

# GENERALIZED QUASIDISKS AND CONFORMALITY II

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ABSTRACT. We introduce a weaker variant of the concept of three point property, which is equivalent to a non-linear local connectivity condition introduced in [12], sufficient to guarantee the extendability of a conformal map  $f : \mathbb{D} \rightarrow \Omega$  to the entire plane as a homeomorphism of locally exponentially integrable distortion. Sufficient conditions for extendability to a homeomorphism of locally  $p$ -integrable distortion are also given.

## 1. INTRODUCTION

One calls a Jordan domain  $\Omega \subset \mathbb{R}^2$  a quasidisk if it is the image of the unit disk  $\mathbb{D}$  under a quasiconformal mapping  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  of the entire plane. If  $f$  is  $K$ -quasiconformal, we say that  $\Omega$  is a  $K$ -quasidisk. Another possibility is to require that  $f$  is additionally conformal in the unit disk  $\mathbb{D}$ . It is essentially due to Kühnau [17] that  $\Omega$  is a  $K$ -quasidisk if and only if  $\Omega$  is the image of  $\mathbb{D}$  under a  $K^2$ -quasiconformal mapping  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  that is conformal in  $\mathbb{D}$ , see [9]. The concept of a quasidisk is central in the theory of planar quasiconformal mappings; see, for example, [2, 4, 8, 21].

A substantial part of the theory of quasiconformal mappings has recently been shown to extend in a natural form to the setting of mappings of locally exponentially integrable distortion [3, 4, 7, 13, 14, 16, 23, 26]. See Section 2 below for the definition of this class of mappings. Thus one could say that  $\Omega \subset \mathbb{R}^2$  is a generalized quasidisk if it is the image of the unit disk  $\mathbb{D}$  under a homeomorphism  $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  of the entire plane with locally exponentially integrable distortion. However, requiring that  $f$  is additionally conformal in the unit disk  $\mathbb{D}$  leads to different classes of domains, see [12, Theorem 1.1]. In this paper, a Jordan domain  $\Omega \subset \mathbb{R}^2$  is termed a generalized quasidisk if the additional conformality requirement is satisfied.

For a quasidisk  $\Omega \subset \mathbb{R}^2$ , there are several equivalent characterizations. One of the simplest is Ahlfors [1] three point property. Recall that a Jordan domain  $\Omega \subset \mathbb{R}^2$  has the three point property if there

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exists a constant  $C \geq 1$  such that for each pair of distinct points  $P_1, P_2 \in \partial\Omega$ ,

$$(1.1) \quad \min_{i=1,2} \text{diam}(\gamma_i) \leq C|P_1 - P_2|,$$

where  $\gamma_1, \gamma_2$  are components of  $\partial\Omega \setminus \{P_1, P_2\}$ . In order to understand the geometry of generalized quasidisks, one naturally has to weaken the three point property. A Jordan domain  $\Omega \subset \mathbb{R}^2$  is said to have the three point property with a control function  $\psi$  if there exists a constant  $C \geq 1$  and an increasing function  $\psi : [0, \infty) \rightarrow [0, \infty)$  such that for each pair of distinct points  $P_1, P_2 \in \partial\Omega$ ,

$$(1.2) \quad \min_{i=1,2} \text{diam}(\gamma_i) \leq \psi\left(C|P_1 - P_2|\right).$$

A closely related concept is the following  $\psi$ -local connectivity, which was introduced in [12]. A domain  $\Omega \subset \mathbb{R}^2$  is said to be  $\psi$ -locally connected if for each  $x$  and all  $r > 0$ ,

- each pair of points in  $B(x, r) \cap \Omega$  can be joined by an arc in  $B(x, \psi^{-1}(r)) \cap \Omega$ , and
- each pair of points in  $\Omega \setminus B(x, r)$  can be joined by an arc in  $\Omega \setminus B(x, \psi(r))$ .

If we were to choose  $\psi(t) = Ct$ , then this would reduce to the usual linear local connectivity condition. In Lemma 3.1 below, we show that that a Jordan domain  $\Omega \subset \mathbb{R}^2$  has the three point property with a control function  $\psi$  if and only if  $\Omega$  is  $\psi^{-1}$ -locally connected.

In [12, Theorem 1.2], it was proved that if a Jordan domain  $\Omega \subset \mathbb{R}^2$  is  $\psi$ -locally connected with  $\psi(t) = \frac{Ct}{\log^s \log \frac{1}{t}}$  for some positive constant  $C$  and some  $s \in (0, \frac{1}{4})$ , then  $\Omega$  is a generalized quasidisk. However, the result is not sharp regarding well-studied examples, see [12]. In fact, the previous studies in [12, 19, 20, 24] suggest that the critical case should be  $\psi(t) = \frac{Ct}{\log \frac{1}{t}}$ . By the equivalence of local connectivity and generalized three point property mentioned in the end of the previous paragraph, for a domain satisfying the three point property with a control function  $\psi$ , the critical case (essentially) becomes  $\psi(t) = Ct \log \frac{1}{t}$ . Our first main result approaches this critical case and improves on [12, Theorem 1.2].

**Theorem 1.1.** *If a Jordan domain  $\Omega \subset \mathbb{R}^2$  has the three point property with the control function  $\psi(t) = Ct \log^{\frac{1}{2}} \frac{1}{t}$  for some positive constant  $C$ , then  $\Omega$  is a generalized quasidisk.*

Equivalently, Theorem 1.1 provides a general sufficient condition for extendability of a conformal mapping  $f : \mathbb{D} \rightarrow \Omega$  to a homeomorphism of locally exponentially integrable distortion. It was pointed out in [12] that this is essentially equivalent to extending the corresponding conformal welding to the whole plane as a homeomorphism of locally exponentially integrable distortion, see also Section 4 below.

Our second main result asserts that if we relax the control function  $\psi$  to be a root in Theorem 1.1, then we end up with a homeomorphism of the whole plane with locally  $p$ -integrable distortion.

**Theorem 1.2.** *Let  $\Omega \subset \mathbb{R}^2$  be a Jordan domain that has the three point property with the control function  $\psi(t) = t^s$ ,  $0 < s < 1$ . Then any conformal mapping  $f: \mathbb{D} \rightarrow \Omega$  can be extended to the entire plane as a homeomorphism of locally  $p$ -integrable distortion for all  $p \in (0, \frac{s^2}{2(1-s^2)})$ .*

As pointed out in [12], (polynomial) interior cusps are more dangerous than (polynomial) exterior cusps in the locally exponentially integrable distortion case. Thus one expects that this is still the case for extensions with locally  $p$ -integrable distortion. Our next result confirms this expectation.

**Theorem 1.3.** *Let  $\Omega \subset \mathbb{R}^2$  be a LLC-1 Jordan domain. Then any conformal mapping  $f: \mathbb{D} \rightarrow \Omega$  can be extended to the entire plane as a homeomorphism of locally  $p$ -integrable distortion for some  $p > 0$ .*

This paper is organized as follows. Section 2 contains the basic definitions and Section 3 some auxiliary results. In Section 4, we study the relation of extending a Riemann mapping and the corresponding conformal welding. We prove our main results in Section 5. In the final section, Section 6, we make some concluding remarks.

## 2. NOTATION AND DEFINITIONS

We sometimes associate the plane  $\mathbb{R}^2$  with the complex plane  $\mathbb{C}$  for convenience and denote by  $\hat{\mathbb{C}}$  the extended complex plane. The closure of a set  $U \subset \mathbb{R}^2$  is denoted  $\overline{U}$  and the boundary  $\partial U$ . The open disk of radius  $r > 0$  centered at  $x \in \mathbb{R}^2$  is denoted by  $B(x, r)$  and we simply write  $\mathbb{D}$  for the unit disk. The boundary of  $B(x, r)$  will be denoted by  $S(x, r)$  and the boundary of the unit disk  $\mathbb{D}$  is written as  $\partial\mathbb{D}$ . The symbol  $\Omega$  always refers to a domain, i.e. a connected and open subset of  $\mathbb{R}^2$ . We call a homeomorphism  $f: \Omega \rightarrow f(\Omega) \subset \mathbb{R}^2$  a homeomorphism of finite distortion if  $f \in W_{loc}^{1,1}(\Omega; \mathbb{R}^2)$  and

$$(2.1) \quad \|Df(x)\|^2 \leq K(x)J_f(x) \text{ a.e. in } \Omega,$$

for some measurable function  $K(x) \geq 1$  that is finite almost everywhere. Recall here that  $J_f \in L_{loc}^1(\Omega)$  for each homeomorphism  $f \in W_{loc}^{1,1}(\Omega; \mathbb{R}^2)$  (cf. [4]). In the distortion inequality (2.1),  $Df(x)$  is the formal differential of  $f$  at the point  $x$  and  $J_f(x) := \det Df(x)$  is the Jacobian. The norm of  $Df(x)$  is defined as

$$\|Df(x)\| := \max_{e \in \partial\mathbb{D}} |Df(x)e|.$$

For a homeomorphism of finite distortion it is convenient to write  $K_f$  for the optimal distortion function. This is obtained by setting  $K_f(x) = \|Df(x)\|^2/J_f(x)$  when  $Df(x)$  exists and  $J_f(x) > 0$ , and  $K_f(x) = 1$

otherwise. The distortion of  $f$  is said to be locally  $\lambda$ -exponentially integrable if  $\exp(\lambda K_f(x)) \in L^1_{\text{loc}}(\Omega)$ , for some  $\lambda > 0$ . Note that if we assume  $K_f(x)$  to be bounded,  $K_f \leq K$ , we recover the class of  $K$ -quasiconformal mappings, see [4] for the theory of quasiconformal mappings.

Recall that a domain  $\Omega$  is said to be linearly locally connected (LLC) if there is a constant  $C \geq 1$  so that

- (LLC-1) each pair of points in  $B(x, r) \cap \Omega$  can be joined by an arc in  $B(x, Cr) \cap \Omega$ , and
- (LLC-2) each pair of points in  $\Omega \setminus B(x, r)$  can be joined by an arc in  $\Omega \setminus B(x, C^{-1}r)$ .

We need a weaker version of this condition, defined as follows. We say that  $\Omega$  is  $(\varphi, \psi)$ -locally connected  $((\varphi, \psi)$ -LC) if

- $(\varphi$ -LC-1) each pair of points in  $B(x, r) \cap \Omega$  can be joined by an arc in  $B(x, \varphi(r)) \cap \Omega$ , and
- $(\psi$ -LC-2) each pair of points in  $\Omega \setminus B(x, r)$  can be joined by an arc in  $\Omega \setminus B(x, \psi(r))$ ,

where  $\varphi, \psi : [0, \infty) \rightarrow [0, \infty)$  are smooth increasing functions such that  $\varphi(0) = \psi(0) = 0$ ,  $\varphi(r) \geq r$  and  $\psi(r) \leq r$  for all  $r > 0$ . For technical reasons, we assume that the function  $t \mapsto \frac{t}{\varphi^{-1}(t)^2}$  is decreasing and that there exist constants  $C_1, C_2$  so that  $C_1\varphi(t) \leq \varphi(2t) \leq C_2\varphi(t)$  and  $C_1\psi(t) \leq \psi(2t) \leq C_2\psi(t)$  for all  $t > 0$ . If  $\varphi^{-1} = \psi$  above, as in the introduction,  $\Omega$  will simply be called  $\psi$ -LC. One could relax joinability by an arc above to joinability by a continuum, but this leads to the same concept; see [15, Theorem 3-17]. Notice that if  $\Omega$  is simply connected and bounded, then  $\varphi$ -LC-1 guarantees that  $\Omega$  is a Jordan domain.

Finally we define the central tool for us – the modulus of a path family. A Borel function  $\rho : \mathbb{R}^2 \rightarrow [0, \infty]$  is said to be admissible for a path family  $\Gamma$  if  $\int_{\gamma} \rho ds \geq 1$  for each locally rectifiable  $\gamma \in \Gamma$ . The modulus of the path family  $\Gamma$  is then

$$\text{mod}(\Gamma) := \inf \left\{ \int_{\Omega} \rho^2(x) dx : \rho \text{ is admissible for } \Gamma \right\}.$$

For subsets  $E$  and  $F$  of  $\overline{\Omega}$  we write  $\Gamma(E, F, \Omega)$  for the path family consisting of all locally rectifiable paths joining  $E$  to  $F$  in  $\Omega$  and abbreviate  $\text{mod}(\Gamma(E, F, \Omega))$  to  $\text{mod}(E, F, \Omega)$ . In what follows,  $\gamma(x, y)$  refers to a curve or an arc from  $x$  to  $y$ .

When we write  $f(x) \lesssim g(x)$ , we mean that  $f(x) \leq Cg(x)$  is satisfied for all  $x$  with some fixed constant  $C \geq 1$ . Similarly, the expression  $f(x) \gtrsim g(x)$  means that  $f(x) \geq C^{-1}g(x)$  is satisfied for all  $x$  with some fixed constant  $C \geq 1$ . We write  $f(x) \approx g(x)$  whenever  $f(x) \lesssim g(x)$  and  $f(x) \gtrsim g(x)$ .

## 3. AUXILIARY RESULTS

We begin this section by showing the equivalence of the generalized three point property and generalized local connectivity mentioned in the introduction.

**Lemma 3.1.** *Let  $\Omega \subset \mathbb{R}^2$  be a Jordan domain. Then  $\Omega$  has the three point property with the control function  $\psi$  if and only if  $\Omega$  is  $\psi^{-1}$ -locally connected.*

*Proof.* For the proof we need the following duality result from [11, Theorem 1.3]: for a Jordan domain  $\Omega \subset \mathbb{R}^2$ ,  $\Omega$  is  $\psi$ -LC-2 if and only if  $\mathbb{R}^2 \setminus \overline{\Omega}$  is  $\psi$ -LC-1.

First, suppose that  $\Omega$  has the three point property with the control function  $\psi$ . We want to show that  $\Omega$  is  $\psi$ -LC-1. To this end, let  $x, y \in B(z, r) \cap \Omega$ . We may assume that there exist  $x', y' \in B(z, r) \cap \partial\Omega$  such that

$$d(x, x') = d(x, \partial\Omega), d(y, y') = d(y, \partial\Omega)$$

and that  $x$  can be connected to  $x'$  by an arc  $\beta_1$  in  $\overline{\Omega} \cap B(z, r)$  and  $y$  can be connected to  $y'$  by an arc  $\beta_2$  in  $\overline{\Omega} \cap B(z, r)$ . Let  $\alpha_1$  and  $\alpha_2$  be the components of  $\partial\Omega \setminus \{x', y'\}$ . We may assume that  $\alpha_1 \leq \alpha_2$ . Then

$$\text{diam}(\alpha_1) \leq \psi(|x' - y'|) \leq \psi(2r).$$

Hence,  $\gamma = \beta_1 \cup \alpha_1 \cup \beta_2$  is a curve that connects  $x$  and  $y$  in  $\overline{\Omega}$  with diameter less than  $2\psi(2r)$ . Then the Jordan assumption for  $\Omega$  implies that we may connect  $x$  to  $y$  in  $\Omega$  by a curve with diameter no more than  $3\psi(2r)$ . This together with Lemma 3.2 below implies that  $\Omega$  is  $\psi$ -LC-1. Similarly, one can prove that  $\mathbb{R}^2 \setminus \overline{\Omega}$  is  $\psi$ -LC-1. Then the duality result recalled in the beginning of the proof implies that  $\Omega$  is  $\psi$ -LC.

Next, we assume that  $\Omega$  is  $\psi^{-1}$ -LC. Then, again by the duality result, we know that both  $\Omega$  and  $\mathbb{R}^2 \setminus \overline{\Omega}$  are  $\psi$ -LC-1. Let  $x, y \in \partial\Omega$  and let  $\alpha_1, \alpha_2$  be the components of  $\partial\Omega \setminus \{x, y\}$ . We may assume that  $\text{diam}(\alpha_1) \leq \text{diam}(\alpha_2)$ . Let  $z = \frac{x+y}{2}$  and  $r = |x - y|$ . Then  $x, y \in B(z, r)$ . We may choose two points  $x'$  and  $y'$  in  $\Omega \cap B(z, r)$  such that  $x$  can be connected to  $x'$  by an arc  $\beta_1$  in  $\overline{\Omega} \cap B(z, r)$  and  $y$  can be connected to  $y'$  by an arc  $\beta_2$  in  $\overline{\Omega} \cap B(z, r)$ . Then we may connect  $x'$  to  $y'$  by an arc  $\gamma$  in  $\Omega \cap B(z, 2\psi(r))$ . Then the curve  $\eta = \beta_1 \cup \gamma \cup \beta_2$  forms a crosscut of  $\Omega$  with diameter no more than  $4\psi(r)$ . Similarly, we may form a crosscut  $\eta'$  of  $\mathbb{R}^2 \setminus \overline{\Omega}$  with diameter no more than  $4\psi(r)$ . Thus  $\eta \cup \eta'$  is a Jordan curve which contains the Jordan arc  $\alpha_1$ . Therefore, the diameter of  $\alpha_1$  is no more than  $8\psi(r)$ . This together with Lemma 3.2 below implies that  $\Omega$  has the three point property with the control function  $\psi$ .  $\square$

**Lemma 3.2** (Lemma 3.5, [11]). *Let  $C_1 \geq 1$ ,  $C_2 \geq 1$ , and  $C_3 \geq 1$  be given. There exists a constant  $C$ , depending only on  $C_0, C_1, C_2$  and  $C_3$ , such that*

$$(3.1) \quad C_1\varphi(C_2t) + C_3t \leq \varphi(Ct)$$

for all  $t > 0$ . Above,  $C_0$  is the doubling constant of  $\varphi^{-1}$ .

The following two modulus estimates are standard, see e.g. [25].

**Lemma 3.3.** *Let  $E, F$  be disjoint nondegenerate continua in  $B(x, R)$ . Then*

$$(3.2) \quad C_0^{-1} \frac{1}{\log(1+t)} \geq \text{mod}(E, F, B(x, R)) \geq C_0 \frac{1}{\log(1+t)},$$

where  $t = \frac{\text{dist}(E, F)}{\min\{\text{diam } E, \text{diam } F\}}$  and  $C_0$  is an absolute constant.

**Lemma 3.4.** *Let  $\Gamma$  be a curve family such that for all  $t \in (r, R)$ , the circle  $|z - z_1| = t$  contains a curve  $\gamma \in \Gamma$ . Then*

$$(3.3) \quad \text{mod}(\Gamma) \geq \frac{1}{2\pi} \log \frac{R}{r}.$$

Next, we recall the following result on the modulus of continuity of a quasiconformal mapping. The proof can be found in [18]; also see [10].

**Lemma 3.5.** *Suppose  $g: \Omega \rightarrow \mathbb{D}$  is a  $K$ -quasiconformal mapping from a simply connected domain  $\Omega$  onto the unit disk. Then there exists a positive constant  $C$ , (depending on  $f$ ), such that for any  $\omega, \xi \in \Omega$ ,*

$$(3.4) \quad |g(\omega) - g(\xi)| \leq C d_I(\omega, \xi)^{\frac{1}{2K}},$$

where  $d_I(\omega, \xi)$  is defined as  $\inf_{\gamma(\omega, \xi) \subset \Omega} \text{diam}(\gamma(\omega, \xi))$ . In particular, if  $\Omega$  above is  $\varphi$ -LC-1, then

$$(3.5) \quad |g(\omega) - g(\xi)| \leq C \varphi(|\omega - \xi|)^{\frac{1}{2K}}.$$

Finally, we need the following key estimate.

**Lemma 3.6.** *Let  $\Omega \subset \mathbb{R}^2$  be a Jordan domain that has the three point property with the control function  $\psi$ . Let  $\alpha_1$  and  $\alpha_2$  be two disjoint arcs in  $\partial\Omega$  and let  $\Gamma$  and  $\Gamma'$  be the family of curves which join  $\alpha_1$  and  $\alpha_2$  in  $\Omega$  and  $\mathbb{R}^2 \setminus \overline{\Omega}$ , respectively. If  $\text{mod}(\Gamma) \leq C$ , then*

$$(3.6) \quad \min\{\text{diam}(\alpha_1), \text{diam}(\alpha_2)\} \leq \psi \circ \psi(d(\alpha_1, \alpha_2))$$

and hence

$$(3.7) \quad \text{mod}(\Gamma') \leq C_0^{-1} \log^{-1} \left( 1 + \frac{\psi^{-1} \circ \psi^{-1}(\min\{\text{diam}(\alpha_1), \text{diam}(\alpha_2)\})}{\min\{\text{diam}(\alpha_1), \text{diam}(\alpha_2)\}} \right).$$

*Proof.* The idea of the proof is similar to that of the proof of Theorem 5.1 in [12]. Let  $\alpha_1$  and  $\alpha_2$  be two disjoint arcs in  $\partial\Omega$ . Choose  $z_1 \in \alpha_1$ ,  $z_2 \in \alpha_2$  so that

$$|z_1 - z_2| = d(\alpha_1, \alpha_2) := d.$$

Without loss of generality, we may assume that

$$r := \text{diam}(\alpha_1) \leq \text{diam}(\alpha_2).$$

Our aim is to show that  $r \leq 2\psi \circ \psi(d)$ . Thus we may clearly assume that  $r > 2\psi \circ \psi(d)$ . Note that our assumption on  $\psi$  implies that  $r >$

$\psi(d)$ . Since  $\Omega$  has the three point property with the control function  $\psi$ ,

$$\min_{i=1,2} \text{diam}(\gamma_i) \leq \psi(d),$$

where  $\gamma_1, \gamma_2$  are the components of  $\partial\Omega \setminus \{z_1, z_2\}$ . Again, we may assume that

$$\text{diam}(\gamma_1) \leq \psi(d).$$

Let  $\beta_1, \beta_2$  be the components of  $\partial\Omega \setminus (\alpha_1 \cup \alpha_2)$ , labeled so that  $\beta_i \subset \gamma_i$ . Then  $\beta_1 \subset \gamma_1 \subset \overline{B}(z_1, \psi(d))$ . Choose  $z_0 \in \beta_2$  and let  $\delta_1, \delta_2$  denote the components of  $\partial\Omega \setminus \{z_0, z_1\}$  labeled so that  $\alpha_2 \subset \delta_2$ . Then the fact  $\Omega$  has the three point property with the control function  $\psi$  implies that

$$\min_{i=1,2} \text{diam}(\delta_i) \leq \psi(|z_1 - z_0|).$$

Choose  $\omega_1, \omega_2 \in \alpha_1$  so that

$$r = |\omega_1 - \omega_2| = \text{diam}(\alpha_1).$$

Then  $\omega_i \in \gamma_1 \cup \delta_1$ , and the fact that  $\text{diam}(\gamma_1) \leq \psi(d) < r$  implies that not both of these points can lie in  $\gamma_1$ . If  $\omega_1 \in \gamma_1$ , then

$$\begin{aligned} \text{diam}(\delta_1) &\geq |\omega_2 - z_1| \geq |\omega_1 - \omega_2| - |z_1 - \omega_1| \\ &\geq r - \text{diam}(\gamma_1) \geq r - \psi(d) \geq \frac{r}{2}. \end{aligned}$$

If both lie in  $\delta_1$ , then

$$\text{diam}(\delta_1) \geq |\omega_1 - \omega_2| = r.$$

Thus

$$\frac{r}{2} \leq \min_{i=1,2} \text{diam}(\delta_i) \leq \psi(|z_1 - z_0|).$$

It follows that

$$\beta_2 \cap B(z_1, \psi^{-1}(\frac{r}{2})) = \emptyset.$$

In particular, the circle  $|z - z_1| = t$  separates  $\beta_1$  and  $\beta_2$  for  $t \in (\psi(d), \psi^{-1}(\frac{r}{2}))$  and hence must contain an arc  $\gamma$  joining  $\alpha_1$  and  $\alpha_2$  in  $\Omega$ . Thus Lemma 3.4 implies that

$$\frac{1}{2\pi} \log \frac{\psi^{-1}(r/2)}{\psi(d)} \leq \text{mod}(\Gamma) \leq C$$

from which the claim follows. The desired inequality (3.7) follows from Lemma 3.3 directly.  $\square$

## 4. EXTENSION OF A CONFORMAL WELDING

Before stating the main result of this section, let us describe the standard way of extending a conformal map  $f: \mathbb{D} \rightarrow \Omega$ , where  $\Omega$  is a Jordan domain, to a mapping of the entire plane. First of all,  $f$  can be extended to a homeomorphism between  $\overline{\mathbb{D}}$  and  $\overline{\Omega}$ . For simplicity, we denote this extended homeomorphism also by  $f$ . It follows from the Riemann Mapping Theorem that there exists a conformal mapping  $g: \mathbb{R}^2 \setminus \overline{\mathbb{D}} \rightarrow \mathbb{R}^2 \setminus \overline{\Omega}$  such that the complement of the closed unit disk gets mapped to the complement of  $\overline{\Omega}$ . In this correspondence the boundary curve  $\Gamma = \partial\Omega$  is mapped homeomorphically onto the boundary circle  $\partial\mathbb{D}$  and hence the composed mapping  $G = g^{-1} \circ f$  is a well-defined circle homeomorphism, called conformal welding. Suppose we are able to extend  $G$  to the exterior of the unit disk, with the extension still denoted by  $G$ . Then the mapping  $G' = g \circ G$  will be well-defined outside the unit disk and it coincides with  $f$  on the boundary circle  $\partial\mathbb{D}$ . Finally, if we define

$$F(x) = \begin{cases} G'(x) & \text{if } |x| \geq 1 \\ f(x) & \text{if } |x| \leq 1, \end{cases}$$

then we obtain an extension of  $f$  to the entire plane. In the case of a quasidisk, that is when  $\Omega$  is linearly locally connected (LLC), the extension  $G$  can be chosen to be quasiconformal and hence the obtained map  $F$  is also quasiconformal.

On the other hand, the extendability of a conformal mapping  $f: \mathbb{D} \rightarrow \Omega$  to a homeomorphism  $\hat{f}: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  of locally integrable distortion is essentially equivalent to being able to extend the conformal welding  $G'$  above to this class. Indeed, if  $\hat{f}$  extends  $f$ , then  $g^{-1} \circ \hat{f}$  extends  $G$  to the exterior of  $\mathbb{D}$  and has the same distortion as  $\hat{f}$ . Reflecting (twice) with respect to the unit circle one then further obtains an extension to  $\mathbb{D} \setminus \{0\}$ . Hence, one obtains an extension  $\hat{G}'$  of  $G'$  to  $\mathbb{R}^2 \setminus \{0\}$  with distortion that has the same local integrability degree as the distortion of  $\hat{f}$ . If the latter distortion is sufficiently nice in a neighborhood of infinity (e.g. bounded), then this holds in all of  $\mathbb{R}^2$  as well.

Given a sense-preserving homeomorphism  $f: \partial\mathbb{D} \rightarrow \partial\mathbb{D}$  and  $0 < t < \frac{\pi}{2}$ , set

$$(4.1) \quad \delta_f(\theta, t) = \max \left\{ \frac{|f(e^{i(\theta+t)}) - f(e^{i\theta})|}{|f(e^{i\theta}) - f(e^{i(\theta-t)})|}, \frac{|f(e^{i(\theta-t)}) - f(e^{i\theta})|}{|f(e^{i\theta}) - f(e^{i(\theta+t)})|} \right\}.$$

Clearly  $\delta_f$  is continuous in both variables,  $\delta_f \geq 1$  and  $\delta_f(\theta + 2\pi, t) = \delta_f(\theta, t)$ . The scalewise distortion of  $f$  is defined as  $\rho_f(t) = \sup_{\theta} \delta_f(\theta, t)$ .

In the following, we discuss a standard way of extending a conformal welding  $G: \partial\mathbb{D} \rightarrow \partial\mathbb{D}$  to a global homeomorphism of the whole plane with controlled distortion. More precisely, we want to present

the following result, which is implicitly contained in [26, Section 2 and Section 3].

**Proposition 4.1.** *Given a conformal welding  $G : \partial\mathbb{D} \rightarrow \partial\mathbb{D}$ , there exists a homeomorphism  $\hat{G} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  with the following property:*

- For some  $\delta \in (0, \frac{1}{2})$ ,  $\hat{G}(z) = z$  if  $|z| < \delta$  or  $|z| > \frac{1}{\delta}$ .
- The distortion of  $\hat{G}$  is bounded above by the scalewise distortion of  $G$ , i.e.

$$(4.2) \quad K_{\hat{G}}(z) \leq C \rho_G(\log |z|) = C \sup_{\theta \in [0, 2\pi]} \delta_G(\theta, \log |z|),$$

if  $\delta \leq |z| \leq \frac{1}{\delta}$  for some absolute constant  $C > 0$ .

Let us describe below the argument leading to Proposition 4.1. Given a conformal welding  $G : \partial\mathbb{D} \rightarrow \partial\mathbb{D}$ , we first want to extend  $G$  to a homeomorphism  $\tilde{G} : \overline{\mathbb{D}} \rightarrow \overline{\mathbb{D}}$ . We may represent  $G$  in the form

$$G(e^{2\pi i x}) = e^{2\pi i h(x)},$$

where  $h : \mathbb{R} \rightarrow \mathbb{R}$  is a homeomorphism of the real line which commutes with the unit translation  $x \mapsto x + 1$ . For simplicity, we may assume that  $G(1) = 1$  and hence  $h(0) = 0$ .

Next, we extend our mapping  $h$  to a homeomorphism  $H : \mathbb{H} \rightarrow \mathbb{H}$ . This can be done via the well-known Beurling-Ahlfors extension. To be more precise, for  $0 < y < 1$ , set

$$(4.3) \quad H(x+iy) = \frac{1}{2} \int_0^1 (h(x+ty) + h(x-ty)) dt + i \int_0^1 (h(x+ty) - h(x-ty)) dt.$$

Then  $H = h$  on the real axis and  $H$  is a  $C^1$ -smooth homeomorphism of  $\mathbb{H}$ . Since  $h(x+1) = h(x) + 1$ , for  $y = 1$

$$H(x+i) = x+i+C_0,$$

where  $C_0 = \int_0^1 h(t) dt - \frac{1}{2} \in [-\frac{1}{2}, \frac{1}{2}]$ . For  $1 \leq y \leq 2$  we extend  $H$  linearly by setting

$$H(z) = z + (2-y)C_0, \quad z = x+iy.$$

Finally, we set  $H(z) = z$  if  $y = \text{Im}(z) \geq 2$ . It is easy to check that  $H(z+k) = H(z) + k$  for  $k \in \mathbb{Z}$ . We set

$$(4.4) \quad \tilde{G} = \mathbf{e} \circ H \circ L,$$

where  $\mathbf{e} : z \mapsto e^{2\pi i z}$  is the lifting mapping and  $L : z \mapsto \frac{\log z}{2\pi i}$  is the logarithmic mapping. We claim that  $\tilde{G} : \mathbb{D} \setminus \{0\} \rightarrow \mathbb{D} \setminus \{0\}$  is a well-defined homeomorphism. To see this, let  $z = re^{0i} = re^{2\pi i}$  be as in Figure 1. We need to show that  $L$  is well-defined on the segment  $P := \{z : r \leq |z| \leq 1\}$ . Note that in Figure 1, the vertical line  $[0, L(z)]$  corresponds to the image of  $P$  with argument 0 and the vertical line  $[1, L(z) + 1]$  corresponds to the image of  $P$  with argument  $2\pi$  under

the mapping  $L$ . Note also that  $L(re^{0i}) = \frac{\log r}{2\pi i}$  and  $L(re^{2\pi i}) = \frac{\log r + 2\pi i}{2\pi i}$ . Since  $H$  satisfies that  $H(z+1) = H(z) + 1$  and  $\mathbf{e}$  is 1-periodic, the mapping  $\tilde{G}$  is a homeomorphism in the annulus  $\mathbb{D} \setminus B(0, r)$ . Moreover,

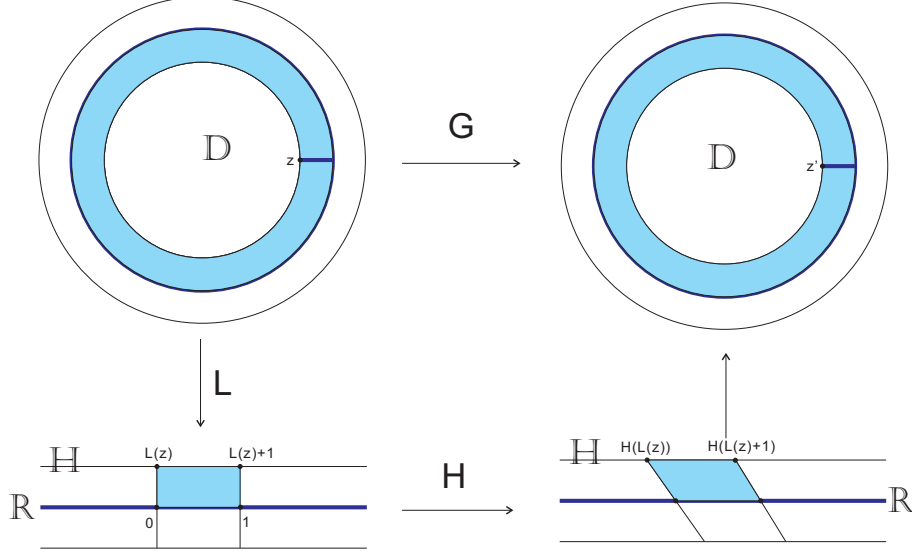


FIGURE 1. The homeomorphism  $\tilde{G}$

$\tilde{G} = G$  on  $\partial\mathbb{D}$  and  $\tilde{G}(z) = z$  for  $0 < |z| \leq \delta := e^{-4\pi}$ . Thus  $\tilde{G}$  is well-defined homeomorphism of the unit disk if we additionally set  $\tilde{G}(0) = 0$ .

Finally, we may define our mapping  $\hat{G} : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  by setting

$$\hat{G}(z) = \begin{cases} \tilde{G}(z) & \text{if } |z| \geq 1 \\ R \circ \tilde{G} \circ R(z) & \text{if } |z| \leq 1, \end{cases}$$

where  $R(z) = \frac{1}{\bar{z}}$  is the inversion with respect to the unit circle. To complete the proof of Proposition 4.1, we need to estimate the distortion of  $\hat{G}$ .

It is clear that we only need to estimate the distortion of  $\tilde{G}$ . Since  $\mathbf{e}$  and  $L$  are conformal mappings, it follows that

$$K_{\tilde{G}}(z) = K_H(\omega), \quad z = e^{2\pi i \omega}, \quad \omega \in \mathbb{H}.$$

So we reduce all distortion estimates for  $\tilde{G}$  to the corresponding ones for  $H$ . Since  $H$  is conformal for  $y > 2$  and linear for  $y \in [1, 2]$ , it suffices to estimate  $K_H$  in the strip  $S = \mathbb{R} \times [0, 1]$ . The desired estimate

$$K_H(x + iy) \leq C_0 \rho_h(y), \quad x + iy \in S$$

follows from the calculation in [6], where

$$\begin{aligned} \rho_h(t) &= \sup_{\theta \in \mathbb{R}} \delta_h(\theta, t) \\ &:= \sup_{\theta \in \mathbb{R}} \max \left\{ \frac{|h(\theta + t) - h(\theta)|}{|h(\theta) - h(\theta - t)|}, \frac{|h(\theta - t) - h(\theta)|}{|h(\theta) - h(\theta + t)|} \right\}. \end{aligned}$$

Note that if  $t \in [0, 1]$ , then

$$\delta_G(\theta, t) \approx \delta_h(\theta, t)$$

and hence

$$\rho_G(t) \approx \rho_h(t).$$

The proof of Proposition 4.1 is complete.

As an application of Proposition 4.1, we easily obtain the following corollary.

Let  $\delta$  be as in Proposition 4.1 and let  $\varepsilon < \delta$  is sufficiently small such that

$$\log |z| \leq 2|r - 1|$$

for  $z = re^{i\theta} \in A := \overline{B(0, 1 + \varepsilon)} \setminus B(0, 1 - \varepsilon)$ . Proposition 4.1 implies that

$$K_{\hat{G}}(z) \leq C\rho_G(\log |z|) \leq C\rho_G(2|r - 1|)$$

for  $z \in A$ . If  $\rho_G(t) \leq C't^{-\alpha}$  as  $t \rightarrow 0$ , then

$$K_{\hat{G}}(z) \leq C|r - 1|^{-\alpha},$$

for  $z \in A$ . Integrating in polar coordinates, we immediately obtain the following corollary.

**Corollary 4.2.** *Let  $G : \partial\mathbb{D} \rightarrow \partial\mathbb{D}$  be a conformal welding. If*

$$\rho_G(t) = O\left(\log \frac{1}{t}\right) \quad \text{as } t \rightarrow 0,$$

*then  $G$  extends to a homeomorphism of the entire plane of locally exponentially integrable distortion. Moreover, if*

$$\rho_G(t) = O(t^{-\alpha}) \quad \text{as } t \rightarrow 0$$

*for some  $\alpha > 0$ , then  $G$  extends to a homeomorphism of the entire plane of locally  $p$ -integrable distortion with any  $p \in (0, \frac{1}{\alpha})$ .*

## 5. MAIN PROOFS

Theorem 1.1 follows from the following more general result.

**Theorem 5.1.** *If  $\Omega \subset \mathbb{R}^2$  is a Jordan domain that has the three point property with a control function  $\psi$  such that*

$$(5.1) \quad \limsup_{r \rightarrow 0} \frac{r}{\psi^{-1} \circ \psi^{-1}(r) \log \frac{1}{r}} \leq C'$$

*for some constant  $C'$ , then  $\Omega$  is a generalized quasidisk.*

*Proof of Theorem 5.1.* The idea is similar to that used in [12, Theorem 5.1]. Since  $\Omega$  is a Jordan domain,  $f$  extends to a homeomorphism between  $\mathbb{D}$  and  $\overline{\Omega}$  and we denote also this extension by  $f$ . Let  $e^{i(\theta-t)}$ ,  $e^{i\theta}$  and  $e^{i(\theta+t)}$  be three points on  $S$ . Since  $f$  is a sense-preserving homeomorphism,  $f(e^{i(\theta-t)})$ ,  $f(e^{i\theta})$  and  $f(e^{i(\theta+t)})$  will be on the boundary of  $\Omega$  in order. Let  $g: \mathbb{R}^2 \setminus \overline{\mathbb{D}} \rightarrow \mathbb{R}^2 \setminus \overline{\Omega}$  be a conformal mapping from the Riemann Mapping Theorem. Then  $g$  extends to a homomorphism between  $\mathbb{R}^2 \setminus \mathbb{D}$  and  $\mathbb{R}^2 \setminus \Omega$ . As before, we still denote this extension by  $g$ . Based on the discussion in the previous section, we only need to estimate the scale-wise distortion of the conformal welding  $G := g^{-1} \circ f$ .

Let  $P = e^{i(\theta+\pi)}$  be the anti-polar point of  $e^{i\theta}$  on  $\partial\mathbb{D}$  and let  $\gamma_f(P, \theta-t)$  denote the arc from  $f(P)$  to  $f(e^{i(\theta-t)})$  on  $\partial\Omega$ . There exists a  $t_0$  small enough such that  $\text{diam}(\gamma_f(-1, \theta-t)) \geq \text{diam}(\gamma_f(\theta, \theta+t))$  when  $t \in [0, t_0]$ . Let  $\Gamma_1$  be the family of curves in  $\mathbb{D}$  joining  $\gamma(P, e^{i(\theta-t)})$  and  $\gamma(e^{i\theta}, e^{i(\theta+t)})$ . Then Lemma 3.3 implies that

$$(5.2) \quad \text{mod}(\Gamma_1) \leq C_1$$

for some absolute constant  $C_1 > 0$ . The conformal invariance of modulus gives us that

$$(5.3) \quad \text{mod}(\Gamma) := \text{mod}(f(\Gamma_1)) \leq C_2.$$

Thus, we may use Lemma 3.6 for  $\alpha_1 = \gamma_f(\theta, \theta+t)$  and  $\alpha_2 = \gamma_f(P, \theta-t)$  and conclude that

$$\text{diam}(\gamma_f(\theta, \theta+t)) \leq \psi \circ \psi(d),$$

where  $d = d(\alpha_1, \alpha_2)$  is the distance between these two arcs. Moreover,

$$(5.4) \quad \text{mod}(\Gamma') \leq C \log^{-1} \left( 1 + \frac{\psi^{-1} \circ \psi^{-1}(\text{diam}(\alpha_1))}{\text{diam}(\alpha_1)} \right),$$

where  $\Gamma'$  is the family of curves joining  $\alpha_1$  and  $\alpha_2$  in  $\mathbb{R}^2 \setminus \overline{\Omega}$ . Again by conformal invariance of modulus, we obtain that

$$(5.5) \quad \log^{-1} \left( 1 + \frac{1}{\delta_G(\theta, t)} \right) \leq C_0^{-1} \text{mod}(\Gamma'),$$

where  $C_0$  is the constant from Lemma 3.3. Note that

$$\frac{1}{\log(1+t)} \approx \frac{1}{t} \quad \text{as } t \rightarrow 0.$$

Combining (5.4) with (5.5) gives us the estimate

$$\delta_G(\theta, t) \leq \frac{C \text{diam}(\alpha_1)}{\psi^{-1} \circ \psi^{-1}(\text{diam}(\alpha_1))}.$$

On the other hand, by applying Lemma 3.5 and noticing that our technical assumptions on  $\psi$  implies that  $\psi(t) \geq Ct^\alpha$  for some  $\alpha > 0$ , we obtain that

$$\text{diam}(\alpha_1) \geq C\psi(t^2) \geq Ct^{2\alpha}.$$

Since  $\frac{t}{\psi^{-1} \circ \psi^{-1}(t)}$  is non-increasing, we obtain that

$$(5.6) \quad \delta_G(\theta, t) \leq \frac{Ct^{2\alpha}}{\psi^{-1} \circ \psi^{-1}(t^{2\alpha})}.$$

Theorem 5.1 follows immediately from (5.1), (5.6) and Corollary 4.2.  $\square$

*Proof of Theorem 1.2.* This is basically contained in the proof of Theorem 5.1. In this case, the desired bound (5.6) reads as follows:

$$\delta_G(\theta, t) \leq Ct^{2(1-\frac{1}{s^2})}.$$

The claim follows directly from Corollary 4.2 with  $\alpha = 2(\frac{1}{s^2} - 1)$ .  $\square$

*Proof of Theorem 1.3.* If  $\Omega$  is LLC-1, then Lemma 3.5 implies that  $f^{-1}$  is uniformly Hölder continuous. On the other hand, the duality result implies that  $\mathbb{R}^2 \setminus \overline{\Omega}$  is LLC-2, which is further equivalent to  $\mathbb{R}^2 \setminus \overline{\Omega}$  being John by the results in [22]. Then by the results in [18],  $g$  is also Hölder continuous. Hence  $G^{-1}$  is uniformly Hölder continuous with some exponent  $\alpha$ . Therefore, for  $t$  sufficiently small, we have

$$\begin{aligned} \delta_G(\theta, t) &\leq \max \left\{ \frac{|G(e^{i(\theta+t)}) - G(e^{i\theta})|}{|G(e^{i\theta}) - G(e^{i(\theta-t)})|}, \frac{|G(e^{i\theta}) - G(e^{i(\theta-t)})|}{|G(e^{i(\theta+t)}) - G(e^{i\theta})|} \right\} \\ &\lesssim t^{-1/\alpha}. \end{aligned}$$

The claim follows from Corollary 4.2.  $\square$

## 6. CONCLUDING REMARKS

**6.1. Definition of generalized quasidisks.** This was previously discussed briefly in the introduction. Recall that  $\Omega \subset \mathbb{R}^2$  is a generalized quasidisk if it is the image of the unit disk  $\mathbb{D}$  under a homeomorphism  $f: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  of the entire plane with locally exponentially integrable distortion and  $f$  is conformal in the unit disk  $\mathbb{D}$ . However, this is not natural from the technical point of view since our extended mapping  $\hat{f}$  is the identity outside a compact disk.

On the other hand, from the point view of conformal welding, requiring that  $f$  is identity at infinity is reasonable since it makes the two extension problems equivalent as discussed in Section 4.

From the point view of finding a geometric characterization of generalized quasidisks, this additional requirement is also natural. More precisely, the geometry of a generalized quasidisk  $\Omega \subset \mathbb{R}^n$  should be determined by the geometry of its boundary (at least this is the case if  $\Omega$  is a quasidisk). Intuitively the geometry of  $\partial\Omega$  should have nothing to do with the behavior of the global homeomorphism  $f$  at infinity.

These observations suggest that it is better to require the global homeomorphism  $f$  to be identity at  $\infty$  in the definition of a generalized quasidisk.

**6.2. Inward pointing and outward pointing cusps.** As we already observed, (polynomial) interior cusps are more dangerous than (polynomial) exterior cusps for our extension problems. This is not a big surprise from the technical point of view since our aim is to estimate the scalewise distortion of our conformal welding  $G$ . It is fairly easy to observe that this is closely related to the modulus of continuity of  $G^{-1}$ . On the other hand, combining the duality results in [11] with the global Hölder continuity estimates of conformal mappings in [10, 18], one can immediately see how the role of  $\Omega$  being  $\varphi$ -LC-1 or  $\psi$ -LC-2 is related to the modulus of continuity of  $G$  and  $G^{-1}$ . In fact, this is exactly the way we proved [12, Theorem 4.4].

**6.3. Open problems.** To end the article, we put forward some open problems, which appear reasonable.

**Problem 6.1.** *In Theorem 1.1, can we further relax the control function  $\psi$  to be of the form  $\psi(t) = Ct \log \frac{1}{t}$  ? By the result in [12], we know that the result fails for  $\psi(t) = Ct \log^{1+\delta} \frac{1}{t}$  for any  $\delta > 0$ .*

**Problem 6.2.** *In Theorem 1.3, can we conclude that the extension has better integrability for the distortion, say locally exponentially integrable distortion, if we additionally assume that  $\Omega$  is  $\psi$ -LC-2 for  $\psi(t) = t^s$  with  $s > 1$  ?*

**Problem 6.3.** *If we require reasonable good moduli of continuity for both  $f$ ,  $g$  and their inverses, say both  $f$  and  $g$  are bi-Hölder continuous up to boundary, can we conclude that  $\Omega$  is a generalized quasidisk ?*

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