

GLOBAL LIPSCHITZ CONTINUITY FOR MINIMA OF DEGENERATE PROBLEMS

PIERRE BOUSQUET AND LORENZO BRASCO

ABSTRACT. We consider the problem of minimizing the Lagrangian $\int [F(\nabla u) + f u]$ among functions on $\Omega \subset \mathbb{R}^N$ with given boundary datum φ . We prove Lipschitz regularity up to the boundary for solutions of this problem, provided Ω is convex and φ satisfies the bounded slope condition. The convex function F is required to satisfy a qualified form of uniform convexity *only outside a ball* and no growth assumptions are made.

CONTENTS

1. Introduction	2
1.1. Aim of the paper	2
1.2. A glimpse of BSC condition	2
1.3. Main results	3
1.4. Steps of the proof	4
1.5. Comparison with previous results	5
1.6. Plan of the paper	6
2. Preliminaries	6
2.1. The bounded slope condition and approximation of convex sets	6
2.2. Some auxiliary regularity results	11
3. Existence of minimizers	12
4. A weaker result: the case of μ -uniformly convex problems	15
4.1. Step 0: a regularized problem	15
4.2. Step 1: construction of uniform barriers	16
4.3. Step 2: construction of competitors	18
4.4. Step 3: a uniform Lipschitz estimate	19
4.5. Step 4: passage to the limit	21
4.6. Step 5: conclusion	23
5. Proof of the Main Theorem	23
5.1. Step 1: reduction to μ -uniformly convex problems	24
5.2. Step 2: conclusion by density	25
6. More general lower order terms	25
Appendix A. Uniformly convex functions outside a ball	27
A.1. Basic properties	27
A.2. Approximation issues	31
References	36

Date: October 26, 2015.

2010 Mathematics Subject Classification. 49N60, 49K20, 35B65.

Key words and phrases. Degenerate and singular problems; regularity of minimizers; uniform convexity.

1. INTRODUCTION

1.1. **Aim of the paper.** Consider the following variational problem arising in the study of optimal thin torsion rods (see [1])

$$\min_{u \in W_0^{1,2}(\Omega)} \int_{\Omega} [F(\nabla u) - \lambda u] dx.$$

Here Ω is a bounded open set of \mathbb{R}^2 , $\lambda \in \mathbb{R}^+$ and the function F is given by

$$(1.1) \quad F(z) = \begin{cases} |z|, & \text{if } |z| \leq 1, \\ \frac{1}{2}|z|^2 + \frac{1}{2}, & \text{if } |z| > 1. \end{cases}$$

By the direct methods in the Calculus of Variations, this problem admits at least one solution u . The regularity of u is obviously limited by the singularities and degeneracy of F . In this respect, observe that F is non differentiable at 0 and the Hessian of F degenerates at any point of the unit ball.

When Ω is a disc centered at the origin, one can prove that this solution is unique, radial and Lipschitz continuous. The main purpose of this paper is to establish that such a regularity property remains true in a more general framework. Notably, we merely assume that the domain $\Omega \subset \mathbb{R}^N$ is convex (here $N \geq 2$) and we replace the parameter λ by a generic function $f \in L^\infty(\Omega)$. We also allow for more general boundary conditions. Most importantly, we consider singular and degenerate Lagrangians, which may have a *wild growth at infinity*. Given such a convex function F which may be singular and/or degenerate inside a ball, we thus consider more generally the following problem:

$$(P_0) \quad \min \left\{ \mathcal{F}(u) := \int_{\Omega} [F(\nabla u) + f u] dx : u - \varphi \in W_0^{1,1}(\Omega) \right\}.$$

1.2. **A glimpse of BSC condition.** In order to neatly motivate the study of this paper and explain some of the difficulties we have to face, let us start by recalling some known facts about Lipschitz regularity. One of the simplest instances of problem (P_0) is when $f \equiv 0$ and F is strictly convex. This substantially simplifies the situation since then:

- (1) a *comparison principle* holds true, i.e. if u and v are two solutions of (P_0) in $\varphi + W_0^{1,1}(\Omega)$ and $\psi + W_0^{1,1}(\Omega)$ respectively and $\varphi \leq \psi$ on $\partial\Omega$, then $u \leq v$ on Ω as well. This statement can be generalized to the case when F is merely convex but superlinear, see [9, 33];
- (2) every affine map $v : x \mapsto \langle \zeta, x \rangle + a$ is a minimum.

The strict convexity of F also implies the uniqueness of the minimum. From the second observation above, it thus follows that when the boundary datum φ is affine, φ is the unique minimum. In particular, it is Lipschitz continuous. In contrast, when φ is assumed to be merely Lipschitz continuous, such a regularity property can not be deduced for a minimizer: even if $F(\nabla u) = |\nabla u|^2$ and Ω is a ball, the harmonic extension of a Lipschitz function $\varphi : \partial\Omega \rightarrow \mathbb{R}$ is not globally Lipschitz in general (see [8] for a counterexample), but only Hölder continuous (see e.g. [2, 5]).

These observations led to consider boundary data satisfying the so-called *bounded slope condition*.

Definition 1.1. Let Ω be a bounded open set in \mathbb{R}^N and $K \geq 0$. We say that a map $\varphi : \partial\Omega \rightarrow \mathbb{R}$ satisfies the *bounded slope condition of rank K* if for every $y \in \partial\Omega$, there exist $\zeta_y^-, \zeta_y^+ \in \mathbb{R}^N$ such

that $|\zeta_y^-|, |\zeta_y^+| \leq K$ and

$$(1.2) \quad \varphi(y) + \langle \zeta_y^-, x - y \rangle \leq \varphi(x) \leq \varphi(y) + \langle \zeta_y^+, x - y \rangle, \quad \text{for every } x \in \partial\Omega.$$

Equivalently, φ satisfies the bounded slope condition if it coincides with the restriction to $\partial\Omega$ of a convex function φ^- and a concave function φ^+ , see Lemma 2.3 below.

Remark 1.2. We recall that whenever there exists a non affine function $\varphi : \partial\Omega \rightarrow \mathbb{R}$ satisfying the bounded slope condition, the set Ω is necessarily convex (see [23, Chapter 1, Section 1.2]).

When F is convex and $f \equiv 0$, the bounded slope condition implies the existence of a Lipschitz solution to (P_0) , see [34, Teorema 1.2] or [23, Theorem 1.2]. The proof relies in an essential way on the two properties (1) and (2).

When $f \not\equiv 0$, these two properties are false in general and the above approach must be supplemented with new ideas. Stampacchia [40] considered Lagrangians of the form $F(\nabla u) + G(x, u)$ for some function $G : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ satisfying suitable growth conditions (see also [28]). For bounded minima, there is no loss of generality in assuming that $G(x, u)$ has the form $f(x)u$, see Section 5. In the following, we shall thus make this restriction.

In this case the bounded slope condition can still be exploited to obtain a Lipschitz regularity result when F is *uniformly convex*, in the following sense: F is C^2 and there exists $\mu > 0$, $\tau > -1/2$ such that for every $z, \xi \in \mathbb{R}^N$,

$$(1.3) \quad \langle D^2F(z) \xi, \xi \rangle \geq \mu (1 + |z|^2)^\tau |\xi|^2.$$

In this framework, if Ω is uniformly convex (see Definition 2.2) and $f \in C^0(\overline{\Omega})$, then in [40] it is proven that every solution of (P_0) is Lipschitz continuous. In Stampacchia's proof, the uniform convexity of F is used in a crucial way to compensate the perturbation caused by the lower order term $f(x)u$. In this respect, we point out that when f is a constant map and F is *isotropic*¹, it is possible to consider a more general class of functions F , see [18].

1.3. Main results. We now describe our contribution to the regularity theory for degenerate and singular Lagrangians which are *uniformly convex at infinity*. We first detail the uniform convexity property that will be considered in this paper. In what follows, we note by B_R the N -dimensional open ball of radius $R > 0$ centered at the origin.

Definition 1.3. Let $\Phi : (0, +\infty) \rightarrow (0, +\infty)$ be a continuous function such that

$$(1.4) \quad \lim_{t \rightarrow +\infty} t \Phi(t) = +\infty.$$

We say that a map $F : \mathbb{R}^N \rightarrow \mathbb{R}$ is Φ -uniformly convex outside the ball $B_R \subset \mathbb{R}^N$ if for every $z, z' \in \mathbb{R}^N$ such that the segment $[z, z']$ does not intersect B_R and for every $\theta \in [0, 1]$

$$(1.5) \quad F(\theta z + (1 - \theta) z') \leq \theta F(z) + (1 - \theta) F(z') - \frac{1}{2} \theta (1 - \theta) \Phi(|z| + |z'|) |z - z'|^2.$$

If the previous property holds with $\Phi \equiv \mu$ for some constant $\mu > 0$, we say that F is μ -uniformly convex outside the ball $B_R \subset \mathbb{R}^N$.

The following is the main result of the paper:

¹By this, we mean that $F(z) = h(|z|)$ for some convex function h .

Main Theorem. *Let $\Omega \subset \mathbb{R}^N$ be a bounded convex open set, $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}$ a Lipschitz continuous function, $F : \mathbb{R}^N \rightarrow \mathbb{R}$ a convex function and $f \in L^\infty(\Omega)$. We consider the following problem*

$$(P_\Phi) \quad \inf \left\{ \mathcal{F}(u) := \int_{\Omega} [F(\nabla u) + f u] dx : u - \varphi \in W_0^{1,1}(\Omega) \right\}.$$

Assume that $\varphi|_{\partial\Omega}$ satisfies the bounded slope condition of rank $K \geq 0$ and that F is Φ -uniformly convex outside the ball B_R , for some $R > 0$. Then problem (P_Φ) admits at least one solution and every solution is Lipschitz continuous. More precisely, we have

$$\|u\|_{L^\infty(\Omega)} + \|\nabla u\|_{L^\infty(\Omega)} \leq \mathcal{L} = \mathcal{L}(N, \Phi, K, R, \|f\|_{L^\infty(\Omega)}, \text{diam}(\Omega)) > 0,$$

for every solution u .

Some comments on the assumptions of the previous result are in order.

Remark 1.4. Observe in particular that we allow for Lagrangians which are not necessarily C^1 . Moreover, we do not assume any growth condition from above on F at infinity. For example, the previous result covers the case of

$$(1.6) \quad F(z) = \mu (|z|^p - \delta)_+ + \sum_{i=1}^N |z_i|^{p_i} \quad \text{or} \quad F(z) = \mu (|z| - \delta)_+^p + \sum_{i=1}^N |z_i|^{p_i},$$

where $\mu > 0$, $\delta \geq 0$, $p > 1$ and $1 < p_1 \leq \dots \leq p_N$ without any further restriction. On the contrary, the case $\mu = 0$ is not covered by our result, not even when $p_1 = p_2 = \dots = p_N$ (see the recent paper [3] for some results in this case). Of course, many more general functions F can be considered, not necessarily of power-type: for example

$$F(z) = (|z| - \delta)_+ [\log(1 + |z|)]^p,$$

with $\delta \geq 0$ and $p > 1$ fulfills our hypothesis. The case $p = 1$ is ruled out by condition (1.4).

Finally, the domain Ω is convex (this is implicitly implied by the bounded slope condition), but not necessarily uniformly convex nor smooth.

1.4. Steps of the proof. The first step of the proof is an approximation lemma which is new in several respects. Given a bounded open convex set Ω and a function $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}$ which satisfies the bounded slope condition of rank $K \geq 0$, we construct

- a sequence of smooth bounded open convex sets $\Omega_k \supset \Omega$ converging to Ω (for the Hausdorff metric);
- a sequence of smooth functions φ_k which satisfy the bounded slope condition of rank $K + 1$ on Ω_k , such that $\varphi_k = \varphi$ on $\partial\Omega$.

This construction relies on some properties of the bounded slope condition that were initially discovered by Hartman [26, 25]. In addition, we approximate the function F satisfying the Φ -uniform convexity assumption (3.1) by a sequence of smooth functions which are uniformly convex on the whole \mathbb{R}^N . We are thus reduced to consider a variational problem (P_k) for which the existence of a smooth solution u_k is well-known. The goal is to establish regularity estimates on u_k , which are independent of k .

The second step is the construction of suitable barriers for the regularized problem (P_k) . Here the bounded slope condition plays a key role. This approach is quite standard but we have to overcome a new difficulty with respect to [40]: the stronger degeneracy of the Lagrangian. This is

handled by introducing new explicit barriers adapted to this setting. From this construction, we deduce a uniform bound on

$$\|u_k\|_{L^\infty(\Omega_k)} + \|\nabla u_k\|_{L^\infty(\partial\Omega_k)}.$$

In the third step of the proof, we obtain an estimate on the Lipschitz constant of u_k . The method that we follow is classical in the setting of nonsmooth Lagrangians, which do not admit an Euler-Lagrange equation. We compare a minimum u with its translations, namely functions of the form $u(\cdot + \tau)$, $\tau \in \mathbb{R}^N$. Once again, we have to cope with the degeneracy of the higher order part F of the Lagrangian, in presence of a term depending on x and u . The main idea in [40] was that the uniform convexity of F could be used to neutralize the lower order term $f(x)u$. In our situation, this is only possible when $|\nabla u| > R$. On the set where $|\nabla u| \leq R$ instead, the gradient is obviously bounded almost everywhere, but this does not imply that the function u is Lipschitz continuous there, since we have no information on the regularity of this set.

Once a Lipschitz estimate independent of k is established, it remains to pass to the limit when k goes to ∞ in order to establish the existence of a Lipschitz solution to the original problem (P_Φ). Since \mathcal{F} is not strictly convex in general, this is not sufficient to infer that *every minimizer* is a Lipschitz function. In order to conclude the proof, we use that the lack of strict convexity is “confined” in the ball B_R , thus the Lipschitz regularity of a minimizer can be “propagated” to all the others (see Lemma 2.8).

1.5. Comparison with previous results. In order to handle the Lagrangian F given by (1.1), an entirely different approach could have been followed. Indeed, such an F has a *Laplacian structure at infinity*, i.e. for every $\xi \in \mathbb{R}^N$

$$\langle D^2F(z)\xi, \xi \rangle \simeq |\xi|^2, \quad \text{for } |z| \gg 1.$$

Instead of exploiting the properties of the boundary condition φ , one can rely on the specific growth property satisfied by F and prove a Lipschitz estimate by using test functions arguments and Caccioppoli-type inequalities.

It is impossible to give a detailed account of all the contributions to the regularity theory of (local) minimizers of Lagrangians having more generally a p -Laplacian structure at infinity, i.e. such that for every $\xi \in \mathbb{R}^N$

$$\langle D^2F(z)\xi, \xi \rangle \simeq |z|^{p-2} |\xi|^2, \quad \text{for } |z| \gg 1.$$

We cite the pioneering papers [10, 21, 38]. More recently, many studies have been devoted to this subject, see for example [6, 12, 7, 14, 15, 17, 30] and [39]. Among the many contributions on the topic, we wish to mention the paper [19, Theorem 2.7] by Fonseca, Fusco and Marcellini. Here the Lagrangian has the form $F(x, \nabla u)$ and is assumed to be p -uniformly convex at infinity in the following sense: there exist $p > 1$, $\mu > 0$ and $R > 0$ such that for every $\xi, \xi' \in \mathbb{R}^N \setminus B_R$ and for every $\theta \in [0, 1]$,

$$(1.7) \quad F(x, \theta z + (1 - \theta) z') \leq \theta F(x, z) + (1 - \theta) F(x, z') - \frac{\mu}{2} \theta (1 - \theta) (|z| + |z'|)^{p-2} |\xi - \xi'|^2.$$

Observe that when F is $C^2(\mathbb{R}^N)$, condition (1.7) coincides with (1.3) for every $z \in \mathbb{R}^N \setminus B_R$. In addition, F is assumed to have p -growth, i.e.

$$(1.8) \quad 0 \leq F(x, \xi) \leq L (1 + |\xi|)^p, \quad \xi \in \mathbb{R}^N.$$

Then [19, Theorem 2.7] shows that every local minimizer is locally Lipschitz continuous. Observe that this holds for local minimizers, thus no regular boundary conditions φ are needed. In particular, this kind of result can not be deduced from our Main Theorem.

On the other hand, such a result is less general for two reasons: first of all, condition (1.7) is more restrictive than our (1.5), since it corresponds to the particular case $\Phi(t) = \mu t^{p-2}$; more importantly, *we do not assume any growth condition* of the type (1.8) on F .

It should be pointed out that the technique of [19] can be pushed further, by weakening (1.8) and replacing it by a q -growth assumption, i.e.

$$0 \leq F(x, \xi) \leq L(1 + |\xi|)^q, \quad \xi \in \mathbb{R}^N,$$

with $q > p$, see for example [13, Theorem 1.1]. But still in this case, some restrictions are necessary: namely a condition like $q \leq (1 + C_N)p$ is required. Indeed, for q and p too far away, well-known examples show that local minimizers could be even unbounded (see [20, 32] or [29] for a counterexample and [11, 16, 31] for some regularity results on so-called (p, q) *growth problems*). In particular, with these methods it is not possible to consider Lagrangians like (1.6). As for global regularity, though not explicitly stated in [19] or [13], we point out that the results of [13, 19] can be extended (as done in [6] for the Neumann case) to Lagrangians of the form $F(\nabla u) + f(x)u$, provided Ω and the boundary datum are smooth enough.

1.6. Plan of the paper. In Section 2 we introduce the required notation and definitions. We recall some basic regularity results that will be needed throughout the whole paper. We also establish a new approximation lemma for a function φ which satisfies the bounded slope condition (this is Lemma 2.5). Then in Section 3 for the sake of completeness we show that problem (P_Φ) admits solutions. The proof of the Main Theorem is then contained in Sections 4 & 5: at first we show the result under the stronger assumption that F is μ -uniformly convex everywhere; then we deduce the general result by an approximation argument. Finally, Section 6 considers the case of more general functionals, where the lower order term $f(x)u$ is replaced by terms of the form $G(x, u)$. A (long) Appendix containing some results on uniformly convex functions complements the paper.

Acknowledgements. We warmly thank Guido De Philippis for pointing out a flaw in a preliminary version of this paper. Part of this work has been written during a visit of the first author to Marseille and of the second author to Toulouse. The IMT and I2M institutions and their facilities are kindly acknowledged.

2. PRELIMINARIES

2.1. The bounded slope condition and approximation of convex sets. We already recalled in Definition 1.1 the *bounded slope condition*. For a detailed account on the history of such a condition, we refer the reader to [23, Section 1.6]. Here we just mention a handful of pioneering papers, such as [24, 36, 37] and in a non variational framework [27].

As observed by Miranda [34] and Hartman [26], there is a close relationship between this condition and the regularity of φ . For example, we recall the following result contained in [26, Corollaries 4.2 & 4.3].

Proposition 2.1 ([26]). *If $\Omega \subset \mathbb{R}^N$ is a $C^{1,1}$ open bounded convex set and φ satisfies the bounded slope condition, then φ is $C^{1,1}$. If in addition Ω is assumed to be uniformly convex, then the converse is true as well, i.e. if φ is $C^{1,1}$, then it satisfies the bounded slope condition.*

Here, the uniform convexity of Ω is defined as follows:

Definition 2.2. An open convex set $\Omega \subset \mathbb{R}^N$ is said *uniformly convex* if the following property is verified: there exists a constant $c > 0$ such that for every $x \in \partial\Omega$, there exists a normal vector

$\nu_x \in \mathcal{S}_\Omega(x)$ such that for every $y \in \Omega$

$$(2.1) \quad \langle \nu_x, x - y \rangle \geq c |x - y|^2.$$

In this section, we indicate how one can approximate a convex set Ω by a sequence of smooth convex sets while preserving the bounded slope condition of a boundary map $\varphi : \partial\Omega \rightarrow \mathbb{R}$. We first introduce some notation: given an open and bounded convex set $\Omega \subset \mathbb{R}^N$, we introduce the *normal cone at a point* $x \in \partial\Omega$ by

$$\mathcal{N}_\Omega(x) = \left\{ \xi \in \mathbb{R}^N : \sup_{y \in \Omega} \langle \xi, y - x \rangle \leq 0 \right\}.$$

We also set

$$\mathcal{S}_\Omega(x) = \{ \xi \in \mathcal{N}_\Omega(x) : |\xi| = 1 \}.$$

Finally, given $x_0 \in \Omega$ we introduce the *gauge function of Ω centered at x_0* by

$$j_{x_0, \Omega}(x) = \inf \{ \lambda > 0 : x - x_0 \in \lambda(\Omega - x_0) \}.$$

This is a convex function such that $j_{x_0, \Omega}(x_0) = 0$ and $j_{x_0, \Omega}(x) = 1$ if and only if $x \in \partial\Omega$. It is positively 1-homogeneous in the following sense: for every $t > 0$

$$(2.2) \quad j_{x_0, \Omega}(t(x - x_0) + x_0) = t j_{x_0, \Omega}(x), \quad x \in \mathbb{R}^N.$$

Moreover, this is a globally Lipschitz function, with Lipschitz constant given by

$$\frac{1}{\text{dist}(x_0, \partial\Omega)}.$$

We present a characterization of functions satisfying the bounded slope condition.

Lemma 2.3. *Let $\Omega \subset \mathbb{R}^N$ be an open bounded convex set. If $\varphi : \partial\Omega \rightarrow \mathbb{R}$ satisfies the bounded slope condition of rank K , then there exist two maps $\varphi^- : \mathbb{R}^N \rightarrow \mathbb{R}$, $\varphi^+ : \mathbb{R}^N \rightarrow \mathbb{R}$ such that:*

- (1) φ^- and φ^+ are $(K + 1)$ -Lipschitz continuous, φ^- is convex, φ^+ is concave and

$$\varphi^-|_{\partial\Omega} = \varphi^+|_{\partial\Omega} = \varphi;$$

- (2) $\Omega = \{x \in \mathbb{R}^N : \varphi^+(x) > \varphi^-(x)\}$, $\partial\Omega = \{x \in \mathbb{R}^N : \varphi^+(x) = \varphi^-(x)\}$ and there exists $\beta_\Omega > 0$ depending on Ω only (see Remark 2.4 below) such that for every $s > 0$,

$$(2.3) \quad \{x \in \mathbb{R}^N : \varphi^-(x) \leq \varphi^+(x) + s\} \subset \overline{\{x \in \mathbb{R}^N : \text{dist}(x, \Omega) \leq \beta_\Omega s\}}.$$

Conversely, if a convex map $\varphi^- : \mathbb{R}^N \rightarrow \mathbb{R}$ agrees with a concave map $\varphi^+ : \mathbb{R}^N \rightarrow \mathbb{R}$ on the boundary of Ω , then $\varphi := \varphi^-|_{\partial\Omega} = \varphi^+|_{\partial\Omega}$ satisfies the bounded slope condition of rank K , where K is a common Lipschitz constant for φ^- and φ^+ on $\overline{\Omega}$.

Proof. Assume first that $\varphi : \partial\Omega \rightarrow \mathbb{R}$ satisfies the bounded slope condition of rank K . For every $y \in \partial\Omega$, there exist $\zeta_y^-, \zeta_y^+ \in \mathbb{R}^N$ as in Definition 1.1. We then define

$$\varphi_0^-(x) = \sup_{y \in \partial\Omega} [\varphi(y) + \langle \zeta_y^-, x - y \rangle], \quad \text{and} \quad \varphi_0^+(x) = \inf_{y \in \partial\Omega} [\varphi(y) + \langle \zeta_y^+, x - y \rangle].$$

Then φ_0^- and φ_0^+ are K -Lipschitz continuous, the former is convex, the latter is concave and they agree with φ on $\partial\Omega$. This implies that

$$\varphi_0^+ \geq \varphi_0^- \quad \text{on } \Omega, \quad \text{and} \quad \varphi_0^+ \leq \varphi_0^- \quad \text{on } \mathbb{R}^N \setminus \Omega.$$

If we now define

$$\varphi^-(x) = \varphi_0^-(x) + \text{dist}(x_0, \partial\Omega) \left(j_{x_0, \Omega}(x) - 1 \right),$$

and

$$\varphi^+(x) = \varphi_0^+(x) + \text{dist}(x_0, \partial\Omega) \left(1 - j_{x_0, \Omega}(x) \right),$$

these two functions have the required properties, thanks to the properties of the gauge function (see Figure 1 below).

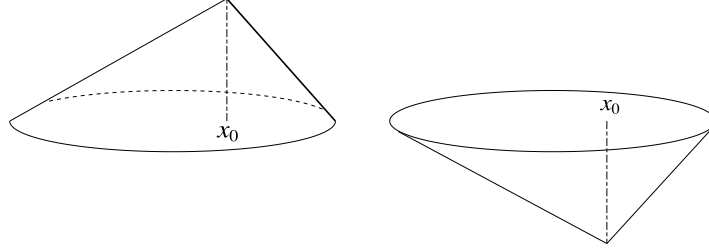


FIGURE 1. The construction of the functions φ^+ and φ^- : we simply add the two cones to the functions φ_0^+ and φ_0^- , respectively.

We proceed to prove² (2.3). Let $x \in \mathbb{R}^N \setminus \Omega$ be such that

$$\varphi^-(x) \leq \varphi^+(x) + s,$$

that is

$$\varphi_0^-(x) + \text{dist}(x_0, \partial\Omega) \left(j_{x_0, \Omega}(x) - 1 \right) \leq \varphi_0^+(x) + \text{dist}(x_0, \partial\Omega) \left(1 - j_{x_0, \Omega}(x) \right) + s.$$

Since on $\mathbb{R}^N \setminus \Omega$ we have $\varphi_0^- \geq \varphi_0^+$, then from the previous inequality we get

$$\text{dist}(x_0, \partial\Omega) \left(j_{x_0, \Omega}(x) - 1 \right) \leq \text{dist}(x_0, \partial\Omega) \left(1 - j_{x_0, \Omega}(x) \right) + s,$$

that is

$$j_{x_0, \Omega}(x) \leq 1 + \frac{s}{2 \text{dist}(x_0, \partial\Omega)}.$$

From (2.2), for $x \in \mathbb{R}^N \setminus \Omega$ we get

$$j_{x_0, \Omega} \left(\frac{x - x_0}{j_{x_0, \Omega}(x)} + x_0 \right) = 1, \quad \text{that is } \frac{x - x_0}{j_{x_0, \Omega}(x)} + x_0 \in \partial\Omega.$$

Thus we can infer

$$\begin{aligned} \text{dist}(x, \partial\Omega) &\leq \left| x - \left(\frac{x - x_0}{j_{x_0, \Omega}(x)} + x_0 \right) \right| = \frac{|x - x_0|}{j_{x_0, \Omega}(x)} |1 - j_{x_0, \Omega}(x)| \\ &\leq \left(\max_{y \in \partial\Omega} |x_0 - y| \right) \frac{s}{2 \text{dist}(x_0, \partial\Omega)} =: \beta_\Omega s, \end{aligned}$$

²We point out that the gauge functions are used to guarantee property (2.3).

which gives (2.3).

We now prove the converse. Assume that there exist a convex function $\varphi^- : \mathbb{R}^N \rightarrow \mathbb{R}$ and a concave function $\varphi^+ : \mathbb{R}^N \rightarrow \mathbb{R}$ agreeing on $\partial\Omega$ and let $\varphi := \varphi^-|_{\partial\Omega} = \varphi^+|_{\partial\Omega}$. For every $y \in \partial\Omega$, let $\zeta_y^- \in \partial\varphi^-(y)$ and $\zeta_y^+ \in -\partial(-\varphi^+)(y)$. Then for every $x \in \partial\Omega$,

$$\varphi(y) + \langle \zeta_y^-, x - y \rangle \leq \varphi(x) \leq \varphi(y) + \langle \zeta_y^+, x - y \rangle.$$

Moreover, if φ^- and φ^+ are K -Lipschitz on $\overline{\Omega}$, then $|\zeta_y^-| \leq K$ and $|\zeta_y^+| \leq K$. \square

Remark 2.4. In view of the above proof, in the previous result one can take

$$\beta_\Omega = \frac{1}{2} \frac{\max_{y \in \partial\Omega} |x_0 - y|}{\min_{y \in \partial\Omega} |x_0 - y|}.$$

By suitably choosing the point $x_0 \in \Omega$, we can then suppose that β_Ω depends on Ω only through the ratio between its diameter and inradius (this quantity is sometimes called *eccentricity*).

We proceed to describe the approximation of a bounded convex set by a sequence of smooth bounded convex sets that we will use in the sequel. Actually, the approximating sets can be chosen *uniformly* convex.

Lemma 2.5. *Let $\Omega \subset \mathbb{R}^N$ be a convex bounded open set and let $\varphi : \partial\Omega \rightarrow \mathbb{R}$ satisfy the bounded slope condition of rank K .*

Then there exists a sequence $\{\Omega_k\}_{k \in \mathbb{N}} \subset \mathbb{R}^N$ of smooth bounded uniformly convex open sets, a sequence of $(K+1)$ -Lipschitz functions $\varphi_k : \mathbb{R}^N \rightarrow \mathbb{R}$ such that

i) $\Omega \Subset \Omega_k$ for every $k \in \mathbb{N}$ and we have the following

$$\text{diam } \Omega_k \leq \text{diam } \Omega + \frac{8\beta_\Omega}{k}, \quad \lim_{k \rightarrow +\infty} |\Omega_k \setminus \Omega| = 0,$$

and

$$(2.4) \quad \lim_{k \rightarrow +\infty} \left[\max_{y \in \partial\Omega} \min_{y' \in \partial\Omega_k} |y - y'| \right] = 0;$$

ii) $\varphi_k|_{\partial\Omega_k}$ is smooth and satisfies the bounded slope condition of rank $K+2$;

iii) φ_k coincides with φ on $\partial\Omega$.

Proof. Let $\varphi^-, \varphi^+ : \mathbb{R}^N \rightarrow \mathbb{R}$ be the two functions given by Lemma 2.3. We consider $\{\rho_\varepsilon\}_{\varepsilon > 0} \subset C_0^\infty(B_\varepsilon)$ a sequence of standard mollifiers. We define

$$\psi_k^- := \varphi^- * \rho_{\varepsilon_k} - \frac{1}{k}, \quad \text{and} \quad \psi_k^+ := \varphi^+ * \rho_{\varepsilon_k} + \frac{1}{k}, \quad \text{where } \varepsilon_k = \frac{1}{2(K+1)k}.$$

Of course, the first function is convex, while the second is concave. Since φ^-, φ^+ are $(K+1)$ -Lipschitz, for every $x \in \mathbb{R}^N$,

$$(2.5) \quad \psi_k^-(x) + \frac{1}{2k} \leq \varphi^-(x) \leq \psi_k^-(x) + \frac{3}{2k} \quad \text{and} \quad \psi_k^+(x) - \frac{3}{2k} \leq \varphi^+(x) \leq \psi_k^+(x) - \frac{1}{2k}.$$

Let $x_0 \in \Omega$. Since the function

$$x \mapsto \psi_k^-(x) - \psi_k^+(x) + \frac{1}{2k \text{diam}(\Omega)^2} |x - x_0|^2,$$

is uniformly convex, for every $k \in \mathbb{N} \setminus \{0\}$ there exists $\alpha_k \in (0, 1/k)$ such that the set

$$\Omega_k := \left\{ x \in \mathbb{R}^N : \psi_k^+(x) + \alpha_k > \psi_k^-(x) + \frac{1}{2k \operatorname{diam}(\Omega)^2} |x - x_0|^2 \right\},$$

is smooth and uniformly convex³. By (2.5) and the fact that $\varphi^+ \geq \varphi^-$ on $\bar{\Omega}$, we have for every $x \in \bar{\Omega}$

$$\psi_k^-(x) + \frac{1}{2k \operatorname{diam}(\Omega)^2} |x - x_0|^2 \leq \psi_k^+(x) - \frac{1}{k} + \frac{1}{2k \operatorname{diam}(\Omega)^2} |x - x_0|^2 \leq \psi_k^+(x),$$

and thus $\bar{\Omega} \subset \Omega_k$. Moreover,

$$(2.6) \quad \Omega_k \subset \left\{ x \in \mathbb{R}^N : \varphi^-(x) < \varphi^+(x) + \frac{4}{k} \right\}.$$

Hence, by using property (2.3) of Lemma 2.3 with $s = 4/k$ we have

$$\operatorname{diam} \Omega_k \leq \operatorname{diam} \Omega + \frac{8\beta_\Omega}{k},$$

where β_Ω is the same constant as before. We now estimate $|\Omega_k \setminus \Omega|$. By (2.6),

$$\Omega_k \setminus \Omega \subset \left\{ x \in \mathbb{R}^N : \varphi^+(x) \leq \varphi^-(x) < \varphi^+(x) + \frac{4}{k} \right\}.$$

It follows that

$$\limsup_{k \rightarrow +\infty} |\Omega_k \setminus \Omega| \leq |\{x \in \mathbb{R}^N : \varphi^+(x) = \varphi^-(x)\}| = |\partial\Omega|,$$

and the last quantity is 0, by convexity of Ω . Hence, $\lim_{k \rightarrow +\infty} |\Omega_k \setminus \Omega| = 0$ as desired.

In order to prove (2.4), let us argue by contradiction. Then there exist $r > 0$, a subsequence $\{k_n\}_{n \in \mathbb{N}}$ diverging to ∞ and $y_n \in \partial\Omega$ such that for every $n \in \mathbb{N}$

$$\min_{y' \in \partial\Omega_{k_n}} |y_n - y'| \geq r,$$

that is, such that for every $n \in \mathbb{N}$

$$|y_n - y'| \geq r, \quad \text{for every } y' \in \partial\Omega_{k_n}.$$

The previous implies that $B_r(y_n) \subset \Omega_{k_n}$ for every $n \in \mathbb{N}$, thus we have⁴

$$|\Omega_{k_n} \setminus \Omega| \geq |B_r(y_n) \setminus \Omega| \geq \frac{\omega_N}{2} r^N.$$

where in the last estimate we used the convexity of Ω . The previous estimate clearly contradicts the fact that $|\Omega_k \setminus \Omega|$ converges to 0.

We now define φ_k by

$$\varphi_k = \max\{\varphi^+, \psi_k^-\}.$$

³It is not difficult to see that if $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}$ is a smooth uniformly convex function, then for every $\alpha > \inf \varphi$ the sublevel set

$$\{x \in \mathbb{R}^N : \varphi(x) < \alpha\},$$

defines a smooth convex set, which verifies (2.1).

⁴We denote by ω_N the volume of the N -dimensional ball of radius 1.

Of course, φ_k is $(K + 1)$ -Lipschitz on \mathbb{R}^N . Since $\varphi^+ = \varphi = \varphi^- \geq \psi_k^-$ on $\partial\Omega$, we have $\varphi_k = \varphi$ on $\partial\Omega$. For $x \in \partial\Omega_k$, we use the fact that

$$\varphi^+(x) \leq \psi_k^+(x) - \frac{1}{2k} = \psi_k^-(x) - \alpha_k + \frac{1}{2k \operatorname{diam}(\Omega)^2} |x - x_0|^2 - \frac{1}{2k} < \psi_k^-(x),$$

to get $\varphi_k = \psi_k^-$ on $\partial\Omega_k$. In particular, $\varphi_k|_{\partial\Omega_k}$ is smooth and satisfies the bounded slope condition of rank $K + 2$ for k sufficiently large. Indeed, we have

$$\varphi_k|_{\partial\Omega_k} = \psi_k^-|_{\partial\Omega_k} = \left(\psi_k^+ + \alpha_k - \frac{1}{2k \operatorname{diam}(\Omega)^2} |x - x_0|^2 \right)|_{\partial\Omega_k},$$

thus can we use the second part of Lemma 2.3 with the last two functions. This completes the proof. \square

Remark 2.6. Since $\Omega_k \supset \Omega$, it is not difficult to see that (2.4) is equivalent to say that Ω_k is converging to Ω with respect to the *Hausdorff metric*. Indeed, we recall that for every $E_1, E_2 \subset \mathbb{R}^N$ the latter is given by

$$d_H(E_1, E_2) = \max \left\{ \sup_{x \in E_1} \operatorname{dist}(x, E_2), \sup_{y \in E_2} \operatorname{dist}(y, E_1) \right\}.$$

If $E_2 \subset E_1$, the previous reduces to

$$d_H(E_1, E_2) = \sup_{x \in E_1} \operatorname{dist}(x, E_2) = \sup_{x \in E_1} \inf_{x' \in E_2} |x - x'|.$$

Moreover, if both E_1 and E_2 are bounded and convex, we can equivalently perform the sup / inf on their respective boundaries.

2.2. Some auxiliary regularity results. The following standard result will be used in the sequel.

Theorem 2.7. *Let $\mathcal{O} \subset \mathbb{R}^N$ be a smooth bounded uniformly convex open set, $H : \mathbb{R}^N \rightarrow \mathbb{R}$ a smooth uniformly convex function (i.e. it verifies (1.3) with $\tau = 0$) and $h : \mathcal{O} \rightarrow \mathbb{R}$ a smooth bounded function. Let $\psi : \partial\mathcal{O} \rightarrow \mathbb{R}$ be a smooth map. Then there exists a unique minimizer u of*

$$v \mapsto \int_{\mathcal{O}} [H(\nabla v) + h v] dx,$$

on $\psi + W_0^{1,2}(\mathcal{O})$. Moreover, u is smooth on $\overline{\mathcal{O}}$.

Proof. We first observe that by Proposition 2.1, the function ψ satisfies the bounded slope condition. Then by [40, Theorem 9.2], we have that the problem

$$\min \left\{ \int_{\mathcal{O}} H(\nabla v) dx + \int_{\mathcal{O}} h v dx : v - \psi \in W_0^{1,\infty}(\mathcal{O}) \right\},$$

admits a solution $u \in W^{1,\infty}(\mathcal{O})$, which is also unique by strict convexity of the Lagrangian in the gradient variable. Then u satisfies the Euler-Lagrange equation

$$(2.7) \quad \int_{\mathcal{O}} \langle \nabla H(\nabla u), \nabla \varphi \rangle dx + \int_{\mathcal{O}} h \varphi dx = 0, \quad \text{for every } \varphi \in W_0^{1,\infty}(\mathcal{O}).$$

Thanks to the hypotheses on H and h and to the fact that $\nabla u \in L^\infty(\mathcal{O})$, equation (2.7) still holds with test functions $\varphi \in W_0^{1,1}(\mathcal{O})$. Thus by convexity, u solves the original problem as well.

By using (2.7), a standard difference quotients argument and the Lipschitz continuity of u , one can prove that $u \in W^{2,2}(\mathcal{O})$ and that any partial derivative u_{x_i} is a solution of a uniformly elliptic equation with bounded measurable coefficients, i.e.

$$-\operatorname{div} (D^2 H(\nabla u) \nabla u_{x_i}) = h_{x_i}.$$

By the De Giorgi-Nash-Moser Theorem, it thus follows that $u_{x_i} \in C^{0,\alpha}(\overline{\mathcal{O}})$. By appealing to Schauder theory, this implies that u is smooth on $\overline{\mathcal{O}}$, see [22, Theorem 9.19]. \square

Finally, in the proof of the Main Theorem we will also need the following simple result.

Lemma 2.8 (Propagation of regularity). *Under the assumptions of the Main Theorem, if u_1 and u_2 are two solutions of (P_Φ) , then*

$$|\nabla u_1 - \nabla u_2| \leq 2R, \quad \text{almost everywhere in } \Omega.$$

Proof. From the identity $\mathcal{F}(u_1) = \mathcal{F}(u_2)$, the convexity of \mathcal{F} and the minimality of u_1 and u_2 , we easily infer that

$$\mathcal{F}(u_1) = \mathcal{F}\left(\frac{u_1 + u_2}{2}\right).$$

Hence, for almost every $x \in \Omega$,

$$F\left(\frac{\nabla u_1(x) + \nabla u_2(x)}{2}\right) = \frac{1}{2} F(\nabla u_1(x)) + \frac{1}{2} F(\nabla u_2(x)).$$

Since F is strictly convex outside B_R , this implies that either $\nabla u_1(x) = \nabla u_2(x)$ or $\nabla u_1(x)$ and $\nabla u_2(x)$ both belong to B_R . In any case, $|\nabla u_1(x) - \nabla u_2(x)| \leq 2R$ for almost every $x \in \Omega$. This concludes the proof. \square

3. EXISTENCE OF MINIMIZERS

In this section, we prove that the minimum in (P_Φ) is attained, under the standing assumptions. We begin by remarking a consequence of Φ -uniform convexity.

Remark 3.1. Observe that if F is Φ -uniformly convex outside B_R , then for every $\xi, \xi' \in \mathbb{R}^N$ such that the segment $[\xi, \xi']$ does not intersect B_R and every $\zeta \in \partial F(\xi)$, we also have

$$(3.1) \quad F(\xi') \geq F(\xi) + \langle \zeta, \xi' - \xi \rangle + \frac{1}{2} \Phi(|\xi| + |\xi'|) |\xi - \xi'|^2.$$

Here $\partial F(\xi)$ denotes the subdifferential of F at the point ξ . Indeed, from (1.5) we get for $0 < \theta < 1$

$$F(\xi + \theta(\xi' - \xi)) - F(\xi) \leq \theta \left(F(\xi') - F(\xi) \right) - \frac{1}{2} \theta(1 - \theta) \Phi(|\xi| + |\xi'|) |\xi - \xi'|^2,$$

then if $\zeta \in \partial F(\xi)$, by convexity of F we have

$$\theta \langle \zeta, \xi' - \xi \rangle \leq \theta \left(F(\xi') - F(\xi) \right) - \frac{1}{2} \theta(1 - \theta) \Phi(|\xi| + |\xi'|) |\xi - \xi'|^2.$$

By dividing by θ and taking the limit as θ goes to 0, we get (3.1).

We can now establish that F is superlinear.

Lemma 3.2. *Let $F : \mathbb{R}^N \rightarrow \mathbb{R}$ be a continuous function, such that F is Φ -uniformly convex outside the ball B_R . Then F is superlinear.*

Proof. We recall that by hypothesis F satisfies (3.1), i.e. for every $\xi, \xi' \in \mathbb{R}^N$ such that $[\xi, \xi']$ does not intersect B_R , we have

$$F(\xi) \geq F(\xi') + \langle \zeta, \xi - \xi' \rangle + \frac{1}{2} \Phi(|\xi| + |\xi'|) |\xi - \xi'|^2,$$

where $\zeta \in \partial F(\xi')$. Let $\xi \in \mathbb{R}^N \setminus B_{2R}$ and $\xi' = 2R\xi/|\xi|$, by using the previous property, Cauchy-Schwarz inequality and the continuity of F we get

$$\frac{F(\xi)}{|\xi|} \geq \frac{1}{|\xi|} \left[\min_{\omega \in \mathbb{S}^{N-1}} F(2R\omega) - |\zeta| (|\xi| - 2R) \right] + \frac{1}{2} \Phi(|\xi| + 2R) \frac{(|\xi| - 2R)^2}{|\xi|},$$

where the norm of $\zeta \in \partial F(2R\xi/|\xi|)$ can be bounded by $\|\nabla F\|_{L^\infty(B_{2R})}$. If we now use the assumption (1.4) on Φ , from the previous estimate we get that

$$\lim_{|\xi| \rightarrow +\infty} \frac{F(\xi)}{|\xi|} = +\infty,$$

which is the desired conclusion. \square

We now prove an existence result for a problem having a slightly more general form than (P_Φ) , namely we consider functionals of the form

$$\mathcal{F}(u) = \int_{\Omega} \left[F(\nabla u) + G(x, u) \right] dx,$$

where $G : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a measurable function which satisfies the following assumptions:

$$(3.2) \quad u \mapsto G(x, u) \quad \text{is continuous for a.e. } x \in \Omega,$$

and there exist two functions $g_1 \in L^N(\Omega)$ and $g_2 \in L^1(\Omega)$ such that

$$(3.3) \quad G(x, u) \geq -|u| |g_1(x)| - |g_2(x)|, \quad \text{for a.e. } x \in \Omega \text{ and every } u \in \mathbb{R}.$$

We have the following existence result.

Proposition 3.3. *Let $\Omega \subset \mathbb{R}^N$ be a bounded convex open set and $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}$ a Lipschitz continuous function. Let $F : \mathbb{R}^N \rightarrow \mathbb{R}$ be a convex function, which is Φ -uniformly convex outside the ball B_R and $G : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ a measurable function satisfying (3.2) and (3.3). Finally, assume that there exists $u_* \in \varphi + W_0^{1,1}(\Omega)$ such that*

$$(3.4) \quad \int_{\Omega} \left| F(\nabla u_*) + G(x, u_*) \right| dx < +\infty.$$

Then the following problem

$$(3.5) \quad \inf \left\{ \mathcal{F}(u) := \int_{\Omega} \left[F(\nabla u) + G(x, u) \right] dx : u - \varphi \in W_0^{1,1}(\Omega) \right\},$$

admits a solution.

Proof. By Lemma 3.2 we know that F is superlinear. In particular, we get that for every $M > 0$, there exists $r = r(M) > 0$ such that for every $\xi \in \mathbb{R}^N \setminus B_r$

$$(3.6) \quad F(\xi) \geq M |\xi|.$$

For every $u \in W^{1,1}(\Omega)$ we thus get

$$F(\nabla u) \geq \min \left\{ M |\nabla u|, \min_{B_r} F \right\}.$$

From (3.3), it also follows that

$$G(x, u) \geq -|u| |g_1(x)| - |g_2(x)|.$$

Hence, we get that $F(\nabla u) + G(x, u)$ is greater than or equal to an $L^1(\Omega)$ function. This proves that the functional \mathcal{F} is well-defined on the class $\varphi + W_0^{1,1}(\Omega)$.

In order to prove that (3.5) admits a solution, we first observe that the functional is not constantly $+\infty$, since by (3.4) $\mathcal{F}(u_*) < +\infty$. By using Hölder and Sobolev inequalities we get

$$\begin{aligned} \int_{\Omega} |u| |g_1| dx &\leq \|g_1\|_{L^N(\Omega)} \left(S_N \|\nabla u\|_{L^1(\Omega)} + S_N \|\nabla \varphi\|_{L^1(\Omega)} + \|\varphi\|_{L^{N'}(\Omega)} \right) \\ &\leq C'_1 \|g_1\|_{L^N(\Omega)} \|\nabla u\|_{L^1(\Omega)} + C'_2, \end{aligned}$$

for some $C'_1 = C'_1(N) > 0$ and $C'_2 = C'_2(N, \Omega, \|g_1\|_{L^N(\Omega)}, \|\varphi\|_{W^{1,1}(\Omega)}) > 0$. In conclusion, we obtain

$$(3.7) \quad \int_{\Omega} F(\nabla u) dx + \int_{\Omega} G(x, u) dx \geq \int_{\Omega} F(\nabla u) dx - C'_1 \|g_1\|_{L^N(\Omega)} \int_{\Omega} |\nabla u| dx - C''_2.$$

with $C''_2 = C''_2(N, \Omega, \|g_1\|_{L^N(\Omega)}, \|g_2\|_{L^1(\Omega)}, \|\varphi\|_{W^{1,1}(\Omega)}) > 0$.

We now take a minimizing sequence $\{u_n\}_{n \in \mathbb{N}} \subset \varphi + W_0^{1,1}(\Omega)$, thanks to the previous discussion we can suppose that

$$\int_{\Omega} \left[F(\nabla u_n) + G(x, u_n) \right] dx \leq C, \quad \text{for every } n \in \mathbb{N}.$$

In particular, by using (3.7), for every $n \in \mathbb{N}$ we get

$$(3.8) \quad \int_{\Omega} F(\nabla u_n) dx \leq C + C'_1 \|g_1\|_{L^N(\Omega)} \int_{\Omega} |\nabla u_n| dx + C''_2.$$

We now claim that the previous estimate implies

$$(3.9) \quad \int_{\Omega} F(\nabla u_n) dx \leq C, \quad \text{for every } n \in \mathbb{N},$$

for a different constant $C = C(N, |\Omega|, \|g_1\|_{L^N(\Omega)}, \|g_2\|_{L^1(\Omega)}, \|\varphi\|_{W^{1,1}(\Omega)}, F) > 0$. Indeed, if $g_1 \equiv 0$, then there is nothing to prove. Let us suppose $\|g_1\|_{L^N(\Omega)} > 0$. We now take

$$M = 2C'_1 \|g_1\|_{L^N(\Omega)},$$

we get

$$C'_1 \|g_1\|_{L^N(\Omega)} \int_{\Omega} |\nabla u_n| dx = \frac{M}{2} \int_{\Omega} |\nabla u_n| dx \leq \frac{1}{2} \int_{\Omega} F(\nabla u_n) dx + \frac{M}{2} r |\Omega|.$$

By using this information into (3.8), we get the claimed estimate (3.9). Since F is superlinear, estimate (3.9) implies that $\{\nabla u_n\}_{n \in \mathbb{N}}$ is equi-integrable ([35, Lemma 1.9.1]). Then Dunford-Pettis Theorem implies that a subsequence of $\{\nabla u_n\}_{n \in \mathbb{N}}$ (we do not relabel) weakly converges in L^1 to $\phi \in L^1(\Omega; \mathbb{R}^N)$. By Rellich Theorem, we may also assume that the sequence $\{u_n\}_{n \in \mathbb{N}}$ is strongly converging in $L^1(\Omega)$ to a function u . It is easy to see that $u \in W^{1,1}(\Omega)$ and $\nabla u = \phi$, since for every $\psi \in C_0^\infty(\Omega; \mathbb{R}^N)$ we have

$$\int_{\Omega} u \operatorname{div} \psi dx = \lim_{n \rightarrow \infty} \int_{\Omega} u_n \operatorname{div} \psi dx = - \lim_{n \rightarrow \infty} \int_{\Omega} \langle \nabla u_n, \psi \rangle dx = - \int_{\Omega} \langle \phi, \psi \rangle dx.$$

Then u is admissible for the variational problem. By lower semicontinuity of the functional we get the desired result. \square

4. A WEAKER RESULT: THE CASE OF μ -UNIFORMLY CONVEX PROBLEMS

In this section, as an intermediate result we prove the following weaker version of the Main Theorem. This will be used in the next section. The form of the Lipschitz estimate (4.1) below will play an important role.

Theorem 4.1. *Let $\Omega \subset \mathbb{R}^N$ be a bounded convex open set, $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}$ a Lipschitz continuous function, $F : \mathbb{R}^N \rightarrow \mathbb{R}$ a convex function and $f \in L^\infty(\Omega)$. We consider the following problem*

$$(P_\mu) \quad \min \left\{ \mathcal{F}(u) := \int_{\Omega} \left[F(\nabla u) + f u \right] dx : u - \varphi \in W_0^{1,1}(\Omega) \right\}.$$

Assume that $\varphi|_{\partial\Omega}$ satisfies the bounded slope condition of rank $K \geq 0$ and that F is μ -uniformly convex outside some ball B_R for some $0 < \mu \leq 1$.

Then every solution u of (P_μ) is Lipschitz continuous. More precisely, there exists a constant $\mathcal{L}_0 = \mathcal{L}_0(N, K, R, \|f\|_{L^\infty(\Omega)}, \text{diam}(\Omega)) > 0$ such that

$$(4.1) \quad \|\nabla u\|_{L^\infty(\Omega)} \leq \frac{\mathcal{L}_0}{\mu},$$

for every solution u .

In order to neatly present the proof of this result, we divide this section into subsections, each one corresponding to a step of the proof.

4.1. Step 0: a regularized problem. We will proceed by approximation. We consider a non-decreasing sequence of smooth convex functions $\{F_k\}_{k \in \mathbb{N}}$ on \mathbb{R}^N which converges uniformly on bounded sets to F and such that for every $k \in \mathbb{N}$

$$(4.2) \quad \langle D^2 F_k(x) \eta, \eta \rangle \geq \frac{\mu}{36} |\eta|^2, \quad \text{for every } x \in \mathbb{R}^N \setminus B_{R+1} \text{ and every } \eta \in \mathbb{R}^N.$$

See Lemma A.4 in Appendix A for the existence of such a sequence.

We also introduce a sequence $\{f_k\}_{k \in \mathbb{N}} \subset C_0^\infty(\mathbb{R}^N)$ which converges $*$ -weakly to f in $L^\infty(\Omega)$ and such that for every $k \in \mathbb{N}$

$$(4.3) \quad \|f_k\|_{L^\infty(\mathbb{R}^N)} \leq (\|f\|_{L^\infty(\Omega)} + 1) =: \Lambda.$$

Finally, let $\{\Omega_k\}_{k \in \mathbb{N}}$ and $\{\varphi_k\}_{k \in \mathbb{N}}$ be as in Lemma 2.5. We then define

$$\mathcal{F}_k(v) = \int_{\Omega_k} F_k(\nabla v) dx + \frac{1}{k} \int_{\Omega_k} |\nabla v|^2 dx + \int_{\Omega_k} f_k v dx,$$

and consider the following problem

$$(P_{\mu,k}) \quad \min \left\{ \mathcal{F}_k(u) : u - \varphi_k \in W_0^{1,1}(\Omega_k) \right\}.$$

Existence of a solution to $(P_{\mu,k})$ follows from Proposition 3.3. Moreover, since the Lagrangian is strictly convex in the gradient variable, such a solution is unique. We will denote it by $u_k \in \varphi_k + W_0^{1,1}(\Omega_k)$. Observe that by Theorem 2.7, we know that u_k is smooth on $\overline{\Omega}_k$. We aim at proving a global Lipschitz estimate independent of k .

Notation. In what follows, in order to simplify the notation, we denote the function u_k by U and the set Ω_k by \mathcal{O} .

4.2. Step 1: construction of uniform barriers. Without loss of generality, we can assume that $K + 2$ (the rank given by the bounded slope condition, see Lemma 2.5) is also the Lipschitz constant of φ_k on the whole \mathbb{R}^N (we only need to redefine φ_k outside $\partial\mathcal{O}$ if necessary).

The proof of Theorem 4.1 is based on the method of barriers that we now construct explicitly. In passing, we will also prove that minimizers of $(P_{\mu,k})$ are bounded, uniformly in k .

Proposition 4.2. *With the previous notation, there exist a constant*

$$L_0 = L_0(N, K, R, \|f\|_{L^\infty(\Omega)}, \text{diam}(\Omega)) > 0,$$

and two (L_0/μ) -Lipschitz maps $\ell^-, \ell^+ : \mathbb{R}^N \rightarrow \mathbb{R}$ with the following properties:

(i) for the solution U of $(P_{\mu,k})$, for every $x \in \mathcal{O}$,

$$\ell^-(x) \leq U(x) \leq \ell^+(x),$$

so that in particular $U \in L^\infty(\mathcal{O})$, with an estimate independent of k ;

(ii) $\ell^- = \ell^+ = \varphi_k$ on $\mathbb{R}^N \setminus \mathcal{O}$.

Proof. We only give the construction for ℓ^- , since the one for ℓ^+ is completely analogous. Let $y \in \partial\mathcal{O}$, we then take $\nu_{\mathcal{O}}(y)$ the unit outer normal to \mathcal{O} at y . Recall that by convexity of \mathcal{O}

$$\langle \nu_{\mathcal{O}}(y), x - y \rangle \leq 0, \quad \text{for every } x \in \mathcal{O}.$$

We introduce the function $a_{k,y}$ defined by

$$a_{k,y}(x) = \left[(2 \text{diam}(\mathcal{O}) + \langle \nu_{\mathcal{O}}(y), x - y \rangle)^2 - 4 \text{diam}(\mathcal{O})^2 \right].$$

Observe that this is a convex function such that

$$(4.4) \quad \Delta a_{k,y} = 2, \quad \text{in } \mathcal{O}, \quad a_{k,y} \leq 0 \text{ in } \overline{\mathcal{O}} \quad \text{and} \quad a_{k,y}(y) = 0.$$

We also observe that by Lemma 2.5, up to choosing k sufficiently large, we can suppose that

$$(4.5) \quad \text{diam}(\Omega) \leq \text{diam}(\mathcal{O}) \leq \text{diam}(\Omega) + 1.$$

Finally, we define for $x \in \mathbb{R}^N$,

$$\psi_y^-(x) = \varphi_k(y) + \langle \zeta_{k,y}^-, x - y \rangle + T a_{k,y}(x),$$

where $\zeta_{k,y}^-$ is chosen as in (1.2) and

$$T := \frac{18}{\mu} \left(\frac{R + K + 3}{\text{diam}(\Omega)} + \Lambda + 1 \right).$$

Recall that Λ is the constant defined by (4.3) and that $0 < \mu \leq 1$, by hypothesis. By construction we have $\psi_y^-(y) = \varphi_k(y)$ and ψ_y^- is (L_0/μ) -Lipschitz on \mathcal{O} , with

$$(4.6) \quad L_0 = 18 \left[4 \left(\frac{R + K + 3}{\text{diam}(\Omega)} + \Lambda + 1 \right) (\text{diam}(\Omega) + 1) + K + 2 \right].$$

In order to compute L_0 , we also used that

$$(4.7) \quad \text{diam}(\Omega) \leq |\nabla a_{k,y}(x)| = 2 \left| 2 \text{diam}(\mathcal{O}) + \langle \nu_{\mathcal{O}}(y), x - y \rangle \right| \leq 4 \text{diam}(\Omega) + 4,$$

which follows from the convexity of \mathcal{O} and (4.5). Moreover, by (1.2) and (4.4), we have

$$\psi_y^- \leq \varphi_k, \quad \text{on } \partial\mathcal{O}.$$

Let U be the minimum of $(P_{\mu,k})$. By testing the minimality of U against the function $\max\{U, \psi_y^-\}$ we get

$$(4.8) \quad \int_{\{U < \psi_y^-\}} [F_k(\nabla U) - F_k(\nabla \psi_y^-)] dx + \frac{1}{k} \int_{\{U < \psi_y^-\}} [|\nabla U|^2 - |\nabla \psi_y^-|^2] dx \\ \leq \int_{\{U < \psi_y^-\}} f_k(\psi_y^- - U) dx \leq \int_{\{U < \psi_y^-\}} f_k^+(\psi_y^- - U) dx.$$

By using convexity in the left-hand side of (4.8), we can estimate

$$(4.9) \quad \int_{\{U < \psi_y^-\}} [F_k(\nabla U) - F_k(\nabla \psi_y^-)] dx + \frac{1}{k} \int_{\{U < \psi_y^-\}} [|\nabla U|^2 - |\nabla \psi_y^-|^2] dx \\ \geq \int_{\{U < \psi_y^-\}} \langle \nabla F_k(\nabla \psi_y^-), \nabla U - \nabla \psi_y^- \rangle dx \\ + \frac{2}{k} \int_{\{U < \psi_y^-\}} \langle \nabla \psi_y^-, \nabla U - \nabla \psi_y^- \rangle dx.$$

By integration by parts,

$$\int_{\{U < \psi_y^-\}} \langle \nabla F_k(\nabla \psi_y^-), \nabla U - \nabla \psi_y^- \rangle dx + \frac{2}{k} \int_{\{U < \psi_y^-\}} \langle \nabla \psi_y^-, \nabla U - \nabla \psi_y^- \rangle dx \\ = \int_{\{U < \psi_y^-\}} \operatorname{div}(\nabla F_k(\nabla \psi_y^-)) (\psi_y^- - U) dx \\ + \frac{2}{k} \int_{\{U < \psi_y^-\}} \Delta \psi_y^- (\psi_y^- - U) dx.$$

By noticing that $\nabla \psi_y^- = \zeta_{k,y}^- + T \nabla a_{k,y}$ with $|\zeta_{k,y}^-| \leq K + 2$, the definition of T and the lower bound in (4.7) imply

$$R + 1 < T |\nabla a_{k,y}| - (K + 2) \leq |\nabla \psi_y^-|.$$

As a consequence of⁵ (4.2) and by construction of ψ_y^- , we have

$$\operatorname{div}(\nabla F_k(\nabla \psi_y^-)) = \sum_{i,j=1}^N \partial_{x_i x_j} F_k(\nabla \psi_y^-(x)) \partial_{x_i x_j} \psi_y^- \geq \frac{\mu}{36} \Delta \psi_y^- \\ = \frac{\mu}{36} T \Delta a_{k,y} = \frac{\mu}{18} T \geq \Lambda + 1 \geq f_k^+ + 1.$$

Hence,

$$\int_{\{U < \psi_y^-\}} \operatorname{div}(\nabla F_k(\nabla \psi_y^-)) (\psi_y^- - U) dx + \frac{2}{k} \int_{\{U < \psi_y^-\}} \Delta \psi_y^- (\psi_y^- - U) dx \\ \geq \int_{\{U < \psi_y^-\}} (f_k^+ + 1) (\psi_y^- - U) dx.$$

⁵If S_1 and S_2 are nonnegative symmetric matrices and λ is the lowest eigenvalue of S_1 , then $\operatorname{tr}(S_1 S_2) \geq \lambda \operatorname{tr}(S_2)$.

In view of (4.9), we thus obtain

$$\begin{aligned} \int_{\{U < \psi_y^-\}} [F_k(\nabla U) - F_k(\nabla \psi_y^-)] dx + \frac{1}{k} \int_{\{U < \psi_y^-\}} [|\nabla U|^2 - |\nabla \psi_y^-|^2] dx \\ \geq \int_{\{U < \psi_y^-\}} (f_k^+ + 1) (\psi_y^- - U) dx. \end{aligned}$$

But (4.8) then implies

$$|\{U < \psi_y^-\}| = 0, \quad \text{i.e. on } \mathcal{O}, \quad U \geq \psi_y^-.$$

We now define the map ℓ^- as follows

$$\ell^-(x) = \begin{cases} \sup_{y \in \partial \mathcal{O}} \psi_y^-(x), & \text{if } x \in \overline{\mathcal{O}}, \\ \varphi_k(x), & \text{otherwise.} \end{cases}$$

Since ℓ^- coincides with φ_k on $\mathbb{R}^N \setminus \mathcal{O}$, is (L_0/μ) -Lipschitz and satisfies $\ell^-(x) \leq U(x)$ for every $x \in \mathcal{O}$, this map has the desired properties. \square

4.3. Step 2: construction of competitors. We still denote by U a solution of $(P_{\mu,k})$ and we extend it by φ_k outside \mathcal{O} . Let L_0 be the constant appearing in Proposition 4.2. We pick $\alpha \geq (L_0/\mu)$ and $\tau \in \mathbb{R}^N \setminus \{0\}$ such that $\mathcal{O} \cap (\mathcal{O} - \tau) \neq \emptyset$. For every function ψ , we denote

$$\psi_\tau(x) = \psi(x + \tau), \quad x \in \mathbb{R}^N,$$

and we set

$$\psi_{\tau,\alpha}(x) = \psi_\tau(x) - \alpha |\tau|, \quad x \in \mathbb{R}^N.$$

Finally, we introduce the notation $\mathcal{O}_\tau := \mathcal{O} - \tau$ and consider the functional

$$\mathcal{F}_{k,\tau}(w) = \int_{\mathcal{O}_\tau} \left[F_k(\nabla w) + \frac{1}{k} |\nabla w|^2 + f_{k,\tau} w \right] dx, \quad w \in W^{1,1}(\mathcal{O}_\tau).$$

By a change of variables, we have the following.

Lemma 4.3. *The map $U_{\tau,\alpha}$ minimizes $\mathcal{F}_{k,\tau}$ on $U_{\tau,\alpha} + W_0^{1,1}(\mathcal{O}_\tau)$.*

In order to compare U and $U_{\tau,\alpha}$ on $\mathcal{O} \cap \mathcal{O}_\tau$, we will use the following result.

Lemma 4.4. *With the previous notation, we have*

$$U_{\tau,\alpha}(x) \leq U(x), \quad \text{for a.e. } x \in \mathbb{R}^N \setminus (\mathcal{O} \cap \mathcal{O}_\tau).$$

Proof. Let $x \in \mathbb{R}^N \setminus (\mathcal{O} \cap \mathcal{O}_\tau)$ be a Lebesgue point of U and U_τ .

We first consider the case $x \notin \mathcal{O}$. By using $U \leq \ell^+$ on \mathbb{R}^N , $\alpha \geq (L_0/\mu)$ and the (L_0/μ) -Lipschitz continuity of ℓ^+ , we get

$$U(x) = \varphi_k(x) = \ell^+(x) \geq \ell_\tau^+(x) - \frac{L_0}{\mu} |\tau| \geq U_\tau(x) - \frac{L_0}{\mu} |\tau| \geq U_{\tau,\alpha}(x).$$

If $x \notin \mathcal{O}_\tau$, we use $U \geq \ell^-$ on \mathbb{R}^N to get

$$U(x) \geq \ell^-(x) \geq \ell_\tau^-(x) - \frac{L_0}{\mu} |\tau| = (\varphi_k)_\tau(x) - \frac{L_0}{\mu} |\tau| = U_\tau(x) - \frac{L_0}{\mu} |\tau| \geq U_{\tau,\alpha}(x).$$

This completes the proof. \square

We now introduce the two functions

$$(4.10) \quad V = \begin{cases} \max\{U, U_{\tau,\alpha}\}, & \text{on } \mathcal{O} \cap \mathcal{O}_\tau, \\ U, & \text{on } \mathcal{O} \setminus \mathcal{O}_\tau, \end{cases} \quad W = \begin{cases} \min\{U, U_{\tau,\alpha}\} & \text{on } \mathcal{O} \cap \mathcal{O}_\tau, \\ U_{\tau,\alpha}, & \text{on } \mathcal{O}_\tau \setminus \mathcal{O}. \end{cases}$$

Then by Lemma 4.4, we have $V \in U + W_0^{1,1}(\mathcal{O})$ and $W \in U_{\tau,\alpha} + W_0^{1,1}(\mathcal{O}_\tau)$. By using the minimality of U , we have

$$\mathcal{F}_k(U) \leq \mathcal{F}_k(\theta V + (1 - \theta)U), \quad \text{for every } \theta \in [0, 1].$$

Analogously, by Lemma 4.3 we get

$$\mathcal{F}_{k,\tau}(U_{\tau,\alpha}) \leq \mathcal{F}_{k,\tau}(\theta W + (1 - \theta)U_{\tau,\alpha}), \quad \text{for every } \theta \in [0, 1].$$

By summing these two inequalities, and taking into account the definitions of V and W , with elementary manipulations we obtain

$$\begin{aligned} & \int_{A_\tau(\alpha)} \left[F_k(\nabla U_{\tau,\alpha}) + F_k(\nabla U) - F_k(\theta \nabla U_{\tau,\alpha} + (1 - \theta) \nabla U) - F_k(\theta \nabla U + (1 - \theta) \nabla U_{\tau,\alpha}) \right] dx \\ & + \frac{1}{k} \int_{A_\tau(\alpha)} \left[|\nabla U_{\tau,\alpha}|^2 + |\nabla U|^2 - |\theta \nabla U_{\tau,\alpha} + (1 - \theta) \nabla U|^2 - |\theta \nabla U + (1 - \theta) \nabla U_{\tau,\alpha}|^2 \right] dx \\ & \leq \theta \int_{A_\tau(\alpha)} (f_k - (f_k)_\tau) (U_{\tau,\alpha} - U) dx, \end{aligned}$$

where

$$A_\tau(\alpha) = \left\{ x \in \mathcal{O} \cap \mathcal{O}_\tau : \frac{U_{\tau,\alpha}(x) - U(x)}{|\tau|} \geq 0 \right\}.$$

By convexity of $z \mapsto |z|^2$, the second integral in the left-hand side above is nonnegative. This implies

$$(4.11) \quad \int_{A_\tau(\alpha)} \left[F_k(\nabla U_{\tau,\alpha}) + F_k(\nabla U) - F_k(\theta \nabla U_{\tau,\alpha} + (1 - \theta) \nabla U) - F_k(\theta \nabla U + (1 - \theta) \nabla U_{\tau,\alpha}) \right] dx \\ \leq \theta \int_{A_\tau(\alpha)} (f_k - (f_k)_\tau) (U_{\tau,\alpha} - U) dx.$$

4.4. Step 3: a uniform Lipschitz estimate. In this part we prove the following.

Proposition 4.5. *With the previous notation, we have*

$$\|\nabla U\|_{L^\infty(\mathcal{O})} \leq \frac{\mathcal{L}}{\mu},$$

for some constant $\mathcal{L} = \mathcal{L}(N, R, K, \|f\|_{L^\infty(\Omega)}, \text{diam}(\Omega)) > 0$. In particular, the estimate is independent of $k \in \mathbb{N}$.

Proof. Let us fix $k \in \mathbb{N}$. We define the set

$$A_\tau(\alpha, R) = \{x \in A_\tau(\alpha) : |\nabla U_{\tau,\alpha}(x)| \geq 2(R + 1) \text{ and } |\nabla U(x)| \geq 2(R + 1)\}.$$

By using equation (A.8) from Lemma A.3 in inequality (4.11), and then dividing by θ and letting θ go 0, we get

$$c\mu \int_{A_\tau(\alpha, R)} |\nabla U - \nabla U_{\tau,\alpha}|^2 dx \leq \int_{A_\tau(\alpha)} (f_k - (f_k)_\tau) (U_{\tau,\alpha} - U) dx,$$

for some universal constant $c > 0$. We now assume that $\tau = h e_1$ where $h > 0$ and e_1 is the first vector of the canonical basis of \mathbb{R}^N . Remember that f_k is compactly supported and define for almost every $x = (x_1, \dots, x_N) \in \mathbb{R}^N$

$$g_{k,h}(x_1, \dots, x_N) = \int_{x_1}^{x_1+h} f_k(t, x_2, \dots, x_N) dt.$$

Observe that $g_{k,h}$ is a smooth compactly supported function. Moreover, we have that $g_{k,h}/h$ converges uniformly to f_k , since

$$\left| \frac{g_{k,h}(x)}{h} - f_k(x) \right| \leq \frac{1}{h} \int_{x_1}^{x_1+h} |f_k(t, x_2, \dots, x_N) - f_k(x_1, x_2, \dots, x_N)| dt,$$

and f_k is smooth and compactly supported. By Fubini theorem, we also have for every $\eta \in W^{1,1}(\mathbb{R}^N)$

$$\int_{\mathbb{R}^N} g_{k,h} \eta_{x_1} dx = \int_{\mathbb{R}^N} (f_k - (f_k)_{h e_1}) \eta dx.$$

We apply this observation to the map $\eta = V - U \in W_0^{1,1}(\mathcal{O})$ (extended by 0 outside \mathcal{O}) where V is defined in (4.10). Since η coincides with $U_{h e_1, \alpha} - U$ on the set $A_{h e_1}(\alpha)$, we obtain

$$\begin{aligned} \int_{A_{h e_1}(\alpha)} (f_k - (f_k)_{h e_1}) (U_{h e_1, \alpha} - U) dx &= \int_{\mathbb{R}^N} g_{k,h} ((U_{h e_1, \alpha} - U)_+)_{x_1} dx \\ &= \int_{A_{h e_1}(\alpha)} g_{k,h} (U_{h e_1, \alpha} - U)_{x_1} dx. \end{aligned}$$

Observe that $(U_{h e_1, \alpha})_{x_1} = (U_{h e_1})_{x_1}$. If we commute the derivative and the translation, by dividing by a factor h^2 we then get

$$(4.12) \quad \int_{A_{h e_1}(\alpha, R)} \left| \frac{\nabla U_{h e_1, \alpha} - \nabla U}{h} \right|^2 dx \leq \frac{C}{\mu} \int_{A_{h e_1}(\alpha)} \frac{g_{k,h} (U_{x_1})_{h e_1} - U_{x_1}}{h} dx.$$

Now, since $\alpha \geq L_0/\mu > 2(R+1)$ (by definition of L_0 in (4.6) and the fact that $0 < \mu \leq 1$),

$$1_{\{U_{x_1} > \alpha\}} \leq \liminf_{h \rightarrow 0} 1_{A_{h e_1}(\alpha, R)} \leq \limsup_{h \rightarrow 0} 1_{A_{h e_1}(\alpha)} \leq 1_{\{U_{x_1} \geq \alpha\}}.$$

Here, we also use the fact that U is smooth on $\bar{\mathcal{O}}$. This implies that we can apply the dominated convergence theorem and let h go to 0 in (4.12), so to get

$$\int_{\{U_{x_1} > \alpha\}} |\nabla U_{x_1}|^2 dx \leq \frac{C}{\mu} \int_{\{U_{x_1} \geq \alpha\}} f_k U_{x_1} dx.$$

From this and the fact that $\nabla U_{x_1} = 0$ almost everywhere on $\{U_{x_1} = \alpha\}$, we get

$$\int_{\{U_{x_1} > \alpha\}} |\nabla U_{x_1}|^2 dx \leq \frac{C\Lambda}{\mu} \left(\int_{\{U_{x_1} > \alpha\}} |U_{x_1}| dx \right),$$

which implies by Hölder inequality

$$(4.13) \quad \|\nabla U_{x_1}\|_{L^2(\{U_{x_1} > \alpha\})} \leq C \frac{\Lambda}{\mu} |\{U_{x_1} > \alpha\}|^{\frac{1}{2}}.$$

We denote $\Theta(\alpha) = |\{x \in \mathcal{O} : U_{x_1} > \alpha\}|$ the distribution function of U_{x_1} . By Cavalieri principle, we have

$$\|U_{x_1} - \alpha\|_{L^1(\{U_{x_1} > \alpha\})} = \int_{\alpha}^{+\infty} |\{x \in \mathcal{O} : U_{x_1} > s\}| ds = \int_{\alpha}^{+\infty} \Theta(s) ds.$$

By Hölder and Sobolev inequalities and using (4.13), we obtain the following inequality for every $\alpha \geq L_0/\mu$,

$$\int_{\alpha}^{+\infty} \Theta(s) ds \leq \frac{C}{\mu} \Theta(\alpha)^\gamma,$$

for some⁶ $\gamma > 1$ and $C = C(N, \Lambda, \text{diam}(\mathcal{O})) > 0$. In other words, the nonnegative nonincreasing function $\chi(\alpha) = \int_{\alpha}^{+\infty} \Theta(s) ds$ satisfies the following differential inequality

$$\chi(\alpha) \leq \frac{C}{\mu} (-\chi'(\alpha))^\gamma, \quad \text{for every } \alpha \geq \frac{L_0}{\mu},$$

where $C = C(N, \Lambda, \text{diam}(\mathcal{O})) > 0$. This easily implies (as in Gronwall Lemma) that $\chi(\alpha) = 0$ for every $\alpha \geq \alpha_0$ where

$$\alpha_0 = \frac{L_0}{\mu} + \frac{\gamma}{\gamma-1} \left(\frac{C}{\mu}\right)^{\frac{1}{\gamma}} \left(\int_{L_0/\mu}^{+\infty} \Theta(s) ds\right)^{\frac{\gamma-1}{\gamma}}.$$

Since $\chi(L_0/\mu) \leq (C/\mu) \Theta(L_0/\mu)^\gamma \leq (C/\mu) |\mathcal{O}|^\gamma$, we get

$$\alpha_0 \leq \frac{L_0}{\mu} + \frac{C}{\mu} \frac{\gamma}{\gamma-1} |\mathcal{O}|^{\gamma-1}.$$

Observe that by definition we have $|\mathcal{O}| = |\Omega_k|$. Then by Lemma 2.5 and the isodiametric inequality, up to choosing k sufficiently large we can suppose that $|\mathcal{O}| = |\Omega_k| \leq C(\text{diam}(\Omega) + 1)^N$, for a constant $C = C(N) > 0$. We thus have

$$\alpha_0 \leq \frac{L_0}{\mu} + \frac{C}{\mu} \frac{\gamma}{\gamma-1} (\text{diam}(\Omega) + 1)^{(\gamma-1)N} =: \frac{L_1}{\mu},$$

possibly for a different constant $C = C(N, \Lambda, \text{diam}(\Omega)) > 0$. Observe that by definition of L_0 , $L_1 = L_1(N, K, R, \Lambda, \text{diam}(\Omega)) > 0$. Thus we have $\Theta(L_1/\mu) = 0$ and hence

$$U_{x_1} \leq \frac{L_1}{\mu} \quad \text{on } \mathcal{O}.$$

By reproducing the previous proof with $h < 0$, we can show that $U_{x_1} \geq -L_1/\mu$ as well. In the end $|U_{x_1}| \leq L_1/\mu$ and of course this is true for every partial derivative, thus $\|\nabla U\|_{L^\infty(\mathcal{O})} \leq \sqrt{N} L_1/\mu =: \mathcal{L}/\mu$. \square

4.5. Step 4: passage to the limit. Since we have to pass to the limit as k goes to ∞ , it is now convenient to restore the original notation u_k and Ω_k . Let us set

$$\tilde{u}_k := u_k|_{\bar{\Omega}}, \quad k \in \mathbb{N}.$$

By Proposition 4.5 and Ascoli-Arzelà Theorem, there exists a subsequence of $\{\tilde{u}_k\}_{k \in \mathbb{N}}$ (we do not relabel) which uniformly converges to some map v on $\bar{\Omega}$. Moreover, v is still (\mathcal{L}/μ) -Lipschitz continuous on $\bar{\Omega}$.

Lemma 4.6. *The limit function v solves (P_μ) .*

⁶In fact, when $N \geq 3$, one can take $\gamma = (N+1)/N$ and C independent of $\text{diam}(\mathcal{O})$.

Proof. We first prove that v agrees with φ on $\partial\Omega$. Let $y \in \partial\Omega$, by Lemma 2.5 there exists a sequence of points $y_k \in \partial\Omega_k$ converging to y . Then

$$|v(y) - \varphi(y)| \leq |v(y) - u_k(y)| + |u_k(y) - u_k(y_k)| + |\varphi_k(y_k) - \varphi_k(y)|.$$

Here, we have used the fact that $u_k|_{\partial\Omega_k} = \varphi_k|_{\partial\Omega_k}$ and $\varphi_k|_{\partial\Omega} = \varphi$. Since the Lipschitz constants of u_k and φ_k can be bounded independently of k , this implies $v(y) = \varphi(y)$. Hence, $v = \varphi$ on $\partial\Omega$.

We now prove that v minimizes \mathcal{F} in $\varphi + W_0^{1,1}(\Omega)$. Let $w \in \varphi + W_0^{1,1}(\Omega)$. If $w \notin W^{1,2}(\Omega)$, then inequality (A.9) in Lemma A.3 below implies that $\mathcal{F}(w) = +\infty$. Hence, we can assume that $w \in W^{1,2}(\Omega)$. We denote by w_k the extension of w by φ_k outside Ω . Observe that we have $w_k \in \varphi_k + W_0^{1,2}(\Omega_k)$. Then for every $k \in \mathbb{N}$ we have $\mathcal{F}_k(u_k) \leq \mathcal{F}_k(w_k)$, which gives

$$(4.14) \quad \int_{\Omega_k} F_k(\nabla u_k) dx + \int_{\Omega_k} f_k u_k dx \leq \int_{\Omega_k} F_k(\nabla w_k) dx + \frac{1}{k} \int_{\Omega_k} |\nabla w_k|^2 dx + \int_{\Omega_k} f_k w_k dx.$$

We observe that by definition of w_k and the fact that $F_k \leq F$, we get

$$\int_{\Omega_k} F_k(\nabla w_k) dx \leq \int_{\Omega} F(\nabla w) dx + \int_{\Omega_k \setminus \Omega} F(\nabla \varphi_k) dx.$$

Since φ_k is $(K+2)$ -Lipschitz, this gives

$$\int_{\Omega_k} F_k(\nabla w_k) dx \leq \int_{\Omega} F(\nabla w) dx + |\Omega_k \setminus \Omega| \max_{\xi \in B_{K+2}} F(\xi).$$

By using Lemma 2.5, we thus obtain

$$(4.15) \quad \limsup_{k \rightarrow +\infty} \int_{\Omega_k} F_k(\nabla w_k) dx \leq \int_{\Omega} F(\nabla w) dx.$$

We also observe that

$$(4.16) \quad \begin{aligned} F_k(\nabla u_k(x)) &\geq F(\nabla u_k(x)) - |F_k(\nabla u_k(x)) - F(\nabla u_k(x))| \\ &\geq F(\nabla u_k(x)) - \max_{\{\xi: |\xi| \leq \mathcal{L}/\mu\}} |F_k(\xi) - F(\xi)|. \end{aligned}$$

and

$$(4.17) \quad \int_{\Omega_k} F(\nabla u_k) dx \geq \int_{\Omega} F(\nabla u_k) dx - |\Omega_k \setminus \Omega| \max_{\xi \in B_{\mathcal{L}/\mu}} F(\xi),$$

where we used Proposition 4.5. The sequence $\{F_k\}_{k \in \mathbb{N}}$ uniformly converges to F on bounded sets, thus using (4.16) and (4.17) we get

$$(4.18) \quad \begin{aligned} \liminf_{k \rightarrow +\infty} \int_{\Omega_k} F_k(\nabla u_k) dx &\geq \liminf_{k \rightarrow +\infty} \left(\int_{\Omega} F(\nabla u_k) dx - |\Omega_k| \|F_k - F\|_{L^\infty(B_{\mathcal{L}/\mu})} - |\Omega_k \setminus \Omega| \|F\|_{L^\infty(B_{\mathcal{L}/\mu})} \right) \\ &\geq \liminf_{k \rightarrow +\infty} \int_{\Omega} F(\nabla u_k) dx \geq \int_{\Omega} F(\nabla v) dx. \end{aligned}$$

In the last inequality we used the weak lower semicontinuity of the functional $w \mapsto \int_{\Omega} F(\nabla w)$ on $W^{1,1}(\Omega)$. Clearly,

$$(4.19) \quad \lim_{k \rightarrow +\infty} \frac{1}{k} \int_{\Omega_k} |\nabla w_k|^2 dx = \lim_{k \rightarrow +\infty} \left[\frac{1}{k} \int_{\Omega} |\nabla w|^2 dx + \frac{1}{k} \int_{\Omega_k \setminus \Omega} |\nabla \varphi_k|^2 dx \right] = 0.$$

By recalling (4.3) and that $|\Omega_k \setminus \Omega|$ converges to 0, we have

$$\lim_{k \rightarrow \infty} \left| \int_{\Omega_k \setminus \Omega} f_k w_k dx \right| \leq \Lambda \lim_{k \rightarrow \infty} \|\varphi_k\|_{L^1(\Omega_k \setminus \Omega)} = 0.$$

By using this fact, the $*$ -weak convergence of f_k to f in $L^\infty(\Omega)$ and that $w_k = w$ on Ω , we get

$$(4.20) \quad \lim_{k \rightarrow \infty} \int_{\Omega_k} f_k w_k dx = \lim_{k \rightarrow \infty} \int_{\Omega} f_k w dx = \int_{\Omega} f w dx.$$

Moreover, since $\{\tilde{u}_k\}_{k \in \mathbb{N}}$ converges to v in $L^1(\Omega)$, with a similar argument we also have

$$(4.21) \quad \lim_{k \rightarrow \infty} \int_{\Omega_k} f_k u_k dx = \int_{\Omega} f v dx.$$

By passing to the limit in (4.14) and using (4.18), (4.15), (4.19), (4.20) and (4.21), we get $\mathcal{F}(v) \leq \mathcal{F}(w)$. By arbitrariness of w , this shows that v is a solution of (P_μ) . \square

4.6. Step 5: conclusion. Since v is a (\mathcal{L}/μ) -Lipschitz solution of (P_μ) , we use Lemma 2.8 to conclude that every solution u of (P_μ) is Lipschitz continuous. More precisely, we have the following estimate

$$\|\nabla u\|_{L^\infty(\Omega)} \leq 2R + \|\nabla v\|_{L^\infty(\Omega)} \leq \frac{(2R + \mathcal{L})}{\mu} =: \frac{\mathcal{L}_0}{\mu},$$

where we used again that $0 < \mu \leq 1$. This completes the proof of Theorem 4.1.

5. PROOF OF THE MAIN THEOREM

Finally, we come to the proof of the Main Theorem. We will need the following ‘‘density in energy’’ result, whose proof can be found in [4, Theorem 4.1]. The original statement is indeed fairly more general, we give a version adapted to our needs.

Lemma 5.1 ([4]). *Let $\Omega \subset \mathbb{R}^N$ be an open bounded convex set. Let $F : \mathbb{R}^N \rightarrow \mathbb{R}$ be a convex function, $f \in L^N(\Omega)$ and $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}$ a Lipschitz continuous function. Then for every $u \in \varphi + W_0^{1,1}(\Omega)$ such that*

$$\int_{\Omega} |F(\nabla u)| dx < +\infty,$$

there exists a sequence $\{u_k\}_{k \in \mathbb{N}} \subset \varphi + W_0^{1,\infty}(\Omega)$ such that

$$(5.1) \quad \lim_{k \rightarrow \infty} \|u_k - u\|_{W^{1,1}(\Omega)} = 0 \quad \text{and} \quad \lim_{k \rightarrow \infty} \int_{\Omega} [F(\nabla u_k) + f u_k] dx = \int_{\Omega} [F(\nabla u) + f u] dx.$$

Proof. For the case $f \equiv 0$, the proof is contained in [4]. In order to cover the case $f \in L^N(\Omega)$, it is sufficient to observe that by Sobolev embedding and strong convergence in $W^{1,1}(\Omega)$, the sequence $\{u_k\}_{k \in \mathbb{N}}$ also converges weakly in $L^{N'}(\Omega)$. Then the result easily follows. \square

5.1. Step 1: reduction to μ -uniformly convex problems. For every $Q > R$, we consider the minimization problem

$$(P_Q) \quad \min \left\{ \int_{\Omega} [F_Q(\nabla u) + f u] dx : u - \varphi \in W_0^{1,1}(\Omega) \right\},$$

where $F_Q : \mathbb{R}^N \rightarrow \mathbb{R}$ is a convex function such that

- i) $F_Q \equiv F$ in B_Q ;
- ii) F is μ_Q -uniformly convex outside the ball B_R , with

$$\mu_Q = \min \left\{ 1, \min_{t \in [2R, 4Q]} \Phi(t) \right\},$$

see Lemma A.5 below. Observe that $0 < \mu_Q \leq 1$. By Theorem 4.1 and (4.1), we get that every minimizer u_Q of (P_Q) is such that

$$\|\nabla u_Q\|_{L^\infty(\Omega)} \leq \frac{\mathcal{L}_0}{\mu_Q},$$

with \mathcal{L}_0 independent of Q . We now take $Q \gg R$ sufficiently large so that

$$\frac{\mathcal{L}_0}{\mu_Q} \leq Q - 1.$$

Observe that this is possible, thanks to the definition of μ_Q and the crucial property (1.4) of the function Φ . Thanks to this choice and the construction of the function F_Q , we thus get

$$(5.2) \quad F_Q(\nabla u_Q) = F(\nabla u_Q).$$

For every $v \in \varphi + W_0^{1,\infty}(\Omega)$ we choose $\theta \in (0, 1)$ such that

$$\theta (Q - 1 - \|\nabla v\|_{L^\infty(\Omega)}) + \|\nabla v\|_{L^\infty(\Omega)} \leq Q.$$

Then the function $\theta u_Q + (1 - \theta)v$ is such that

$$\|\theta \nabla u_Q + (1 - \theta) \nabla v\|_{L^\infty(\Omega)} \leq Q,$$

so that by using again $F \equiv F_Q$ in the ball B_Q and the convexity of F , we get

$$(5.3) \quad \begin{aligned} F_Q(\theta \nabla u_Q + (1 - \theta) \nabla v) &= F(\theta \nabla u_Q + (1 - \theta) \nabla v) \\ &\leq \theta F(\nabla u_Q) + (1 - \theta) F(\nabla v). \end{aligned}$$

We observe that $\theta u_Q + (1 - \theta)v$ is admissible for (P_Q) , then by using the minimality of u_Q , (5.2) and (5.3), we obtain

$$\int_{\Omega} F(\nabla u_Q) + f u_Q dx \leq \theta \int_{\Omega} [F(\nabla u_Q) + f u_Q] dx + (1 - \theta) \int_{\Omega} [F(\nabla v) + f v] dx,$$

which finally shows that u_Q minimizes the original Lagrangian \mathcal{F} among Lipschitz functions, i.e. u_Q is a solution of

$$\min \left\{ \int_{\Omega} [F(\nabla u) + f u] dx : u - \varphi \in W_0^{1,\infty}(\Omega) \right\}.$$

5.2. Step 2: conclusion by density. In order to complete the proof, it is only left to prove that u_Q minimizes \mathcal{F} among $W^{1,1}$ functions as well. At this aim, let $v \in \varphi + W_0^{1,1}(\Omega)$ be such that

$$\int_{\Omega} \left[F(\nabla v) + f v \right] dx < +\infty.$$

Since $f v \in L^1(\Omega)$, this implies that $\int_{\Omega} F(\nabla v) < +\infty$. By noting F_+ and F_- the positive and negative parts of F , we observe that by (3.6), we can infer

$$\int_{\Omega} F_-(\nabla v) dx \leq \max_{B_r} |F| |\Omega|.$$

This and the fact that

$$+\infty > \int_{\Omega} F(\nabla v) dx = \int_{\Omega} F_+(\nabla v) dx - \int_{\Omega} F_-(\nabla v) dx,$$

imply $F(\nabla v) \in L^1(\Omega)$. By Lemma 5.1, then there exists a sequence $\{v_k\}_{k \in \mathbb{N}} \subset \varphi + W_0^{1,\infty}(\Omega)$ such that (5.1) holds. By using the minimality of u_Q in $\varphi + W_0^{1,\infty}(\Omega)$, we get

$$\int_{\Omega} \left[F(\nabla u_Q) + f u_Q \right] dx \leq \int_{\Omega} \left[F(\nabla v_k) + f v_k \right] dx.$$

If we now pass to the limit and use (5.1), we obtain that u_Q is a Lipschitz solution of (P_{Φ}) . By appealing again to Lemma 2.8, we finally obtain that every solution of (P_{Φ}) is globally Lipschitz continuous. This concludes the proof of the Main Theorem.

6. MORE GENERAL LOWER ORDER TERMS

In this section, we consider more general functionals of the form

$$\mathcal{F}(u) = \int_{\Omega} \left[F(\nabla u) + G(x, u) \right] dx,$$

where $G : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ is a measurable function which satisfies the following assumptions:

(HG) • there exists a constant $L > 0$ such that

$$|G(x, u) - G(x, v)| \leq L |u - v|, \quad \text{for a.e. } x \in \Omega, \text{ every } u, v \in \mathbb{R};$$

• there exists $b \in L^1(\Omega)$ such that

$$\int_{\Omega} |G(x, b(x))| dx < +\infty.$$

Remark 6.1. As a consequence of (HG), we have that for every $v \in L^1(\Omega)$ (in particular for every $v \in \varphi + W_0^{1,1}(\Omega)$), the map $x \mapsto G(x, v(x))$ is in $L^1(\Omega)$.

We then have the following generalization of the Main Theorem.

Theorem 6.2. *Let $\Omega \subset \mathbb{R}^N$ be a bounded convex open set, $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}$ a Lipschitz function, $F : \mathbb{R}^N \rightarrow \mathbb{R}$ a convex function and $G : \Omega \times \mathbb{R} \rightarrow \mathbb{R}$ a map satisfying (HG). We consider the following problem*

$$(P_G) \quad \min \left\{ \int_{\Omega} \left[F(\nabla u) + G(x, u) \right] dx : u - \varphi \in W_0^{1,1}(\Omega) \right\}.$$

We assume that $\varphi|_{\partial\Omega}$ satisfies the bounded slope condition of rank $K \geq 0$ and that F is Φ -uniformly convex outside some ball B_R . Then problem (P_G) admits a solution and every such a solution is Lipschitz continuous.

Proof. Assumption (HG) implies that for almost every $x \in \Omega$ and every $v \in \mathbb{R}$,

$$G(x, v) \geq G(x, b(x)) - L|v - b(x)| \geq \left[G(x, b(x)) - L|b(x)| \right] - L|v|,$$

and the function into square brackets is in $L^1(\Omega)$. Thus we can apply Proposition 3.3 and deduce existence of a solution $u \in W_0^{1,1}(\Omega) + \varphi$. We now divide the proof in two parts.

Part I. Let us first assume that for almost every $x \in \Omega$, $v \mapsto G(x, v)$ is differentiable. We denote by f the measurable map

$$f(x) = G_u(x, u(x)).$$

Observe that $|f| \leq L$ almost everywhere on Ω . For every $v \in \varphi + W_0^{1,1}(\Omega)$ and every $\theta \in (0, 1)$, the minimality of u implies

$$\mathcal{F}(u) \leq \mathcal{F}((1 - \theta)u + \theta v).$$

Hence, by convexity of F ,

$$\int_{\Omega} F(\nabla u) dx \leq \int_{\Omega} F(\nabla v) dx + \int_{\Omega} \left[\frac{G(x, u + \theta(v - u)) - G(x, u)}{\theta} \right] dx.$$

Thanks to (HG) , we can apply the dominated convergence theorem in the right-hand side to get

$$\int_{\Omega} \left[F(\nabla u) + f u \right] dx \leq \int_{\Omega} \left[F(\nabla v) + f v \right] dx.$$

This proves that u is a minimum of the initial problem (P_{Φ}) to which the Main Theorem applies. In particular, u is \mathcal{L} -Lipschitz continuous, where \mathcal{L} depends on $N, \Phi, K, R, \text{diam}(\Omega)$ and L . This proves the statement under the additional assumption that G is differentiable with respect to u .

Part II. In the general case, we introduce the sequence

$$G_{\varepsilon}(x, u) = \int_{\mathbb{R}} G(x, u - v) \rho_{\varepsilon}(v) dv,$$

where ρ_{ε} is a smooth convolution kernel. Observe that G_{ε} satisfies (HG) with the same quantities L and b and is differentiable with respect to u . Hence, we can apply Proposition 3.3 again to obtain a solution u_{ε} to

$$\min \left\{ \int_{\Omega} \left[F(\nabla u) + G_{\varepsilon}(x, u) \right] dx : u - \varphi \in W_0^{1,1}(\Omega) \right\}.$$

By Part I of the proof, we know that u_{ε} is α_1 -Lipschitz continuous, with α_1 independent of ε . Up to a subsequence, this net of minimizers thus converges to a Lipschitz continuous function, which solves (P_G) . This last assertion can be established as in Lemma 4.6. In view of Lemma 2.8, this completes the proof of Theorem 6.2. \square

When Ω is a uniformly convex set, every $C^{1,1}$ map $\varphi : \partial\Omega \rightarrow \mathbb{R}$ satisfies the bounded slope condition. In contrast, this condition becomes more restrictive when $\partial\Omega$ contains affine faces. For instance, if Ω is a convex polytope, the bounded slope condition requires φ to be affine on each face of $\partial\Omega$. In [8], Clarke has introduced the lower bounded slope condition, which can be seen as one half of the full two sided bounded slope condition.

Definition 6.3. Let Ω be a bounded open set in \mathbb{R}^N and $K > 0$. We say that a map $\varphi : \partial\Omega \rightarrow \mathbb{R}$ satisfies the *lower bounded slope condition of rank K* if for every $y \in \partial\Omega$, there exists $\zeta_y^- \in \mathbb{R}^N$ such that $|\zeta_y^-| \leq K$ and

$$\varphi(y) + \langle \zeta_y^-, x - y \rangle \leq \varphi(x), \quad \text{for every } x \in \partial\Omega.$$

It follows from the proof of Lemma 2.3 that a function $\varphi : \partial\Omega \rightarrow \mathbb{R}$ satisfies the lower bounded slope condition if and only if it is the restriction to $\partial\Omega$ of a convex function defined on \mathbb{R}^N . The Main Theorem has the following variant when the bounded slope condition is replaced by the weaker lower bounded slope condition:

Theorem 6.4. *Let Ω be a bounded convex open set in \mathbb{R}^N , $\varphi : \mathbb{R}^N \rightarrow \mathbb{R}$ a Lipschitz continuous function, $F : \mathbb{R}^N \rightarrow \mathbb{R}$ a convex function and $f \in L^\infty(\Omega)$. We assume that $\varphi|_{\partial\Omega}$ satisfies the lower bounded slope condition of rank $K \geq 0$ and that F is μ -uniformly convex outside some ball B_R . Then every solution u of (P_Φ) is locally Lipschitz continuous on Ω .*

The proof follows the lines of the proof of the Main Theorem except that the translation technique in Step 2 of the proof of Theorem 4.1 must be replaced by the dilation technique introduced in [8]. We omit the details.

APPENDIX A. UNIFORMLY CONVEX FUNCTIONS OUTSIDE A BALL

A.1. Basic properties. We first present a characterization of uniformly convex functions outside a ball in terms of second order derivatives.

Lemma A.1. *Let $F : \mathbb{R}^N \rightarrow \mathbb{R}$ be a convex function and $\{\rho_\varepsilon\}_{\varepsilon>0} \subset C_0^\infty(B_\varepsilon)$ be a sequence of standard mollifiers.*

(i) *Assume that F is Φ -uniformly convex outside some ball B_R . Then for every $\varepsilon > 0$, for every $R' > R + \varepsilon$, for every $\xi \in B_{R'} \setminus B_{R+\varepsilon}$ and $\eta \in \mathbb{R}^N$,*

$$(A.1) \quad \langle D^2(F * \rho_\varepsilon)(\xi) \eta, \eta \rangle \geq \left(\min_{t \in [2R, 2(R'+\varepsilon)]} \Phi(t) \right) |\eta|^2.$$

(ii) *Assume that there exist $\mu > 0$ and $R > 0$ such that for every $\varepsilon > 0$, for every $|x| \geq R + \varepsilon$, for every $\eta \in \mathbb{R}^N$,*

$$(A.2) \quad \langle D^2(F * \rho_\varepsilon)(x) \eta, \eta \rangle \geq \mu |\eta|^2.$$

Then F is μ -uniformly convex outside B_R .

Proof. Assume first that F is Φ -uniformly convex outside B_R . For every $\xi \in B_{R'} \setminus B_{R+\varepsilon}$, for every $y \in B_\varepsilon$, $\eta \in \mathbb{R}^N$ and every $h > 0$ sufficiently small, the segment $[\xi + h\eta - y, \xi - h\eta - y]$ does not intersect B_R . Hence

$$\begin{aligned} F(\xi - y) &\leq \frac{1}{2}F(\xi + h\eta - y) + \frac{1}{2}F(\xi - h\eta - y) - \frac{1}{2}h^2|\eta|^2\Phi(|\xi + h\eta - y| + |\xi - h\eta - y|) \\ &\leq \frac{1}{2}F(\xi + h\eta - y) + \frac{1}{2}F(\xi - h\eta - y) - \frac{1}{2}h^2|\eta|^2 \left(\min_{t \in [2R, 2(R'+\varepsilon+h|\eta|)]} \Phi(t) \right). \end{aligned}$$

By multiplying by $\rho_\varepsilon(y)$ and integrating, this gives

$$F * \rho_\varepsilon(\xi) \leq \frac{1}{2}F * \rho_\varepsilon(\xi + h\eta) + \frac{1}{2}F * \rho_\varepsilon(\xi - h\eta) - \frac{1}{2}h^2|\eta|^2 \left(\min_{t \in [2R, 2(R'+\varepsilon+h|\eta|)]} \Phi(t) \right).$$

Hence, we get

$$\begin{aligned} \langle D^2(F * \rho_\varepsilon)(\xi) \eta, \eta \rangle &= \lim_{h \rightarrow 0} \frac{F * \rho_\varepsilon(\xi + h \eta) + F * \rho_\varepsilon(\xi - h \eta) - 2F * \rho_\varepsilon(\xi)}{h^2} \\ &\geq \left(\min_{t \in [2R, 2(R'+\varepsilon)]} \Phi(t) \right) |\eta|^2. \end{aligned}$$

This completes the proof of (A.1).

Assume now that (A.2) holds true. Let $\theta \in [0, 1]$ and $\xi, \xi' \in \mathbb{R}^N$ be such that $[\xi, \xi'] \cap B_R = \emptyset$. For every $\varepsilon > 0$, we take $\xi_\varepsilon, \xi'_\varepsilon \in \mathbb{R}^N$ such that $[\xi_\varepsilon, \xi'_\varepsilon] \cap B_{R+\varepsilon} = \emptyset$ and

$$\lim_{\varepsilon \rightarrow 0} |\xi_\varepsilon - \xi| = 0 \quad \text{and} \quad \lim_{\varepsilon \rightarrow 0} |\xi'_\varepsilon - \xi'| = 0.$$

We have

$$\begin{aligned} F * \rho_\varepsilon(\xi_\varepsilon) &= F * \rho_\varepsilon(\theta \xi_\varepsilon + (1 - \theta) \xi'_\varepsilon) + (1 - \theta) \langle \nabla(F * \rho_\varepsilon)(\theta \xi_\varepsilon + (1 - \theta) \xi'_\varepsilon), \xi_\varepsilon - \xi'_\varepsilon \rangle \\ &\quad + (1 - \theta)^2 \int_0^1 (1 - t) \langle D^2(F * \rho_\varepsilon)(t \xi_\varepsilon + (1 - t) (\theta \xi_\varepsilon + (1 - \theta) \xi'_\varepsilon)) (\xi_\varepsilon - \xi'_\varepsilon), \xi_\varepsilon - \xi'_\varepsilon \rangle dt. \end{aligned}$$

Since the segment $[\xi_\varepsilon, \theta \xi_\varepsilon + (1 - \theta) \xi'_\varepsilon]$ does not intersect $B_{R+\varepsilon}$, assumption (A.2) implies

$$\begin{aligned} F * \rho_\varepsilon(\xi_\varepsilon) &\geq F * \rho_\varepsilon(\theta \xi_\varepsilon + (1 - \theta) \xi'_\varepsilon) + (1 - \theta) \langle \nabla(F * \rho_\varepsilon)(\theta \xi_\varepsilon + (1 - \theta) \xi'_\varepsilon), \xi_\varepsilon - \xi'_\varepsilon \rangle \\ &\quad + \frac{\mu}{2} (1 - \theta)^2 |\xi_\varepsilon - \xi'_\varepsilon|^2. \end{aligned}$$

Similarly, we get

$$\begin{aligned} F * \rho_\varepsilon(\xi'_\varepsilon) &\geq F * \rho_\varepsilon(\theta \xi_\varepsilon + (1 - \theta) \xi'_\varepsilon) + \theta \langle \nabla(F * \rho_\varepsilon)(\theta \xi_\varepsilon + (1 - \theta) \xi'_\varepsilon), \xi'_\varepsilon - \xi_\varepsilon \rangle \\ &\quad + \frac{\mu}{2} \theta^2 |\xi_\varepsilon - \xi'_\varepsilon|^2. \end{aligned}$$

We multiply the first inequality by θ and the second one by $(1 - \theta)$. By summing them, we get

$$\theta F * \rho_\varepsilon(\xi_\varepsilon) + (1 - \theta) F * \rho_\varepsilon(\xi'_\varepsilon) \geq F * \rho_\varepsilon(\theta \xi_\varepsilon + (1 - \theta) \xi'_\varepsilon) + \frac{\mu}{2} \theta (1 - \theta) |\xi_\varepsilon - \xi'_\varepsilon|^2.$$

We then let ε go to 0 to obtain (1.5). This completes the proof. \square

We will also need the following technical result. Here \mathcal{H}^1 denotes the 1-dimensional Hausdorff measure.

Lemma A.2. *Let F be a convex function which is μ -uniformly convex outside $B_R \subset \mathbb{R}^N$. For every $\xi, \xi' \in \mathbb{R}^N$ and every $\zeta \in \partial F(\xi)$, we have*

$$(A.3) \quad F(\xi') \geq F(\xi) + \langle \zeta, \xi' - \xi \rangle + \frac{\mu}{4} \mathcal{H}^1([\xi, \xi'] \setminus B_R)^2.$$

Proof. We can assume that $\xi \neq \xi'$. We have several possible cases:

Case A. $\mathcal{H}^1([\xi, \xi'] \setminus B_R) = \mathcal{H}^1([\xi, \xi'])$. In this case, the segment $[\xi, \xi']$ does not intersect B_R and thus (A.3) follows directly from (3.1) with $\Phi \equiv \mu$.

Case B. $\mathcal{H}^1([\xi, \xi'] \setminus B_R) = 0$. Then (A.3) follows from the convexity of F .

Case C. $0 < \mathcal{H}^1([\xi, \xi'] \setminus B_R) < \mathcal{H}^1([\xi, \xi'])$. Without loss of generality, we may assume that $\xi \notin \overline{B_R}$ and that the half-line $\{\xi + t(\xi' - \xi); t \geq 0\}$ intersects the sphere ∂B_R at two points ξ_1, ξ_2 such that $\xi_1 \in [\xi_2, \xi]$. We now in turn have to consider two cases:

$$\xi' \in [\xi_1, \xi_2] \quad \text{or} \quad \xi_2 \in [\xi', \xi_1],$$

(see Figure 2 below).

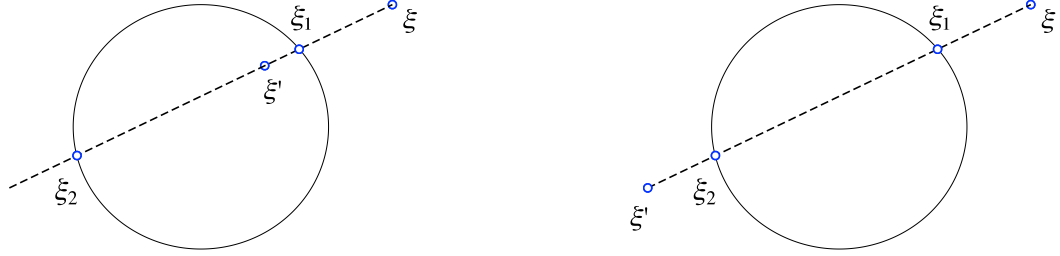


FIGURE 2. The two possibilities for *Case C* in the proof of Lemma A.2.

When $\xi' \in [\xi_1, \xi_2]$, we use the fact that the segment $[\xi_1, \xi]$ lies outside the ball B_R . It follows from (3.1) with $\Phi \equiv \mu$ that for every $\zeta_1 \in \partial F(\xi_1)$,

$$(A.4) \quad F(\xi) \geq F(\xi_1) + \langle \zeta_1, \xi - \xi_1 \rangle + \frac{\mu}{2} |\xi - \xi_1|^2.$$

Let $\zeta' \in \partial F(\xi')$. By convexity of F , we also have

$$(A.5) \quad F(\xi_1) \geq F(\xi') + \langle \zeta', \xi_1 - \xi' \rangle,$$

and

$$\langle \zeta_1 - \zeta', \xi_1 - \xi' \rangle \geq 0,$$

since the subdifferential of F is a monotone map. The latter inequality implies that

$$\langle \zeta_1 - \zeta', \xi - \xi_1 \rangle \geq 0.$$

Together with (A.4) and (A.5), with some manipulations this yields

$$\begin{aligned} F(\xi) &\geq F(\xi') + \langle \zeta', \xi - \xi' \rangle + \frac{\mu}{2} |\xi - \xi_1|^2 \\ &= F(\xi') + \langle \zeta', \xi - \xi' \rangle + \frac{\mu}{2} \mathcal{H}^1([\xi, \xi'] \setminus B_R)^2, \end{aligned}$$

which settles the first case.

In the second case, in addition to (A.4), we also use the fact that for every $\zeta_2 \in \partial F(\xi_2)$,

$$F(\xi_1) \geq F(\xi_2) + \langle \zeta_2, \xi_1 - \xi_2 \rangle,$$

and for every $\zeta' \in \partial F(\xi')$

$$F(\xi_2) \geq F(\xi') + \langle \zeta', \xi_2 - \xi' \rangle + \frac{\mu}{2} |\xi_2 - \xi'|^2,$$

again by (3.1) with $\Phi \equiv \mu$. By using as in the first case that $\langle \zeta_1 - \zeta', \xi - \xi_1 \rangle \geq 0$ and $\langle \zeta_2 - \zeta', \xi_1 - \xi_2 \rangle \geq 0$, we thus obtain

$$\begin{aligned} F(\xi) &\geq F(\xi') + \langle \zeta', \xi - \xi' \rangle + \frac{\mu}{2} (|\xi - \xi_1|^2 + |\xi' - \xi_2|^2) \\ &\geq F(\xi') + \langle \zeta', \xi - \xi' \rangle + \frac{\mu}{4} \mathcal{H}^1([\xi, \xi'] \setminus B_R)^2. \end{aligned}$$

This completes the proof of (A.3). \square

Thanks to the previous result, we can detail some consequences of the uniform convexity that we used in the proof of the Main Theorem.

Lemma A.3. *Let F be a convex function which is μ -uniformly convex outside $B_R \subset \mathbb{R}^N$. Then we have:*

i) for every $\xi, \xi' \in \mathbb{R}^N$, and every $\zeta \in \partial F(\xi)$, if $|\xi| \geq 2R$ or $|\xi'| \geq 2R$, then there holds

$$(A.6) \quad F(\xi') \geq F(\xi) + \langle \zeta, \xi' - \xi \rangle + \frac{\mu}{36} |\xi' - \xi|^2;$$

ii) for every $\xi, \xi' \in \mathbb{R}^N$, and every $\zeta \in \partial F(\xi), \zeta' \in \partial F(\xi')$, if $|\xi| \geq 2R$ or $|\xi'| \geq 2R$ we have

$$(A.7) \quad \langle \zeta - \zeta', \xi - \xi' \rangle \geq \frac{\mu}{18} |\xi - \xi'|^2;$$

iii) for every $\xi, \xi' \in \mathbb{R}^N \setminus B_{2R}$ and for every $\theta \in [0, 1]$,

$$(A.8) \quad F(\theta \xi + (1 - \theta) \xi') \leq \theta F(\xi) + (1 - \theta) F(\xi') - \frac{\mu}{36} \theta(1 - \theta) |\xi - \xi'|^2;$$

iv) for every $\xi \in \mathbb{R}^N$, if $|\xi| \geq 2R$, then

$$(A.9) \quad F(\xi) \geq \frac{\mu}{72} |\xi|^2 - \left(|F(0)| + \frac{18}{\mu} |\partial^\circ F(0)|^2 \right),$$

where $\partial^\circ F(0)$ denotes the element of $\partial F(0)$ having minimal Euclidean norm.

Proof. We claim that for every $\xi \in \mathbb{R}^N$ and every $\xi' \in \mathbb{R}^N \setminus B_{2R}$,

$$(A.10) \quad \mathcal{H}^1([\xi, \xi'] \setminus B_R) \geq \frac{1}{3} |\xi - \xi'|.$$

Let us fix $\xi' \in \mathbb{R}^N \setminus B_{2R}$ and let $\xi \in \mathbb{R}^N$. We set $r = |\xi' - \xi| > 0$. Then we see that among all ξ such that $|\xi - \xi'| = r$, the length of the set $[\xi, \xi'] \setminus B_R$ is minimal for the vector

$$\xi'' := t \xi', \quad \text{with } t < 1 \text{ such that } (1 - t) = \frac{r}{|\xi'|}.$$

Then we have

$$\mathcal{H}^1([\xi', \xi''] \setminus B_R) = \begin{cases} r, & \text{if } r \leq |\xi'| - R, \\ |\xi'| - R & \text{if } |\xi'| - R < r < |\xi'| + R, \\ r - 2R, & \text{if } |\xi'| + R \leq r. \end{cases}$$

Observe that

$$\frac{|\xi'|}{2} \leq |\xi'| - R,$$

thus for $|\xi'| - R < r < |\xi'| + R$ we have

$$r < 3 \frac{|\xi'|}{2} \leq 3(|\xi'| - R) = 3 \mathcal{H}^1([\xi', \xi''] \setminus B_R).$$

Similarly, for $|\xi'| + R \leq r$, we have

$$\mathcal{H}^1([\xi', \xi''] \setminus B_R) = r - 2R = \frac{r}{3} + \left(\frac{2}{3}r - 2R\right) \geq \frac{r}{3} + \left(\frac{2}{3}|\xi'| - \frac{4}{3}R\right) \geq \frac{r}{3}.$$

By recalling that $r = |\xi - \xi'|$, the claim (A.10) follows. The inequality (A.6) can now be easily deduced from (A.3) and (A.10).

Inequality (A.7) can be easily obtained from (A.6). Indeed, by exchanging the role of ξ and ξ' in (A.6) we get

$$F(\xi') - F(\xi) \geq \langle \zeta, \xi' - \xi \rangle + \frac{\mu}{36} |\xi - \xi'|^2,$$

and

$$F(\xi) - F(\xi') \geq \langle \zeta', \xi - \xi' \rangle + \frac{\mu}{36} |\xi - \xi'|^2.$$

By combining these two inequalities we get (A.7).

Let us take $\xi, \xi' \in \mathbb{R}^N \setminus B_{2R}$. For every $\theta \in [0, 1]$ and every $\zeta \in \partial F(\theta \xi + (1 - \theta) \xi')$ by (A.6) we get

$$F(\xi) \geq F(\theta \xi + (1 - \theta) \xi') + (1 - \theta) \langle \zeta, \xi - \xi' \rangle + \frac{\mu}{36} (1 - \theta)^2 |\xi' - \xi|^2,$$

and

$$F(\xi') \geq F(\theta \xi + (1 - \theta) \xi') + \theta \langle \zeta, \xi' - \xi \rangle + \frac{\mu}{36} \theta^2 |\xi' - \xi|^2.$$

Then (A.8) can be obtained by multiplying the first inequality by θ , the second one by $(1 - \theta)$ and then summing up.

Finally, we use (A.6) with $\xi' \in \mathbb{R}^N \setminus B_{2R}$, $\xi = 0$ and $\zeta = \partial^\circ F(0)$ as in the statement, then we obtain

$$F(\xi') \geq F(0) + \langle \zeta, \xi' \rangle + \frac{\mu}{36} |\xi'|^2 \geq \frac{\mu}{72} |\xi'|^2 - \left(|F(0)| + \frac{18}{\mu} |\zeta|^2 \right).$$

where we used Young inequality in the last passage. This proves (A.9). \square

A.2. Approximation issues. This section is devoted to prove some approximation results we used in the proof of the Main Theorem.

Lemma A.4. *Let $F : \mathbb{R}^N \rightarrow \mathbb{R}$ be a convex function, which is μ -uniformly convex outside the ball B_R for some $\mu > 0$ and $R > 0$. Then there exists a nondecreasing sequence $\{F_k\}_{k \in \mathbb{N}}$ of smooth convex functions which converges to F uniformly on bounded sets. Moreover, F_k is $(\mu/36)$ -uniformly convex outside B_{R+1} .*

Proof. Let us set for simplicity $\mu' = \mu/36$. For every $k \in \mathbb{N}$, we define at first

$$\tilde{F}_k(x) := \sup_{\substack{|y| \leq k \\ \zeta \in \partial F(y)}} \left[F(y) + \langle \zeta, x - y \rangle + \frac{\mu'}{2} |x - y|^2 1_{\mathbb{R}^N \setminus B_{2R}}(y) \right], \quad x \in \mathbb{R}^N.$$

Of course, this is a nondecreasing sequence of convex functions. If $k \leq 2R$, then by convexity of F for every $|y| \leq k$, every $\zeta \in \partial F(y)$ and every $x \in \mathbb{R}^N$ we get

$$(A.11) \quad F(y) + \langle \zeta, x - y \rangle + \frac{\mu'}{2} |x - y|^2 1_{\mathbb{R}^N \setminus B_{2R}}(y) \leq F(x).$$

If $k > 2R$ and $|y| \leq k$, we have two possibilities: either $|y| \leq 2R$ or $|y| > 2R$. In the first case we still have (A.11) for every $\zeta \in \partial F(y)$ and $x \in \mathbb{R}^N$, simply by convexity of F . In the second case,

we can appeal to inequality (A.6) of Lemma A.3: indeed, for every $x \in \mathbb{R}^N$ and every $\zeta \in \partial F(y)$, we have

$$F(x) \geq F(y) + \langle \zeta, x - y \rangle + \mu' |x - y|^2.$$

In any case, we obtain that for every $x \in \mathbb{R}^N$

$$\tilde{F}_k(x) \leq F(x),$$

and the equality holds when $x \in \overline{B}_k$. In particular, for every $k \geq R$ the function \tilde{F}_k is μ -uniformly convex on $\overline{B}_k \setminus B_R$.

When $k \geq 2R + 1$ and $|x| \geq 2R$, we claim that

$$(A.12) \quad \tilde{F}_k(x) = \sup_{\substack{2R \leq |y| \leq k \\ \zeta \in \partial F(y)}} \left[F(y) + \langle \zeta, x - y \rangle + \frac{\mu'}{2} |x - y|^2 \right].$$

This follows from the fact that for every $y_0 \in B_{2R}$ and $\zeta_0 \in \partial F(y_0)$, there exists $y \in \overline{B}_k \setminus B_{2R}$ and $\zeta \in \partial F(y)$ such that

$$(A.13) \quad F(y) + \langle \zeta, x - y \rangle \geq F(y_0) + \langle \zeta_0, x - y_0 \rangle.$$

Indeed, take any $y \in [y_0, x] \cap (\overline{B}_k \setminus B_{2R})$ and any $\zeta \in \partial F(y)$. Then, by convexity of F ,

$$F(y) \geq F(y_0) + \langle \zeta_0, y - y_0 \rangle.$$

Hence, by using this and the fact that $y - x = t(y_0 - y)$ for some $t \geq 0$, we can infer

$$\begin{aligned} F(y) + \langle \zeta, x - y \rangle &\geq F(y_0) + \langle \zeta_0, y - y_0 \rangle + \langle \zeta, x - y \rangle \\ &= F(y_0) + \langle \zeta_0, x - y_0 \rangle + \langle \zeta_0 - \zeta, y - x \rangle \\ &= F(y_0) + \langle \zeta_0, x - y_0 \rangle + t \langle \zeta_0 - \zeta, y_0 - y \rangle \\ &\geq F(y_0) + \langle \zeta_0, x - y_0 \rangle. \end{aligned}$$

In the last line, we have used the monotonicity of the subdifferential. This proves (A.13) and thus (A.12).

It follows that \tilde{F}_k is μ' -uniformly convex on $\mathbb{R}^N \setminus B_{2R}$ as the supremum of μ' -uniformly convex functions on $\mathbb{R}^N \setminus B_{2R}$. Since $\mu' < \mu$, on the whole we get that \tilde{F}_k is μ' -uniformly convex on $\mathbb{R}^N \setminus B_R$.

In the remaining part of the proof, we fix some $k \geq 2R + 1$. We claim that for every $x \in \mathbb{R}^N$,

$$(A.14) \quad \tilde{F}_{k+1}(x) \geq \tilde{F}_k(x) + \mu' (|x| - k - 1)_+.$$

If $|x| \leq k + 1$ this is immediate (recall that \tilde{F}_k is nondecreasing), thus let us assume that $|x| > k + 1$. Let $y_0 \in \overline{B}_k \setminus B_{2R}$ and $\zeta_0 \in \partial F(y_0)$ achieving the supremum in the definition of \tilde{F}_k , i.e.

$$(A.15) \quad \tilde{F}_k(x) = F(y_0) + \langle \zeta_0, x - y_0 \rangle + \frac{\mu'}{2} |x - y_0|^2.$$

Let $y \in \partial B_{k+1} \cap [x, y_0]$ and observe that $[y, x] \cap B_R = \emptyset$. By the equivalent definition (A.12) of \tilde{F}_{k+1} , we get for every $\zeta \in \partial F(y)$

$$\tilde{F}_{k+1}(x) \geq F(y) + \langle \zeta, x - y \rangle + \frac{\mu'}{2} |x - y|^2,$$

while by (A.6) of Lemma A.3

$$F(y) \geq F(y_0) + \langle \zeta_0, y - y_0 \rangle + \mu' |y - y_0|^2.$$

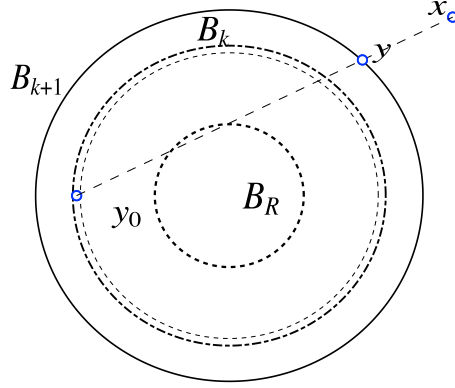


FIGURE 3. The construction for the proof of (A.14).

Combining these two inequalities, we get

$$(A.16) \quad \tilde{F}_{k+1}(x) \geq F(y_0) + \langle \zeta_0, x - y_0 \rangle + \frac{\mu'}{2} |x - y_0|^2 + A,$$

where

$$(A.17) \quad A = \langle \zeta_0 - \zeta, y - x \rangle + \frac{\mu'}{2} |x - y|^2 + \mu' |y - y_0|^2 - \frac{\mu'}{2} |x - y_0|^2.$$

If we now use (A.7), we obtain

$$\langle \zeta_0 - \zeta, y_0 - y \rangle \geq 2\mu' |y_0 - y|^2.$$

Since $y - x = (y_0 - y) |y - x| / |y_0 - y|$, this implies

$$\langle \zeta_0 - \zeta, y - x \rangle \geq 2\mu' |y_0 - y| |y - x|.$$

By inserting this into (A.17) and observing that $|x - y_0| = |x - y| + |y - y_0|$, we obtain

$$A \geq \mu' |y_0 - y| |y - x| + \frac{\mu'}{2} |y - y_0|^2.$$

In view of (A.16), (A.15) and also using the fact that

$$|y_0 - y| \geq 1 \quad \text{and} \quad |y - x| \geq |x| - |y| \geq |x| - (k + 1),$$

this finally implies

$$\tilde{F}_{k+1}(x) \geq \tilde{F}_k(x) + \mu' (|x| - k - 1),$$

and (A.14) is proved.

We now establish the following Lipschitz-type estimate for \tilde{F}_k : for every $x, x' \in \mathbb{R}^N$,

$$(A.18) \quad \left| \tilde{F}_k(x) - \tilde{F}_k(x') \right| \leq \left(L_k + \frac{\mu'}{2} (|x| + |x'| + 2k) \right) |x - x'|,$$

where L_k is the Lipschitz constant of F on B_k . Indeed, for every $y \in \overline{B_k}$ and every $\zeta \in \partial F(y)$, we have⁷

$$\begin{aligned} F(y) + \langle \zeta, x - y \rangle + \frac{\mu'}{2} |x - y|^2 \mathbf{1}_{\mathbb{R}^N \setminus B_{2R}}(y) &\leq F(y) + \langle \zeta, x' - y \rangle + \frac{\mu'}{2} |x' - y|^2 \mathbf{1}_{\mathbb{R}^N \setminus B_{2R}}(y) \\ &\quad + |\zeta| |x - x'| + \frac{\mu'}{2} |x - x'| (|x| + |x'| + 2|y|) \\ &\leq \tilde{F}_k(x') + \left(L_k + \frac{\mu'}{2} (|x| + |x'| + 2k) \right) |x - x'|. \end{aligned}$$

By exchanging the role of x and x' we get (A.18).

Let us introduce a family $\{\rho_\varepsilon\}_{\varepsilon>0} \subset C_0^\infty(B_\varepsilon)$ of standard smooth mollifiers. For some sequence $\{\varepsilon_k\}_{k \in \mathbb{N}} \subset (0, 1/2)$ to be specified later, let us consider

$$F_k(x) := \tilde{F}_k * \rho_{\varepsilon_k} - \frac{1}{k}.$$

By Lemma A.1, every F_k is a smooth μ' -uniformly convex function outside B_{R+1} and the sequence $\{F_k\}_{k \in \mathbb{N}}$ uniformly converges on bounded sets to F . It remains to prove that $\{F_k\}_{k \in \mathbb{N}}$ is nondecreasing. By (A.18), for every $x \in \mathbb{R}^N$,

$$F_k(x) \leq \tilde{F}_k(x) + \left(L_k + \frac{\mu'}{2} (2|x| + \varepsilon_k + 2k) \right) \varepsilon_k - \frac{1}{k}.$$

Moreover, by (A.14) we have

$$\tilde{F}_k(x) \leq \tilde{F}_{k+1}(x) - \mu' (|x| - k - 1)_+.$$

Since \tilde{F}_{k+1} is convex, by Jensen inequality we also have

$$\tilde{F}_{k+1}(x) \leq \tilde{F}_{k+1} * \rho_{\varepsilon_{k+1}}(x) = F_{k+1}(x) + \frac{1}{k+1}.$$

Hence in order to have $F_k(x) \leq F_{k+1}(x)$ it is sufficient that for every $x \in \mathbb{R}^N$

$$(A.19) \quad \left(L_k + \frac{\mu'}{2} (2|x| + \varepsilon_k + 2k) \right) \varepsilon_k \leq \mu' (|x| - k - 1)_+ + \frac{1}{k} - \frac{1}{k+1}.$$

When $|x| \leq 2(k+1)$, by recalling that $\varepsilon_k < 1/2$ we have

$$\left(L_k + \frac{\mu'}{2} (2|x| + \varepsilon_k + 2k) \right) \leq \left(L_k + \frac{\mu'}{2} (6k + 5) \right),$$

while for the right-hand side of (A.19)

$$\mu' (|x| - k - 1)_+ + \frac{1}{k} - \frac{1}{k+1} \geq \frac{1}{k(k+1)}.$$

⁷We use the following elementary manipulations

$$|x - y|^2 = |x' - y|^2 + (|x|^2 - |x'|^2) + 2 \langle x' - x, y \rangle,$$

and

$$\begin{aligned} (|x|^2 - |x'|^2) + 2 \langle x' - x, y \rangle &\leq (|x| - |x'|) (|x| + |x'|) + 2|x - x'| |y| \\ &\leq |x - x'| (|x| + |x'| + 2|y|). \end{aligned}$$

Hence in this case (A.19) holds true provided

$$(A.20) \quad \varepsilon_k \leq \Gamma_k^- := \frac{1}{k(k+1)} \frac{1}{L_k + (6k+5)\mu'/2}.$$

When $|x| > 2(k+1)$, the coefficient in front of ε_k on the left-hand side of (A.19) can be estimated by

$$\left(L_k + \frac{\mu'}{2}(2|x| + \varepsilon_k + 2k) \right) \leq \mu'|x| + (L_k + \mu'(k+1))$$

while for the right-hand side we have

$$\mu'(|x| - k - 1)_+ + \frac{1}{k} - \frac{1}{k+1} \geq \frac{\mu'}{2}|x| + \frac{1}{k(k+1)}.$$

In that case, by recalling that $\varepsilon_k < 1/2$ we only need to take

$$(A.21) \quad \varepsilon_k \leq \Gamma_k^+ := \frac{1}{k(k+1)} \frac{1}{L_k + \mu'(k+1)}.$$

Observe that both $\{\Gamma_k^+\}_{k \in \mathbb{N}}$ and $\{\Gamma_k^-\}_{k \in \mathbb{N}}$ monotonically converge to 0 as k goes to ∞ . Hence, by choosing any decreasing sequence $\{\varepsilon_k\}_{k \in \mathbb{N}}$ such that

$$0 < \varepsilon_k < \min \left\{ \frac{1}{2}, \Gamma_k^-, \Gamma_k^+ \right\}, \quad k \in \mathbb{N},$$

this satisfies both (A.20) and (A.21) and thus (A.19) is guaranteed. In conclusion, up to relabeling the sequence, $\{F_k\}_{k \in \mathbb{N}}$ satisfies all the required properties. \square

Lemma A.5. *Let $F : \mathbb{R}^N \rightarrow \mathbb{R}$ be a convex function, which is Φ -uniformly convex outside the ball B_R for some $R > 0$. Then for every $Q > R$ there exists a convex function $F_Q : \mathbb{R}^N \rightarrow \mathbb{R}$ with the following properties:*

i) $F_Q \equiv F$ in B_Q ;

ii) F is μ_Q -uniformly convex outside the ball B_R , with⁸

$$\mu_Q = \min \left\{ 1, \min_{t \in [2R, 4Q]} \Phi(t) \right\}.$$

Proof. For every $Q > R$, we define the function $F_Q : \mathbb{R}^N \rightarrow \mathbb{R}$ by

$$F_Q(x) = F(x) + \mu_Q J_Q(x), \quad \text{where } J_Q(x) := (|x| - Q)_+^2.$$

Of course, this is a convex function such that $F_Q \equiv F$ in B_Q .

In order to verify property ii), we first observe that $\mu_Q J_Q$ is μ_Q -uniformly convex outside B_{2Q} (see Lemma A.6 below). We consider again a sequence $\{\rho_\varepsilon\}_{\varepsilon > 0} \subset C_0^\infty(B_\varepsilon)$ of standard mollifiers. Then for every $\eta \in \mathbb{R}^N$ and every $\xi \in \mathbb{R}^N \setminus B_{R+\varepsilon}$, we have

$$\langle D^2(F_Q * \rho_\varepsilon)(\xi) \eta, \eta \rangle = \langle D^2(F * \rho_\varepsilon)(\xi) \eta, \eta \rangle + \mu_Q \langle D^2(J_Q * \rho_\varepsilon)(\xi) \eta, \eta \rangle.$$

Since F is Φ -uniformly convex outside B_R , the first part of Lemma A.1 implies that when $\xi \in B_{2Q+\varepsilon} \setminus B_{R+\varepsilon}$,

$$\langle D^2(F * \rho_\varepsilon)(\xi) \eta, \eta \rangle \geq \left(\min_{t \in [2R, 4(Q+\varepsilon)]} \Phi(t) \right) |\eta|^2.$$

⁸Observe that $\mu_Q > 0$ thanks to fact that Φ is continuous and $\Phi(t) > 0$ for $t > 0$.

Since $\mu_Q J_Q$ is μ_Q -uniformly convex outside B_{2Q} , we get similarly when $\xi \in \mathbb{R}^N \setminus B_{2Q+\varepsilon}$,

$$\mu_Q \langle D^2(J_Q * \rho_\varepsilon)(\xi) \eta, \eta \rangle \geq \mu_Q |\eta|^2.$$

In any case, we thus have for every $\xi \in \mathbb{R}^N \setminus B_{R+\varepsilon}$

$$\langle D^2(F_Q * \rho_\varepsilon)(\xi) \eta, \eta \rangle \geq \left(\min(\mu_Q, \min_{t \in [2R, 4(Q+\varepsilon)]} \Phi(t)) \right) |\eta|^2.$$

By the second part of Lemma A.1, this proves that F_Q is μ_Q -uniformly convex outside B_R . \square

Lemma A.6 (A useful function). *The function*

$$J_Q(x) = (|x| - Q)_+^2,$$

is 1-uniformly convex outside the ball B_{2Q} .

Proof. We first observe that J_Q is C^2 outside B_Q . Thus it is sufficient to compute the Hessian of J_Q in $\mathbb{R}^N \setminus B_{2Q}$. Let $x \in \mathbb{R}^N \setminus B_{2Q}$, we have

$$D^2 J_Q(x) = 2 \frac{|x| - Q}{|x|} \text{Id}_N + 2 \frac{x \otimes x}{|x|^2} - 2(|x| - Q) \frac{x \otimes x}{|x|^3}.$$

For every $\eta \in \mathbb{R}^N$ we get

$$\langle D^2 J_Q(x) \eta, \eta \rangle = 2 \frac{|x| - Q}{|x|} |\eta|^2 + 2 \left[1 - \frac{|x| - Q}{|x|} \right] \left(\frac{\langle x, \eta \rangle}{|x|} \right)^2 \geq 2 \left(1 - \frac{Q}{|x|} \right) |\eta|^2,$$

and thus the conclusion follows, by using that $|x| \geq 2Q$. \square

REFERENCES

- [1] J. J. Alibert, G. Bouchitté, I. Fragalà, I. Lucardesi, A nonstandard free boundary problem arising in the shape optimization of thin torsion rods, *Interfaces Free Bound.*, **15** (2013), 95–119. [2](#)
- [2] P. Bousquet, Continuity of solutions of a problem in the calculus of variations, *Calc. Var. Partial Differential Equations*, **41** (2011), 413–433. [2](#)
- [3] P. Bousquet, L. Brasco, V. Julin, Lipschitz regularity for local minimizers of some widely degenerate problems, to appear on *Ann. Sc. Norm. Super. Pisa Cl. Sci.* (2015), available at <http://cvgmt.sns.it/paper/2515/> [4](#)
- [4] P. Bousquet, C. Mariconda, G. Treu, On the Lavrentiev phenomenon for multiple integral scalar variational problems, *J. Funct. Anal.*, **226** (2014), 5921–5954. [23](#)
- [5] P. Bousquet, C. Mariconda, G. Treu, Hölder continuity of solutions to a basic problem in the Calculus of Variations, *C. R. Math. Acad. Sci. Paris*, **346** (2008), 1301–1305. [2](#)
- [6] L. Brasco, Global L^∞ gradient estimates for solutions to a certain degenerate elliptic equation, *Nonlinear Anal.*, **72** (2011), 516–531. [5](#), [6](#)
- [7] C. Carstensen, S. Muller, Local stress regularity in scalar nonconvex variational problems, *SIAM J. Math. Anal.*, **34** (2002), 495–509. [5](#)
- [8] F. Clarke, Continuity of solutions to a basic problem in the calculus of variations, *Ann. Sc. Norm. Super. Pisa Cl. Sci.*, **4** (2005), 511–530. [2](#), [26](#), [27](#)
- [9] A. Cellina, Comparison results and estimates on the gradient without strict convexity, *SIAM J. Control Optim.*, **46** (2007), 738–749. [2](#)
- [10] M. Chipot, L. C. Evans, Linearization at infinity and Lipschitz estimates for certain problems in the calculus of variations, *Proc. R. Soc. Edinb. Sect. A*, **102** (1986), 291–303. [5](#)
- [11] M. Colombo, G. Mingione, Regularity for Double Phase Variational Problems, *Arch. Rational Mech. Anal.*, **215** (2015), 443–496. [6](#)
- [12] M. Colombo, A. Figalli, Regularity results for very degenerate elliptic equations, *J. Math. Pures Appl.*, **101** (2014), 94–117. [5](#)

- [13] G. Cupini, M. Guidorzi, E. Mascolo, Regularity of minimizers of vectorial integrals with $p-q$ growth, *Nonlinear Anal.*, **54** (2003), 591–616. [6](#)
- [14] L. Diening, B. Stroffolini, A. Verde, Lipschitz regularity for some asymptotically convex problems, *ESAIM Control Optim. Calc. Var.*, **17** (2011), 178–189. [5](#)
- [15] G. Dolzmann, J. Kristensen, Higher integrability of minimizing Young measures, *Calc. Var. Partial Differential Equations*, **22** (2005), 283–301. [5](#)
- [16] L. Esposito, F. Leonetti, G. Mingione, Sharp regularity for functionals with (p, q) growth, *J. Diff. Eq.*, **204** (2004), 5–55. [6](#)
- [17] L. Esposito, G. Mingione, C. Trombetti, On the Lipschitz regularity for certain elliptic problems, *Forum Math.* **18** (2006), 263–292. [5](#)
- [18] A. Fiaschi, G. Treu, The Bounded Slope Condition for Functionals Depending on x , u , and ∇u , *SIAM J. Control Optim.*, **50** (2012), 991–1011. [3](#)
- [19] I. Fonseca, N. Fusco, P. Marcellini, An existence result for a nonconvex variational problem via regularity, *ESAIM Control Optim. Calc. Var.* **7** (2002), 69–95. [5](#), [6](#)
- [20] M. Giaquinta, Growth conditions and regularity, a counterexample, *Manuscripta Math.*, **59** (1987), 245–248. [6](#)
- [21] M. Giaquinta, G. Modica, Remarks on the regularity of the minimizers of certain degenerate functionals, *Manuscripta Math.*, **57** (1986), 55–99. [5](#)
- [22] D. Gilbarg, N. Trudinger, *Elliptic partial differential equations of second order*. Reprint of the 1998 edition. *Classics in Mathematics*. Springer-Verlag, Berlin, 2001. [12](#)
- [23] E. Giusti, *Metodi diretti nel calcolo delle variazioni*. (Italian) [Direct methods in the calculus of variations], *Unione Matematica Italiana*, Bologna, 1994. [3](#), [6](#)
- [24] A. Haar, Über das Plateausche Problem, *Math. Ann.*, **97** (1927), 124–258. [6](#)
- [25] P. Hartman, Convex sets and the bounded slope condition, *Pacific J. Math.*, **25** (1968), 511–522. [4](#)
- [26] P. Hartman, On the bounded slope condition, *Pacific J. Math.*, **18** (1966), 495–511. [4](#), [6](#)
- [27] P. Hartman, L. Nirenberg, On spherical image maps whose Jacobians do not change sign, *Amer. J. Math.*, **81** (1959), 901–920. [6](#)
- [28] P. Hartman, G. Stampacchia, On some non-linear elliptic differential-functional equations, *Acta Math.*, **115** (1966), 271–310. [3](#)
- [29] Hong Min-Chun, Some remarks on the minimizers of variational integrals with non standard growth conditions, *Boll. Un. Mat. Ital. A*, **6** (1992), 91–101. [6](#)
- [30] C. Leone, A. Passarelli di Napoli, A. Verde, Lipschitz regularity for some asymptotically subquadratic problems, *Nonlinear Anal.*, **67** (2007), 1532–1539. [5](#)
- [31] P. Marcellini, Regularity of minimizers of integrals of the Calculus of Variations under non standard growth conditions, *Arch. Rational Mech. Anal.*, **105** (1989), 267–284. [6](#)
- [32] P. Marcellini, Un exemple de solution discontinue d’un problème variationnel dans le cas scalaire, preprint n. 11 dell’Ist. Mat. Univ. Firenze (1987). Available at <http://web.math.unifi.it/users/marcell/lavori> [6](#)
- [33] C. Mariconda, G. Treu, Local Lipschitz regularity of Minima for a scalar problem of the Calculus of Variations, *Commun. Contemp. Math.* **10** (2008), 1129–1149. [2](#)
- [34] M. Miranda, Un teorema di esistenza e unicità per il problema dell’area minima in n variabili, *Ann. Scuola Norm. Sup. Pisa*, **19** (1965), 233–249. [3](#), [6](#)
- [35] C. B. Morrey, *Multiple integrals in the Calculus of Variations*. Die Grundlehren der mathematischen Wissenschaften, **130**. Springer-Verlag New York, Inc., New York 1966. [14](#)
- [36] J. von Neumann, Über einen Hilfssatz der Variationsrechnung, *Abhandlungen aus dem Mathematischen Seminar der Hamburgischen Universität*, **8** (1931), 28–31. [6](#)
- [37] T. Radó, The problem of the least area and the problem of Plateau, *Math. Z.*, **32** (1930), 763–796. [6](#)
- [38] J. P. Raymond, Lipschitz regularity of solutions of some asymptotically convex problems, *Proc. Roy. Soc. Edinburgh Sect. A*, **117** (1991), 59–73. [5](#)
- [39] F. Santambrogio, V. Vespi, Continuity in two dimensions for a very degenerate elliptic equation, *Nonlinear Anal.*, **73** (2010), 3832–3841. [5](#)
- [40] G. Stampacchia, On some regular multiple integral problems in the calculus of variations, *Comm. Pure Appl. Math.*, **16** (1963), 383–421. [3](#), [4](#), [5](#), [11](#)

INSTITUT DE MATHÉMATIQUES DE TOULOUSE, CNRS UMR 5219, UNIVERSITÉ DE TOULOUSE, F-31062 TOULOUSE
CEDEX 9, FRANCE.

E-mail address: pierre.bousquet@math.univ-toulouse.fr

AIX-MARSEILLE UNIVERSITÉ, CNRS, CENTRALE MARSEILLE, I2M, UMR 7373, 13453 MARSEILLE, FRANCE

E-mail address: lorenzo.brasco@univ-amu.fr