# Remarks on the Total Variation of the Jacobian 

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The total variation $T V(u)$ of the Jacobian determinant of non-smooth vector fields $u$ has recently been studied in [2]. We focus on the subclass $u(x)=\varphi(x /|x|)$ of homogeneous extensions of smooth functions $\varphi: \partial B^{n} \rightarrow \mathbf{R}^{n}$. In the case $n=2$, we explicitely compute $T V(u)$ for some relevant examples exhibiting a gap with respect to the total variation $|\operatorname{Det} D u|$ of the distributional determinant. We then provide examples of functions with $|\operatorname{Det} D u|=0$ and $T V(u)=+\infty$. We finally show that this gap phenomenon doesn't occur if $n \geq 3$.

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## 1 Introduction and statements

In a recent paper [2], I. Fonseca, N. Fusco and P. Marcellini address the study of the Jacobian determinant $\operatorname{det} D u$ of fields $u: \Omega \rightarrow \mathbf{R}^{n}$ outside the traditional regularity Sobolev space $W^{1, n}\left(\Omega ; \mathbf{R}^{n}\right)$, where $\Omega \subset \mathbf{R}^{n}$ is a fixed open set and $n \geq 2$. We refer to [2] for motivations, applications and related references. More precisely, denote

$$
\operatorname{det} D u(x):=\frac{\partial\left(u^{1}, u^{2}, \ldots, u^{n}\right)}{\partial\left(x_{1}, x_{2}, \ldots, x_{n}\right)}
$$

the Jacobian determinant, i.e., the determinant of the $n \times n$ Jacobian matrix of the gradient $D u=D u(x)$ of a smooth vector-valued map $u: \Omega \rightarrow \mathbf{R}^{n}$, where $u=\left(u^{1}, u^{2}, \ldots, u^{n}\right)$ and $x=\left(x_{1}, \ldots, x_{n}\right)$.

If $u \in W^{1, n}\left(\Omega ; \mathbf{R}^{n}\right)$, since

$$
\begin{equation*}
|\operatorname{det} D u(x)| \leq n^{-n / 2}|D u(x)|^{n}, \tag{1.1}
\end{equation*}
$$

the Jacobian determinant is a function of class $L^{1}(\Omega)$. In this case the set function

$$
\Omega \supset A \mapsto m(A):=\int_{A} \operatorname{det} D u(x) d x
$$

is a measure in $\Omega$, with total variation $|m|$ in $\Omega$ given by

$$
|m|(\Omega):=\int_{\Omega}|\operatorname{det} D u(x)| d x
$$

Under weaker assumptions on $u$, taking account of the integration by part formula after multiplication by a test function, it is possible to consider the distributional determinant

$$
\begin{equation*}
\operatorname{Det} D u:=\sum_{i=1}^{n} \frac{\partial}{\partial x_{i}}\left(u^{1}(\operatorname{adj} D u)_{i}^{1}\right) \tag{1.2}
\end{equation*}
$$

where $\operatorname{adj} D u$ is the matrix of the adjoints of $D u$, so that

$$
(\operatorname{adj} D u)_{i}^{1}:=(-1)^{i+1} \frac{\partial\left(u^{2}, \ldots, u^{n}\right)}{\partial\left(x_{1}, \ldots, x_{i-1}, x_{i+1}, \ldots, x_{n}\right)}
$$

Now, if $u: \Omega \rightarrow \mathbf{R}^{n}$ is a smooth map, by Laplace formula

$$
\begin{align*}
& \sum_{i=1}^{n} \frac{\partial}{\partial x_{i}}\left(u^{1}(\operatorname{adj} D u)_{i}^{1}\right)  \tag{1.3}\\
& =\sum_{i=1}^{n} \frac{\partial u^{1}}{\partial x_{i}}(\operatorname{adj} D u)_{i}^{1}+u^{1} \sum_{i=1}^{n} \frac{\partial}{\partial x_{i}}(\operatorname{adj} D u)_{i}^{1}=\operatorname{det} D u+0 .
\end{align*}
$$

Then, if $u \in W^{1, n}\left(\Omega ; \mathbf{R}^{n}\right)$, by (1.1) and by $W^{1, n}$-density of smooth maps, (1.2) coincides a.e. with the pointwise Jacobian determinant det $D u$. Anyway, (1.2) is well defined e.g. if $u$ is a bounded function in $L^{\infty}\left(\Omega ; \mathbf{R}^{n}\right)$ and the distributional gradient $D u$ is a summable function in the class $L^{n-1}\left(\Omega ; \mathbf{R}^{n^{2}}\right)$. Another possibility to make (1.2) be mathematically precise is to require $u \in W^{1, p}\left(\Omega ; \mathbf{R}^{n}\right)$ for some $p \geq n^{2} /(n+1)$. In this case, in fact, by the Sobolev's embedding theorem $u \in$ $L^{n^{2}}\left(\Omega ; \mathbf{R}^{n}\right)$ whereas $(\operatorname{adj} D u)_{i}^{1} \in L^{n^{2} /\left(n^{2}-1\right)}(\Omega)$. Then, since $L^{n^{2} /\left(n^{2}-1\right)}$ is the dual space to $L^{n^{2}}$, we have

$$
u^{1}(\operatorname{adj} D u)_{i}^{1} \in L^{1}(\Omega) \quad \forall i=1, \ldots, n
$$

Motivated by the study of the relations between the distribution $\operatorname{Det} D u$ and the "total variation" of the Jacobian determinant, given $u \in L_{\text {loc }}^{\infty}\left(\Omega ; \mathbf{R}^{n}\right) \cap$ $W^{1, p}\left(\Omega ; \mathbf{R}^{n}\right)$, the authors in [2] consider the following limit formula

$$
\begin{array}{r}
T V_{p}(u, A):=\inf \left\{\liminf _{j \rightarrow+\infty} \int_{A}\left|\operatorname{det} D u_{k}(x)\right| d x \mid u_{k} \in W^{1, n}\left(A ; \mathbf{R}^{n}\right)\right.  \tag{1.4}\\
\left.u_{k} \rightharpoonup u \quad \text { weakly in } W^{1, p}\left(A ; \mathbf{R}^{n}\right)\right\}
\end{array}
$$

for every open set $A \subset \Omega$. It is obtained by a relaxation procedure in the weak $W^{1, p}$ topology, where $n-1<p<n$, i.e., below the natural growth exponent $n$.

Note that even if a priori definition (1.4) may depend on the choice of $p$, the representation formulas given in [2] turn out to be independent of $p$. Also, for certain classes of functions weak convergence in $W^{1, p}$ may be equivalently replaced by strong convergence in $W^{1, p}$. Moreover, it has been first noted by Malý [7] and by Giaquinta, Modica and Souček [4], see also Jerrard and Soner [6], that for some maps $u \in L^{\infty}\left(\Omega ; \mathbf{R}^{n}\right) \cap W^{1, p}\left(\Omega ; \mathbf{R}^{n}\right)$, with $n-1<p<n$, it may happen that the distribution $\operatorname{Det} D u$ is identically equal to zero whereas the total variation of the Jacobian determinant is different from zero. Finally, when $\operatorname{Det} D u$ is a measure, it turns out that, in general, the total variation of the Jacobian determinant (1.4) is not the total variation of the measure $\operatorname{Det} D u$.

In this paper we focus on a particular subclass of Sobolev functions $u \in$ $L_{\text {loc }}^{\infty}\left(\Omega ; \mathbf{R}^{n}\right) \cap W^{1, p}\left(\Omega ; \mathbf{R}^{n}\right)$, where $n^{2} /(n+1)<p<n$. To this aim, denote by $B_{r}^{n}$ the $n$-ball of radius $r$ centered at the origin, $B^{n}:=B_{1}^{n}$, the unit ball, and by $\partial B_{r}^{n}$ its boundary, so that $S^{n-1}:=\partial B^{n}$ is the unit $(n-1)$-sphere in $\mathbf{R}^{n}$. We will consider the homogeneous extension $u: B^{n} \rightarrow \mathbf{R}^{n}$ of Lipschitz-continuous functions $\varphi: S^{n-1} \rightarrow \mathbf{R}^{n}$, given by

$$
\begin{equation*}
u(x):=\varphi\left(\frac{x}{|x|}\right) . \tag{1.5}
\end{equation*}
$$

Of course $u \in W^{1, p}\left(B^{n} ; \mathbf{R}^{n}\right)$ for every $p<n$ whereas, since the image of $B^{n}$ by $u$ is at most $(n-1)$-dimensional, by the area formula $[3,3.2 .3]$ we have $\operatorname{det} D u(x)=0$ a.e. in $B^{n}$. We stress now that condition $|\operatorname{Det} D u|=0$ is related to a homological property of such maps $u$. In fact, in [5, Vol. I], Sec. 3.2.4, it is given the following result, the proof of which is brought back for the sake of clearness.

Proposition 1.1 If $\varphi_{\#} \llbracket S^{n-1} \rrbracket=0$, then $|\operatorname{Det} D u|=0$.
Proof: following the notation from Geometric measure theory [3], $\llbracket S^{n-1} \rrbracket$ is the ( $n-1$ )-dimensional current in $\mathbf{R}^{n}$ given by integration of $(n-1)$-forms on $S^{n-1}$, equipped with the natural orientation. Also, $\varphi_{\#} \llbracket S^{n-1} \rrbracket$ is the current image via $\varphi$ in the target space $\mathbf{R}^{n}$, or push forward, defined by duality as $\varphi_{\#} \llbracket S^{n-1} \rrbracket(\omega):=$ $\llbracket S^{n-1} \rrbracket\left(\varphi^{\#} \omega\right)$ for every smooth $(n-1)$-form $\omega$ in the target $\mathbf{R}^{n}$. We recall by [5] that the boundary in $B^{n} \times \mathbf{R}^{n}$ of the $n$-current $G_{u}$ carried by the graph of $u$ is given by

$$
\begin{equation*}
\partial G_{u}\left\llcorner B^{n} \times \mathbf{R}^{n}=-\delta_{0} \times \varphi_{\#} \llbracket S^{n-1} \rrbracket,\right. \tag{1.6}
\end{equation*}
$$

where $\delta_{x}$ is the Dirac unit mass centered at $x \in B^{n}$. Hence, if $\varphi_{\#} \llbracket S^{n-1} \rrbracket=0$ we have that the graph $G_{u}$ has no boundary in $B^{n} \times \mathbf{R}^{n}$, i.e., $u$ is a Cartesian map. This corresponds to a series of integration by part formulas which yield, in
particular,

$$
\int_{B^{n}} \sum_{i=1}^{n} D_{i}\left(\phi u^{1}\right)(\operatorname{adj} D u)_{i}^{1} d x=0 \quad \forall \phi \in C_{c}^{1}\left(B^{n}\right)
$$

By (1.2) and (1.3) this gives

$$
-<\operatorname{Det} D u, \phi>+\int_{B^{n}} \phi \operatorname{det} D u d x=\int_{B^{n}} \sum_{i=1}^{n} D_{i}\left(\phi u^{1}\right)(\operatorname{adj} D u)_{i}^{1} d x
$$

and hence the assertion $|\operatorname{Det} D u|=0$, since $\operatorname{det} D u(x)=0$ a.e. in $B^{n}$.
For example, following [7] and [4], if $n=2$ and $\varphi: S^{1} \rightarrow \mathbf{R}^{2}$ is defined by

$$
\varphi(\theta):=\left\{\begin{array}{lll}
(-1+\cos 4 \theta, \sin 4 \theta) & \text { if } & 0 \leq \theta<\pi / 2  \tag{1.7}\\
(1-\cos 4 \theta, \sin 4 \theta) & \text { if } & \pi / 2 \leq \theta<\pi \\
(-1+\cos 4 \theta,-\sin 4 \theta) & \text { if } & \pi \leq \theta<3 \pi / 2 \\
(1-\cos 4 \theta,-\sin 4 \theta) & \text { if } & 3 \pi / 2 \leq \theta<2 \pi
\end{array}\right.
$$

where we identify $[0,2 \pi]$ with $S^{1}$ via $\theta \mapsto(\cos \theta, \sin \theta)$, since the image of $S^{1}$ through $\varphi$ is the boundary of the union of the two unit disks of the target space $\mathbf{R}^{2}$ centered at $(-1,0)$ and $(1,0)$, and $\varphi\left(S^{1}\right)$ is covered twice with opposite orientation, one has $\varphi_{\#} \llbracket S^{1} \rrbracket=0$ and hence $|\operatorname{Det} D u|=0$, by Proposition 1.1.

Most importantly, due to the non-trivial homotopy type of the mapping $\varphi$, it is proved that $u$ cannot be approximated by smooth maps $\left\{u_{k}\right\}$ neither in the strong $W^{1, p}$ topology with $\operatorname{det} D u_{k} \rightarrow \operatorname{det} D u$ in $L^{p}$, if $p<2$, see [7], nor weakly with the mass in the sense of currents, i.e., $G_{u_{k}} \rightharpoonup G_{u}$ and $\mathbf{M}\left(G_{u_{k}}\right) \rightarrow \mathbf{M}\left(G_{u}\right)$, see [4].

In [2], an upper and a lower bound for the total variation of the Jacobian determinant are provided. This formulas allow to compute exactly (1.4) for a large class of functions, but do not comprehend the examples of the type (1.7) or similar ones, in which the geometry of the target space comes into play.

In this note we give a contribution in this direction by proving the following results. In the first one we explicitly compute the gap between $|\operatorname{Det} D u|$ and $T V_{p}\left(u, B^{2}\right)$ in the relevant example (1.7). In the second one we give an example of Sobolev function for which the distributional determinant is zero, whereas the total variation of the Jacobian determinant is $+\infty$. Finally, in the third one we show that this gap phenomenon does not occur in case of dimension $n \geq 3$. This is due to the Hurewicz homomorphism theorem, compare [8], and to the commutativity of the higher order homotopy groups, see Remark 2.2.

Theorem 1.2 If $n=2,4 / 3<p<2, u: B^{2} \rightarrow \mathbf{R}^{2}$ is given by (1.5) and $\varphi: S^{1} \rightarrow \mathbf{R}^{2}$ is defined by (1.7), then for every radius $0<r<1$

$$
\begin{equation*}
T V_{p}\left(u, B_{r}^{2}\right)=2 \omega_{2} \tag{1.8}
\end{equation*}
$$

$\omega_{2}$ being the measure of the unit disk in $\mathbf{R}^{2}$.
Theorem 1.3 If $n=2$ and $4 / 3<p<2$, there exist functions $u \in W^{1, p}\left(B^{2} ; \mathbf{R}^{2}\right)$ such that $|\operatorname{Det} D u|=0$ in $B^{2}$ and $T V_{p}\left(u, B^{2}\right)=+\infty$.

Theorem 1.4 Let $n \geq 3, n^{2} /(n+1)<p<n$ and $u: B^{n} \rightarrow \mathbf{R}^{n}$ be given by (1.5), where $\varphi: S^{n-1} \rightarrow \mathbf{R}^{n}$ is Lipschitz-continuous. Then, if $\varphi_{\#} \llbracket S^{n-1} \rrbracket=0$, we have that $T V_{p}\left(u, B^{n}\right)=0$.

Remark 1.5 The result of Theorem 1.2 has been independently obtained by E. Paolini [10].

## 2 Proofs

We first show that in (1.4) we can actually impose a Dirichlet type condition.
Proposition 2.1 Let $n^{2} /(n+1)<p<n$ and $u: B^{n} \rightarrow \mathbf{R}^{n}$ be given by (1.5), where $\varphi: S^{n-1} \rightarrow \mathbf{R}^{n}$ is Lipschitz-continuous. Then for every $0<r<1$

$$
\begin{align*}
T V_{p}\left(u, B_{r}^{n}\right) & =\inf \left\{\liminf _{j \rightarrow+\infty} \int_{B_{r}^{n}}\left|\operatorname{det} D u_{k}(x)\right| d x \mid u_{k} \in \operatorname{Lip}\left(B_{r}^{n} ; \mathbf{R}^{n}\right)\right.  \tag{2.1}\\
u_{k} & \left.\rightharpoonup u \quad \text { weakly in } W^{1, p}\left(B_{r}^{n} ; \mathbf{R}^{n}\right), \quad u_{k \mid \partial B_{r}^{n}}=u_{\mid \partial B_{r}^{n}}\right\}
\end{align*}
$$

Proof: due to the invariance of $\int|\operatorname{det} D v| d x$ under reparametrization, and to the homogeneity of $u$, it suffices to prove the claim for $r=1$. By (1.1), for every $v \in W^{1, n}\left(B^{n} ; \mathbf{R}^{n}\right)$ we can find in a standard way a sequence $\left\{v_{k}\right\} \subset$ $\operatorname{Lip}\left(B^{n} ; \mathbf{R}^{n}\right)$ converging to $u$ in strong $W^{1, n}$-sense, hence in weak $W^{1, p}$-sense and with $\int_{B^{n}}\left|\operatorname{det} D v_{k}\right| d x \rightarrow \int_{B^{n}}|\operatorname{det} D v| d x$. Then by a diagonal procedure we can suppose $u_{k} \in \operatorname{Lip}\left(B_{r}^{n} ; \mathbf{R}^{n}\right)$ in (1.4). To prove the claim, it then suffices to find, for every given sequence $\left\{u_{k}\right\} \subset \operatorname{Lip}\left(B^{n} ; \mathbf{R}^{n}\right)$ weakly converging to $u$ in $W^{1, p}\left(B^{n} ; \mathbf{R}^{n}\right)$, a sequence $\left\{v_{k}\right\} \subset \operatorname{Lip}\left(B^{n} ; \mathbf{R}^{n}\right)$ weakly converging to $u$ in $W^{1, p}\left(B^{n} ; \mathbf{R}^{n}\right)$, with $v_{k \mid \partial B^{n}}=u_{\mid \partial B^{n}}$, such that

$$
\begin{equation*}
\liminf _{k \rightarrow+\infty} \int_{B^{n}}\left|\operatorname{det} D v_{k}(x)\right| d x \leq \liminf _{k \rightarrow+\infty} \int_{B^{n}}\left|\operatorname{det} D u_{k}(x)\right| d x \tag{2.2}
\end{equation*}
$$

To this aim, denote by $\nu$ and $\tau:=\left(\tau_{1}, \ldots, \tau_{n-1}\right)$ the outward unit normal and an orthonormal basis to the tangent $(n-1)$-space to $\partial B_{\rho}^{n}$, respectively. Then, setting
$D_{\tau} u:=\left(D_{\tau_{1}} u, \ldots, D_{\tau_{n-1}} u\right)$, we have that $|D u|^{2}=\left|D_{\nu} u\right|^{2}+\left|D_{\tau} u\right|^{2}$. Moreover, if $G \in \mathbf{R}^{n N}$ is an $N \times n$ matrix, we denote by $\left|M_{(j)}(G)\right|$ the square root of the sum of the squares of the determinants of all minors of order $j$ of $G$, for $j=1, \ldots, \underline{n}:=$ $\min (n, N)$, and set $\left|M_{(0)}(G)\right|:=1$. If $u_{k} \rightharpoonup u$ weakly in $W^{1, p}\left(B^{n} ; \mathbf{R}^{n}\right)$, and the right-hand side of (2.2) is finite, otherwise there is nothing to prove, possibly passing to a subsequence we can suppose that it is a finite limit. Then $\left|M_{(j)}\left(D u_{k}\right)\right|$ is equibounded in $L^{p / j}\left(B^{n}\right)$ for every $j=1, \ldots, n-1$, whereas $u_{k} \rightarrow u$ strongly in $L^{n^{2}}\left(B^{n}\right)$, by Rellich's theorem. As a consequence, since

$$
\frac{j}{p}+\frac{n-1-j}{p}=\frac{n-1}{p}<\frac{n^{2}-1}{n^{2}} \quad \forall j=0, \ldots, n-1
$$

by duality we obtain

$$
\lim _{k \rightarrow+\infty} \int_{B^{n}}\left|u_{k}-u\right|\left(\sum_{j=0}^{n-1}\left|M_{(j)}\left(D u_{k}\right)\right|\left|M_{(n-1-j)}(D u)\right|\right) d x=0
$$

Setting then

$$
\begin{aligned}
f_{k}(\rho) & :=\int_{\partial B_{\rho}^{n}}\left|u_{k}-u\right|\left(\sum_{j=0}^{n-1}\left|M_{(j)}\left(D_{\tau} u_{k}\right)\right|\left|M_{(n-1-j)}\left(D_{\tau} u\right)\right|\right) d \mathcal{H}^{n-1} \\
g_{k}(\rho) & :=\int_{\partial B_{\rho}^{n}}\left|u_{k}-u\right|^{p} d \mathcal{H}^{n-1} \\
h_{k}(\rho) & :=\int_{\partial B_{\rho}^{n}}\left|D_{\tau} u_{k}\right|^{p} d \mathcal{H}^{n-1}
\end{aligned}
$$

where $\mathcal{H}^{n-1}$ is the ( $n-1$ )-dimensional Hausdorff measure in $\mathbf{R}^{n}$, possibly passing to a subsequence, by the coarea formula $[3,3.2 .12]$ we have

$$
\int_{0}^{1} f_{k}(\rho) d \rho \leq \varepsilon_{k}, \quad \int_{0}^{1} g_{k}(\rho) d \rho \leq \varepsilon_{k} \quad \text { and } \quad \int_{0}^{1} h_{k}(\rho) d \rho \leq C
$$

where $C>0$ is an absolute constant and $\left\{\varepsilon_{k}\right\} \subset(0,1)$ is a decreasing sequence with $\varepsilon_{k} \searrow 0$. Then

$$
\begin{aligned}
& \operatorname{meas}\left(\left\{\rho \in(0,1) \mid f_{k}(\rho) \leq \sqrt{\varepsilon_{k}}\right\}\right) \geq\left(1-\sqrt{\varepsilon_{k}}\right) \\
& \operatorname{meas}\left(\left\{\rho \in(0,1) \mid g_{k}(\rho) \leq \sqrt{\varepsilon_{k}}\right\}\right) \geq\left(1-\sqrt{\varepsilon_{k}}\right), \\
& \operatorname{meas}\left(\left\{\rho \in(0,1) \mid h_{k}(\rho) \leq C / \sqrt{\varepsilon_{k}}\right\}\right) \geq\left(1-\sqrt{\varepsilon_{k}}\right)
\end{aligned}
$$

As a consequence, for $k$ large enough we can find a sequence $\left\{r_{k}\right\} \subset(0,1)$ of radii with $r_{k} \rightarrow 1$ and

$$
\begin{equation*}
0<1-4 \sqrt{\varepsilon_{k}} \leq r_{k} \leq 1-\sqrt{\varepsilon_{k}} \quad \forall k \tag{2.3}
\end{equation*}
$$

for which

$$
\begin{equation*}
f_{k}\left(r_{k}\right) \leq \sqrt{\varepsilon_{k}}, \quad g_{k}\left(r_{k}\right) \leq \sqrt{\varepsilon_{k}} \quad \text { and } \quad h_{k}\left(r_{k}\right) \leq \frac{C}{\sqrt{\varepsilon_{k}}} \tag{2.4}
\end{equation*}
$$

Define now $v_{k}: B^{n} \rightarrow \mathbf{R}^{n}$ by

$$
v_{k}(x):=\left\{\begin{array}{lll}
u_{k}(x) & \text { if } & |x| \leq r_{k} \\
\frac{|x|-r_{k}}{1-r_{k}} u(x)+\frac{1-|x|}{1-r_{k}} u_{k}\left(r_{k} \frac{x}{|x|}\right) & \text { if } & r_{k}<|x|<1
\end{array}\right.
$$

For a.e. $r_{k}<|x|<1$ we have

$$
D_{\nu} v_{k}(x)=\frac{1}{1-r_{k}}\left(u(x)-u_{k}\left(r_{k} \frac{x}{|x|}\right)\right)
$$

and for every $i=1, \ldots, n-1$

$$
D_{\tau_{i}} v_{k}(x)=t D_{\tau_{i}} u(x)+(1-t) D_{\tau_{i}} u_{k}\left(r_{k} \frac{x}{|x|}\right)
$$

for some $0 \leq t \leq 1$. Moreover if $u(x)=v(y), y:=R \frac{x}{|x|}$, we have $D_{\tau_{i}} u(x)=$ $\frac{R}{|x|} D_{\tau_{i}} v(y)$. Hence for a.e. $r_{k}<|x|<1$, writing $\operatorname{det} D v_{k}$ in coordinates $(\nu, \tau)$, and using the Laplace formula, we estimate

$$
\begin{array}{r}
\left|\operatorname{det} D v_{k}(x)\right| \leq \frac{c(n)}{1-r_{k}}\left(\frac{r_{k}}{|x|}\right)^{n-1}\left|u(x)-u_{k}\left(r_{k} \frac{x}{|x|}\right)\right| \times \\
\left(\sum_{j=0}^{n-1}\left|M_{(j)}\left(D_{\tau} u_{k}\left(y_{k}\right)\right)\right|\left|M_{(n-1-j)}\left(D_{\tau} u\left(y_{k}\right)\right)\right|\right)
\end{array}
$$

where $y_{k}(x):=r_{k} \frac{x}{|x|}$. Then by the coarea formula and by changing variables

$$
\int_{B^{n} \backslash B_{r_{k}}^{n}}\left|\operatorname{det} D v_{k}(x)\right| d x \leq c(n) f_{k}\left(r_{k}\right)
$$

which goes to zero by (2.4), so that (2.2) holds. Moreover $\left\{v_{k}\right\} \subset \operatorname{Lip}\left(B^{n} ; \mathbf{R}^{n}\right)$ and $v_{k \mid \partial B^{n}}=u_{\mid \partial B^{n}}$. Finally, to show that $v_{k} \rightharpoonup u$ weakly in $W^{1, p}\left(B^{n} ; \mathbf{R}^{n}\right)$, and conclude with the assertion, since $r_{k}<\rho<1$ yields $1<\rho / r_{k}<2$ for $k$ large, we
readily estimate

$$
\begin{aligned}
& \int_{B^{n} \backslash B_{r_{k}}^{n}}\left|D u_{k}\right|^{p} d x \leq c(p) \int_{B^{n} \backslash B_{r_{k}}^{n}}\left(\left|D_{\nu} u_{k}\right|^{p}+\left|D_{\tau} u_{k}\right|^{p}\right) d x \\
& \leq c(n, p)\left(\left(1-r_{k}\right)^{1-p} g_{k}\left(r_{k}\right)+\left(1-r_{k}\right) h_{k}\left(r_{k}\right)+\left(1-r_{k}\right) \int_{\partial B^{n}}\left|D_{\tau} u\right|^{p} d \mathcal{H}^{n-1}\right)
\end{aligned}
$$

which is equibounded since $r_{k} \rightarrow 1$ and by (2.3) and (2.4)

$$
\left(1-r_{k}\right)^{1-p} g_{k}\left(r_{k}\right) \leq{\sqrt{\varepsilon_{k}}}^{2-p} \quad \text { and } \quad\left(1-r_{k}\right) h_{k}\left(r_{k}\right) \leq 4 C
$$

Proof of Theorem 1.2: first note that if $v: B_{r}^{2} \rightarrow \mathbf{R}^{2}$ is a Lipschitz-continuous function such that $v(x)=u(x)$ for each point $x \in \partial B_{r}^{2}$, then

$$
\begin{equation*}
\int_{B_{r}^{2}}|\operatorname{det} D v(x)| d x \geq 2 \omega_{2} \tag{2.5}
\end{equation*}
$$

In fact, $v_{\mid \partial B_{\rho}^{2}}: \partial B_{\rho}^{2} \rightarrow \mathbf{R}^{2}, \rho \in[0, r]$, defines a 1-parameter continuous family of loops in $\mathbf{R}^{2}$, moving $u_{\mid \partial B_{r}^{2}}$ to one point. Then, by definition of $u$ and by the non-trivial homotopy type of the loop $\varphi_{\mid S^{1}}$, see [8], $v_{\mid B_{r}^{2}}$ must completely cover at least one of the two disks $B^{2}\left(p_{i}, 1\right) \subset \mathbf{R}^{2}, p_{i}:=\left((-1)^{i}, 0\right), i=1,2$. Also, since $v_{\mid \partial B_{r}^{2}}=u_{\mid \partial B_{r}^{2}}$ has index zero with respect to any point of $\mathbf{R}^{2} \backslash \varphi\left(S^{1}\right)$, the multiplicity function of $v$ is at least 2 in each point contained in such disk, see [1]. By the area formula we finally obtain (2.5). As a consequence, by Proposition 2.1 we obtain the lower bound $" \geq "$ in (1.8). To obtain the upper bound $" \leq "$, it suffices to define a weakly approximating smooth sequence $u_{k}: B_{r}^{2} \rightarrow \mathbf{R}^{2}$ such that

$$
\begin{equation*}
\lim _{k \rightarrow+\infty} \int_{B_{r}^{2}}\left|\operatorname{det} D u_{k}\right| d x=2 \omega_{2} \tag{2.6}
\end{equation*}
$$

To this aim, taking polar coordinates $x:=\rho(\cos \theta, \sin \theta)$, we define for each $k \in \mathbf{N}, k>3 / r$,

$$
u_{k}(\rho, \theta):=\left\{\begin{array}{lll}
\varphi(\theta) & \text { if } & 3 / k \leq \rho<r \\
\widetilde{u}_{k}(\rho, \theta) & \text { if } & 2 / k \leq \rho \leq 3 / k \\
\widehat{u}_{k}(\rho, \theta) & \text { if } & 1 / k \leq \rho \leq 2 / k \\
(0,0) & \text { if } & 0 \leq \rho \leq 1 / k
\end{array}\right.
$$

where $\varphi$ is given by (1.7), for $2 / k \leq \rho \leq 3 / k$

$$
\widetilde{u}_{k}(\rho, \theta):=\left\{\begin{array}{lll}
\varphi(\theta) & \text { if } & \theta \in[0, \pi / 2] \cup[\pi, 3 \pi / 2] \\
(k \rho-2) \varphi(\theta) & \text { if } & \theta \in[\pi / 2, \pi] \cup[3 \pi / 2,2 \pi]
\end{array}\right.
$$

and finally for $1 / k \leq \rho \leq 2 / k$

$$
\widehat{u}_{k}(\rho, \theta):= \begin{cases}\varphi(\theta) & \text { if } \quad \theta \in[0,(k \rho-1) \pi / 2] \\ \varphi((k \rho-1) \pi / 2) & \text { if } \quad \theta \in[(k \rho-1) \pi / 2,(4-k \rho) \pi / 2] \\ \varphi(\theta) & \text { if } \quad \theta \in[(4-k \rho) \pi / 2,3 \pi / 2] \\ (0,0) & \text { if } \quad \theta \in[3 \pi / 2,2 \pi]\end{cases}
$$

Clearly $u_{k}: B_{r}^{2} \rightarrow \mathbf{R}^{2}$ is a sequence of Lipschitz continuous functions with $\operatorname{Lip}\left(u_{k}, B_{r}^{2}\right) \leq c / k$ and $u_{k} \equiv u$ in $B_{r}^{2} \backslash B_{3 / k}^{2}$; moreover, since $p<2$, it is not difficult to show that $u_{k} \rightharpoonup u$ weakly in $W^{1, p}\left(B_{r}^{2} ; \mathbf{R}^{2}\right)$. Finally, by the area formula

$$
\int_{B_{3 / k}^{2}}\left|\operatorname{det} D u_{k}(x)\right| d x=\int_{u_{k}\left(B_{3 / k}^{2}\right)} \mathcal{H}^{0}\left(B_{3 / k} \cap u_{k}^{-1}(y)\right) d \mathcal{H}^{2}(y)=2 \omega_{2}
$$

for each $k$, so that (2.6) holds.
Proof of Theorem 1.3: it suffices to define a function $u \in W^{1, p}\left(B^{2} ; \mathbf{R}^{2}\right)$, with 1-dimensional image, such that the current $G_{u}$ carried by its graph has no boundary in $B^{2} \times \mathbf{R}^{2}$ and for which there is a sequence $\left\{B_{j}\right\}$ of pairwise disjoint balls contained in $B^{2}$ such that the restriction $u_{\mid B_{j}}$ behaves like the function of Theorem 1.2, so that $T V_{p}\left(u, B_{j}\right)=2 \omega_{2}$ for every $j$. In fact, arguing as in Proposition 1.1, conditions $\partial G_{u}\left\llcorner B^{2} \times \mathbf{R}^{2}=0\right.$ and $\operatorname{det} D u=0$ will give $|\operatorname{Det} D u|=0$ whereas, by superadditivity of the set function $A \mapsto T V_{p}(u, A)$, we will obtain

$$
T V_{p}\left(u, B^{2}\right) \geq \sum_{j=1}^{+\infty} T V_{p}\left(u, B_{j}\right)=\sum_{j=1}^{+\infty} 2 \omega_{2}=+\infty
$$

To this aim, following an example by [9], we set $B_{j}:=B^{2}\left(c_{j}, 2^{-(j+1)}\right)$, where

$$
c_{j}=\left(-1+\sum_{k=0}^{j-1} 2^{-k}, 0\right), \quad j=1,2, \ldots
$$

Moreover we define $u_{\mid B_{j}}:=u^{(j)}: B_{j} \rightarrow \mathbf{R}^{2}$ by

$$
u^{(j)}(x):=\left\{\begin{array}{lll}
\varphi\left(\frac{x-c_{j}}{\left|x-c_{j}\right|}\right) & \text { if } & j=1,3,5, \ldots \\
\psi\left(\frac{x-c_{j}}{\left|x-c_{j}\right|}\right) & \text { if } & j=2,4,6, \ldots
\end{array}\right.
$$

where $\varphi$ is given by (1.7) and $\psi: S^{1} \rightarrow \mathbf{R}^{2}$ is defined by

$$
\psi(\theta):=\varphi(-\theta+\pi)
$$

If $Q_{j}:=c_{j}+\left[-2^{-(j+1)}, 2^{-(j+1)}\right]^{2}$ denotes the square circumscribing $B_{j}$, we extend $u_{\mid B_{j}}$ to $Q_{j}$ as the continuous map which is constant in the $x_{1}$-variable (note that $Q_{j} \subset B^{2}$ for every $j \geq 1$ ). Then $u \equiv 0$ over all the sides of the boundary of the $Q_{j}$ 's which are parallel to the $x_{1}$-axis, whereas on the sides parallel to the $x_{2}$-axis,

$$
L_{j}^{k}:=c_{j}+\left\{\left((-1)^{k} 2^{-(j+1)}, x_{2}\right) \mid-2^{-(j+1)} \leq x_{2} \leq 2^{-(j+1)}\right\}, \quad k=1,2
$$

$u_{\mid L_{j}^{2}}$ and $u_{\mid L_{j+1}^{1}}$ parametrize the circles $\partial B^{2}\left(p_{i}, 1\right) \subset \mathbf{R}^{2}, p_{i}=\left((-1)^{i}, 0\right), i=1,2$, with the same order and orientation. We can thus define $u$ over the convex hull of $L_{j}^{2}$ and $L_{j+1}^{1}$, the right-hand side of $\partial Q_{j}$ and the left-hand side of $\partial Q_{j+1}$, as the continuous map which is constant along the straight lines connecting the corresponding points in $L_{j}^{2}$ and $L_{j+1}^{1}$ (points on which $u$ takes the same value). We finally define $u$ in the strip connecting $L_{1}^{1}$ to the boundary of $B^{2}$ as the continuous map constant in the $x_{1}$-variable, and set $u \equiv 0$ in the rest of $B^{2}$. Then, it is not difficult to show that $u \in W^{1, p}\left(B^{2} ; \mathbf{R}^{2}\right)$ and that $\operatorname{det} D u=0$ in $B^{2}$, whereas due to the construction

$$
\partial G_{u}\left\llcorner B_{j} \times \mathbf{R}^{2}=-\delta_{c_{j}} \times f_{\#} \llbracket S^{1} \rrbracket,\right.
$$

where $f=\varphi$ if $j$ is odd, $f=\psi$ if $j$ is even, so that since $f_{\#} \llbracket S^{1} \rrbracket=0$ we have $\partial G_{u}\left\llcorner B^{2} \times \mathbf{R}^{2}=0\right.$, as required.

Proof of Theorem 1.4: let $N \geq n, f: S^{n-1} \rightarrow \mathbf{R}^{N}$ be a Lipschitz-continuous function and $T \in \mathcal{R}_{n}\left(\mathbf{R}^{N}\right)$ be an $n$-dimensional integer multiplicity rectifiable current with boundary $\partial T=f_{\#} \llbracket S^{n-1} \rrbracket$. Then, by Thm. 1 and Prop. 1 in [11], for every $\varepsilon>0$ it can be performed a Lipschitz-continuous function $v_{\varepsilon}: B^{n} \rightarrow$ $\mathbf{R}^{N}$ with boundary values $f, v_{\varepsilon \mid \partial B^{n}}=f$, and with $n$-dimensional mapping area comparable to the mass of $T$. In particular, if $N=n$ and $f=\varphi$, this means

$$
\begin{equation*}
\int_{B^{n}}\left|\operatorname{det} D v_{\varepsilon}\right| d x \leq \mathbf{M}(T)+\varepsilon \tag{2.7}
\end{equation*}
$$

Remark 2.2 This result does hold under the condition $n \geq 3$, and it is based on the Hurewicz theorem. Roughly speaking, if $n \geq 3$, a homologically trivial ( $n-1$ )-dimensional cycle of a 1-connected $(n-1)$-skeleton $K$ is homotopically trivial, hence contractible in $K$. Note that Theorem 1.2 actually shows that it is false if $n=2$, simply by taking $T=0$.

Now, since $\varphi_{\#} \llbracket S^{n-1} \rrbracket=0$, we may apply this result, with $T=0$ and $f=\varphi$, and define $u_{k}^{(\varepsilon)}: B^{n} \rightarrow \mathbf{R}^{n}$ by

$$
u_{k}^{(\varepsilon)}(x):=\left\{\begin{array}{lll}
v_{\varepsilon}(k x) & \text { if } & |x|<1 / k \\
u(x) & \text { if } & 1 / k \leq|x|<1
\end{array}\right.
$$

Then by the area formula and (2.7) we have

$$
\int_{B^{n}}\left|\operatorname{det} D u_{k}^{(\varepsilon)}(x)\right| d x=\int_{B_{1 / k}^{n}}\left|\operatorname{det} D v_{\varepsilon}(k x)\right| d x=\int_{B^{n}}\left|\operatorname{det} D v_{\varepsilon}(x)\right| d x \leq \varepsilon
$$

Moreover $u_{k}^{(\varepsilon)} \in \operatorname{Lip}\left(B^{n} ; \mathbf{R}^{n}\right)$ and since

$$
\int_{B_{1 / k}^{n}}\left|D u_{k}^{(\varepsilon)}\right|^{p} d x=k^{p-n} \int_{B^{n}}\left|D v_{\varepsilon}\right|^{p} d x
$$

and $p<n$, we infer that $u_{k}^{(\varepsilon)} \rightharpoonup u$ weakly in $W^{1, p}\left(B^{n} ; \mathbf{R}^{n}\right)$ as $k \rightarrow+\infty$. We then obtain $T V_{p}\left(u, B^{n}\right) \leq \varepsilon$ and hence the assertion, as $\varepsilon \rightarrow 0^{+}$.

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