i)) \quad \text{for } t \in \Sigma^i, \quad (6.48)$$

so that

$$\dot{u}_n(t) = \frac{\dot{\mathbf{u}}}{\dot{\mathbf{t}}_n}(\mathbf{t}_n^{-1}(\lambda_n^i(t - t^i) + t_n^i)) \lambda_n^i \quad \text{for } t \in (\Sigma^i)^\circ.$$

We have now that

$$\begin{aligned} &\int_0^T \left(\Psi_n(\dot{u}_n(t)) + \Psi_n^*(-D\mathcal{E}(t, u_n(t))) \right) dt \\ &= \sum_i \int_{\Sigma^i} \left(\Psi_n \left(\frac{\dot{\mathbf{u}}}{\dot{\mathbf{t}}_n}(\mathbf{t}_n^{-1}(\lambda_n^i(t - t^i) + t_n^i)) \lambda_n^i \right) + \Psi_n^*(-D\mathcal{E}(t, \mathbf{u}(\mathbf{t}_n^{-1}(\lambda_n^i(t - t^i) + t_n^i)))) \right) dt \\ &= \sum_i \int_{s(t^i)}^{s(t^{i+1})} \left[\Psi_n \left(\frac{\dot{\mathbf{u}}(s)}{\dot{\mathbf{t}}_n(s)} \lambda_n^i \right) + \Psi_n^*(-D\mathcal{E}((\lambda_n^i)^{-1}(\mathbf{t}_n(s) - t_n^i) + t^i, \mathbf{u}(s))) \right] \frac{\dot{\mathbf{t}}_n(s)}{\lambda_n^i} ds. \end{aligned}$$

Applying estimate (6.21) in every subinterval $[s(t^i), s(t^{i+1})]$ and Fatou's Lemma (cf. (6.22)) on the whole interval $[0, S]$, we obtain inequality (6.15).

The convergence of the variations again follows by the definition of u_n . The pointwise convergence $u_n(t) \rightarrow u(t)$ for $t \in [0, T] \setminus J_u$ is again trivial. The following calculations show that, by construction, the convergence holds also in the points $\{t^i\} \subseteq J_u$. Indeed,

$$u_n(t^i) \stackrel{(6.48)}{=} u(t_n^{-1}(t_n^i)) = u(t_n^{-1}(t_n(s(t^i)))) = u(s(t^i)) \stackrel{(6.12)}{=} u(t^i),$$

while from (6.47) and the convergence of the variations we have that

$$\lim_{n \rightarrow \infty} |u_n(t) - u(t)| < \varepsilon \quad \text{for all } t \in J_u \setminus \{t^i\}.$$

In fact, the recovery sequence u_n has a hidden dependence on ε . Then taking $\varepsilon = n^{-1}$ we define a new recovery sequence, that we keep labelling u_n , and sending $n \rightarrow \infty$ (ε to zero) we conclude.

This finishes the proof of Theorem 5.9. \square

Remark 6.2. Let us briefly outline how the proof of Thm. 5.9 carries over to the case in which the dissipation potentials are given by (5.37). Clearly, it is sufficient to comment on the changes in the calculations carried out throughout Step 6b, starting from the Euler-Lagrange equation (5.29). In the case

$$\Psi_n(v) = A\|v\|_1 + \frac{1}{pn^{p-1}}\|v\|^p, \quad \text{with } \Psi_n^*(\xi) = \frac{n}{p'}d_*(\xi, K^*)^{p'}, \quad (6.49a)$$

and $p' = \frac{p}{p-1}$ the conjugate exponent of p , (5.29) becomes

$$\left(1 - \frac{1}{p}\right) \frac{1}{n^{p-1}} \left\| \frac{\dot{u}(s)}{\tau_n^\delta(s)} \right\|^2 + \frac{n}{p'} d_*(-D\mathcal{E}(t(s), u(s)), K^*)^{p'} + \delta = 0 \quad \text{for a.a. } s \in (0, S),$$

whence we deduce that

$$\tau_n^\delta(s) = \frac{1}{n} \frac{\|\dot{u}(s)\|}{(d_*(-D\mathcal{E}(t(s), u(s)), K^*)^{p'} + 2\frac{\delta}{n})^{1/p}} \quad \text{for a.a. } s \in (0, S). \quad (6.49b)$$

We now write the analogue of (6.41), taking into account formulae (6.49), and prove with straightforward algebra that

$$\limsup_{n \rightarrow \infty} \mathbf{b}_{\Psi_n}^\delta(\tau_n^\delta(s), \dot{u}(s), -D\mathcal{E}(t(s), u(s))) \leq \mathbf{p}(\dot{t}(s), \dot{u}(s), -D\mathcal{E}(t(s), u(s))).$$

All the remaining calculations in Step 6b extend to the case of (5.37).

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GIOVANNI A. BONASCHI, TECHNISCHE UNIVERSITEIT EINDHOVEN, 5600 MB, EINDHOVEN, THE NETHERLANDS, AND, AVIVA, MILANO, ITALY.

E-mail address: giovanni.bonaschi@gmail.com

RICCARDA ROSSI, DIMI, UNIVERSITÀ DI BRESCIA, VIA BRANZE 38, I-25133 BRESCIA, ITALY.

E-mail address: riccarda.rossi@unibs.it