REGULARITY AND BERNSTEIN-TYPE RESULTS FOR NONLOCAL MINIMAL SURFACES

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ABSTRACT. We prove that, in every dimension, Lipschitz nonlocal minimal surfaces are smooth. Also, we extend to the nonlocal setting a famous theorem of De Giorgi [6] stating that the validity of Bernstein's theorem in dimension n+1 is a consequence of the nonexistence of n-dimensional singular minimal cones in \mathbb{R}^n .

1. Introduction

Given $n \ge 1$ and $s \in (0,1)$, we investigate the regularity of nonlocal s-minimal surfaces in \mathbb{R}^{n+1} . To begin, we recall the notion of s-perimeter and s-minimal surface, as introduced in [3].

Given two disjoint measurable sets $F, G \subseteq \mathbb{R}^{n+1}$ we consider the s-interaction between them defined by

$$L(F,G) := \iint_{F \times G} \frac{dX \, dY}{|X - Y|^{n+1+s}}.$$

Given a measurable set E and a bounded set $\Omega \subset \mathbb{R}^{n+1}$, the "s-perimeter" of the set E inside Ω is defined as

$$\operatorname{Per}_{s}(E,\Omega) := L(E \cap \Omega, \mathbb{R}^{n+1} \setminus E) + L(E \setminus \Omega, \Omega \setminus E).$$

We say that E is a "s-minimal surface" in Ω if $\operatorname{Per}_s(E,\Omega)<+\infty$ and for any measurable set $F\subseteq \mathbb{R}^{n+1}$ with $F\setminus\Omega=E\setminus\Omega$ we have that

$$\operatorname{Per}_s(E,\Omega) \leqslant \operatorname{Per}_s(F,\Omega).$$

If E is a s-minimal surface in any ball, we simply say that E is a s-minimal surface. Namely, s-minimal surfaces are local minimizers of the s-perimeter functional. The "s-mean curvature" of E at a point $X \in \partial E$ is defined by

(1.1)
$$I[E](X) := \int_{\mathbb{R}^{n+1}} \frac{\chi_E(Y) - \chi_{E^c}(Y)}{|X - Y|^{n+1+s}} \, dY,$$

where $E^c := \mathbb{R}^{n+1} \setminus E$. We remark that if ∂E is C^2 in a neighborhood of X, then I[E](X) is well-defined in the principal value sense. On the other hand, while a priori a s-minimal surface E may not be smooth, it is shown in [3] that it satisfies the equation I[E](X) = 0 for any $X \in \partial E$ in a suitable viscosity sense (in particular, it satisfies the equation in the classical sense at every point where ∂E is C^2).

With this notation, s-minimal surfaces have vanishing s-mean curvature, and the analogy with the classical perimeter case is evident. To make the analogy even stronger we recall that, as $s \nearrow 1$, the s-perimeter converges to the classical perimeter, with good geometric and functional analytic properties, see [1,4].

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From the results in [2,3,8] it is known that boundaries of s-minimal surfaces are C^{∞} with the possible exception of a closed singular set of Hausdorff dimension at most n-2.

The first result of this paper shows that Lipschitz s-minimal surfaces are smooth. Notice that, in the classical case, this result is a consequence of the De Giorgi-Nash Theorem on the Hölder regularity of solutions to uniformly elliptic equations in divergence form. However, in this nonlocal setting it does not seem possible to use the regularity theory for nonlocal equations to deduce this result and we need to employ geometric arguments instead.

Theorem 1.1. Let $n \ge 1$ and E be a s-minimal surface in $B_1 \subset \mathbb{R}^{n+1}$. Suppose that $\partial E \cap B_1$ is locally Lipschitz. Then $\partial E \cap B_1$ is C^{∞} .

We say that a s-minimal surface E is a "s-minimal graph" if it can be written as a global graph in some direction (that is, up to a rotation, $E = \{(x,\tau) \in \mathbb{R}^n \times \mathbb{R} : \tau < u(x)\}$ for some function $u : \mathbb{R}^n \to \mathbb{R}$), and it is a "s-minimal cone" if it is a cone (that is, up to a translation, E = tE for any t > 0). A variant of the techniques used in the proof of Theorem 1.1 allows us to show that the validity of Bernstein's theorem in dimension n + 1 is a consequence of the nonexistence of n-dimensional singular s-minimal cones in \mathbb{R}^n , thus extending to the fractional case a famous result of De Giorgi for minimal surfaces [6]:

Theorem 1.2. Let $E = \{(x, \tau) \in \mathbb{R}^n \times \mathbb{R} : \tau < u(x)\}$ be a s-minimal graph, and assume that there are no singular s-minimal cones in dimension n (that is, if $\mathscr{C} \subset \mathbb{R}^n$ is a s-minimal cone, then \mathscr{C} is a half-space). Then u is an affine function (thus E is a half-space).

The above result combined with the nonexistence of s-minimal cones in \mathbb{R}^n for $n \leq 2$ (see [8]) implies the following:

Corollary 1.3. Let $E = \{(x, \tau) \in \mathbb{R}^n \times \mathbb{R} : \tau < u(x)\}$ be a s-minimal graph, and assume that $n \in \{1, 2\}$. Then u is an affine function.

When n = 1 Corollary 1.3 is a particular case of the result in [8], but for n = 2 the result is new.

The paper is organized as follows. Some preliminary results on Lipschitz functions are collected in Section 2, and a useful observation on the asymptotic behavior of the s-minimal cones at large scale is given in Section 3. Then, the proofs of Theorems 1.1 and 1.2 are given in Sections 4 and 5, respectively.

2. Technical Lemmata on Lipschitz functions

This section contains some auxiliary results of elementary nature.

In the first lemma we show that Lipschitz functions whose gradient is almost constant in a suitably large set need to be uniformly close to an affine hyperplane:

Lemma 2.1. Let M > 0 and $\omega \in \mathbb{R}^n$ with $|\omega| \leq M$. Given $\varepsilon > 0$ there exists $\delta = \delta(n, \varepsilon, M) > 0$, such that the following holds: if $u : B_1 \to \mathbb{R}$ is a M-Lipschitz function satisfying

$$\left| \left\{ x \in B_1 : \left| \nabla u(x) - \omega \right| \geqslant \delta \right\} \right| \leqslant \delta,$$

then $|u(x) - u(0) - \omega \cdot x| \leq \varepsilon$ for any $x \in B_1$.

Proof. In this proof C will denote a generic constant depending only M, which may change from line to line. Set $w(x) := u(x) - \omega \cdot x$. It is immediate to check that w is (2M)-Lipschitz and from our assumptions on u we get

$$\int_{B_1} |\nabla w(x)| \, dx = \int_{B_1 \cap \{|\nabla w| < \delta\}} |\nabla w(x)| \, dx + \int_{B_1 \cap \{|\nabla w| \in [\delta, 2M]\}} |\nabla w(x)| \, dx \leqslant C\delta.$$

Hence, by Hölder inequality,

$$\|\nabla w\|_{L^{n+1}(B_1)} \leq \|\nabla w\|_{L^1(B_1)}^{1/(n+1)} \|\nabla w\|_{L^{\infty}(B_1)}^{n/(n+1)} \leq C\delta^{1/(n+1)},$$

and applying Sobolev inequality in $W^{1,n+1}(B_1)$ we deduce that there exists a constant $\ell \in \mathbb{R}$ such that

$$||w - \ell||_{L^{\infty}(B_1)} \le C||\nabla w||_{L^{n+1}(B_1)} \le C\delta^{1/(n+1)}.$$

Since

$$||w - w(0)||_{L^{\infty}(B_1)} \le ||w - \ell||_{L^{\infty}(B_1)} + |\ell - w(0)| \le 2||w - \ell||_{L^{\infty}(B_1)},$$

this concludes the proof with $\varepsilon = C\delta^{1/(n+1)}$.

In the next result we observe that if a Lipschitz function has local growth close to the maximal one at many points, then it needs to be uniformly close to an affine map:

Proposition 2.2. Let M > 0. Then, for any $\varepsilon > 0$ there exists $\mu = \mu(n, \varepsilon, M)$, with

$$0<\mu<\min\{1,M\},$$

such that the following holds: fix $\sigma \in \partial B_1$, and let $u : B_1 \to \mathbb{R}$ be a M-Lipschitz function satisfying

(2.2)
$$\left| \left\{ x \in B_1 : u(x + t_k \sigma) - u(x) \geqslant (M - \mu) t_k \right\} \right| \geqslant (1 - \mu) |B_1|$$

for some sequence $t_k \searrow 0$. Then $|u(x) - u(0) - M\sigma \cdot x| \leqslant \varepsilon$ for all $x \in B_1$.

Proof. Up to a rotation we can assume that $\sigma = e_1$. Set

$$(2.3) A_k := \left\{ x \in B_1 : u(x + t_k e_1) - u(x) \geqslant (M - \mu) t_k \right\}$$

and

$$A_{\star} := \bigcap_{k=0}^{+\infty} \bigcup_{j=k}^{+\infty} A_j.$$

Notice that $|A_k| \ge (1-\mu)|B_1|$ (thanks to (2.2)) and

$$\bigcap_{k=0}^{m} \bigcup_{j=k}^{+\infty} A_j \supseteq A_m.$$

Therefore, by monotone convergence,

(2.4)
$$|A_{\star}| = \lim_{m \nearrow \infty} \left| \bigcap_{k=0}^{m} \bigcup_{j=k}^{+\infty} A_{j} \right| \geqslant \lim_{m \nearrow \infty} |A_{m}| \geqslant (1-\mu) |B_{1}|.$$

Let $D \subset B_1$ denote the set of differentiability points of u (recall that D has full measure). We claim that

(2.5)
$$\sup_{x \in A_{\star} \cap D} |\nabla u(x) - Me_1| < \mu^{1/4}.$$

For this, we take $x \in A_{\star} \cap D$. By definition of A_{\star} there exists a subsequence $j_k \nearrow \infty$ such that $x \in A_{j_k}$, thus, by (2.3),

$$u(x+t_{i_k}e_1)-u(x)\geqslant (M-\mu)t_{i_k}$$
.

Dividing by $t_{j_k} > 0$ and letting $k \nearrow \infty$ we obtain (recall that $t_{j_k} \searrow 0$ as $k \nearrow \infty$)

$$(2.6) \partial_1 u(x) \geqslant (M - \mu).$$

As a consequence

$$M^2 \ge |\nabla u(x)|^2 \ge (M - \mu)^2 + \sum_{i=2}^n |\partial_i u(x)|^2,$$

which gives

$$\sum_{i=2}^{n} |\partial_i u(x)|^2 \leqslant 2M\mu.$$

Also (2.6) and the fact that $\partial_1 u(x) \leq M$ imply that

$$-\mu \leqslant \partial_1 u(x) - M \leqslant 0,$$

hence $|\partial_1 u(x) - M| \leq \mu$. We conclude that

$$|\nabla u(x) - Me_1|^2 = |\partial_1 u(x) - M|^2 + \sum_{i=2}^n |\partial_i u(x)|^2 \le \mu^2 + 2M\mu < \sqrt{\mu}$$

provided μ is sufficiently small, proving (2.5).

By (2.4) and (2.5) we deduce that

$$\left| \left\{ x \in B_1 : |\nabla u(x) - Me_1| \geqslant \mu^{1/4} \right\} \right| \leqslant |B_1 \setminus A_{\star}| \leqslant \mu |B_1| \leqslant \mu^{1/4}.$$

Hence, if μ is small enough, we can apply Lemma 2.1 with $\delta = \mu^{1/4}$ to obtain the desired result.

3. A REMARK ON FLAT BLOW-DOWNS

First of all, we recall here the notion of blow-up and blow-down of a s-minimal surface E, which will be used in the proofs of Theorems 1.1 and 1.2.

Assume that $0 \in \partial E$, define the family of sets $E_r := E/r$, and let E_0 (resp. E_{∞}) be a cluster point with respect to the L^1_{loc} -convergence for E_r as $r \searrow 0$ (resp. $r \nearrow \infty$).

With this notation, E_0 is called a "blow-up" of E (at 0), while E_{∞} is called a "blow-down". By [3, Theorem 9.2] we know that both E_0 and E_{∞} are s-minimal cones passing through the origin.

In the proof of Theorem 1.2 we will use the following observation:

Lemma 3.1. If E_{∞} is a half-space, then $E = E_{\infty}$.

Proof. Up to a rotation we can assume that

$$E_{\infty} = \{ (x, \tau) \in \mathbb{R}^n \times \mathbb{R} : \tau \leq 0 \}.$$

Let $r_k \nearrow \infty$ be a sequence such that $E_{r_k} \to E_{\infty}$, and let ε_0 be the universal flatness parameter in [3, Theorem 6.1]. By the uniform density estimates for s-minimal surfaces (see [3, Theorem 4.1]) we have that

$$\partial E_{r_k} \cap B_1 \to \partial E_{\infty} \cap B_1$$

in the Hausdorff distance¹ as $r_k \nearrow \infty$.

$$\min\{|E_{r_k} \cap B_{\rho}(X_k)|, |B_{\rho}(X_k) \setminus E_{r_k}|\} \geqslant c\rho^n \qquad \forall \rho \in (0, 1),$$

we deduce that

(3.7)
$$\min\{|E_{\infty} \cap B_{\rho}(X)|, |B_{\rho}(X) \setminus E_{\infty}|\} \geqslant c\rho^{n} \quad \forall \rho \in (0,1),$$

which implies that $X \in \partial E_{\infty}$.

¹The fact that density estimates improve the L^1 -convergence into Hausdorff convergence is a classical fact. For completeness, we sketch the argument. Let $X_k \in \partial E_{r_k} \cap B_1$, and consider X a cluster point. Taking the limit in the density estimate

Hence, for r_k sufficiently large we have that $E_{r_k} \cap B_1$ lies in a ε_0 -neighborhood of E_{∞} , and [3, Theorem 6.1] yields that $\partial E_{r_k} \cap B_{1/2}$ is a $C^{1,\alpha}$ -graph parameterized by a function $u_{r_k}: B_1 \to \mathbb{R}$, with $\|u_{r_k}\|_{C^{1,\alpha}(B_{1/2})} \leq C$ for some universal constants $\alpha \in (0,1)$ and C > 0 (to be precise, [3, Theorem 6.1] gives that $u_{r_k} \in C^{1,\alpha}(B_{1/2})$, and the fact that the $C^{1,\alpha}$ norm is universally bounded is pointed out for instance in [7, Corollary 3.5]).

Scaling back, we deduce that $\partial E \cap B_{r_k/2}$ coincides with the graph of a function u which satisfies $u(x) = r_k u_{r_k}(x/r_k)$ and u(0) = 0 (since $0 \in \partial E$). Hence

$$r_k^{\alpha}[\nabla u]_{C^{\alpha}(B_{r_k/2})} = [\nabla u_{r_k}]_{C^{\alpha}(B_{1/2})} \leqslant C,$$

and by letting $r_k \nearrow \infty$ we see that ∇u is constant. Thus u is a linear function, which implies that E is a half-space. Since $0 \in \partial E$ it is immediate to check that $E = E_r$ for all r > 0, therefore (by letting $r \nearrow \infty$) $E = E_\infty$ as desired.

4. Proof of Theorem 1.1

The idea of the proof is that, in some cases, nonlocal equations give a measure theoretic estimate on the separation of approximate solutions which in turn is helpful to control the pointwise fluctuations of the solution.

By [3, Theorem 6.1] and [2, Theorem 5], there exists $\varepsilon_0 > 0$ such that, if $B_r(X) \subset B_1$ and $\partial E \cap B_r(X)$ lies in a slab of height $2\varepsilon_0 r$, then $\partial E \cap B_{r/2}(X)$ is C^{∞} . Hence we only need to show that, for any $X \in B_1$, there exists a radius r < 1 - |X| such that $\partial E \cap B_r(X)$ lies in a slab of height $2\varepsilon_0 r$.

So, we fix $X_0 \in B_1$, we suppose (up to a change of coordinates) that ∂E is a Lipschitz graph in the e_{n+1} -direction in a neighborhood of X, and we assume by contradiction that, for any r > 0 small,

(4.8)
$$\partial E \cap B_r(X_0)$$
 is never trapped inside a slab of height $2\varepsilon_0 r$.

After translating the system of coordinate we can assume that $X_0 = 0$, and we consider a blow-up E_0 of E (recall the notion of blow-up introduced in Section 3). By [3, Theorem 9.2] we know that E_0 is a Lipschitz s-minimal cone passing through the origin.

We claim that

(4.9)
$$\partial E_0 \cap B_R$$
 is never trapped inside a slab of height $2\varepsilon_0 R$,

for any R > 0. Indeed, if by contradiction $\partial E_0 \cap B_R$ is trapped inside a slab of height $2\varepsilon_0 R$ then [3, Theorem 6.1] and [2, Theorem 5] imply that ∂E_0 is C^{∞} , hence (since E_0 is a cone)

$$\partial E_0$$
 is a hyperplane.

Then by the uniform density estimates for s-minimal surfaces (see [3, Theorem 4.1], or Footnote 1 here) we obtain that $\partial E_r \cap B_1$ lies in a ε_0 -neighborhood of ∂E_0 , and scaling back we obtain that $\partial E \cap B_r$ lies in a slab of height $2\varepsilon_0 r$. This is in contradiction with (4.8), and the proof of (4.9) is complete.

Now, up to a standard "dimension reduction argument" (see [3, Theorem 10.3]) we can "remove" all the singular points of ∂E_0 except the origin and we end up² with the following situation:

Viceversa, if $X \in \partial E_{\infty} \cap B_1$ then (3.7) and the L^1_{loc} -convergence of E_k to E_{∞} implies that, for any $\rho \in (0,1)$, $\partial E_{r_k} \cap B_{\rho}(X) \neq \emptyset$ for $k \gg 1$. Then, the arbitrariness of ρ yields the existence of a sequence $X_k \in \partial E_{r_k} \cap B_1$ converging to X.

²We notice that, since ∂E_0 is a Lipschitz graph, one can perform the dimension reduction argument without changing system of coordinates. Therefore, after a finite number of blow-ups, we still end up with a Lipschitz graph.

 E_0 is a Lipschitz cone passing through the origin,

(4.10)
$$\partial E_0 \cap B_1$$
 does not lie in a slab of height ε_0 ,

and ∂E_0 is a Lipschitz graph in the e_{n+1} -direction which is smooth outside the origin, that is

$$E_0 = \{ X = (x, \tau) \in \mathbb{R}^n \times \mathbb{R} : \tau < u(x) \},$$

(4.11)
$$u(0) = 0, \quad u \in C^2(\mathbb{R}^n \setminus \{0\}), \quad |\nabla u(x)| \leq M \text{ for any } x \neq 0.$$

To be precise, the dimension reduction argument in [3] gives that $u \in C^{1,\alpha}(\mathbb{R}^n \setminus \{0\})$, and by [2, Theorem 1] we obtain that $u \in C^{\infty}(\mathbb{R}^n \setminus \{0\})$. Of course we can take M > 0 to be the smallest possible (i.e., M is the optimal Lipschitz constant of u).

Take $\mu_0 := \mu(n, \varepsilon_0/2, M)$ as in Proposition 2.2. Then it follows from (4.10) that (2.2) cannot hold true. Hence, for any $\sigma \in \partial B_1$ there exists $t_{\sigma} > 0$ such that

(4.12)
$$\left| \left\{ x \in B_1 : u(x+t\sigma) - u(x) < (M-\mu_0) t \right\} \right| \geqslant \mu_0 |B_1|$$

for all $t \in (0, t_{\sigma})$. Now we take $w_0 \in C^{\infty}(\mathbb{R}, [0, 1])$, with $w_0(t) = 0$ for any $t \in (-\infty, 1/4] \cup [3/4, +\infty)$ and $w_0(t) = 1$ for any $t \in [2/5, 3/5]$. We set $w(x) = w_0(|x|)$ and observe that

(4.13)
$$w(x) = 1 \text{ for any } x \in B_{3/5} \setminus B_{2/5}.$$

Our goal is to show that there exists a constant $\vartheta > 0$ such that

$$(4.14) u(x+t\sigma) \leqslant u(x) + Mt - \vartheta t w(x) \forall x \in B_1, t \in (0, t_\sigma), \sigma \in \partial B_1.$$

Before proving (4.14) we observe that, once (4.14) is established, we easily reach a contradiction and complete the proof of Theorem 1.1. Indeed, letting $t \searrow 0$ in (4.14) and using (4.13) we deduce that

$$\nabla u(x) \cdot \sigma \leqslant M - \vartheta w(x) = M - \vartheta$$
 $\forall x \in B_{3/5} \setminus B_{2/5}, \ \sigma \in \partial B_1,$

hence

$$|\nabla u(x)| \leqslant M - \vartheta \qquad \forall x \in B_{3/5} \setminus B_{2/5}$$

by the arbitrariness of σ . Since ∇u is homogeneous of degree zero it follows that $|\nabla u(x)| \leq M - \vartheta$ for any $x \neq 0$, which contradicts our assumption that M was the optimal Lipschitz constant of u. So, it only remains to prove (4.14).

For this we consider the sets

$$F := \{(x,\tau) \in \mathbb{R}^n \times \mathbb{R} : \tau < u(x+t\sigma)\}$$
 and
$$G_{\vartheta,\alpha} := \{(x,\tau) \in \mathbb{R}^n \times \mathbb{R} : \tau < u(x) + (M-\vartheta w(x))t + \alpha\},$$

and notice that (4.14) is equivalent to

$$(4.15) F \subseteq G_{\vartheta,0}.$$

To prove (4.15) we first observe that

$$u(x+t\sigma) \leqslant u(x) + Mt \leqslant u(x) + (M-\vartheta w(x))t + Mt$$

provided $\vartheta \leq M$, thus $F \subseteq G_{\vartheta,\alpha}$ for any $\alpha > Mt$. Now we reduce α until we find a critical α_0 for which G_{ϑ,α_0} touches F from above. We claim that

$$(4.16) \alpha_0 \leqslant 0.$$

Suppose by contradiction that $\alpha_0 > 0$. Since u is M-Lipschitz we have that

$$u(x+t\sigma) \le u(x) + Mt < u(x) + Mt + \alpha_0.$$

which implies that G_{ϑ,α_0} and F can only touch at a some point $X_0 = (x_0,t_0) \in \mathbb{R}^n \times \mathbb{R}$ with $x_0 \in \operatorname{supp}(w) \subset B_{3/4} \setminus B_{1/4}$. Hence, it is easy to see (by compactness) that a contact point $X_0 = (x_0,t_0)$ exists, and since $x_0 \in B_{3/4} \setminus B_{1/4}$ we have that both sets are uniformly C^2 near X_0 ,

so the s-mean curvature operators I[F] and $I[G_{\vartheta,\alpha_0}]$ (recall (1.1)) may be computed at X_0 in the classical sense.

Since F and G_{0,α_0} are s-minimal surfaces, we have that

$$(4.17) I[F](X_0) = 0 = I[G_{0,\alpha_0}](X_0).$$

Also, since G_{ϑ,α_0} is a C^2 -diffeomorphism of G_{0,α_0} of size ϑt , and G_{ϑ,α_0} is uniformly C^2 in a neighborhood of X_0 , we have that

$$(4.18) |I[G_{\vartheta,\alpha_0}](X_0)| \leqslant C\vartheta t,$$

for some universal constant C > 0 (see also [5] for detailed computations on the effect of a small diffeomorphism on the fractional mean curvature). Furthermore, since $F \subseteq G_{\vartheta,\alpha_0}$ we have that

$$\chi_{G_{\vartheta,\alpha_0}} - \chi_{G_{\vartheta,\alpha_0}^c} - \chi_F + \chi_{F^c} = 2\chi_{G_{\vartheta,\alpha_0}\setminus F}.$$

Now we define

$$Z := \{x \in B_1 : u(x + t\sigma) - u(x) < (M - \mu_0) t\} \subset \mathbb{R}^n$$

and

$$W := \left\{ (x, \tau) \in \mathbb{R}^n \times \mathbb{R} : x \in Z \text{ and } u(x + t\sigma) < \tau < u(x + t\sigma) + \mu_0 t/2 \right\} \subset \mathbb{R}^{n+1}$$

We remark that $|Z| \ge \mu_0 |B_1|$ thanks to (4.12), therefore $|W| \ge \mu_0^2 t |B_1|/2$. (Notice that, by abuse of notation, we are using $|\cdot|$ to denote both the Lebesgue measure in \mathbb{R}^n and \mathbb{R}^{n+1} .)

We claim that

$$(4.20) (G_{\vartheta,\alpha_0} \setminus F) \supseteq W$$

provided ϑ is sufficiently small. Indeed, let $(x,\tau) \in W$. Then $x \in Z$ and $u(x+t\sigma) < \tau < u(x+t\sigma) + \mu_0 t/2$, which implies that $(x,\tau) \notin F$ and

$$\tau < u(x + t\sigma) + \frac{\mu_0 t}{2} < u(x) + (M - \mu_0)t + \frac{\mu_0 t}{2} \leqslant u(x) + Mt - \vartheta t \leqslant u(x) + Mt - \vartheta w(x)t$$

provided $\vartheta \in (0, \mu_0/4)$. This shows that $(x, \tau) \in G_{\vartheta,\alpha_0}$ proving (4.20).

Since by construction $Z \subseteq B_1 \subset \mathbb{R}^n$ and u is M-Lipschitz with u(0) = 0, we deduce that $W \subset B_1 \times [-1 - 2M, 1 + 2M]$, which implies that

$$\sup_{Y \in W} |X_0 - Y| \leqslant C_M$$

for some $C_M > 0$, and (by (4.20)) that

$$\left| (G_{\vartheta,\alpha_0} \setminus F) \cap W \right| = |W| \geqslant \frac{\mu_0^2 t |B_1|}{2}.$$

From this, (1.1), and (4.19), we conclude that

$$I[G_{\vartheta,\alpha_0}](X_0) - I[F](X_0) = \int_{\mathbb{R}^{n+1}} \frac{2\chi_{G_{\vartheta,\alpha_0} \backslash F}(Y)}{|X_0 - Y|^{n+1+s}} \, dy$$

$$\geqslant \int_W \frac{2\chi_{G_{\vartheta,\alpha_0} \backslash F}(Y)}{|X_0 - Y|^{n+1+s}} \, dy$$

$$\geqslant 2C_M^{-n-1-s} \int_W \chi_{G_{\vartheta,\alpha_0} \backslash F}(Y) \, dy$$

$$= 2C_M^{-n-1-s} |W|$$

$$\geqslant C_M^{-n-1-s} \mu_0^2 t |B_1|.$$

Hence, combining (4.17) and (4.18) we get

(4.21)
$$C\vartheta t \geqslant I[G_{\vartheta,\alpha_0}](X_0) = I[G_{\vartheta,\alpha_0}](X_0) - I[F](X_0) \geqslant C_M^{-n-1-s} \mu_0^2 t |B_1|,$$

which is a contradiction if ϑ is sufficiently small. This contradiction proves (4.16), that in turn implies (4.15) and so (4.14). This concludes the proof of Theorem 1.1.

5. Proof of Theorem 1.2

Let E_{∞} be a blow-down of E, that is a cluster point for $E_r := E/r$ as $r \nearrow \infty$. In this way we get a s-minimal cone, and the assumption that no singular s-minimal cones exist in dimension n combined with a standard dimension reduction argument implies that E_{∞} can only be singular at the origin.

Also, because ∂E was a graph, E_{∞} is an hypograph in \mathbb{R}^{n+1} , that is

$$(5.22) (x,\tau) \in E_{\infty} \implies (x,\tau-t) \in E_{\infty} \quad \forall t \geqslant 0.$$

To check (5.22) one can observe that, as ∂E_r is a graph, the above property holds with E_r in place of E_{∞} . Then, since $E_r \to E_{\infty}$ in the Hausdorff distance (see for instance Footnote 1 in the proof of Lemma 3.1), the claim in (5.22) follows.

Now we show that E_{∞} is in fact a graph (and not only an hypograph). For this, suppose by contradiction that there exists $\tau_{\infty} > 0$ such that ∂E_{∞} touches $\partial E_{\infty} + \tau_{\infty} e_{n+1}$ at some point. Then, by the strong maximum principle³ we get $E_{\infty} = E_{\infty} + \tau_{\infty} e_{n+1}$, from which (iterating this equality) we get $E_{\infty} = E_{\infty} + k\tau_{\infty} e_{n+1}$ for any $k \in \mathbb{N}$. This fact combined with (5.22) implies that

$$E_{\infty} = \mathscr{C} \times IR$$

where \mathscr{C} is a s-minimal cone in \mathbb{R}^n . Hence it follows by our assumption that \mathscr{C} is a half-space, and Lemma 3.1 gives that $E = \mathscr{C} \times \mathbb{R}$ which is in contradiction with the fact that E was a graph.

Hence we have shown that ∂E_{∞} and $\partial E_{\infty} + \tau e_{n+1}$ never touch for any $\tau > 0$, which implies that ∂E_{∞} is the graph of a function $u_{\infty} : \mathbb{R}^n \to \mathbb{R}$. In addition, since E_{∞} is smooth outside the origin, we can compute $|\nabla u_{\infty}(x)|$ at any point $x \neq 0$ (though, in principle, it can be infinite at points with vertical tangent hyperplanes).

Now, as in the proof of Theorem 1.1, we consider a bump function $w_0 \in C^{\infty}(\mathbb{R}, [0, 1])$, with $w_0(t) = 0$ for any $t \in (-\infty, 1/4] \cup [3/4, +\infty)$ and $w_0(t) = 1$ for any $t \in [2/5, 3/5]$, and we define $w(x) = w_0(|x|)$. Then, we fix $\sigma \in \partial B_1$ and consider the family of sets

$$F_t := \{(x,\tau) : \tau \leqslant u_{\infty}(x + t\vartheta w(x)\sigma) - t\},\,$$

where $t \in [0,1]$ and $\vartheta > 0$. By compactness we see that, if ϑ is sufficiently small, then $F_1 \subseteq E_{\infty}$. Let $t_0 \in [0,1]$ be the smallest t for which $F_t \subseteq E_{\infty}$, and assume by contradiction that $t_0 > 0$. Since E_{∞} is a graph, we see that F_{t_0} can only touch E_{∞} from below at some point $X_0 = (x_0, t_0)$ with $x_0 \in \text{supp}(w) \subset B_{3/4} \setminus B_{1/4}$. Hence, it is easy to see (by compactness) that a contact point $X_0 = (x_0, t_0)$ exists, and since $x_0 \in B_{3/4} \setminus B_{1/4}$ we have that both sets are smooth near X_0 .

Therefore we can easily adapt the arguments provided in (4.17)–(4.21) as follows: First, by the s-minimality of E_{∞} we have that $I[E_{\infty}](X_0) = 0 = I[F_0](X_0)$. Also, since F_{t_0} is a C^2 -diffeomorphism of F_0 of size ϑt_0 and F_0 is uniformly C^2 in a neighborhood of X_0 , we have that

$$\left|I[F_{t_0}](X_0)\right| \leqslant C\vartheta t_0.$$

On the other hand, since the graph of u_{∞} is uniformly Lipschitz in a nontrivial fraction of points (just pick a point where the tangent space to ∂E_{∞} is not vertical and consider a small

$$0 = I[E_{\infty} + \tau_{\infty} e_{n+1}](X_0) - I[E_{\infty}](X_0) = \int_{\mathbb{R}^{n+1}} \frac{2\chi_{E_{\infty} + \tau_{\infty} e_{n+1} \setminus E_{\infty}}(Y)}{|X_0 - Y|^{n+1+s}} \, dy,$$

which implies that $E_{\infty} = E_{\infty} + \tau_{\infty} e_{n+1}$, as desired.

 $^{^3}$ A simple and direct way to see the strong maximum principle is to use that E_{∞} and $E_{\infty} + \tau_{\infty}e_{n+1}$ are smooth cones outside the origin. So, if they touch, we can find a contact point $X_0 \neq 0$, and by computing the operator I defined in (1.1) at X_0 for both surfaces, since both E_{∞} and $E_{\infty} + \tau_{\infty}e_{n+1}$ are s-minimal and $E_{\infty} \subset E_{\infty} + \tau_{\infty}e_{n+1}$ we get

neighborhood of this point) we see that ∂F_{t_0} and ∂E_{∞} lie at distance $\geq ct_0$ on a nontrivial fraction of points, therefore

$$\left| (E_{\infty} \setminus F_{t_0}) \cap B_1 \right| \geqslant c_0 t_0$$

for some $c_0 > 0$. Hence, arguing as in the proof of Theorem 1.1 we get

$$|I[F_{t_0}](X_0)| = |I[F_{t_0}](X_0) - I[E_{\infty}](X_0)| \ge c't_0$$

for some c' > 0, which is in contradiction with (5.23) if ϑ was chosen sufficiently small.

This proves that $t_0 = 0$, which implies that $F_t \subseteq E_{\infty}$ for any $t \in (0,1)$, or equivalently

$$\frac{u_{\infty}(x + t\vartheta w(x)\sigma) - u_{\infty}(x)}{t} \leqslant 1 \qquad \forall t \in (0, 1).$$

Hence, letting $t \searrow 0$ we obtain

$$\vartheta w(x) \nabla u_{\infty}(x) \cdot \sigma \leqslant 1 \qquad \forall x \in \mathbb{R}^n \setminus \{0\}, \ \sigma \in \partial B_1,$$

which combined with the fact that w=1 in $B_{3/5}\setminus B_{2/5}$ and $\sigma\in\partial B_1$ is arbitrary implies

$$|\nabla u_{\infty}(x)| \leq 1/\vartheta \qquad \forall x \in B_{3/5} \setminus B_{2/5}.$$

Since u_{∞} is 1-homogeneous we deduce that u_{∞} is globally Lipschitz. So by Theorem 1.1 it is smooth also at the origin, hence (being a cone) E_{∞} a half-space. Using again Lemma 3.1 we deduce that E is a half-space as well, concluding the proof of Theorem 1.2.

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