# FUNCTIONALS DEFINED ON PIECEWISE RIGID FUNCTIONS: INTEGRAL REPRESENTATION AND $\Gamma$-CONVERGENCE 

MANUEL FRIEDRICH AND FRANCESCO SOLOMBRINO


#### Abstract

We analyse integral representation and $\Gamma$-convergence properties of functionals defined on piecewise rigid functions, i.e., functions which are piecewise affine on a Caccioppoli partition where the derivative in each component is constant and lies in a set without rank-one connections. Such functionals account for interfacial energies in the variational modeling of materials which locally show a rigid behavior. Our results are based on localization techniques for $\Gamma$-convergence and a careful adaption of the global method for relaxation [17, 18] to this new setting, under rather general assumptions. They constitute a first step towards the investigation of lower semicontinuity, relaxation, and homogenization for free-discontinuity problems in spaces of (generalized) functions of bounded deformation.


## 1. Introduction

Many problems in materials science, physics, computer science, and other fields involve the minimization of surface energies for configurations which represent partitions of the domain into regions of finite perimeter. Among the vast body of literature, we only mention examples in the direction of liquid crystals [41, phase transition problems in immiscible fluids [13, 53, 54, fracture mechanics [8], image segmentation [55], spin-like lattice systems [1, 2, 21], or polycrystalline structures [27, 40], and refer to the references cited therein.

In the framework of the calculus of variations, these phenomena can be formulated by means of integral functionals defined on Caccioppoli partitions or piecewise constant functions on such partitions, see [11, Section 4.4] or Section 3.1]below for their definition. Problems of this kind have first been studied in the seminal work by Almgren [3]. Later, Ambrosio and Braides [6, 7] carried out a comprehensive analysis by developing a theory of integral representation, compactness, $\Gamma$-convergence, and relaxation. They also addressed the problem of lower semicontinuity which has been further developed over the last years, see, e.g., [11, Section 5.3] or [27, 28, 29]. Recent advances dealing with density and continuity results [15, 56] witness that the study of this class of functionals is of ongoing interest.

Understanding the properties of Caccioppoli partitions is also a mainstay in the analysis of free-discontinuity problems [11, 39] defined on special functions of bounded variation (SBV) (see [11, Section 4]). Indeed, in this context, the study of lower semicontinuity conditions [4, 5], the derivation of integral representation formulas [17, 18, 20, 23], or compactness properties [49] can often be reduced to corresponding problems on partitions. In a similar fashion, homogenization and $\Gamma$-convergence for free-discontinuity problems [23, 25, 26, 51, their approximation [12, 16, 19, 57], as well as results on the existence of quasistatic evolutions [45, 51] rely fundamentally on the

[^0]decoupling of bulk and surface effects, for which a profound understanding of energies defined on piecewise constant functions is necessary.

In the present paper we are interested in analogous problems for functionals defined on piecewise rigid functions, i.e., functions which are piecewise affine on a Caccioppoli partition where the derivative in each component is constant and lies in a set $L$ without rank-one connections [14]. Our standard examples are the rotations $L=S O(d)$ and the space $L=\mathbb{R}_{\text {skew }}^{d \times d}$ of skew symmetric matrices. In the application of materials science, particularly in fracture mechanics, piecewise rigid functions for $L=S O(d)$ can be interpreted as the configurations which may exhibit cracks along surfaces but do not store nonlinear elastic energy. In fact, in 36, a remarkable piecewise rigidity result has been proved showing that the set of these functions coincides with the (seemingly larger) set of functions $u \in S B V$ with approximate gradient $\nabla u \in S O(d)$ almost everywhere. An analogous result holds in the geometrically linear setting $L=\mathbb{R}_{\text {skew }}^{d \times d}$ for functions in the space $(G) S B D$ of (generalized) special functions of bounded deformation, introduced in [10, 38. In the context of fracture mechanics, these results imply that a deformation of a cracked hyperelastic (respectively, linearly elastic) body does not store elastic energy if and only if it is piecewise rigid. Thus, interfacial energies of materials which show locally rigid behavior in different regions of the body can be naturally modeled by functionals defined on piewise rigid functions.

However, our primary purpose comes from the study of free-discontinuity problems defined on the space $G S B D^{p}$, see [38], which has obtained steadily increasing attention over the last years, cf., e.g., [30, 31, 32, 33, 34, 35, 46, 47, 48, 50. We have indeed already mentioned before how the analysis of partition problems has proved to be a relevant tool in the study of freediscontinuity problems on $S B V$. When coming to similar problems on $G S B D^{p}$, where only a control on the symmetrized gradient of the competitors is available, a larger space than piecewise constant functions must be taken into account in order, e.g., to provide lower semicontinuity conditions for surface integrands, or representation formulas for $\Gamma$-limits, and, in general, to deal with the issues that we mentioned above in the $S B V$ context. In our opinion, it is quite natural to expect that the understanding of energies defined on piecewise rigid functions for $L=\mathbb{R}_{\text {skew }}^{d \times d}$ represents a significant first step (or maybe even the building block) of such a research program.

In this first paper on this topic, we investigate integral representation and $\Gamma$-convergence for functionals defined on piecewise rigid functions. Lower semicontinuity, homogenization, and relaxation will be carried out in a forthcoming paper. We now proceed by describing our setting in more detail.

Let $L \subset \mathbb{R}^{d \times d}$ be a closed set of rigid matrices not satisfying the Hadamard compatibility condition (equivalently, having no rank-one connections between each other, see [14]), for which a locally Bilipschitz parametrization exists, see 2.2 below for details. The condition of no rank-one connections is needed to ensure that functions exhibit discontinuities along the interface of two components with different constant derivative in $L$. This rules out the formation of laminates. The local Bilipschitz parametrization allows us to treat the matrices $L$ as a subset of a linear space instead of a manifold, cf. the case $L=S O(d)$. For $\Omega \subset \mathbb{R}^{d}$ open and bounded, we denote by $P R_{L}(\Omega)$ the set of piecewise rigid functions $u$, i.e.,

$$
\begin{equation*}
u(x)=\sum_{j \in \mathbb{N}}\left(Q_{j} x+b_{j}\right) \chi_{P_{j}}(x) \tag{1.1}
\end{equation*}
$$

where $\left(P_{j}\right)_{j \in \mathbb{N}}$ is a Caccioppoli partition of $\Omega, Q_{j} \in L$, and $b_{j} \in \mathbb{R}^{d}$ for all $j \in \mathbb{N}$. For open subsets $A \subset \Omega$, we consider functionals $\mathcal{F}(\cdot, A): P R_{L}(\Omega) \rightarrow[0, \infty)$ of the form

$$
\begin{equation*}
\mathcal{F}(u, A)=\int_{J_{u} \cap A} f\left(x,[u](x), \nu_{u}(x)\right) d \mathcal{H}^{d-1}(x) \tag{1.2}
\end{equation*}
$$

where by $[u]$ and $\nu_{u}$ we denote the jump height and a normal to the jump (i.e., a normal to the interface), respectively, and $f$ represents an interfacial energy density which may additionally depend on the material point $x$.

We are interested in the problem if, for a sequence of functionals $\left(\mathcal{F}_{n}\right)_{n}$ with densities $\left(f_{n}\right)_{n}$, an effective limiting problem exists in the sense of variational convergence ( $\Gamma$-convergence). Then, it is a natural question if also the $\Gamma$-limit is of the form (1.2). In this context, a standard procedure relies on localization techniques for $\Gamma$-convergence (see [37]), i.e., passing to a $\Gamma$-limit $\mathcal{F}(\cdot, A)$ of the sequence $\mathcal{F}_{n}(\cdot, A)$ for every open $A \subset \Omega$. Afterwards, one shows that under certain conditions for $\mathcal{F}(\cdot, A)$, including suitable semicontinuity, locality, and measure theoretic properties, there exists an integral representation for $\mathcal{F}(\cdot, A)$ in the sense of 1.2 .

An approach in this spirit has been performed in 6] for finitely valued piecewise constant functions, i.e., for functions of the form (1.1) with $Q_{j}=0$ and $b_{j} \in K$ for a finite set $K \subset \mathbb{R}^{d}$. $\Gamma$-convergence and integral representation are guaranteed under the natural growth conditions $0<\alpha \leq f_{n}(x, \xi, \nu) \leq \beta$ and a uniform continuity condition $x \mapsto f_{n}(x, \xi, \nu)$ along the sequence of densities $\left(f_{n}\right)_{n}$, which are maintained in the $\Gamma$-limit. Later, for the problem of integral representation (but not for $\Gamma$-convergence), the continuity assumption in $x$ has been dropped in 17, Theorem 3], and, under a continuity condition $\xi \mapsto f(x, \xi, \nu)$, the result has been generalized to $K=\mathbb{R}^{d}$ in 20, Theorem 3.2]. In the present paper, under similar growth and continuity conditions, we derive analogous results for $P R_{L}(\Omega)$ in place of piecewise constant functions. As a byproduct, choosing $L=\{0\}$, we also generalize the above mentioned $\Gamma$-convergence results to the case $K=\mathbb{R}^{d}$.

We now give a more thorough outline of our proof strategy and provide a comparison with [6]. First, concerning integral representation, we follow the global method for relaxation developed in [17, 18, which essentially consists in comparing asymptotic Dirichlet problems on small balls with different boundary data depending on the local properties of $u$. For $\Gamma$-convergence, we apply the localization techniques described above, see e.g. [22, 37].

For both methods, the key ingredient is a construction for joining two functions $u, v \in P R_{L}(\Omega)$, which is usually called the fundamental estimate. Typically, this is achieved by means of a cut-off construction of the form $w:=u \varphi+(1-\varphi) v$ for some smooth $\varphi$ with $0 \leq \varphi \leq 1$. In the present context, however, a crucial problem has to be faced since in general $w$ is not in $P R_{L}(\Omega)$. In the case of piecewise constant functions, this issue was solved in [6] by using the coarea formula in $B V$, see [6, Lemma 4.4], which allows to approximate $w$ by a piecewise constant function $\tilde{w}$. Geometrically, the joining of $u$ and $v$ to $\tilde{w}$ consists in modifying the partitions and adding additional interface whose length is controlled by $d(u, v)$, where $d(u, v)$ is a suitable metric on the space. The same strategy cannot be pursued in the present context: e.g., when $L=\mathbb{R}_{\text {skew }}^{d \times d}$, we have $P R_{L}(\Omega) \subset S B D(\Omega)$, where no analog of the coarea formula is known to hold. (We refer to [48] for more details in that direction.)

Our main trick is the following: we apply the coarea formula twice, once for the functions themselves and once for their derivatives. Roughly speaking, this allows to join two functions $u, v \in P R_{L}(\Omega)$ by adding additional interface whose length is controlled in terms of $d(u, v)$ and $d_{\nabla}(\nabla u, \nabla v)$ for suitable metrics $d$ and $d_{\nabla}$. Unfortunately, the metric $d_{\nabla}$ is too strong and not compatible with the available compactness results. Therefore, we apply this construction only on components $P_{j}$ in 1.1 whose volume is 'not too small' since on such sets the derivative of an affine mapping can be controlled in terms of the mapping itself by elementary arguments (cf. Lemma 3.4. This in turn allows to control $d_{\nabla}(\nabla u, \nabla v)$ in terms of $d(u, v)$ on such components. On the other components (i.e., those having small volume), we introduce additional interface by a direct geometrical construction, see Lemma 4.7. This strategy leads to a fundamental estimate in $P R_{L}(\Omega)$, see Lemma 4.1. Under an additional technical condition, see (4.6), we are able to
provide also a refined version of this result in Lemma 4.5 where boundary values are preserved. This is instrumental for the application to the global method of relaxation.

Apart from the fundamental estimate, we encounter another technical difficulty with respect to other integral representation results [17, 18, 20, 35]. There, at least as an intermediate step, one may consider growth conditions of the form

$$
\alpha \mathcal{H}^{d-1}\left(J_{u} \cap A\right)+\alpha^{\prime} \int_{J_{u} \cap A}|[u]| d \mathcal{H}^{d-1} \leq \mathcal{F}(u, A) \leq \beta \mathcal{H}^{d-1}\left(J_{u} \cap A\right)+\beta^{\prime} \int_{J_{u} \cap A}|[u]| d \mathcal{H}^{d-1}
$$

for $0<\alpha \leq \beta$ and $0<\alpha^{\prime} \leq \beta^{\prime}$. The lower bound allows to apply compactness results in $S B V$. In the present context, however, we are forced to work with $\alpha^{\prime}=\beta^{\prime}=0$ since in the construction of the fundamental estimate we control only the length of the added interface but not the modification of the jump heights. Thus, more delicate arguments are necessary to obtain suitable compactness results and, as a consequence, convergence of minima for asymptotic Dirichlet problems, see Lemma 6.3 and Lemma 7.5 . The latter is not only of general interest, but in particular instrumental to show that the uniform continuity condition $\xi \mapsto f_{n}(x, \xi, \nu)$ along the sequence of densities $\left(f_{n}\right)_{n}$ is maintained in the $\Gamma$-limit, see 6.10 . These arguments are based on novel truncation techniques, see Section 7.1 , which are inspired by the recent work 49 where compactness results for freediscontinuity problems on $(G) S B V^{p}$ have been derived in a very general sense.

Finally, let us briefly compare our result for $L=\mathbb{R}_{\text {skew }}^{2 \times 2}$ with the integral representation in $S B D^{p}$, $p>1$, in dimension two, proved in [35]. Although in this specific case our functionals are defined on a subspace of $(G) S B D^{p}$, our result is not merely a simple consequence of [35] since there is in general no obvious way to extend a functional from $P R_{L}$ to $(G) S B D^{p}$. Indeed, as explained above, the issue of joining two functions is more delicate in the present context and calls for novel versions of a fundamental estimate.

The paper is organized as follows. In Section 2 we introduce our setting and present our main results about integral representation and $\Gamma$-convergence. Section 3 is devoted to preliminaries about Caccioppoli partitions and (piecewise) rigid functions. In Section 4 we formulate and prove the fundamental estimate. Here, we also present a refinement preserving boundary values and a scaled version on small balls. Section 5 and Section 6 are devoted to the proofs of the integral representation and the $\Gamma$-convergence result, respectively. Finally, Section 7 discusses the examples $L=S O(d), L=\mathbb{R}_{\text {skew }}^{d \times d}$ and introduces a truncation method which is instrumental for the convergence of minima for asymptotic Dirichlet problems.

## 2. The setting and main Results

Notation: Throughout the paper $\Omega \subset \mathbb{R}^{d}$ is open, bounded with Lipschitz boundary. Let $\mathcal{A}(\Omega)$ be the family of open subsets of $\Omega$, and $\mathcal{A}_{0}(\Omega) \subset \mathcal{A}(\Omega)$ be the subset of sets with regular boundary. By $\mathcal{B}(\Omega)$ we denote the family of Borel sets contained in $\Omega$. By $\omega_{m}$ we denote the $m$-dimensional measure of the unit ball in $\mathbb{R}^{m}$. The symbol $B_{R}(x)$ will denote a ball of radius $R$ centered at $x$ in an Euclidian space. The notations $\mathcal{L}^{d}$ and $\mathcal{H}^{d-1}$ are used for the Lebesgue measure, and the $(d-1)$-dimensional Hausdorff measure in $\mathbb{R}^{d}$, respectively. For a $\mathcal{L}^{d}$-measurable set $E \subset \mathbb{R}^{d}$, the symbol $\chi_{E}$ denotes its characteristic function. For $A, B \in \mathcal{A}(\Omega)$ with $\bar{B} \subset A$, we write $B \subset \subset A$.

Jump set: If $u: \Omega \rightarrow \mathbb{R}^{d}$ is a $\mathcal{L}^{d}$-measurable function, $u$ is said to have an approximate limit $a \in \mathbb{R}^{d}$ at a point $x \in \Omega$ if and only if

$$
\lim _{\varrho \rightarrow 0^{+}} \frac{\mathcal{L}^{d}\left(\{|u-a| \geq \varepsilon\} \cap B_{\varrho}(x)\right)}{\varrho^{d}}=0 \text { for every } \varepsilon>0
$$

In this case, one writes ap $\lim _{y \rightarrow x} u(y)=a$. The approximate jump set $J_{u}$ is defined as the set of points $x \in \Omega$ such that there exist $a \neq b \in \mathbb{R}^{d}$ and $\nu \in S^{d-1}:=\left\{\xi \in \mathbb{R}^{d}:|\xi|=1\right\}$ with

$$
\text { ap } \lim _{\substack{y \rightarrow x \\\langle y-x, \nu\rangle>0}} u(y)=a \quad \text { ap } \lim _{\substack{y \rightarrow x \\\langle y-x, \nu\rangle<0}} u(y)=b \text {. }
$$

The triplet $(a, b, \nu)$ is uniquely determined up to a permutation of $(a, b)$ and a change of sign of $\nu$, and is denoted by $\left(u^{+}(x), u^{-}(x), \nu_{u}(x)\right)$. The jump of $u$ is the function $[u]: J_{u} \rightarrow \mathbb{R}^{d}$ defined by $[u](x):=u^{+}(x)-u^{-}(x)$ for every $x \in J_{u}$.

Set of rigid matrices: We consider a closed subset $L \subset \mathbb{R}^{d \times d}$ with the following two properties: First, each pair of matrices in $L$ does not satisfy the Hadamard compatibility condition (see [14]), i.e., there holds

$$
\begin{equation*}
\operatorname{rank}\left(Q_{1}-Q_{2}\right) \geq 2 \quad \text { for all } Q_{1}, Q_{2} \in L, \quad Q_{1} \neq Q_{2} \tag{2.1}
\end{equation*}
$$

Moreover, we suppose that, roughly speaking, there exists a locally Bilipschitz parametrization of $L$. More precisely, we suppose that there exist constants $d_{L} \in \mathbb{N}, 0<c_{L}<1, C_{L}>0, r_{L} \in(0,+\infty]$, and a surjective Lipschitz mapping $\Psi_{L}:\left(-r_{L}, r_{L}\right)^{d_{L}} \rightarrow L$ with Lipschitz constant $C_{L}$ such that, for each $Q \in L$, there exists a right inverse mapping $\Xi_{L}: B_{c_{L} r_{L}}(Q) \cap L \rightarrow\left(-r_{L}, r_{L}\right)^{d_{L}}$ of $\Psi_{L}$ satisfying

$$
\begin{equation*}
\left|\Xi_{L}\left(Q_{1}\right)-\Xi_{L}\left(Q_{2}\right)\right| \leq C_{L}\left|Q_{1}-Q_{2}\right| \quad \text { for all } Q_{1}, Q_{2} \in B_{c_{L} r_{L}}(Q) \cap L \tag{2.2}
\end{equation*}
$$

In particular, $r_{L}=\infty$ is admissible. In this case, we use the convention $c_{L} r_{L}=\infty$, which means that $\Psi_{L}$ has a globally Lipschitz right inverse $\Xi_{L}$ defined on all of $L$. If instead $r_{L}<+\infty$ (that is, $L$ is compact), it suffices that a Lipschitz right inverse is defined on small balls around each point having uniform radius, and that its Lipschitz constant is uniformly bounded by $C_{L}$.

It is well-known that property 2.1 is satisfied for $L=\mathbb{R}_{\text {skew }}^{d \times d}$ as well as for $L=S O(d)$. Property (2.2) is immediate in the case $L=\mathbb{R}_{\text {skew }}^{d \times d}$ since it suffices to define $\Psi_{L}$ as the canonical isomorphism between $\mathbb{R}^{\frac{d(d-1)}{2}}$ and $\mathbb{R}_{\text {skew }}^{d \times d}$, which is bijective and Bilipschitz. Actually, property $(2.2)$ is also satisfied for $L=S O(d)$, when $d=2$ or $d=3$.
Proposition 2.1. Let $d=2$, or $d=3$. Then, the set $L=S O(d)$ complies with property 2.2 .
This fact, although based on standard representation properties of rotation matrices, seems to be nontrivial to us. For the reader's convenience, we will thus give a proof below in Appendix A.

Piecewise rigid functions: We introduce the space of piecewise rigid functions by

$$
\begin{align*}
P R_{L}(\Omega):= & \left\{u: \Omega \rightarrow \mathbb{R}^{d} \mathcal{L}^{d} \text {-measurable: } u(x)=\sum_{j \in \mathbb{N}}\left(Q_{j} x+b_{j}\right) \chi_{P_{j}}(x),\right. \\
& \text { where } \left.Q_{j} \in L, b_{j} \in \mathbb{R}^{d}, \text { and }\left(P_{j}\right)_{j} \text { is a Caccioppoli partition of } \Omega\right\} . \tag{2.3}
\end{align*}
$$

Here and henceforth, we will call an affine mapping of the form $q_{Q, b}(x):=Q x+b$ with $Q \in L$ and $b \in \mathbb{R}^{d}$ a rigid motion. It follows from the properties of Caccioppoli partitions, see Section 3.1, that for each $u \in P R_{L}(\Omega)$ we have that $\mathcal{H}^{d-1}\left(J_{u} \backslash \bigcup_{j} \partial^{*} P_{j}\right)=0$ and thus $\mathcal{H}^{d-1}\left(J_{u}\right)<+\infty$. We equip $P R_{L}(\Omega)$ with the topology induced by measure convergence on $\Omega$.

When $L=\mathbb{R}_{\text {skew }}^{d \times d}$, one can equivalently characterize $P R_{L}(\Omega)$ as the subspace of $G S B D$ functions (see [38]) whose symmetrized approximate gradient $e(u)$ equals zero $\mathcal{L}^{d}$-almost everywhere. For a proof we refer to [36, Theorem A.1] and [48, Remark 2.2(i)]. In a similar fashion, in the case $L=S O(d), P R_{L}(\Omega)$ coincides with the $G S B V$ functions whose approximate gradient satisfies $\nabla u(x) \in S O(d)$ for $\mathcal{L}^{d}$-a.e. $x \in \Omega$, see [36].

Functionals: We consider functionals $\mathcal{F}: P R_{L}(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ with the following general assumptions:
$\left(\mathrm{H}_{1}\right) \mathcal{F}(u, \cdot)$ is a Borel measure for any $u \in P R_{L}(\Omega)$,
$\left(\mathrm{H}_{2}\right) \mathcal{F}(\cdot, A)$ is lower semicontinuous with respect to convergence in measure on $\Omega$ for any $A \in \mathcal{A}(\Omega)$,
$\left(\mathrm{H}_{3}\right) \mathcal{F}(\cdot, A)$ is local for any $A \in \mathcal{A}(\Omega)$, in the sense that, if $u, v \in P R_{L}(\Omega)$ satisfy $u=v$ a.e. in $A$, then $\mathcal{F}(u, A)=\mathcal{F}(v, A)$,
$\left(\mathrm{H}_{4}\right)$ there exist $0<\alpha<1$ and $\beta \geq 1$ such that for any $u \in P R_{L}(\Omega)$ and $B \in \mathcal{B}(\Omega)$,

$$
\alpha \mathcal{H}^{d-1}\left(J_{u} \cap B\right) \leq \mathcal{F}(u, B) \leq \beta \mathcal{H}^{d-1}\left(J_{u} \cap B\right)
$$

$\left(\mathrm{H}_{5}\right)$ there exists an increasing modulus of continuity $\sigma:[0,+\infty) \rightarrow[0, \beta]$ with $\sigma(0)=0$ such that for any $u, v \in P R_{L}(\Omega)$ and $S \in B(\Omega)$ with $S \subset J_{u} \cap J_{v}$ we have

$$
|\mathcal{F}(u, S)-\mathcal{F}(v, S)| \leq \int_{S} \sigma(|[u]-[v]|) d \mathcal{H}^{d-1}
$$

where we choose the orientation $\nu_{u}=\nu_{v}$ on $J_{u} \cap J_{v}$.
We remark that $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{3}\right)$ are standard assumptions, see [6, 17, 20, 24, 35]. In these results, the growth condition in $\left(\mathrm{H}_{4}\right)$ is replaced by one of the form $\int_{J_{u}}(1+|[u]|) d \mathcal{H}^{d-1}$ from below and above. Our growth assumption from below is more relevant for fracture models and the growth assumption from above is instrumental for our fundamental estimate proved in Section 4 However, it comes at the expense of more elaborated compactness arguments and the fact that we need to consider functionals defined on measurable, but possibly not integrable functions. A continuity condition of the form $\left(\mathrm{H}_{5}\right)$ was also used, e.g., in [20, 23].

Main results: We now formulate the first main result of this article addressing integral representation of functionals $\mathcal{F}$ satisfying $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{5}\right)$. To this end, we introduce some further notation: for every $u \in P R_{L}(\Omega)$ and $A \in \mathcal{A}(\Omega)$ we define

$$
\begin{equation*}
\mathbf{m}_{\mathcal{F}}(u, A)=\inf _{v \in P R_{L}(\Omega)}\{\mathcal{F}(v, A): v=u \text { in a neighborhood of } \partial A\} \tag{2.4}
\end{equation*}
$$

and for $x_{0} \in \Omega, \xi \in \mathbb{R}^{d}$, and $\nu \in S^{d-1}$ we introduce the functions

$$
u_{x_{0}, \xi, \nu}(x)= \begin{cases}0 & \text { if }\left\langle x-x_{0}, \nu\right\rangle>0  \tag{2.5}\\ \xi & \text { if }\left\langle x-x_{0}, \nu\right\rangle<0\end{cases}
$$

Theorem 2.2 (Integral representation). Let $\Omega \subset \mathbb{R}^{d}$ be open, bounded with Lipschitz boundary and $\mathcal{F}: P R_{L}(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ be such that $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{5}\right)$ hold. Then

$$
\begin{equation*}
\mathcal{F}(u, B)=\int_{J_{u} \cap B} f\left(x,[u](x), \nu_{u}(x)\right) d \mathcal{H}^{d-1}(x) \tag{2.6}
\end{equation*}
$$

for all $u \in P R_{L}(\Omega), B \in \mathcal{B}(\Omega)$, where $f$ is given by

$$
\begin{equation*}
f\left(x_{0}, \xi, \nu\right)=\limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u_{x_{0}, \xi, \nu}, B_{\varepsilon}(x)\right)}{\omega_{d-1} \varepsilon^{d-1}} \tag{2.7}
\end{equation*}
$$

for all $x_{0} \in \Omega, \xi \in \mathbb{R}^{d}$, and $\nu \in S^{d-1}$.
The second main theorem addresses $\Gamma$-convergence of functionals $\mathcal{F}$ satisfying $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{3}\right)-$ $\left(\mathrm{H}_{5}\right)$. For an exhaustive treatment of $\Gamma$-convergence we refer to [22, 37].
Theorem 2.3 ( $\Gamma$-convergence). Let $\Omega \subset \mathbb{R}^{d}$ open, bounded with Lipschitz boundary. Let $\mathcal{F}_{n}$ : $P R_{L}(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ be a sequence of functionals satisfying $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{5}\right)$ for the same $0<\alpha<\beta$ and $\sigma:[0,+\infty) \rightarrow[0, \beta]$. Then there exists $\mathcal{F}: P R_{L}(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ satisfying $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$ and a subsequence (not relabeled) such that

$$
\mathcal{F}(\cdot, A)=\Gamma-\lim _{n \rightarrow \infty} \mathcal{F}_{n}(\cdot, A) \quad \text { with respect to convergence in measure on } A
$$

for all $A \in \mathcal{A}_{0}(\Omega)$. Moreover, if there holds

$$
\begin{equation*}
\limsup _{n \rightarrow \infty} \mathbf{m}_{\mathcal{F}_{n}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right) \leq \mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right) \leq \sup _{0<\varepsilon^{\prime}<\varepsilon} \liminf _{n \rightarrow \infty} \mathbf{m}_{\mathcal{F}_{n}}\left(u, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right) \tag{2.8}
\end{equation*}
$$

for all $u \in P R_{L}(\Omega)$ and each ball $B_{\varepsilon}\left(x_{0}\right) \subset \Omega$, then $\mathcal{F}$ satisfies also $\left(\mathrm{H}_{5}\right)$ and admits the representation 2.6-2.7.

We note that condition (2.8) can be verified for $L=\mathbb{R}_{\text {skew }}^{d \times d}$ and $L=S O(d), d=2,3$, see Section 7. Theorem 2.2 and Theorem 2.3 will be proved in Section 5 and Section 6, respectively. The key ingredient for both results, namely a fundamental estimate in $P R_{L}(\Omega)$, is addressed in Section 4 From now on we drop the index $L$ and write $P R(\Omega)$ instead of $P R_{L}(\Omega)$ if now confusion arises.

## 3. Preliminaries

3.1. Caccioppoli partitions. We say that a partition $\mathcal{P}=\left(P_{j}\right)_{j}$ of an open set $\Omega \subset \mathbb{R}^{d}, d \geq 2$, is a Caccioppoli partition of $\Omega$ if $\sum_{j} \mathcal{H}^{d-1}\left(\partial^{*} P_{j}\right)<+\infty$, where $\partial^{*} P_{j}$ denotes the essential boundary of $P_{j}$ (see [11, Definition 3.60]). Moreover, by $\left(P_{j}\right)^{1}$ we denote the points where $P_{j}$ has density one (see again [11, Definition 3.60]). By definition, the sets $\left(P_{j}\right)^{1}$ and $\partial^{*} P_{j}$ are Borel measurable. The local structure of Caccioppoli partitions can be characterized as follows (see [11, Theorem 4.17]).

Theorem 3.1 (Local structure). Let $\left(P_{j}\right)_{j}$ be a Caccioppoli partition of $\Omega$. Then

$$
\bigcup_{j}\left(P_{j}\right)^{1} \cup \bigcup_{i \neq j}\left(\partial^{*} P_{i} \cap \partial^{*} P_{j}\right)
$$

contains $\mathcal{H}^{d-1}$-almost all of $\Omega$.
Essentially, the theorem states that $\mathcal{H}^{d-1}$-a.e. point of $\Omega$ either belongs to exactly one element of the partition or to the intersection of exactly two sets $\partial^{*} P_{i}, \partial^{*} P_{j}$. We say that a partition is ordered if $\mathcal{L}^{d}\left(P_{i}\right) \geq \mathcal{L}^{d}\left(P_{j}\right)$ for $i \leq j$. Moreover, we say that a set of finite perimeter $P_{j}$ is indecomposable if it cannot be written as $P^{1} \cup P^{2}$ with $P^{1} \cap P^{2}=\emptyset, \mathcal{L}^{d}\left(P^{1}\right), \mathcal{L}^{d}\left(P^{2}\right)>0$ and $\mathcal{H}^{d-1}\left(\partial^{*} P_{j}\right)=\mathcal{H}^{d-1}\left(\partial^{*} P^{1}\right)+\mathcal{H}^{d-1}\left(\partial^{*} P^{2}\right)$. We state a compactness result for ordered Caccioppoli partitions. (See [11, Theorem 4.19, Remark 4.20] or [50, Theorem 2.8] for the slightly adapted version presented here.)

Theorem 3.2 (Compactness). Let $\Omega \subset \mathbb{R}^{d}$ be a bounded Lipschitz domain. Let $\mathcal{P}_{i}=\left(P_{j, i}\right)_{j}$, $i \in \mathbb{N}$, be a sequence of ordered Caccioppoli partitions of $\Omega$ with

$$
\sup _{i \geq 1} \sum_{j} \mathcal{H}^{d-1}\left(\partial^{*} P_{j, i}\right)<+\infty
$$

Then there exists a Caccioppoli partition $\left(P_{j}\right)_{j}$ of $\Omega$ and a subsequence (not relabeled) such that $\sum_{j} \mathcal{L}^{d}\left(P_{j, i} \triangle P_{j}\right) \rightarrow 0$ as $i \rightarrow \infty$, where $P_{j, i} \triangle P_{j}=\left(P_{j, i} \backslash P_{j}\right) \cup\left(P_{j} \backslash P_{j, i}\right)$.
3.2. Properties of rigid and piecewise rigid functions. Recall the function space $P R(\Omega)$ introduced in 2.3), and the fact that each $u \in P R(\Omega)$ can be written as $u=\sum_{j} q_{j} \chi_{P_{j}}$, where $\left(P_{j}\right)_{j}$ is a Caccioppoli partition of $\Omega$ and $\left(q_{j}\right)_{j}$ are rigid motions, i.e., $q_{j}(x)=Q_{j} x+b_{j}$ with $Q_{j} \in L$ and $b_{j} \in \mathbb{R}^{d}$. We point out that the representation of $u$ is not unique. In the following, we will use two specific representations of $u$ : (a) We say that the representation is pairwise distinct if all affine mappings $\left(q_{j}\right)_{j}$ are pairwise different. In this case, we observe by 2.1) that

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(J_{u} \triangle\left(\bigcup_{j \in \mathbb{N}} \partial^{*} P_{j} \backslash \partial \Omega\right)\right)=0 \tag{3.1}
\end{equation*}
$$

(b) We say that the representation is indecomposable if each $P_{j}$ is a indecomposable set of finite perimeter and we have

$$
\mathcal{H}^{d-1}\left(\partial^{*} P_{i} \cap \partial^{*} P_{j}\right)>0 \text { for } i \neq j \quad \Rightarrow \quad q_{i} \neq q_{j} .
$$

Note that for such representations there also holds by 2.1

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(J_{u} \triangle\left(\bigcup_{j \in \mathbb{N}} \partial^{*} P_{j} \backslash \partial \Omega\right)\right)=0 \tag{3.2}
\end{equation*}
$$

An indecomposable representation can be deduced from a piecewise distinct representation by splitting each $P_{j}$ uniquely into its connected components, i.e., into a countable family of pairwise disjoint, indecomposable sets, see [9, Theorem 1]. We start by a compactness result in $P R(\Omega)$.

Lemma 3.3 (Compactness and lower semicontinuity). Let $\Omega \subset \mathbb{R}^{d}$ be open, bounded with Lipschitz boundary.
(i) Let $\left(u_{n}\right)_{n} \subset P R(\Omega)$ be a sequence with $\sup _{n} \int_{\Omega} \psi\left(\left|u_{n}\right|\right)+\mathcal{H}^{d-1}\left(J_{u_{n}}\right)<+\infty$, where $\psi$ : $[0, \infty) \rightarrow[0, \infty)$ is continuous, strictly increasing, and satisfies $\lim _{t \rightarrow \infty} \psi(t)=+\infty$. Then there exist $u \in P R(\Omega)$ and a subsequence (not relabeled) such that $u_{n} \rightarrow u$ in measure.
(ii) Given $\left(u_{n}\right)_{n} \subset P R(\Omega)$ with $u_{n} \rightarrow u$ in measure, there holds $\mathcal{H}^{d-1}\left(J_{u}\right) \leq \liminf _{n \rightarrow \infty} \mathcal{H}^{d-1}\left(J_{u_{n}}\right)$.

The proof of the above compactness result relies on 2.1, as well as on the following auxiliary result, which will be used several times in the sequel.
Lemma 3.4. Let $G \in \mathbb{R}^{d \times d}, b \in \mathbb{R}^{d}$. Let $\delta>0, R>0$, and let $\psi: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$be a continuous, strictly increasing function with $\psi(0)=0$. Consider a measurable, bounded set $E \subset \mathbb{R}^{d}$ with $E \subset B_{R}(0)$ and $\mathcal{L}^{d}(E) \geq \delta$. Then there exists a continuous, strictly increasing function $\tau_{\psi}:$ $\psi\left(\mathbb{R}_{+}\right) \rightarrow \mathbb{R}_{+}$with $\tau_{\psi}(0)=0$ only depending on $\delta$, $R$, and $\psi$ such that

$$
\begin{equation*}
|G|+|b| \leq \tau_{\psi}\left(f_{E} \psi(|G x+b|) \mathrm{d} x\right) \tag{3.3}
\end{equation*}
$$

If $\psi(t)=t^{p}, p \in[1, \infty)$, then $\tau_{\psi}$ can be chosen as $\tau_{\psi}(t)=c t^{1 / p}$ for $c=c(p, \delta, R)>0$. Moreover, there exists $c_{0}>0$ only depending on $\delta$ and $R$ such that

$$
\begin{equation*}
\|G x+b\|_{L^{\infty}\left(B_{R}(0)\right)} \leq\left(\omega_{d} R^{d}\right)^{-1} c_{0}\|G x+b\|_{L^{1}(E)} \leq c_{0}\|G x+b\|_{L^{\infty}(E)} . \tag{3.4}
\end{equation*}
$$

Proof. We start by proving an estimate under weaker assumptions than in the statement above. We claim that for each measurable, bounded set $E$ with $\operatorname{diam}(E) \leq 2 R$ (not necessarily contained in $\left.B_{R}(0)\right)$ and $\mathcal{L}^{d}(E) \geq \delta$ there holds

$$
\begin{equation*}
|G| \leq \hat{\tau}_{\psi}\left(f_{E} \psi(|G x+b|) \mathrm{d} x\right) \tag{3.5}
\end{equation*}
$$

for a continuous, strictly increasing function $\hat{\tau}_{\psi}$ with $\hat{\tau}_{\psi}(0)=0$. It is not restrictive to consider only the case $b=0$. Indeed, every $b \in \mathbb{R}^{d}$ can be decomposed orthogonally as $b=\hat{b}-G y$, with $\hat{b} \in(\operatorname{im}(G))^{\perp}$ and $y \in \mathbb{R}^{d}$. Then clearly $|G x+b| \geq|G(x-y)|$ for all $x \in \mathbb{R}^{d}$. Since $\psi$ and $\hat{\tau}_{\psi}$ are increasing, and $\mathcal{L}^{d}(E)$ and diam $(E)$ are left unchanged by a translation of $E$, we can then assume $y=\hat{b}=b=0$.

Since matrix norms are equivalent, we endow $\mathbb{R}^{d \times d}$ with the spectral norm throughout the proof. We fix an eigenvector $v$ with unit norm corresponding to the maximal eigenvalue of the symmetric positive semidefinite matrix $G^{T} G$, i.e. $G^{T} G v=|G|^{2} v$ by the definition of spectral norm. Let $v^{\perp}$ be the $(d-1)$-dimensional hyperplane orthogonal to $v$. Since $|v|=1$, for each $y \in v^{\perp}$ there holds

$$
\begin{equation*}
|G(y+s v)|=\left(|G y|^{2}+2 s|G|^{2}\langle y, v\rangle+s^{2}|G|^{2}|v|^{2}\right)^{1 / 2} \geq|s||G| \tag{3.6}
\end{equation*}
$$

for all $s \in \mathbb{R}$. For $r>0$ we define

$$
\begin{equation*}
E_{r}:=\left\{x=y+s v \in E: y \in v^{\perp},|s| \geq r\right\} \tag{3.7}
\end{equation*}
$$

Using the isodiametric inequality and the fact that $\operatorname{diam}(E) \leq 2 R$, we have $\mathcal{L}^{d}\left(E \backslash E_{r}\right) \leq$ $2 r \omega_{d-1} R^{d-1}$. Let $m:=\sup _{t \in \mathbb{R}_{+}} \psi(t) \in \mathbb{R}_{+} \cup\{+\infty\}$. Hence, setting for each $t \in[0, m) m_{t}=$ $\min \{4 t, m\}, r(t)>0$ can be chosen, only depending on $\delta$ and $R$, such that

$$
\begin{equation*}
\mathcal{L}^{d}\left(E \backslash E_{r(t)}\right) \leq \delta \frac{\sqrt{m_{t}}-\sqrt{t}}{\sqrt{m_{t}}+\sqrt{t}} \tag{3.8}
\end{equation*}
$$

Above the right-hand side is extended by continuity with the value $\frac{1}{3} \delta$ for $t=0$. Note that $r(t)$ is continuous in $t$. We define the function

$$
\begin{equation*}
\hat{\tau}_{\psi}(t)=r(t)^{-1} \psi^{-1}\left(\sqrt{t}\left(\sqrt{m_{t}}+\sqrt{t}\right) / 2\right), \quad t \in[0, m) \tag{3.9}
\end{equation*}
$$

which is clearly well defined for $t \in[0, m)$, and satisfies $\hat{\tau}_{\psi}(0)=0$ since $\psi^{-1}(0)=0$.
By (3.8) and $\mathcal{L}^{d}(E) \geq \delta$ we get $\mathcal{L}^{d}\left(E_{r(t)}\right) \geq 2 \sqrt{t}\left(\sqrt{m_{t}}+\sqrt{t}\right)^{-1} \mathcal{L}^{d}(E)$. Let $t=f_{E} \psi(|G x|)$ for brevity. This along with (3.6)-(3.7) and the fact that $\psi \geq 0$ is monotone increasing yields

$$
\begin{aligned}
\psi(r(t)|G|) & \leq \frac{1}{\mathcal{L}^{d}\left(E_{r(t)}\right)} \int_{E_{r(t)}} \psi(|G x|) \mathrm{d} x \leq \frac{1}{\mathcal{L}^{d}\left(E_{r(t)}\right)} \int_{E} \psi(|G x|) \mathrm{d} x \leq \frac{\sqrt{m_{t}}+\sqrt{t}}{2 \sqrt{t}} f_{E} \psi(|G x|) \mathrm{d} x \\
& =\sqrt{t}\left(\sqrt{m_{t}}+\sqrt{t}\right) / 2
\end{aligned}
$$

This implies $|G| \leq r(t)^{-1} \psi^{-1}\left(\sqrt{t}\left(\sqrt{m_{t}}+\sqrt{t}\right) / 2\right)=\hat{\tau}_{\psi}(t)$ since $\psi^{-1}$ is strictly increasing, too. This concludes the proof of (3.5).

We now show (3.3) for $\tau_{\psi}:=(2 R+1) \hat{\tau}_{\psi}+2 \psi^{-1}$. Whenever $|b| \leq 2 R|G|$, the statement follows directly from (3.5). If instead $|b|>2|G| R$, since $|G x| \leq R|G|$ for all $x \in B_{R}(0)$, we have $|G x+b|>\frac{1}{2}|b|$ for all $x \in E \subset B_{R}(0)$. This implies $\psi(|b| / 2) \leq f_{E} \psi(|G x+b|) \mathrm{d} x$ and thus

$$
|b| \leq 2 \psi^{-1}\left(f_{E} \psi(|G x+b|) \mathrm{d} x\right) .
$$

This along with (3.5) and the definition $\tau_{\psi}=(2 R+1) \hat{\tau}_{\psi}+2 \psi^{-1}$ shows (3.3).
We consider the special situation $\psi(t)=t^{p}, p \in[1, \infty)$. Since $m=\infty$ in this case, in view of (3.9), it is not hard to check that $\hat{\tau}_{\psi}(t) \leq c t^{1 / p}$ and thus $\tau_{\psi}(t) \leq c t^{1 / p}$ for some $c$ sufficiently large depending only on $\delta, R$, and $p$. Thus, $\tau_{\psi}$ can be replaced by the function $t \mapsto c t^{1 / p}$.

We finally show (3.4). We apply (3.3) with $\psi(t)=t$. By using that $\tau_{\psi}(t) \leq c t$ we get $|G|+$ $|b| \leq c f_{E}|G x+b| \mathrm{d} x$. We conclude the proof by recalling that $\mathcal{L}^{d}(E) \geq \delta$ and noting that $|G x+b| \leq|G| R+|b|$ for all $x \in B_{R}(0)$.

For similar estimates of this kind, we also refer to $30,48,50$. We can now prove Lemma 3.3 .
Proof of Lemma 3.3. We start with (i). We consider the pairwise distinct representation $u_{n}=$ $\sum_{j} q_{j, n} \chi_{P_{j, n}}$ of each $u_{n}$ and the associated ordered Caccioppoli partitions $\mathcal{P}_{n}=\left(P_{j, n}\right)_{j}, n \in \mathbb{N}$. Observe that the assumption $\sup _{n \geq 1} \mathcal{H}^{d-1}\left(J_{u_{n}}\right)<+\infty$ and 3.1) imply that

$$
\sup _{n \geq 1} \sum_{j} \mathcal{H}^{d-1}\left(\partial^{*} P_{j, n}\right)<+\infty
$$

Thus, up to a subsequence (not relabeled), there exists a limiting Caccioppoli partition $\left(P_{j}\right)_{j}$ in the sense of Theorem 3.2. It is clearly not restrictive to assume that $\mathcal{L}^{d}\left(P_{j}\right)>0$ for all $j$, since,
after neglecting all null sets, we still have a Caccioppoli partition of $\Omega$. By lower semicontinuity of the perimeter, by using Theorem 3.1, and by 3.1 we also have

$$
\begin{equation*}
\frac{1}{2} \sum_{j} \mathcal{H}^{d-1}\left(\partial^{*} P_{j} \backslash \partial \Omega\right) \leq \liminf _{n \rightarrow \infty} \frac{1}{2} \sum_{j} \mathcal{H}^{d-1}\left(\partial^{*} P_{j, n} \backslash \partial \Omega\right)=\liminf _{n \rightarrow \infty} \mathcal{H}^{d-1}\left(J_{u_{n}}\right) \tag{3.10}
\end{equation*}
$$

For a fixed $j \in \mathbb{N}$, Theorem 3.2 implies that there exists $\delta_{j}$, independently of $n$, with $\mathcal{L}^{d}\left(P_{j, n}\right) \geq$ $\delta_{j}$ for all $n$. Now, by assumption there holds $f_{P_{j, n}} \psi\left(\left|q_{j, n}(x)\right|\right) \mathrm{d} x \leq \frac{M}{\delta_{j}}$, where $M:=\sup _{n} \int_{\Omega} \psi\left(\left|u_{n}\right|\right)$. Hence, we deduce by Lemma 3.4 and the coerciveness of $\psi$ that there exists a constant $c_{\Omega, M, j}$ such that

$$
\sup _{n \geq 1}\left\|q_{j, n}\right\|_{W^{1, \infty}(\Omega)} \leq c_{\Omega, M, j}
$$

By the Ascoli-Arzelà Theorem, a diagonal argument, and by the fact that $L$ is closed, we deduce that there exist rigid motions $\left(q_{j}\right)_{j}$ so that, for each $j$, there holds

$$
\begin{equation*}
\lim _{n \rightarrow \infty}\left\|q_{j, n}-q_{j}\right\|_{L^{\infty}(\Omega)} \rightarrow 0 \tag{3.11}
\end{equation*}
$$

along a subsequence independent of $j$, which we do not relabel. We set $u=\sum_{j} q_{j} \chi_{P_{j}}$, and clearly we get $u \in P R(\Omega)$, while (3.11) and Theorem 3.2 give $u_{n} \rightarrow u$ in measure. To see (ii), we note that by construction $J_{u} \subset \bigcup_{j}\left(\partial^{*} P_{j} \backslash \partial \Omega\right)$ up to an $\mathcal{H}^{d-1}$-negligible set. Thus, we deduce the inequality $\mathcal{H}^{d-1}\left(J_{u}\right) \leq \liminf _{n \rightarrow \infty} \mathcal{H}^{d-1}\left(J_{u_{n}}\right)$ directly from Theorem 3.1 and 3.10).

We now collect some crucial properties of piecewise rigid functions in the blow-up at jump points. In particular, we construct suitable modifications with the property that they converge to the function defined in 2.5 in $L^{p}, 1 \leq p<+\infty$, see 3.12 (vi). This convergence property will be instrumental for the proof of the integral representation formula in Section 5. We denote the half spaces $\left\{\left\langle x-x_{0}, \nu\right\rangle>0\right\}$ and $\left\{\left\langle x-x_{0}, \nu\right\rangle<0\right\}$ by $H^{+}\left(x_{0}, \nu\right)$ and $H^{-}\left(x_{0}, \nu\right)$, respectively.
Lemma 3.5 (Blow-up at jump points). Let $u=\sum_{j \in \mathbb{N}} q_{j} \chi_{P_{j}} \in P R(\Omega)$. Let $\theta \in(0,1)$. For $\mathcal{H}^{d-1}$-a.e. $x_{0} \in J_{u}$ we find $i, j \in \mathbb{N}$ such that $x_{0} \in \partial^{*} P_{i} \cap \partial^{*} P_{j}$, and a sequence $u_{\varepsilon} \in P R\left(B_{\varepsilon}\left(x_{0}\right)\right)$ satisfying
(i) $\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{d}} \mathcal{L}^{d}\left(\left(B_{\varepsilon}\left(x_{0}\right) \cap H^{+}\left(x_{0}, \nu_{u}\right)\right) \backslash P_{i}\right)+\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{d}} \mathcal{L}^{d}\left(\left(B_{\varepsilon}\left(x_{0}\right) \cap H^{-}\left(x_{0}, \nu_{u}\right)\right) \backslash P_{j}\right)=0$,
(ii) $\lim _{\varepsilon \rightarrow 0} \frac{1}{\omega_{d-1} \varepsilon^{d-1}} \mathcal{H}^{d-1}\left(J_{u} \cap\left(B_{\varepsilon}\left(x_{0}\right) \backslash B_{t \varepsilon}\left(x_{0}\right)\right)\right)=\left(1-t^{d-1}\right) \quad$ for all $t \in(0,1)$,
(iii) $u_{\varepsilon}=q_{i} \chi_{P_{i}}+q_{j} \chi_{P_{j}}$ on $B_{(1-\theta) \varepsilon}\left(x_{0}\right)$,
(iv) $u_{\varepsilon}=u$ in a neighborhood of $\partial B_{\varepsilon}\left(x_{0}\right)$,
(v) $\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{d-1}}\left(\mathcal{H}^{d-1}\left(J_{u_{\varepsilon}} \backslash J_{u}\right)+\mathcal{H}^{d-1}\left(\left\{x \in J_{u_{\varepsilon}} \cap J_{u}: \quad\left[u_{\varepsilon}\right](x) \neq[u](x)\right\}\right)\right)=0$,
(vi) $\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{d}} \int_{B_{(1-\theta) \varepsilon}\left(x_{0}\right)}\left|u_{\varepsilon}(x)-\left(u^{-}\left(x_{0}\right)+u_{x_{0},[u]\left(x_{0}\right), \nu_{u}\left(x_{0}\right)}\right)\right|^{p} \mathrm{~d} x=0 \quad \forall 1 \leq p<\infty$.

Proof. For $\mathcal{H}^{d-1}$-a.e. $x_{0} \in J_{u}$ there exist two components $P_{i}$ and $P_{j}$ such that $x_{0} \in \partial^{*} P_{i} \cap \partial^{*} P_{j}$ and

$$
\begin{align*}
& \text { (i) } \lim _{\varepsilon \rightarrow 0} \frac{\mathcal{L}^{d}\left(\left(B_{\varepsilon}\left(x_{0}\right) \cap H^{+}\left(x_{0}, \nu_{u}\right)\right) \backslash P_{i}\right)+\mathcal{L}^{d}\left(\left(B_{\varepsilon}\left(x_{0}\right) \cap H^{-}\left(x_{0}, \nu_{u}\right)\right) \backslash P_{j}\right)}{\varepsilon^{d}}=0 \\
& \text { (ii) } \lim _{\varepsilon \rightarrow 0} \frac{\mathcal{H}^{d-1}\left(B_{\varepsilon}\left(x_{0}\right) \cap J_{u}\right)}{\omega_{d-1} \varepsilon^{d-1}}=\lim _{\varepsilon \rightarrow 0} \frac{\mathcal{H}^{d-1}\left(B_{\varepsilon}\left(x_{0}\right) \cap J_{u} \cap \partial^{*} P_{i} \cap \partial^{*} P_{j}\right)}{\omega_{d-1} \varepsilon^{d-1}}=1 \tag{3.13}
\end{align*}
$$

This follows from Theorem 3.1 and [11, Theorem 3.59]. Note that 3.13 implies 3.12 (i),(ii). Using the coarea formula and (3.13) (i) we can choose $\gamma_{\varepsilon} \in((1-\theta) \varepsilon, \varepsilon)$ such that

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \frac{\mathcal{H}^{d-1}\left(\partial B_{\gamma_{\varepsilon}}\left(x_{0}\right) \backslash\left(P_{i} \cup P_{j}\right)\right)}{\varepsilon^{d-1}}=0 \tag{3.14}
\end{equation*}
$$

We define $u_{\varepsilon} \in P R\left(B_{\varepsilon}\left(x_{0}\right)\right)$ by

$$
u_{\varepsilon}(x)= \begin{cases}u(x) \chi_{P_{i} \cup P_{j}}(x) & \text { if } x \in B_{\gamma_{\varepsilon}}\left(x_{0}\right), \\ u(x) & \text { if } x \in B_{\varepsilon}\left(x_{0}\right) \backslash \overline{B_{\gamma_{\varepsilon}}\left(x_{0}\right)}\end{cases}
$$

The definition directly implies (3.12)(iii),(iv). By (3.13) (ii) we observe

$$
\frac{1}{\varepsilon^{d-1}} \mathcal{H}^{d-1}\left(\left(B_{\gamma_{\varepsilon}}\left(x_{0}\right) \cap J_{u}\right) \backslash\left(\partial^{*} P_{i} \cap \partial^{*} P_{j}\right)\right) \rightarrow 0
$$

This along with (3.14) shows (3.12) (v). Finally, 3.12 (vi) follows from 3.12 (i),(iii) and the fact that $q_{i}(x)$ and $q_{j}(x)$ converge uniformly to $u^{+}\left(x_{0}\right)$ and $u^{-}\left(x_{0}\right)$, respectively, as $x \rightarrow x_{0}$.

## 4. Fundamental estimate for $P R(\Omega)$

This section is devoted to a fundamental estimate for functionals defined on piecewise rigid functions. It will be the key tool to prove our integral representation and $\Gamma$-convergence results. The results in this section will be proven using a weaker assumption than $\left(\mathrm{H}_{5}\right)$. We will namely assume
$\left(\mathrm{H}_{5}{ }^{\prime}\right)$ there exists an increasing modulus of continuity $\sigma:[0,+\infty) \rightarrow[0, \beta]$ with $\sigma(0)=0$ such that for any $u, v \in P R_{L}(\Omega)$ and $S \in B(\Omega)$ with $S \subset J_{u} \cap J_{v}$ we have

$$
|\mathcal{F}(u, S)-\mathcal{F}(v, S)| \leq \int_{S} \sigma\left(\left|u^{+}-v^{+}\right|+\left|u^{-}-v^{-}\right|\right) d \mathcal{H}^{d-1}
$$

where we choose the orientation $\nu_{u}=\nu_{v}$ on $J_{u} \cap J_{v}$.
4.1. Fundamental estimate. In this section we formulate different versions of the fundamental estimate. We first give the main statement and afterwards we provide a generalization which also takes boundary data into account. We use the following convention in the whole section: given $A, U \in \mathcal{A}_{0}(\Omega), A \subset U$, we may regard every $u \in P R(A)$ as a function on $U$, extended by $u=0$ on $U \backslash A$.
Lemma 4.1 (Fundamental estimate). Let $\eta>0$ and $A^{\prime}, A, B \in \mathcal{A}_{0}(\Omega)$ with $A^{\prime} \subset \subset A$, and let $\psi: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$be continuous and strictly increasing with $\psi(0)=0$. Then there exist a constant $M>0$ and a lower semicontinuous function $\Lambda: P R(A) \times P R(B) \rightarrow \mathbb{R}_{+} \cup\{+\infty\}$ satisfying

$$
\begin{equation*}
\Lambda\left(z_{1}, z_{2}\right) \rightarrow 0 \quad \text { whenever } \int_{\left(A \backslash A^{\prime}\right) \cap B} \psi\left(\left|z_{1}-z_{2}\right|\right) \rightarrow 0 \tag{4.1}
\end{equation*}
$$

such that for every functional $\mathcal{F}$ satisfying $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right),\left(\mathrm{H}_{4}\right)$, and $\left(\mathrm{H}_{5}{ }^{\prime}\right)$ and for all $u \in P R(A)$, $v \in P R(B)$ there exists a function $w \in P R\left(A^{\prime} \cup B\right)$ such that
(i) $\mathcal{F}\left(w, A^{\prime} \cup B\right) \leq \mathcal{F}\left(u, A \cap J_{w}\right)+\mathcal{F}\left(v, B \cap J_{w}\right)$

$$
\begin{equation*}
+\left(\mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right)+\mathcal{F}(u, A)+\mathcal{F}(v, B)\right)(\eta+M \sigma(\Lambda(u, v))) \tag{4.2}
\end{equation*}
$$

(ii) $\|\min \{|w-u|,|w-v|\}\|_{L^{\infty}\left(A^{\prime} \cup B\right)} \leq \Lambda(u, v)$,
where $\sigma$ is given in $\left(\mathrm{H}_{5}^{\prime}\right)$. If $\psi(t)=t^{p}, 1 \leq p<\infty$, then $\Lambda\left(z_{1}, z_{2}\right)=M\left\|z_{1}-z_{2}\right\|_{L^{p}\left(\left(A \backslash A^{\prime}\right) \cap B\right)}$.

Remark 4.2 (Topology). We recall that $P R(\Omega)$ is equipped with the topology induced by measure convergence, i.e., a natural choice in Lemma 4.1 is $\psi(t)=\frac{t}{1+t}$. For the applications, however, we are also interested in other topologies, e.g. $\psi(t)=t^{p}$, and therefore we account for different choices in the statement. Note that $\int_{\left(A \backslash A^{\prime}\right) \cap B} \psi\left(\left|z_{1}-z_{2}\right|\right)$ might be infinite. In this case, also $\Lambda$ satisfies $\Lambda\left(z_{1}, z_{2}\right)=+\infty$, and $\sigma(\Lambda(u, v))$ has to be understood as $\lim _{t \rightarrow \infty} \sigma(t)$.

Remark 4.3 ( $L^{\infty}$-estimate). In the case of piecewise constant functions studied by Ambrosio and Braides [6], it is possible to construct $w$ in such a way that $w(x) \in\{u(x), v(x)\}$ for a.e. $x \in A^{\prime} \cup B$. In our setting, we slightly have to modify rigid motions by the coarea formula, with modifications controlled in terms of $\Lambda(u, v)$. This allows us to establish an $L^{\infty}$-control on $\min \{|w-u|,|w-v|\}$ in 4.2 (ii). (Note that each function $u, v, w$ itself might not lie in $L^{\infty}$.)
Remark 4.4 (Non-attainment of boundary data). (i) We emphasize that the function $w$ provided above does not necessarily satisfy $w=v$ on $B \backslash A$, as it will be often required in the applications in Section 5 and Section 6. Indeed, consider the following example (for simplicity, in the planar setting $d=2$ for scalar-valued functions. The extension to the vector case is straightforward):

Let $\rho>0$ and define the set $A^{\prime}=B_{1-2 \rho}(0), A=B_{1-\rho}(0)$, and $B=B_{1}(0) \backslash B_{1-3 \rho}(0)$. For $\varepsilon>0$, we consider the piecewise constant functions $u \in P R(A)$ and $v_{\varepsilon} \in P R(B)$ defined by

$$
\begin{equation*}
u=0 \text { on } A, \quad v_{\varepsilon}=0 \text { on } B \cap\left\{x_{2}>0\right\}, \quad v_{\varepsilon}=\varepsilon \text { on } B \cap\left\{x_{2}<0\right\} \tag{4.3}
\end{equation*}
$$

For each $w \in P R\left(B_{1}(0)\right)$ with $w=v_{\varepsilon}$ on $B \backslash A$, one observes that each line parallel to $e_{2}$ intersects $J_{w}$. To see this, we choose a piecewise constant function $\bar{w} \in S B V\left(B_{1}(0) ;[0,1]\right)$ with $\bar{w}=w$ on $B \backslash A$ and $\mathcal{H}^{1}\left(J_{w} \triangle J_{\bar{w}}\right)=0$, and apply the slicing property [11, Theorem 3.108] of $B V$ functions. This implies $\mathcal{H}^{1}\left(J_{w}\right) \geq 2$ and thus $\mathcal{F}\left(w, B_{1}(0)\right) \geq 2 \alpha$ by $\left(\mathrm{H}_{4}\right)$. On the other hand, we have

$$
\begin{aligned}
& \mathcal{F}(u, A)+\mathcal{F}\left(v_{\varepsilon}, B\right)+\left(\mathcal{H}^{1}\left(\partial A^{\prime} \cup \partial A \cup \partial B\right)+\mathcal{F}(u, A)+\mathcal{F}\left(v_{\varepsilon}, B\right)\right)\left(\eta+M \sigma\left(\Lambda\left(u, v_{\varepsilon}\right)\right)\right) \\
& \leq 6 \rho \beta+(6 \pi+6 \rho \beta)\left(\eta+M \sigma\left(\Lambda\left(u, v_{\varepsilon}\right)\right)\right)
\end{aligned}
$$

Observe that $\int_{\left(A \backslash A^{\prime}\right) \cap B} \psi\left(\left|u-v_{\varepsilon}\right|\right) \leq \pi \rho\left(1-\frac{3}{2} \rho\right) \psi(\varepsilon) \rightarrow 0$ as $\varepsilon \rightarrow 0$ for fixed $\rho$ and thus $\Lambda\left(u, v_{\varepsilon}\right) \rightarrow 0$ by 4.1). In view of $\mathcal{F}\left(w, B_{1}(0)\right) \geq 2 \alpha$, this contradicts 4.2 (i) when we choose $\eta$ small enough, and let first $\varepsilon \rightarrow 0$ and then $\rho \rightarrow 0$.
(ii) The example in (i) shows that the issue of non-attainment of boundary data occurs already on the level of piecewise constant functions. The only reason why this problem did not appear in the fundamental estimate for piecewise constant functions by Ambrosio and Braides, see 6. Lemma 4.4], is due to the fact that the functions considered there attain only a finite number of different values. In fact, the delicate point here is the case where the functions $u$ and $v_{\varepsilon}$ attain very similar values, see 4.3).

For the formulation of a version of the fundamental estimate with boundary data, we need to introduce the following technical definition: for sets $A^{\prime}, U \in \mathcal{A}_{0}(\Omega)$ with $A^{\prime} \subset U$, a piecewise rigid function $v=\sum_{j \in \mathbb{N}} q_{j} \chi_{P_{j}} \in P R\left(U \backslash \overline{A^{\prime}}\right)$ in its pairwise distinct representation (see Section 3.2, and a constant $\delta>0$ we define

$$
\begin{equation*}
\Phi\left(A^{\prime}, U ; v, \delta\right):=\min _{j_{1}, j_{2} \in J, j_{1} \neq j_{2}}\left\|q_{j_{1}}-q_{j_{2}}\right\|_{L^{\infty}(U)} \tag{4.4}
\end{equation*}
$$

where $J \subset \mathbb{N}$ denotes the index set of large components defined by

$$
\begin{equation*}
J:=\left\{j \in \mathbb{N}: \mathcal{L}^{d}\left(P_{j} \cap\left(U \backslash \overline{A^{\prime}}\right)\right) \geq \delta\right\} \tag{4.5}
\end{equation*}
$$

As $J$ contains a finite number of indices, it is clear that $\Phi\left(A^{\prime}, U ; v, \delta\right)>0$. If $\# J \leq 1$, then $\Phi\left(A^{\prime}, U ; v, \delta\right)=+\infty$. We remark that the difference of the affine mappings in 4.4) is compared on $U$ and not on $U \backslash \overline{A^{\prime}}$ (where $v$ is defined) as in the proof we need to modify functions in the whole
domain $U$ and not only inside $U \backslash \overline{A^{\prime}}$. On the contrary, we emphasize that in 4.5 the volume of the components inside $U \backslash \overline{A^{\prime}}$ is measured.
Lemma 4.5 (Fundamental estimate, boundary data). Let $\eta>0$ and $A^{\prime}, A, B \in \mathcal{A}_{0}(\Omega)$ with $A^{\prime} \subset \subset A$. Let $\psi: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$be continuous and strictly increasing with $\psi(0)=0$. Let $\Lambda$ be the function of Lemma 4.1. Then there exist constants $\delta>0$ and $M_{1} \geq 1$ such that for every functional $\mathcal{F}$ satisfying $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right),\left(\mathrm{H}_{4}\right)$, and $\left(\mathrm{H}_{5}{ }^{\prime}\right)$ and for all $u \in P R(A), v \in P R(B)$ satisfying the condition

$$
\begin{equation*}
M_{1} \Lambda(u, v) \leq \Phi\left(A^{\prime}, A^{\prime} \cup B ;\left.v\right|_{B \backslash \overline{A^{\prime}}}, \delta\right) \tag{4.6}
\end{equation*}
$$

there exists a function $w \in P R\left(A^{\prime} \cup B\right)$ such that
(i) $\mathcal{F}\left(w, A^{\prime} \cup B\right) \leq \mathcal{F}(u, A)+\mathcal{F}(v, B)$

$$
+\left(\mathcal{H}^{d-1}\left(\partial A^{\prime} \cup \partial A \cup \partial B\right)+\mathcal{F}(u, A)+\mathcal{F}(v, B)\right)\left(2 \eta+M_{2} \sigma(\Theta(u, v))\right)
$$

(ii) $\|\min \{|w-u|,|w-v|\}\|_{L^{\infty}\left(A^{\prime} \cup B\right)} \leq \Theta(u, v)$,
(iii) $w=v$ on $B \backslash A$,
where $\sigma$ is given in $\left(\mathrm{H}_{5}{ }^{\prime}\right)$, and $M_{2}>0$ as well as $\Theta: P R(A) \times P R(B) \rightarrow \mathbb{R}_{+} \cup\{+\infty\}$ are independent of $u, v$, and $\mathcal{F}$. Here, $\Theta$ is a lower semicontinuous function satisfying

$$
\begin{equation*}
\Theta\left(z_{1}, z_{2}\right) \rightarrow 0 \quad \text { whenever } \int_{\left(A \backslash A^{\prime}\right) \cap B} \psi\left(\left|z_{1}-z_{2}\right|\right) \rightarrow 0 \tag{4.8}
\end{equation*}
$$

If $\psi(t)=t^{p}, 1 \leq p<\infty$, then $\Theta(u, v)=M_{2}\|u-v\|_{L^{p}\left(\left(A \backslash A^{\prime}\right) \cap B\right)}$.
The object $\Phi$ measures how 'similar' a function is on different (large) components. Roughly speaking, the technical condition 4.6 ensures that, for the functions $u$ and $v$, the phenomenon described in Remark 4.4 cannot occur. In this context, we remark that, for given $\delta>0$, the constant $M_{1}$ will be chosen sufficiently large in the proof, depending on the constant $c_{0}$ in Lemma 3.4.

In the applications, we will need to use the fundamental estimate on balls of different sizes. To this end, we formulate a scaled version of Lemma 4.5 .

Corollary 4.6 (Scaled version of the fundamental estimate). Let $\eta>0$ and $\rho>0$. Suppose that $A^{\prime}, A, B \in \mathcal{A}_{0}(\Omega)$ with $A^{\prime} \subset \subset A$ are given such that $\rho A^{\prime}, \rho A, \rho B \subset \Omega$. Let $u_{\rho} \in P R(\rho A)$ and $v_{\rho} \in P R(\rho B)$. Under the assumption that

$$
\begin{equation*}
\rho^{-d} M M_{1}\left\|u_{\rho}-v_{\rho}\right\|_{L^{1}\left(\left(\rho A \backslash \rho A^{\prime}\right) \cap \rho B\right)} \leq \Phi\left(\rho A^{\prime}, \rho A^{\prime} \cup \rho B ;\left.v_{\rho}\right|_{\rho B \backslash \rho \overline{A^{\prime}}}, \rho^{d} \delta\right) \tag{4.9}
\end{equation*}
$$

one finds a function $w_{\rho} \in P R\left(\rho A^{\prime} \cup \rho B\right)$ satisfying
(i) $\mathcal{F}\left(w_{\rho}, \rho A^{\prime} \cup \rho B\right) \leq \mathcal{F}\left(u_{\rho}, \rho A\right)+\mathcal{F}\left(v_{\rho}, \rho B\right)$

$$
+\left(\rho^{d-1} C_{A^{\prime}, A, B}+\mathcal{F}\left(u_{\rho}, \rho A\right)+\mathcal{F}\left(v_{\rho}, \rho B\right)\right)\left(2 \eta+M_{2} \sigma\left(M_{2} \rho^{-d}\left\|u_{\rho}-v_{\rho}\right\|_{L^{1}\left(\rho\left(A \backslash A^{\prime}\right) \cap \rho B\right)}\right)\right)
$$

(ii) $\left\|\min \left\{\left|w_{\rho}-u_{\rho}\right|,\left|w_{\rho}-v_{\rho}\right|\right\}\right\|_{L^{\infty}\left(\rho A^{\prime} \cup \rho B\right)} \leq M_{2} \rho^{-d}\left\|u_{\rho}-v_{\rho}\right\|_{L^{1}\left(\rho\left(A \backslash A^{\prime}\right) \cap \rho B\right)}$,
(iii) $w_{\rho}=v_{\rho}$ on $\rho B \backslash \rho A$,
where $M$ is the constant of Lemma 4.1, $M_{1}, M_{2}, \delta$ are the constants of Lemma 4.5 (applied for $\psi(t)=t)$, and $C_{A^{\prime}, A, B}:=\mathcal{H}^{d-1}\left(\partial A^{\prime} \cup \partial A \cup \partial B\right)$ for brevity.

The proof of Lemma 4.1 will be addressed in Section 4.2. The proofs of Lemma 4.5 and Corollary 4.6 will be given in Section 4.3. The reader may also skip the following subsections and go directly to the proofs of our main results in Section 5 and Section 6.
4.2. Proof of Lemma 4.1. This section is devoted to the proof of Lemma 4.1. As a preparation, we formulate and prove a lemma about the choice of subsets.
Lemma 4.7 (Choice of subsets). Let $\lambda>0$. Let $A^{\prime}, A \in \mathcal{A}_{0}(\Omega)$ with $A^{\prime} \subset \subset A$. For $0<t<$ $d_{A^{\prime}, A}:=\operatorname{dist}\left(\partial A^{\prime}, \partial A\right)$ we define

$$
\begin{equation*}
E_{t}:=\left\{x \in \mathbb{R}^{d}: \operatorname{dist}\left(x, A^{\prime}\right)<t\right\} \tag{4.11}
\end{equation*}
$$

Then for each set of finite perimeter $D \subset \Omega$ there exist $\frac{1}{4} d_{A^{\prime}, A}<T_{1}<T_{2}<\frac{3}{4} d_{A^{\prime}, A}$ and a function $\varphi \in C^{\infty}(A)$ with $0 \leq \varphi \leq 1, \varphi=1$ in a neighborhood of $\overline{E_{T_{1}}}$, and $\operatorname{supp}(\varphi) \subset \subset E_{T_{2}}$ such that the set of finite perimeter $F:=D \cap\left(E_{T_{2}} \backslash \overline{E_{T_{1}}}\right)$ and the function $\varphi$ satisfy

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(\partial^{*} F\right) \leq \lambda \mathcal{H}^{d-1}\left(\partial^{*} D\right)+M_{\lambda} \mathcal{L}^{d}(D) \quad \text { and } \quad\|\nabla \varphi\|_{\infty} \leq M_{\lambda} \tag{4.12}
\end{equation*}
$$

where $M_{\lambda}$ only depends on $\lambda, A^{\prime}$, and $A$.
Proof. Choose $k \in \mathbb{N}$ such that $k \geq \lambda^{-1}$. Let $t_{i}=\left(\frac{1}{4}+\frac{i}{2 k}\right) d_{A, A^{\prime}}$ for $i=0, \ldots, k$, and define $A_{i}=E_{t_{i}} \backslash \overline{E_{t_{i-1}}}$ for $i=1, \ldots, k$. We also define the smaller sets $B_{i}=E_{t_{i}^{-}} \backslash \overline{E_{t_{i-1}^{+}}}$, where $t_{i}^{ \pm}=t_{i} \pm \frac{1}{8 k} d_{A, A^{\prime}}$. For $i=1, \ldots, k$, let $\varphi_{i} \in C^{\infty}(A)$ with $0 \leq \varphi_{i} \leq 1, \varphi_{i}=1$ in a neighborhood of $\overline{E_{t_{i-1}^{+}}}$, and $\operatorname{supp}(\varphi) \subset \subset E_{t_{i}^{-}}$, i.e., $\left\{0<\varphi_{i}<1\right\} \subset \subset B_{i}$. Define

$$
M_{\lambda}=\max \left\{16 k d_{A, A^{\prime}}^{-1}, \max _{i=1, \ldots, k}\left\|\nabla \varphi_{i}\right\|_{\infty}\right\}
$$

By recalling $k \geq \lambda^{-1}$ we find $i_{0} \in\{1, \ldots, k\}$ such that

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(\partial^{*} D \cap A_{i_{0}}\right) \leq \frac{1}{k} \sum_{i=1}^{k} \mathcal{H}^{d-1}\left(\partial^{*} D \cap A_{i}\right) \leq \lambda \mathcal{H}^{d-1}\left(\partial^{*} D\right) \tag{4.13}
\end{equation*}
$$

We now claim that one can find $t_{i_{0}-1}<T_{1}<t_{i_{0}-1}^{+}$and $t_{i_{0}}^{-}<T_{2}<t_{i_{0}}$ such that

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(D \cap \partial E_{T_{1}}\right) \leq \frac{8 k}{d_{A^{\prime}, A}} \mathcal{L}^{d}\left(D \cap A_{i_{0}}\right), \quad \mathcal{H}^{d-1}\left(D \cap \partial E_{T_{2}}\right) \leq \frac{8 k}{d_{A^{\prime}, A}} \mathcal{L}^{d}\left(D \cap A_{i_{0}}\right) \tag{4.14}
\end{equation*}
$$

We only prove the first inequality above since the other one is similar. To this aim, we observe that

$$
\left\{x \in \mathbb{R}^{d}: t_{i_{0}-1}<\operatorname{dist}\left(x, A^{\prime}\right)<t_{i_{0}-1}^{+}\right\} \subset A_{i_{0}}
$$

Hence, applying the coarea formula to the Lipschitz function $g(x):=\operatorname{dist}\left(x, A^{\prime}\right)$, whose gradient has norm 1 a.e., (see for instance [42, Theorem 3.14]) we get

$$
\mathcal{L}^{d}\left(D \cap A_{i_{0}}\right) \geq \int_{t_{i_{0}-1}}^{t_{i_{0}-1}^{+}} \mathcal{H}^{d-1}(D \cap\{g=t\}) \mathrm{d} t
$$

Thus, since $t_{i_{0}-1}^{+}-t_{i_{0}-1}=\frac{d_{A^{\prime}, A}}{8 k}$, we can choose $t_{i_{0}-1}<T_{1}<t_{i_{0}-1}^{+}$such that 4.14) holds.
We define $F:=D \cap\left(E_{T_{2}} \backslash \overline{E_{T_{1}}}\right)$. In view of $\left\{0<\varphi_{i_{0}}<1\right\} \subset B_{i_{0}}$, the definition of $T_{1}$ and $T_{2}$ implies that $\varphi_{i_{0}}$ satisfies $\varphi_{i_{0}}=1$ in a neighborhood of $\overline{E_{T_{1}}}$, and $\operatorname{supp}\left(\varphi_{i_{0}}\right) \subset \subset E_{T_{2}}$. Moreover, by (4.13)-4.14 we get

$$
\begin{aligned}
\mathcal{H}^{d-1}\left(\partial^{*} F\right) & \leq \mathcal{H}^{d-1}\left(\partial^{*} D \cap A_{i_{0}}\right)+\mathcal{H}^{d-1}\left(D \cap \partial E_{T_{1}}\right)+\mathcal{H}^{d-1}\left(D \cap \partial E_{T_{2}}\right) \\
& \leq \lambda \mathcal{H}^{d-1}\left(\partial^{*} D\right)+M_{\lambda} \mathcal{L}^{d}(D)
\end{aligned}
$$

where we used $M_{\lambda} \geq 16 k d_{A, A^{\prime}}^{-1}$. This yields the first part of 4.12. The second part of 4.12 follows directly from the definition of $M_{\lambda}$.

For the proof of Lemma 4.1, we will need another two ingredients. First, we state an elementary property about the covering of points by balls.

Lemma 4.8 (Covering with balls). Let $N \in \mathbb{N}$ and $r_{0}>0$. Then each set of points $\left\{x_{1}, \ldots, x_{N}\right\} \subset$ $\mathbb{R}^{m}$ can be covered by finitely many pairwise disjoint balls $\left\{B_{r_{k}}\left(y_{k}\right)\right\}_{k=1}^{M}, M \leq N,\left(y_{k}\right)_{k=1}^{M} \subset \mathbb{R}^{m}$, satisfying

$$
r_{k} \in\left[8^{-N} r_{0}, r_{0}\right], \quad \operatorname{dist}\left(B_{r_{i}}\left(y_{i}\right), B_{r_{j}}\left(y_{j}\right)\right)>2 \max _{k=1, \ldots, M} r_{k} \quad \text { for } 1 \leq i<j \leq M
$$

Proof. From [49, Lemma 3.7] applied for $\gamma=4$ and $R_{0}=r_{0} 8^{-N}$ we get pairwise disjoint balls $\left\{B_{r_{k}}\left(y_{k}\right)\right\}_{k=1}^{M}$ with $r_{k} \in\left[8^{-N} r_{0}, r_{0}\right]$ and $\left|y_{i}-y_{j}\right|>4 \max _{k=1, \ldots, M} r_{k}$ for $1 \leq i<j \leq M$. The statement follows with the triangle inequality.

We will also need the following result on the approximation of $G S B V$ functions with piecewise constant functions, which can be seen as a piecewise Poincaré inequality and essentially relies on the $B V$ coarea formula. For basic properties of $G S B V$ functions we refer to [11, Section 4].
Theorem 4.9 (Piecewise Poincaré inequality). Let $m \geq 1$ and $z \in(G S B V(\Omega))^{m}$ with $\|\nabla z\|_{L^{1}(\Omega)}+$ $\mathcal{H}^{d-1}\left(J_{z}\right)<\infty$. Consider a Borel subset $D \subset \Omega$ with finite perimeter. Fix $\theta>0$. Then there exists a partition $\left(P_{k}\right)_{k=1}^{\infty}$ of $D$, made of sets of finite perimeter, and a piecewise constant function $z_{\mathrm{pc}}:=\sum_{k=1}^{\infty} b_{k} \chi_{P_{k}}$ such that

$$
\begin{aligned}
& \text { (i) } \sum_{k=1}^{\infty} \mathcal{H}^{d-1}\left(\left(\partial^{*} P_{k} \cap D^{1}\right) \backslash J_{z}\right) \leq \theta, \\
& \text { (ii) }\left\|z-z_{\mathrm{pc}}\right\|_{L^{\infty}(D)} \leq c \theta^{-1}\|\nabla z\|_{L^{1}(D)},
\end{aligned}
$$

for a dimensional constant $c=c(m)>0$, where $D^{1}$ denotes the set of points with density one. If additionally for some $i=1, \ldots, m$ the component $z^{i}$ satisfies $\left\|z^{i}\right\|_{L^{\infty}(D)} \leq M$, we also have $\left\|z_{\mathrm{pc}}^{i}\right\|_{L^{\infty}(D)} \leq M$.

For a proof we refer to [48, Theorem 2.3], although the argument can be retrieved in previous literature (see for instance [4, 23]). The additional property that $L^{\infty}$-caps are preserved by the approximation, which was not stated explicitly there, is a direct consequence of the proof. (The values of the piecewise constant approximation are sampled from intersections of nonempty superlevel sets of the $G S B V$ function.) Moreover, we remark that in 48 only sets $D$ with Lipschitz boundary have been considered. The statement is still true in the present situation, provided that the $\mathcal{H}^{d-1}$-measure of $\partial^{*} D$ does not contribute in estimate (i). To this end, it is essential to intersect with $D^{1}$.

As a final preparation for the proof of Lemma 4.1, we recall the definition of the Lipschitz mapping $\Psi_{L}$ before 2.2 , and we discuss how piecewise rigid functions can be parametrized by means of the mapping $\Psi_{L}$. Given a Caccioppoli partition $\left(P_{j}\right)_{j=1}^{\infty}$ of $\Omega,\left(\gamma_{j}\right)_{j=1}^{\infty} \subset\left(-r_{L}, r_{L}\right)^{d_{L}}$, and $\left(b_{j}\right)_{j=1}^{\infty} \subset \mathbb{R}^{d}$, we can define a piecewise rigid function $z \in P R(\Omega)$ by

$$
\begin{equation*}
z(x)=\sum_{j=1}^{\infty}\left(\Psi_{L}\left(\gamma_{j}\right) x+b_{j}\right) \chi_{P_{j}}(x) \quad \text { for } x \in \Omega \tag{4.15}
\end{equation*}
$$

We call $z_{\text {par }}=\sum_{j=1}^{\infty}\left(\gamma_{j}, b_{j}\right) \chi_{P_{j}} \in G S B V\left(\Omega ; \mathbb{R}^{d_{L}} \times \mathbb{R}^{d}\right)$ a parametrization of $z$ and observe that $z_{\text {par }}$ is a piecewise constant function in the sense of [11, Definition 4.21]. Given another piecewise rigid function $\tilde{z} \in P R(\Omega)$ and a corresponding parametrization $\tilde{z}_{\text {par }}=\sum_{j=1}^{\infty}\left(\tilde{\gamma}_{j}, \tilde{b}_{j}\right) \chi_{\tilde{P}_{j}}$, we observe that for all $i, j \in \mathbb{N}$

$$
\|z-\tilde{z}\|_{L^{\infty}\left(P_{i} \cap \tilde{P}_{j}\right)} \leq \sup _{x \in \Omega}|x|\left|\Psi_{L}\left(\gamma_{i}\right)-\Psi_{L}\left(\tilde{\gamma}_{j}\right)\right|+\left|b_{i}-\tilde{b}_{j}\right| \leq \sup _{x \in \Omega}|x| C_{L}\left|\gamma_{i}-\tilde{\gamma}_{j}\right|+\left|b_{i}-\tilde{b}_{j}\right|
$$

where $C_{L}$ is larger or equal to the Lipschitz constant of $\Psi_{L}$. This implies

$$
\begin{equation*}
\|z-\tilde{z}\|_{L^{\infty}(\Omega)} \leq\left(C_{L} \sup _{x \in \Omega}|x|+1\right)\left\|z_{\mathrm{par}}-\tilde{z}_{\mathrm{par}}\right\|_{L^{\infty}(\Omega)} . \tag{4.16}
\end{equation*}
$$

We are now ready to prove Lemma 4.1.

Proof of Lemma 4.1. Let $A^{\prime}, A, B \in \mathcal{A}_{0}(\Omega)$ with $A^{\prime} \subset \subset A$ and $\eta>0$. Let $\lambda=\eta \alpha /(8 \beta)$, where $\alpha, \beta$ are the constants from $\left(\mathrm{H}_{4}\right)$, and let $M_{\lambda}$ be the constant from Lemma 4.7 applied for $A^{\prime}, A$, and $\lambda$. We define $d_{A^{\prime}, A}=\operatorname{dist}\left(\partial A^{\prime}, \partial A\right)$. Let $\delta=\left(\alpha \eta /\left(8 \beta c_{\pi, d} M_{\lambda}\right)\right)^{d}$, where $c_{\pi, d}$ denotes the isoperimetric constant in dimension $d$. All constants may depend on $L$ without further notice. Throughout the proof we will assume without loss of generality that

$$
\begin{equation*}
\frac{1}{\delta} \int_{\left(A \backslash A^{\prime}\right) \cap B} \psi(|u-v|)<\sup _{t \in \mathbb{R}^{+}} \psi(t) \tag{4.17}
\end{equation*}
$$

Indeed, if this does not hold we simply set $\Lambda(u, v)=+\infty$ and $w=u \chi_{A}+v \chi_{B \backslash A}$. Then, in view of $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{4}\right), 4.2$ is satisfied for $M=\beta\left(\lim _{t \rightarrow+\infty} \sigma(t)\right)^{-1}$, see also Remark 4.2.

Let $u \in P R(A), v \in P R(B)$ be given, and let $u=\sum_{j} q_{j}^{u} \chi_{P_{j}^{u}}$ and $v=\sum_{j} q_{j}^{v} \chi_{P_{j}^{v}}$ be their pairwise distinct representations (see Section 3.2). We first define parametrizations $u_{\text {par }}$ and $v_{\text {par }}$ of $u$ and $v$ in the sense of 4.15) (Step 1). Then we decompose $A^{\prime} \cup B$ into a good set and a bad set (Step 2). Roughly speaking, the bad set consists of the sets $\left(P_{i}^{u} \cap P_{j}^{v}\right)_{i, j \in \mathbb{N}}$ of measure smaller than $\delta$. On the good set, we join the parametrizations $u_{\text {par }}$ and $v_{\text {par }}$ by means of a cut-off construction to a function $z_{\text {par }}$ (Step 3). Afterwards, we use Theorem 4.9 to approximate $z_{\text {par }}$ by a piecewise constant function $w_{\text {par }}$. In the good set, the desired function $w$ is then obtained from $w_{\text {par }}$ via 4.15) and in the bad set we define $w=u$ (Step 4). Finally, we prove 4.1)-4.2) for $w$ (Step 5).

Step 1 (Parametrization of $u$ and $v$ ): We introduce the index sets $\mathcal{P}_{\text {large }}^{u}=\left\{i \in \mathbb{N}: \mathcal{L}^{d}\left(P_{i}^{u}\right) \geq \delta\right\}$ and $\mathcal{P}_{\text {large }}^{v}=\left\{j \in \mathbb{N}: \mathcal{L}^{d}\left(P_{j}^{v}\right) \geq \delta\right\}$. Let $Q_{i}^{u}$ and $Q_{j}^{v}$ be the corresponding matrices in $L$, and denote by $b_{i}^{u}$ and $b_{j}^{v}$ the translations. We will show that for all $i \in \mathcal{P}_{\text {large }}^{u}$ and $j \in \mathcal{P}_{\text {large }}^{v}$, respectively, there exist $\gamma_{i}^{u} \in \Psi_{L}^{-1}\left(Q_{i}^{u}\right)$ and $\gamma_{j}^{v} \in \Psi_{L}^{-1}\left(Q_{j}^{v}\right)$ such that

$$
\begin{equation*}
\left|\gamma_{i}^{u}-\gamma_{j}^{v}\right| \leq C_{\delta}\left|Q_{i}^{u}-Q_{j}^{v}\right| \quad \text { for all } \quad i \in \mathcal{P}_{\text {large }}^{u}, j \in \mathcal{P}_{\text {large }}^{v}, \tag{4.18}
\end{equation*}
$$

for a constant $C_{\delta}>0$ depending only on $\delta, A, B$, and $L$. Once this is proved, we define the parametrizations $u_{\mathrm{par}} \in G S B V\left(A ; \mathbb{R}^{d_{L}} \times \mathbb{R}^{d}\right)$ and $v_{\mathrm{par}} \in G S B V\left(B ; \mathbb{R}^{d_{L}} \times \mathbb{R}^{d}\right)$ by

$$
\begin{equation*}
u_{\mathrm{par}}=\sum_{i=1}^{\infty}\left(\gamma_{i}^{u}, b_{i}^{u}\right) \chi_{P_{i}^{u}} \quad \text { and } \quad v_{\mathrm{par}}=\sum_{j=1}^{\infty}\left(\gamma_{j}^{v}, b_{j}^{v}\right) \chi_{P_{j}^{v}} \tag{4.19}
\end{equation*}
$$

where for $i \notin \mathcal{P}_{\text {large }}^{u}$ and $j \notin \mathcal{P}_{\text {large }}^{v}$ we can choose arbitrary $\gamma_{i}^{u} \in \Psi_{L}^{-1}\left(Q_{i}^{u}\right)$ and $\gamma_{j}^{v} \in \Psi_{L}^{-1}\left(Q_{j}^{v}\right)$, respectively.

We now proceed to show 4.18). First, if $r_{L}=+\infty$, then $\Psi_{L}$ has a globally Lipschitz right inverse $\Xi_{L}$ defined on all of $L$, and the property follows directly from 2.2 when we choose $C_{\delta} \geq C_{L}$. Otherwise, we proceed as follows: as a preliminary observation, we note that

$$
\begin{equation*}
N:=\# \mathcal{P}_{\text {large }}^{u}+\# \mathcal{P}_{\text {large }}^{v} \leq \delta^{-1}\left(\mathcal{L}^{d}(A)+\mathcal{L}^{d}(B)\right) \tag{4.20}
\end{equation*}
$$

Indeed, since $\delta \leq \mathcal{L}^{d}\left(P_{i}^{u}\right)$ for $i \in \mathcal{P}_{\text {large }}^{u}$, we have

$$
\# \mathcal{P}_{\text {large }}^{u} \leq \sum_{i \in \mathcal{P}_{\text {large }}^{u}} \delta^{-1} \mathcal{L}^{d}\left(P_{i}^{u}\right) \leq \delta^{-1} \mathcal{L}^{d}(A)
$$

A similar estimate holds for $\# \mathcal{P}_{\text {large }}^{v}$ with $B$ in place of $A$. This yields 4.20.
Let $\mathcal{R}=\left\{Q_{i}^{u}: i \in \mathcal{P}_{\text {large }}^{u}\right\} \cup\left\{Q_{j}^{v}: j \in \mathcal{P}_{\text {large }}^{v}\right\}$. For convenience, we write $\mathcal{R}=\left(Q_{k}\right)_{k}$. Using Lemma 4.8 for $r_{0}=c_{L} r_{L}$ we find a finite number of pairwise disjoint balls $B_{1}, \ldots, B_{n} \subset \mathbb{R}^{d \times d}$, $n \leq N$, with radius smaller than $c_{L} r_{L}$ such that the balls $\left(B_{i}\right)_{i=1}^{n}$ cover $\left(Q_{k}\right)_{k}$, and one has

$$
\begin{equation*}
Q_{k_{1}} \in B_{i_{1}} \quad \text { and } \quad Q_{k_{2}} \in B_{i_{2}} \quad \text { for } \quad k_{1} \neq k_{2}, i_{1} \neq i_{2} \quad \Rightarrow \quad\left|Q_{k_{1}}-Q_{k_{2}}\right| \geq 8^{-N} c_{L} r_{L} \tag{4.21}
\end{equation*}
$$

In view of 2.2 , on each $B_{i}, i=1, \ldots, n$, a Lipschitz right-inverse mapping $\Xi_{L}$ of $\Psi_{L}$ is well defined. We set $\gamma_{k}=\Xi_{L}\left(Q_{k}\right)$ for all $Q_{k} \in B_{i}$. We recall that each $Q_{i}^{u}, i \in \mathcal{P}_{\text {large }}^{u}$, coincides with some $Q_{k} \in \mathcal{R}$, and we let $\gamma_{i}^{u}=\gamma_{k}$. For each $Q_{j}^{v}$ we proceed in a similar fashion. In view of this
definition, we derive that 4.18 holds for the constant $C_{\delta}=\max \left\{C_{L}, 2 \sqrt{d_{L}} 8^{N} / c_{L}\right\}$. Indeed, if $Q_{k_{1}}, Q_{k_{2}}$ are contained in the same ball $B_{i}$, the property follows from 2.2. Otherwise, 4.21 and the fact that $\gamma_{k_{1}}, \gamma_{k_{2}} \in\left(-r_{L}, r_{L}\right)^{d_{L}}$ imply

$$
\left|\gamma_{k_{1}}-\gamma_{k_{2}}\right| \leq 2 \sqrt{d_{L}} r_{L} \leq 2 \sqrt{d_{L}} 8^{N} c_{L}^{-1}\left|Q_{k_{1}}-Q_{k_{2}}\right|
$$

We note that $C_{\delta}>0$ depends only on $\delta, A, B$, and $L$, see 4.20.
Step 2 (Identification of good and bad sets): Let $\left(P_{k}^{u, v}\right)_{k}$ be the partition of $\left(A \backslash A^{\prime}\right) \cap B$ consisting of the nonempty sets $P_{i}^{u} \cap P_{j}^{v} \cap\left(\left(A \backslash A^{\prime}\right) \cap B\right), i, j \in \mathbb{N}$. Clearly, by Theorem 3.1 and $\left(\mathrm{H}_{4}\right)$ we have

$$
\begin{align*}
\sum_{k=1}^{\infty} \mathcal{H}^{d-1}\left(\partial^{*} P_{k}^{u, v}\right) & \leq \mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right)+2 \mathcal{H}^{d-1}\left(J_{u}\right)+2 \mathcal{H}^{d-1}\left(J_{v}\right) \\
& \leq 2 \alpha^{-1}\left(\mathcal{F}(u, A)+\mathcal{F}(v, B)+\mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right)\right) \tag{4.22}
\end{align*}
$$

Let $\mathcal{P}_{\text {large }}^{u, v}=\left\{k: \mathcal{L}^{d}\left(P_{k}^{u, v}\right) \geq \delta\right\}$ and $\mathcal{P}_{\text {small }}^{u, v}=\mathbb{N} \backslash \mathcal{P}_{\text {large }}^{u, v}$. We also define

$$
\begin{equation*}
D_{\text {large }}=\bigcup_{k \in \mathcal{P}_{\text {large }}^{u, v}} P_{k}^{u, v}, \quad D_{\text {small }}=\left(\left(A \backslash A^{\prime}\right) \cap B\right) \backslash D_{\text {large }} \tag{4.23}
\end{equation*}
$$

We observe by 4.22 and the isoperimetric inequality that

$$
\begin{align*}
\mathcal{L}^{d}\left(D_{\text {small }}\right) & =\sum_{k \in \mathcal{P}_{\text {small }}^{u, v}} \mathcal{L}^{d}\left(P_{k}^{u, v}\right) \leq \delta^{1 / d} \sum_{k \in \mathcal{P}_{\text {small }}^{u, v}}\left(\mathcal{L}^{d}\left(P_{k}^{u, v}\right)\right)^{(d-1) / d} \leq c_{\pi, d} \delta^{1 / d} \sum_{k \in \mathcal{P}_{\text {small }}^{u, v}} \mathcal{H}^{d-1}\left(\partial^{*} P_{k}^{u, v}\right) \\
& \leq 2 c_{\pi, d} \delta^{1 / d} \alpha^{-1}\left(\mathcal{F}(u, A)+\mathcal{F}(v, B)+\mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right)\right) \tag{4.24}
\end{align*}
$$

We apply Lemma 4.7 on $D_{\text {small }}$ for $\lambda=\eta \alpha /(8 \beta)$ to obtain $\frac{1}{4} d_{A^{\prime}, A}<T_{1}<T_{2}<\frac{3}{4} d_{A^{\prime}, A}$ and a function $\varphi \in C^{\infty}(A)$ with $\varphi=1$ in a neighborhood of $\overline{E_{T_{1}}}$ and $\operatorname{supp}(\varphi) \subset \subset E_{T_{2}}$ satisfying 4.12). We define the sets

$$
\begin{equation*}
D_{\text {bad }}=\left(D_{\text {small }} \cap\left(E_{T_{2}} \backslash \overline{E_{T_{1}}}\right)\right)^{1}, \quad D_{\text {good }}=\left(\left(A^{\prime} \cup B\right) \backslash D_{\text {bad }}\right)^{1} \tag{4.25}
\end{equation*}
$$

where $(\cdot)^{1}$ denotes the set of points with density one. For an illustration of the sets we refer to Figure 1 . Lemma 4.7 and 4.22 - 4.24 imply

$$
\begin{align*}
\mathcal{H}^{d-1}\left(\partial^{*} D_{\mathrm{bad}}\right) & \leq \lambda \mathcal{H}^{d-1}\left(\partial^{*} D_{\text {small }}\right)+M_{\lambda} \mathcal{L}^{d}\left(D_{\text {small }}\right) \\
& \leq \frac{\eta}{2 \beta}\left(\mathcal{F}(u, A)+\mathcal{F}(v, B)+\mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right)\right) \tag{4.26}
\end{align*}
$$

where we used $\lambda=\eta \alpha /(8 \beta)$ and $\delta=\left(\alpha \eta /\left(8 \beta c_{\pi, d} M_{\lambda}\right)\right)^{d}$.


Figure 1. Left: The sets $A^{\prime}, A$, and $B$, and $\partial E_{T_{1}}, \partial E_{T_{2}}$ (dashed). (For illustration purposes, we replaced $\operatorname{dist}\left(x, A^{\prime}\right)$ in 4.11) by $\operatorname{dist}_{\infty}\left(x, A^{\prime}\right)$ in the picture.) Middle: $D_{\text {large }}$ (blue) and $D_{\text {small }}$ (gray). Right: $D_{\text {good }}$ (blue) and $D_{\text {bad }}$ (gray).

Step 3 (Joining $u_{\text {par }}$ and $v_{\text {par }}$ on $D_{\text {good }}$ ): Choose $R$ sufficiently large depending on $A$ and $B$ such that $A^{\prime} \cup B \subset B_{R}(0)$. Recall the function $\psi$ given in the statement of the lemma. Consider $P_{k}^{u, v}$, $k \in \mathcal{P}_{\text {large }}^{u, v}$, and choose $i \in \mathcal{P}_{\text {large }}^{u}, j \in \mathcal{P}_{\text {large }}^{v}$ such that $P_{k}^{u, v}=P_{i}^{u} \cap P_{j}^{v} \cap\left(\left(A \backslash A^{\prime}\right) \cap B\right)$. By Lemma 3.4 there exists a continuous, strictly increasing function $\tau_{\psi}: \psi\left(\mathbb{R}_{+}\right) \rightarrow \mathbb{R}_{+}$with $\tau_{\psi}(0)=0$ only depending on $\delta, R$, and $\psi$ such that by (4.18)

$$
\left|\gamma_{i}^{u}-\gamma_{j}^{v}\right|+\left|b_{i}^{u}-b_{j}^{v}\right| \leq C_{\delta}\left|Q_{i}^{u}-Q_{j}^{v}\right|+\left|b_{i}^{u}-b_{j}^{v}\right| \leq C_{\delta} \tau_{\psi}\left(f_{P_{k}^{u, v}} \psi\left(\left|\left(Q_{i}^{u}-Q_{j}^{v}\right) x+\left(b_{i}^{u}-b_{j}^{v}\right)\right|\right) \mathrm{d} x\right)
$$

Recall that $\mathcal{L}^{d}\left(P_{k}^{u, v}\right) \geq \delta$. For each $z_{1} \in P R(A), z_{2} \in P R(B)$, we let

$$
\begin{equation*}
\Lambda_{*}\left(z_{1}, z_{2}\right):=C_{\delta} \tau_{\psi}\left(\frac{1}{\delta} \int_{\left(A \backslash A^{\prime}\right) \cap B} \psi\left(\left|z_{1}-z_{2}\right|\right) \mathrm{d} x\right) \tag{4.27}
\end{equation*}
$$

if $\delta^{-1} \int_{\left(A \backslash A^{\prime}\right) \cap B} \psi\left(\left|z_{1}-z_{2}\right|\right) \mathrm{d} x<\sup _{t \in \mathbb{R}_{+}} \psi(t)$, and $\Lambda_{*}\left(z_{1}, z_{2}\right)=+\infty$ else. (Note that this is consistent with the definition below 4.17).) Recalling 4.19 we thus find that

$$
\begin{equation*}
\left\|u_{\text {par }}-v_{\text {par }}\right\|_{L^{\infty}\left(D_{\text {large }}\right)} \leq \Lambda_{*}(u, v)<+\infty \tag{4.28}
\end{equation*}
$$

where $D_{\text {large }}$ is defined in 4.23.
Let $\varphi \in C^{\infty}(A \cup B)$ be the function provided by Lemma 4.7 which satisfies $0 \leq \varphi \leq 1, \varphi=1$ in a neighborhood of $\overline{E_{T_{1}}}$, and $\operatorname{supp} \varphi \subset \subset E_{T_{2}}$. We define

$$
z_{\mathrm{par}}=\varphi u_{\mathrm{par}}+(1-\varphi) v_{\mathrm{par}} \in G S B V\left(A^{\prime} \cup B ; \mathbb{R}^{d_{L}} \times \mathbb{R}^{d}\right)
$$

As $u_{\text {par }}$ and $v_{\text {par }}$ are piecewise constant, we get $\nabla z_{\text {par }}=0$ on $\left(A^{\prime} \cup B\right) \backslash\{0<\varphi<1\}$ and $\nabla z_{\text {par }}=\nabla \varphi \otimes\left(u_{\text {par }}-v_{\text {par }}\right)$ on $\{0<\varphi<1\}$. By recalling the definition of $D_{\text {large }}$ and $D_{\text {good }}$ in 4.23 and 4.25 , respectively, we observe $D_{\text {good }} \cap\{0<\varphi<1\} \subset D_{\text {good }} \cap\left(E_{T_{2}} \backslash \overline{E_{T_{1}}}\right) \subset D_{\text {large }}$ up to an $\mathcal{L}^{d}$-negligible set, see Figure 1 . Therefore, we obtain by (4.28)
(i) $\left\|\max \left\{\left|z_{\text {par }}-u_{\text {par }}\right|,\left|z_{\text {par }}-v_{\text {par }}\right|\right\}\right\|_{L^{\infty}\left(D_{\text {large }}\right)} \leq\left\|u_{\text {par }}-v_{\text {par }}\right\|_{L^{\infty}\left(D_{\text {large }}\right)} \leq \Lambda_{*}(u, v)$,
(ii) $\left\|\nabla z_{\text {par }}\right\|_{L^{1}\left(D_{\text {good }}\right)} \leq\|\nabla \varphi\|_{\infty}\| \| u_{\text {par }}-v_{\text {par }}\left\|_{L^{1}\left(D_{\text {large }}\right)} \leq \mathcal{L}^{d}\left(A^{\prime} \cup B\right)\right\| \nabla \varphi \|_{\infty} \Lambda_{*}(u, v)$.

Moreover, since $J_{u}, J_{u_{\mathrm{par}}}$ and $J_{v}, J_{v_{\mathrm{par}}}$ coincide up to $\mathcal{H}^{d-1}$-negligible sets, we have

$$
\begin{equation*}
J_{z_{\text {par }}} \cap D_{\text {good }} \subset\left(\left(J_{u} \cap E_{T_{2}}\right) \cup\left(J_{v} \backslash \overline{E_{T_{1}}}\right)\right) \cap D_{\text {good }} \tag{4.30}
\end{equation*}
$$

up to an $\mathcal{H}^{d-1}$-negligible set.
Step 4 (Definition of the piecewise rigid function $w$ using $z_{\text {par }}$ ): We apply Theorem 4.9 for $z=z_{\text {par }}$, $D=D_{\text {good }}$, and for $\theta=\eta(2 \beta)^{-1} \mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right)$ to find a partition $\left(P_{k}\right)_{k}$ of $D_{\text {good }}$ and corresponding constants $\left(\gamma_{k}, b_{k}\right)_{k=1}^{\infty} \subset\left(-r_{L}, r_{L}\right)^{d_{L}} \times \mathbb{R}^{d}$ such that
(i) $\quad \sum_{k=1}^{\infty} \mathcal{H}^{d-1}\left(\left(\partial^{*} P_{k} \cap D_{\text {good }}\right) \backslash J_{z_{\text {par }}}\right) \leq \eta(2 \beta)^{-1} \mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right)$,
(ii) $\left\|z_{\text {par }}-\left(\gamma_{k}, b_{k}\right)\right\|_{L^{\infty}\left(P_{k}\right)} \leq C_{\eta}\left\|\nabla z_{\text {par }}\right\|_{L^{1}\left(D_{\text {good }}\right)} \quad$ for all $k \in \mathbb{N}$,
where $C_{\eta}>0$ depends on $\eta, \beta, A, A^{\prime}$, and $B$. We define $w_{\text {par }}=\sum_{k=1}^{\infty}\left(\gamma_{k}, b_{k}\right) \chi_{P_{k}}$ on $D_{\text {good }}$. By (4.12), 4.29) (ii), and 4.31 (ii) we obtain

$$
\left\|w_{\mathrm{par}}-z_{\mathrm{par}}\right\|_{L^{\infty}\left(D_{\mathrm{good}}\right)} \leq C_{\eta} \mathcal{L}^{d}\left(A^{\prime} \cup B\right)\|\nabla \varphi\|_{\infty} \Lambda_{*}(u, v) \leq C_{\eta} M_{\lambda} \Lambda_{*}(u, v)
$$

where in the last step we passed to a larger constant $C_{\eta}$. We observe that $D_{\text {good }}$ coincides with $\left(\left(A^{\prime} \cup B\right) \cap E_{T_{1}}\right) \cup\left(B \backslash \overline{E_{T_{2}}}\right) \cup D_{\text {large }}$ up to set of negligible $\mathcal{L}^{d}$-measure, see 4.25 and Figure 1 By 4.29 (i) and the fact that $z_{\text {par }}=u_{\text {par }}$ on $\left(A^{\prime} \cup B\right) \cap E_{T_{1}}, z_{\text {par }}=v_{\text {par }}$ on $B \backslash \overline{E_{T_{2}}}$, we get
(i) $\left\|w_{\text {par }}-u_{\text {par }}\right\|_{L^{\infty}\left(\left(A^{\prime} \cup B\right) \cap E_{T_{1}}\right)} \leq C_{\eta} M_{\lambda} \Lambda_{*}(u, v),\left\|w_{\text {par }}-v_{\text {par }}\right\|_{L^{\infty}\left(B \backslash E_{T_{2}}\right)} \leq C_{\eta} M_{\lambda} \Lambda_{*}(u, v)$,
(i) $\left\|\max \left\{\left|w_{\text {par }}-u_{\text {par }}\right|,\left|w_{\text {par }}-v_{\text {par }}\right|\right\}\right\|_{L^{\infty}\left(D_{\text {large }}\right)} \leq\left(1+C_{\eta} M_{\lambda}\right) \Lambda_{*}(u, v)$.

Define $w^{\text {good }} \in P R\left(D_{\text {good }}\right)$ by $w^{\text {good }}(x)=\sum_{k=1}^{\infty}\left(\Psi_{L}\left(\gamma_{k}\right) x+b_{k}\right) \chi_{P_{k}}(x)$. Recalling $A^{\prime} \cup B \subset B_{R}(0)$ by the choice of $R$, we get by 4.16
(i) $\left\|w^{\text {good }}-u\right\|_{L^{\infty}\left(\left(A^{\prime} \cup B\right) \cap E_{T_{1}}\right)} \leq \frac{1}{2} \Lambda(u, v), \quad\left\|w^{\text {good }}-v\right\|_{L^{\infty}\left(B \backslash E_{T_{2}}\right)} \leq \frac{1}{2} \Lambda(u, v)$,
(ii) $\left\|\max \left\{\left|w^{\text {good }}-u\right|,\left|w^{\text {good }}-v\right|\right\}\right\|_{L^{\infty}\left(D_{\text {large }}\right)} \leq \frac{1}{2} \Lambda(u, v)$,
where $\Lambda$ is defined by

$$
\begin{equation*}
\Lambda\left(z_{1}, z_{2}\right):=2\left(1+C_{L} R\right)\left(1+C_{\eta} M_{\lambda}\right) \Lambda_{*}\left(z_{1}, z_{2}\right) \quad \text { for } \quad z_{1} \in P R(A), z_{2} \in P R(B) \tag{4.33}
\end{equation*}
$$

We now define the piecewise rigid function $w \in P R\left(A^{\prime} \cup B\right)$ by

$$
w= \begin{cases}w^{\text {good }} & \text { on } D_{\text {good }}  \tag{4.34}\\ u & \text { on } D_{\text {bad }}\end{cases}
$$

In particular, this definition implies

$$
\begin{equation*}
\|w-u\|_{L^{\infty}\left(D_{\operatorname{good}} \cap E_{T_{2}}\right)} \leq \frac{1}{2} \Lambda(u, v), \quad\|w-v\|_{L^{\infty}\left(D_{\operatorname{good}} \backslash E_{T_{1}}\right)} \leq \frac{1}{2} \Lambda(u, v) \tag{4.35}
\end{equation*}
$$

In fact, this follows from 4.32 and the fact that $\left(E_{T_{2}} \backslash E_{T_{1}}\right) \cap D_{\text {good }} \subset D_{\text {large }}$, see 4.23 and 4.25 . We close this step of the proof by noticing that

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(\left(J_{w} \cap D_{\text {good }}\right) \backslash J_{z_{\text {par }}}\right) \leq \frac{\eta}{2 \beta} \mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right) \tag{4.36}
\end{equation*}
$$

which follows from the definition of $w^{\text {good }}$ and 4.31)(i).
Step 5 (Proof of (4.1)-(4.2) : Having defined $w$, it remains to confirm 4.1)-4.2). Recall the definition of $\Lambda$ in (4.33). In view of (4.27), (4.33), and the fact that $\tau_{\psi}(0)=0$, property (4.1) holds. By Fatou's lemma it is elementary to check that $\Lambda$ is lower semicontinuous. In particular, if $\psi(t)=t^{p}, 1 \leq p<\infty$, then $\Lambda\left(z_{1}, z_{2}\right)=M\left\|z_{1}-z_{2}\right\|_{L^{p}\left(\left(A \backslash A^{\prime}\right) \cap B\right)}$ for some $M>0$ sufficiently large since in this case $\tau_{\psi}(t)=c t^{1 / p}$, see Lemma 3.4.

Let us now show (4.2). We first observe that 4.2 (ii) follows from $4.34-4.35$. Thus, it remains to prove 4.2 (i). Recall the definition of $D_{\text {good }}$ and $D_{\text {bad }}$ in 4.25). By $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right),\left(\mathrm{H}_{4}\right)$, and the definition of $w$ we obtain

$$
\begin{align*}
\mathcal{F}\left(w, A^{\prime} \cup B\right) & =\mathcal{F}\left(w, D_{\text {good }}\right)+\mathcal{F}\left(w, \partial^{*} D_{\mathrm{bad}}\right)+\mathcal{F}\left(w, D_{\mathrm{bad}}\right) \\
& =\mathcal{F}\left(w, D_{\text {good }}\right)+\mathcal{F}\left(w, \partial^{*} D_{\mathrm{bad}}\right)+\mathcal{F}\left(u, J_{w} \cap D_{\mathrm{bad}}\right) . \tag{4.37}
\end{align*}
$$

It now suffices to show that there holds
(i) $\mathcal{F}\left(w, D_{\text {good }}\right) \leq \mathcal{F}\left(u, D_{\text {good }} \cap A \cap J_{w}\right)+\mathcal{F}\left(v, D_{\text {good }} \cap B \cap J_{w}\right)+\Delta$,
(ii) $\mathcal{F}\left(w, \partial^{*} D_{\mathrm{bad}}\right) \leq \Delta$,
where for brevity we set

$$
\left.\Delta=\left(\mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right)+\mathcal{F}(u, A)+\mathcal{F}(v, B)\right)\right)\left(\eta / 2+\alpha^{-1} \sigma(\Lambda(u, v))\right.
$$

In fact, once this is shown, 4.2 (i) follows from 4.37) for $M \geq 2 \alpha^{-1}$.
Proof of 4.38 (i). In view of $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{4}\right)$, and 4.30, we find

$$
\begin{equation*}
\mathcal{F}\left(w, D_{\text {good }}\right) \leq \sum_{j=1}^{3} \mathcal{F}\left(w, \Gamma_{j}\right) \tag{4.39}
\end{equation*}
$$

where we define

$$
\begin{aligned}
& \Gamma_{1}:=\left(J_{w} \cap D_{\text {good }}\right) \cap\left(J_{u} \cap E_{T_{2}}\right), \\
& \Gamma_{2}:=\left(J_{w} \cap D_{\text {good }}\right) \cap\left(J_{v} \backslash \overline{E_{T_{1}}}\right), \\
& \Gamma_{3}:=\left(J_{w} \cap D_{\text {good }}\right) \backslash J_{z_{\text {par }}} .
\end{aligned}
$$

We estimate each $\mathcal{F}\left(w, \Gamma_{j}\right)$ separately.
(1) For $\mathcal{H}^{d-1}$-a.e. $x \in \Gamma_{1}=J_{w} \cap J_{u} \cap E_{T_{2}} \cap D_{\text {good }}$, the one-sided approximate limits $w^{+}(x), w^{-}(x)$ of $w$ satisfy $\left|w^{+}(x)-u^{+}(x)\right|,\left|w^{-}(x)-u^{-}(x)\right| \leq \frac{1}{2} \Lambda(u, v)$ by 4.35, where we choose $\nu_{w}=\nu_{u}$ on $J_{w} \cap J_{u}$. This implies $\left|w^{+}(x)-u^{+}(x)\right|+\left|w^{-}(x)-u^{-}(x)\right| \leq \Lambda(u, v)$ for $\mathcal{H}^{d-1}$-a.e. $x \in \Gamma_{1}$. Thus, by $\left(\mathrm{H}_{4}\right)$ this yields

$$
\int_{\Gamma_{1}} \sigma\left(\left|w^{+}-u^{+}\right|+\left|w^{-}-u^{-}\right|\right) d \mathcal{H}^{d-1} \leq \mathcal{H}^{d-1}\left(J_{u}\right) \sigma(\Lambda(u, v)) \leq \alpha^{-1} \mathcal{F}(u, A) \sigma(\Lambda(u, v))
$$

where $\sigma$ is the modulus of continuity from $\left(\mathrm{H}_{5}{ }^{\prime}\right)$. This implies by $\left(\mathrm{H}_{5}{ }^{\prime}\right)$

$$
\begin{align*}
\mathcal{F}\left(w, \Gamma_{1}\right) & \leq \mathcal{F}\left(u, \Gamma_{1}\right)+\int_{\Gamma_{1}} \sigma\left(\left|w^{+}-u^{+}\right|+\left|w^{-}-u^{-}\right|\right) d \mathcal{H}^{d-1} \\
& \leq \mathcal{F}\left(u, \Gamma_{1}\right)+\alpha^{-1} \mathcal{F}(u, A) \sigma(\Lambda(u, v)) \tag{4.40}
\end{align*}
$$

(2) In a similar fashion, for $\mathcal{H}^{d-1}$-a.e. $x \in \Gamma_{2}$, we have $\left|w^{+}(x)-u^{+}(x)\right|+\left|w^{-}(x)-u^{-}(x)\right| \leq$ $2 \frac{1}{2} \Lambda(u, v)=\Lambda(u, v)$ by 4.35. Therefore, we have by $\left(\mathrm{H}_{4}\right)$ and $\left(\mathrm{H}_{5}{ }^{\prime}\right)$

$$
\begin{align*}
\mathcal{F}\left(w, \Gamma_{2}\right) & \leq \mathcal{F}\left(v, \Gamma_{2}\right)+\int_{\Gamma_{2}} \sigma\left(\left|w^{+}-u^{+}\right|+\left|w^{-}-u^{-}\right|\right) d \mathcal{H}^{d-1} \\
& \leq \mathcal{F}\left(v, \Gamma_{2}\right)+\alpha^{-1} \mathcal{F}(v, B) \sigma(\Lambda(u, v)) \tag{4.41}
\end{align*}
$$

(3) Finally, 4.36) and $\left(\mathrm{H}_{4}\right)$ imply

$$
\begin{equation*}
\mathcal{F}\left(w, \Gamma_{3}\right) \leq \beta \mathcal{H}^{d-1}\left(\left(J_{w} \cap D_{\text {good }}\right) \backslash J_{z_{\mathrm{par}}}\right) \leq \frac{\eta}{2} \mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right) \tag{4.42}
\end{equation*}
$$

By combining 4.39-4.42 we obtain 4.38(i).
Proof of 4.38 (ii). We use $\left(\mathrm{H}_{4}\right)$ and (4.26) to find

$$
\begin{equation*}
\mathcal{F}\left(w, \partial^{*} D_{\mathrm{bad}}\right) \leq \beta \mathcal{H}^{d-1}\left(\partial^{*} D_{\mathrm{bad}}\right) \leq \frac{\eta}{2}\left(\mathcal{F}(u, A)+\mathcal{F}(v, B)+\mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right)\right) \leq \Delta \tag{4.43}
\end{equation*}
$$

This concludes the proof.

Remark 4.10. For later purposes in the proof of Lemma 4.5. we observe that by the estimate on $\Gamma_{3}$ and $\partial^{*} D_{\text {bad }}$, see $4.42-4.43$, we have that

$$
\mathcal{H}^{d-1}\left(J_{w}\right) \leq \mathcal{H}^{d-1}\left(J_{u} \cup J_{v}\right)+\eta\left(\mathcal{F}(u, A)+\mathcal{F}(v, B)+\mathcal{H}^{d-1}\left(\partial A^{\prime} \cup \partial A \cup \partial B\right)\right)
$$

By $\left(\mathrm{H}_{4}\right)$ this yields

$$
\mathcal{H}^{d-1}\left(J_{w}\right) \leq(1+\eta) \alpha^{-1}\left(\mathcal{F}(u, A)+\mathcal{F}(v, B)+\mathcal{H}^{d-1}\left(\partial A^{\prime} \cup \partial A \cup \partial B\right)\right)
$$

Moreover, 4.35 implies that with $K:=\left\{x \in \mathbb{R}^{d}: \operatorname{dist}\left(x, A^{\prime}\right) \geq \frac{3}{4} d_{A^{\prime}, A}\right\}$ we get

$$
\|w-v\|_{L^{\infty}(B \cap K)} \leq \frac{1}{2} \Lambda(u, v)
$$

since $K \cap E_{T_{2}}=\emptyset$ and thus $B \cap K \subset D_{\text {good }} \backslash E_{T_{2}}$, see 4.25).
4.3. Proofs of Lemma 4.5 and Corollary 4.6. In this section we prove the fundamental estimate for piecewise rigid functions with boundary data and present a scaled version as corollary. We start with the proof of Lemma 4.5 .

Proof of Lemma 4.5. Let $A^{\prime}, A, B \in \mathcal{A}_{0}(\Omega)$ with $A^{\prime} \subset \subset A$ and $\eta>0$ be given. It is not restrictive to suppose that $0<\eta<1$. Set $U=A^{\prime} \cup B$ for brevity. We define $d_{A^{\prime}, A}=\operatorname{dist}\left(\partial A^{\prime}, \partial A\right)$ and $\delta=\left(d_{A^{\prime}, A} \alpha \eta /\left(24 \beta c_{\pi, d}\right)\right)^{d}$, where $c_{\pi, d}$ denotes the isoperimetric constant in dimension $d$, and $\alpha, \beta$ are the constants from $\left(\mathrm{H}_{4}\right)$. Choose $R>0$ such that $U \subset B_{R}(0)$. Let $c_{0} \geq 1$ be the constant in (3.4), depending on $R$ and $\delta$. Define $M_{1}=2 c_{0}$.

Let $u \in P R(A), v \in P R(B)$ be given and let $u=\sum_{j} q_{j}^{u} \chi_{P_{j}^{u}}$ and $v=\sum_{j} q_{j}^{v} \chi_{P_{j}^{v}}$ be their pairwise distinct representations. Suppose that 4.6) holds, where $\Lambda(u, v)$ is the function from 4.1). It is not restrictive to assume that $\Lambda(u, v)<+\infty$ is satisfied, so that in particular 4.17) holds. Otherwise, the result follows exactly as discussed below 4.17). We apply Lemma 4.1 on $u$ and $v$, and denote by $z \in P R(U)$ the piecewise rigid function satisfying 4.2). By recalling Remark 4.10 and using $0<\eta<1$, we also find

$$
\begin{align*}
& \text { (i) } \mathcal{H}^{d-1}\left(J_{z}\right) \leq 2 \alpha^{-1}\left(\mathcal{F}(u, A)+\mathcal{F}(v, B)+\mathcal{H}^{d-1}\left(\partial A^{\prime} \cup \partial A \cup \partial B\right)\right) \text {, } \\
& \text { (ii) }\|z-v\|_{L^{\infty}(B \cap K)} \leq \frac{1}{2} \Lambda(u, v) \tag{4.44}
\end{align*}
$$

where $K:=\left\{x \in \mathbb{R}^{d}: \operatorname{dist}\left(x, A^{\prime}\right) \geq \frac{3}{4} d_{A^{\prime}, A}\right\}$.
We let $z=\sum_{i} q_{i}^{z} \chi_{P_{i}^{z}} \in P R(U)$ be the corresponding pairwise distinct representation. We first identify the small components which are given by the sets $\left(P_{i}^{v} \cap P_{j}^{z}\right)_{i, j \in \mathbb{N}}$ of measure smaller than $\delta$ (Step 1). Then we consider the other components and show, by means of condition 4.6), that for each $P_{i}^{z}$ there is at most one component $P_{j}^{v}$ such that the measure of $P_{i}^{z} \cap P_{j}^{v}$ exceeds $\delta$. We prove that the difference of the affine mappings $q_{i}^{z}$ and $q_{j}^{v}$ can be controlled suitably (Step 2). Starting from $z$, we then define $w$ where the main idea in the definition is to replace $z$ on each $P_{i}^{z}$ by $v$ near $B \backslash A$ and by $q_{j}^{v}$ otherwise (Step 3). This allows to show that the correct boundary values are attained. Moreover, the control on the difference of the affine mappings yields that the energy increases only slightly by passing from $z$ to $w$ (Step 4).
Step 1 (Small components): Let $\left(P_{k}^{v, z}\right)_{k}$ be the partition of $B$ consisting of the nonempty sets $P_{i}^{z} \cap P_{j}^{v}, i, j \in \mathbb{N}$. Let $J_{\text {small }}^{v, z}=\left\{k \in \mathbb{N}: \mathcal{L}^{d}\left(P_{k}^{v, z} \cap K\right)<\delta\right\}$ and $J_{\text {large }}^{v, z}=\mathbb{N} \backslash J_{\text {small }}^{v, z}$. We define $F_{\text {small }}=\bigcup_{k \in J_{\text {small }}^{v, z}} P_{k}^{v, z}$ and observe by (3.1) that

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(\left(\partial^{*} F_{\text {small }} \cap B\right) \backslash\left(J_{v} \cup J_{z}\right)\right)=0 \tag{4.45}
\end{equation*}
$$

By using the isoperimetric inequality we get

$$
\begin{aligned}
\mathcal{L}^{d}\left(F_{\text {small }} \cap K\right) & =\sum_{k \in J_{\text {small }}^{v, z}} \mathcal{L}^{d}\left(P_{k}^{v, z} \cap K\right) \leq \delta^{1 / d} \sum_{k \in J_{\text {small }}^{v, z}}\left(\mathcal{L}^{d}\left(P_{k}^{v, z}\right)\right)^{(d-1) / d} \\
& \leq \delta^{1 / d} c_{\pi, d} \sum_{k \in J_{\text {small }}^{v, z}} \mathcal{H}^{d-1}\left(\partial^{*} P_{k}^{v, z}\right) \\
& \leq 2 \delta^{1 / d} c_{\pi, d}\left(\mathcal{H}^{d-1}\left(J_{v}\right)+\mathcal{H}^{d-1}\left(J_{z}\right)+\mathcal{H}^{d-1}(\partial B)\right)
\end{aligned}
$$

where the last step follows from (3.1) and Theorem 3.1. Similar to the proof of Lemma 4.7 , we cut small components. For $t>0$ define

$$
E_{t}:=\left\{x \in \mathbb{R}^{d}: \operatorname{dist}\left(x, A^{\prime}\right)<t\right\}
$$

and observe that $E_{t} \cap(U \backslash A)=\emptyset$ for all $t \in\left(0, d_{A^{\prime}, A}\right)$. By repeating the argument leading to (4.14), we find $T \in\left(\frac{3}{4} d_{A^{\prime}, A}, d_{A^{\prime}, A}\right)$ such that

$$
\begin{align*}
\mathcal{H}^{d-1}\left(F_{\text {small }} \cap \partial E_{T}\right) & =\mathcal{H}^{d-1}\left(\left(F_{\text {small }} \cap K\right) \cap \partial E_{T}\right) \leq 4 d_{A^{\prime}, A}^{-1} \mathcal{L}^{d}\left(F_{\text {small }} \cap K\right) \\
& \leq 8 \delta^{1 / d} d_{A^{\prime}, A}^{-1} c_{\pi, d}\left(\mathcal{H}^{d-1}\left(J_{v}\right)+\mathcal{H}^{d-1}\left(J_{z}\right)+\mathcal{H}^{d-1}(\partial B)\right) \tag{4.46}
\end{align*}
$$

Step 2 (Large components): For each $i \in \mathbb{N}$, we define

$$
\begin{equation*}
J_{i}=\left\{j \in \mathbb{N}: \exists k \in J_{\text {large }}^{v, z} \text { such that } P_{k}^{v, z}=P_{i}^{z} \cap P_{j}^{v}\right\} \tag{4.47}
\end{equation*}
$$

and observe that for each $i \in \mathbb{N}$

$$
\begin{equation*}
\bigcup_{j \in J_{i}}\left(P_{i}^{z} \cap P_{j}^{v}\right)=P_{i}^{z} \cap \bigcup_{k \in J_{\text {large }}^{v, z}} P_{k}^{v, z}=P_{i}^{z} \cap\left(B \backslash F_{\text {small }}\right), \tag{4.48}
\end{equation*}
$$

where in the last step we used the definition of $F_{\text {small }}$ before 4.45. We point out that $J_{i}=\emptyset$ is possible. In this case, 4.48 still holds because both sides of the equality are empty.

We now provide some properties of the sets $J_{i}$. For each $i \in \mathbb{N}$ and each $j \in J_{i}$, we choose $k \in J_{\text {large }}^{v, z}$ such that $P_{k}^{v, z}=P_{i}^{z} \cap P_{j}^{v}$. Since $U \subset B_{R}(0)$ and $\mathcal{L}^{d}\left(P_{k}^{v, z} \cap K\right) \geq \delta$, by (3.4) we have $\left\|q_{i}^{z}-q_{j}^{v}\right\|_{L^{\infty}(U)} \leq c_{0}\left\|q_{i}^{z}-q_{j}^{v}\right\|_{L^{\infty}\left(P_{k}^{u, v} \cap K\right)}$. By using the fact that $v=q_{j}^{v}$ and $z=q_{i}^{z}$ on $P_{k}^{v, z}$, by recalling $M_{1}=2 c_{0}$, and applying 4.44 (ii) we derive

$$
\begin{equation*}
\left\|q_{i}^{z}-q_{j}^{v}\right\|_{L^{\infty}(U)} \leq c_{0}\left\|q_{i}^{z}-q_{j}^{v}\right\|_{L^{\infty}\left(P_{k}^{u, v} \cap K\right)} \leq c_{0}\|v-z\|_{L^{\infty}(B \cap K)} \leq \frac{1}{4} M_{1} \Lambda(u, v) \tag{4.49}
\end{equation*}
$$

We now show that

$$
\begin{equation*}
\# J_{i} \leq 1 \quad \text { for all } i \in \mathbb{N} \text {. } \tag{4.50}
\end{equation*}
$$

In fact, assume by contradiction that for some $i$ there exist two different $j, j^{\prime} \in J_{i}$. Then 4.49 together with the triangle inequality yields

$$
\left\|q_{j}^{v}-q_{j^{\prime}}^{v}\right\|_{L^{\infty}(U)} \leq \frac{1}{2} M_{1} \Lambda(u, v)
$$

Moreover, by 4.47 and the definition of $J_{\text {large }}^{v, z}$ we have $\mathcal{L}^{d}\left(P_{j}^{v}\right) \geq \delta$ and $\mathcal{L}^{d}\left(P_{j^{\prime}}^{v}\right) \geq \delta$. In view of (4.4) and the fact that $j \neq j^{\prime}$, this yields $0<\Phi\left(A^{\prime}, U ;\left.v\right|_{B \backslash \overline{A^{\prime}}}, \delta\right) \leq \frac{1}{2} M_{1} \Lambda(u, v)$. This, however, contradicts 4.6). In the following, the unique index in $J_{i}$, if existent, will be denoted by $j_{i}$.
Step 3 (Definition of $w$ ): We now introduce the piecewise rigid function $w$. We define $w: U \rightarrow \mathbb{R}^{d}$ on each $P_{i}$ separately by distinguishing the two cases $\# J_{i}=1$ and $\# J_{i}=0$, see 4.50. Recall $E_{T}$ defined before (4.46) and the fact that $\mathbb{R}^{d} \backslash E_{T} \subset K$. We let

$$
\begin{array}{rll}
w=q_{j_{i}}^{v} \text { on } P_{i}^{z} \cap E_{T}, & w=v \text { on } P_{i}^{z} \backslash E_{T} & \text { if } \# J_{i}=1 \\
w=z \text { on } P_{i}^{z} \cap E_{T}, & w=v \text { on } P_{i}^{z} \backslash E_{T} & \text { if } \# J_{i}=0, \tag{4.51}
\end{array}
$$

where $j_{i} \in J_{i}$ is the index corresponding to $i \in \mathbb{N}$. Clearly, $w \in P R(U)$ is well defined and piecewise rigid since $v \in P R(B)$ and $U \backslash E_{T} \subset K \cap B$. For later purposes, we observe that up to sets of negligible $\mathcal{H}^{d-1}$-measure there holds

$$
\begin{align*}
& \text { (i) } J_{w} \cap\left(J_{v} \backslash J_{z}\right) \subset K \cap B \\
& \text { (ii) } J_{w} \backslash\left(J_{z} \cup J_{v}\right) \subset F_{\text {small }} \cap \partial E_{T}, \tag{4.52}
\end{align*}
$$

where $F_{\text {small }} \subset B$ was defined before (4.45). Indeed, property (i) follows from (4.51) and the fact that $U \backslash E_{T} \subset K \cap B$. To see (ii), we first observe that Theorem 3.1, (3.1), and (4.51) imply (up to sets of negligible $\mathcal{H}^{d-1}$-measure)

$$
J_{w} \backslash\left(J_{z} \cup J_{v}\right) \subset J_{w} \cap \partial E_{T} \cap \bigcup_{i \in \mathbb{N}}\left(P_{i}^{z}\right)^{1} \subset\left(\partial E_{T} \cap F_{\text {small }}\right) \cup \bigcup_{i \in \mathbb{N}}\left(J_{w} \cap\left(P_{i}^{z}\right)^{1} \cap\left(\partial E_{T} \backslash F_{\text {small }}\right)\right)
$$

By using 4.48) we have $P_{i}^{z} \cap\left(B \backslash F_{\text {small }}\right)=\emptyset$ if $\# J_{i}=0$ and $P_{i}^{z} \cap\left(B \backslash F_{\text {small }}\right)=P_{i}^{z} \cap P_{j_{i}}^{v}$ for $\# J_{i}=1$. In view of 4.51), we also observe that $w$ does not jump on $P_{i}^{z} \cap P_{j_{i}}^{v} \cap \partial E_{T}$ for $\# J_{i}=1$. In both cases, we thus have $\mathcal{H}^{d-1}\left(J_{w} \cap\left(P_{i}^{z}\right)^{1} \cap\left(\partial E_{T} \backslash F_{\text {small }}\right)\right)=0$. This yields 4.52 (ii). Step 4 (Proof of 4.7) ): We define

$$
\begin{equation*}
\Theta\left(z_{1}, z_{2}\right)=\left(\frac{1}{2} M_{1}+1\right) \Lambda\left(z_{1}, z_{2}\right) \quad \text { for } \quad z_{1} \in P R(A), z_{2} \in P R(B) \tag{4.53}
\end{equation*}
$$

where $\Lambda$ is given in 4.1). Then, if $\psi(t)=t^{p}, 1 \leq p<\infty, \Theta$ has the form $\Theta(u, v)=M_{2} \| u-$ $v \|_{L^{p}\left(\left(A \backslash A^{\prime}\right) \cap B\right)}$ for some $M_{2}$ sufficiently large.

We now establish 4.7). First, 4.7 (iii) follows directly from 4.51) and the fact that $B \backslash A=$ $U \backslash A \subset U \backslash E_{T}$. As a preparation for (4.7)(ii), we observe that

$$
\begin{equation*}
\|w-z\|_{L^{\infty}(U)} \leq \frac{1}{4} M_{1} \Lambda(u, v) \tag{4.54}
\end{equation*}
$$

In fact, on $U \backslash E_{T} \subset B \cap K$ we have $w=v$ by (4.51), hence the inequality holds by (4.44)(ii) and the fact that $M_{1} \geq 2$. On the other hand, on each $P_{i}^{z} \cap E_{T}$, we either have $w=z$, if $\# J_{i}=0$, or we can apply 4.49 for $j=j_{i}$, if $\# J_{i}=1$. In both cases, 4.54 follows. This along with 4.2 (ii) (applied for $z$ in place of $w$ ) and 4.53 yields 4.7 (ii).

Finally, we prove 4.7 (i). In view of $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{4}\right)$, we have

$$
\begin{equation*}
\mathcal{F}(w, U) \leq \sum_{j=1}^{3} \mathcal{F}\left(w, \Gamma_{j}\right) \tag{4.55}
\end{equation*}
$$

where we define

$$
\Gamma_{1}:=J_{w} \cap J_{z}, \quad \Gamma_{2}:=J_{w} \cap\left(J_{v} \backslash J_{z}\right), \quad \Gamma_{3}:=J_{w} \backslash\left(J_{z} \cup J_{v}\right)
$$

We estimate each $\mathcal{F}\left(w, \Gamma_{j}\right)$ separately.
(1) For $\mathcal{H}^{d-1}$-a.e. $x \in \Gamma_{1}$, the one-sided approximate limits $w^{+}(x)$, $w^{-}(x)$ of $w$ satisfy $\mid w^{+}(x)-$ $z^{+}(x)\left|,\left|w^{-}(x)-z^{-}(x)\right| \leq \frac{1}{4} M_{1} \Lambda(u, v)\right.$ by (4.54), where we choose $\nu_{w}=\nu_{z}$ on $J_{w} \cap J_{z}$. This implies $\left|w^{+}(x)-z^{+}(x)\right|+\left|w^{-}(x)-z^{-}(x)\right| \leq \frac{1}{2} M_{1} \Lambda(u, v) \leq \Theta(u, v)$ for $\mathcal{H}^{d-1}$-a.e. $x \in \Gamma_{1}$, where we used (4.53). Thus, by $\left(\mathrm{H}_{5}{ }^{\prime}\right)$ this yields

$$
\mathcal{F}\left(w, \Gamma_{1}\right) \leq \mathcal{F}\left(z, \Gamma_{1}\right)+\int_{\Gamma_{1}} \sigma\left(\left|w^{+}-z^{+}\right|+\left|w^{-}-z^{-}\right|\right) d \mathcal{H}^{d-1} \leq \mathcal{F}(z, U)+\mathcal{H}^{d-1}\left(J_{z}\right) \sigma(\Theta(u, v))
$$

where $\sigma$ is the modulus of continuity from $\left(\mathrm{H}_{5}{ }^{\prime}\right)$. Then by 4.2 (i) (applied for $\mathcal{F}(z, U)$ ) and 4.44 (i) we get

$$
\begin{align*}
\mathcal{F}\left(w, \Gamma_{1}\right) \leq & \mathcal{F}\left(u, A \cap J_{z}\right)+\mathcal{F}\left(v, B \cap J_{z}\right)  \tag{4.56}\\
& +\left(\mathcal{H}^{d-1}\left(\partial A \cup \partial A^{\prime} \cup \partial B\right)+\mathcal{F}(u, A)+\mathcal{F}(v, B)\right)\left(\eta+M \sigma(\Lambda(u, v))+2 \alpha^{-1} \sigma(\Theta(u, v))\right)
\end{align*}
$$

(2) In a similar fashion, for $\mathcal{H}^{d-1}$-a.e. $x \in \Gamma_{2}$, we have $\left|w^{+}(x)-v^{+}(x)\right|,\left|w^{-}(x)-v^{-}(x)\right| \leq$ $\frac{1}{4}\left(M_{1}+2\right) \Lambda(u, v)$ by (4.44), 4.54), and the fact that $\Gamma_{2} \subset K \cap B$, see 4.52 (i). Thus, we get $\left|w^{+}(x)-z^{+}(x)\right|+\left|w^{-}(x)-z^{-}(x)\right| \leq\left(\frac{1}{2} M_{1}+1\right) \Lambda(u, v)=\Theta(u, v)$ by 4.53). Therefore, we obtain by $\left(\mathrm{H}_{4}\right)$ and $\left(\mathrm{H}_{5}{ }^{\prime}\right)$

$$
\begin{align*}
\mathcal{F}\left(w, \Gamma_{2}\right) & \leq \mathcal{F}\left(v, \Gamma_{2}\right)+\int_{\Gamma_{2}} \sigma\left(\left|w^{+}-z^{+}\right|+\left|w^{-}-z^{-}\right|\right) d \mathcal{H}^{d-1} \\
& \leq \mathcal{F}\left(v, \Gamma_{2}\right)+\mathcal{H}^{d-1}\left(J_{v}\right) \sigma(\Theta(u, v)) \leq \mathcal{F}\left(v, B \backslash J_{z}\right)+\alpha^{-1} \mathcal{F}(v, B) \sigma(\Theta(u, v)) \tag{4.57}
\end{align*}
$$

(3) Finally, 4.44 (i), 4.46), 4.52 (ii), and $\left(\mathrm{H}_{4}\right)$ imply

$$
\begin{align*}
\mathcal{F}\left(w, \Gamma_{3}\right) & \leq \beta \mathcal{H}^{d-1}\left(F_{\text {small }} \cap \partial E_{T}\right) \leq 8 \beta \delta^{1 / d} d_{A^{\prime}, A}^{-1} c_{\pi, d}\left(\mathcal{H}^{d-1}\left(J_{v}\right)+\mathcal{H}^{d-1}\left(J_{z}\right)+\mathcal{H}^{d-1}(\partial B)\right) \\
& \leq 8 \beta \delta^{1 / d} d_{A^{\prime}, A}^{-1} c_{\pi, d} 3 \alpha^{-1}\left(\mathcal{F}(u, A)+\mathcal{F}(v, B)+\mathcal{H}^{d-1}\left(\partial A^{\prime} \cup \partial A \cup \partial B\right)\right) \\
& \leq \eta\left(\mathcal{F}(u, A)+\mathcal{F}(v, B)+\mathcal{H}^{d-1}\left(\partial A^{\prime} \cup \partial A \cup \partial B\right)\right) \tag{4.58}
\end{align*}
$$

where in the last step we used the definition $\delta=\left(d_{A^{\prime}, A} \alpha \eta /\left(24 \beta c_{\pi, d}\right)\right)^{d}$. Define $M_{2}=M+3 \alpha^{-1}$ and recall $\Theta(u, v) \geq \Lambda(u, v)$ by 4.53, as well as that $\sigma$ is increasing. By combining 4.55 4.58) and using $\left(\mathrm{H}_{1}\right)$ we obtain 4.7)(i). This concludes the proof.

We now close this section with the proof of Corollary 4.6.
Proof of Corollary 4.6. We suppose that $A^{\prime}, A, B \in \mathcal{A}_{0}(\Omega)$ with $A^{\prime} \subset \subset A$ are given such that $\rho A^{\prime}, \rho A, \rho B \subset \Omega$. Let $U=A^{\prime} \cup B$. Let $M$ be the constant of Lemma 4.1 and $M_{1}, M_{2}, \delta$ be the constants of Lemma 4.5 (applied for $\psi(t)=t)$. For brevity, set $C_{A^{\prime}, A, B}=\mathcal{H}^{d-1}\left(\partial A^{\prime} \cup \partial A \cup \partial B\right)$.

Given $\mathcal{F}: P R(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ satisfying $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{4}\right)$ and $\left(\mathrm{H}_{5}{ }^{\prime}\right)$, we define $\mathcal{F}^{\rho}:$ $P R\left(\rho^{-1} \Omega\right) \times \mathcal{B}\left(\rho^{-1} \Omega\right) \rightarrow[0, \infty)$ by

$$
\begin{equation*}
\mathcal{F}^{\rho}(z, B)=\rho^{-(d-1)} \mathcal{F}\left(z_{\rho}, \rho B\right) \tag{4.59}
\end{equation*}
$$

for all $z \in P R\left(\rho^{-1} \Omega\right)$ and $B \in \mathcal{B}\left(\rho^{-1} \Omega\right)$, where $z_{\rho} \in P R(\Omega)$ is defined by $z_{\rho}(x):=z(x / \rho)$. Then it is elementary to check that also $\mathcal{F}^{\rho}$ satisfies $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{4}\right)$ and $\left(\mathrm{H}_{5}{ }^{\prime}\right)$.

Let $u_{\rho} \in P R(\rho A)$ and $v_{\rho} \in P R(\rho B)$. We define $u \in P R(A)$ by $u(x)=u_{\rho}(\rho x)$ and $v \in P R(B)$ by $v(x)=v_{\rho}(\rho x)$. Note that a scaling argument yields

$$
\begin{equation*}
\rho^{-d}\left\|u_{\rho}-v_{\rho}\right\|_{L^{1}\left(\rho\left(A \backslash A^{\prime}\right) \cap \rho B\right)}=\|u-v\|_{L^{1}\left(\left(A \backslash A^{\prime}\right) \cap B\right)} . \tag{4.60}
\end{equation*}
$$

Assumption 4.9) and 4.60 imply

$$
\begin{aligned}
M M_{1}\|u-v\|_{L^{1}\left(\left(A \backslash A^{\prime}\right) \cap B\right)} & =\rho^{-d} M M_{1}\left\|u_{\rho}-v_{\rho}\right\|_{L^{1}\left(\left(\rho A \backslash \rho A^{\prime}\right) \cap \rho B\right)} \\
& \leq \Phi\left(\rho A^{\prime}, \rho A^{\prime} \cup \rho B ;\left.v_{\rho}\right|_{\rho B \backslash \rho \overline{A^{\prime}}}, \rho^{d} \delta\right)=\Phi\left(A^{\prime}, A^{\prime} \cup B ;\left.v\right|_{B \backslash \overline{A^{\prime}}}, \delta\right) .
\end{aligned}
$$

We apply Lemma 4.5 on $u$ and $v$ for $\psi(t)=t$ and $\mathcal{F}^{\rho}$, where we note that in this case $\Lambda\left(z_{1}, z_{2}\right)=$ $M\left\|z_{1}-z_{2}\right\|_{L^{1}\left(\left(A \backslash A^{\prime}\right) \cap B\right)}$, see Lemma 4.1. We obtain $w \in P R\left(A^{\prime} \cup B\right)$ such that
(i) $\mathcal{F}^{\rho}\left(w, A^{\prime} \cup B\right) \leq \mathcal{F}^{\rho}(u, A)+\mathcal{F}^{\rho}(v, B)$

$$
+\left(C_{A^{\prime}, A, B}+\mathcal{F}^{\rho}(u, A)+\mathcal{F}^{\rho}(v, B)\right)\left(2 \eta+M_{2} \sigma\left(M_{2}\|u-v\|_{L^{1}\left(\left(A \backslash A^{\prime}\right) \cap B\right)}\right)\right)
$$

(ii) $\|\min \{|w-u|,|w-v|\}\|_{L^{\infty}\left(A^{\prime} \cup B\right)} \leq M_{2}\|u-v\|_{L^{1}\left(\left(A \backslash A^{\prime}\right) \cap B\right)}$,
(iii) $w=v$ on $B \backslash A$.

Define $w_{\rho} \in P R\left(\rho A^{\prime} \cup \rho B\right)$ by $w_{\rho}(x)=w(x / \rho)$. Then 4.10 follows from the estimates on $w$ along with 4.59-4.60).

## 5. Integral representation in $P R(\Omega)$

This section is devoted to the proof of Theorem 2.2. In Section 5.1 we show how Theorem 2.2 can be deduced from two auxiliary lemmas whose proofs are given in Section 5.2 . In Section 5.3 we also present a generalization which will be instrumental in Section 6 .
5.1. Proof of Theorem 2.2. Let $\mathcal{F}: P R(\Omega) \times \mathcal{A}(\Omega) \rightarrow[0, \infty)$ and $u \in P R(\Omega)$. We first state that $\mathcal{F}$ is equivalent to $\mathbf{m}_{\mathcal{F}}$ (see 2.4 ) in the sense that the two quantities have the same Radon-Nykodym derivative with respect to $\mathcal{H}^{d-1}\left\lfloor_{J_{u} \cap \Omega}\right.$.
Lemma 5.1. Suppose that $\mathcal{F}$ satisfies $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$. Let $u \in P R(\Omega)$ and $\mu=\mathcal{H}^{d-1}\left\lfloor_{J_{u} \cap \Omega}\right.$. Then for $\mu$-a.e. $x_{0} \in \Omega$ we have

$$
\lim _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\mu\left(B_{\varepsilon}\left(x_{0}\right)\right)}=\lim _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\mu\left(B_{\varepsilon}\left(x_{0}\right)\right)} .
$$

We defer the proof of Lemma 5.1 to Section 5.2. The second ingredient is that, asymptotically as $\varepsilon \rightarrow 0$, the minimization problems $\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)$ and $\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{\varepsilon}\left(x_{0}\right)\right)$ coincide for $\mathcal{H}^{d-1}$-a.e. $x_{0} \in J_{u}$, where we write $\bar{u}_{x_{0}}:=u_{x_{0},[u]\left(x_{0}\right), \nu_{u}\left(x_{0}\right)}$ for brevity, see 2.5).

Lemma 5.2. Suppose that $\mathcal{F}$ satisfies $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{5}\right)$. Then for $\mathcal{H}^{d-1}$-a.e. $x_{0} \in J_{u}$ we have

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}}=\limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}} . \tag{5.1}
\end{equation*}
$$

We defer the proof of Lemma 5.2 also to Section 5.2 and now proceed to prove Theorem 2.2
Proof of Theorem 2.2. We need to show that for $\mathcal{H}^{d-1}$-a.e. $x_{0} \in J_{u}$ one has

$$
\frac{\mathrm{d} \mathcal{F}(u, \cdot)}{\mathrm{d} \mathcal{H}^{d-1}\left\lfloor J_{u}\right.}\left(x_{0}\right)=f\left(x_{0},[u]\left(x_{0}\right), \nu_{u}\left(x_{0}\right)\right)
$$

where $f$ was defined in 2.7). By Lemma 5.1 and the fact that $\lim _{\varepsilon \rightarrow 0}\left(\omega_{d-1} \varepsilon^{d-1}\right)^{-1} \mu\left(B_{\varepsilon}\left(x_{0}\right)\right)=1$ for $\mathcal{H}^{d-1}$-a.e. $x_{0} \in J_{u}$ we deduce

$$
\frac{\mathrm{d} \mathcal{F}(u, \cdot)}{\mathrm{d} \mathcal{H}^{d-1}\left\lfloor J_{u}\right.}\left(x_{0}\right)=\lim _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\mu\left(B_{\varepsilon}\left(x_{0}\right)\right)}=\lim _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\mu\left(B_{\varepsilon}\left(x_{0}\right)\right)}=\lim _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}}<\infty
$$

for $\mathcal{H}^{d-1}$-a.e. $x_{0} \in J_{u}$. The statement now follows from 2.7 and Lemma 5.2 ,
5.2. Proof of Lemmata 5.1 and 5.2. For the proof of Lemma 5.1, we basically follow the lines of [17, 18, 35], with the difference that the required compactness results are more delicate due to the weaker growth condition from below $\left(\right.$ see $\left(\mathrm{H}_{4}\right)$ ) compared to [17, 18, 35]. We start with some notation. We set $c_{d}$ as the dimensional constant

$$
c_{d}:=\frac{1}{2} \frac{\omega_{d-1}}{d \omega_{d}} .
$$

For $\delta>0$ and $A \in \mathcal{A}(\Omega)$ we define

$$
\begin{align*}
\mathbf{m}_{\mathcal{F}}^{\delta}(u, A)=\inf \{ & \sum_{i=1}^{\infty} \mathbf{m}_{\mathcal{F}}\left(u, B_{i}\right): B_{i} \subset A \text { pairwise disjoint balls, diam }\left(B_{i}\right) \leq \delta \\
& \left.\mathcal{H}^{d-1}\left(B_{i} \cap J_{u}\right) \geq c_{d} \mathcal{H}^{d-1}\left(\partial B_{i}\right), \mathcal{H}^{d-1}\left(J_{u} \cap\left(A \backslash \bigcup_{i=1}^{\infty} B_{i}\right)\right)=0\right\} \tag{5.2}
\end{align*}
$$

and, as $\mathbf{m}_{\mathcal{F}}^{\delta}(u, A)$ is decreasing in $\delta$, we can also introduce

$$
\begin{equation*}
\mathbf{m}_{\mathcal{F}}^{*}(u, A)=\lim _{\delta \rightarrow 0} \mathbf{m}_{\mathcal{F}}^{\delta}(u, A) . \tag{5.3}
\end{equation*}
$$

Notice that the existence of coverings as in (5.2) follows from the Morse covering theorem (see, e.g., [44. Theorem 1.147]), provided one observes that at $\mathcal{H}^{d-1}$-a.e. $x \in J_{u}$, there holds by rectifiability

$$
\lim _{\delta \rightarrow 0} \frac{\mathcal{H}^{d-1}\left(J_{u} \cap B_{\delta}(x)\right)}{\mathcal{H}^{d-1}\left(\partial B_{\delta}(x)\right)}=2 c_{d}
$$

Lemma 5.3. Suppose that $\mathcal{F}$ satisfies $\left(\mathrm{H}_{1}\right)$, $\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{4}\right)$. Let $u \in P R(\Omega)$ and $\mu=\mathcal{H}^{d-1}\left\lfloor J_{u} \cap \Omega\right.$. If $\mathcal{F}(u, A)=\mathbf{m}_{\mathcal{F}}^{*}(u, A)$ for all $A \in \mathcal{A}(\Omega)$, then for $\mu$-a.e. $x_{0} \in \Omega$ we have

$$
\lim _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\mu\left(B_{\varepsilon}\left(x_{0}\right)\right)}=\lim _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\mu\left(B_{\varepsilon}\left(x_{0}\right)\right)} .
$$

Proof. The statement follows by repeating exactly the arguments in [35, Proofs of Lemma 4.2 and Lemma 4.3]. Note that the assumption $\mathcal{F}(u, A)=\mathbf{m}_{\mathcal{F}}^{*}(u, A)$ enters the proof at the very end of [35, Proof of Lemma 4.3] and replaces the application of [35, Lemma 4.1].

In view of Lemma 5.3 in order to see that $\mathcal{F}$ and $\mathbf{m}_{\mathcal{F}}$ have the same Radon-Nykodym derivative with respect to $\mathcal{H}^{d-1}\left\lfloor_{J_{u} \cap \Omega}\right.$, it remains to show the following.

Lemma 5.4. Suppose that $\mathcal{F}$ satisfies $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$. Then for all $u \in P R(\Omega)$ and all $A \in \mathcal{A}(\Omega)$ there holds $\mathcal{F}(u, A)=\mathbf{m}_{\mathcal{F}}^{*}(u, A)$.

Proof. We follow the proof of [35, Lemma 4.1] and only indicate the necessary changes. For each ball $B \subset A$ we have $\mathbf{m}_{\mathcal{F}}(u, B) \leq \mathcal{F}(u, B)$ by definition. By $\left(\mathrm{H}_{1}\right)$ we get $\mathbf{m}_{\mathcal{F}}^{\delta}(u, A) \leq \mathcal{F}(u, A)$ for all $\delta>0$. This shows $\mathbf{m}_{\mathcal{F}}^{*}(u, A) \leq \mathcal{F}(u, A)$, see (5.3).

We now address the reverse inequality. We fix $A \in \mathcal{A}(\Omega)$ and $\delta>0$. Let $\left(B_{i}^{\delta}\right)_{i}$ be balls as in the definition of $\mathbf{m}_{\mathcal{F}}^{\delta}(u, A)$ such that

$$
\begin{equation*}
\sum_{i=1}^{\infty} \mathbf{m}_{\mathcal{F}}\left(u, B_{i}^{\delta}\right) \leq \mathbf{m}_{\mathcal{F}}^{\delta}(u, A)+\delta \tag{5.4}
\end{equation*}
$$

By the definition of $\mathbf{m}_{\mathcal{F}}$, we find $v_{i}^{\delta} \in P R\left(B_{i}^{\delta}\right)$ such that $v_{i}^{\delta}=u$ in a neighborhood of $\partial B_{i}^{\delta}$ and

$$
\begin{equation*}
\mathcal{F}\left(v_{i}^{\delta}, B_{i}^{\delta}\right) \leq \mathbf{m}_{\mathcal{F}}\left(u, B_{i}^{\delta}\right)+\delta \mathcal{L}^{d}\left(B_{i}^{\delta}\right) \tag{5.5}
\end{equation*}
$$

We define

$$
v^{\delta}=\sum_{i=1}^{\infty} v_{i}^{\delta} \chi_{B_{i}^{\delta}}+u \chi_{N_{0}^{\delta}},
$$

where $N_{0}^{\delta}:=\Omega \backslash \bigcup_{i=1}^{\infty} B_{i}^{\delta}$. By (5.4)-(5.5) and $\left(\mathrm{H}_{4}\right)$ we get $\mathcal{H}^{d-1}\left(J_{v^{\delta}}\right)<+\infty$. Thus, by construction, we obtain $v^{\delta} \in P R(\Omega)$. Moreover, by $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right)$, and 5.4$)-(5.5$ we have

$$
\begin{align*}
\mathcal{F}\left(v^{\delta}, A\right) & =\sum_{i=1}^{\infty} \mathcal{F}\left(v_{i}^{\delta}, B_{i}^{\delta}\right)+\mathcal{F}\left(u, N_{0}^{\delta} \cap A\right) \leq \sum_{i=1}^{\infty}\left(\mathbf{m}_{\mathcal{F}}\left(u, B_{i}^{\delta}\right)+\delta \mathcal{L}^{d}\left(B_{i}^{\delta}\right)\right) \\
& \leq \mathbf{m}_{\mathcal{F}}^{\delta}(u, A)+\delta\left(1+\mathcal{L}^{d}(A)\right) \tag{5.6}
\end{align*}
$$

where we also used the fact that $\mathcal{H}^{d-1}\left(J_{u} \cap N_{0}^{\delta} \cap A\right)=\mathcal{F}\left(u, N_{0}^{\delta} \cap A\right)=0$ by the definition of $\left(B_{i}^{\delta}\right)_{i}$ and $\left(\mathrm{H}_{4}\right)$. We now claim that $v^{\delta} \rightarrow u$ in measure. To prove this, it suffices to show that

$$
\sum_{i=1}^{\infty} \mathcal{L}^{d}\left(B_{i}^{\delta}\right) \rightarrow 0
$$

as $\delta \rightarrow 0$. The above limit ensues from the definition of the covering $\left(B_{i}^{\delta}\right)_{i}$, the isoperimetric inequality, and 5.2 , which yield

$$
\begin{aligned}
\sum_{i=1}^{\infty} \mathcal{L}^{d}\left(B_{i}^{\delta}\right) \leq & \sum_{i=1}^{\infty} \mathcal{L}^{d}\left(B_{i}^{\delta}\right)^{\frac{1}{d}} \mathcal{L}^{d}\left(B_{i}^{\delta}\right)^{\frac{d-1}{d}} \leq c_{\pi, d} \delta \sum_{i=1}^{\infty} \mathcal{H}^{d-1}\left(\partial B_{i}^{\delta}\right) \\
& \leq \frac{c_{\pi, d}}{c_{d}} \delta \sum_{i=1}^{\infty} \mathcal{H}^{d-1}\left(B_{i}^{\delta} \cap J_{u}\right) \leq \frac{c_{\pi, d}}{c_{d}} \delta \mathcal{H}^{d-1}\left(J_{u}\right) \rightarrow 0
\end{aligned}
$$

where $c_{\pi, d}$ denotes the isoperimetric constant. With this, using $\left(\mathrm{H}_{2}\right)$, 5.3), and 5.6 we get the required inequality $\mathbf{m}_{\mathcal{F}}^{*}(u, A) \geq \mathcal{F}(u, A)$ in the limit as $\delta \rightarrow 0$. This concludes the proof.

Proof of Lemma 5.1. The combination of Lemma 5.3 and Lemma 5.4 yields the result.

We now turn our attention to Lemma 5.2. Our goal is to show that, asymptotically as $\varepsilon \rightarrow 0$, the minimization problems $\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)$ and $\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{\varepsilon}\left(x_{0}\right)\right)$ coincide for $\mathcal{H}^{d-1}$-a.e. $x_{0} \in J_{u}$. Essentially, the argument relies on Lemma 4.1, which allows us to join two piecewise rigid functions, and some properties of piecewise rigid functions, see Lemma 3.5 .

Proof of Lemma 5.2. It suffices to prove (5.1) for points $x_{0} \in J_{u}$ where the statement of Lemma 3.5 holds.

Step 1 (Inequality " $\leq$ " in 5.1) : We fix $\eta>0$ and $\theta>0$. Choose $z_{\varepsilon} \in P R\left(B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)\right)$ with $z_{\varepsilon}=\bar{u}_{x_{0}}$ in a neighborhood of $\partial B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)$ and

$$
\begin{equation*}
\mathcal{F}\left(z_{\varepsilon}, B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)\right) \leq \mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)\right)+\varepsilon^{d} . \tag{5.7}
\end{equation*}
$$

We extend $z_{\varepsilon}$ to a function in $P R\left(B_{\varepsilon}\left(x_{0}\right)\right)$ by setting $z_{\varepsilon}=\bar{u}_{x_{0}}$ outside $B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)$. Let $\left(u_{\varepsilon}\right)_{\varepsilon}$ be the sequence given by Lemma 3.5. We now want to apply Corollary 4.6 on $z_{\varepsilon}$ (in place of $u_{\rho}$ ) and $u_{\varepsilon}$ (in place of $v_{\rho}$ ) for $\eta, \rho=\varepsilon, A^{\prime}=B_{1-2 \theta}\left(x_{0}\right), A=B_{1-\theta}\left(x_{0}\right)$, and $B=B_{1}\left(x_{0}\right) \backslash \overline{B_{1-4 \theta}\left(x_{0}\right)}$.

To be in a position for applying Corollary 4.6, we must first check that in fact 4.9 holds for $\varepsilon$ sufficiently small. Let $\delta$ be the constant provided by Lemma 4.5. Now, for the given $x_{0} \in J_{u}$, consider the components $P_{i}$ and $P_{j}$ provided by Lemma 3.5 satisfying $x_{0} \in \partial^{*} P_{i} \cap \partial^{*} P_{j}$. Note that $u_{\varepsilon}=q_{i} \chi_{P_{i}}+q_{j} \chi_{P_{j}}$ on $\varepsilon A$, see (3.12)(iii). Notice that $P_{i} \cup P_{j}$ might not form a Caccioppoli partition of $\varepsilon A^{\prime} \cup \varepsilon B$. However, the remaining components contained in $\left(\varepsilon A^{\prime} \cup \varepsilon B\right) \backslash\left(P_{i} \cup P_{j}\right)$, if nonempty, do not belong to the index set $J$ in 4.5) (with $\varepsilon^{d} \delta$ in place of $\delta$, cf. 4.9) for small values of $\varepsilon$. Indeed, 3.12 (i) implies

$$
\lim _{\varepsilon \rightarrow 0} \frac{\mathcal{L}^{d}\left(\left(\varepsilon A^{\prime} \cup \varepsilon B\right) \backslash\left(P_{i} \cup P_{j}\right)\right)}{\varepsilon^{d}}=0
$$

Hence, $J$ contains at most the indices $i$ and $j$. Now, on the one hand, we find $\left\|q_{i}-q_{j}\right\|_{L^{\infty}\left(\varepsilon A^{\prime} \cup \varepsilon B\right)} \geq$ $\left|\left[u\left(x_{0}\right)\right]\right| / 2$ for $\varepsilon$ sufficiently small. By (4.4) and (4.5) this yields

$$
\Phi\left(\varepsilon A^{\prime}, \varepsilon A^{\prime} \cup \varepsilon B ;\left.u_{\varepsilon}\right|_{\varepsilon B \backslash \varepsilon \overline{A^{\prime}}}, \varepsilon^{d} \delta\right) \geq\left|\left[u\left(x_{0}\right)\right]\right| / 2
$$

for $\varepsilon$ sufficiently small. On the other hand, 3.12 (vi) and the fact that $z_{\varepsilon}=\bar{u}_{x_{0}}$ on $\varepsilon\left(A \backslash A^{\prime}\right)$ imply

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{d}} \int_{\varepsilon\left(A \backslash A^{\prime}\right)}\left|z_{\varepsilon}-u_{\varepsilon}\right| \mathrm{d} x=0 \tag{5.8}
\end{equation*}
$$

This shows that 4.9 holds with $z_{\varepsilon}$ in place of $u_{\rho}$ and $u_{\varepsilon}$ in place of $v_{\rho}$, for $\varepsilon$ sufficiently small.
By (4.10) there exist functions $w_{\varepsilon} \in P R\left(B_{\varepsilon}\left(x_{0}\right)\right)$ such that $w_{\varepsilon}=u_{\varepsilon}$ on $B_{\varepsilon}\left(x_{0}\right) \backslash B_{(1-\theta) \varepsilon}\left(x_{0}\right)$ and

$$
\begin{aligned}
& \mathcal{F}\left(w_{\varepsilon}, B_{\varepsilon}\left(x_{0}\right)\right) \leq \mathcal{F}\left(z_{\varepsilon}, \varepsilon A\right)+\mathcal{F}\left(u_{\varepsilon}, \varepsilon B\right) \\
& \quad+\left(\mathcal{F}\left(z_{\varepsilon}, \varepsilon A\right)+\mathcal{F}\left(u_{\varepsilon}, \varepsilon B\right)+3 d \omega_{d} \varepsilon^{d-1}\right) \cdot\left(2 \eta+M_{2} \sigma\left(\varepsilon^{-d} M_{2}\left\|z_{\varepsilon}-u_{\varepsilon}\right\|_{L^{1}\left(\varepsilon\left(A \backslash A^{\prime}\right)\right)}\right)\right)
\end{aligned}
$$

where $M_{2}$ is the constant of Lemma 4.5. In particular, $w_{\varepsilon}=u$ in a neighborhood of $\partial B_{\varepsilon}\left(x_{0}\right)$ by (3.12)(iv). Using (5.8) and the fact that $\lim _{t \rightarrow 0} \sigma(t)=0$ we find a sequence $\left(\rho_{\varepsilon}\right)_{\varepsilon}$ with $\rho_{\varepsilon} \rightarrow 0$ such that

$$
\begin{equation*}
\mathcal{F}\left(w_{\varepsilon}, B_{\varepsilon}\left(x_{0}\right)\right) \leq\left(1+2 \eta+\rho_{\varepsilon}\right)\left(\mathcal{F}\left(z_{\varepsilon}, \varepsilon A\right)+\mathcal{F}\left(u_{\varepsilon}, \varepsilon B\right)\right)+3 d \omega_{d} \varepsilon^{d-1}\left(2 \eta+\rho_{\varepsilon}\right) \tag{5.9}
\end{equation*}
$$

Using that $z_{\varepsilon}=\bar{u}_{x_{0}}$ on $B_{\varepsilon}\left(x_{0}\right) \backslash B_{(1-3 \theta) \varepsilon}\left(x_{0}\right) \subset \varepsilon B,\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{4}\right), 2.5$, and 5.7) we compute

$$
\begin{align*}
\limsup _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(z_{\varepsilon}, \varepsilon A\right)}{\varepsilon^{d-1}} & \leq \limsup _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(z_{\varepsilon}, B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)\right)}{\varepsilon^{d-1}}+\limsup _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(\bar{u}_{x_{0}}, \varepsilon B\right)}{\varepsilon^{d-1}} \\
& \leq \limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)\right)}{\varepsilon^{d-1}}+\omega_{d-1}\left[1-(1-4 \theta)^{d-1}\right] \beta \\
& \leq(1-3 \theta)^{d-1} \limsup _{\varepsilon^{\prime} \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)}{\left(\varepsilon^{\prime}\right)^{d-1}}+\omega_{d-1}\left[1-(1-4 \theta)^{d-1}\right] \beta \tag{5.10}
\end{align*}
$$

where in the step we substituted $(1-3 \theta) \varepsilon$ by $\varepsilon^{\prime}$. By 3.12 (ii), (v), $\left(\mathrm{H}_{4}\right)$, and $B=B_{1}\left(x_{0}\right) \backslash \overline{B_{1-4 \theta}\left(x_{0}\right)}$ we also find

$$
\begin{equation*}
\limsup _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(u_{\varepsilon}, \varepsilon B\right)}{\varepsilon^{d-1}} \leq \limsup _{\varepsilon \rightarrow 0} \frac{\mathcal{F}(u, \varepsilon B)}{\varepsilon^{d-1}} \leq \omega_{d-1}\left[1-(1-4 \theta)^{d-1}\right] \beta \tag{5.11}
\end{equation*}
$$

Recall that $w_{\varepsilon}=u$ in a neighborhood of $\partial B_{\varepsilon}\left(x_{0}\right)$. This together with 5.9 - 5.11) and $\rho_{\varepsilon} \rightarrow 0$ yields

$$
\begin{align*}
\lim _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}} \leq & \limsup _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(w_{\varepsilon}, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}} \\
\leq & (1+2 \eta)\left((1-3 \theta)^{d-1} \lim \sup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}}\right) \\
& +2(1+2 \eta)\left[1-(1-4 \theta)^{d-1}\right] \beta+6 d \frac{\omega_{d}}{\omega_{d-1}} \eta . \tag{5.12}
\end{align*}
$$

Passing to $\eta, \theta \rightarrow 0$ we obtain inequality " $\leq$ " in 5.1.
Step 2 (Inequality " $\geq$ " in 5.1) : Let $\left(u_{\varepsilon}\right)_{\varepsilon}$ be again the sequence from Lemma 3.5. Since $u_{\varepsilon}=u$ in a neighborhood of $\partial B_{\varepsilon}\left(x_{0}\right)$ by (3.12) (iv), we get

$$
\begin{equation*}
\mathbf{m}_{\mathcal{F}}\left(u_{\varepsilon}, B_{\varepsilon}\left(x_{0}\right)\right)=\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right) \tag{5.13}
\end{equation*}
$$

for all $\varepsilon>0$. With (5.13) at hand, the proof is now very similar to Step 1 , and we only indicate the main changes. Fix $\eta>0, \theta>0$, and choose $z_{\varepsilon} \in P R\left(B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)\right)$ with $z_{\varepsilon}=u_{\varepsilon}$ in a neighborhood of $\partial B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)$ such that

$$
\begin{equation*}
\mathcal{F}\left(z_{\varepsilon}, B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)\right) \leq \mathbf{m}_{\mathcal{F}}\left(u_{\varepsilon}, B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)\right)+\varepsilon^{d} \tag{5.14}
\end{equation*}
$$

We extend $z_{\varepsilon}$ to a function in $P R\left(B_{\varepsilon}\left(x_{0}\right)\right)$ by setting $z_{\varepsilon}=u_{\varepsilon}$ outside $B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)$. We apply Corollary 4.6 on $z_{\varepsilon}$ (in place of $u_{\rho}$ ) and $\bar{u}_{x_{0}}$ (in place of $v_{\rho}$ ) for the same sets as in Step 1. We observe $\Phi\left(\varepsilon A^{\prime}, \varepsilon A^{\prime} \cup \varepsilon B ;\left.\bar{u}_{x_{0}}\right|_{\varepsilon B \backslash \varepsilon \overline{A^{\prime}}}, \varepsilon^{d} \delta\right)=\left|\left[u\left(x_{0}\right)\right]\right|$ and, as $z_{\varepsilon}=u_{\varepsilon}$ on $\varepsilon\left(A \backslash A^{\prime}\right)$, 3.12 (vi) yields

$$
\begin{equation*}
\lim _{\varepsilon \rightarrow 0} \frac{1}{\varepsilon^{d}} \int_{\varepsilon\left(A \backslash A^{\prime}\right)}\left|z_{\varepsilon}-\bar{u}_{x_{0}}\right| \mathrm{d} x=0 . \tag{5.15}
\end{equation*}
$$

Thus, 4.9) holds for $\varepsilon$ sufficiently small. By 4.10) there exist functions $w_{\varepsilon} \in P R\left(B_{\varepsilon}\left(x_{0}\right)\right)$ such that $w_{\varepsilon}=\bar{u}_{x_{0}}$ on $B_{\varepsilon}\left(x_{0}\right) \backslash B_{(1-\theta) \varepsilon}\left(x_{0}\right)$ and

$$
\begin{aligned}
& \mathcal{F}\left(w_{\varepsilon}, B_{\varepsilon}\left(x_{0}\right)\right) \leq \mathcal{F}\left(z_{\varepsilon}, \varepsilon A\right)+\mathcal{F}\left(\bar{u}_{x_{0}}, \varepsilon B\right) \\
& \quad+\left(\mathcal{F}\left(z_{\varepsilon}, \varepsilon A\right)+\mathcal{F}\left(\bar{u}_{x_{0}}, \varepsilon B\right)+3 d \omega_{d} \varepsilon^{d-1}\right) \cdot\left(2 \eta+M_{2} \sigma\left(\varepsilon^{-d} M_{2}\left\|z_{\varepsilon}-\bar{u}_{x_{0}}\right\|_{L^{1}\left(\varepsilon\left(A \backslash A^{\prime}\right)\right)}\right)\right)
\end{aligned}
$$

Similar to Step 1, cf. (5.9), using (5.15 we find a sequence $\left(\rho_{\varepsilon}\right)_{\varepsilon}$ with $\rho_{\varepsilon} \rightarrow 0$ such that

$$
\begin{equation*}
\mathcal{F}\left(w_{\varepsilon}, B_{\varepsilon}\left(x_{0}\right)\right) \leq\left(1+2 \eta+\rho_{\varepsilon}\right)\left(\mathcal{F}\left(z_{\varepsilon}, \varepsilon A\right)+\mathcal{F}\left(\bar{u}_{x_{0}}, \varepsilon B\right)\right)+3 d \omega_{d} \varepsilon^{d-1}\left(2 \eta+\rho_{\varepsilon}\right) \tag{5.16}
\end{equation*}
$$

Repeating the arguments in 5.10-5.11), in particular using that $z_{\varepsilon}=u_{\varepsilon}$ on $B_{\varepsilon}\left(x_{0}\right) \backslash B_{(1-3 \theta) \varepsilon}\left(x_{0}\right)$, and using (5.14) we derive

$$
\begin{equation*}
\limsup _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(z_{\varepsilon}, \varepsilon A\right)}{\varepsilon^{d-1}} \leq(1-3 \theta)^{d-1} \limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u_{\varepsilon}, B_{\varepsilon}\left(x_{0}\right)\right)}{\varepsilon^{d-1}}+\omega_{d-1}\left[1-(1-4 \theta)^{d-1}\right] \beta \tag{5.17}
\end{equation*}
$$

Estimating $\mathcal{F}\left(\bar{u}_{x_{0}}, \varepsilon B\right)$ as in 5.10, with 5.16-5.17) and $\rho_{\varepsilon} \rightarrow 0$ we then obtain

$$
\begin{aligned}
\limsup _{\varepsilon \rightarrow 0} \frac{\mathcal{F}\left(w_{\varepsilon}, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}} \leq & (1+2 \eta)\left((1-3 \theta)^{d-1} \limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u_{\varepsilon}, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}}\right) \\
& +2(1+2 \eta)\left[1-(1-4 \theta)^{d-1}\right] \beta+6 d \frac{\omega_{d}}{\omega_{d-1}} \eta
\end{aligned}
$$

Passing to $\eta, \theta \rightarrow 0$ and recalling that $w_{\varepsilon}=\bar{u}_{x_{0}}$ in a neighborhood of $\partial B_{\varepsilon}\left(x_{0}\right)$ we derive

$$
\limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}} \leq \limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u_{\varepsilon}, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}}
$$

This along with 5.13 shows inequality " $\geq$ " in 5.1 .
5.3. A useful generalization. We now formulate a generalization of Theorem 2.2 which will be instrumental in Section 6 below. Suppose that we have a sequence of functionals $\mathcal{F}_{n}: P R(\Omega) \times$ $\mathcal{B}(\Omega) \rightarrow[0, \infty)$ satisfying $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{5}\right)$ uniformly, i.e., for the same $0<\alpha<\beta$ and $\sigma$ : $[0,+\infty) \rightarrow[0, \beta]$.

Let $\mathcal{F}: P R(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty]$ be a functional satisfying $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$. Later, we will show that these conditions will be guaranteed when $\mathcal{F}$ is the $\Gamma$-limit of the sequence $\left(\mathcal{F}_{n}\right)_{n}$. If we additionally assume $\sqrt{2.8}$, we have the following generalization of Theorem 2.2 ,

Corollary 5.5. Consider a sequence $\left(\mathcal{F}_{n}\right)_{n}$ satisfying $\left(\mathrm{H}_{1}\right)$, $\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{5}\right)$ uniformly and $\mathcal{F}$ satisfying $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$. Assume that 2.8 holds. Then $\mathcal{F}$ admits the representation

$$
\mathcal{F}(u, B)=\int_{J_{u} \cap B} f\left(x,[u](x), \nu_{u}(x)\right) d \mathcal{H}^{d-1}(x)
$$

for all $u \in P R(\Omega)$ and $B \in \mathcal{B}(\Omega)$, with $f(x, \xi, \nu)$ given by 2.7.
We emphasize that we cannot apply directly Theorem 2.2 on $\mathcal{F}$, since we do not assume $\left(\mathrm{H}_{5}\right)$. The idea is to prove equality in Lemma 5.2 for $\mathcal{F}$ by using the corresponding properties for $\mathcal{F}_{n}$. To prove Corollary 5.5, we need the following preliminary result, which is itself a corollary of Lemma 5.2. In the statement, we write again $\bar{u}_{x_{0}}:=u_{x_{0},[u]\left(x_{0}\right), \nu_{u}\left(x_{0}\right)}$ for brevity, see 2.5.

Corollary 5.6. Consider a sequence $\left(\mathcal{F}_{n}\right)_{n}$ satisfying $\left(\mathrm{H}_{1}\right)$, $\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{5}\right)$ uniformly. Assume that (2.8) holds. Let $u \in \operatorname{PR}(\Omega)$. Then for $\mathcal{H}^{d-1}$-a.e. $x_{0} \in J_{u}$ we have

$$
\lim _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}}=\limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}}
$$

Proof. The proof is analogous to the one of Lemma 5.2. We therefore only highlight the adaptions for one inequality, see Step 1 above. Fix $\eta, \theta>0$. First, by using 2.8, for each $\varepsilon$ we can choose first $\varepsilon^{\prime}(\varepsilon)<\varepsilon$ and then $n(\varepsilon) \in \mathbb{N}$, both depending on $\varepsilon$, such that

$$
\begin{align*}
& \text { (i) } \mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right) \leq \mathbf{m}_{\mathcal{F}_{n(\varepsilon)}}\left(u, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)+\varepsilon^{d} \\
& \text { (i) } \mathbf{m}_{\mathcal{F}_{n(\varepsilon)}}\left(\bar{u}_{x_{0}}, B_{(1-3 \theta) \varepsilon^{\prime}}\left(x_{0}\right)\right) \leq \mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{(1-3 \theta) \varepsilon^{\prime}}\left(x_{0}\right)\right)+\varepsilon^{d} \tag{5.18}
\end{align*}
$$

In fact, first choose $\varepsilon^{\prime}(\varepsilon)<\varepsilon$ such that $\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right) \leq \lim \inf _{n \rightarrow \infty} \mathbf{m}_{\mathcal{F}_{n}}\left(u, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)+\varepsilon^{d} / 2$. Then, choose $n(\varepsilon)$ depending on $\varepsilon^{\prime}$ (and thus on $\varepsilon$ ) such that 5.18 holds. Choose $z_{\varepsilon^{\prime}} \in P R\left(B_{(1-3 \theta) \varepsilon^{\prime}}\left(x_{0}\right)\right)$ with $z_{\varepsilon^{\prime}}=\bar{u}_{x_{0}}$ in a neighborhood of $\partial B_{(1-3 \theta) \varepsilon^{\prime}}\left(x_{0}\right)$ and

$$
\mathcal{F}_{n(\varepsilon)}\left(z_{\varepsilon^{\prime}}, B_{(1-3 \theta) \varepsilon^{\prime}}\left(x_{0}\right)\right) \leq \mathbf{m}_{\mathcal{F}_{n(\varepsilon)}}\left(\bar{u}_{x_{0}}, B_{(1-3 \theta) \varepsilon^{\prime}}\left(x_{0}\right)\right)+\varepsilon^{d} .
$$

We proceed as in the proof of Lemma 5.2 we apply Corollary 4.6 to obtain $w_{\varepsilon^{\prime}} \in P R\left(B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)$ with $w_{\varepsilon^{\prime}}=u_{\varepsilon^{\prime}}$ on $B_{\varepsilon^{\prime}}\left(x_{0}\right) \backslash B_{(1-\theta) \varepsilon^{\prime}}\left(x_{0}\right)$ which satisfies (cf. (5.9)

$$
\begin{equation*}
\mathcal{F}_{n(\varepsilon)}\left(w_{\varepsilon^{\prime}}, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right) \leq\left(1+2 \eta+\rho_{\varepsilon}\right)\left(\mathcal{F}_{n(\varepsilon)}\left(z_{\varepsilon^{\prime}}, \varepsilon^{\prime} A\right)+\mathcal{F}_{n(\varepsilon)}\left(u_{\varepsilon^{\prime}}, \varepsilon^{\prime} B\right)\right)+3 d \omega_{d} \varepsilon^{d-1}\left(2 \eta+\rho_{\varepsilon}\right) \tag{5.19}
\end{equation*}
$$

for a sequence $\rho_{\varepsilon}$ converging to zero, where we use that $\left(\mathcal{F}_{n}\right)_{n}$ satisfy $\left(\mathrm{H}_{4}\right)$ and $\left(\mathrm{H}_{5}\right)$ uniformly. Applying (5.18) (ii) and following the lines of 5.10 we get

$$
\begin{aligned}
\limsup _{\varepsilon \rightarrow 0} \frac{\mathcal{F}_{n(\varepsilon)}\left(z_{\varepsilon^{\prime}}, \varepsilon^{\prime} A\right)}{\left(\varepsilon^{\prime}\right)^{d-1}} & \leq \limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}_{n(\varepsilon)}}\left(\bar{u}_{x_{0}}, B_{(1-3 \theta) \varepsilon^{\prime}}\left(x_{0}\right)\right)}{\left(\varepsilon^{\prime}\right)^{d-1}}+\omega_{d-1}\left[1-(1-4 \theta)^{d-1}\right] \beta \\
& \leq(1-3 \theta)^{d-1} \limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{\varepsilon^{\prime \prime}}\left(x_{0}\right)\right)}{\left(\varepsilon^{\prime \prime}\right)^{d-1}}+\omega_{d-1}\left[1-(1-4 \theta)^{d-1}\right] \beta,
\end{aligned}
$$

where we set $\varepsilon^{\prime \prime}=(1-3 \theta) \varepsilon^{\prime}$, and recall that $\varepsilon^{\prime \prime}=\varepsilon^{\prime \prime}(\varepsilon)$ depends on $\varepsilon$. Admitting arbitrary sequence $\varepsilon^{\prime \prime} \rightarrow 0$, we do not decrease the right hand side. Therefore,

$$
\begin{equation*}
\limsup _{\varepsilon \rightarrow 0} \frac{\mathcal{F}_{n(\varepsilon)}\left(z_{\varepsilon^{\prime}}, \varepsilon^{\prime} A\right)}{\left(\varepsilon^{\prime}\right)^{d-1}} \leq(1-3 \theta)^{d-1} \limsup _{\varepsilon^{\prime \prime} \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{\varepsilon^{\prime \prime}}\left(x_{0}\right)\right)}{\left(\varepsilon^{\prime \prime}\right)^{d-1}}+\omega_{d-1}\left[1-(1-4 \theta)^{d-1}\right] \beta . \tag{5.20}
\end{equation*}
$$

 the fact that $\left(\mathrm{H}_{4}\right)$ holds uniformly, cf. 5.11). This together with (5.18)(i), 5.19)-(5.20), $\varepsilon^{\prime}<\varepsilon$, and $w_{\varepsilon^{\prime}}=u_{\varepsilon^{\prime}}=u$ in a neighborhood of $\overline{\partial B_{\varepsilon^{\prime}}}\left(x_{0}\right)$ now shows (cf. $\left.5.12 p\right)$

$$
\begin{aligned}
\lim _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}} \leq & \limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}_{n(\varepsilon)}}\left(u, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)}{\omega_{d-1}\left(\varepsilon^{\prime}\right)^{d-1}} \leq \lim _{\sup _{\varepsilon \rightarrow 0}} \frac{\mathcal{F}_{n(\varepsilon)}\left(w_{\varepsilon^{\prime}}, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)}{\omega_{d-1}\left(\varepsilon^{\prime}\right)^{d-1}} \\
\leq & (1+2 \eta)\left((1-3 \theta)^{d-1} \lim \sup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(\bar{u}_{x_{0}}, B_{\varepsilon}\left(x_{0}\right)\right)}{\omega_{d-1} \varepsilon^{d-1}}\right) \\
& +2(1+2 \eta)\left[1-(1-4 \theta)^{d-1}\right] \beta+6 d \frac{\omega_{d}}{\omega_{d-1}} \eta .
\end{aligned}
$$

Passing to $\eta, \theta \rightarrow 0$ we obtain one inequality. To see the reverse one, we follow the lines of Step 2 of the proof of Lemma 5.2 and carry out similar adaptions.

We close this section by noting that Corollary 5.5 follows from Corollary 5.6 arguing exactly as in the proof of Theorem 2.2. (Note that Lemma 5.1 is applicable since $\mathcal{F}$ satisfies $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$.)

## 6. $\Gamma$-convergence results for functionals on $P R(\Omega)$

This section is devoted to the proof of Theorem 2.3. Consider a sequence of functionals $\left(\mathcal{F}_{n}\right)_{n}$ satisfying $\left(\mathrm{H}_{1}\right)$ and $\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{5}\right)$ uniformly, i.e., for the same $0<\alpha<\beta$ and $\sigma:[0,+\infty) \rightarrow[0, \beta]$. We will first identify a $\Gamma$-limit $\mathcal{F}$ with respect to the convergence in measure on $\Omega$. Then, our goal is to obtain an integral representation of $\mathcal{F}$. To this aim, we apply the localization method for $\Gamma$-convergence together with the fundamental estimate in Lemma 4.1 to deduce that properties $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$ are satisfied. As mentioned before, we cannot prove directly that $\mathcal{F}$ satisfies $\left(\mathrm{H}_{5}\right)$ and therefore the results of Subsections 5.1, 5.2 cannot be used. To circumvent this problem, we will use Corollary 5.5 to get the representation result. We will also eventually prove that $\left(\mathrm{H}_{5}\right)$ is satisfied by showing that the integrand $f$ satisfies an equivalent property.

Consider a sequence of functionals $\left(\mathcal{F}_{n}\right)_{n}$ defined on $P R(\Omega)$. As a first step, we analyze fundamental properties of the $\Gamma$-liminf and $\Gamma$-limsup with respect to the topology of the convergence in measure. To this end, we define

$$
\begin{align*}
\mathcal{F}^{\prime}(u, A) & :=\Gamma-\liminf _{n \rightarrow \infty} \mathcal{F}_{n}(u, A)=\inf \left\{\liminf _{n \rightarrow \infty} \mathcal{F}_{n}\left(u_{n}, A\right): u_{n} \rightarrow u \text { in measure on } A\right\}, \\
\mathcal{F}^{\prime \prime}(u, A) & :=\Gamma-\limsup _{n \rightarrow \infty} \mathcal{F}_{n}(u, A)=\inf \left\{\limsup _{n \rightarrow \infty} \mathcal{F}_{n}\left(u_{n}, A\right): u_{n} \rightarrow u \text { in measure on } A\right\} \tag{6.1}
\end{align*}
$$

for all $u \in P R(\Omega)$ and $A \in \mathcal{A}(\Omega)$.
Lemma 6.1 (Properties of $\Gamma$-liminf and $\Gamma$-limsup). Let $\Omega \subset \mathbb{R}^{d}$ open, bounded with Lipschitz boundary. Let $\mathcal{F}_{n}: \operatorname{PR}(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ be a sequence of functionals satisfying $\left(\mathrm{H}_{1}\right)$, $\left(\mathrm{H}_{3}\right)-$ $\left(\mathrm{H}_{5}\right)$ for the same $0<\alpha<\beta$ and $\sigma:[0,+\infty) \rightarrow[0, \beta]$. Define $\mathcal{F}^{\prime}$ and $\mathcal{F}^{\prime \prime}$ as in 6.1). Then we have
(i) $\mathcal{F}^{\prime}(u, A) \leq \mathcal{F}^{\prime}(u, B), \quad \mathcal{F}^{\prime \prime}(u, A) \leq \mathcal{F}^{\prime \prime}(u, B) \quad$ whenever $A \subset B$,
(ii) $\alpha \mathcal{H}^{d-1}\left(J_{u} \cap A\right) \leq \mathcal{F}^{\prime}(u, A) \leq \mathcal{F}^{\prime \prime}(u, A) \leq \beta \mathcal{H}^{d-1}\left(J_{u} \cap A\right)$,
(iii) $\mathcal{F}^{\prime}(u, A)=\sup _{B \subset \subset A} \mathcal{F}^{\prime}(u, B), \quad \mathcal{F}^{\prime \prime}(u, A)=\sup _{B \subset \subset A} \mathcal{F}^{\prime \prime}(u, B) \quad$ whenever $A \in \mathcal{A}_{0}(\Omega)$,
(iv) $\mathcal{F}^{\prime}(u, A \cup B) \leq \mathcal{F}^{\prime}(u, A)+\mathcal{F}^{\prime \prime}(u, B)$,
$\mathcal{F}^{\prime \prime}(u, A \cup B) \leq \mathcal{F}^{\prime \prime}(u, A)+\mathcal{F}^{\prime \prime}(u, B) \quad$ whenever $A, B \in \mathcal{A}_{0}(\Omega)$.
Proof. First, (i) is clear as all $\mathcal{F}_{n}(u, \cdot)$ are measures. The upper bound in (ii) follows from $\left(\mathrm{H}_{4}\right)$ by taking the constant sequence $u_{n}=u$ in 6.1). For the lower bound in (ii), we take an (almost) optimal sequence in 6.1), use $\left(\mathrm{H}_{4}\right)$, as well as the lower semicontinuity stated in Lemma 3.3(ii).

To see (iii), we fix $D \in \mathcal{A}_{0}(\Omega)$ and first prove that for all sets $E, F \in \mathcal{A}_{0}(\Omega), E \subset \subset F \subset \subset D$, we have

$$
\begin{equation*}
\mathcal{F}^{\prime}(u, D) \leq \mathcal{F}^{\prime}(u, F)+\mathcal{F}^{\prime}(u, D \backslash \bar{E}), \quad \mathcal{F}^{\prime \prime}(u, D) \leq \mathcal{F}^{\prime \prime}(u, F)+\mathcal{F}^{\prime \prime}(u, D \backslash \bar{E}) . \tag{6.3}
\end{equation*}
$$

(We use different notation for the sets to avoid confusion with the notation in Lemma 4.1.) Indeed, let $\left(u_{n}\right)_{n},\left(v_{n}\right)_{n} \subset P R(\Omega)$ be sequences converging in measure to $u$ on $F$ and $D \backslash \bar{E}$, respectively, such that

$$
\begin{equation*}
\mathcal{F}^{\prime \prime}(u, F)=\limsup _{n \rightarrow \infty} \mathcal{F}_{n}\left(u_{n}, F\right), \quad \mathcal{F}^{\prime \prime}(u, D \backslash \bar{E})=\limsup _{n \rightarrow \infty} \mathcal{F}_{n}\left(v_{n}, D \backslash \bar{E}\right) \tag{6.4}
\end{equation*}
$$

We apply Lemma 4.1 for $\psi(t):=\frac{t}{1+t}, A=F, B=D \backslash \bar{E}$, and some $A^{\prime} \in \mathcal{A}_{0}(\Omega), E \subset \subset A^{\prime} \subset \subset F$, to obtain $w_{n} \in P R(D)$ satisfying (see 4.2) (i))

$$
\begin{equation*}
\mathcal{F}_{n}\left(w_{n}, D\right) \leq\left(\mathcal{F}_{n}\left(u_{n}, F\right)+\mathcal{F}_{n}\left(v_{n}, D \backslash \bar{E}\right)\right)\left(1+\eta+\rho_{n}\right)+C\left(\eta+\rho_{n}\right) \tag{6.5}
\end{equation*}
$$

where $C$ depends on $E, F, D$, and for brevity we set $\rho_{n}:=M \sigma\left(\Lambda\left(u_{n}, v_{n}\right)\right)$. We observe that $u_{n}-v_{n}$ tends to 0 in measure on $F \backslash \bar{E}$, which is equivalent to

$$
\int_{F \backslash \bar{E}} \psi\left(\left|u_{n}-v_{n}\right|\right) \rightarrow 0
$$

for $\psi(t)=\frac{t}{1+t}$. Hence, $\Lambda\left(u_{n}, v_{n}\right) \rightarrow 0$ by 4.1), which implies $\rho_{n} \rightarrow 0$. Since by assumption $u_{n} \rightarrow u$ and $v_{n} \rightarrow u$ in measure on $F$ and $D \backslash \bar{E}$, respectively, and $\left\|\min \left\{\left|w_{n}-u_{n}\right|,\left|w_{n}-v_{n}\right|\right\}\right\|_{L^{\infty}(D)} \leq$ $\Lambda\left(u_{n}, v_{n}\right)$ by 4.2 (ii), the functions $w_{n}$ converge to $u$ in measure on $D$. Thus, passing to the limit $n \rightarrow \infty$ and using 6.1), 6.4-6.5), we obtain

$$
\mathcal{F}^{\prime \prime}(u, D) \leq \lim \sup _{n \rightarrow \infty} \mathcal{F}_{n}\left(w_{n}, D\right) \leq\left(\mathcal{F}^{\prime \prime}(u, F)+\mathcal{F}^{\prime \prime}(u, D \backslash \bar{E})\right)(1+\eta)+C \eta
$$

Since $\eta>0$ was arbitrary, we obtain $(6.3)$ for $\mathcal{F}^{\prime \prime}$. For $\mathcal{F}^{\prime}$ we argue in a similar fashion.

By (6.3) and 6.2)(ii) we get $\mathcal{F}^{\prime \prime}(u, D) \leq \mathcal{F}^{\prime \prime}(u, F)+\beta \mathcal{H}^{d-1}\left(J_{u} \cap(D \backslash \bar{E})\right)$. As $\mathcal{H}^{d-1}\left(J_{u} \cap(D \backslash \bar{E})\right)$ can be taken arbitrarily small and $\mathcal{F}^{\prime \prime}(u, \cdot)$ is an increasing set function, we obtain $\mathcal{F}^{\prime \prime}(u, D) \leq$ $\sup _{F \subset \subset D} \mathcal{F}^{\prime \prime}(u, F)$. This shows (iii) for $\mathcal{F}^{\prime \prime}$. The proof of $\mathcal{F}^{\prime}$ is similar.

We finally show (iv). Observe that the inequalities are clear if $A \cap B=\emptyset$. Let $A, B \in \mathcal{A}_{0}(\Omega)$ with nonempty intersection. Given $\varepsilon>0$, one can choose $M \subset \subset M^{\prime} \subset \subset A$ and $N \subset \subset N^{\prime} \subset \subset B$ such that $M, M^{\prime}, N, N^{\prime} \in \mathcal{A}_{0}(\Omega), M^{\prime} \cap N^{\prime}=\emptyset$, and $\mathcal{H}^{d-1}\left(J_{u} \cap((A \cup B) \backslash \overline{M \cup N})\right) \leq \varepsilon$, see [6, Proof of Lemma 5.2] for details. Then using 6.2 (i),(ii) and 6.3)

$$
\begin{aligned}
\mathcal{F}^{\prime \prime}(u, A \cup B) & \leq \mathcal{F}^{\prime \prime}\left(u, M^{\prime} \cup N^{\prime}\right)+\mathcal{F}^{\prime \prime}(u,(A \cup B) \backslash \overline{M \cup N}) \leq \mathcal{F}^{\prime \prime}\left(u, M^{\prime}\right)+\mathcal{F}^{\prime \prime}\left(u, N^{\prime}\right)+\beta \varepsilon \\
& \leq \mathcal{F}^{\prime \prime}(u, A)+\mathcal{F}^{\prime \prime}(u, B)+\beta \varepsilon
\end{aligned}
$$

Here, we also used $\mathcal{F}^{\prime \prime}\left(u, M^{\prime} \cup N^{\prime}\right) \leq \mathcal{F}^{\prime \prime}\left(u, M^{\prime}\right)+\mathcal{F}^{\prime \prime}\left(u, N^{\prime}\right)$ which holds due to $M^{\prime} \cap N^{\prime}=\emptyset$. The statement follows as $\varepsilon$ was arbitrary. The proof for $\mathcal{F}^{\prime}$ is again the same.

The previous lemma allows us to identify a $\Gamma$-limit on $P R(\Omega)$.
Lemma 6.2. Let $\Omega \subset \mathbb{R}^{d}$ open, bounded with Lipschitz boundary. Let $\mathcal{F}_{n}: P R(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ be a sequence of functionals satisfying $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{5}\right)$ for the same $0<\alpha<\beta$ and $\sigma:[0,+\infty) \rightarrow$ $[0, \beta]$. Then there exists $\mathcal{F}: P R(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty]$ and a subsequence (not relabeled) such that

$$
\begin{equation*}
\mathcal{F}(\cdot, A)=\Gamma-\lim _{n \rightarrow \infty} \mathcal{F}_{n}(\cdot, A), \tag{6.6}
\end{equation*}
$$

with respect to the topology of the convergence in measure, for all $A \in \mathcal{A}_{0}(\Omega)$. The functional $\mathcal{F}$ satisfies $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$.

Proof. We apply a compactness result for $\bar{\Gamma}$-convergence, see [37, Theorem 16.9], to find an increasing sequence of integers $\left(n_{k}\right)_{k}$ such that the objects $\mathcal{F}^{\prime}$ and $\mathcal{F}^{\prime \prime}$ defined in 6.1 with respect to $\left(n_{k}\right)_{k}$ satisfy

$$
\left(\mathcal{F}^{\prime}\right)_{-}(u, A)=\left(\mathcal{F}^{\prime \prime}\right)_{-}(u, A)
$$

for all $u \in P R(\Omega)$ and $A \in \mathcal{A}(\Omega)$, where $\left(\mathcal{F}^{\prime}\right)_{-}$and $\left(\mathcal{F}^{\prime \prime}\right)_{-}$denote the inner regular envelope defined by

$$
\begin{equation*}
\left(\mathcal{F}^{\prime}\right)_{-}(u, A)=\sup _{B \subset \subset A, B \in \mathcal{A}(\Omega)} \mathcal{F}^{\prime}(u, B), \quad\left(\mathcal{F}^{\prime \prime}\right)_{-}(u, A)=\sup _{B \subset \subset A, B \in \mathcal{A}(\Omega)} \mathcal{F}^{\prime \prime}(u, B) \tag{6.7}
\end{equation*}
$$

We write $\mathcal{F}_{0}:=\left(\mathcal{F}^{\prime \prime}\right)_{-}$for simplicity. This along with 6.1) and Lemma 6.1(i) yields

$$
\begin{equation*}
\mathcal{F}_{0}=\left(\mathcal{F}^{\prime}\right)_{-} \leq \mathcal{F}^{\prime} \leq \mathcal{F}^{\prime \prime} \tag{6.8}
\end{equation*}
$$

We now check that

$$
\begin{equation*}
\mathcal{F}^{\prime \prime}(u, A)=\mathcal{F}_{0}(u, A) \quad \text { for all } u \in P R(\Omega) \text { and all } A \in \mathcal{A}_{0}(\Omega) \tag{6.9}
\end{equation*}
$$

In view of 6.8, it suffices to show $\mathcal{F}_{0}(u, A) \geq \mathcal{F}^{\prime \prime}(u, A)$. To this end, we fix $u \in P R(\Omega)$, $A \in \mathcal{A}_{0}(\Omega)$, and $\varepsilon>0$. We choose sets $A^{\prime \prime} \subset \subset A^{\prime} \subset \subset A$ such that $A^{\prime} \in \mathcal{A}_{0}(\Omega), A \backslash \overline{A^{\prime \prime}} \in \mathcal{A}_{0}(\Omega)$, and $\mathcal{H}^{d-1}\left(J_{u} \cap\left(A \backslash \overline{A^{\prime \prime}}\right)\right) \leq \varepsilon$. We then find by Lemma 6.1(ii),(iv) and 6.7)

$$
\mathcal{F}^{\prime \prime}(u, A) \leq \mathcal{F}^{\prime \prime}\left(u, A^{\prime}\right)+\mathcal{F}^{\prime \prime}\left(u, A \backslash \overline{A^{\prime \prime}}\right) \leq \mathcal{F}^{\prime \prime}\left(u, A^{\prime}\right)+\beta \varepsilon \leq \mathcal{F}_{0}(u, A)+\beta \varepsilon
$$

As $\varepsilon$ is arbitrary, the desired inequality follows.
Now (6.8) $-\sqrt{6.9}$ show that the $\Gamma$-limit exists for all $u \in P R(\Omega)$ and all $A \in \mathcal{A}_{0}(\Omega)$. It remains to extend $\mathcal{F}_{0}: P R(\Omega) \times \mathcal{A}(\Omega) \rightarrow[0, \infty]$ to a functional $\mathcal{F}$ defined on $P R(\Omega) \times \mathcal{B}(\Omega)$. To this end, we first note that $\mathcal{F}_{0}$ is superadditive and inner regular, see [37, Proposition 16.12 and Remark
16.3]. Moreover, $\mathcal{F}_{0}$ is subadditive. In fact, for $A, B \in \mathcal{A}(\Omega)$, we choose $A^{\prime}, B^{\prime} \in \mathcal{A}_{0}(\Omega)$ with $A^{\prime} \subset \subset A, B^{\prime} \subset \subset B$, and since $\mathcal{F}_{0}$ is subadditive on $\mathcal{A}_{0}(\Omega)$ (see Lemma 6.1(iv) and 6.9), we get

$$
\mathcal{F}_{0}\left(u, A^{\prime} \cup B^{\prime}\right) \leq \mathcal{F}_{0}\left(A^{\prime}\right)+\mathcal{F}_{0}\left(B^{\prime}\right) \leq \mathcal{F}_{0}(A)+\mathcal{F}_{0}(B)
$$

Then $\mathcal{F}_{0}(u, A \cup B) \leq \mathcal{F}_{0}(A)+\mathcal{F}_{0}(B)$ follows from the inner regularity of $\mathcal{F}_{0}$. By De Giorgi-Letta (see [37, Theorem 14.23]), $\mathcal{F}_{0}(u, \cdot)$ can thus be extended to a Borel measure.

Lemma 6.1 also yields that the extended functional $\mathcal{F}$ satisfies $\left(\mathrm{H}_{1}\right)$, $\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{4}\right)$. The lower semicontinuity $\left(\mathrm{H}_{2}\right)$ of $\mathcal{F}(\cdot, A)=\mathcal{F}_{0}(\cdot, A)$ for $A \in \mathcal{A}(\Omega)$ follows from [37, Remark 16.3].

We are now in the position to prove Theorem 2.3 .
Proof of Theorem 2.3. We observe that $\mathcal{F}$ satisfies 6.6 and $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{4}\right)$ by Lemma 6.2. Since we assume (2.8), we can apply Corollary 5.5, so that $\mathcal{F}$ admits the integral representation

$$
\mathcal{F}(u, B)=\int_{J_{u} \cap B} f\left(x,[u](x), \nu_{u}(x)\right) d \mathcal{H}^{d-1}(x)
$$

with the density $f$ given in 2.7.
We are only left to show that $\left(\mathrm{H}_{5}\right)$ holds. We will equivalently prove that $f$ satisfies

$$
\left|f\left(x_{0}, \xi, \nu\right)-f\left(x_{0}, \xi^{\prime}, \nu\right)\right| \leq \alpha^{-1} \beta \sigma\left(\mid\left(\xi-\xi^{\prime} \mid\right)\right.
$$

for all $x_{0} \in \Omega, \xi, \xi^{\prime} \in \mathbb{R}^{d}$, and $\nu \in S^{d-1}$. This shows that $\left(\mathrm{H}_{5}\right)$ holds for the modulus of continuity $\alpha^{-1} \beta \sigma$. To this end, it suffices to prove that for all $x_{0} \in \Omega, \xi, \xi^{\prime} \in \mathbb{R}^{d}$, and $\nu \in S^{d-1}$ one has

$$
\begin{equation*}
\left|\limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u_{x_{0}, \xi, \nu}, B_{\varepsilon}(x)\right)}{\omega_{d-1} \varepsilon^{d-1}}-\underset{\varepsilon \rightarrow 0}{\limsup } \frac{\mathbf{m}_{\mathcal{F}}\left(u_{x_{0}, \xi^{\prime}, \nu}, B_{\varepsilon}(x)\right)}{\omega_{d-1} \varepsilon^{d-1}}\right| \leq \alpha^{-1} \beta \sigma\left(\left|\xi-\xi^{\prime}\right|\right) . \tag{6.10}
\end{equation*}
$$

Indeed, then the statement follows from 2.7.
Let us show 6.10). We first observe that, in view of 2.8), it suffices to prove

$$
\begin{equation*}
\left|\mathbf{m}_{\mathcal{F}_{n}}\left(u_{x_{0}, \xi, \nu}, B_{\varepsilon}\left(x_{0}\right)\right)-\mathbf{m}_{\mathcal{F}_{n}}\left(u_{x_{0}, \xi^{\prime}, \nu}, B_{\varepsilon}\left(x_{0}\right)\right)\right| \leq \omega_{d-1} \varepsilon^{d-1} \alpha^{-1} \beta \sigma\left(\left|\xi-\xi^{\prime}\right|\right) \tag{6.11}
\end{equation*}
$$

for every $n \in \mathbb{N}$. Indeed, once 6.11 is proved, we conclude as follows: without restriction we suppose that the term inside the brackets on the left hand side of 6.10 is nonnegative as otherwise we interchange the roles of $\xi$ and $\xi^{\prime}$. By 2.8, for each $\varepsilon>0$, choose $n(\varepsilon) \in \mathbb{N}$ and $\varepsilon^{\prime}(\varepsilon)<\varepsilon$ with

$$
\begin{aligned}
& \mathbf{m}_{\mathcal{F}}\left(u_{x_{0}, \xi, \nu}, B_{\varepsilon}\left(x_{0}\right)\right) \leq \mathbf{m}_{\mathcal{F}_{n(\varepsilon)}}\left(u_{x_{0}, \xi, \nu}, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)+\varepsilon^{d} \\
& \mathbf{m}_{\mathcal{F}_{n(\varepsilon)}}\left(u_{x_{0}, \xi^{\prime}, \nu}, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right) \leq \mathbf{m}_{\mathcal{F}}\left(u_{x_{0}, \xi^{\prime}, \nu}, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)+\left(\varepsilon^{\prime}\right)^{d}
\end{aligned}
$$

Then, since $\varepsilon^{\prime}=\varepsilon^{\prime}(\varepsilon)<\varepsilon$, we get by 6.11

$$
\begin{aligned}
0 & \leq \limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u_{x_{0}, \xi, \nu}, B_{\varepsilon}(x)\right)}{\omega_{d-1} \varepsilon^{d-1}}-\limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}}\left(u_{x_{0}, \xi^{\prime}, \nu}, B_{\varepsilon^{\prime}}(x)\right)}{\omega_{d-1}\left(\varepsilon^{\prime}\right)^{d-1}} \\
& \leq \limsup _{\varepsilon \rightarrow 0} \frac{\mathbf{m}_{\mathcal{F}_{n(\varepsilon)}}\left(u_{x_{0}, \xi, \nu}, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)-\mathbf{m}_{\mathcal{F}_{n(\varepsilon)}}\left(u_{x_{0}, \xi^{\prime}, \nu}, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)}{\omega_{d-1}\left(\varepsilon^{\prime}\right)^{d-1}} \leq \alpha^{-1} \beta \sigma\left(\left|\xi-\xi^{\prime}\right|\right)
\end{aligned}
$$

This gives 6.10. It thus remains to show (6.11). To this end, let $\delta>0$ and choose $z \in P R\left(B_{\varepsilon}\left(x_{0}\right)\right)$ with $z=u_{x_{0}, \xi, \nu}$ in a neighborhood of $\partial B_{\varepsilon}\left(x_{0}\right)$ and

$$
\begin{equation*}
\mathcal{F}_{n}\left(z, B_{\varepsilon}\left(x_{0}\right)\right) \leq \mathbf{m}_{\mathcal{F}_{n}}\left(u_{x_{0}, \xi, \nu}, B_{\varepsilon}\left(x_{0}\right)\right)+\delta \tag{6.12}
\end{equation*}
$$

Clearly, in view of $\left(\mathrm{H}_{4}\right), \mathbf{m}_{\mathcal{F}_{n}}\left(u_{x_{0}, \xi, \nu}, B_{\varepsilon}\left(x_{0}\right)\right) \leq \omega_{d-1} \varepsilon^{d-1} \beta$ by taking $u_{x_{0}, \xi, \nu}$ as competitor. Therefore, $\left(\mathrm{H}_{4}\right)$ implies

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(J_{z}\right) \leq\left(\omega_{d-1} \varepsilon^{d-1} \beta+\delta\right) \alpha^{-1} \tag{6.13}
\end{equation*}
$$

Let $P=\{z=\xi\}$ and note that $P$ is a set of finite perimeter. (In fact, up to set of negligible $\mathcal{L}^{d}$-measure, it coincides with one component of its pairwise distinct representation, see 3.1 .) We define $z^{\prime}=z+\left(\xi^{\prime}-\xi\right) \chi_{P}$ and observe that $z^{\prime} \in P R\left(B_{\varepsilon}\left(x_{0}\right)\right)$ and that $z^{\prime}=u_{x_{0}, \xi^{\prime}, \nu}$ in a neighborhood of $\partial B_{\varepsilon}\left(x_{0}\right)$. Moreover, we have $J_{z^{\prime}} \subset J_{z}$, $\left[z^{\prime}\right]=[z] \mathcal{H}^{d-1}$-a.e. on $J_{z^{\prime}} \backslash \partial^{*} P$, and $\left[z^{\prime}\right]=[z]+\xi^{\prime}-\xi \mathcal{H}^{d-1}$-a.e. on $J_{z^{\prime}} \cap \partial^{*} P$. Since the functionals $\mathcal{F}_{n}$ satisfy $\left(\mathrm{H}_{5}\right)$ uniformly, we get

$$
\mathbf{m}_{\mathcal{F}_{n}}\left(u_{x_{0}, \xi^{\prime}, \nu}, B_{\varepsilon}\left(x_{0}\right)\right) \leq \mathcal{F}_{n}\left(z^{\prime}, B_{\varepsilon}\left(x_{0}\right)\right) \leq \mathcal{F}_{n}\left(z, B_{\varepsilon}\left(x_{0}\right)\right)+\int_{J_{z^{\prime}} \cap \partial^{*} P} \sigma\left(\left|\xi^{\prime}-\xi\right|\right) \mathrm{d} \mathcal{H}^{d-1}
$$

Then by 6.12 and 6.13 we derive

$$
\mathbf{m}_{\mathcal{F}_{n}}\left(u_{x_{0}, \xi^{\prime}, \nu}, B_{\varepsilon}\left(x_{0}\right)\right) \leq \mathbf{m}_{\mathcal{F}_{n}}\left(u_{x_{0}, \xi, \nu}, B_{\varepsilon}\left(x_{0}\right)\right)+\delta+\left(\omega_{d-1} \varepsilon^{d-1} \beta+\delta\right) \alpha^{-1} \sigma\left(\left|\xi^{\prime}-\xi\right|\right)
$$

As $\delta>0$ was arbitrary, we obtain one inequality in 6.11. The other inequality can be obtained in a similar fashion by interchanging the roles of $\xi$ and $\xi^{\prime}$.

The above proof makes use of the assumption 2.8, which is not a-priori guaranteed for our functionals, due to lack of coerciveness. As a matter of fact, we below prove that the first inequality in (2.8) holds always true in our setting. In the next section, we will then show how, under an additional assumption on $\mathcal{F}_{n}$ and for specific choices of $L$, also the second one can be confirmed. This yields a finer $\Gamma$ - convergence result for those cases.

Lemma 6.3 (Convergence of minima, upper bound). Let $\Omega \subset \mathbb{R}^{d}$ open, bounded with Lipschitz boundary. Let $\mathcal{F}_{n}: \operatorname{PR}(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ be a sequence of functionals satisfying $\left(\mathrm{H}_{1}\right)$, $\left(\mathrm{H}_{3}\right)-$ $\left(\mathrm{H}_{5}\right)$ for the same $0<\alpha<\beta$ and $\sigma:[0,+\infty) \rightarrow[0, \beta]$. Let $\mathcal{F}: P R(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty]$ be the $\Gamma$-limit identified in Lemma 6.2. Then for all $A \in \mathcal{A}_{0}(\Omega)$ and all $u \in P R(\Omega)$ we have

$$
\limsup _{n \rightarrow \infty} \mathbf{m}_{\mathcal{F}_{n}}(u, A) \leq \mathbf{m}_{\mathcal{F}}(u, A)
$$

Proof. Let $D \in \mathcal{A}_{0}(\Omega)$ and let $\delta>0$. (It will be convenient from a notational point of view to use $D$ instead of $A$.) Let $v \in P R(D)$ with $\mathcal{F}(v, D) \leq \mathbf{m}_{\mathcal{F}}(u, D)+\delta$ and $v=u$ on $N$, where $N \subset D$ is a neighborhood of $\partial D$ such that $N \in \mathcal{A}_{0}(\Omega)$ and

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(J_{v} \cap N\right)=\mathcal{H}^{d-1}\left(J_{u} \cap N\right) \leq \delta \tag{6.14}
\end{equation*}
$$

Let $\left(v_{n}\right)_{n} \subset P R(D)$ be a recovery sequence for $v$, i.e.,

$$
\begin{equation*}
\int_{D} \psi\left(\left|v_{n}-v\right|\right) \mathrm{d} x \rightarrow 0 \quad \text { for } n \rightarrow \infty \tag{6.15}
\end{equation*}
$$

where $\psi(t):=\frac{t}{1+t}$, and

$$
\begin{equation*}
\lim _{n \rightarrow \infty} \mathcal{F}_{n}\left(v_{n}, D\right)=\mathcal{F}(v, D) \leq \mathbf{m}_{\mathcal{F}}(u, D)+\delta \tag{6.16}
\end{equation*}
$$

We need to adjust the boundary data of $v_{n}$ to obtain competitors for the minimization problems $\mathbf{m}_{\mathcal{F}_{n}}(u, D)$. To this end, choose further neighborhoods $N^{\prime}, N^{\prime \prime} \subset D$ of $\partial D$ satisfying $N^{\prime \prime} \subset \subset$ $N^{\prime} \subset \subset N$ and $D \backslash \overline{N^{\prime}}, D \backslash \overline{N^{\prime \prime}} \in \mathcal{A}_{0}(\Omega)$. We apply Lemma 4.5 with $A^{\prime}=D \backslash \overline{N^{\prime}}, A=D \backslash \overline{N^{\prime \prime}}$, $B=N$, and some $\eta>0$ for the functions $u=\left.v_{n}\right|_{A} \in P R(A)$ and $v=\left.v\right|_{B} \in P R(B)$. We note that (4.6) is satisfied for $n$ sufficiently large since the right hand side is independent of $n$ and the left hand side converges to zero by (4.1) and 6.15. Consequently, we obtain a function $w_{n} \in P R(D)$, which satisfies $w_{n}=v=u$ on $N^{\prime \prime}$ by 4.7)(iii). Moreover, 4.7) (i) yields

$$
\mathcal{F}_{n}\left(w_{n}, D\right) \leq \mathcal{F}_{n}\left(v_{n}, D\right)+\mathcal{F}_{n}(v, N)+\left(C_{\delta}+\mathcal{F}_{n}\left(v_{n}, D\right)+\mathcal{F}_{n}(v, N)\right)\left(2 \eta+\rho_{n}\right)
$$

where $C_{\delta}$ depends on $D, N, N^{\prime}$ (and thus on $\delta$ ), and $\rho_{n}$ is a sequence converging to zero by 4.8 and 6.15. In view of (6.14), 6.16), and the fact that $\left(\mathrm{H}_{4}\right)$ holds for each $\mathcal{F}_{n}$, we then derive

$$
\limsup _{n \rightarrow \infty} \mathbf{m}_{\mathcal{F}_{n}}(u, D) \leq \limsup _{n \rightarrow \infty} \mathcal{F}_{n}\left(w_{n}, D\right) \leq\left(\mathbf{m}_{\mathcal{F}}(u, D)+\delta+\beta \delta\right)(1+2 \eta)+2 C_{\delta} \eta
$$

Letting first $\eta \rightarrow 0$ and afterwards $\delta \rightarrow 0$, we obtain the desired inequality.

## 7. Examples

In this final section, we focus on the case $L=\mathbb{R}_{\text {skew }}^{d \times d}$ and $L=S O(d)$, with $d=2,3$, which is relevant from the point of view of the applications. We consider an additional assumption $\left(\mathrm{H}_{6}\right)$ (in the spirit of $[25,49]$ ) for the functionals $\mathcal{F}_{n}$, and use it to truncate piecewise rigid functions at a low energy expense. This will allow us to overcome the lack of coercivity of our functionals, and to deduce the lower bound in the inequality (2.8) (see Lemma 7.5). With this, a full integral representation result for the $\Gamma$-limit holds true, which we state in Theorem 7.6 .
7.1. Truncation. We point out that in general, for a sequence $\left(u_{n}\right)_{n} \subset P R_{L}(\Omega)$, the bound $\sup _{n} \int_{\Omega} \psi\left(\left|u_{n}\right|\right)<+\infty$ needed to apply Lemma 3.3(i) is not guaranteed by the growth condition $\left(\mathrm{H}_{4}\right)$. As a remedy, we will therefore truncate piecewise rigid functions in a suitable way. In this context, we will need to assume
$\left(\mathrm{H}_{6}\right)$ there exists $c_{0} \geq 1$ such that for any $u, v \in P R_{L}(\Omega)$ and $S \in \mathcal{B}(\Omega)$ with the property $S \subset\left\{x \in J_{u} \cap J_{v}: c_{0} \leq|[v]| \leq c_{0}^{-1}|[u]|\right\}$ we have

$$
\mathcal{F}(v, S) \leq \mathcal{F}(u, S)
$$

This condition can be interpreted as a kind of 'monotonicity condition at infinity' for the jump height. A similar assumption was used in [25, 49], we refer to [25, Remark 3.2, 3.3] for more details. Recall the constants $\beta$, $c_{0}$ in $\left(\mathrm{H}_{4}\right)$ and $\left(\mathrm{H}_{6}\right)$, respectively.

Lemma 7.1 (Truncation). Let $d=2,3$, let $\Omega \subset \mathbb{R}^{d}$ open, bounded with Lipschitz boundary, and let $L=\mathbb{R}_{\text {skew }}^{d \times d}$ or $L=S O(d)$. Let $\theta>0$. Then there exists $C_{\theta}=C_{\theta}\left(\theta, c_{0}, \Omega\right)>0$ such that for every $u \in P R_{L}(\Omega)$ and every $\lambda \geq 1$ the following holds: there exist a rest set $R \subset \mathbb{R}^{d}$ with

$$
\begin{equation*}
\mathcal{L}^{d}(R) \leq \theta\left(\mathcal{H}^{d-1}\left(J_{u}\right)+\mathcal{H}^{d-1}(\partial \Omega)\right)^{d /(d-1)}, \quad \mathcal{H}^{d-1}\left(\partial^{*} R\right) \leq \theta\left(\mathcal{H}^{d-1}\left(J_{u}\right)+\mathcal{H}^{d-1}(\partial \Omega)\right) \tag{7.1}
\end{equation*}
$$

and a function $v \in P R_{L}(\Omega) \cap L^{\infty}\left(\Omega ; \mathbb{R}^{d}\right)$ such that
(i) $\{u \neq v\} \subset R \cup\{|u|>\lambda\} \quad$ up to a set of negligible $\mathcal{L}^{d}$-measure,
(ii) $\|v\|_{L^{\infty}(\Omega)} \leq C_{\theta} \lambda$,
(iii) $\mathcal{F}(v, \Omega) \leq \mathcal{F}(u, \Omega)+\beta \mathcal{H}^{d-1}\left(\partial^{*} R\right)$
for all $\mathcal{F}$ satisfying $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right),\left(\mathrm{H}_{4}\right)$, and $\left(\mathrm{H}_{6}\right)$.
We remark that the function $v$ also lies in $S B V\left(\Omega ; \mathbb{R}^{d}\right)$. For $L=S O(d)$ this is clear. For $L=\mathbb{R}_{\text {skew }}^{d \times d}$, this follows from the (much more general) embedding $S B D^{2}(\Omega) \cap L^{\infty}\left(\Omega ; \mathbb{R}^{d}\right) \hookrightarrow$ $S B V\left(\Omega ; \mathbb{R}^{d}\right)$ (see [48, Theorem 2.7]) or from [34, Theorem 2.2].

Remark 7.2. In the statement of Lemma 7.1, we can additionally get that $R \subset \Omega$ if $L=S O(d)$, as we are going to show in the proof. In the case $L=\mathbb{R}_{\text {skew }}^{d \times d}$, our construction of $R$ might in principle not comply with the above inclusion. It can however be easily recovered a posteriori for many geometries of $\Omega$. Indeed, e.g., for convex $\Omega$, we can simply replace $R$ with $R \cap \Omega$ at the
expense of a larger, but still universal, constant in 7.1 ) and 7.2 (iii). This follows from the fact that

$$
\begin{equation*}
\mathcal{H}^{d-1}(\partial \Omega \cap R) \leq C \mathcal{H}^{d-1}\left(\partial^{*} R\right) \tag{7.3}
\end{equation*}
$$

To see this, we fix a finite subset $\tilde{S} \subset S^{d-1}$ and we first remark that, up to changing $R$ on a null set, we can assume that, for $\nu \in \tilde{S}$ and $y \in \Pi_{\nu}:=\left\{x \in \mathbb{R}^{d}:\langle x, \nu\rangle=0\right\}$, either the line $y+\mathbb{R} \nu$ intersects $R$ on a set of positive Lebesgue measure, or has empty intersection therewith. If now $\partial \Omega \cap R \cap(y+\mathbb{R} \nu) \neq \emptyset$, on the one hand the line intersects $\partial \Omega$ at most twice (due to convexity). On the other hand, for $\mathcal{H}^{d-1}$-a.e. $y \in \Pi_{\nu}$ with $\partial \Omega \cap R \cap(y+\mathbb{R} \nu) \neq \emptyset$, applying slicing properties [11. Theorem 3.108] for the $B V$ function $\chi_{R}$ we have

$$
\mathcal{H}^{0}\left((y+\mathbb{R} \nu) \cap \partial^{*} R\right)=\mathcal{H}^{0}\left(\partial^{*}((y+\mathbb{R} \nu) \cap R)\right) \geq 2
$$

since $(y+\mathbb{R} \nu) \cap R$ is bounded with positive measure. Thus, for each $\nu \in \tilde{S}$ there holds by the Slicing Theorem (see, e.g., 43, Theorem 3.2.22])

$$
\begin{aligned}
\int_{\partial \Omega \cap R}\left|\nu \cdot \nu_{\Omega}\right| \mathrm{d} \mathcal{H}^{d-1} & =\int_{\Pi_{\nu}} \mathcal{H}^{0}((y+\mathbb{R} \nu) \cap \partial \Omega \cap R) \mathrm{d} \mathcal{H}^{d-1}(y) \\
& \leq \int_{\Pi_{\nu}} \mathcal{H}^{0}\left((y+\mathbb{R} \nu) \cap \partial^{*} R\right) \mathrm{d} \mathcal{H}^{d-1}(y) \leq \mathcal{H}^{d-1}\left(\partial^{*} R\right)
\end{aligned}
$$

This applied for a finite collection of $\left(\nu_{i}\right)_{i} \in S^{d-1}$ such that $\sup _{i}\left|\left\langle\nu, \nu_{i}\right\rangle\right| \geq \frac{1}{2}$ for all $\nu \in S^{d-1}$ yields (7.3).

We point out that standard Lipschitz-truncation techniques in $S B V$, see [23, Lemma 3.5] or [25. Lemma 4.1], are not applicable here as they do not preserve the property that the function is piecewise rigid. The main idea in the construction consists in replacing the function $u=\sum_{j} q_{j} \chi_{P_{j}}$ by a constant function on components where $q_{j}$ is 'too large'. Since the energy in general depends on the jump height, the energy is affected by such modifications. Thus, this constant has to be chosen in a careful way, and one needs to use $\left(\mathrm{H}_{6}\right)$ to ensure 7.2 (iii). In this context, it is essential to control the maximal and minimal values of $q_{j}$ on each component $P_{j}$ outside of a rest set $R$ with small perimeter. To this aim, an additional tool is required when dealing with the case $L=\mathbb{R}_{\text {skew }}^{d \times d}$, namely a careful decomposition of sets (Lemma 7.4) for which an additional rest set $R_{\text {aux }}$ has to be introduced. Our construction is inspired by similar techniques used in 49, Theorem 3.2] and [50, Theorem 4.1].

While Lemma 7.1 can be proved directly in the case $L=S O(d)$, so that a reader only interested in this case can now already skip to its proof, we need two auxiliary lemmas to deal with the case $L=\mathbb{R}_{\text {skew }}^{d \times d}$. In the sequel, given $Q \in \mathbb{R}_{\text {skew }}^{d \times d}$ and $b \in \mathbb{R}^{d}$, we denote by $\pi_{\operatorname{ker} Q}(b) \in \mathbb{R}^{d}$ the orthogonal projection of $b$ onto the kernel of $Q$. Likewise, $\pi_{\text {ker } Q^{\perp}}(b) \in \mathbb{R}^{d}$ denotes the projection on the orthogonal complement of ker $Q$. The first lemma concerns a uniform control for an affine function $q$ in terms of its minimal modulus on sets whose minimal and maximal distance from the affine space $\left\{q=\pi_{\text {ker } Q}(b)\right\}$ are comparable.

Lemma 7.3 (Minimal and maximal values of rigid motions). Let $d=2$, 3 , let $E \subset \mathbb{R}^{d}$ be a set of finite perimeter, and let $q=q_{Q, b}$ with $Q \in \mathbb{R}_{\text {skew }}^{d \times d}$ such that

$$
\begin{equation*}
\operatorname{esssup}_{x \in E} \operatorname{dist}\left(x,\left\{q=\pi_{\text {ker } Q}(b)\right\}\right) \leq C_{0} \operatorname{ess}_{\inf }^{x \in E} \text { dist }\left(x,\left\{q=\pi_{\operatorname{ker} Q}(b)\right\}\right) \tag{7.4}
\end{equation*}
$$

for some $C_{0} \geq 1$. Then there holds

$$
\|q\|_{L^{\infty}(E)} \leq C_{0}{\operatorname{ess} \inf _{x \in E}|q(x)| .}
$$

Proof. We start with $d=2$. Without restriction we can suppose that $Q \neq 0$. Then $Q$ is invertible, hence $\operatorname{ker} Q=\{0\}$, and $\{q=0\}=\{z\}$ for $z:=-Q^{-1} b$. If $|Q|$ denotes the Frobenius norm, we have $|Q y|=\frac{\sqrt{2}}{2}|Q||y|$ for all $y \in \mathbb{R}^{2}$. Then the fact that $q(z)=0$ implies

$$
|q(x)|=|q(x)-q(z)|=|Q(x-z)|=\frac{\sqrt{2}}{2}|Q||x-z|=\frac{\sqrt{2}}{2}|Q| \operatorname{dist}(x,\{q=0\})
$$

By (7.4) this implies

$$
\begin{align*}
& \operatorname{ess}_{\inf }^{x \in E} \\
&|q(x)|=\frac{\sqrt{2}}{2}|Q| \operatorname{ess} \inf _{x \in E} \operatorname{dist}(x,\{q=0\}) \geq \frac{\sqrt{2}}{2 C_{0}}|Q| \operatorname{ess}_{\sup }^{x \in E}  \tag{7.5}\\
& \operatorname{dist}(x,\{q=0\}) \\
&=\frac{1}{C_{0}}\|q\|_{L^{\infty}(E)}
\end{align*}
$$

This yields the statement for $d=2$. The case $d=3$ may simply be reduced to the two-dimensional problem by performing calculation (7.5) restricted to planes which are orthogonal to the line $\left\{q=\pi_{\text {ker } Q}(b)\right\}$. (Note that $\left\{q=\pi_{\text {ker } Q}(b)\right\}$ is one-dimensional unless $Q=0$.)

Note that for $Q \neq 0$ we have $\operatorname{dim}\left\{q=\pi_{\text {ker } Q}(b)\right\}=0$ if $d=2$ and $\operatorname{dim}\left\{q=\pi_{\text {ker } Q}(b)\right\}=1$ if $d=3$. Property (7.4) can always be achieved by introducing a suitable partition of sets of finite perimeter, as the following lemma shows. Its proof is deferred to Appendix B.

Lemma 7.4 (Decomposition of sets). There exists a universal constant $c>0$ such that the following holds for each $0<\theta<1$ :
(a) For each $x_{0} \in \mathbb{R}^{2}$ and each indecomposable, bounded set of finite perimeter $E \subset \mathbb{R}^{2}$ there exists $R \subset \mathbb{R}^{2}$ with $\mathcal{H}^{1}\left(\partial^{*} R\right) \leq \theta \mathcal{H}^{1}\left(\partial^{*} E\right)$ such that

$$
\begin{equation*}
\operatorname{ess}_{\sup }^{x \in E \backslash R} \text { }\left|x-x_{0}\right| \leq c \theta^{-1} \operatorname{ess}^{2} \inf _{x \in E \backslash R}\left|x-x_{0}\right| \tag{7.6}
\end{equation*}
$$

(b) For each line $K=x_{0}+\mathbb{R} \nu \subset \mathbb{R}^{3}, x_{0}, \nu \in \mathbb{R}^{3}$, and each indecomposable, bounded set of finite perimeter $E \subset \mathbb{R}^{3}$ there exist pairwise disjoint sets of finite perimeter $R$ and $\left(D_{j}\right)_{j=1}^{J}$ satisfying $\bigcup_{j=1}^{J} D_{j} \subset E \subset R \cup \bigcup_{j=1}^{J} D_{j}$ and

$$
\begin{equation*}
\mathcal{H}^{2}\left(\partial^{*} R\right) \leq \theta \mathcal{H}^{2}\left(\partial^{*} E\right), \quad \sum_{j=1}^{J} \mathcal{H}^{2}\left(\partial^{*} D_{j} \backslash \partial^{*} E\right) \leq \theta \mathcal{H}^{2}\left(\partial^{*} E\right) \tag{7.7}
\end{equation*}
$$

such that

$$
\begin{equation*}
\operatorname{ess} \sup _{x \in D_{j}} \operatorname{dist}(x, K) \leq c \theta^{-3}{\operatorname{ess} \inf _{x \in D_{j}} \operatorname{dist}(x, K) \quad \text { for all } j=1 \ldots, J . . . . . . . ~}_{\text {. }} \tag{7.8}
\end{equation*}
$$

We now proceed with the proof of Lemma 7.1 .
Proof of Lemma 7.1. We first provide the proof for $L=\mathbb{R}_{\text {skew }}^{3 \times 3}$. Then, we briefly indicate the necessary changes for the two-dimensional case $L=\mathbb{R}_{\text {skew }}^{2 \times 2}$. In both cases, an additional step using the previous lemmata is needed to construct an auxiliary rest set $R_{\text {aux }}$ and to derive $(7.9)-(7.11)$. We then sketch the proof for the nonlinear case $L=S O(d), d=2,3$, which follows by a similar argument but does not need Lemmata 7.3 and 7.4 . We note that it suffices to prove the lemma for $\theta \leq \theta_{0}$ for some small $\theta_{0} \leq \frac{1}{2}$ depending on $c_{0}$ and $\Omega$.

Proof for $L=\mathbb{R}_{\text {skew }}^{3 \times 3}$ : Let $u \in P R_{L}(\Omega)$ and let $u=\sum_{i \in \mathbb{N}} q_{i}^{\prime} \chi_{P_{i}^{\prime}}$ be an indecomposable representation (see Section 3.2). On each $P_{i}^{\prime}$ with $Q_{i}^{\prime} \neq 0$, we have $\operatorname{dim}\left\{q_{i}^{\prime}=\pi_{\text {ker } Q_{i}^{\prime}}\left(b_{i}^{\prime}\right)\right\}=1$. Hence, we may apply Lemma $7.4(\mathrm{~b})$ for $K=\left\{q_{i}^{\prime}=\pi_{\text {ker } Q_{i}^{\prime}}\left(b_{i}^{\prime}\right)\right\}$ to obtain a covering $P_{i}^{\prime} \subset R_{i} \cup \bigcup_{j=1}^{J_{i}} D_{j}^{i}$ with $D_{j}^{i} \subset P_{i}^{\prime}, j=1, \ldots, J_{i}$, satisfying 7.7 7.8. Otherwise, if $Q_{i}^{\prime}=0$, it trivially holds $\left\{q_{i}^{\prime}=\pi_{\text {ker } Q_{i}^{\prime}}\left(b_{i}^{\prime}\right)\right\}=\mathbb{R}^{3}$. On such components $P_{i}^{\prime}$, we simply set $R_{i}=\emptyset$ and $D_{1}^{i}=P_{i}^{\prime}$.

We define $R_{\text {aux }}=\bigcup_{i \in \mathbb{N}} R_{i}$ and denote by $\left(P_{j}\right)_{j \in \mathbb{N}}$ the partition of $\Omega \backslash R_{\text {aux }}$ consisting of the sets $\left(D_{j}^{i} \backslash R_{\text {aux }}\right)_{i, j}$. For each $j \in \mathbb{N}$, we let $q_{j}=q_{Q_{j}, b_{j}}=q_{i_{j}}^{\prime}$, where the index $i_{j} \in \mathbb{N}$ is chosen such that $P_{j} \subset P_{i_{j}}^{\prime}$. From $7.7-7.8$ and Theorem 3.1 we then obtain

$$
\begin{align*}
& \mathcal{H}^{2}\left(\partial^{*} R_{\mathrm{aux}}\right) \leq \theta \sum_{i \in \mathbb{N}} \mathcal{H}^{2}\left(\partial^{*} P_{i}^{\prime}\right)  \tag{7.9}\\
& \sum_{j \in \mathbb{N}} \mathcal{H}^{2}\left(\partial^{*} P_{j} \backslash \bigcup_{i \in \mathbb{N}} \partial^{*} P_{i}^{\prime}\right) \leq \sum_{i \in \mathbb{N}} \sum_{j=1}^{J_{i}} \mathcal{H}^{2}\left(\partial^{*} D_{j}^{i} \backslash \partial^{*} P_{i}^{\prime}\right)+\mathcal{H}^{2}\left(\partial^{*} R_{\mathrm{aux}}\right) \\
& \leq \theta \sum_{i \in \mathbb{N}} \mathcal{H}^{2}\left(\partial^{*} P_{i}^{\prime}\right)+\mathcal{H}^{2}\left(\partial^{*} R_{\mathrm{aux}}\right) \leq 2 \theta \sum_{i \in \mathbb{N}} \mathcal{H}^{2}\left(\partial^{*} P_{i}^{\prime}\right)
\end{align*}
$$

Moreover, we have
for all $j \in \mathbb{N}$. Indeed, if $\operatorname{dim}\left\{q_{j}=\pi_{\operatorname{ker} Q_{j}}\left(b_{j}\right)\right\}=1,7.10$ follows from (7.8) and the fact that $P_{j} \subset D_{k}^{i}$ for some $D_{k}^{i}$. If $\left\{q_{j}=\pi_{\operatorname{ker} Q_{j}}\left(b_{j}\right)\right\}=\mathbb{R}^{3}$, it is trivially satisfied. We also note that (3.2), (7.9), and Theorem 3.1 imply

$$
\begin{equation*}
\sum_{j \in \mathbb{N}} \mathcal{H}^{2}\left(\partial^{*} P_{j}\right) \leq c \sum_{i \in \mathbb{N}} \mathcal{H}^{2}\left(\partial^{*} P_{i}^{\prime}\right) \leq c\left(\mathcal{H}^{2}\left(J_{u}\right)+\mathcal{H}^{2}(\partial \Omega)\right) \tag{7.11}
\end{equation*}
$$

where $c>0$ is universal.
We define $I_{\lambda}=\left\{j \in \mathbb{N}:\left\|q_{j}\right\|_{L^{\infty}\left(P_{j}\right)}>\lambda \theta^{-6}\right\}$ and introduce a decomposition of $I_{\lambda}$ according to the $L^{\infty}$-norms of the rigid motions: for $k \in \mathbb{N}$ we introduce the set of indices

$$
\begin{equation*}
I_{\lambda}^{k}=\left\{j \in I_{\lambda}: \lambda \theta^{-6 k}<\left\|q_{j}\right\|_{L^{\infty}\left(P_{j}\right)} \leq \lambda \theta^{-6(k+1)}\right\} \tag{7.12}
\end{equation*}
$$

and define $s_{k}=\sum_{j \in I_{\lambda}^{k}} \mathcal{H}^{2}\left(\partial^{*} P_{j}\right)$ for $k \in \mathbb{N}$. By 7.11 we find some $K_{\theta} \in \mathbb{N}, K_{\theta} \leq \theta^{-1}$, such that

$$
\begin{equation*}
s_{K_{\theta}} \leq c \theta\left(\mathcal{H}^{2}\left(J_{u}\right)+\mathcal{H}^{2}(\partial \Omega)\right) \tag{7.13}
\end{equation*}
$$

We define the index set

$$
\begin{equation*}
I=\bigcup_{k>K_{\theta}} I_{\lambda}^{k} \tag{7.14}
\end{equation*}
$$

and introduce the rest set

$$
\begin{equation*}
R=\bigcup_{j \in I_{\lambda}^{K_{\theta}}} P_{j} \cup R_{\mathrm{aux}} \tag{7.15}
\end{equation*}
$$

By Theorem 3.1, (7.9, 7.11, and 7.13 we find

$$
\begin{equation*}
\mathcal{H}^{2}\left(\partial^{*} R\right) \leq \sum_{j \in I_{\lambda}^{K_{\theta}}} \mathcal{H}^{2}\left(\partial^{*} P_{j}\right)+\mathcal{H}^{2}\left(\partial^{*} R_{\text {aux }}\right) \leq s_{K_{\theta}}+\theta \sum_{i \in \mathbb{N}} \mathcal{H}^{2}\left(\partial^{*} P_{i}^{\prime}\right) \leq c \theta\left(\mathcal{H}^{2}\left(J_{u}\right)+\mathcal{H}^{2}(\partial \Omega)\right) \tag{7.16}
\end{equation*}
$$

In view of Lemma 7.3 and 7.10 , we obtain for each $j \in I$
where the last step holds for $\theta_{0}$ sufficiently small. We define $U=R \cup \bigcup_{j \in I} P_{j}$ and get by 7.12 , (7.14) (7.15), and 7.17) that
(i) $\|u\|_{L^{\infty}(\Omega \backslash U)} \leq \lambda \theta^{-6 K_{\theta}}$,
(ii) $\operatorname{ess} \inf \{|u(x)|: x \in U \backslash R\} \geq 3 \theta^{4} \lambda \theta^{-6\left(K_{\theta}+1\right)}=3 \lambda \theta^{-6 K_{\theta}-2}$.

We define $v \in P R_{L}(\Omega) \cap L^{\infty}\left(\Omega ; \mathbb{R}^{3}\right)$ by

$$
\begin{equation*}
v:=u \chi_{\Omega \backslash U}+b e_{1} \chi_{U}, \quad \text { where } b:=\lambda \theta^{-6 K_{\theta}-1} \tag{7.19}
\end{equation*}
$$

We now show (7.1)-7.2 and start with 7.2). First, 7.2 (i) follows from 7.18 (ii). Setting $C_{\theta}=\theta^{-6 / \theta-1}, \sqrt{7.2}\left(\right.$ (ii) follows from 7.18 (i), 7.19), and the fact that $K_{\theta} \leq 1 / \theta$.

We now address $\overline{7.2}$ (iii). As a preparation, we compare the jump sets of $u$ and $v$. First, 7.18) (i) and 7.19 show that $J_{v} \supset \partial^{*} U \cap \Omega$ up to an $\mathcal{H}^{2}$-negligible set. Choose the orientation of $\nu_{v}(x)$ for $x \in \partial^{*} U \cap \Omega$ such that $v^{+}(x)$ coincides with the trace of $v \chi_{U}$ at $x$ and $v^{-}(x)$ coincides with the trace of $v \chi_{\Omega \backslash U}$ at $x$. (The traces have to be understood in the sense of [11, Theorem 3.77].) Moreover, we suppose that $\nu_{v}=\nu_{u}$ on $J_{u} \cap \partial^{*} U \cap \Omega$. Suppose that $\theta \leq \theta_{0} \leq \frac{1}{2}$. For $\mathcal{H}^{2}$-a.e. $x \in\left(\partial^{*} U \cap \Omega\right) \backslash \partial^{*} R$ we derive by 7.18) 7.19) and $[v](x)=v^{+}(x)-v^{-}(x)=b e_{1}-u^{-}(x)$ that

$$
\lambda \theta^{-6 K_{\theta}} \leq b-\|u\|_{L^{\infty}(\Omega \backslash U)} \leq|[v](x)| \leq b+\|u\|_{L^{\infty}(\Omega \backslash U)} \leq 2 \lambda \theta^{-6 K_{\theta}-1}
$$

In a similar fashion, we obtain

$$
|[u](x)| \geq\left|u^{+}(x)\right|-\left|u^{-}(x)\right| \geq 3 \lambda \theta^{-6 K_{\theta}-2}-\lambda \theta^{-6 K_{\theta}} \geq 2 \lambda \theta^{-6 K_{\theta}-2}
$$

Therefore, since $\lambda \geq 1$ and $K_{\theta} \geq 1$, we find

$$
\begin{equation*}
\theta^{-1} \leq|[v](x)| \leq \theta|[u](x)| \tag{7.20}
\end{equation*}
$$

for $\mathcal{H}^{2}$-a.e. $x \in\left(\partial^{*} U \cap \Omega\right) \backslash \partial^{*} R$. We are now in a position to show 7.2 (iii). By $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right), u=v$ on $\Omega \backslash U$, and the fact that $v$ is constant on $U$, we get

$$
\begin{aligned}
\mathcal{F}(v, \Omega) & =\mathcal{F}\left(v,(U)^{1}\right)+\mathcal{F}\left(v,(\Omega \backslash U)^{1}\right)+\mathcal{F}\left(v, \partial U^{*} \cap \Omega\right)=\mathcal{F}\left(u,(\Omega \backslash U)^{1}\right)+\mathcal{F}\left(v, \partial U^{*} \cap \Omega\right) \\
& \leq \mathcal{F}\left(u,(\Omega \backslash U)^{1}\right)+\mathcal{F}\left(v,\left(\partial^{*} U \backslash \partial^{*} R\right) \cap \Omega\right)+\mathcal{F}\left(v, \partial^{*} R \cap \Omega\right)
\end{aligned}
$$

By $\left(\mathrm{H}_{4}\right),\left(\mathrm{H}_{6}\right)$, and 7.20 (for $\theta$ sufficiently small such that $\left.\theta^{-1} \geq c_{0}\right)$ we get

$$
\begin{aligned}
\mathcal{F}(v, \Omega) & \leq \mathcal{F}\left(u,(\Omega \backslash U)^{1}\right)+\mathcal{F}\left(u,\left(\partial^{*} U \backslash \partial^{*} R\right) \cap \Omega\right)+\beta \mathcal{H}^{1}\left(\partial^{*} R\right) \\
& \leq \mathcal{F}(u, \Omega)+\beta \mathcal{H}^{1}\left(\partial^{*} R\right)
\end{aligned}
$$

where in the last step we again used $\left(\mathrm{H}_{1}\right)$ and the fact that $\mathcal{F}\left(u,(U)^{1}\right) \geq 0$. This concludes the proof of 7.2 (iii).

It remains to show (7.1). By 7.16 and the isoperimetric inequality we obtain the desired estimate with $c \theta$ in place of $\theta$. Clearly, the constant $c$ can be absorbed in $\theta$ by repeating the above arguments for $\theta / c$ in place of $\theta$. This concludes the proof for $L=\mathbb{R}_{\text {skew }}^{3 \times 3}$.

Adaptions for $L=\mathbb{R}_{\text {skew }}^{2 \times 2}$ : For the two-dimensional case $L=\mathbb{R}_{\text {skew }}^{2 \times 2}$, the following small adaption is necessary: before 7.9 ), for components $P_{i}^{\prime}$ with $\operatorname{dim}\left\{q_{i}^{\prime}=0\right\}=0$ (i.e., $Q_{i}^{\prime} \neq 0$ ), we apply Lemma 7.4 (a) in place of Lemma 7.4 (b). (This case is even easier since the collection $\left(D_{j}^{i}\right)_{j}$ consists of one set only.)

Proof for $L=S O(d), d=2,3$ : Here, we do not need to introduce a decomposition using Lemma 7.4. and we can work directly with the indecomposable representation $u=\sum_{j \in \mathbb{N}} q_{j} \chi_{P_{j}}$. We define the index sets $I_{\lambda}^{k}$, the integer $K_{\theta}$, and the index set $I$ exactly as in $7.12-(7.14)$. We set

$$
R=\bigcup_{j \in I_{\lambda}^{K_{\theta}}} P_{j}
$$

Notice that, by construction, we have $R \subset \Omega$ as stated in Remark 7.2. By Theorem 3.1 and 7.13 we find

$$
\mathcal{H}^{d-1}\left(\partial^{*} R\right) \leq \sum_{j \in I_{\lambda}^{K_{\theta}}} \mathcal{H}^{d-1}\left(\partial^{*} P_{j}\right) \leq s_{K_{\theta}} \leq c \theta\left(\mathcal{H}^{d-1}\left(J_{u}\right)+\mathcal{H}^{d-1}(\partial \Omega)\right)
$$

We further observe by 7.12 and 7.14 that we have for each $j \in I$ that $\left\|q_{j}\right\|_{L^{\infty}\left(P_{j}\right)} \geq \lambda \theta^{-6} \geq$ $2 \operatorname{diam}(\Omega)$, where the second step holds for $\theta_{0}$ sufficiently small. As $q_{j}$ is an isometry, there holds

$$
\left\|q_{j}\right\|_{L^{\infty}\left(P_{j}\right)} \leq{\operatorname{ess} \inf _{x \in P_{j}}\left|q_{j}(x)\right|+\operatorname{diam}(\Omega) \leq \operatorname{ess}_{\inf }^{x \in P_{j}} \mid}\left|q_{j}(x)\right|+\frac{1}{2}\left\|q_{j}\right\|_{L^{\infty}\left(P_{j}\right)}
$$

which in turn implies $\left\|q_{j}\right\|_{L^{\infty}\left(P_{j}\right)} \leq 2 \operatorname{ess}^{\inf }{ }_{x \in P_{j}}\left|q_{j}(x)\right|$ for all $j \in I$. This inequality clearly yields (7.17). The result then follows by verbatim repeating the argument after (7.17).
7.2. A finer $\Gamma$-convergence result. We first show that, under assumption $\left(\mathrm{H}_{6}\right)$ and for $L=$ $\mathbb{R}_{\text {skew }}^{d \times d}$ or $L=S O(d), d=2,3$, the second inequality in 2.8 holds as a consequence of Lemma 7.1 .
Lemma 7.5 (Convergence of minima, lower bound). Let $d=2,3$, and let $L=\mathbb{R}_{\text {skew }}^{d \times d}$ or $L=$ $S O(d)$. Let $\Omega \subset \mathbb{R}^{d}$ open, bounded with Lipschitz boundary. Let $\mathcal{F}_{n}: P R_{L}(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ be a sequence of functionals satisfying $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{6}\right)$ for the same $0<\alpha<\beta, c_{0} \geq 1$, and $\sigma:[0,+\infty) \rightarrow[0, \beta]$. Let $\mathcal{F}: P R_{L}(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty]$ be the $\Gamma$-limit identified in Lemma 6.2. Then for each ball $B_{\varepsilon}\left(x_{0}\right) \subset \Omega$ and all $u \in P R_{L}(\Omega)$ we have

$$
\sup _{0<\varepsilon^{\prime}<\varepsilon} \liminf _{n \rightarrow \infty} \mathbf{m}_{\mathcal{F}_{n}}\left(u, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right) \geq \mathbf{m}_{\mathcal{F}}\left(u, B_{\varepsilon}\left(x_{0}\right)\right)
$$

Proof. For convenience, we again drop the subscript $L$ in the proof and write $A=B_{\varepsilon}\left(x_{0}\right)$. Let $\theta>0$. Fix $u \in P R(\Omega)$ and choose a ball $A^{\prime}:=B_{\varepsilon^{\prime}}\left(x_{0}\right), \varepsilon^{\prime}<\varepsilon$, such that

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(J_{u} \cap\left(A \backslash A^{\prime}\right)\right) \leq \theta \tag{7.21}
\end{equation*}
$$

As $u$ is measurable, we may fix a nonnegative, monotone increasing, and coercive function $\psi$ with

$$
\begin{equation*}
\int_{A} \psi(|u|) \mathrm{d} x<+\infty \tag{7.22}
\end{equation*}
$$

Now, let $u=\sum_{j \in \mathbb{N}} q_{j} \chi_{P_{j}}$ be the piecewise distinct representation. In view of Theorem 3.1, we can choose $J \in \mathbb{N}$ sufficiently large such that the set $S_{\theta}:=\bigcup_{j>J} P_{j}$ satisfies

$$
\begin{equation*}
\mathcal{H}^{d-1}\left(J_{u} \cap\left(\partial^{*} S_{\theta} \cup\left(S_{\theta}\right)^{1}\right)\right) \leq \theta \tag{7.23}
\end{equation*}
$$

where $\left(S_{\theta}\right)^{1}$ denotes the set of points with density 1 . Since $J$ is finite, we may fix $\lambda_{\theta} \geq 1$ such that

$$
\begin{equation*}
\|u\|_{L^{\infty}\left(A \backslash S_{\theta}\right)}<\lambda_{\theta} . \tag{7.24}
\end{equation*}
$$

We now consider a sequence $\left(v_{n}\right)_{n} \subset P R\left(A^{\prime}\right)$ with $v_{n}=u$ in a neighborhood $N_{n} \subset A^{\prime}$ of $\partial A^{\prime}$ and

$$
\begin{equation*}
\mathcal{F}_{n}\left(v_{n}, A^{\prime}\right) \leq \mathbf{m}_{\mathcal{F}_{n}}\left(u, A^{\prime}\right)+1 / n \tag{7.25}
\end{equation*}
$$

Without restriction we can suppose that $\sup _{n} \mathcal{F}_{n}\left(v_{n}, A^{\prime}\right)<+\infty$, i.e., $\sup _{n} \mathcal{H}^{d-1}\left(J_{v_{n}}\right)<+\infty$ by $\left(\mathrm{H}_{4}\right)$. We apply Lemma 7.1 and Remark 7.2 with $A^{\prime}$ in place of $\Omega$ and for $\lambda=\lambda_{\theta}$ on each $v_{n}$ and find $v_{n}^{\prime} \in P R\left(A^{\prime}\right) \cap L^{\infty}\left(A^{\prime} ; \mathbb{R}^{d}\right)$ and sets of finite perimeter $R_{n}^{\theta} \subset A^{\prime}$ such that by (7.1) and 7.2 (iii)

$$
\begin{equation*}
\mathcal{F}_{n}\left(v_{n}^{\prime}, A^{\prime}\right) \leq \mathcal{F}\left(v_{n}, A^{\prime}\right)+C \beta \theta, \quad \mathcal{H}^{d-1}\left(\partial^{*} R_{n}^{\theta}\right) \leq C \theta \tag{7.26}
\end{equation*}
$$

where $C$ depends on $A$ and $\sup _{n} \mathcal{H}^{d-1}\left(J_{v_{n}}\right)<+\infty$. Observe by 7.2 (i) that we have $\left\{v_{n} \neq v_{n}^{\prime}\right\} \subset$ $R_{n}^{\theta} \cup\left\{\left|v_{n}\right|>\lambda_{\theta}\right\}$, so that using (7.24) we deduce that $v_{n}^{\prime}=u$ on $N_{n} \backslash\left(R_{n}^{\theta} \cup S_{\theta}\right)$.

We introduce the functions $v_{n}^{\theta} \in P R(A)$ by

$$
v_{n}^{\theta}= \begin{cases}u & \text { on }\left(A \backslash \overline{A^{\prime}}\right) \cup S_{\theta}  \tag{7.27}\\ v_{n}^{\prime} & \text { else }\end{cases}
$$

By $\left(\mathrm{H}_{1}\right),\left(\mathrm{H}_{3}\right)$, and $\left(\mathrm{H}_{4}\right)$ this implies

$$
\begin{align*}
\mathcal{F}_{n}\left(v_{n}^{\theta}, A\right) \leq & \mathcal{F}\left(u,\left(A \backslash \overline{A^{\prime}}\right) \cup\left(S_{\theta}\right)^{1}\right)+\mathcal{F}_{n}\left(v_{n}^{\prime}, A^{\prime} \cap\left(S_{\theta}\right)^{0}\right) \\
& +\beta \mathcal{H}^{d-1}\left(\partial^{*} S_{\theta}\right)+\beta \mathcal{H}^{d-1}\left(J_{v_{n}^{\theta}} \cap \partial A^{\prime} \cap\left(S_{\theta}\right)^{0}\right), \tag{7.28}
\end{align*}
$$

where $\left(S_{\theta}\right)^{0}$ denotes the set of points with density 0 . Since $v_{n}^{\prime}=u$ on $N_{n} \backslash\left(R_{n}^{\theta} \cup S_{\theta}\right)$, we have $J_{v_{n}^{\theta}} \cap \partial A^{\prime} \cap\left(S_{\theta}\right)^{0} \subset \partial^{*} R_{n}^{\theta}$. With this, using 7.28), $\left(\mathrm{H}_{1}\right)$, and $\left(\mathrm{H}_{4}\right)$, we get

$$
\mathcal{F}_{n}\left(v_{n}^{\theta}, A\right) \leq \mathcal{F}_{n}\left(v_{n}^{\prime}, A^{\prime}\right)+\beta \mathcal{H}^{d-1}\left(J_{u} \cap\left(\left(A \backslash \overline{A^{\prime}}\right) \cup\left(S_{\theta}\right)^{1}\right)\right)+\beta \mathcal{H}^{d-1}\left(\partial^{*} S_{\theta}\right)+\beta \mathcal{H}^{d-1}\left(\partial^{*} R_{n}^{\theta}\right)
$$

Therefore, by (7.21, 7.23), and 7.26 we get

$$
\begin{equation*}
\mathcal{F}_{n}\left(v_{n}^{\theta}, A\right) \leq \mathcal{F}_{n}\left(v_{n}, A^{\prime}\right)+C \beta \theta \tag{7.29}
\end{equation*}
$$

Since $\sup _{n} \mathcal{F}_{n}\left(v_{n}, A^{\prime}\right)<+\infty$, we get $\sup _{n} \mathcal{H}^{d-1}\left(J_{v_{n}^{\theta}}\right)<+\infty$ by $\left(\mathrm{H}_{4}\right)$ and 7.29 . By 7.2 (ii) and the construction in $\sqrt{7.27}$ ), it holds $\left|v_{n}^{\theta}(x)\right| \leq \max \left\{C_{\theta} \lambda_{\theta},|u(x)|\right\}$ for a.e. $x \in A$, where $C_{\theta}$ is the constant in 7.2 (ii). With 7.22 we then have $\sup _{n} \int_{A} \psi\left(\left|v_{n}^{\theta}\right|\right) \mathrm{d} x<+\infty$. Hence, we can apply Lemma 3.3(i) to find $v^{\theta} \in P R(A)$ such that, up to a subsequence (not relabeled), $v_{n}^{\theta} \rightarrow v^{\theta}$ in measure on $A$. Clearly, by $(7.27)$ we have $v^{\theta}=u$ on $A \backslash \overline{A^{\prime}}$. By (6.6), (7.25), and (7.29) we get

$$
\mathcal{F}\left(v^{\theta}, A\right) \leq \liminf _{n \rightarrow \infty} \mathcal{F}_{n}\left(v_{n}^{\theta}, A\right) \leq \liminf _{n \rightarrow \infty} \mathcal{F}_{n}\left(v_{n}, A^{\prime}\right)+C \beta \theta \leq \liminf _{n \rightarrow \infty} \mathbf{m}_{\mathcal{F}_{n}}\left(u, A^{\prime}\right)+C \beta \theta
$$

As $v^{\theta}=u$ in a neighborhood of $\partial A$, we get

$$
\mathbf{m}_{\mathcal{F}}(u, A) \leq \mathcal{F}\left(v^{\theta}, A\right) \leq \liminf _{n \rightarrow \infty} \mathbf{m}_{\mathcal{F}_{n}}\left(u, A^{\prime}\right)+C \beta \theta \leq \sup _{0<\varepsilon^{\prime}<\varepsilon} \liminf _{n \rightarrow \infty} \mathbf{m}_{\mathcal{F}_{n}}\left(u, B_{\varepsilon^{\prime}}\left(x_{0}\right)\right)+C \beta \theta
$$

where in the last step we used that $A^{\prime}=B_{\varepsilon^{\prime}}\left(x_{0}\right)$. By passing to $\theta \rightarrow 0$ we conclude the proof.
By combining the above lemma with Theorem 2.3 and Lemma 6.3 we finally get a full integral representation result for the $\Gamma$-limit in the setting considered in this section.

Theorem 7.6. Let $d=2,3$, and let $L=\mathbb{R}_{\text {skew }}^{d \times d}$ or $L=S O(d)$. Let $\Omega \subset \mathbb{R}^{d}$ open, bounded with Lipschitz boundary. Let $\mathcal{F}_{n}: P R_{L}(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ be a sequence of functionals satisfying $\left(\mathrm{H}_{1}\right)$, $\left(\mathrm{H}_{3}\right)-\left(\mathrm{H}_{6}\right)$ for the same $0<\alpha<\beta, c_{0} \geq 1$, and $\sigma:[0,+\infty) \rightarrow[0, \beta]$. Then there exists $\mathcal{F}: P R_{L}(\Omega) \times \mathcal{B}(\Omega) \rightarrow[0, \infty)$ satisfying $\left(\mathrm{H}_{1}\right)-\left(\mathrm{H}_{5}\right)$ and a subsequence (not relabeled) such that

$$
\mathcal{F}(\cdot, A)=\Gamma-\lim _{n \rightarrow \infty} \mathcal{F}_{n}(\cdot, A) \quad \text { with respect to convergence in measure on } A
$$

for all $A \in \mathcal{A}_{0}(\Omega)$. Moreover, $\mathcal{F}$ admits the representation (2.6)-2.7).

## Acknowledgements

This work was supported by the DFG project FR 4083/1-1 and by the Deutsche Forschungsgemeinschaft (DFG, German Research Foundation) under Germany's Excellence Strategy EXC 2044 -390685587, Mathematics Münster: Dynamics-Geometry-Structure. The support by the Alexander von Humboldt Foundation is gratefully acknowledged. The authors are gratefully indebted to Marco Cicalese for many stimulating discussions on the content of this work.

## Appendix A. Proof of Proposition 2.1

Proof. We give the proof only for $d=3$ since it is similar and simpler for $d=2$. Consider the exponential map $S \mapsto \exp (S)$, which is surjective from a compact subset of $\mathbb{R}_{\text {skew }}^{3 \times 3}$ to $S O(3)$. Clearly, once we have proved property 2.2 for $\exp$, the desired map $\Psi_{L}$ can be defined as the composition of $\exp$ with the canonical isomorphism between $\mathbb{R}_{\text {skew }}^{3 \times 3}$ and $\mathbb{R}^{3}$. Throughout the proof, we denote by $|\cdot|$ the Frobenius norm of a matrix, by $|\cdot|_{2}$ its spectral norm, and with $c_{2} \in(0,1)$ an equivalence constant between the two norms. Since in this case $r_{L}<+\infty$ (we can take for instance $r_{L}=2 \pi$ ), up to rescaling the constant, it is equivalent to prove (2.2) for a ball of radius $c_{0}$ in place of $c_{L} r_{L}$.

We start by fixing $c_{0}<\frac{1}{4}$ and $\bar{R} \in S O(3)$. If $|\bar{R}-I| \leq \frac{1}{2}$, then $|R-I|<\frac{3}{4}$ for all $R \in B_{c_{0}}(\bar{R})$ : therefore, a smooth inverse given by a matrix logarithm is well-defined in $B_{c_{0}}(\bar{R})$ through the usual Taylor expansion around the identity. By its smoothness it clearly satisfies 2.2 .

We therefore focus on the case where $|\bar{R}-I|>\frac{1}{2}$. Since $c_{0}<\frac{1}{4}$, there holds

$$
\begin{equation*}
|R-I| \geq \frac{1}{4} \quad \text { for all } \quad R \in B_{c_{0}}(\bar{R}) \tag{A.1}
\end{equation*}
$$

In view of Rodrigues' rotation formula and the power series expansion of $\exp$, for each $R \in$ $B_{c_{0}}(\bar{R}) \cap S O(3)$ there exists a unit vector $n_{R}$ and an angle $\theta_{R}$ such that

$$
\begin{equation*}
R=I+\sin \left(\theta_{R}\right) N_{R}+\left(1-\cos \left(\theta_{R}\right)\right) N_{R}^{2}=\exp \left(\theta_{R} N_{R}\right) \tag{A.2}
\end{equation*}
$$

where $N_{R} \in \mathbb{R}_{\text {skew }}^{3 \times 3}$ denotes the unique matrix with $N_{R} u=n_{R} \times u$ for all $u \in \mathbb{R}^{3}$. In particular, for each $u \in \mathbb{R}^{3}$ there holds with the help of the Graßmann identity $n_{R} \times\left(n_{R} \times u\right)=n_{R}\left\langle n_{R}, u\right\rangle-u$

$$
\begin{equation*}
R u=\cos \left(\theta_{R}\right) u+\sin \left(\theta_{R}\right)\left(n_{R} \times u\right)+\left\langle n_{R}, u\right\rangle\left(1-\cos \left(\theta_{R}\right)\right) n_{R} \tag{A.3}
\end{equation*}
$$

Thus, our goal is to specify the choice of $N_{R}$ and $\theta_{R}$. The desired matrix $S_{R} \in \mathbb{R}_{\text {skew }}^{3 \times 3}$ is then defined by $S_{R}=\theta_{R} N_{R}$ since $\exp \left(S_{R}\right)=R$, see A.2). We start with some preliminary facts (Step 1). Then, we define the map $R \mapsto S_{R}$ on $B_{c_{0}}(\bar{R}) \cap S O(3)$ and show that it is Lipschitz (Step 2).

Step 1: Preliminary facts. Let $R \neq I$ be a rotation. Then there exists a unit eigenvector $n$ of $R$ with eigenvalue 1 which corresponds to the rotation axis. Let $n^{\perp}=\left\{w \in \mathbb{R}^{3}:\langle n, w\rangle=0\right\}$. Since $R n=n$, for all $w \in n^{\perp}$ with $|w|=1$ there holds that

$$
\begin{equation*}
|(R-I) w|=|R-I|_{2} \tag{A.4}
\end{equation*}
$$

is constant with respect to $w$. Indeed, the fact that $|(R-I) w|$ is constant follows from the Rodrigues' rotation formula A.3), and the second implication immediately follows by the definition of the spectral norm. Notice also that for $R, n$ as before, and for all $w \in n^{\perp}$ with $|w|=1$ it holds $|(R-I) w|^{2}=-2\langle(R-I) w, w\rangle$ since $R$ is a rotation. Combining with A.4 we get

$$
\begin{equation*}
\langle(R-I) w, w\rangle=-\frac{1}{2}|R-I|_{2}^{2} \tag{A.5}
\end{equation*}
$$

As a further preparation, we show that for $R_{1}, R_{2} \in B_{c_{0}}(\bar{R}) \cap S O(3)$ there holds

$$
\begin{equation*}
\sqrt{1-\left|\left\langle n_{1}, n_{2}\right\rangle\right|^{2}} \leq 4 c_{2}^{-1}\left|R_{1}-R_{2}\right| \leq 8 c_{2}^{-1} c_{0} \tag{A.6}
\end{equation*}
$$

where $n_{i}$ are unit eigenvectors of $R_{i}$ with eigenvalue 1 for $i=1,2$. The second inequality is clear. To see the first, by $R_{2} n_{2}=n_{2}$ we get on the one hand

$$
\left|\left(R_{1}-I\right) n_{2}\right|=\left|\left(R_{1}-R_{2}\right) n_{2}\right| \leq\left|R_{1}-R_{2}\right|
$$

On the other hand, writing $n_{2}=\mu n_{1}+\sqrt{1-\mu^{2}} y$, where $\mu=\left\langle n_{1}, n_{2}\right\rangle$ and $y \in n_{1}^{\perp}$ with $|y|=1$, we have by A.1), A.4), and $R_{1} n_{1}=n_{1}$

$$
\left|\left(R_{1}-I\right) n_{2}\right|=\sqrt{1-\mu^{2}}\left|\left(R_{1}-I\right) y\right|=\sqrt{1-\mu^{2}}\left|R_{1}-I\right|_{2} \geq c_{2} \sqrt{1-\mu^{2}}\left|R_{1}-I\right| \geq \frac{1}{4} c_{2} \sqrt{1-\mu^{2}}
$$

where we also used $|\cdot|_{2} \geq c_{2}|\cdot|$. By combining the two estimates we get A.6).
Step 2: Construction of the inverse mapping. Given $\bar{R}$, we define a positive orthonormal basis $\{\bar{n}, \bar{w}, \bar{z}\}$ of $\mathbb{R}^{3}$ with $\bar{R} \bar{n}=\bar{n}$. Consider $R \in B_{c_{0}}(\bar{R}) \cap S O(3)$ and let $n$ be a unit vector with $R n=n$. Provided that we let $c_{0} \leq c_{2} / 16, n$ can be chosen such that $\langle n, \bar{n}\rangle \geq \frac{3}{4}$, see A.6. We define a positive orthonormal basis $\{n, w, z\}$ by $w=(\bar{z} \times n) /|\bar{z} \times n|$ and $z=n \times w$. Since $R \in S O(3)$ and $R n=n$, the vectors $\{n, R w, R z\}$ form a positive orthornormal basis of $\mathbb{R}^{3}$ as well. Hence, we get the equalities

$$
R w=\langle R w, w\rangle w+\langle R w, z\rangle z, \quad R z=-\langle R w, z\rangle w+\langle R w, w\rangle z
$$

Now, the point $(\langle R w, w\rangle,\langle R w, z\rangle)$ lies in $S^{1}$. By an elementary computation along with A.1 and A.5) we get

$$
|(\langle R w, w\rangle,\langle R w, z\rangle)-(1,0)|=\sqrt{2\langle(I-R) w, w\rangle}=|R-I|_{2} \geq c_{2}|R-I| \geq c_{2} / 4
$$

Hence, we can consider a smooth inverse $\Theta$ of the mapping $\theta \mapsto(\cos (\theta), \sin (\theta))$ defined on $S^{1} \backslash$ $B_{c_{2} / 4}(1,0)$ and with values in a compact interval of the form $[\eta, 2 \pi-\eta]$. We define

$$
\begin{equation*}
\theta_{R}=\Theta(\langle R w, w\rangle,\langle R w, z\rangle) \tag{A.7}
\end{equation*}
$$

The function $\Theta$ can be taken globally Lipschitz on its domain since the latter is at positive distance to the singularity at $(1,0)$.

Summarizing, given $R \in B_{c_{0}}(\bar{R}) \cap S O(3)$, we let $n_{R}=n$ with $R n=n,|n|=1, N_{R} \in \mathbb{R}_{\text {skew }}^{3 \times 3}$ with $N_{R} u=n_{R} \times u$ for all $u \in \mathbb{R}^{3}, \theta_{R}$ as in A.7), and $S_{R}=\theta_{R} N_{R}$. Recall that $R=\exp \left(S_{R}\right)$, see (A.2). Finally, to check that $R \mapsto S_{R}$ is Lipschitz, we first note that $R \mapsto n_{R}$ is Lipschitz. Indeed, let $n_{1}$ and $n_{2}$ be the rotation axes corresponding to $R_{1}$ and $R_{2}$ with $\left\langle n_{i}, \bar{n}\right\rangle \geq \frac{3}{4}$ for $i=1,2$. Then it is elementary to check that $\left\langle n_{1}, n_{2}\right\rangle \geq\left\langle n_{2}, \bar{n}\right\rangle-\left|n_{1}-\bar{n}\right| \geq \frac{1}{4} \geq 0$. By A.6 we then get

$$
\begin{equation*}
\left|n_{1}-n_{2}\right|=\sqrt{2-2\left\langle n_{1}, n_{2}\right\rangle} \leq \sqrt{2} \sqrt{\left(1+\left\langle n_{1}, n_{2}\right\rangle\right)\left(1-\left\langle n_{1}, n_{2}\right\rangle\right)} \leq 4 \sqrt{2} c_{2}^{-1}\left|R_{1}-R_{2}\right| \tag{A.8}
\end{equation*}
$$

In a similar fashion, $R \mapsto \theta_{R}$ is Lipschitz with $\theta_{R}$ from A.7). In fact, $\Theta$ is globally Lipschitz on $S^{1} \backslash B_{c_{2} / 4}(1,0)$, and by construction together with A.8 there holds

$$
\left|w_{1}-w_{2}\right| \leq C\left|R_{1}-R_{2}\right|, \quad\left|z_{1}-z_{2}\right| \leq C\left|R_{1}-R_{2}\right|
$$

for some universal $C>0$, where $w_{i}=\left(\bar{z} \times n_{i}\right) /\left|\bar{z} \times n_{i}\right|$ and $z_{i}=n_{i} \times w_{i}$ for $i=1,2$.

## Appendix B. Proof of Lemma 7.4

Proof. For the proof we use the notation $\operatorname{diam}(F)=\operatorname{ess} \sup \{|x-y|: x, y \in F\}$ and

$$
\operatorname{diam}_{1}(F)=\operatorname{ess} \sup \left\{\left|\left\langle x-y, e_{1}\right\rangle\right|: x, y \in F\right\}
$$

for bounded, measurable sets $F \subset \mathbb{R}^{d}, d=2,3$.
Part (a) relies on the property that for each indecomposable, bounded set of finite perimeter $E$ one has

$$
\begin{equation*}
\operatorname{diam}(E) \leq \mathcal{H}^{1}\left(\partial^{*} E\right) \tag{B.1}
\end{equation*}
$$

For a proof we refer to [52, Propostion 12.19, Remark 12.28]. Then the statement follows simply by letting $R=B_{r}\left(x_{0}\right)$ be the circle with center $x_{0}$ and radius $r=\frac{1}{2 \pi} \theta \operatorname{diam}(E)$. Then B.1 implies $\mathcal{H}^{1}(\partial R) \leq \theta \mathcal{H}^{1}\left(\partial^{*} E\right)$ and 7.6 holds since

$$
\operatorname{ess} \sup _{x \in E \backslash R}\left|x-x_{0}\right| \leq{\operatorname{ess} \inf _{x \in E \backslash R}\left|x-x_{0}\right|+\operatorname{diam}(E) \leq\left(1+2 \pi \theta^{-1}\right) \operatorname{ess} \inf _{x \in E \backslash R}\left|x-x_{0}\right| . . . . ~}_{x}
$$

For (b), we may suppose that $K=\mathbb{R} \times\{(0,0)\}$ after applying an isometry. The proof is considerably more difficult than the one in (a) since an estimate of the form (B.1) is wrong in general and the object

$$
\begin{equation*}
r:=\left(\operatorname{diam}_{1}(E)\right)^{-1} \mathcal{H}^{2}\left(\partial^{*} E\right) \tag{B.2}
\end{equation*}
$$

might be much smaller than 1 . To this end, we will first need to construct a decomposition of $E$ into pieces with smaller diameter in $e_{1}$ direction (Step 1 ) which allows us to control the relation of perimeter and diam (see Step 2). Afterwards, a further tubular decomposition of each of these pieces is needed (Step 3). In Step 4 we will finally show that the constructed partition satisfies (7.7)-7.8). Throughout Steps 1-2 we will assume that $\operatorname{diam}_{1}(E)>2 \mathcal{H}^{2}\left(\partial^{*} E\right)^{\frac{1}{2}}$, so that in particular $\operatorname{diam}_{1}(E)>0$ and $\operatorname{diam}_{1}(E)>4 r$. If instead $\operatorname{diam}_{1}(E) \leq 2 \mathcal{H}^{2}\left(\partial^{*} E\right)^{\frac{1}{2}}$ holds, one can
directly skip to Step 3, consider a single $T_{1}=E$ in Step 3-4, and observe that in this case B.10 is clearly satisfied for $\theta \leq c_{\pi, 2}$, where this latter is the isoperimetric constant in the plane.
Step 1 (Cutting in $e_{1}$ direction): The goal of this step is to construct a decomposition of $E$ into pairwise disjoint sets $\left(T_{i}\right)_{i=1}^{I}$ of the form $T_{i}=E \cap\left(\left(t_{i-1}, t_{i}\right) \times \mathbb{R}^{2}\right), i=1, \ldots, I$, for suitable $t_{0}<t_{1}<\ldots<t_{I}$, which satisfy

$$
\begin{equation*}
\sum_{i=1}^{I} \mathcal{H}^{2}\left(\partial^{*} T_{i} \backslash \partial^{*} E\right) \leq c \theta \mathcal{H}^{2}\left(\partial^{*} E\right) \tag{B.3}
\end{equation*}
$$

for a universal constant $c>0$ and

$$
\begin{equation*}
\mathcal{H}^{2}\left(E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)>\theta \mathcal{H}^{2}\left(\partial^{*} E \cap\left(\left(t_{i-1}, t_{i}\right) \times \mathbb{R}^{2}\right)\right) \quad \text { for } \mathcal{H}^{1} \text {-a.e. } t_{i-1}+r \leq t \leq t_{i}-r . \tag{B.4}
\end{equation*}
$$

We point out that $\operatorname{diam}_{1}\left(T_{i}\right)=t_{i}-t_{i-1}<2 r$ is possible. In this case, condition (B.4) is trivial.
To achieve this, we perform an iterative decomposition of the set $E$. Choose the largest $t^{\prime} \in \mathbb{R}$ and the smallest $t^{\prime \prime}>t^{\prime}$ such that $E \subset\left(t^{\prime}, t^{\prime \prime}\right) \times \mathbb{R}^{2}$ up to a set of negligible $\mathcal{L}^{3}$-measure. We start to construct a first auxiliary decomposition $\left(S_{j}\right)_{j=1}^{J}$. We describe the first step of the construction of $\left(S_{j}\right)_{j=1}^{J}$ in detail: choose $s_{1} \in\left(t^{\prime}, t^{\prime \prime}\right]$ such that
(i) $\mathcal{H}^{2}\left(E \cap\left(\left\{s_{1}\right\} \times \mathbb{R}^{2}\right)\right) \leq 2 \theta \mathcal{H}^{2}\left(\partial^{*} E \cap\left(\left(t^{\prime}, s_{1}\right) \times \mathbb{R}^{2}\right)\right) \quad$ or $\quad s_{1}=t^{\prime \prime}$,
(ii) $\mathcal{H}^{2}\left(E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)>2 \theta \mathcal{H}^{2}\left(\partial^{*} E \cap\left(\left(t^{\prime}, t\right) \times \mathbb{R}^{2}\right)\right)$ for $\mathcal{H}^{1}$-a.e. $t^{\prime}+r \leq t \leq s_{1}-r$.

In fact, this is possible: let

$$
M=\left\{t \in\left(t^{\prime}+r, t^{\prime \prime}\right): \mathcal{H}^{2}\left(E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right) \leq 2 \theta \mathcal{H}^{2}\left(\partial^{*} E \cap\left(\left(t^{\prime}, t\right) \times \mathbb{R}^{2}\right)\right)\right\}
$$

If $M \neq \emptyset$, select $s_{1} \in M$ such that $\left(t^{\prime}+r, s_{1}-r\right) \cap M=\emptyset$. (This is indeed possible by choosing $s_{1} \in M \cap[\inf M, \inf M+r)$. As pointed out below (B.4), $s_{1}-t^{\prime}<2 r$ is admissible. In this case, the interval is empty and condition (B.5)(ii) is trivial.) If $M=\emptyset$, let $s_{1}=t^{\prime \prime}$. Define $S_{1}:=\left(\left(t^{\prime}, s_{1}\right) \times \mathbb{R}^{2}\right) \cap E$. Observe that this also implies $\operatorname{diam}_{1}\left(S_{1}\right) \geq r$.

We now proceed iteratively: suppose that $\left(S_{j}\right)_{j=1}^{k}$ have been defined and let $E_{k}=E \backslash \bigcup_{j=1}^{k} S_{j}$. As long as $\operatorname{diam}_{1}\left(E_{k}\right)>r$, we then repeat the above procedure for $E_{k}$ in place of $E$. Hereby, after a finite number of iterations, we obtain a decomposition $E=\bigcup_{j=1}^{J} S_{j}$, where $\operatorname{diam}_{1}\left(S_{j}\right) \geq r$ for all $j=1, \ldots, J-1$. (Note that the control from below by $r$ on $\operatorname{diam}_{1}$ ensures that the iteration procedure stops after a finite number of steps.) Setting $s_{0}=t^{\prime}$ and $s_{J}=t^{\prime \prime}$ for convenience, we find by B.5)(ii)

$$
\begin{equation*}
\mathcal{H}^{2}\left(E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)>2 \theta \mathcal{H}^{2}\left(\partial^{*} E \cap\left(\left(s_{j-1}, t\right) \times \mathbb{R}^{2}\right)\right) \quad \text { for } \mathcal{H}^{1} \text {-a.e. } s_{j-1}+r \leq t \leq s_{j}-r \tag{B.6}
\end{equation*}
$$

for all $j=1, \ldots, J$. Moreover, by using B.5)(i) (with $s_{j-1}$ and $s_{j}$ in place of $t^{\prime}$ and $s_{1}$ ) we get

$$
\begin{align*}
\sum_{j=1}^{J} \mathcal{H}^{2}\left(\partial^{*} S_{j} \backslash \partial^{*} E\right) & \leq 2 \sum_{j=1}^{J-1} \mathcal{H}^{2}\left(E \cap\left(\left\{s_{j}\right\} \times \mathbb{R}^{2}\right)\right) \\
& \leq 4 \theta \sum_{j=1}^{J-1} \mathcal{H}^{2}\left(\partial^{*} E \cap\left(\left(s_{j-1}, s_{j}\right) \times \mathbb{R}^{2}\right)\right) \leq 4 \theta \mathcal{H}^{2}\left(\partial^{*} E\right) \tag{B.7}
\end{align*}
$$

We now repeat the above procedure for each $S_{j}$ in place of $E$ starting from the right instead of from the left: the first set in the decomposition of each $S_{j}$ is obtained by choosing $s_{j}^{1} \in\left[s_{j-1}, s_{j}\right)$ such that
(i) $\mathcal{H}^{2}\left(S_{j} \cap\left(\left\{s_{j}^{1}\right\} \times \mathbb{R}^{2}\right)\right) \leq 2 \theta \mathcal{H}^{2}\left(\partial^{*} S_{j} \cap\left(\left(s_{j}^{1}, s_{j}\right) \times \mathbb{R}^{2}\right)\right) \quad$ or $\quad s_{j}^{1}=s_{j-1}$,
(ii) $\mathcal{H}^{2}\left(S_{j} \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)>2 \theta \mathcal{H}^{2}\left(\partial^{*} S_{j} \cap\left(\left(t, s_{j}\right) \times \mathbb{R}^{2}\right)\right)$ for $\mathcal{H}^{1}$-a.e. $s_{j}^{1}+r \leq t \leq s_{j}-r$.

We set $S_{j}^{1}:=\left(s_{j}^{1}, s_{j}\right) \cap S_{j}=\left(s_{j}^{1}, s_{j}\right) \cap E$ and proceed iteratively as before to define sets $\left(S_{j}^{k}\right)_{k \geq 1}$ of the form $S_{j}^{k}=\left(\left(s_{j}^{k+1}, s_{j}^{k}\right) \times \mathbb{R}^{2}\right) \cap E$.

For convenience, we denote the decomposition $\left(S_{j}^{k}\right)_{j, k}$ of $E$ by $\left(T_{i}\right)_{i=1}^{I}$ and observe that there exist $t^{\prime}=t_{0}<t_{1}<\ldots<t_{I}=t^{\prime \prime}$ such that $T_{i}=E \cap\left(\left(t_{i-1}, t_{i}\right) \times \mathbb{R}^{2}\right)$ for all $i=1, \ldots, I$.

We show (B.4): first, by (B.6) and the fact that $\left(s_{j}^{k+1}, t\right) \subset\left(s_{j-1}, t\right)$ for all $s_{j}^{k+1}+r \leq t \leq s_{j}^{k}-r$ we get

$$
\mathcal{H}^{2}\left(E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)>2 \theta \mathcal{H}^{2}\left(\partial^{*} E \cap\left(\left(t_{i-1}, t\right) \times \mathbb{R}^{2}\right)\right) \quad \text { for } \mathcal{H}^{1} \text {-a.e. } t_{i-1}+r \leq t \leq t_{i}-r
$$

The fact that in B .8 (ii) we may replace $S_{j}$ by $E$ without changing the estimate yields

$$
\mathcal{H}^{2}\left(E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)>2 \theta \mathcal{H}^{2}\left(\partial^{*} E \cap\left(\left(t, t_{i}\right) \times \mathbb{R}^{2}\right)\right) \quad \text { for } \mathcal{H}^{1} \text {-a.e. } t_{i-1}+r \leq t \leq t_{i}-r
$$

Combining the previous two estimates and using that $\mathcal{H}^{2}\left(\partial^{*} E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)=0$ for $\mathcal{H}^{1}$-a.e. $t$, we get (B.4). Moreover, repeating the argument (B.7) we derive

$$
\begin{equation*}
\sum_{k \geq 1} \mathcal{H}^{2}\left(\partial^{*} S_{j}^{k} \backslash \partial^{*} S_{j}\right) \leq 4 \theta \mathcal{H}^{2}\left(\partial^{*} S_{j}\right) \tag{B.9}
\end{equation*}
$$

for all $j=1, \ldots, J$. Then from (B.7) and B.9 we obtain

$$
\begin{aligned}
\sum_{i=1}^{I} \mathcal{H}^{2}\left(\partial^{*} T_{i} \backslash \partial^{*} E\right) & \leq \sum_{j=1}^{J} \mathcal{H}^{2}\left(\partial^{*} S_{j} \backslash \partial^{*} E\right)+\sum_{j=1}^{J} \sum_{k \geq 1} \mathcal{H}^{2}\left(\partial^{*} S_{j}^{k} \backslash \partial^{*} S_{j}\right) \\
& \leq 4 \theta\left(\mathcal{H}^{2}\left(\partial^{*} E\right)+\sum_{j=1}^{J} \mathcal{H}^{2}\left(\partial^{*} S_{j}\right)\right) \leq 4 \theta\left(\mathcal{H}^{2}\left(\partial^{*} E\right)+2 \mathcal{H}^{2}\left(\bigcup_{j=1}^{J} \partial^{*} S_{j}\right)\right) \\
& \leq 12 \theta \mathcal{H}^{2}\left(\partial^{*} E\right)+8 \theta \sum_{j=1}^{J} \mathcal{H}^{2}\left(\partial^{*} S_{j} \backslash \partial^{*} E\right) \leq\left(12 \theta+32 \theta^{2}\right) \mathcal{H}^{2}\left(\partial^{*} E\right)
\end{aligned}
$$

where we also used that each $x \in \mathbb{R}^{3}$ lies in at most two different $\partial^{*} S_{j}$. This yields (B.3).
Step 2 (Relation of $\operatorname{diam}_{1}$ and perimeter): We now prove a fundamental diam ${ }_{1}$-perimeter-relation of the sets $\left(T_{i}\right)_{i=1}^{I}$ which have been constructed in Step 1: each $T_{i}$ with $\operatorname{diam}_{1}\left(T_{i}\right) \geq 4 r$ satisfies

$$
\begin{equation*}
\operatorname{diam}_{1}\left(T_{i}\right) \leq 2 \sqrt{c_{\pi, 2} \sigma_{i} / \theta} \tag{B.10}
\end{equation*}
$$

where $c_{\pi, 2}$ denotes the isoperimetric constant in dimension two and for brevity we use the notation

$$
\begin{equation*}
\sigma_{i}:=\mathcal{H}^{2}\left(\partial^{*} E \cap\left(\left(t_{i-1}, t_{i}\right) \times \mathbb{R}^{2}\right)\right) \tag{B.11}
\end{equation*}
$$

We prove (B.10). Since we are assuming $\operatorname{diam}_{1}\left(T_{i}\right) \geq 4 r$, B.4 is nontrivial and yields

$$
\theta \sigma_{i}<\mathcal{H}^{2}\left(E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)
$$

for $\mathcal{H}^{1}$-a.e. $t_{i-1}+r \leq t \leq t_{i}-r$. Thus, the isoperimetric inequality in dimension two applied on the sets $E \cap\left(\{t\} \times \mathbb{R}^{2}\right)$ implies for $\mathcal{H}^{1}$-a.e. $t_{i-1}+r \leq t \leq t_{i}-r$ that

$$
\theta \sigma_{i} \leq c_{\pi, 2}\left(\mathcal{H}^{1}\left(\partial^{*}\left(E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)\right)\right)^{2}
$$

We recall that the coarea formula on rectifiable sets (see, e.g., [52, Theorem 18.8 and Formula (18.25)]) gives, for all $a, b \in \mathbb{R}$, that

$$
\mathcal{H}^{2}\left(\partial^{*} E \cap\left((a, b) \times \mathbb{R}^{2}\right)\right) \geq \int_{a}^{b} \mathcal{H}^{1}\left(\partial^{*} E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right) \mathrm{d} t=\int_{a}^{b} \mathcal{H}^{1}\left(\partial^{*}\left(E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)\right) \mathrm{d} t
$$

where the last equality is proved, for instance, in [52, Theorem 18.11]. With this, by using $t_{i}-$ $t_{i-1}-2 r=\operatorname{diam}_{1}\left(T_{i}\right)-2 r \geq \operatorname{diam}_{1}\left(T_{i}\right) / 2$ and by integrating from $t_{i-1}+r$ to $t_{i}-r$ we find

$$
\frac{1}{2} \operatorname{diam}_{1}\left(T_{i}\right) \sqrt{\theta \sigma_{i}} \leq\left(t_{i}-t_{i-1}-2 r\right) \sqrt{\theta \sigma_{i}} \leq \sqrt{c_{\pi, 2}} \int_{t_{i-1}+r}^{t_{i}-r} \mathcal{H}^{1}\left(\partial^{*}\left(E \cap\left(\{t\} \times \mathbb{R}^{2}\right)\right)\right) d t \leq \sqrt{c_{\pi, 2}} \sigma_{i}
$$

where the last step follows from the shorthand (B.11). This yields B.10) and concludes the proof of this step.

Step 3 (Tubular covering of each $T_{i}$ ): Consider $T_{i}=\left(\left(t_{i-1}, t_{i}\right) \times \mathbb{R}^{2}\right) \cap E$. For notational convenience, we will often not add indices $i$, even if the following objects depend on $i$. We set $w_{j}=j \theta^{-1}\left(\mathcal{H}^{2}\left(\partial^{*} T_{i}\right)\right)^{1 / 2}$ for all $j \in \mathbb{N}$. We introduce the function $f: \mathbb{R}^{3} \rightarrow \mathbb{R}$ defined by $f(x)=\operatorname{dist}\left(x, \mathbb{R} e_{1}\right)=\sqrt{\left|x_{2}\right|^{2}+\left|x_{3}\right|^{2}}$ for $x \in \mathbb{R}^{3}$. We now decompose $T_{i}$ into sublevel sets of the function $f$ : define $z_{0}=\theta^{2}\left(\mathcal{H}^{2}\left(\partial^{*} T_{i}\right)\right)^{1 / 2}$ and choose $z_{j} \in\left(w_{j}, w_{j+1}\right)$ for $j \in \mathbb{N}$ such that

$$
\begin{equation*}
\mathcal{H}^{2}\left(\left\{f=z_{j}\right\} \cap T_{i}\right) \leq \frac{1}{w_{j+1}-w_{j}} \int_{w_{j}}^{w_{j+1}} \mathcal{H}^{2}\left(\{f=z\} \cap T_{i}\right) \mathrm{d} z=\frac{1}{w_{1}} \int_{w_{j}}^{w_{j+1}} \mathcal{H}^{2}\left(\{f=z\} \cap T_{i}\right) \mathrm{d} z \tag{B.12}
\end{equation*}
$$

where the last step follows from the definition of $w_{j}$.
We define a covering of $T_{i}$ by setting $U_{0}^{i}:=\left(\left(t_{i-1}, t_{i}\right) \times \mathbb{R}^{2}\right) \cap\left\{f \leq z_{0}\right\}$ and $U_{j}^{i}:=T_{i} \cap\left\{z_{j-1}<\right.$ $\left.f \leq z_{j}\right\}$ for $j \geq 1$. We observe that this decomposition is finite since $E$ (and thus $T_{i}$ ) is a bounded set in $\mathbb{R}^{3}$. For later purposes, we observe that

$$
\begin{equation*}
\inf _{x \in U_{1}^{i}} f(x) \geq z_{0}=\theta^{3} w_{1}=\frac{1}{2} \theta^{3} w_{2} \geq \frac{1}{2} \theta^{3} z_{1} \geq \frac{1}{2} \theta^{3} \sup _{x \in U_{1}^{i}} f(x) \tag{B.13}
\end{equation*}
$$

and in a similar fashion, for all $j \geq 2$,

$$
\begin{equation*}
\inf _{x \in U_{j}^{i}} f(x) \geq z_{j-1} \geq w_{j-1}=\frac{j-1}{j+1} w_{j+1} \geq \frac{1}{3} z_{j} \geq \frac{1}{3} \sup _{x \in U_{j}^{i}} f(x) \tag{B.14}
\end{equation*}
$$

(Clearly, the above property is false for $U_{0}^{i}$.) We now estimate the perimeter of the sets $\left(U_{j}^{i}\right)_{j \geq 0}$. First, observe that by construction we clearly have $\sigma_{i} \leq \mathcal{H}^{2}\left(\partial^{*} T_{i}\right)$, where $\sigma_{i}$ was defined in B.11. Moreover, by B.10. we get $\operatorname{diam}_{1}\left(T_{i}\right) \leq 2 \sqrt{c_{\pi, 2} \sigma_{i} / \theta}$ if $\operatorname{diam}_{1}\left(T_{i}\right) \geq 4 r$ and $\operatorname{diam}_{1}\left(T_{i}\right) \leq$ $2 \sqrt{r}\left(\operatorname{diam}_{1}\left(T_{i}\right)\right)^{1 / 2}$ otherwise. To summarize both cases, by recalling the previous observation, we can write

$$
\operatorname{diam}_{1}\left(T_{i}\right) \leq 2 \sqrt{c_{\pi, 2} / \theta} \mathcal{H}^{2}\left(\partial^{*} T_{i}\right)^{\frac{1}{2}}+2 \sqrt{r}\left(\operatorname{diam}_{1}\left(T_{i}\right)\right)^{1 / 2}
$$

Thus, recalling $z_{0}=\theta^{2}\left(\mathcal{H}^{2}\left(\partial^{*} T_{i}\right)\right)^{1 / 2}$ we can estimate the perimeter of the cylinder $U_{0}^{i}$ by

$$
\begin{align*}
\mathcal{H}^{2}\left(\partial^{*} U_{0}^{i}\right) & =2 \cdot \pi z_{0}^{2}+2 \pi z_{0} \operatorname{diam}_{1}\left(T_{i}\right) \leq c \theta^{4} \mathcal{H}^{2}\left(\partial^{*} T_{i}\right)+c \theta^{2}\left(\mathcal{H}^{2}\left(\partial^{*} T_{i}\right)\right)^{1 / 2} \operatorname{diam}_{1}\left(T_{i}\right) \\
& \leq c \theta \mathcal{H}^{2}\left(\partial^{*} T_{i}\right)+c \theta\left(\mathcal{H}^{2}\left(\partial^{*} T_{i}\right)\right)^{1 / 2} \sqrt{r}\left(\operatorname{diam}_{1}\left(T_{i}\right)\right)^{1 / 2} \tag{B.15}
\end{align*}
$$

where in the last step we suitably enlarged the absolute constant $c$ and also used $\theta^{m} \leq \theta$ for $m \geq 1$. By using (B.12) and the coarea formula we get

$$
\sum_{j \geq 1} \mathcal{H}^{2}\left(\partial^{*} U_{j}^{i} \backslash \partial^{*} T_{i}\right) \leq 2 \sum_{j \geq 1} \mathcal{H}^{2}\left(\left\{f=z_{j}\right\} \cap T_{i}\right) \leq \frac{2}{w_{1}} \int_{0}^{\infty} \mathcal{H}^{2}\left(\{f=z\} \cap T_{i}\right) \mathrm{d} z=\frac{2}{w_{1}} \mathcal{L}^{3}\left(T_{i}\right)
$$

since $|\nabla f|=1$ a.e. in $\mathbb{R}^{3}$. Then the isoperimetric inequality in dimension three applied on the set $T_{i}$ yields

$$
\begin{equation*}
\sum_{j \geq 1} \mathcal{H}^{2}\left(\partial^{*} U_{j}^{i} \backslash \partial^{*} T_{i}\right) \leq \frac{2 c_{\pi, 3}}{w_{1}}\left(\mathcal{H}^{2}\left(\partial^{*} T_{i}\right)\right)^{3 / 2} \leq 2 c_{\pi, 3} \theta \mathcal{H}^{2}\left(\partial^{*} T_{i}\right) \tag{B.16}
\end{equation*}
$$

where $c_{\pi, 3}$ denotes the isoperimetric constant in dimension three. Here, in the last step we used the definition $w_{1}=\theta^{-1}\left(\mathcal{H}^{2}\left(\partial^{*} T_{i}\right)\right)^{1 / 2}$.
Step 4 (Conclusion): We are now in a position to define the covering of $E$ and to confirm (7.7)7.8). Define $R=\bigcup_{i=1}^{I} U_{0}^{i}$ and let $\left(D_{j}\right)_{j=1}^{J}$ be the partition of $E \backslash R$ consisting of the sets $\left\{U_{j}^{i}\right.$ : $i=1, \ldots, I, j \geq 1\}$ constructed in Step 3. Then (7.8) follows directly from (B.13)-(B.14). To see
(7.7), we first recall $\sum_{i=1}^{I} \mathcal{H}^{2}\left(\partial^{*} T_{i}\right) \leq c \mathcal{H}^{2}\left(\partial^{*} E\right)$ by B.3) and that $\sum_{i=1}^{I} \operatorname{diam}_{1}\left(T_{i}\right)=\operatorname{diam}_{1}(E)$. We compute by B.15 and Hölder's inequality

$$
\begin{aligned}
\mathcal{H}^{2}\left(\partial^{*} R\right) & \leq \sum_{i=1}^{I} \mathcal{H}^{2}\left(\partial^{*} U_{0}^{i}\right) \leq c \theta \sum_{i=1}^{I} \mathcal{H}^{2}\left(\partial^{*} T_{i}\right)+c \theta \sqrt{r} \sum_{i=1}^{I}\left(\mathcal{H}^{2}\left(\partial^{*} T_{i}\right)\right)^{1 / 2}\left(\operatorname{diam}_{1}\left(T_{i}\right)\right)^{1 / 2} \\
& \leq c \theta \mathcal{H}^{2}\left(\partial^{*} E\right)+c \theta \sqrt{r}\left(\operatorname{diam}_{1}(E)\right)^{1 / 2}\left(\mathcal{H}^{2}\left(\partial^{*} E\right)\right)^{1 / 2} \leq c \theta \mathcal{H}^{2}\left(\partial^{*} E\right)
\end{aligned}
$$

where the last step follows from the definition of $r$ in (B.2). In a similar fashion, by using B.3) and $(\overline{\mathrm{B} .16})$ we get

$$
\begin{aligned}
\sum_{j=1}^{J} \mathcal{H}^{2}\left(\partial^{*} D_{j} \backslash \partial^{*} E\right) & \leq \sum_{i=1}^{I} \sum_{j \geq 1} \mathcal{H}^{2}\left(\partial^{*} U_{j}^{i} \backslash \partial^{*} T_{i}\right)+\sum_{i=1}^{I} \mathcal{H}^{2}\left(\partial^{*} T_{i} \backslash \partial^{*} E\right) \\
& \leq c \theta \sum_{i=1}^{I} \mathcal{H}^{2}\left(\partial^{*} T_{i}\right)+c \theta \mathcal{H}^{2}\left(\partial^{*} E\right) \leq c \theta \mathcal{H}^{2}\left(\partial^{*} E\right)
\end{aligned}
$$

The previous two estimates show (7.7) and conclude the proof. (Clearly, the constant can be absorbed in $\theta$ by repeating the above arguments for $\theta / c$ in place of $\theta$.)

## References

[1] R. Alicandro, A. Braides, M. Cicalese. Phase and anti-phase boundaries in binary discrete systems: a variational viewpoint. Netw. Heterog. Media 1 (2006), 85-107.
[2] R. Alicandro, M. Cicalese, M. Ruf. Domain formation inmagnetic polymer composites: an approach via stochastic homogenization. Arch. Ration. Mech. Anal. 218 (2015), 945-984.
[3] F.J. Almgren. Existence and regularity almost everywhere of solutions to elliptic variational problems with constraints. Mem. Am. Math. Soc. 165 (1976).
[4] L. Ambrosio. Existence theory for a new class of variational problems. Arch. Ration. Mech. Anal. 111 (1990), 291-322.
[5] L. Ambrosio. On the lower semicontinuity of quasi-convex integrals in $S B V\left(\Omega ; \mathbb{R}^{k}\right)$. Nonlinear Anal. 23 (1994), 405-425.
[6] L. Ambrosio, A. Braides. Functionals defined on partitions of sets of finite perimeter, I: integral representation and $\Gamma$-convergence. J. Math. Pures Appl. 69 (1990), 285-305.
[7] L. Ambrosio, A. Braides. Functionals defined on partitions of sets of finite perimeter, II: semicontinuity, relaxation and homogenization. J. Math. Pures Appl. 69 (1990), 307-333.
[8] L. Ambrosio, A. Braides. Energies in SBV and variational models in fracture mechanics. In: Homogenization and Applications to Material Sciences, Nice, 1995. GAKUTO Internat. Ser. Math. Sci. Appl., vol. 9, 1-22, Tokyo, 1995.
[9] L. Ambrosio, V. Caselles, S. Masnou, J. Morel. Connected components of sets of finite perimeter and applications to image processing. J. Eur. Math. Soc. (JEMS) 3 (2001), 39-92.
[10] L. Ambrosio, A. Coscia, G. Dal Maso. Fine properties of functions with bounded deformation. Arch. Ration. Mech. Anal. 139 (1997), 201-238.
[11] L. Ambrosio, N. Fusco, D. Pallara. Functions of bounded variation and free discontinuity problems. Oxford University Press, Oxford 2000.
[12] A. Bach, A. Braides, C. I. Zeppieri. Quantitative analysis of finite-difference approximations of freediscontinuity problems. Preprint, 2018. Available at: arXiv:1807.05346.
[13] S. Baldo. Minimal interface criterion for phase transitions in mixtures of Cahn-Hilliard fluids. Ann. Inst. H. Poincaré Anal. Non Linéaire 7 (1990), 67-90 .
[14] J. Ball, R.D. James. Fine phase mixtures as minimizers of the energy. Arch. Ration. Mech. Anal. 100 (1987), 13-52.
[15] A. Braides, S. Conti, A. Garroni. Density of polyhedral partitions. Calc. Var. PDE 56 (2017), art. 28.
[16] G. Bellettini, A. Coscia. Discrete approximation of a free discontinuity problem. Numer. Funct. Anal. Optim. 15 (1994), 201-224.
[17] G. Bouchitté, I. Fonseca, G. Leoni, L. Mascarenhas. A global method for relaxation in $W^{1, p}$ and in $S B V_{p}$. Arch. Ration. Mech. Anal. 165 (2002), 187-242.
[18] G. Bouchitté, I. Fonseca, L. Mascarenhas. A global method for relaxation. Arch. Ration. Mech. Anal. 145 (1998), 51-98.
[19] A. Braides. Approximation of Free-Discontinuity Problems. Springer, Berlin 1998.
[20] A. Braides, V. Chiadò Piat. Integral representation results for functionals defined in $S B V\left(\Omega ; \mathbb{R}^{m}\right)$. J. Math. Pures Appl. 75 (1996), 595-626.
[21] A. Braides, M. Cicalese. Interfaces, modulated phases and textures in lattice systems. Arch. Ration. Mech. Anal. 223 (2017), 977-1017.
[22] A. Braides, A. Defranceschi. Homogenization of multiple integrals. Oxford University Press, New York 1998.
[23] A. Braides, A. Defranceschi, E. Vitali. Homogenization of free discontinuity problems. Arch. Ration. Mech. Anal. 135 (1996), 297-356.
[24] G. Buttazzo, G. Dal Maso. A characterization of nonlinear functionals on Sobolev spaces which admit an integral representation with a Carathéodory integrand. J. Math. Pures Appl. 64 (1985), 337-361.
[25] F. Cagnetti, G. Dal Maso, L. Scardia, C. I. Zeppieri. Г-convergence of free-discontinuity problems. Ann. Inst. H. Poincaré Anal. Non Linéaire, to appear. Available at: http://cvgmt.sns.it/paper/3371/.
[26] F. Cagnetti, G. Dal Maso, L. Scardia, C. I. Zeppieri. Stochastic Homogenisation of Free-Discontinuity Problems. Preprint, 2017. Available at: http://cvgmt.sns.it/paper/3708/.
[27] D. G. Caraballo. Crystals and polycrystals in $\mathbb{R}^{n}$ : lower semicontinuity and existence. J. Geom. Anal. 18 (2008), 68-88.
[28] D. G. Caraballo. The triangle inequalities and lower semi-continuity of surface energy of partitions. Proc. Roy. Soc. Edinburgh Sect. A 139 (2009), 449-457.
[29] D. G. Caraballo. BV-ellipticity and lower semicontinuity of surface energy of Caccioppoli partitions of $\mathbb{R}^{n}$. J. Geom. Anal. 23 (2013), 202-220.
[30] A. Chambolle, S. Conti, G. Francfort. Korn-Poincaré inequalities for functions with a small jump set. Indiana Univ. Math. J. 65 (2016), 1373-1399.
[31] A. Chambolle, S. Conti, F. Iurlano. Approximation of functions with small jump sets and existence of strong minimizers of Griffith's energy. J. Math. Pures Appl., to appear. Available at: arXiv:1710.01929.
[32] A. Chambolle, V. Crismale. A density result in $G S B D^{p}$ with applications to the approximation of brittle fracture energies. Arch. Ration. Mech. Anal. 232 (2019), 1329-1378.
[33] A. Chambolle, V. Crismale. Compactness and lower semicontinuity in GSBD. J. Eur. Math. Soc. (JEMS), to appear. Available at: http://cvgmt.sns.it/paper/3767/
[34] S. Conti, M. Focardi, F. Iurlano. Which special functions of bounded deformation have bounded variation? Proc. Roy. Soc. Edinb. A. 148 (2018), 33-50.
[35] S. Conti, M. Focardi, F. Iurlano. Integral representation for functionals defined on $S B D^{p}$ in dimension two Arch. Ration. Mech. Anal. 223 (2017), 1337-1374.
[36] A. Chambolle, A. Giacomini, M. Ponsiglione. Piecewise rigidity. J. Funct. Anal. 244 (2007), 134-153.
[37] G. Dal Maso. An introduction to $\Gamma$-convergence. Birkhäuser, Boston • Basel • Berlin 1993.
[38] G. Dal Maso. Generalised functions of bounded deformation. J. Eur. Math. Soc. (JEMS) 15 (2013), $1943-1997$.
[39] E. De Giorgi, L. Ambrosio. Un nuovo funzionale del calcolo delle variazioni. Acc. Naz. Lincei, Rend. Cl. Sci. Fis. Mat. Natur. 82 (1988), 199-210.
[40] L. De Luca, M. Novaga, M. Ponsiglione. $\Gamma$-convergence of the Heitmann-Radin sticky disc energy to the crystalline perimeter. J. Nonlinear Sci. (2018). https://doi.org/10.1007/s00332-018-9517-3.
[41] J. L. Ericksen. Equilibrium theory of liquid crystals. Adv. in liquid crystals 2, Academic Press, 1976.
[42] L. C Evans, R. F. Gariepy. Measure theory and fine properties of functions (Revised Version). CRC Press, Boca Raton 2015.
[43] H. Federer. Geometric measure theory. Springer, Berlin, 1969.
[44] I. Fonseca, G. Leoni. Modern Methods in the Calculus of Variations: L ${ }^{p}$ Spaces. Springer Monographs in Mathematics. Springer, New York, 2007.
[45] G. A. Francfort, C. J. Larsen. Existence and convergence for quasi-static evolution in brittle fracture. Comm. Pure Appl. Math. 56 (2003), 1465-1500.
[46] M. Friedrich. A derivation of linearized Griffith energies from nonlinear models. Arch. Ration. Mech. Anal. 225 (2017), 425-467.
[47] M. Friedrich. A Korn-type inequality in SBD for functions with small jump sets. Math. Models Methods Appl. Sci. 27 (2017), 2461-2484.
[48] M. Friedrich. A piecewise Korn inequality in SBD and applications to embedding and density results. SIAM J. Math. Anal. 50 (2018), 3842-3918.
[49] M. Friedrich. A compactness result in $G S B V^{p}$ and applications to $\Gamma$-convergence for free discontinuity problems. Calc. Var. PDE, to appear. Available at: arXiv:1807.03647.
[50] M. Friedrich, F. Solombrino. Quasistatic crack growth in $2 d$-linearized elasticity. Ann. Inst. H. Poincaré Anal. Non Linéaire 35 (2018), 27-64.
[51] A. Giacomini, M. Ponsiglione. A $\Gamma$-convergence approach to stability of unilateral minimality properties. Arch. Ration. Mech. Anal. 180 (2006), 399-447.
[52] F. Maggi. Sets of Finite Perimeter and Geometric Variational Problems: An Introduction to Geometric Measure Theory. Cambridge Studies in Advanced Mathematics No. 135. Cambridge University Press, Cambridge 2012.
[53] L. Modica. The gradient theory of phase transitions and the minimal interface criterion. Arch. Ration. Mech. Anal. 98 (1987), 123-142.
[54] F. Morgan. Immiscible fluid clusters in $\mathbb{R}^{2}$ and $\mathbb{R}^{3}$. Mich. Math. J. 45 (1998), 441-450.
[55] D. Mumford, J. Shah. Optimal approximation by piecewise smooth functions and associated variational problems. Comm. Pure Appl. Math. 17 (1989), 577-685.
[56] M. Ruf. On the continuity of functionals defined on partitions. Adv. Calc. Var. 11 (2017), 335-339.
[57] M. RuF. Discrete stochastic approximations of the Mumford-Shah functional. Ann. Inst. H. Poincaré Anal. Non Linéaire, in press.
(Manuel Friedrich) Applied Mathematics, Universität Münster, Einsteinstr. 62, D-48149 Münster, GerMANY

Email address: manuel.friedrich@uni-muenster.de
URL: https://www.uni-muenster.de/AMM/Friedrich/index.shtml
(Francesco Solombrino) Dip. Mat. Appl. "Renato Caccioppoli", Univ. Napoli "Federico II", Via Cintia, Monte S. Angelo 80126 Napoli, Italy

Email address: francesco.solombrino@unina.it
URL: http://www.docenti.unina.it/francesco.solombrino


[^0]:    2010 Mathematics Subject Classification. 49J45, 49Q20, 70G75, 74R10.
    Key words and phrases. Piecewise rigid functions, free-discontinuity problems, integral representation, $\Gamma$ convergence, fundamental estimates, fracture mechanics, polycrystals.

