

Approximation of functions with small jump sets and existence of strong minimizers of Griffith's energy

October 25, 2017

Antonin Chambolle¹, Sergio Conti², and Flavia Iurlano³

¹ *CMAP, École Polytechnique, CNRS,
91128 Palaiseau Cedex, France*

² *Institut für Angewandte Mathematik, Universität Bonn
53115 Bonn, Germany*

³ *Laboratoire Jacques-Louis Lions, Université Paris 6
75005 Paris, France*

We prove that special functions of bounded deformation with small jump set are close in energy to functions which are smooth in a slightly smaller domain. This permits to generalize the decay estimate by De Giorgi, Carriero, and Leaci to the linearized context in dimension n and to establish the closedness of the jump set for local minimizers of the Griffith energy.

1 Introduction

The last few years have seen the development of several techniques to approximate a certain class of special functions with bounded deformation (*SBD*). Such functions appear in the mathematical formulation of fracture in the framework of linearized elasticity [18, 14]. Their peculiarity is the structure of the symmetric distributional derivative, which unveils the presence of a regularity zone, where the function admits a symmetric gradient in an approximate sense, and of a singularity zone, where the function jumps. The variational problems in such spaces are generally hard to tackle, and few strong existence results are known with no artificial additional constraint (L^∞ bounds, a priori bounds on the discontinuity set, ...) We address in this paper the issue of the existence of strong minimizers for Griffith's model of brittle fracture in linear elasticity [23], in the formulation introduced by Francfort and Marigo in [18] (up to lower-order terms, see Theorem 1 below for details). A scalar simplification of this problem leads to the Mumford-Shah functional [29], well known in the mathematical literature. By strong minimizers, we mean functions defined in an open set, with a closed $(n-1)$ -dimensional discontinuity set. This class of "free-discontinuity problems" has been thoroughly studied, in the scalar case, in the 90's and is now well understood; a classical way to the

existence of strong minimizers is to show first the existence of minimizers in the class SBV [15] and then, that the jump set of such solutions is closed [16]. The technical point where the proof of [16] (and most subsequent proofs, see for instance [27, 2]) is not easily transferred is an approximation issue where one needs to show that a minimizer with almost no jump is close to a smooth minimizer. Hence the need to develop new approximation methods in such a context.

Indeed, standard methods do not work in a linearized framework, being these based on the identification of bad parts of the function *via* coarea formula and their removal *via* truncation [16]. In contrast, results of this kind have important applications, beyond the already mentioned existence of minimizers for the Griffith’s problem in its strong formulation, including the integral representation in SBD of functionals with p growth, or the study of the quasi-static evolution of brittle fracture, in the 2d case see respectively [12], [11], and [22].

The first two authors, together with G. Francfort established in [5] a Poincaré-Korn’s inequality for functions with p -integrable strain and small jump set. Their idea is to estimate the symmetric variation of u on many lines having different orientations and not intersecting the jump set, thus allowing to use the fundamental theorem of calculus along such lines. Through a variant of this strategy with restrictions to the planar setting, the last two authors, together with M. Focardi, proved in [12] that such functions are in fact Sobolev out of an exceptional set with small area and perimeter, and obtained a Korn’s inequality in that class. Similar slicing techniques were first used in [3, 4, 24] to prove density and in [13, 17, 26] to prove rigidity. A different approach, based on the idea of binding the jump heights after suitable modifications of the jump set and of the displacement field, has been employed by Friedrich in [19, 20, 21] to prove Poincaré-Korn’s, Korn’s with a non-sharp exponent, and piecewise Korn’s inequalities in the planar case.

On the one hand, the drawback of [5] is the lack of control on the perimeter of the exceptional set, which prevents good estimates for the strain; nevertheless these can be recovered through a suitable mollification. On the other hand, [12] and [20, 21] use respectively a scaling argument and geometric constructions which hold in dimension 2 and do not trivially extend to higher dimensions.

The purpose of this paper is to establish a n -dimensional version of the approximation result in [12], where it is shown that SBD functions with a small jump set can be approximated with $W^{1,p}$ functions. Our technique, which is slightly different from [12] and other “classical” methods already developed for the approximation of $(G)SBD$ functions [3, 4, 25, 10], is based on a subdivision of the domain into “bad” and “good” little cubes (depending on the size of the jump set in each cube) which was first introduced

in [6] and also recently used in [7]. Given a function with p -integrable strain and small jump set, we first cover the domain by dyadic small cubes which become smaller and smaller close to the boundary, we then identify the good cubes, those which still contain a small amount of jump. The biggest cubes are chosen with size much larger than the measure of total jump, so that they are all good, and give rise to a compact set which covers most of the domain. In the good cubes the result in [5] provides a small set and an affine function which is close to the original function out of the exceptional set. In such set we redefine the function as the aforementioned affine function, then we mollify the new function in the good cube in order to gain regularity. Finally our approximations are obtained by taking a partition of unity on the good part and keeping the original function in the rest. Since a large compact is made of good cubes, our approximation is smooth in most of the domain. For more details we refer to Section 3. Since there are no additional mathematical difficulties, we prove the approximation in the more general setting *GSBD*, see Section 2 for the definition.

As we mentioned, this result can be employed to prove the existence of strong minimizers for Griffith's energy, thus extending for $p = 2$ ¹ the result in [11] in any dimension. Denoting by \mathbb{C} the ‘‘Hooke's law’’ of a linear-elastic material, that is, \mathbb{C} is a symmetric linear map from $\mathbb{R}^{n \times n}$ to itself with the properties

$$\mathbb{C}(\xi - \xi^T) = 0 \text{ and } \mathbb{C}\xi \cdot \xi \geq c_0|\xi + \xi^T|^2 \text{ for all } \xi \in \mathbb{R}^{n \times n}, \quad (1)$$

we obtain the following result:

Theorem 1. *Let $\Omega \subset \mathbb{R}^n$ be a bounded Lipschitz set, $g \in L^\infty(\Omega; \mathbb{R}^n)$, $\beta > 0$, $\kappa > 0$, \mathbb{C} as in (1). Then the functional*

$$E_2[\Gamma, u] := \int_{\Omega \setminus \Gamma} (\mathbb{C}e(u) : e(u) + \kappa|u - g|^2) dx + 2\beta\mathcal{H}^{n-1}(\Gamma \cap \Omega) \quad (2)$$

has a minimizer in the class

$$\mathcal{A}_2 := \{(u, \Gamma) : \Gamma \subset \bar{\Omega} \text{ closed, } u \in C^1(\Omega \setminus \Gamma)\}. \quad (3)$$

Here, $e(u) = (Du + Du^T)/2$ is the symmetrized gradient of the displacement u .

In [11] the only part of the argument which is restricted to two dimensions was in fact the convergence of quasi-minimizers with vanishing jump to a minimizer without jump, which is obtained precisely using the 2d approximation of [12]. We show the convergence in Section 4, making use of the approximation result in Section 3. We refer to [11] for the rest of the proof of existence since it remains unchanged in higher dimension.

¹This only holds for $p = 2$, since [11] relies, when $p \neq 2$, on integral estimates proved in [8] which do not scale with the appropriate exponent in dimensions larger than 2.

We remark that apparently the formulation of Griffith's problem considered in [11] and here differs from the original one for the presence of a fidelity term of type $|u - g|^2$, and for the absence of boundary conditions. Both of them have the only role of guaranteeing existence of a minimizer in $GSBD^p$ for the weak global problem, hence one should employ different compactness and semicontinuity theorems in the two cases. One uses [14, Theorem 11.3] in the first case; in the second case, in presence of Dirichlet boundary conditions, one uses [22, Theorem 4.15] in dimension 2. Compactness in the n -dimensional $GSBD$ setting in presence of Dirichlet boundary conditions is still an open problem. If weak compactness holds, or, in other words, if the weak problem has a minimizer, then the present argument yields the desired regularity. This regularity result also holds in the case $\kappa = 0$, which coincides with the classical Griffith model.

Theorem 2. *Let $\Omega \subset \mathbb{R}^n$ be a bounded Lipschitz set, $g \in L^\infty(\Omega; \mathbb{R}^n)$, $\beta > 0$, $\kappa \geq 0$, \mathbb{C} as in (1). Let $u \in GSBD^2(\Omega)$ be a local minimizer of*

$$\int_{\Omega \setminus J_u} (\mathbb{C}e(u) : e(u) + \kappa|u - g|^2) dx + 2\beta \mathcal{H}^{n-1}(J_u) \quad (4)$$

Then, up to null sets, u and J_u coincide with a local minimizer of $E_2[\Gamma, u]$ in the class \mathcal{A}_2 .

By local minimizer we mean here minimizer with respect to perturbations with compact support, i.e., in the class of all $v \in GSBD^2(\Omega)$ such that $\{u \neq v\} \subset\subset \Omega$.

The structure of the paper is the following. In Section 2 we introduce the notation for $GSBD$ functions. In Section 3 we state and prove our main result, the approximation in any dimension for functions with p -integrable strain and small jump set. In Section 4 we study the limit of quasi-minimizers with vanishing jump sets, which is instrumental to obtain existence of minimizers for Griffith's problem in any dimension. Finally, in Section 5 we recall from [11] the main steps of the proof of Theorem 1.

2 Notation

Fixed $\Omega \subset \mathbb{R}^n$ open and $u \in L^1(\Omega; \mathbb{R}^n)$ one defines the slice $u_y^\xi : \Omega_y^\xi \rightarrow \mathbb{R}$ for $\xi \in \mathbb{S}^{n-1}$ and $y \in \mathbb{R}^n$ by $u_y^\xi(t) = u(y + t\xi) \cdot \xi$, where $\Omega_y^\xi := \{t \in \mathbb{R} : y + t\xi \in \Omega\}$. One also introduces $\Omega^\xi := (\text{Id} - \xi \otimes \xi)\Omega$, that is the orthogonal projection of Ω in the direction ξ .

A generalized special function with bounded deformation $GSBD(\Omega)$ (see [14]) is then a \mathcal{L}^n -measurable function $u : \Omega \rightarrow \mathbb{R}^n$ for which there exists a bounded positive Radon measure $\lambda_u \in \mathcal{M}_b^+(\Omega)$ such that the following condition holds for every $\xi \in \mathbb{S}^{n-1}$: for \mathcal{H}^{n-1} -a.e. $y \in \Omega^\xi$ the function $u_y^\xi(t)$ belongs to $SBV_{\text{loc}}(\Omega_y^\xi)$ and for every Borel set

$B \subset \Omega$ it satisfies

$$\int_{\Omega^\xi} \left(|Du_y^\xi|(B_y^\xi \setminus J_{u_y^\xi}^1) + \mathcal{H}^0(B_y^\xi \cap J_{u_y^\xi}^1) \right) d\mathcal{H}^{n-1} \leq \lambda_u(B), \quad (5)$$

where $J_{u_y^\xi}^1 := \{t \in J_{u_y^\xi} : |[u_y^\xi](t)| \geq 1\}$.

If $u \in GSBD(\Omega)$, the approximate symmetric gradient $e(u)$ and the approximate jump set J_u are well-defined, are respectively integrable and rectifiable, and can be reconstructed by slicing, see [14] for details. We refer to [1] for properties of functions of bounded variation BV .

The subspace $GSBD^p(\Omega)$ contains all functions in $GSBD(\Omega)$ satisfying $e(u) \in L^p(\Omega; \mathbb{R}^{n \times n})$ and $\mathcal{H}^{n-1}(J_u) < \infty$.

3 Approximation of functions with small jump

3.1 Preliminary results

We begin by stating a slight generalization of the Poincaré-Korn inequality for functions with small jump set obtained in [5, Prop. 3].

Proposition 3.1. *Let $0 < \theta'' < \theta' < 1$, $r > 0$. Let $Q = (-r, r)^n$, $Q' = (-\theta'r, \theta'r)^n$, $p \in [1, \infty)$, $u \in GSBD^p(Q)$.*

1. *There exists a set $\omega \subset Q'$ and an affine function $a : \mathbb{R}^n \rightarrow \mathbb{R}^n$ with $e(a) = 0$ such that*

$$|\omega| \leq c_* r \mathcal{H}^{n-1}(J_u) \quad (6)$$

and

$$\int_{Q' \setminus \omega} |u - a|^{np/(n-1)} \leq c_* r^{n(p-1)/(n-1)} \left(\int_Q |e(u)|^p dx \right)^{n/(n-1)} \quad (7)$$

2. *If additionally $p > 1$ then there is $\bar{p} > 0$ (depending on p and n) such that, for a given mollifier $\rho_r \in C_c^\infty(B_{(\theta' - \theta'')r})$, $\rho_r(x) = r^{-n} \rho_1(x/r)$, the function $v = u \chi_{Q' \setminus \omega} + a \chi_\omega$ obeys*

$$\int_{Q''} |e(v * \rho_r) - e(u) * \rho_r|^p dx \leq c \left(\frac{\mathcal{H}^{n-1}(J_u)}{r^{n-1}} \right)^{\bar{p}} \int_Q |e(u)|^p dx,$$

where $Q'' = (-\theta''r, \theta''r)^n$.

The constant in 1. depends only on p , n and θ' , the one in 2. also on ρ_1 and θ'' .

Proof. This result was proven in Prop. 3 of [5] for $\theta' = 1/2$, $\theta'' = 1/4$ and $u \in SBD^p$.

The same proof works in $u \in GSBD^p(Q)$, since it uses only the properties of slices, which hold also in the generalized context (see [14, Theorem 8.1 and 9.1] for the slicing formulas for J_u and $e(u)$ in GBD). At the same time, the proof works for general values of θ' and θ'' after very minor corrections. Basically, using the same notation of [5], the explicit bound $\mathcal{H}^1(R_\xi^x) \geq 1$ becomes $\mathcal{H}^1(R_\xi^x) \geq 2(1 - \theta')$, correspondingly in the definition of ω_ξ^* one takes $(1 - \theta')$ instead of $1/2$. The explicit constant in (3.5) becomes $1/(1 - \theta')$, which then propagates (via the unspecified constants “ c ”, which hereby acquire a dependence on θ') to the end of the proof. The proof of 2. is unchanged, since it already depends on the choice of the mollifier. \square

Remark 3.2. *The statement still holds for $\theta' = 1$, but we do not need this here.*

3.2 The main result

We first show how a $GSBD^p$ function with (very) small jump set can be well approximated by a function which is smooth on a large subset of the domain. For simplicity we assume that the domain is a cube Q , so that the coverings are all explicit, using a Whitney-type argument our proof extends easily to other regular open sets. The key idea is to cover the domain Q into a large number of small cubes of side length δ , and then to let the decomposition refine towards the boundary. Then one applies the Korn-Poincaré estimate of Proposition 3.1 to each cube. If $\mathcal{H}^{n-1}(J_u)$ is sufficiently small, on a scale set by the length scale δ (and the constants of Proposition 3.1), then for each of the “interior” cubes (with side length δ) one finds that the exceptional set covers only a small part of the cube. One replaces u by the affine approximant in the exceptional set, mollifies, and then interpolates between neighbouring cubes, to obtain a smooth function with the needed properties. A bound on the difference between the affine approximants in neighbouring cubes is obtained by using Proposition 3.1 on slightly enlarged versions of the cubes.

The boundary layer is however different. Moving towards the exterior boundary, one uses smaller and smaller cubes, and eventually it may happen that the exceptional set covers some cubes entirely. Then the rigidity estimate gives no information on the structure of u , and our construction cannot be performed. The union of those cubes, denoted by \mathcal{B} in the proof, is therefore treated differently: the function u is left untouched here. This generates a difficulty with the partition-of-unity approach, at the boundary between the two regions. The key idea here is to construct a partition of unity only in $Q \setminus \mathcal{B}$, with summands that do not have to obey any boundary data on $\partial^* \mathcal{B}$ (but vanish as usual on ∂Q). Then one can completely separate the construction in $Q \setminus \mathcal{B}$, which is

done by filling the holes and mollifying, from the one on \mathcal{B} , where u is untouched. As a result, we create a small amount of jump, which however remains in a δ -neighborhood of the original jump set and whose measure remains controlled. In 2D, it is possible to perform a similar construction without any additional jump, see [12].

In order to have good estimates it is as usual necessary to introduce the refinement not close to the (fixed) boundary of Q but instead close to the boundary of a slightly smaller cube, and to work with several coverings with families of cubes (denoted by $q \subset q' \subset q'' \subset q'''$) which are slightly enlarged versions of each other, see Figure 1 for a representation.

Let $f_0(\xi) := \frac{1}{p}(\mathbb{C}\xi \cdot \xi)^{p/2}$, for $\xi \in \mathbb{R}_{\text{sym}}^{n \times n}$, with \mathbb{C} obeying (1). Let $Q_r := (-r, r)^n$ and let $Q := Q_1 = (-1, 1)^n$.

Theorem 3. *There exist η, c positive constants and a mollifier $\rho \in C_c^\infty(B(0, 1); \mathbb{R}_+)$ such that if $u \in \text{GSBD}^p(Q_1)$ and $\delta := \mathcal{H}^{n-1}(J_u)^{1/n}$ satisfies $\delta < \eta$, then there exist $R \in (1 - \sqrt{\delta}, 1)$, $\tilde{u} \in \text{GSBD}^p(Q_1)$, and $\tilde{\omega} \subset Q_R \subset\subset Q_1$, such that*

1. $\tilde{u} \in C^\infty(Q_{1-\sqrt{\delta}})$, $\tilde{u} = u$ in $Q_1 \setminus Q_R$, $\mathcal{H}^{n-1}(J_u \cap \partial Q_R) = \mathcal{H}^{n-1}(J_{\tilde{u}} \cap \partial Q_R) = 0$;

2. $\mathcal{H}^{n-1}(J_{\tilde{u}} \setminus J_u) \leq c\sqrt{\delta}\mathcal{H}^{n-1}(J_u \cap (Q_1 \setminus Q_{1-\sqrt{\delta}}))$;

3. It holds

$$\|e(\tilde{u}) - \rho_\delta * e(u)\|_{L^p(Q_{1-\sqrt{\delta}})} \leq c\delta^s \|e(u)\|_{L^p(Q)}$$

and for any open set $\Omega \subset Q$ we have

$$\int_\Omega f_0(e(\tilde{u}))dx \leq \int_{\Omega_\delta} f_0(e(u))dx + c\delta^s \int_{Q_1} f_0(e(u))dx,$$

where $\Omega_\delta := Q \cap \cup_{x \in \Omega} (x + (-3\delta, 3\delta)^n)$; and $s \in (0, 1)$ depends only on n and p .

4. $|\tilde{\omega}| \leq c\delta\mathcal{H}^{n-1}(J_u \cap Q_R)$ and $\int_{Q \setminus \tilde{\omega}} |\tilde{u} - u|^p dx \leq c\delta^p \int_Q |e(u)|^p dx$;

5. If $\psi \in \text{Lip}(Q; [0, 1])$, then

$$\int_Q \psi f_0(e(\tilde{u}))dx \leq \int_Q \psi f_0(e(u))dx + c\delta^s (1 + \text{Lip}(\psi)) \int_Q |e(u)|^p dx.$$

6. If in addition $u \in L^p(Q)$, then for $\Omega \subset Q$,

$$\|\tilde{u}\|_{L^p(\Omega)} \leq \|u\|_{L^p(\Omega)} + c\delta^{\frac{1}{2p}} (\|u\|_{L^p(Q)} + \|e(u)\|_{L^p(Q)}).$$

The constant c depends on n , p , and \mathbb{C} .

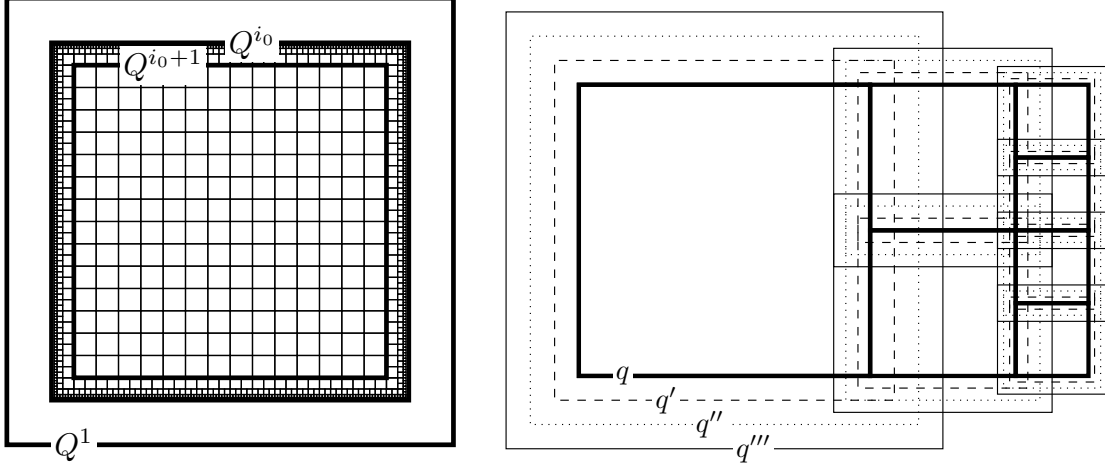


Figure 1: Sketch of the decomposition of Q^{i_0} into disjoint squares. Left: global decomposition. The refinement takes place in $C^{i_0} = Q^{i_0} \setminus Q^{i_0+1}$. Right: blow-up showing a few of the cubes q and the corresponding enlarged cubes q' , q'' , q''' . See text.

Proof. We let $\eta := 1/(2 \cdot 8^n c_*)$, where c_* is the constant entering (6). We can assume without loss of generality that $c_* \geq 1$.

Let $N := \lceil 1/\delta \rceil$, so that $(-N\delta, N\delta)^n \subseteq Q$. For $i = 0, \dots, N-1$ we let $Q^i := (- (N-i)\delta, (N-i)\delta)^n$ and $C^i := Q^i \setminus Q^{i+1}$ ($C^{N-1} = Q^{N-1}$). Up to a small translation of the Q^i 's we can assume that J_u does not intersect the boundaries ∂Q^i and that almost every point $y \in \partial Q^i$ is a Lebesgue point for $e(u)$, in the sense that

$$\mathcal{H}^{n-1}(J_u \cap \partial Q^i) = 0, \quad (8)$$

$$\lim_{r \rightarrow 0} \int_{B_r(y)} |e(u) - e(u)(y)|^p dx = 0, \quad \mathcal{H}^{n-1}\text{-a.e. } y \in \partial Q^i, \quad (9)$$

for every $i = 0, \dots, N-1$.

We choose $i_0 \in \mathbb{N} \cap [1, 1/\sqrt{\delta} - 3]$ such that (see Lemma 3.3, and observe that $(N - \lceil 1/\sqrt{\delta} \rceil + 1)\delta \geq 1 - \sqrt{\delta}$) we have both

$$\begin{cases} \int_{C^{i_0} \cup C^{i_0+1}} |e(u)|^p dx \leq 8\sqrt{\delta} \int_{Q \setminus Q_{1-\sqrt{\delta}}} |e(u)|^p dx \\ \mathcal{H}^{n-1}(J_u \cap (C^{i_0} \cup C^{i_0+1})) \leq 8\sqrt{\delta} \mathcal{H}^{n-1}(J_u \cap (Q \setminus Q_{1-\sqrt{\delta}})) \end{cases} \quad (10)$$

if δ is small enough.

Next, we cover Q^{i_0} by disjoint cubes, up to a null set. First we subdivide Q^{i_0+1} into cubes $z + (0, \delta)^n$, $z \in \delta\mathbb{Z}^n$. Then we divide the crown C^{i_0} into dyadic slabs

$$S_k := (- (N - i_0 - 2^{-k})\delta, (N - i_0 - 2^{-k})\delta)^n \setminus (- (N - i_0 - 2^{-k+1})\delta, (N - i_0 - 2^{-k+1})\delta)^n,$$

$k = 1, \dots, \infty$ and each slab S_k into σ_k cubes of the type $z + (0, \delta 2^{-k})^n$, $z \in 2^{-k} \delta \mathbb{Z}^n$, so that $\sigma_k \leq C 2^{k(n-1)} / \delta^{n-1}$. Here and henceforth C will denote a dimensional constant. We denote by \mathcal{W} the collection of these cubes and $\mathcal{W}_0 \subset \mathcal{W}$ the cubes of size δ , which cover the central cube Q^{i_0+1} (see Figure 1). For $q \in \mathcal{W}$, we let q', q'', q''' , be respectively the cubes with same center and dilated by $7/6, 4/3, 3/2$. In particular, the cubes q''' have a finite overlap; also, one has

$$\bigcup_{q \in \mathcal{W} \setminus \mathcal{W}_0} q''' \subset C^{i_0} \cup C^{i_0+1}.$$

Given $q \in \mathcal{W}$, we say that q is “good” if

$$\mathcal{H}^{n-1}(q''' \cap J_u) \leq \eta \delta_q^{n-1} \quad (11)$$

where δ_q is the size of the edge of the cube ($\delta_q = \delta$ if $q \in \mathcal{W}_0$ and $\delta 2^{-k}$ if $q \subseteq S_k$, $k \geq 1$). We say that q is “bad” if (11) is not satisfied. Observe in particular that since by definition, $\delta^n = \mathcal{H}^{n-1}(J_u) \leq \eta \delta^{n-1}$, each $q \in \mathcal{W}_0$ is good. On the other hand, there are at most (since the cubes q''' can overlap with their neighbours)

$$C(2^{k(n-1)} / \delta^{n-1}) \mathcal{H}^{n-1}(J_u \cap (S_{k-1} \cup S_k \cup S_{k+1})) / \eta$$

bad cubes in the slab S_k , with a total perimeter bounded by

$$\frac{C}{\eta} \mathcal{H}^{n-1}(J_u \cap (S_{k-1} \cup S_k \cup S_{k+1})).$$

Hence the total perimeter of the union \mathcal{B} of the bad cubes is bounded by

$$\mathcal{H}^{n-1}(\partial^* \mathcal{B}) \leq \frac{C}{\eta} \mathcal{H}^{n-1}(J_u \cap (C^{i_0} \cup C^{i_0+1})) \leq \frac{C}{\eta} \sqrt{\delta} \mathcal{H}^{n-1}(J_u \cap (Q \setminus Q_{1-\sqrt{\delta}})) \quad (12)$$

thanks to (10). Observe also that $\mathcal{B} \subset C^{i_0}$, with

$$|\mathcal{B}| \leq C \frac{\delta^{3/2}}{\eta} \mathcal{H}^{n-1}(J_u \cap (Q \setminus Q_{1-\sqrt{\delta}})).$$

We enumerate the good cubes, denoted $(q_i)_{i=1}^\infty$, and we assume that $\mathcal{W}_0 = \bigcup_{i \leq N_0} q_i$ for some $N_0 \in \mathbb{N}$. We construct a partition of unity associated to the “good” cubes (q_i) , so that $\varphi_i \in C^\infty(Q^{i_0} \setminus \bar{\mathcal{B}}; [0, 1])$, $\varphi_i = 0$ on $Q^{i_0} \setminus q'_i \setminus \mathcal{B}$, $|\nabla \varphi_i| \leq C / \delta_{q_i}$ and $\sum_i \varphi_i = 1$ on $Q^{i_0} \setminus \mathcal{B}$, the sum being locally finite. To do this, we first choose for each q'_i a function $\tilde{\varphi}_i \in C_c^\infty(q'_i; [0, 1])$ with $\tilde{\varphi}_i = 1$ on q_i and $|\nabla \tilde{\varphi}_i| \leq C / \delta_{q_i}$, then in $Q^{i_0} \setminus \mathcal{B}$ we set $\varphi_i := \tilde{\varphi}_i / (\sum_j \tilde{\varphi}_j)$. We recall that the sum runs over all good cubes and stress that the functions φ_i are not defined in \mathcal{B} .

Thanks to Prop. 3.1, for each good cube q_i one can find a set $\omega_i \subset q_i''$ with $|\omega_i| \leq c_* \delta_{q_i} \mathcal{H}^{n-1}(J_u \cap q_i''') \leq c_* \eta \delta_{q_i}^n$, and an affine function a_i with $e(a_i) = 0$ such that

$$\int_{q_i'' \setminus \omega_i} |u - a_i|^p dx \leq c \delta_{q_i}^p \int_{q_i'''} |e(u)|^p dx, \quad (13)$$

$$\int_{q_i'' \setminus \omega_i} |u - a_i|^{np/(n-1)} dx \leq c \delta_{q_i}^{n(p-1)/(n-1)} \left(\int_{q_i'''} |e(u)|^p dx \right)^{n/(n-1)}. \quad (14)$$

Moreover, given a symmetric mollifier ρ with support in $B_{1/6}$, if one lets

$$u_i := \rho_{\delta_{q_i}} * (u \chi_{q_i'' \setminus \omega_i} + a_i \chi_{\omega_i}), \quad (15)$$

then

$$\int_{q_i'} |e(u_i) - e(u) * \rho_{\delta_{q_i}}|^p dx \leq c \left(\frac{\mathcal{H}^{n-1}(J_u \cap q_i''')}{\delta_{q_i}^{n-1}} \right)^{\bar{p}} \int_{q_i'''} |e(u)|^p dx \quad (16)$$

where c depends on ρ, n, p . Observe in addition that (the mollifier being symmetric, one has $\rho_{\delta_{q_i}} * a_i = a_i$):

$$\begin{aligned} \int_{q_i'} |u_i - a_i|^p dx &= \int_{q_i'} |\rho_{\delta_{q_i}} * ((u - a_i) \chi_{q_i'' \setminus \omega_i})|^p dx \\ &\leq \int_{q_i'' \setminus \omega_i} |u - a_i|^p dx \leq c \delta_{q_i}^p \int_{q_i'''} |e(u)|^p dx \end{aligned} \quad (17)$$

thanks to (13).

Notice that if q_i and q_j are touching, one can estimate the distance between a_i and a_j . Using (13) on the two squares q_i'' and q_j'' we find

$$\begin{aligned} \|a_i - a_j\|_{L^p(q_i'' \cap q_j'' \setminus (\omega_i \cup \omega_j))} &\leq \|a_i - u\|_{L^p(q_i'' \setminus \omega_i)} + \|a_j - u\|_{L^p(q_j'' \setminus \omega_j)} \\ &\leq c \delta_{q_i} \|e(u)\|_{L^p(q_i''')} + c \delta_{q_j} \|e(u)\|_{L^p(q_j''')}. \end{aligned}$$

We now observe that by the properties of the grid, if $q_i'' \cap q_j'' \neq \emptyset$ then necessarily $|q_i'' \cap q_j''| \geq 4^{-n} \max\{|q_i|, |q_j|\}$ (the critical case is the one with two squares whose side lengths differ by a factor of 2, and which share a corner). By the choice of η , since q_i and q_j are good we obtain $|\omega_i| \leq \frac{1}{2} 8^{-n} |q_i|$, and the same for j . Therefore $|\omega_i \cup \omega_j| \leq |q_i'' \cap q_j''|/4$. Since $a_i - a_j$ is affine (see for example [9, Lemma 4.3], which generalizes immediately to parallelepipeds)

$$\|a_i - a_j\|_{L^{np/(n-1)}(q_i'' \cap q_j'')} \leq c \delta_{q_i}^{(p-1)/p} \|e(u)\|_{L^p(q_i'' \cup q_j''')}. \quad (18)$$

This is the point which motivates the choice of η .

We then define

$$\tilde{u} = \begin{cases} \sum_i u_i \varphi_i & \text{in } Q^{i_0} \setminus \mathcal{B} \\ u & \text{in } \mathcal{B} \cup (Q \setminus Q^{i_0}). \end{cases}$$

and observe that \tilde{u} is smooth in $Q^{i_0} \setminus \bar{\mathcal{B}}$, with

$$e(\tilde{u}) = \sum_i \varphi_i e(u_i) + \sum_i \nabla \varphi_i \odot u_i. \quad (19)$$

Since $\sum_i \nabla \varphi_i = 0$, we write $\nabla \varphi_i = -\sum_{j \sim i} \nabla \varphi_j$ (where $i \sim j$ if $i \neq j$ and $q'_i \cap q'_j \neq \emptyset$). Hence for each $x \in q'_i$,

$$\sum_l (\nabla \varphi_l \odot u_l)(x) = (\nabla \varphi_i \odot u_i)(x) + \sum_{j \sim i} (\nabla \varphi_j \odot u_j)(x) = \sum_{j \sim i} (\nabla \varphi_j \odot (u_j - u_i))(x). \quad (20)$$

Let now $\Omega \subset Q$ be open, and define Ω_δ as a 3δ -neighbourhood in the $\|\cdot\|_\infty$ norm, in the sense that

$$\Omega_\delta := \{x \in Q : \exists y \in \Omega, |x_i - y_i| < 3\delta \text{ for } i = 1, \dots, n\} = Q \cap \bigcup_{x \in \Omega} (x + 3(-\delta, \delta)^n).$$

The key property of this neighbourhood, which motivates the choice of the factor 3, is the fact that if $q'_i \cap \Omega \neq \emptyset$ then $q'''_i \subset \Omega_\delta$ and, additionally, for any j with $q_i \sim q_j$ one has $q'''_j \subset \Omega_\delta$. In the following, all constants will not depend on the choice of Ω .

We first introduce $\tilde{Q} := Q^{i_0+1} \setminus \bigcup_{i > N_0} q'_i$ and start with estimating (19) in \tilde{Q} , where all mollifications are at scale δ . In particular, if $x \in \tilde{Q}$, then all cubes q_j appearing in the right-hand side of (20) (with a non-vanishing term) are of size δ .

For any two good cubes $q_i \sim q_j$, $i, j \leq N_0$, we have

$$\begin{aligned} \|u_i - u_j\|_{L^p(q'_i \cap q'_j)} &= \|\rho_\delta * (u \chi_{q'_i \setminus \omega_i} + a_i \chi_{\omega_i} - u \chi_{q'_j \setminus \omega_j} - a_j \chi_{\omega_j})\|_{L^p(q'_i \cap q'_j)} \\ &\leq \|(u - a_i) \chi_{\omega_j \setminus \omega_i} - (u - a_j) \chi_{\omega_i \setminus \omega_j} + (a_i - a_j) \chi_{\omega_i \cup \omega_j}\|_{L^p(q'_i \cap q'_j)} \\ &\leq \|u - a_i\|_{L^{\frac{pn}{n-1}}(q''_i \setminus \omega_i)} |\omega_j|^{\frac{1}{np}} + \|u - a_j\|_{L^{\frac{pn}{n-1}}(q''_j \setminus \omega_j)} |\omega_i|^{\frac{1}{np}} \\ &\quad + \|a_i - a_j\|_{L^{\frac{pn}{n-1}}(q''_i \cap q''_j)} |\omega_i \cup \omega_j|^{\frac{1}{np}}. \end{aligned}$$

Recalling (14), (18), (20), and $|\nabla \varphi_i| \leq c/\delta$, we obtain

$$\left\| \sum_i \nabla \varphi_i \odot u_i \right\|_{L^p(\Omega \cap \tilde{Q})} \leq c \sum_{i: q'''_i \subset \Omega_\delta, i \leq N_0} \left(\frac{|\omega_i|^{1/n}}{\delta} \right)^{1/p} \sum_{j \sim i, j \leq N_0} \|e(u)\|_{L^p(q'''_j)}.$$

Since $|\omega_i| \leq c_* \delta^{n+1}$ for $i \leq N_0$, we see that the factor is bounded by $\delta^{1/(np)}$ and

$$\left\| \sum_{i=1}^{N_0} \nabla \varphi_i \odot u_i \right\|_{L^p(\Omega \cap \tilde{Q})} \leq c \delta^{1/(np)} \|e(u)\|_{L^p(\Omega_\delta \cap Q^{i_0})}. \quad (21)$$

It follows from (19) and (21) that

$$\begin{aligned}
& \|e(\tilde{u}) - \rho_\delta * e(u)\|_{L^p(\Omega \cap \tilde{Q})} \\
& \leq \left\| \sum_{i=1}^{N_0} \varphi_i(e(u_i) - e(u) * \rho_\delta) \right\|_{L^p(\Omega \cap \tilde{Q})} + c\delta^{1/(np)} \|e(u)\|_{L^p(\Omega_\delta \cap Q^{i_0})} \\
& \leq \sum_{i \leq N_0, q_i''' \subset \Omega_\delta} \|e(u_i) - e(u) * \rho_\delta\|_{L^p(q_i')} + c\delta^{1/(np)} \|e(u)\|_{L^p(\Omega_\delta \cap Q^{i_0})} \\
& \leq c \sum_{i \leq N_0, q_i''' \subset \Omega_\delta} \left(\frac{\mathcal{H}^{n-1}(J_u \cap q_i''')}{\delta^{n-1}} \right)^{\frac{\bar{p}}{p}} \|e(u)\|_{L^p(q_i''')} + c\delta^{1/(np)} \|e(u)\|_{L^p(\Omega_\delta \cap Q^{i_0})} \\
& \leq c\delta^s \|e(u)\|_{L^p(\Omega_\delta \cap Q^{i_0})} \quad (22)
\end{aligned}$$

where $s := \min\{\bar{p}/p, 1/(np)\}$ and we have used (16). We deduce the first assertion in Property 3. by choosing $\Omega = Q_{1-\sqrt{\delta}}$. In addition, it follows that

$$\begin{aligned}
\left(\int_{\Omega \cap \tilde{Q}} f_0(e(\tilde{u})) dx \right)^{1/p} & \leq \left(\int_{\Omega \cap \tilde{Q}} f_0(e(u) * \rho_\delta) dx \right)^{1/p} + c\delta^s \|e(u)\|_{L^p(\Omega_\delta \cap Q^{i_0})} \\
& \leq \left(\int_{\Omega_\delta \cap \tilde{Q}} f_0(e(u)) dx \right)^{1/p} + c\delta^s \|e(u)\|_{L^p(\Omega_\delta \cap Q^{i_0})} \\
& \leq (1 + c\delta^s) \left(\int_{\Omega_\delta \cap Q^{i_0}} f_0(e(u)) dx \right)^{1/p}. \quad (23)
\end{aligned}$$

Observing that for $\delta \leq \eta \leq 1$, $(1 + c\delta^s)^p \leq 1 + pc(1 + c)^{p-1}\delta^s$, we end up with the estimate

$$\int_{\Omega \cap \tilde{Q}} f_0(e(\tilde{u})) dx \leq (1 + c\delta^s) \int_{\Omega_\delta \cap Q^{i_0}} f_0(e(u)) dx. \quad (24)$$

We now turn to the boundary layer and estimate $\int_{\Omega \cap Q^{i_0} \setminus \tilde{Q}} f_0(e(\tilde{u})) dx$. This is done in a similar way, however less precise, and we only find that

$$\int_{\Omega \cap Q^{i_0} \setminus \tilde{Q}} f_0(e(\tilde{u})) dx \leq c \int_{\Omega_\delta \cap (C^{i_0} \cup C^{i_0+1})} f_0(e(u)) dx. \quad (25)$$

Indeed, for now $i > N_0$ (that is, q_i a good cube at scale $\delta 2^{-k}$ for some $k \geq 1$), one writes first that (using again that $\rho_{\delta q_i} * a_i = a_i$ since ρ is even),

$$\begin{aligned}
\|e(u_i)\|_{L^p(q_i')} & = \|e(u_i - a_i)\|_{L^p(q_i')} = \|e(\rho_{\delta q_i} * (u \chi_{q_i'' \setminus \omega_i} + a_i \chi_{\omega_i} - a_i))\|_{L^p(q_i')} \\
& \leq \frac{\|\nabla \rho\|_{L^1}}{\delta_{q_i}} \|u - a_i\|_{L^p(q_i'' \setminus \omega_i)} \leq C \|e(u)\|_{L^p(q_i''')},
\end{aligned}$$

thanks to (13). Hence, to show (25) it remains to estimate $\|\sum_i \nabla \varphi_i \odot u_i\|_{L^p(q_i')}$ for $i > N_0$. As before we observe that this is bounded by

$$\sum_{j \sim i} \|\nabla \varphi_j \odot (u_i - u_j)\|_{L^p(q_j' \cap q_i')}$$

and thanks to the fact that $|\nabla\varphi_i| \leq C/\delta_{q_i}$ and, when $j \sim i$, $\delta_{q_j} \in \{(1/2)\delta_{q_i}, \delta_{q_i}, 2\delta_{q_i}\}$, each term in the sum is bounded by

$$\frac{C}{\delta_{q_i}} \|u_i - a_i\|_{L^p(q'_i)} + \frac{C}{\delta_{q_j}} \|u_j - a_j\|_{L^p(q'_j)} + \frac{C}{\delta_{q_i}} \|a_i - a_j\|_{L^p(q'_i \cap q'_j)}.$$

Thanks to (17) and (18), this is bounded by $\|e(u)\|_{L^p(q''_i \cup q''_j)}$ and (25) follows.

Hence using (10) and $\tilde{u} = u$ in $\mathcal{B} \cup Q \setminus Q^{i_0}$ we get

$$\int_{\Omega} f_0(e(\tilde{u})) dx \leq (1 + c\delta^s) \int_{\Omega_{\delta}} f_0(e(u)) dx + c\sqrt{\delta} \int_{Q \setminus Q_{1-\sqrt{\delta}}} f_0(e(u)) dx. \quad (26)$$

Using $s < 1/2$, we deduce Property 3.

Let now $\psi \in \text{Lip}(Q; [0, 1])$. Then

$$\int_Q \psi f_0(e(\tilde{u})) dx = \int_Q \int_0^{\psi(x)} f_0(e(\tilde{u})) dx dt = \int_0^1 \int_{\{x: t < \psi(x)\}} f_0(e(\tilde{u})) dx dt.$$

If $\Omega = \{x : t < \psi(x)\}$, then $\Omega_{\delta} \subset \{x : t < \psi(x) + c_{\psi}\delta\}$, where $c_{\psi} = 3n^{1/2}\text{Lip}(\psi)$.

Therefore (26) implies

$$\begin{aligned} & \int_Q \psi f_0(e(\tilde{u})) dx \\ & \leq \int_0^1 \left((1 + c\delta^s) \int_{\{x: t < \psi(x) + c_{\psi}\delta\}} f_0(e(u)) dx + c\sqrt{\delta} \int_{Q \setminus Q_{1-\sqrt{\delta}}} f_0(e(u)) dx \right) dt \\ & = (1 + c\delta^s) \int_Q (\psi(x) + c_{\psi}\delta) f_0(e(u)) dx + c\sqrt{\delta} \int_{Q \setminus Q_{1-\sqrt{\delta}}} f_0(e(u)) dx. \end{aligned}$$

This proves Property 5.

We finally estimate the distance between \tilde{u} and u outside of $\tilde{\omega} := \bigcup_i \omega_i \setminus \mathcal{B}$. We find by (13) and (17):

$$\begin{aligned} \int_{Q \setminus \tilde{\omega}} |\tilde{u} - u|^p dx & \leq c \sum_i \int_{q'_i \setminus \omega_i} |u_i - u|^p dx \leq \\ & \leq c \sum_i \int_{q'_i} |u_i - a_i|^p dx + c \sum_i \int_{q'_i \setminus \omega_i} |u - a_i|^p dx \leq c\delta^p \int_Q |e(u)|^p dx. \quad (27) \end{aligned}$$

This proves Property 4, together with the observation² that $|\omega_i| \leq c_* \delta \mathcal{H}^{n-1}(J_u \cap q''_i)$.

One has moreover $J_{\tilde{u}} \cap Q^{i_0} \subseteq \partial^* \mathcal{B} \cup (J_u \setminus Q^{i_0+1})$, and $J_{\tilde{u}} \setminus J_u \subseteq \partial^* \mathcal{B}$, which is bounded by (12).

²[5, Prop. 6] shows that, in fact, one could ensure that $|\omega_i| \leq c \mathcal{H}^{n-1}(J_u \cap q''_i)^{n/(n-1)}$. With our choice of δ , this improves the inequality to $|\omega_i| \leq c \delta^{n/(n-1)} \mathcal{H}^{n-1}(J_u \cap q''_i)$. Hence the first point in Prop. 4 could be improved, in fact, to $|\tilde{\omega}| \leq c \delta^{n/(n-1)} \mathcal{H}^{n-1}(J_u \cap Q_R) \approx \mathcal{H}^{n-1}(J_u \cap Q_R)^{n/(n-1)}$.

For $y \in \partial Q^{i_0}$ one also obtains (letting $\delta_k := \delta 2^{-k}$) that

$$\int_{B_{\delta_k}(y) \setminus \tilde{\omega}} |\tilde{u} - u|^p dx \leq C \delta^p 2^{-kp} \int_{B_{\delta_{k-1}}(y)} |e(u)|^p dx,$$

while $|\tilde{\omega} \cap B_{\delta_k}(y)| \leq C \delta_k (1 + 1/\eta) \mathcal{H}^{n-1}(J_u \cap B_{\delta_{k-1}}(y))$. Hence we have for every $\varepsilon > 0$ and for \mathcal{H}^{n-1} -a.e. $y \in \partial Q^{i_0}$

$$\begin{aligned} \frac{1}{\delta_k^n} |\{|\tilde{u} - u| > \varepsilon\} \cap B_{\delta_k}(y)| &\leq \\ &\leq \frac{|\tilde{\omega} \cap B_{\delta_k}(y)|}{\delta_k^n} + \frac{1}{\varepsilon} \left(\int_{B_{\delta_k}(y) \setminus \tilde{\omega}} |\tilde{u} - u|^p dx \right)^{1/p} \\ &\leq \frac{c \mathcal{H}^{n-1}(J_u \cap B_{\delta_k}(y))}{\delta_k^{n-1}} + c \delta_k \left(\int_{B_{\delta_{k-1}}(y)} |e(u)|^p dx \right)^{1/p}, \end{aligned}$$

with the last line which vanishes as $\delta_k \downarrow 0$ thanks to (8). Hence one can deduce that the trace of \tilde{u} on ∂Q^{i_0} coincides with the inner trace of u , showing that \tilde{u} is *GSBD* when extended with the value of u out of Q^{i_0} , with $J_{\tilde{u}} \setminus Q^{i_0} = J_u$. In particular we obtain that

$$\tilde{u} \in \text{GSBD}^p(Q) \cap C^\infty(Q^{i_0+1}), \quad \text{and} \quad \tilde{u} \in C^\infty((-1 - \sqrt{\delta}, 1 - \sqrt{\delta})^n).$$

Assume eventually that $u \in L^p(Q; \mathbb{R}^n)$, and let us show also that we can ensure also Property 6. in this case. Let $\Omega \subset Q$. One now has thanks to (27)

$$\|\tilde{u}\|_{L^p(\Omega)} \leq \|u\|_{L^p(\Omega \setminus \tilde{\omega})} + c\delta \|e(u)\|_{L^p(Q)} + \|\tilde{u}\|_{L^p(\Omega \cap \tilde{\omega})} \quad (28)$$

and we need to estimate the last term, starting from the fact that

$$\int_{\Omega \cap \tilde{\omega}} |\tilde{u}|^p dx \leq \sum_{i=1}^{\infty} \int_{\Omega \cap q'_i \cap \tilde{\omega}} |u_i|^p dx. \quad (29)$$

For each $i \geq 1$,

$$\begin{aligned} \int_{\Omega \cap q'_i \cap \tilde{\omega}} |u_i|^p dx &\leq c \int_{\Omega \cap q'_i \cap \tilde{\omega}} |u_i - a_i|^p dx + c \int_{\Omega \cap q'_i \cap \tilde{\omega}} |a_i|^p dx \\ &\leq c \delta_{q'_i}^p \int_{q_i'''} |e(u)|^p dx + c \int_{\Omega \cap q'_i \cap \tilde{\omega}} |a_i|^p dx \quad (30) \end{aligned}$$

thanks to (17). We now consider q_i such that $q'_i \cap \Omega \neq \emptyset$. Notice that

$$|\tilde{\omega} \cap q'_i| \leq c_* \left[\delta_{q_i} \mathcal{H}^{n-1}(J_u \cap q_i''') + \sum_{j \sim i} \delta_{q_j} \mathcal{H}^{n-1}(J_u \cap q_j''') \right] \leq c_* \min\{3^n \delta^{n+1}, 6^n \eta \delta_{q_i}^n\},$$

which is small if η is small enough. In this case, thanks to Lemma 3.4 (and more precisely its consequence (32))³

$$\int_{\Omega \cap q'_i \cap \tilde{\omega}} |a_i|^p dx \leq c \frac{|\tilde{\omega} \cap q'_i|}{|q_i|} \int_{q_i \setminus \tilde{\omega}_i} |a_i|^p dx \leq c \frac{|\tilde{\omega} \cap q'_i|}{|q_i|} \int_{q_i \setminus \tilde{\omega}_i} (|u - a_i|^p + |u|^p) dx.$$

The first term in the integral is estimated as usual with $\delta_{q_i}^p \int_{q_i} |e(u)|^p dx$, while, for the second, we use that

$$\frac{|\tilde{\omega} \cap q'_i|}{|q_i|} \leq \begin{cases} 3^n c_* \delta & \text{if } i \leq N_0, \\ 6^n c_* \eta & \text{if } i > N_0 \end{cases}$$

to deduce

$$\sum_i \int_{\Omega \cap q'_i \cap \tilde{\omega}} |a_i|^p dx \leq c \delta^p \int_Q |e(u)|^p dx + c \delta \int_{\Omega_\delta \cap Q^{i_0+1}} |u|^p dx + c \eta \int_{\Omega_\delta \cap C^{i_0}} |u|^p dx.$$

Using (29), (30), we find

$$\int_{\Omega \cap \tilde{\omega}} |\tilde{u}|^p dx \leq c \delta^p \int_Q |e(u)|^p dx + c \delta \int_{\Omega_\delta} |u|^p dx + c \eta \int_{\Omega_\delta \cap C^{i_0}} |u|^p dx.$$

To estimate the last term, there are two possible strategies: one is to send $\eta \rightarrow 0$ as $\delta \rightarrow 0$, the other which we adopt here is to require, when selecting the index i_0 , that in addition to (10) it satisfies:

$$\int_{C^{i_0}} |u|^p dx \leq 8\sqrt{\delta} \int_{Q \setminus Q_{1-\sqrt{\delta}}} |u|^p dx,$$

which can be ensured in the same way. We deduce in this case that

$$\int_{\Omega \cap \tilde{\omega}} |\tilde{u}|^p dx \leq c \delta^p \int_Q |e(u)|^p dx + c \delta \int_{\Omega_\delta} |u|^p dx + c \sqrt{\delta} \int_{Q \setminus Q_{1-\sqrt{\delta}}} |u|^p dx. \quad (31)$$

Hence we obtain Property 6. from (28) and (31). □

Lemma 3.3. *Let $a_i \geq 0$, $b_i \geq 0$ be such that*

$$\sum_{i=1}^k a_i \leq A \quad \text{and} \quad \sum_{i=1}^k b_i \leq B.$$

Then there is $j \in \{1, \dots, k\}$ such that

$$a_j \leq \frac{2}{k} A \quad \text{and} \quad b_j \leq \frac{2}{k} B.$$

³this requires an additional condition on η which might need to be reduced.

Proof. We write

$$\sum_{i=1}^k \frac{a_i}{A} + \frac{b_i}{B} \leq 2$$

and choose j as one index for which the summand is minimal. Notice that if $A = 0$ then all a_i are also 0. \square

Lemma 3.4. *Let $q \subset \mathbb{R}^n$ be a cube, and $\omega \subset q$ and $p \geq 1$: there exists a constant c (depending only on n, p) such that*

$$\int_{\omega} |a|^p dx \leq c \frac{|\omega|}{|q|} \int_q |a|^p dx$$

for any affine function $a : q \rightarrow \mathbb{R}$.

If $\theta < 1$ and θq is the cube with same center as q and sides multiplied by θ , it is possible to show by a direct computation that for a affine,

$$\|a\|_{L^p(q)} \leq \frac{1}{\theta^{n/p+1}} \|a\|_{L^p(\theta q)}.$$

Hence one can also deduce (for $c = c(n, p, \theta)$)

$$\int_{\omega} |a|^p dx \leq c \frac{|\omega|}{|q|} \int_{\theta q} |a|^p dx;$$

additionally if $\frac{|\omega|}{|q|}$ is small enough (so that $\frac{|\omega|}{|q|} \left(1 - c \frac{|\omega|}{|q|}\right)^{-1} \leq 2 \frac{|\omega|}{|q|}$), we deduce

$$\int_{\omega} |a|^p dx \leq c \frac{|\omega|}{|q|} \int_{\theta q \setminus \omega} |a|^p dx. \quad (32)$$

Proof. By translation and scaling, it is enough to show the lemma for $q = (0, 1)^n$. Then, $\|a\|_{L^p(q)}$ is a norm on the finite-dimensional space of affine functions. Hence there exists c (depending only on p) such that $\sup_{x \in q} |a(x)| \leq c \|a\|_{L^p(q)}$. We conclude by observing that $(1/|\omega|) \int_{\omega} |a(x)|^p dx \leq \sup_{x \in q} |a(x)|^p$ for any $\omega \subset q$. \square

4 Limit of minimizing sequences with vanishing jump

Let $\kappa \geq 0$, $\beta > 0$, $p > 1$, $g \in L^\infty(\Omega; \mathbb{R}^n)$, $\mu \geq 0$, and let $\Omega \subset \mathbb{R}^n$ be a bounded, open, Lipschitz set. For all $u \in GSBD(\Omega)$ and all Borel sets $A \subset \Omega$ let us define the functional

$$G(u, \kappa, \beta, A) := \int_A f_\mu(e(u)) dx + \kappa \int_A |u - g|^p dx + \beta \mathcal{H}^{n-1}(J_u \cap A), \quad (33)$$

where

$$f_\mu(\xi) := \frac{1}{p} \left((C\xi \cdot \xi + \mu)^{p/2} - \mu^{p/2} \right) \quad (34)$$

and \mathbb{C} is a symmetric linear map from $\mathbb{R}^{n \times n}$ to itself which satisfies (1).

We assume that u is a local minimizer of G in $GSBD(\Omega)$. We remark that, if $\kappa > 0$, then a global minimizer exists by [14, Theorem 11.3].

Let us introduce the following homogeneous version of G

$$G_0(u, \kappa, \beta, A) := \int_A f_0(e(u))dx + \kappa \int_A |u|^p dx + \beta \mathcal{H}^{n-1}(J_u \cap A),$$

which will be useful to establish the decay estimate and the density lower bound. For open sets $A \subset \Omega$ we define also the deviation from minimality

$$\Psi_0(u, \kappa, \beta, A) := G_0(u, \kappa, \beta, A) - \Phi_0(u, \kappa, \beta, A),$$

where

$$\Phi_0(u, \kappa, \beta, A) := \inf\{G_0(v, \kappa, \beta, A) : v \in GSBD(\Omega), \{v \neq u\} \llcorner A\}. \quad (35)$$

The minimality of the limit u of energy-minimizing sequences u_h with vanishing jump sets is established similarly to [11, Prop. 3.3]. Any competitor of u is modified close to the boundary of the domain in order to become a competitor of $u_h - a_h$ for G_0 . Estimating in L^p the symmetric gradient of the transition, one obtains a term of the form $|u_h - a_h - u|^p$, which is known to vanish only a.e. and not in L^1 . Therefore an intermediate interpolation step which passes through $\tilde{u}_h - a_h$ becomes necessary. The functions \tilde{u}_h , constructed via Theorem 3, are smooth away from a small neighborhood of the boundary, whose size decreases as $h \rightarrow \infty$. This permits to perform the entire construction in $W^{1,p}$ and greatly simplifies the computations.

The following theorem is the generalization to arbitrary dimension of [11, Prop. 3.4]. Notice that the proof is made a bit easier with respect to [11, Prop. 3.4] by the fact that the approximation we employ (see Section 3) is more precise than the one employed in [11] (see [12, Sections 2 and 3]).

Theorem 4 (Convergence and minimality). *Let $p \in (1, \infty)$. Let Q_r be a cube, $u_h \in GSBD^p(Q_r)$ and $\kappa_h \in [0, \infty)$, $\beta_h \in (0, \infty)$ be two sequences with $\kappa_h \rightarrow 0$ as $h \rightarrow \infty$, and such that*

$$\sup_h G_0(u_h, \kappa_h, \beta_h, Q_r) < \infty, \text{ and } \lim_{h \rightarrow \infty} \Psi_0(u_h, \kappa_h, \beta_h, Q_r) = \lim_{h \rightarrow \infty} \mathcal{H}^{n-1}(J_{u_h}) = 0.$$

Then there exist $u \in W^{1,p}(Q_r; \mathbb{R}^n)$, $\bar{a} : \mathbb{R}^n \rightarrow \mathbb{R}^n$ affine with $e(\bar{a}) = 0$, and a subsequence h_j such that

1. for all $t \in (0, r)$

$$\lim_{j \rightarrow \infty} G_0(u_{h_j}, \kappa_{h_j}, \beta_{h_j}, Q_t) = \int_{Q_t} f_0(e(u))dx + \int_{Q_t} |\bar{a}|^p dx;$$

2. for all $v \in u + W_0^{1,p}(Q_r)$

$$\int_{Q_r} f_0(e(u))dx \leq \int_{Q_r} f_0(e(v))dx;$$

3. $u_{h_j} - a_j \rightarrow u$ pointwise \mathcal{L}^n -a.e. on Q_r for some affine functions a_j , $e(u_{h_j}) \rightarrow e(u)$ in $L^p(Q_t)$, $\beta_{h_j} \mathcal{H}^{n-1}(J_{u_{h_j}} \cap Q_t) \rightarrow 0$, and $\kappa_{h_j}^{1/p} u_{h_j} \rightarrow \bar{a}$ in $L^p(Q_t)$ for all $t \in (0, r)$.

Proof. We assume $r = 1$ (wlog) and we denote $Q := Q_1$. By monotonicity, after taking a subsequence (not relabelled) we can assume that for all $s \in (0, 1]$,

$$\lim_{h \rightarrow \infty} G_0(u_h, \kappa_h, \beta_h, Q_s) =: \Lambda(s)$$

exists and is finite. Since $\kappa_h^{1/p} u_h$ is bounded in $L^p(Q)$, it has a subsequence converging to some \bar{a} , weakly. By [5, Prop. 2] there exist ω_h, a_h such that $|\omega_h| \leq c\mathcal{H}^{n-1}(J_{u_h})$ and

$$\int_{Q \setminus \omega_h} |u_h - a_h|^p dx \leq C \int_Q |e(u_h)|^p dx$$

which is bounded. Therefore $\kappa_h^{1/p}(u_h - a_h)\chi_{Q \setminus \omega_h} \rightarrow 0$ strongly in L^p . Recalling that $\kappa_h^{1/p} u_h \rightharpoonup \bar{a}$ weakly in L^p , we deduce $\chi_{Q \setminus \omega_h} \kappa_h^{1/p} a_h \rightarrow \bar{a}$ and then $\kappa_h^{1/p} a_h \rightarrow \bar{a}$, since $|\omega_h| \rightarrow 0$ and a_h are affine functions. Being the space of affine functions finite dimensional, the convergence $\kappa_h^{1/p} a_h \rightarrow \bar{a}$ is in fact strong in L^p and \bar{a} is a linearized rigid motion. Also, observe that still up to a subsequence,

$$(u_h - a_h)\chi_{Q \setminus \omega_h} \rightharpoonup u \text{ in } L^p(Q),$$

for some $u \in L^p(Q; \mathbb{R}^n)$.

Let $t \in (0, 1]$ be a point of (left) continuity of Λ . Let $\delta_h = \mathcal{H}^{n-1}(J_{u_h} \cap Q_t)^{1/n}$ and let $\tilde{u}_h, \tilde{\omega}_h$ be the functions and sets obtained applying Theorem 3 in Q_t , which obey $(\tilde{u}_h - u_h)\chi_{Q_t \setminus \tilde{\omega}_h} \rightarrow 0$ in L^p thanks to Property 4. in Theorem 3.

We have that up to a subsequence, $\tilde{u}_h - a_h \rightarrow \tilde{u}$ in $W^{1,p}(Q_s)$ for every $s < t$. In fact, $\tilde{u} = u$ and we do not have to extract a subsequence at this stage. Indeed, given $\varphi \in C_c^\infty(Q_t)$, one has

$$\begin{aligned} \int_{Q_t} (\tilde{u}_h - a_h) \cdot \varphi dx &= \int_{Q_t \cap (\omega_h \cup \tilde{\omega}_h)} (\tilde{u}_h - a_h) \cdot \varphi dx + \\ &+ \int_Q [(u_h - a_h)\chi_{Q \setminus \omega_h}] \cdot [\varphi\chi_{Q_t \setminus \tilde{\omega}_h}] dx + \int_{Q_t} [(\tilde{u}_h - u_h)\chi_{Q_t \setminus \tilde{\omega}_h}] \cdot \varphi\chi_{Q_t \setminus \omega_h} dx \\ &\rightarrow \int_Q u \cdot \varphi dx \end{aligned}$$

as $h \rightarrow \infty$, which shows the claim.

Observe now that thanks to Property 3. of Theorem 3, any weak limit of $e(u_h)$ in $L^p(Q_t)$ must coincide with the weak limit of $e(\tilde{u}_h)$, which is $e(u)$. We deduce that $e(u_h) \rightharpoonup e(u)$ in $L^p(Q_t)$ and in particular that

$$\int_{Q_t} f_0(e(u))dx \leq \liminf_{h \rightarrow \infty} \int_{Q_t} f_0(e(u_h))dx. \quad (36)$$

Using also that $\kappa_h^{1/p} u_h \rightharpoonup \bar{a}$ in $L^p(Q)$, we deduce that

$$\int_{Q_t} f_0(e(u)) + |\bar{a}|^p dx \leq \Lambda(t). \quad (37)$$

Consider now $v \in W^{1,p}(Q_t; \mathbb{R}^n)$ with $\{v \neq u\} \subset\subset Q_t$. Let $\psi \in C_c(Q_t)$ be a Lipschitz cut-off with $\{0 < \psi < 1\} \subset \{v = u\} \cap Q_{t'}$ for some $t' < t$. If h is large enough, one also has that $\tilde{u}_h \in W^{1,p}(Q_{t'}; \mathbb{R}^n)$. We let $v_h := (\tilde{u}_h - a_h)(1 - \psi) + \psi v$. Then, for large h one has $v_h \in W^{1,p}(Q_{t'}; \mathbb{R}^n)$ and $\{v_h + a_h \neq u_h\} \subset\subset Q_t$, so that by definition of Ψ_0 we have

$$G_0(u_h, \kappa_h, \beta_h, Q_t) \leq \Psi_0(u_h, \kappa_h, \beta_h, Q_1) + G_0(v_h + a_h, \kappa_h, \beta_h, Q_t), \quad (38)$$

which we write as

$$\begin{aligned} & \int_{Q_t} (f_0(e(u_h)) + \kappa_h |u_h|^p) dx + \beta_h \mathcal{H}^{n-1}(J_{u_h} \cap Q_t) \\ & \leq \int_{Q_t} (f_0(e(v_h)) + \kappa_h |v_h + a_h|^p) dx + \beta_h \mathcal{H}^{n-1}(J_{v_h} \cap Q_t) + o(1). \end{aligned} \quad (39)$$

Recalling that (by Properties 1. and 2. of Theorem 3) $J_{v_h} \subset J_{\tilde{u}_h} \subset Q_t \setminus Q_{t-\sqrt{\delta_h}}$ and $\mathcal{H}^{n-1}(J_{\tilde{u}_h} \setminus J_{u_h}) \leq c\sqrt{\delta_h} \mathcal{H}^{n-1}(J_{u_h})$, we then subtract $\beta_h \mathcal{H}^{n-1}(J_{u_h} \cap Q_t \setminus Q_{t-\sqrt{\delta_h}})$ from both sides of inequality (39) and we deduce

$$\begin{aligned} & \int_{Q_t} (f_0(e(u_h)) + \kappa_h |u_h|^p) dx + \beta_h \mathcal{H}^{n-1}(J_{u_h} \cap Q_{t-\sqrt{\delta_h}}) \\ & \leq \int_{Q_t} (f_0(e(v_h)) + \kappa_h |v_h + a_h|^p) dx + o(1). \end{aligned} \quad (40)$$

We have $e(v_h) = \psi e(v) + (1 - \psi)e(\tilde{u}_h) + \nabla \psi \odot (v - \tilde{u}_h + a_h)$. Recalling that $\tilde{u}_h - a_h \rightarrow u$ in $L^p_{\text{loc}}(Q_t)$ and that $v = u$ outside of $\{\psi = 1\}$, we obtain $\tilde{u}_h - a_h - v \rightarrow 0$ in $L^p(\{0 < \psi < 1\})$. Hence

$$\int_{Q_t} f_0(e(v_h)) dx \leq (1 + o(1)) \left[\int_{Q_t} \psi f_0(e(v)) dx + \int_{Q_t} (1 - \psi) f_0(e(\tilde{u}_h)) dx \right] + o(1).$$

By 5. in Theorem 3 we find

$$\int_{Q_t} (1 - \psi) f_0(e(\tilde{u}_h)) dx \leq \int_{Q_t} (1 - \psi) f_0(e(u_h)) dx + o(1),$$

so that subtracting $(1 - \psi)f_0(e(u_h))$ from both sides of (40) we conclude

$$\begin{aligned} \int_{Q_t} (\psi f_0(e(u_h)) + \kappa_h |u_h|^p) dx + \beta_h \mathcal{H}^{n-1}(J_{u_h} \cap Q_{t-\sqrt{\delta_h}}) \\ \leq \int_{Q_t} (\psi f_0(e(v)) + \kappa_h |v_h + a_h|^p) dx + o(1). \end{aligned} \quad (41)$$

Similarly, thanks to Property 6. of Theorem 3 we have:

$$\begin{aligned} \kappa_h \int_{Q_t} (1 - \psi) |\tilde{u}_h|^p dx \\ = \kappa_h \int_0^1 \left(\int_{Q_t \cap \{1-\psi > s\}} |\tilde{u}_h|^p dx \right) ds \leq \kappa_h \int_0^1 \left(\int_{Q_t \cap \{1-\psi > s\}} |u_h|^p dx + o(1) \right) ds \\ \leq \kappa_h \int_{Q_t} (1 - \psi) |u_h|^p dx + o(1) \end{aligned}$$

so that, since $v_h + a_h = \psi(v + a_h) + (1 - \psi)\tilde{u}_h$, we deduce from (41)

$$\begin{aligned} \int_{Q_t} \psi (f_0(e(u_h)) + \kappa_h |u_h|^p) dx + \beta_h \mathcal{H}^{n-1}(J_{u_h} \cap Q_{t-\sqrt{\delta_h}}) \\ \leq \int_{Q_t} \psi (f_0(e(v)) + \kappa_h |v + a_h|^p) dx + o(1). \end{aligned} \quad (42)$$

Observe that $\kappa_h^{1/p} |v + a_h| \rightarrow |\bar{a}|$ strongly. Then, recalling (36) and the convergence $\kappa_h^{1/p} u_h \rightharpoonup \bar{a}$ in L^p , we obtain in the limit

$$\int_{Q_t} \psi (f_0(e(u)) + |\bar{a}|^p) dx \leq \int_{Q_t} \psi (f_0(e(v)) + |\bar{a}|^p) dx.$$

Since $v = u$ outside of $\{\psi = 1\}$, we may add $(1 - \psi)f_0(e(u))$ to both sides and we find

$$\int_{Q_t} f_0(e(u)) dx \leq \int_{Q_t} f_0(e(v)) dx \quad (43)$$

which implies Property 2. of the Theorem.

Next we show Property 1., namely that:

$$\Lambda(t) = \int_{Q_t} (f_0(e(u)) + |\bar{a}|^p) dx. \quad (44)$$

For this we choose $v = u$ in (42), and let $\bar{t} < t$ be such that $\psi \equiv 1$ in $Q_{\bar{t}}$, then we find as $h \rightarrow \infty$ that

$$\Lambda(\bar{t}) \leq \int_{Q_t} \psi (f_0(e(u)) + |\bar{a}|^p) dx \leq \Lambda(t)$$

thanks to (37). Since t is a point of continuity of Λ , (44) follows, sending \bar{t} to t . In particular, we deduce that every $t \in (0, 1]$ is a point of continuity of Λ .

It remains to show Properties 3. The fact that $\lim_h \beta_h \mathcal{H}^{n-1}(J_{u_h} \cap Q_t) = 0$ and that $e(u_h) \rightarrow e(u)$, $\kappa_h^{1/p} u_h \rightarrow \bar{a}$ strongly easily follows from Property 1. Finally, as $t = 1$ is a point of (left) continuity of Λ , the above construction applied to Q_1 provides \tilde{u}_h such that $(\tilde{u}_h - a_h)_h$ converges strongly to u in $L^p_{\text{loc}}(Q_1)$, and therefore, also $u_h \chi_{Q_1 \setminus \tilde{\omega}_h}$ converges to u in $L^p_{\text{loc}}(Q_1)$. Hence, possibly extracting a last subsequence, we may also assume that $u_h \rightarrow u$ a.e. in Q_1 . \square

We conclude this section by stating explicitly the compactness and semicontinuity result for functions with vanishing jump sets which has been proved within the proof of Theorem 4.

Corollary 4.1 (Compactness and semicontinuity). *Let $p \in (1, \infty)$ and let $u_k \in GSBD^p(Q_1)$ be such that*

$$\sup_k \int_{Q_1} f_0(e(u_k)) dx < \infty, \quad \delta_k := \mathcal{H}^{n-1}(J_{u_k})^{1/n} \rightarrow 0. \quad (45)$$

Then there are a subsequence k_h of k , a sequence $\tilde{u}_h \in GSBD^p(Q_1) \cap C^\infty(Q_{1-\sqrt{\delta_{k_h}}})$ with $\{\tilde{u}_h \neq u_{k_h}\} \subset\subset Q_1$, affine functions $a_h : \mathbb{R}^n \rightarrow \mathbb{R}^n$ with $e(a_h) = 0$, and $u \in W^{1,p}(Q_1; \mathbb{R}^n)$, such that

1. $\tilde{u}_h - a_h \rightarrow u$ in $L^p_{\text{loc}}(Q_1)$ and $u_{k_h} - a_h \rightarrow u$ \mathcal{L}^n -a.e. on Q_1 ;
2. for every r, s with $r < s < 1$ we have

$$\begin{aligned} \int_{Q_1 \setminus Q_s} f_0(e(\tilde{u}_h)) dx &\leq (1 + o(1)) \int_{Q_1 \setminus Q_r} f_0(e(u_{k_h})) dx, \\ \mathcal{H}^{n-1}(J_{\tilde{u}_h} \cap (Q_1 \setminus Q_r)) &\leq (1 + o(1)) \mathcal{H}^{n-1}(J_{u_{k_h}} \cap (Q_1 \setminus Q_r)), \\ \int_{Q_1 \setminus Q_r} |\tilde{u}_h|^p dx &\leq \int_{Q_1 \setminus Q_r} |u_{k_h}|^p dx + o(1) \int_{Q_1} (|u_{k_h}|^p + f_0(e(u_{k_h}))) dx; \end{aligned}$$

3. the following lower estimate holds for all $t \in (0, 1]$:

$$\int_{Q_t} f_0(e(u)) dx \leq \liminf_{k \rightarrow \infty} \int_{Q_t} f_0(e(u_k)) dx. \quad (46)$$

Proof. For large h we can apply Theorem 3 to obtain $\tilde{u}_k \in GSBD(Q_1)$ from u_k . By Properties 1. and 3. up to a subsequence and a rigid motion a_k the sequence \tilde{u}_k converges in $L^p_{\text{loc}}(Q_1)$ to a limit $u \in W^{1,p}(Q_1)$. Moreover $(u_k - a_k) \chi_{Q_1 \setminus \tilde{\omega}_k}$ converges also to u in $L^p_{\text{loc}}(Q_1)$ by Theorem 3, Property 4. Since $|\tilde{\omega}_k| \rightarrow 0$ we can deduce that $u_k - a_k$ converges to u in measure and then up to subsequences also almost everywhere in Q_1 .

The assertion in 2. directly follows by Theorem 3, Properties 2., 4., 5., and 6. Let now $0 < t' < t < 1$. Then $e(\tilde{u}_k) \rightharpoonup e(u)$ in $L^p(Q_t)$, and using convexity of f_0 and then Property 3. of Theorem 3 we obtain

$$\int_{Q_{t'}} f_0(e(u)) dx \leq \liminf_k \int_{Q_{t'}} f_0(e(\tilde{u}_k)) dx \leq \liminf_k \int_{Q_t} f_0(e(u_k)) dx.$$

By continuity of the left-hand side we deduce first the case $t' = t$ and then the case $t = 1$. \square

5 Existence of Griffith's minimizers in dimension n

The following statements follow from Theorem 4 with exactly the same proof as [11, Lemma 3.8 and Corollary 3.9] respectively.

The following density lower bound is explicitly stated for $p = 2$. In that case, it is well-known that solutions of $\operatorname{div} \mathbb{C}e(u) = 0$ are smooth and can be computed using a (\mathbb{C} -dependent) kernel which is $(2 - n)$ -essentially homogeneous (see for instance [28, § 6.2, Thm. 6.2.1]). It follows that (for a solution defined in the unit ball)

$$\|e(u)\|_{L^\infty(B_{1/2})} \leq c \|e(u)\|_{L^2(B_1)}$$

for some c depending only on \mathbb{C} and thus, for $\rho \leq 1/2$,

$$\int_{B_\rho} f_0(e(u)) dx \leq c \rho^n \int_{B_1} f_0(e(u)) dx.$$

Therefore, one can reproduce the proof of [11, Lemma 3.7] with almost no change, and obtain the following result.

Lemma 5.1 (Density lower bound for G_0). *Let $p = 2$, $\kappa \geq 0$, and $\beta > 0$. If $u \in GSBD^2(\Omega)$ is a local minimizer of $G(\cdot, \kappa, \beta, \Omega)$ defined in (33), then there exist ϑ_0 and R_0 , depending only on $n, \mathbb{C}, \kappa, \beta, \mu$, and $\|g\|_{L^\infty(\Omega)}$, such that if $0 < \rho < R_0$, $x \in \overline{J_u}$, and $B_\rho(x) \subset\subset \Omega$, then*

$$G_0(u, \kappa, \beta, B_\rho(x)) \geq \vartheta_0 \rho^{n-1}. \quad (47)$$

Moreover

$$\mathcal{H}^{n-1}(\Omega \cap (\overline{J_u} \setminus J_u)) = 0. \quad (48)$$

Corollary 5.2 (Density lower bound for the jump). *Let $p = 2$, $\kappa \geq 0$, and $\beta > 0$. If $u \in GSBD^2(\Omega)$ is a local minimizer of $G(\cdot, \kappa, \beta, \Omega)$ defined in (33), then there exist ϑ_1 and R_1 , depending only on $n, \mathbb{C}, \kappa, \beta, \mu$, and $\|g\|_{L^\infty(\Omega)}$, such that if $0 < \rho < R_1$, $x \in \overline{J_u}$, and $B_\rho(x) \subset\subset \Omega$, then*

$$\mathcal{H}^{n-1}(J_u \cap B_\rho(x)) \geq \vartheta_1 \rho^{n-1}. \quad (49)$$

Theorem 2 follows from Lemma 5.1, see [11, Theorem 1.2] for the details of the proof. Theorem 1 follows from Theorem 2 and the existence of weak global solutions proven in [14, Theorem 11.3].

Acknowledgments

F. Iurlano has been supported by the program FSMP and the project Emergence Sorbonne-Université ANIS. S. Conti has been partially supported by the Deutsche Forschungsgemeinschaft through the Sonderforschungsbereich 1060 “*The mathematics of emergent effects*”. The authors wish to thank G. Friesecke for useful references.

References

- [1] L. AMBROSIO, N. FUSCO, AND D. PALLARA, *Functions of bounded variation and free discontinuity problems*, Oxford Mathematical Monographs, The Clarendon Press Oxford University Press, New York, 2000.
- [2] D. BUCUR AND S. LUCKHAUS, *Monotonicity formula and regularity for general free discontinuity problems*, Arch. Ration. Mech. Anal., 211 (2014), pp. 489–511.
- [3] A. CHAMBOLLE, *An approximation result for special functions with bounded deformation*, J. Math. Pures Appl. (9), 83 (2004), pp. 929–954.
- [4] ———, *Addendum to: “An approximation result for special functions with bounded deformation” [3]*, J. Math. Pures Appl. (9), 84 (2005), pp. 137–145.
- [5] A. CHAMBOLLE, S. CONTI, AND G. FRANCFORT, *Korn-Poincaré inequalities for functions with a small jump set*, Indiana Univ. Math. J., 65 (2016), pp. 1373–1399.
- [6] ———, *Approximation of a brittle fracture energy with a constraint of non-interpenetration*, preprint arXiv:1709.04208, (2017).
- [7] A. CHAMBOLLE AND V. CRISMALE, *A density result in $GSBD^p$ with applications to the approximation of brittle fracture energies*, preprint arXiv:1708.03281, (2017).
- [8] S. CONTI, M. FOCARDI, AND F. IURLANO, *A note on the Hausdorff dimension of the singular set of solutions to elasticity type systems*. (in preparation).
- [9] ———, *Which special functions of bounded deformation have bounded variation?*, Proc. Roy. Soc. Edinb. A, to appear, preprint arXiv:1502.07464, (2015).

- [10] —, *Approximation of fracture energies with p -growth via piecewise affine finite elements*, preprint arXiv:1706.01735, (2017).
- [11] —, *Existence of strong minimizers for the Griffith static fracture model in dimension two*, preprint arXiv:1611.03374v2, (2017).
- [12] —, *Integral representation for functionals defined on SBD^p in dimension two*, Arch. Ration. Mech. Anal., 223 (2017), pp. 1337–1374.
- [13] S. CONTI AND B. SCHWEIZER, *Rigidity and Gamma convergence for solid-solid phase transitions with $SO(2)$ invariance*, Comm. Pure Appl. Math., 59 (2006), pp. 830–868.
- [14] G. DAL MASO, *Generalised functions of bounded deformation*, J. Eur. Math. Soc. (JEMS), 15 (2013), pp. 1943–1997.
- [15] E. DE GIORGI AND L. AMBROSIO, *New functionals in the calculus of variations*, Atti Accad. Naz. Lincei Rend. Cl. Sci. Fis. Mat. Natur. (8), 82 (1988), pp. 199–210 (1989).
- [16] E. DE GIORGI, M. CARRIERO, AND A. LEACI, *Existence theorem for a minimum problem with free discontinuity set*, Arch. Rational Mech. Anal., 108 (1989), pp. 195–218.
- [17] G. DOLZMANN AND S. MÜLLER, *Microstructures with finite surface energy: the two-well problem*, Arch. Ration. Mech. Anal., 132 (1995), pp. 101–141.
- [18] G. A. FRANCFORT AND J.-J. MARIGO, *Revisiting brittle fracture as an energy minimization problem*, J. Mech. Phys. Solids, 46 (1998), pp. 1319–1342.
- [19] M. FRIEDRICH, *A Korn-Poincaré-type inequality for special functions of bounded deformation*, preprint arxiv:1503.06755, (2015).
- [20] —, *A Korn-type inequality in SBD for functions with small jump sets*, preprint arxiv:1505.00565, (2015).
- [21] —, *A piecewise Korn inequality in SBD and applications to embedding and density results*, preprint arXiv:1604.08416, (2016).
- [22] M. FRIEDRICH AND F. SOLOMBRINO, *Quasistatic crack growth in linearized elasticity*, Ann. Inst. H. Poincaré Anal. Non Linéaire, to appear, (2017).

- [23] A. A. GRIFFITH, *VI. The phenomena of rupture and flow in solids*, Philosophical Transactions of the Royal Society of London A: Mathematical, Physical and Engineering Sciences, 221 (1921), pp. 163–198.
- [24] F. IURLANO, *Fracture and plastic models as Γ -limits of damage models under different regimes*, Adv. Calc. Var., 6 (2013), pp. 165–189.
- [25] ———, *A density result for GSBD and its application to the approximation of brittle fracture energies*, Calc. Var. Partial Differential Equations, 51 (2014), pp. 315–342.
- [26] R. KOHN, *New integral estimates for deformations in terms of their nonlinear strains*, Arch. Ration. Mech. Anal., 78 (1982), pp. 131–172.
- [27] F. MADDALENA AND S. SOLIMINI, *Lower semicontinuity properties of functionals with free discontinuities*, Arch. Ration. Mech. Anal., 159 (2001), pp. 273–294.
- [28] C. B. MORREY, JR., *Multiple integrals in the calculus of variations*, Classics in Mathematics, Springer-Verlag, Berlin, 2008. Reprint of the 1966 edition [MR0202511].
- [29] D. MUMFORD AND J. SHAH, *Optimal approximations by piecewise smooth functions and associated variational problems*, Comm. Pure Appl. Math., 42 (1989), pp. 577–685.