# About the regularity of average distance minimizers in $\mathbb{R}^{2}$. 

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#### Abstract

We focus on the following irrigation problem introduced in [3] $$
\min \mathcal{F}(\Sigma):=\int_{\Omega} \operatorname{dist}(x, \Sigma) \mathrm{d} \mu(x)
$$ where $\Omega$ is an open subset of $\mathbb{R}^{2}, \mu$ is a probability measure and where the minimum is taken over all the sets $\Sigma \subset \Omega$ such that $\Sigma$ is compact, connected, and $\mathcal{H}^{1}(\Sigma) \leq \alpha_{0}$ for a given positive constant $\alpha_{0}$. In this paper we seek for some conditions to find in $\Sigma$ some pieces of $C^{1}$ (or more) regular curves. We prove that it is the case in the ball $B$ when $\Sigma \cap B$ contains no corner points. More generally we prove that the Left and Right tangents half lines of $\Sigma$ (that exist everywhere out of endpoints and triple points) are semicontinuous. We also discuss how the regularity is linked with the pull back measure $\psi:=k \sharp \mu$ where $k$ is the projection on $\Sigma$. In particular $\Sigma \cap B$ is $C^{1, \alpha}$ when $\psi$ is regular with respect to $\mathcal{H}^{1}$ with density in a certain $L^{p}$. We also prove that $\Sigma$ is locally a Lipschitz graph away from triple points and endpoints, and that the mean curvature of $\Sigma$ is a measure that is explicited in terms of measure $\psi$.


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## 1 Introduction

Let $\Omega \subset \mathbb{R}^{2}$ be a bounded open set, $\alpha_{0}>0$ a fixed constant, and $\mu$ a given probability measure on $\Omega$. In this paper we study the regularity of the following minimization problem

$$
\begin{equation*}
\min _{\Sigma \in \mathcal{A}} \mathcal{F}(\Sigma):=\int_{\Omega} \operatorname{dist}(x, \Sigma) \mathrm{d} \mu(x) \tag{1.1}
\end{equation*}
$$

where the minimum is taken over the family $\mathcal{A}$ of all the compact and connected sets $\Sigma \subset \Omega$ satisfying the length constraint $\mathcal{H}^{1}(\Sigma) \leq \alpha_{0}$. This problem also known as the "irrigation problem", was introduced by G. Buttazzo, E. Oudet and E. Stepanov in [3] and then in [5] in a more general formulation in terms of optimal mass transport problem with "free Dirichlet regions". In the sequel we will call $\Sigma$ an optimal set for the problem (1.1).

An easy interpretation of the Problem (1.1) is the following. One could consider $\Sigma$ as being a ressource of limited length (for instance some water in pipes) that one wants to place in the domain $\Omega$ in such a way that the average cost for people living in $\Omega$ to reach the resource $\Sigma$ is minimal, according to the density of population given by the measure $\mu$. We refer to $[3-5,9,11]$ for some more detailed interpretations of Problem (1.1).

In [5], the topological description of minimizers is studied and it has been proved in particular that $\Sigma$ has no loops and is a finite union of Lipschitz arcs, that meet by number of three at some finite number of triple junctions. Concerning the regularity, it is only proved in [5] that $\Sigma$ is Ahlfors-Regular.

Then in [10], F. Santambrogio and P. Tilli restrict themselves to the simpler formulation (1.1), which in the end is not so restrictive according to some later results [11], and they characterize the blow up limits of the minimal set $\Sigma$ in order to prove some regularity. They prove that any blow up sequence of the minimal set $\Sigma_{r}:=\frac{1}{r}(\Sigma \cap B(x, r)-x)$ converges in $B(0,1)$ when $r \rightarrow 0$, and the limit could be either a radius ( $x$ is an endpoint), a diameter ( $x$ is ordinary point), three radius making angles of 120 degrees ( $x$ is a triple junction), or two radius making an angle different from 180 degrees ( $x$ is a corner point).
F. Santambrogio and P. Tilli [10] also found a sufficient condition for having $C^{1,1}$ regularity in a neighborhood of a point $x \in \Sigma$, involving the diameter of the set of points that are projected on $\Sigma \cap B(x, r)$. Since this condition is satisfied in a small enough neighborhood of any triple point, they obtain that any triple point admits a small neighborhood in which the three pieces of curve of $\Sigma$ are $C^{1,1}$.

Very recently, P. Tilli [12] proved that for any $C^{1,1}$ simple curve $\Sigma$ of length less than $\pi$ times the inverse of the infimum of its curvature, one can find an open set $\Omega$ containing $\Sigma$ in such a way that $\Sigma$ is a minimizer for the problem (1.1) in $\Omega$ with $\mu$ equals to the Lebesgue measure. This fact implies that no further regularity is possible for $\Sigma$ and that $C^{1,1}$ is optimal.

Recall that by "corner point" we mean a point in $\Sigma$ for which the blow up limit is a union of two radius with a strict angle (different from 180 degrees). Although it is not difficult to find some examples of domains $\Omega$ where any minimizer $\Sigma$ necessarily contains a triple point, it remains an open question as to whether a minimizer could actually contain corner points. On the other hand in [2], the first order Euler-Lagrange equation is computed (see Section 5 below) and the existence of stationary sets $\Sigma$ that contain corner points is shown.

Now let us describe the contributions of this paper. One of our main result is that away from triple points, $\Sigma$ is locally at least as regular as the graph of a convex fonction, namely that the Right and Left tangent maps admit some Right and Left limits at every point and are semicontinuous. More precisely, for a given parametrization $\gamma$ of an injective Lipschitz $\operatorname{arc} \Gamma \subset \Sigma$, by existence of
blow up limits one can define the Left and Right tangent half-lines at every point $x \in \Gamma$ by

$$
\begin{aligned}
& T_{R}(x):=x+\mathbb{R}^{+} \cdot \lim _{h \rightarrow 0} \frac{\gamma\left(t_{0}+h\right)-\gamma\left(t_{0}\right)}{h} \\
& T_{L}(x):=x+\mathbb{R}^{+} \cdot \lim _{h \rightarrow 0} \frac{\gamma\left(t_{0}-h\right)-\gamma\left(t_{0}\right)}{h}
\end{aligned}
$$

Then we have the following.
Theorem 1. Let $\Gamma \subset \Sigma$ be an open injective Lipschitz arc. Then the Right and Left tangent maps $x \mapsto T_{R}(x)$ and $x \mapsto T_{L}(x)$ are semicontinuous, i.e. for every $y_{0} \in \Gamma$,

$$
\lim _{\substack{y \rightarrow y_{0} \\ y<\gamma y_{0}}} T_{L}(y)=T_{L}\left(y_{0}\right) \quad \text { and } \quad \lim _{\substack{y \rightarrow y_{0} \\ y>\gamma y_{0}}} T_{R}(y)=T_{R}\left(y_{0}\right) .
$$

In addition the limit from the other side exists and we have

$$
\lim _{\substack{y \rightarrow y_{0} \\ y>\gamma y_{0}}} T_{L}(y)=T_{R}\left(y_{0}\right) \quad \text { and } \quad \lim _{\substack{y \rightarrow y_{0} \\ y<\gamma y_{0}}} T_{R}(y)=T_{L}\left(y_{0}\right) .
$$

An interesting and immediate consequence is the following result.
Corollary 2. Assume that $\Gamma \subset \Sigma$ is a relatively open subset of $\Sigma$ that contains no corner points neither triple points. Then $\Gamma$ is locally a $C^{1}$ regular curve.

The strategy to prove Theorem 1 is to use on one hand that when the diameter of transported set is small we have $C^{1,1}$ regularity (thank to [10]), and on the other hand when the diameter is big $\Sigma$ stays under some very large "tangent circles" that makes $\Sigma$ similar to a convex set locally. The difficulty is to glue together all the regions where we control the tangents from one argument or another. This is what we do in Section 4.

In Section 5 and 6 we try to exploit the Euler Equation to get some regularity. In [2], G. Buttazzo E. Mainini and E. Stepanov give the first order equation for the penalized functional

$$
\mathcal{F}(\Sigma)+\lambda \mathcal{H}^{1}(\Sigma) .
$$

In Section 5 we prove the existence of a $\lambda_{0}$ such that the Euler equation for the original problem with length constraint is the same as the penalized one. The method, that was already used by F. Santambrogio and P. Tilli to characterize the blow up limits in [10], is to estimate what we loose or win in the average distance functional by adding or erasing a piece of curve at an endpoint. In particular we obtain an explicit value for $\lambda_{0}$ depending on the mass of transport rays arriving at any endpoint and which corresponds to the "shape derivative" of $\mathcal{F}$.

As an application of the Euler equation, in Section 6 we give a "tilt estimate". In other words, we obtain a local control on the oscillations of the tangents lines of $\Sigma$ with respect to a fixed line.

In Section 7 we apply Theorem 1 to find in $\Sigma$ some Lipschitz graphs (see Theorem 41) and applying the Euler Equation and the tilt estimate on those graphs we obtain some results that are summarized in the following statement.

Theorem 3. For every point $x \in \Sigma$ which is not an endpoint nor a triple point, one can find $a$ radius $r$, a line $\pi \subset \mathbb{R}^{2}$ containing $x$ and a 5-Lipschitz function $f: \pi \rightarrow \pi^{\perp}$ such that

$$
\begin{gathered}
\Sigma \cap B(x, r / 4)=\{(x, f(x)), x \in \pi\} \cap B(x, r / 4), \quad \text { and } \\
\int_{\pi \cap B\left(x, \frac{r}{16}\right)}\left|f^{\prime}(t)\right|^{2} d t \leq \operatorname{Cr} \psi(B(x, r))^{2}
\end{gathered}
$$

$$
-\frac{d}{d t}\left(\frac{f^{\prime}}{\sqrt{1+\left|f^{\prime}\right|^{2}}}\right)=\psi_{0}
$$

on $B\left(x, \frac{r}{16}\right) \cap \pi$. Here $\frac{d}{d t}$ is the derivative in the distributional sense and $\psi_{0}$ is a measure that verifies

$$
\left|\psi_{0}\right| \leq(p \circ k) \sharp \mu
$$

where $p: \mathbb{R}^{2} \rightarrow \pi$ is the projection on $\pi$ and $k$ is a mesurable selection of the projection multimap onto $\Sigma$.

As a complement of Theorem 3, we also discuss how the regularity is linked with the behavior of the measure $\psi$. In particular we have the following.

Theorem 4. Assume that $\Gamma \subset \Sigma$ is a relatively open subset of $\Sigma$ that contains no triple points and such that $\left.\psi\right|_{\Gamma}$ is absolutely continuous with respect to $\mathcal{H}^{1}$ with density in $L^{p}\left(\Gamma, d \mathcal{H}^{1}\right)$. Then $\Gamma$ is locally a $C^{1, \alpha}$ curve with $\alpha=\frac{p-1}{p}$.

This last result is proved independently from all the other sections (in particular does not use the Euler equation), and this is why Theorem 4 is actually proved at the very beginning in Section 3. It can be seen as an introduction to understand why the regularity of $\Sigma$ is difficult to obtain. We also get a reverse statement, namely that if $\Sigma$ is $C^{1,1}$ regular then $\psi$ is absolutely continuous with respect to $\mathcal{H}^{1}$ with density in $L^{\infty}$.

## 2 Preliminaries

Recall that in all the sequel, $\Sigma$ will refer to an optimal set for the problem (1.1). The existence of a minimizer is an easy consequence of Blaschke and Goła̧b Theorems and is proved in [5]. It is also proved in [5] that it is not restrictive to assume $\Omega$ convex. We will denote by $d$ the euclidian distance in $\mathbb{R}^{2}$ and by $d_{H}$ the Hausdorff distance. For any minimizer $\Sigma$ we associate a fixed measurable selection of the projection multimap $k: \Omega \rightarrow \Sigma$, that is for every $x \in \Omega$

$$
d(x, \Sigma)=d(x, k(x))
$$

Then we introduce the image measure $\psi:=k \sharp \mu$ which is defined for any Borel set $A \subset \mathbb{R}^{2}$ by

$$
\psi(A):=\mu\left(k^{-1}(A)\right)
$$

By abuse of notation we will sometimes simply denote $k^{-1}(x)$ instead of $k^{-1}(\{x\})$.
For $x \in \Sigma$ we will say that $R_{x}$ is a transport ray ending at $x$ if $R_{x}$ is a segment in $\Omega$ bounded by $x$, and having maximal length for the property that every point $y \in R_{x}$ satisfies $\operatorname{dist}(y, \Sigma)=$ $\operatorname{dist}(y, x)$.

Recall that we already know by [5] that $\Sigma$ is a finite union of injective Lipschitz arcs meeting at some finite number of triple points. We also know that for any endpoint $x$ of $\Sigma$ it holds $\psi(x)>c$ for a positive constant $c$. If we exclude the endpoints and triple junctions, thank to [10] we have a characterization of the blow up limits at point $x$ in terms of $\psi(x)$. Indeed, if $x$ is neither an endpoint nor a triple junction, then $x$ is a corner point if and only if $x$ is an atom for $\psi$, that is $\psi(x)>0$. Otherwise it is an "ordinary point" (i.e. the blow up limit is a diameter).

In the sequel we denote $\mathbb{T}_{\Sigma}$ the set of triple points of $\Sigma$ and $\mathbb{E}_{\Sigma}$ its endpoints.

### 2.1 Standard facts on compact connected 1-dimensional sets

Here we recall some standard properties on compact connected 1-dimensional sets that can be found in [7].
Proposition 5. Let $\Sigma \subset \mathbb{R}^{N}$ be a compact and connected set such that $\mathcal{H}^{1}(\Sigma)<+\infty$. Then there is a $C_{N}$-Lipschitz surjective mapping $f:[0, L] \rightarrow \Sigma$. As a consequence, $\Sigma$ is arcwise connected and rectifiable. Moreover, for each choice of $x_{0}, y_{0} \in \Sigma$ with $x_{0} \neq y_{0}$, we can find an injective Lipschitz mapping $f:[0,1] \rightarrow \Sigma$ such that $f(0)=x_{0}$ and $f(1)=y_{0}$.

Thank to Proposition 5, our minimizer $\Sigma$ is already rectifiable. Further, we will see that $\Sigma$ is actually "uniformly rectifiable" in the sense of David and Semmes. This will follow from the fact that any minimizer $\Sigma$ is Ahlfors-Regular as it is proved in [5]. Let us give some more definitions.
Definition 6. A set $\Sigma$ is said to be an Ahlfors-regular set (of dimension 1), if there exists a constant $C$ and a positive radius $r_{0}$ such that for every point $x \in \Sigma$ and every $r<r_{0}$,

$$
r C^{-1} \leq \mathcal{H}^{1}(\Sigma \cap B(x, r)) \leq C r
$$

In [5] it is proved that any minimizer $\Sigma$ is Ahlfors regular. More precisely, there is an $r_{0}>0$ such that for every $x \in \Sigma$ and any $r<r_{0}$,

$$
\begin{equation*}
r \leq \mathcal{H}^{1}(\Sigma \cap B(x, r)) \leq 3 \pi r . \tag{2.1}
\end{equation*}
$$

There is a lot of equivalent definitions of Uniform rectifiability but we will choose the one with Ahlfors-regular curves.
Definition 7. An Ahlfors-regular curve with constant $\leq C$ is a set of the form $\Sigma=z(I)$ where $I \subset \mathbb{R}$ is a closed interval (not reduced to one point) and $z: I \rightarrow \mathbb{R}^{N}$ is a Lipschitz function such that

$$
|z(x)-z(y)| \leq|x-y| \text { for } x, y \in I
$$

and

$$
\mathcal{H}^{1}(\{x \in I ; z(x) \in B(y, r)\}) \leq C r
$$

for all $y \in \mathbb{R}^{N}$ and $r>0$.
Definition 8. Let $\Sigma \subset \mathbb{R}^{N}$ be an Ahlfors-regular set of dimension 1. We say that $\Sigma$ is uniformly rectifiable when $\Sigma$ is contained in some Ahlfors-regular curve.
Theorem 9. [8] Every 1 dimensional connected Ahlfors-regular set is uniformly rectifiable.
We deduce the following fact that will be used in Section 3.2.
Corollary 10. Any minimizer $\Sigma$ is uniformly rectifiable.

### 2.2 Useful estimates and standard assumptions

We will use some estimates that are proved in [10], and that come from comparing $\Sigma$ with a competitor made by replacing a piece of $\Sigma$ by a segment.
Lemma 11. [10] There exist a constant $C$ satisfying the following properties. Let $\Gamma \subset \Sigma$ be a closed injective arc, with endpoints $x$, $y$, such that $\Gamma \backslash\{x, y\}$ contains no triple junctions of $\Sigma$ and $C \psi(\Gamma \backslash\{x, y\})<\frac{1}{2}$. Then

$$
\begin{align*}
\mathcal{H}^{1}(\Gamma) & \leq|x-y|+C \psi(\Gamma \backslash\{x, y\}) d_{H}(\Gamma,[x, y]) \\
d_{H}(\Gamma,[x, y]) & \leq C \psi(\Gamma \backslash\{x, y\})|x-y| \\
\mathcal{H}^{1}(\Gamma) & \leq|x-y|\left(1+C \psi(\Gamma \backslash\{x, y\})^{2}\right)  \tag{2.2}\\
\mathcal{H}^{1}(\Gamma) & \leq 2|x-y| \tag{2.3}
\end{align*}
$$

It will be convenient in the sequel to work in some balls where $\Sigma \cap \partial B(x, r)$ consists in exactly 2 points. For this purpose, let us recall some results that are still contained in [10].

For any $x_{0} \in \Sigma$ consider a branch of $\Sigma$ starting at $x_{0}$ consisting of a Lipschitz curve $\gamma:[0, T] \rightarrow$ $\Sigma$, parameterized by arclength, such that $\gamma(0)=x_{0}$ and $\gamma(T)$ is either an endpoint or a triple point of $\Sigma$. We may also assume that $\gamma$ contains neither endpoints nor triple junctions in its relative interior.

Theorem 2.3 of [10] says the following.
Lemma 12. [10] Consider $x \in \Sigma$ and $r>0$ such that $B(x, r)$ contains no endpoint and triple junction other than, possibly, $x$ itself. For any $s<r$, set

$$
\begin{aligned}
t_{1} & :=\min \{t \geq 0 ; \gamma(t) \in \partial B(x, s)\}, \quad t_{2}:=\max \{t \leq T ; \gamma(t) \in \partial B(x, s)\} \\
\text { If } C_{1} \psi\left(\gamma\left(0, t_{2}\right]\right) & <1, \text { then } t_{1}=t_{2}
\end{aligned}
$$

Lemma 12 is generally used together with the following fact which is Lemma 2.4. of [10].
Lemma 13. [10] For any $x \in \Sigma$ there exists $r(x)>0$ such that for all $r<r(x)$ the ball $B(x, r)$ contains no triple junction nor endpoint other than, possibly, $x$ itself, and $C_{1} \psi\left(\gamma\left(\left(0, t_{2}\right]\right)\right)<1$.

In the sequel, for any $x \in \Sigma$ we will denote $r(x)$ the maximum radius satisfying the assumptions of Lemma 13. In particular, for every $x \in \Sigma \backslash \mathbb{T}_{\Sigma} \cup \mathbb{E}_{\Sigma}$ and for all $r<r(x)$ we have

$$
\sharp \Sigma \cap \partial B(x, r)=2
$$

In [10], a uniform version of the above result is stated, saying that in fact one can take a common radius $r(x)=r_{0}$ for every $x \in \Sigma_{1}$, where $\Sigma_{1} \subset \Sigma$ is compactly contained in the complement of atoms of mass at least $\left(2 C_{1}\right)^{-1}$ and of triple junctions and endpoints, $r_{0}$ depending now on $\Sigma_{1}$. In this paper we will need this slightly different version of the preceding results.
Proposition 14. For every compact set $\Sigma_{1}$ compactly contained in $\Sigma \backslash \mathbb{T}_{\Sigma}$, there exists a constant $C_{2}:=C_{2}\left(\Sigma_{1}\right)$ and a radius $r_{0}:=r_{0}\left(\Sigma_{1}\right)$ such that for all $x \in \Sigma_{1}$ and $r<r_{0}$,

$$
\psi(B(x, r)) \leq C_{2} \Rightarrow r \leq r(x)
$$

Proof. We argue by contradiction as in the proof of Lemma 2.5. of [10]. If the proposition is not true, then there exists a sequence of points $x_{n} \in \Sigma_{1}$ and a sequence of radii $r_{n}$ such that $\psi\left(B\left(x_{n}, r_{n}\right)\right)$ tends to $0, r_{n}$ tends to 0 and does not satisfy the assumptions of Lemma 13 . Observe that for $n$ big enough, $B\left(x_{n}, r_{n}\right)$ contains no endpoints nor triple points. Indeed, it is easy to exclude endpoints as soon as $\psi\left(B\left(x_{n}, r_{n}\right)\right)$ gets smaller than $\min \left\{\psi(\{x\}) ; x \in \mathbb{E}_{\Sigma}\right\}$. For triple points, it suffice to wait until $r_{n}$ gets small enough with respect to $\operatorname{dist}\left(\Sigma_{1}, \mathbb{T}_{\Sigma}\right)>0$. Possibly by extracting a subsequence we may assume that $x_{n}$ converges to a point $x$ in $\Sigma_{1}$ and since $\psi\left(B\left(x_{n}, r_{n}\right)\right) \rightarrow 0$ we deduce that

$$
\begin{equation*}
\psi(\{x\})=0 \tag{2.4}
\end{equation*}
$$

We also know that $x_{n}$ is never a triple junction. That means that for every $x_{n}$, exactly two branches of Lipschitz arcs are starting from $x_{n}$ and meet $\partial B\left(x_{n}, r_{n}\right)$ at least once and at different points (because $\Sigma$ has no loops). Assume by contradiction that

$$
\begin{equation*}
\sharp\left\{\Sigma \cap \partial B\left(x_{n}, r_{n}\right)\right\}>2 . \tag{2.5}
\end{equation*}
$$

We denote by $\gamma_{n}^{1}$ and $\gamma_{n}^{2}$ the two corresponding parameterizations and $\gamma_{n}^{1}\left(\left[0, t_{2}^{1}(n)\right]\right)$ and $\gamma_{n}^{1}\left(\left[0, t_{2}^{2}(n)\right]\right)$ the two branches of "first return" in $B\left(x_{n}, r_{n}\right)$. From Lemma 12 we know that one of the $\psi\left(\gamma_{n}^{i}\left(\left[0, t_{2}^{i}(n)\right]\right)\right)$ is greater than $C$ otherwise (2.5) would not be true. By extracting a further subsequence we may assume that $\psi\left(\gamma_{n}^{1}\left(\left[0, t_{2}^{1}(n)\right]\right)\right)>C$ for all $n$ and arguing as in the proof of [10] Theorem 2.5. we obtain that $\gamma_{n}^{1}\left(\left[0, t_{2}^{1}(n)\right]\right)$ converges for the Hausdorff distance to $x$ which must be an atom of mass at least $C$ and contradicts (2.4).

Let us introduce a quantity which will measure the flatness of $\Sigma$ in the ball $B(x, r)$, defined for $x \in \Sigma \backslash\left(\mathbb{T}_{\Sigma} \cup \mathbb{E}_{\Sigma}\right)$ and $r<r(x)$ by

$$
\beta(x, r):=\frac{d_{H}\left(\Sigma \cap B(x, r),\left[z, z^{\prime}\right]\right)}{\left|z-z^{\prime}\right|}
$$

where $z$ and $z^{\prime}$ are the two points of $\partial B(x, r) \cap \Sigma$. The notation is given compared to the well known P. Jones $\beta$-numbers.

For simplicity, when there is no possible confusion we will denote $\psi(x, r)$ instead of $\psi(B(x, r))$. By Lemma 11 we directly have

$$
\begin{equation*}
\beta(x, r) \leq C \psi(x, r) \tag{2.6}
\end{equation*}
$$

Finally, we end this preliminary section by recalling the basic steps that lead to the regularity result of [10] since we will also need the intermediate estimates. The next proposition is a direct consequence of the proof of Lemma 2.10 of [10]. We let the details to the reader.

Proposition 15. [10] For all $x \in \Sigma$ and $r$ such that there exists a line $\pi \subset \mathbb{R}^{2}$ satisfying

$$
d_{H}(\Sigma \cap B(x, 2 r), \pi \cap B(x, 2 r)) \leq \frac{r}{100}
$$

we have

$$
\begin{equation*}
\psi(x, r) \leq \operatorname{Crdiam}\left(k^{-1}\left(B\left(x, r_{0}\right)\right)\right)+C r^{-1} d_{H}(\Sigma \cap B(x, 2 r), \pi \cap B(x, 2 r)) \tag{2.7}
\end{equation*}
$$

In particular if $r<r(x)$ and $\psi(x, r)$ is small enough then

$$
\psi(x, r) \leq C(r+\beta(x, 2 r))
$$

As it is shown in [10] (Theorem 2.11.), the last estimate can be iterated in the case when $r<r(x)$ in order to obtain the following result which will be also needed later.
Proposition 16. [10] Let $x \in \Sigma \backslash\left(\mathbb{T}_{\Sigma} \cup \mathbb{E}_{\Sigma}\right)$ and $r<r(x)$. If $\operatorname{diam}\left(k^{-1}\left(B\left(x, r_{0}\right)\right)\right)<1 /(2 C)$ then there exists $r_{0}$ depending on $\Sigma$ such that

$$
\begin{equation*}
\psi(x, r) \leq C r \quad \forall r \leq \min \left(r_{0}, r(x)\right) \tag{2.8}
\end{equation*}
$$

where $C$ is a constant depending only on $\Sigma, \Omega$ and $\mu$.
Observe that (2.8) together with (2.6) leads to some $C^{1,1}$ regularity.

## 3 The measure $\psi$

In the next sections we will see how $\psi$ is linked with the mean curvature of $\Sigma$. Therefore it is natural to think that some good control on $\psi$ will give some regularity on $\Sigma$. This is what we do in this section.

### 3.1 The regularity is equivalent to the behavior of $\psi$

Let us first prove that the regularity of $\Sigma$ implies some decay on $\psi(x, r)$.
Proposition 17. If $\Sigma \cap B\left(x_{0}, r_{0}\right)$ is a $C^{1, \alpha}$ regular curve then there exists $r_{1} \leq r_{0}$ such that $\psi(x, r) \leq C r^{\alpha}$ for all $x \in \Sigma \cap B\left(x_{0}, r_{0} / 2\right)$ and $r \leq r_{1}$.

Proof. Assume that $\Sigma^{\prime}:=\Sigma \cap B\left(x_{0}, r_{0}\right)$ is a $C^{1, \alpha}$ regular curve $\gamma$ parameterized by arclenght. Let $x \in \Sigma \cap B\left(x_{0}, r_{0} / 2\right)$ and $r \leq r_{0} / 2$. Then for all $y \in B(x, r)$ one has

$$
\gamma(t)-\gamma(0)=\int_{0}^{t} \gamma^{\prime}(s) d s
$$

with $\gamma(0)=x$ and $\gamma(t)=y$. Further,

$$
\begin{aligned}
\gamma(t)-\gamma(0) & =\int_{0}^{t} \gamma^{\prime}(s)-\gamma^{\prime}(0) d s+\int_{0}^{t} \gamma^{\prime}(0) d s \\
\left|\gamma(t)-\gamma(0)-t \gamma^{\prime}(0)\right| & \leq \int_{0}^{t}\left|\gamma^{\prime}(s)-\gamma^{\prime}(0)\right| d s \\
& \leq C t^{1+\alpha}
\end{aligned}
$$

which implies

$$
\operatorname{dist}(y, T(x)) \leq C|x-y|^{1+\alpha} \leq C r^{1+\alpha}
$$

where $T\left(x_{0}\right)$ is the tangent line at $x_{0}$. Since $y$ is an arbitrary point lying in $\Sigma \cap B(x, r)$, by (2.7) we conclude that $\psi(x, r) \leq C r^{\alpha}$ for $r$ small enough depending on $r_{0}$ an other constants.

Now we prove the reverse statement.
Proposition 18. Assume that $x_{0} \in \Sigma$ and $r_{0}>0$ are such that $B\left(x_{0}, r_{0}\right)$ contains no triple points nor endpoints and such that $\psi(x, r) \leq C r^{\alpha}$ for all $x \in \Sigma \cap B\left(x_{0}, r_{0} / 2\right)$ and $r<r_{0} / 2$. Then $\Sigma \cap B\left(x_{0}, r_{0} / 2\right)$ is a $C^{1, \alpha}$ regular curve.

Proof. We denote $r_{0}\left(\Sigma_{1}\right)$ the radius given by Proposition 14 with $\Sigma_{1}:=\Sigma \cap B\left(x_{0}, r_{0}\right)$. We also denote $r_{2} \leq \min \left(r_{0}\left(\Sigma_{1}\right), r_{0} / 2\right)$ a radius such that $C r_{2}^{\alpha} \leq C_{2}\left(\Sigma_{1}\right)$ in such a way that for all $x \in \Sigma \cap B\left(x_{0}, r_{0} / 2\right), r_{2} \leq r(x)$. Now from $\psi(x, r) \leq C r^{\alpha}$ for all $r \leq r_{2}$ we obtain by (2.6) that $\beta(x, r) \leq C r^{\alpha}$ for all $x \in \Sigma_{1}$ and $r<r_{2}$.

For every $x \in B\left(x_{0}, r_{0} / 2\right)$ and $r<r_{2}$, we denote $\pi_{x, r}$ the line through the two points of $\Sigma \cap \partial B(x, r)$. We claim that $\pi_{x, r}$ converges to some tangent line $\pi_{x}$ at $x$ when $r$ goes to 0 . To see this, let us introduce for two lines $\pi_{x, s_{1}}$ and $\pi_{x, s_{2}}$ the distance

$$
\operatorname{dist}\left(\pi_{x, s_{1}}, \pi_{x, s_{2}}\right):=d_{H}\left(\bar{\pi}_{x, s_{1}} \cap B(0,1), \bar{\pi}_{x, s_{2}} \cap B(0,1)\right)
$$

where $d_{H}$ the Hausdorff distance, and $\bar{\pi}_{x, r}$ is the line parallel to $\pi_{x, r}$ through the origin. In other words $\operatorname{dist}\left(\pi_{x, s_{1}}, \pi_{x, s_{2}}\right) \simeq \alpha\left(\pi_{x, s_{1}}, \pi_{x, s_{2}}\right)$ where $\alpha$ is the smallest angle between the two lines $\pi_{x, s_{1}}$ and $\pi_{x, s_{2}}$ thus endowed with this distance the set of lines in $\mathbb{R}^{2}$ centered at the origin is a complete metric space. Now since $\beta(x, r) \leq C r^{\alpha}$ we claim that for any $s_{1}<s_{2}$,

$$
\begin{equation*}
\operatorname{dist}\left(\pi_{x, s_{1}}, \pi_{x, s_{2}}\right) \leq C s_{2}^{\alpha} \tag{3.1}
\end{equation*}
$$

Indeed, for all $s \leq r_{2}$ it is clear that

$$
\begin{equation*}
\operatorname{dist}\left(\pi_{x, s / 2}, \pi_{x, s}\right) \leq C s^{\alpha} \tag{3.2}
\end{equation*}
$$

Now if $k$ is such that $2^{-(k+1)} s_{2}<s_{1} \leq 2^{-k} s_{2}$ we have

$$
\operatorname{dist}\left(\pi_{x, s_{1}}, \pi_{x, s_{2}}\right) \leq C \sum_{j=0}^{k} \operatorname{dist}\left(\pi_{x, 2^{-(j+1)} r_{2}}, \pi_{x, 2^{-j} r_{2}}\right) \leq C \sum_{j=0}^{k} 2^{-j \alpha} s_{2}^{\alpha} \leq C s_{2}^{\alpha}
$$

which proves (3.1).

Now (3.1) says that $\bar{\pi}_{x, r}$ is a Cauchy sequence and converges to some line $\bar{\pi}_{x}$ centered at the origin. Moreover, if $\pi_{x}$ denotes the line parallel to $\bar{\pi}_{x}$ passing through $x$, for all $r<r_{0}$ we have that

$$
\operatorname{dist}\left(\pi_{x}, \pi_{x, r}\right) \leq C r^{\alpha}
$$

and

$$
\begin{aligned}
d_{H}\left(\Sigma \cap B(x, r), \pi_{x} \cap B(x, r)\right) & \left.\leq 2 d_{H}\left(\pi_{x, r} \cap B(x, r), \pi_{x} \cap B(x, r)\right)\right) \\
& \leq 4 \operatorname{rdist}\left(\pi_{x, r}, \pi_{x}\right) \leq C r^{\alpha+1}
\end{aligned}
$$

thus $\pi_{x}$ is a tangent line at $x$.
So $\Sigma \cap B\left(x_{0}, r_{0} / 2\right)$ admits a tangent line $\pi_{x}$ at every point $x$. To prove that $\Sigma \cap B\left(x, r_{0} / 2\right)$ is a $C^{1, \alpha}$ regular curve, it suffice to show that the map $x \mapsto \pi_{x}$ is Hölder regular. Let $y$ and $z$ be two different points of $\Sigma \cap B\left(x_{0}, r_{0} / 2\right)$ and let $\rho:=|y-z|$. Assume first that $\rho \leq r_{2} / 10$. We have that

$$
\begin{align*}
\operatorname{dist}\left(\pi_{y}, \pi_{z}\right) & \leq \operatorname{dist}\left(\pi_{y}, \pi_{y, 2 \rho}\right)+\operatorname{dist}\left(\pi_{y, 2 \rho}, \pi_{z, 2 \rho}\right)+\operatorname{dist}\left(\pi_{z, 2 \rho}, \pi_{z}\right) \\
& \leq C \rho^{\alpha}+\operatorname{dist}\left(\pi_{y, 2 \rho}, \pi_{z, 2 \rho}\right) . \tag{3.3}
\end{align*}
$$

Now observe that taking a point $z^{\prime}$ between $y$ and $z$ and applying (3.1) at this point with $r=4 \rho$ we have that

$$
\begin{equation*}
\operatorname{dist}\left(\pi_{y, 2 \rho}, \pi_{z, 2 \rho}\right) \leq C\left[\beta\left(z^{\prime}, 4 \rho\right)+\operatorname{dist}\left(\pi_{y, 2 \rho}, \pi_{z^{\prime}, 4 \rho}\right)+\operatorname{dist}\left(\pi_{z, 2 \rho}, \pi_{z^{\prime}, 4 \rho}\right)\right] \leq C \rho^{\alpha} \tag{3.4}
\end{equation*}
$$

Therefore, (3.3) and (3.4) imply

$$
\begin{equation*}
\operatorname{dist}\left(\pi_{y}, \pi_{z}\right) \leq C|y-z|^{\alpha} . \tag{3.5}
\end{equation*}
$$

Now if $\rho \geq r_{2} / 10$ (3.5) is also true up to change $C$ (depending on $r_{2}$ ), which means that $\Sigma \cap$ $B\left(x_{0}, r_{0} / 2\right)$ is $C^{1, \alpha}$.

As an application we can state the following.
Theorem 19. Assume that $\Gamma \subset \Sigma$ is a relatively open subset of $\Sigma$ that contains no triple points and such that $\left.\psi\right|_{\Gamma}$ is absolutely continuous with respect to $\mathcal{H}^{1}$ with density in $L^{p}\left(\Gamma, d \mathcal{H}^{1}\right)$. Then $\Gamma$ is locally a $C^{1, \alpha}$ curve with $\alpha=\frac{p-1}{p}$.

Proof. Let $x \in \Gamma$. Since $\Gamma$ is open, we may assume that there is a ball $B(x, r)$ such that $r<r(x)$ and $\left.\psi\right|_{\Sigma \cap B(x, r)}$ is absolutely continuous with respect to $\mathcal{H}^{1}$ in $B(x, r)$ and its density belongs to $L^{p}$. Then for all $x \in \Sigma \cap B(x, r / 2)$ Hölder inequality gives, for all $y \in B(x, r)$ and $s<r / 2$,

$$
\psi(y, s):=\psi(B(y, s)) \leq\|\psi\|_{p} \mathcal{H}^{1}(\Sigma \cap B(y, s))^{\frac{1}{p^{\prime}}} \leq C s^{\frac{1}{p^{\prime}}}
$$

thus Proposition 18 applies which proves that $\Gamma$ is $C_{l o c}^{1, \alpha}$ with $\alpha=1-\frac{1}{p}$.
As far as the reverse implication is concerned, we can prove the following.
Proposition 20. If $\Sigma \cap B(x, r)$ is a $C^{1,1}$ regular curve then $\left.\psi\right|_{\Sigma_{r}}$ is absolutely continuous with respect to $\mathcal{H}^{1}$ in $B(x, r / 2)$ and its density belongs to $L^{\infty}$.

Proof. According to Theorem 2.56 of [1], it is enough to find a constant $M$ such that for every $y \in \Sigma \cap B(x, r / 2)$,

$$
\begin{equation*}
\limsup _{s \rightarrow 0} \frac{\psi(y, s)}{s} \leq M \tag{3.6}
\end{equation*}
$$

and this is the case when $\Sigma \cap B(x, r)$ is $C^{1,1}$, because then arguing as for Proposition 17 we easily have that $\beta(y, s) \leq C s$ for every $y \in \Sigma \cap B(x, r / 2)$ and $s<r_{2}(\Sigma \cap B(x, r))$ thus $\psi(y, s) \leq C r$ by (2.7).

## $3.2 \psi(x, t) d \mathcal{H}^{1}(x) \frac{d t}{t}$ satisfies a Carleson measure condition

As Proposition 17 and 18 say, the regularity of $\Sigma$ depends on the behavior of $\psi(x, r)$ with respect to $r$. The next proposition shows that in mean, $\psi(x, t)$ is very small with respect to $t$ at every scale, at least sufficiently small to make a certain integral converging. In other words $\psi(x, t) \chi_{[x, r(x)]}(t) d \mathcal{H}^{1}(x) \frac{d t}{t}$ is a Carleson Measure.
Proposition 21. For all $x \in \Sigma \backslash\left(\mathbb{T}_{\Sigma} \cup \mathbb{E}_{\Sigma}\right)$. Then there exists $r_{0}(x) \leq r(x)$ such that

$$
\int_{y \in \Sigma \cap B(x, r)} \int_{0<t<r} \psi(y, t)^{2} d \mathcal{H}^{1}(y) \frac{d t}{t} \leq C r \quad \forall r \in\left(0, r_{0}(x)\right) .
$$

Proof. Since $\Sigma$ is a uniformly rectifiable set of dimension 1 in $\mathbb{R}^{2}$, there is a constant $C$ (see [6]) such that

$$
\begin{equation*}
\int_{y \in \Sigma \cap B(x, r)} \int_{0<t<r} \beta(y, t)^{2} d \mathcal{H}^{1}(y) \frac{d t}{t} \leq C r \tag{3.7}
\end{equation*}
$$

for $x \in \Sigma$ and $r \in\left(0, r_{0}\right)$. Actually the $\beta$ in (3.7) is normally the one of P . Jones which is slightly different than our $\beta$ but smaller than 2 times ours thus (3.7) holds. Now possibly by taking a smaller $r_{0}$ (depending on $r(x)$ ) and using inequality (2.7) we compute

$$
\begin{aligned}
\int_{y \in \Sigma \cap B(x, r)} \int_{0<t<r} \psi(y, t)^{2} d \mathcal{H}^{1}(y) \frac{d t}{t} & \leq C \int_{y \in \Sigma \cap B(x, r)} \int_{0<t<r} t^{2}+\beta(y, t)^{2} d \mathcal{H}^{1}(y) \frac{d t}{t} \\
& \leq C r .
\end{aligned}
$$

## 4 About the diameter of the transported set and applications

In [10], it is proved that $\Sigma$ is $C^{1,1}$ provided that the diameter of the transported set is small. In the next section we are interested in the opposite situation, when the diameter is very large. In this case $\Sigma$ stays under some very large "tangent circles" that makes it close to be a convex graph.

### 4.1 Considerations for large diameters

We first want to give a notion of Right and Left tangents at a point $x \in \Sigma$ when its blow up is a line or a corner. To do this, we need to give an orientation on $\Sigma$ to say in which direction $\Sigma$ is followed.

Definition 22. For any injective parametrization $\gamma:[0, T] \rightarrow \Sigma$ of a piece of $\Sigma$ that contains no triple point we define the Right and Left Tangent at point $x=\gamma\left(t_{0}\right) \in \gamma(] 0, T[)$ associated to $\gamma$ and denote by $T_{R}(x)$ and $T_{L}(x)$ the half lines

$$
\begin{aligned}
& T_{R}(x):=x+\mathbb{R}^{+} \cdot \lim _{h \rightarrow 0} \frac{\gamma\left(t_{0}+h\right)-\gamma\left(t_{0}\right)}{h} \\
& T_{L}(x):=x+\mathbb{R}^{+} \cdot \lim _{h \rightarrow 0} \frac{\gamma\left(t_{0}-h\right)-\gamma\left(t_{0}\right)}{h}
\end{aligned}
$$

Remark 23. Notice that the existence of Right and Left tangents comes from the existence of blow up limits (line or corner) at each points and that the dependance on $\gamma$ is only relying on orientation.

In the sequel we will prove that $x \mapsto T_{R}(x)$ and $x \mapsto T_{L}(x)$ admits some Left and Right limits at every point (see Theorem 31) and are semi-continuous but let us check first that it is the case in basic situations when the diameter of transported set is under control.

For any parametrization $\gamma:[0, T] \rightarrow \Sigma$ we will use the notation

$$
x<_{\gamma} y
$$

to say that $x=\gamma(t)$ and $y=\gamma\left(t^{\prime}\right)$ with $t<t^{\prime}$.
Since our result is local, it is not restrictive to consider the situation in a small ball $B(x, r)$ around $x:=\gamma(t) \in \Sigma$. We need to define a sort of local orientation on $\Sigma$. Recall that for every $x \in \Sigma$ which is not a triple point, nor an endpoint, Lemma 13 gives a radius $r(x)$ such that $\sharp \Sigma \cap \partial B(x, r)=2$ for all $r<r(x)$. It follows that for all $r<r(x), B(x, r) \backslash \Sigma$ is cut by $\Sigma$ in exactly two connected components. Suppose now that $x \in \Sigma$ and $r \in(0, r(x))$ are such that $\Sigma \cap B(x, r)=\Gamma \cap B(x, r)$ where $\Gamma:=\gamma([0, T])$. Let $s<r$ be given and let $\gamma\left(t_{1}\right)$ and $\gamma\left(t_{2}\right)$ be the two points of $\partial B(x, s) \cap \Gamma$. Assume in addition that $t_{1}<t_{2}$. Then we denote $\partial B(x, s)^{ \pm}$the two connected components of $\partial B(x, s) \backslash \Gamma$, in such a way that $\partial B(x, s)^{+}$is corresponding to the piece of circle obtained when we start at $\gamma\left(t_{1}\right)$ and follow the circle in the clockwise sense as in the following picture.


Then we define $B(x, s)^{ \pm}$as being the connected components of $B(x, s) \backslash \Gamma$ labeled in such a way that the boundary of $B(x, s)^{+}$meets $\partial B(x, s)^{+}$. Observe that by this way, if $s^{\prime}<s$ then $\partial B\left(x, s^{\prime}\right)^{+} \subset B(x, s)^{+}$. This follows from the fact that the points $z_{s}$ and $z_{s}^{\prime}$ lying on $\Sigma \cap \partial B(x, s)$ are continuous with respect to $s$. It is worth mentioning that the orientation does not depend on point $x$, in other words if $B(x, s)$ and $B\left(x^{\prime}, s^{\prime}\right)$ are both contained in $B\left(x_{0}, r_{0}\right)$ with $r_{0}<r\left(x_{0}\right)$, then $B(x, s)^{+} \cap B\left(x^{\prime}, s^{\prime}\right)^{-}=\emptyset$ and viceversa.

General assumptions 1 : We will say that we are under General assumptions 1 in $B\left(x_{0}, r_{0}\right)$ when $\gamma:[0, T] \rightarrow \Sigma$ is a given parametrization as in Definition 22, $\Sigma \cap B\left(x_{0}, r_{0}\right)=\gamma\left[t_{1}, t_{2}\right]$ for some $t_{1}, t_{2} \in[0, T]$ and $\gamma\left(\left[t_{1}, t_{2}\right]\right)$ contains no triple points nor endpoints. We also assume that $r_{0} \leq r\left(x_{0}\right)$. In this situation we have an orientation, namely $B\left(x_{0}, s\right)^{ \pm}$are well defined for all $s \leq r_{0}$. We also denote $\Gamma:=\gamma([0, T])$.

Notice that for every $x \in \Sigma \backslash\left(\mathbb{T}_{\Sigma} \cup \mathbb{E}_{\Sigma}\right)$ one can always find a parametrization $\gamma$ and a radius $r$ in such a way that $B(x, r)$ satisfies General Assumptions 1.
Definition 24. Assume that we are under general assumptions 1 in $B\left(x_{0}, r_{0}\right)$. Then for every $y \in \Gamma \cap B\left(x_{0}, r_{0}\right)$ and for every transport ray $R_{y}$ ending at $y$ we say that $R_{y}$ is coming from above if $R_{y} \cap B\left(x_{0}, r_{0}\right)^{+} \neq \emptyset$ and we say that $R_{y}$ is coming from below if $R_{y} \cap B\left(x_{0}, r_{0}\right)^{-} \neq \emptyset$. If $R_{y}$ and $R_{z}$ are two different transport rays that are both coming from below or both coming from above we will say that $R_{y}$ and $R_{z}$ are coming from the same direction. We denote $k^{-1}(y)^{+}$the family of transported Rays ending at $y$ and coming from above and $k^{-1}(y)^{-}$the ones coming from below.
Remark 25. Of course a non empty ray cannot comes from above and below at the same time. The definition of Above and Below depends only on the orientation given by $\gamma$.

We will need this elementary fact which was already used in a slightly different version in [10].
Proposition 26. Assume that $\Omega$ is convex and that we are under General assumptions 1 in $B\left(x_{0}, r_{0}\right)$. Then $x \mapsto \operatorname{diam}\left(k^{-1}(x)^{ \pm}\right)$are upper-semicontinuous for $x \in \Sigma \cap B\left(x_{0}, r_{0}\right)$.

Proof. It is enough to prove the Proposition for $\operatorname{diam}\left(k^{-1}(x)^{+}\right)$. Assume the contrary. Namely, there exists $\delta>0$ and a sequence of points $x_{n}$ that converges to $x_{\infty}$ in $\Sigma \cap B\left(x_{0}, r_{0}\right)$ and such that

$$
\begin{equation*}
\operatorname{diam}\left(k^{-1}\left(x_{n}\right)^{+}\right) \geq \operatorname{diam}\left(k^{-1}\left(x_{\infty}\right)^{+}\right)+\delta \tag{4.1}
\end{equation*}
$$

Let $y_{n}$ be a sequence of points in $k^{-1}\left(\left\{x_{n}\right\}\right)^{+}$such that $d\left(x_{n}, y_{n}\right)=\operatorname{diam}\left(k^{-1}\left(x_{n}\right)^{+}\right)$. Up to a subsequence we can assume that $y_{n}$ converges to a certain $y_{\infty}$, and by continuity of $x \mapsto \operatorname{dist}(x, \Sigma)$ we deduce that $y_{\infty} \in k^{-1}\left(x_{\infty}\right)$. Moreover $y_{\infty}$ is still coming from above. Then from (4.1) and

$$
d\left(y_{n}, x_{n}\right) \leq d\left(y_{n}, x_{\infty}\right)+d\left(x_{\infty}, x_{n}\right)
$$

we obtain

$$
\operatorname{diam}\left(k^{-1}\left(x_{\infty}\right)^{+}\right)+\delta \leq d\left(y_{n}, x_{\infty}\right)+d\left(x_{\infty}, x_{n}\right)
$$

thus passing to the limit it comes

$$
\operatorname{diam}\left(k^{-1}\left(x_{\infty}\right)\right)+\delta \leq d\left(y_{\infty}, x_{\infty}\right)
$$

which is a contradiction.

For all $x \in \Sigma$ and $R_{x}$ a transported ray arriving at $x$ we will denote $\nu\left(R_{x}\right)$ the unit "normal" vector oriented by $R_{x}$ and defined by the identity

$$
R_{x}=x+\left[0, \mathcal{H}^{1}\left(R_{x}\right)\right] \cdot \nu\left(R_{x}\right)
$$

In most of our next arguments we will need the following "key lemma".
Lemma 27. Assume that we have General assumptions 1 in $B\left(x_{0}, r_{0}\right)$ with $x_{0} \in \Sigma$ and a parametrization $\gamma$. Then for every $C_{3}>r_{0}$ the following holds. Let $t<t^{\prime}$ be such that $\gamma(t)$ and $\gamma\left(t^{\prime}\right)$ lie in $B\left(x_{0}, r_{0}\right)$ and admit some transport rays $R_{t}$ and $R_{t^{\prime}}$ that are both coming from above and satisfying $\min \left(\mathcal{H}^{1}\left(R_{t}\right), \mathcal{H}^{1}\left(R_{t^{\prime}}\right)\right) \geq C_{3}$. Then:

$$
\operatorname{Angle}\left(\nu\left(R_{\gamma\left(t^{\prime}\right)}\right), \nu\left(R_{\gamma(t)}\right)\right) \leq 2 \arcsin \left(\frac{1}{C_{3}}\left|\gamma(t)-\gamma\left(t^{\prime}\right)\right|\right)
$$

where $\operatorname{Angle}(v, w)$ denotes the oriented angle between the two vectors $v$ and $w$.

Proof. Let $t$ and $t^{\prime}$ be as in the statement of the Lemma. We know that $\gamma(t)$ is under a circle of radius bigger than $C_{3}$ "tangent" to $\gamma\left(t^{\prime}\right)$ and viceversa. Let us assume without loss of generality that $\gamma\left(t^{\prime}\right)$ is the origin and $R_{\gamma\left(t^{\prime}\right)}^{\perp}$ is the first axis. Let $L_{t}$ be the line containing the two points $\gamma(t)$ and $\gamma\left(t^{\prime}\right)$ and let $v_{t}$ be the unit vector orthogonal to $L_{t}$ pointing in the "above" direction, which means pointing in the clockwise sense on the circle $B\left(\gamma\left(t^{\prime}\right),\left|\gamma(t)-\gamma\left(t^{\prime}\right)\right|\right)$. The only way for the angle $\operatorname{Angle}\left(\nu\left(R_{\gamma\left(t^{\prime}\right)}\right), v_{t}\right)$ to be positive is when $\gamma(t)$ has negative first coordinate and positive second coordinate as in the following picture

and since $\gamma(t)$ must be at the same time lying under the "tangent" circle associated to $\gamma\left(t^{\prime}\right)$ we deduce that

$$
\operatorname{Angle}\left(\nu\left(R_{\gamma\left(t^{\prime}\right)}\right), v_{t}\right) \leq \arcsin \left[\frac{1}{C_{3}}\left|\gamma(t)-\gamma\left(t^{\prime}\right)\right|\right]
$$

By the same argument considering this time the circle associated to $\gamma(t)$ we also have that

$$
\operatorname{Angle}\left(v_{t}, \nu\left(R_{\gamma(t)}\right)\right) \leq \arcsin \left[\frac{1}{C_{3}}\left|\gamma(t)-\gamma\left(t^{\prime}\right)\right|\right]
$$

which all together gives $(i)$, and the Lemma is proved.
Now we can state a first regularity result.
Proposition 28. Assume that we have General assumptions 1 in $B\left(x_{0}, r_{0}\right)$ and that

$$
\begin{equation*}
\inf \left\{\operatorname{diam}\left(t^{-1}(y)^{+}\right) ; y \in \Sigma \cap B\left(x_{0}, r_{0}\right)\right\}>0 \tag{4.2}
\end{equation*}
$$

then $x \mapsto T_{R}(x)$ and $x \mapsto T_{L}(x)$ are semicontinuous, i.e. for every $y_{0} \in B\left(x_{0}, r_{0}\right)$,

$$
\begin{equation*}
\lim _{\substack{y \rightarrow y_{0} \\ y<\gamma y_{0}}} T_{L}(y)=T_{L}\left(y_{0}\right) \quad \text { and } \quad \lim _{\substack{y>y_{0} \\ y>\gamma y_{0}}} T_{R}(y)=T_{R}\left(y_{0}\right) \text {. } \tag{4.3}
\end{equation*}
$$

In addition the limit from the other side exists and we have

$$
\begin{equation*}
\lim _{\substack{y \rightarrow y_{0} \\ y>\gamma y_{0}}} T_{L}(y)=T_{R}\left(y_{0}\right) \quad \text { and } \quad \lim _{\substack{y>y_{0} \\ y<\gamma y_{0}}} T_{R}(y)=T_{L}\left(y_{0}\right) \text {. } \tag{4.4}
\end{equation*}
$$

Proof. Up to change the orientation it is enough to prove the result for $T_{L}$. For any corner point $y \in \Sigma \cap B(x, r)$ let us denote $R_{y}^{R}$ and $R_{y}^{L}$ the two transported Rays orthogonal to $T_{R}(y)$ and $T_{L}(y)$ as in the following picture


Under assumption (4.2), if $R_{y}^{R}$ and $R_{y}^{L}$ are not empty they can only arrive from above. We denote $\mathcal{R}_{1}$ the union of all the $R_{y}^{R}$ and $R_{y}^{L}$ for $y$ a corner point in $\Sigma \cap B\left(x_{0}, r_{0}\right)$. Then, for every ordinary point $y \in \Sigma \cap B\left(x_{0}, r_{0}\right)$ we denote $R_{y}^{+}$the single ray coming from above and arriving at $y$ and we denote $\mathcal{R}_{2}$ the union of all the $R_{y}^{+}$for all ordinary point $y$. Finally, we denote $\mathcal{R}:=\mathcal{R}_{1} \cup \mathcal{R}_{2}$.

We claim that (4.2) implies the following stronger condition

$$
\begin{equation*}
\inf \left\{\mathcal{H}^{1}\left(R_{y}\right) ; R_{y} \in \mathcal{R}\right\} \geq C_{3} / 2 \tag{4.5}
\end{equation*}
$$

where

$$
C_{3}:=\inf \left\{\operatorname{diam}\left(t^{-1}(y)^{+}\right) ; y \in \Sigma \cap B(x, r)\right\} .
$$

Indeed, if $y$ is an ordinary point then $\operatorname{diam}\left(t^{-1}(y)^{+}\right)=\mathcal{H}^{1}\left(R_{y}^{+}\right)$so the problem could only occur at corner points. Now let $y$ be a corner point and assume by contradiction that $\mathcal{H}^{1}\left(R_{y}^{R}\right)<C_{3} / 2$ (the argument will work by the same way for $R_{y}^{L}$ ). Then by semicontinuity of the length of transported rays (Proposition 28), all the transported rays coming from above and arriving in a sufficiently small neigborhood at the right hand side of $y$ still has a length strictly less than $C_{3}$. Now to get a contradiction with (4.2) it suffice to choose an ordinary point $z$ in this neighborhood for which we know that the lenght of $R_{z}^{+}$is exactly $\operatorname{diam}\left(t^{-1}(z)^{+}\right) \geq C_{3}$. It is always possible to find such a point $z$ because ordinary points of $\Sigma$ have full $\mathcal{H}^{1}$ measure.

Now to prove the existence of limit we will use the "key lemma". Let $y_{0}$ be a fixed point in $B\left(x_{0}, r_{0}\right)$. Since the result is local we can restrict ourself to $B\left(y_{0}, s\right)$ for a radius $s$ small as we want. For instance we can take $s \leq C_{3} / 100$. Now by convention, when $y$ is an ordinary point we set $R_{y}^{R}=R_{y}^{L}=R_{y}^{+}$and we define for $y \in B\left(y_{0}, s\right)$ and $y \leq_{\gamma} y_{0}$ the function

$$
\theta(y):=\operatorname{Angle}\left(\nu\left(R_{y_{0}}^{L}\right), \nu\left(R_{y}^{L}\right)\right) .
$$

We want to prove that $\theta(y)$ has a limit when $y \rightarrow y_{0}$, and $y<_{\gamma} y_{0}$. Let

$$
M:=\sup \left\{\theta(y) ; y \in B\left(y_{0}, s\right) \text { and } y<_{\gamma} y_{0}\right\} .
$$

It is clear that

$$
\begin{equation*}
\underset{\substack{y \rightarrow y_{0} \\ y<\gamma y_{0}}}{\limsup } \theta(y) \leq M \tag{4.6}
\end{equation*}
$$

Now by definition of $M$, for every $\varepsilon>0$ one can find $y_{\varepsilon} \in \Sigma \cap B\left(y_{0}, s\right)$ such that $\theta\left(y_{\varepsilon}\right) \geq M-\varepsilon$. On the other hand for all $y>_{\gamma} y_{\varepsilon}$ Lemma 27 implies

$$
\theta\left(y_{\varepsilon}\right) \leq \theta(y)+2 \arcsin \left(\frac{1}{C_{3}}\left|y-y_{\varepsilon}\right|\right)
$$

which leads to

$$
M-\varepsilon \leq \liminf _{\substack{y \rightarrow y_{0} \\ y<\gamma y_{0}}} \theta(y)
$$

and since $\varepsilon$ is arbitrary, combining the last inequality with (4.6) and letting $\varepsilon$ goes to 0 we obtain that the Left limit of $\theta(y)$ exists and is equal to $M$, which means that the Left limit

$$
\lim _{\substack{y \rightarrow y_{0} \\ y<\gamma y_{0}}} T_{L}(y)
$$

exists. For the existence of Right limit of $T_{L}$ one can argue by the same way using this time the infimum instead of supremum.

Let us prove now that

$$
\begin{equation*}
\lim _{\substack{y \rightarrow y_{0} \\ y<\gamma y_{0}}} T_{L}(y)=T_{L}\left(y_{0}\right) \tag{4.7}
\end{equation*}
$$

The proof of

$$
\begin{equation*}
\lim _{\substack{y \rightarrow y_{0} \\ y>\gamma}} T_{L}(y)=T_{R}\left(y_{0}\right) \tag{4.8}
\end{equation*}
$$

will follow by the same argument.
We already know that

$$
\limsup _{\substack{y \rightarrow y_{0} \\ y<\gamma y_{0}}} \theta(y) \leq \theta\left(y_{0}\right)=0
$$

so it is enough to prove the reverse inequality, for which we argue as follows. Let $y_{k}$ be a sequence of points converging to $y_{0}$ and let $z_{k}$ be a corresponding sequence of points belonging to a transport Ray $R_{y_{k}}^{L}$ ending at $y_{k}$. By continuity of $x \mapsto \operatorname{dist}(x, \Sigma)$ we obtain that the $z_{k}$ converges to a point $z$ which belongs to $k^{-1}\left(y_{0}\right)^{+}$. This implies that

$$
\limsup _{\substack{y \rightarrow y_{0} \\ y<\gamma y_{0}}} \theta(y) \geq 0
$$

which ends the proof.
Remark 29. A consequence of the proposition just proved is that if we assume $\Sigma$ to contain no corner points in $B(x, r)$, then under assumption (4.2) $\Sigma$ is $C^{1}$ in $B(x, r)$ because in this case $T_{L}(x)=T_{R}(x)$ at every point.

Now if (4.2) holds from above and below at the same time we have more regularity as it is shown by the following proposition.

Proposition 30. Assume that we have General assumption 1 in $B\left(x_{0}, r_{0}\right)$. If

$$
\begin{equation*}
\inf \left\{\min \left(\operatorname{diam}\left(t^{-1}(x)^{+}\right), \operatorname{diam}\left(t^{-1}(x)^{-}\right)\right) ; x \in \Sigma \cap B(x, r)\right\}>0 \tag{4.9}
\end{equation*}
$$

then $\Sigma$ is $C^{1,1}$ in $B\left(x_{0}, r_{0} / 2\right)$.
Proof. Observe that under assumption (4.9), for every point $y \in \Sigma \cap B\left(x_{0}, r_{0} / 2\right)$ we have that $\Sigma$ is lying in the complement of two circles with radius uniformly bounded from below and tangent to each other at $y$. From this fact one can find a radius $r_{1}$ such that $\beta(y, r) \leq C r$ for all $r<r_{1}$ and the proposition follows from the same argument as for Proposition 18.

### 4.2 A regularity result

This paragraph is devoted to the proof of the following result.
Theorem 31. For any minimizer $\Sigma$ and for every injective and open arc $\Gamma \subset \Sigma$, the Right and Left Tangents $T_{R}(x)$ and $T_{L}(x)$ admit some Right and Left limits at every point $x \in \Gamma$ and are semicontinuous. More precisely (4.3) and (4.4) holds for every point $y_{0} \in \Gamma$.

To prove Theorem 31 we will first need a precision about the $C^{1,1}$ regularity result of [10].
Lemma 32. Let $\Sigma_{1}$ be compactly contained in $\Sigma \backslash\left(\mathbb{T}_{\Sigma} \cup \mathbb{E}_{\Sigma}\right)$. Let $x \in \Sigma_{1}$ be such that diam $\left(k^{-1}(x)\right)<$ $\min \left(C, C_{2}\left(\Sigma_{1}\right)\right)$ and let $I \subset \Sigma$ be an "interval" in $\Sigma_{1}$ (i.e. an injective Lipschitz image of $[0,1]$ ) containing $x$ maximal for the property that

$$
\sup _{y \in I} \operatorname{diam}\left(k^{-1}(y)\right) \leq \min \left(C, C_{2}\left(\Sigma_{1}\right)\right)
$$

and let $z \in \bar{I} \backslash I$. Then $\Sigma$ is $C^{1,1}$ regular up to $z$, with Lipschitz constant for the derivative depending only on $\Sigma, \Omega$ and $\mu$, in particular does not depend on $I$ and $x$.

Proof. The Lemma is an easy consequence of the regularity result of [10] so let us give only a sketch of the proof. Assume that $\bar{I}$ is parameterized by an injective map $\gamma:[0,1] \rightarrow \bar{I}$ and assume that $z=\gamma(0)$. We already know by the result of [10] that $\gamma$ is $C^{1,1}$ in the interior of $I$. Moreover, by existence of blow up limits we know that $\gamma^{\prime}$ exists at 0 . Denoting $T_{R}(z)$ the half tangent line at $z$, and using Lemma 11 we have that

$$
\frac{1}{\delta} \sup _{t \in[0, \delta]} \operatorname{dist}\left(\gamma(t), T_{R}(z)\right) \leq C \psi(\gamma((0, \delta])
$$

On the other hand, one can easily prove the estimate

$$
\begin{equation*}
\psi\left(\gamma((0, \delta]) \leq C r \quad \forall \delta<\delta_{0}\right. \tag{4.10}
\end{equation*}
$$

by a small modification of the proof of Proposition 16. Indeed, the only difference is to find an analogous "one-sided" version of inequality (2.7). This is done by delimiting one side of the domain $k^{-1}(\gamma(0, \delta))$ with exactly the same argument as for the original proof of (2.7), and for the other side the rays are delimited by the line orthogonal to the left tangent $T_{L}(z)$. Then the proof of (4.10) follows by the same way as the proof of Proposition 16, the iteration still works since the diameter of transported set is small enough for the points of $\gamma((0, \delta]$ by our assumptions. We left the details to the reader.

Once (4.10) is proved, the desired $C^{1,1}$ regularity follows by the same argument as in the proof Proposition 17.

We are now ready to prove our regularity result.

Proof of Theorem 31. We can assume that we are working on $\Sigma_{1}$ compactly contained in the complement of $\mathbb{T}_{\Sigma}$ and $\mathbb{E}_{\Sigma}$ since we already know by [10] that the curves that compose $\Sigma$ are $C^{1,1}$ in a neighborhood of any triple point. Let $C_{0}$ be the constant depending on $\Omega, \mu$ and $\Sigma$ that comes from the regularity result of [10] (i.e. that implies $C^{1,1}$ regularity whenever $\left.\operatorname{diam}\left(k^{-1}(\{x\})\right)<C_{0}\right)$ and let $C<\min \left(C_{0}, C_{2}\left(\Sigma_{1}\right)\right)$. Since the result is local, when $x_{0}$ is not an endpoint we can work under General assumption 1 in a ball $B\left(x_{0}, r_{0}\right)$, and we can assume that $r_{0}<C / 100$.

Then let us decompose $\Gamma \cap B\left(x_{0}, r_{0}\right)$ in a disjoint union

$$
\Gamma \cap B\left(x_{0}, r_{0}\right):=O_{1} \cup A^{+} \cup A^{-} \cup F
$$

where

$$
\begin{gathered}
O_{1}:=\left\{x \in \Gamma \cap B\left(x_{0}, r_{0}\right) ; \operatorname{diam}\left(t^{-1}(x)\right)<C\right\} \\
A^{+}:=\left\{x \in \Gamma \cap B\left(x_{0}, r_{0}\right) ; \operatorname{diam}\left(t^{-1}(x)^{-}\right)<C / 4 \text { and } \operatorname{diam}\left(t^{-1}(x)^{+}\right) \geq C / 2\right\} \\
A^{-}:=\left\{x \in \Gamma \cap B\left(x_{0}, r_{0}\right) ; \operatorname{diam}\left(t^{-1}(x)^{+}\right)<C / 4 \text { and } \operatorname{diam}\left(t^{-1}(x)^{-}\right) \geq C / 2\right\} \\
F:=\Sigma \cap B\left(x_{0}, r_{0}\right) \backslash\left(O_{1} \cup A^{+} \cup A^{-}\right) .
\end{gathered}
$$

In particular in $F$, all the points have very big transported sets from above and below. By semicontinuity of the diameter of transported set (Proposition 26), we get that $O_{1}, O_{1} \cup A_{+}$and $O_{1} \cup A^{-}$are relatively open sets in $\Gamma \cap B\left(x_{0}, r_{0}\right)$ thus $F$ is relatively closed by definition. We will first prove that taken separately in the interior of all the above sets, $\Sigma$ is $C^{1}$ regular. Indeed by definition of constant $C$, from [10] we directly know that $O_{1}$ is $C_{l o c}^{1,1}$, which means that the maps $T_{L}$ and $T_{R}$ are continuous (even Lipschitz) in $O_{1}$. In the interior of $F, A^{+}$and $A^{-}$, we know that the maps $T_{L}$ and $T_{R}$ are semicontinuous by Proposition 28. Now we have to glue together those sets to prove that $T_{L}$ and $T_{R}$ are semicontinuous everywhere. Up to a change of orientation it is enough to prove the result for only $T_{L}$.

Let us consider $O_{1}$ as a countably union of disjoints "intervals" like

$$
O_{1}:=\sum_{i \in \mathbb{N}} \gamma(] t_{i}, t_{i+1}[)
$$

with $t_{i}<t_{i+1}$. We already know that $\gamma$ is $C^{1,1}$ in each of the $I_{i}:=\gamma\left(\left[t_{i}, t_{i+1}\right]\right)$ (also up the the boundaries of each interval thanks to Lemma 32). Now we will enlarge the set of points in which $T_{L}$ is semicontinuous to progressively achieve the semicontinuity everywhere. Let us start with the open set $A^{+} \cup O_{1}$. Let $y_{0} \in A^{+} \backslash O_{1}$ (otherwise $\gamma$ is $C^{1,1}$ in the neighborhood of $x$ and we have nothing to prove). For $r$ small enough we know that $B(x, r) \cap \Sigma \subset A^{+} \cup O_{1}$. We want to prove
that $T_{L}(y)$ tends to $T_{L}\left(y_{0}\right)$ when $y \rightarrow y_{0}$ and $y<_{\gamma} y_{0}$. We use the same notations as for the proof of Proposition 28, i.e. we denote the oriented angle

$$
\theta(y):=\operatorname{Angle}\left(\nu\left(R_{y_{0}}^{L}\right), \nu\left(R_{y}^{L}\right)\right)
$$

and we want to prove that $\theta(y)$ tends to $\theta\left(y_{0}\right)=0$.
First of all, since $y_{0} \in A^{+}$, for all subsequence $y_{n} \rightarrow y_{0}$ with $y_{n}<_{\gamma} y_{0}$ and such that for all $n>0, y_{n} \in A^{+} \cap B\left(y_{0}, r\right)$ we can prove that $\theta\left(y_{n}\right)$ converges to $\theta\left(y_{0}\right)=0$ arguing exactly as for Proposition 28. This means that for every $\varepsilon>0$ there exists $r_{\varepsilon}<r$ such that

$$
\begin{equation*}
\sup \left\{|\theta(y)| ; y \in A^{+} \cap B\left(y_{0}, r_{\varepsilon}\right) \text { and } y<_{\gamma} y_{0}\right\}<\varepsilon \tag{4.11}
\end{equation*}
$$

Now we have to control the angle for points in $O_{1}$. Since $y_{0} \in A^{+}$, we deduce that

$$
I_{i} \cap B\left(y_{0}, r_{\varepsilon}\right) \neq \emptyset \Rightarrow I_{i} \subset\left\{y ; y<_{\gamma} y_{0}\right\} \text { or } I_{i} \subset\left\{y ; y>_{\gamma} y_{0}\right\} .
$$

Then by Lemma 32, for all $y \in I_{i}$ with $I_{i} \subset O_{1} \cap\left\{y ; y<_{\gamma} y_{0}\right\} \cap B\left(y_{0}, r_{\varepsilon}\right)$, one can estimate (possibly taking a smaller $r_{\varepsilon}$ )

$$
\left|\theta(y)-\theta\left(y_{i}\right)\right| \leq C \mathcal{H}^{1}(I) \leq \varepsilon
$$

where $y_{i}$ is the right hand side bound of the interval $I_{i}$, in other words the point maximal in $I_{i}$ for the order $<_{\gamma}$. Then it comes, for all $y \in O_{1} \cap B\left(x, r_{\varepsilon}\right) \cap\left\{y<_{\gamma} y_{0}\right\}$,

$$
|\theta(y)| \leq\left|\theta(y)-\theta\left(y_{i}\right)\right|+\left|\theta\left(y_{i}\right)\right| \leq 2 \varepsilon
$$

because in particular $y_{i} \in A^{+}$so that we can apply (4.11) to estimate $\left|\theta\left(y_{i}\right)\right|$, and finally we have proved that

$$
\lim _{\substack{y \rightarrow y_{0} \\ y<\gamma y_{0}}} \theta(y)=0
$$

which implies the semicontinuity of $T_{L}$ in $O_{1} \cup A^{+}$.
By a similar argument we can also prove that for every $y_{0} \in O_{1} \cup A^{+}$,

$$
\begin{equation*}
\lim _{\substack{y \rightarrow y_{0} \\ y>\gamma y_{0}}} T_{R}(y)=T_{R}\left(y_{0}\right) . \tag{4.12}
\end{equation*}
$$

Thus reversing the orientation and applying (4.12) we obtain the semicontinuity for $T_{L}$, when $y<_{\gamma} y_{0}$ at every point $y_{0}$ of $A^{-} \cup O_{1}$ as well. Since $A^{ \pm} \cup O_{1}$ are open sets we have proved that $T_{L}$ is semicontinuous in $O_{1} \cup A^{+} \cup A^{-}$. To have the semicontinuity of $T_{L}$ everywhere it remains to prove the semicontinuity at points of $F$.

We already know that $T_{L}$ is semicontinuous in the interior of $F\left(\Sigma\right.$ is even $C^{1,1}$ in this case by Lemma 30). So it is enough to prove semicontinuity at point $y_{0} \in F \cap \overline{A^{+} \cup O_{1} \cup A^{-}}$. But this will be done by the same arguments as before. All we have to prove is that for $r_{\varepsilon}$ small enough and for all points $y \in B\left(y_{0}, r_{\varepsilon}\right) \cap\left\{y<_{\gamma} y_{0}\right\}$, we have that $|\theta(y)| \leq \varepsilon$. Since the point $y_{0} \in F$ is achieved by two large transport rays from above and below at the same time, we can control the angle of tangents for every point $y \in B\left(y_{0}, r_{\varepsilon}\right) \cap\left\{y<_{\gamma} y_{0}\right\}$ by considering the four different cases whenever $y$ lie in $O_{1}, A^{+}, A^{-}$or $F$. Indeed, in each situation between $O_{1}, A^{+}$and $A^{-}$we can use one of the arguments that we already used before to prove semicontinuity in $O_{1} \cup A^{+} \cup A^{-}$, and for points of $F$ we can use either the argument associated to $A^{+}$or the one of $A^{-}$.

In conclusion we have proved that (4.3) holds at every point of $\Gamma$, and the proof of (4.4) works by the same way.

As an immediate consequence of Theorem 31 we can state the following interesting result.
Corollary 33. Let $\Sigma$ be an optimal set for the problem (1.1) and let $B$ be a ball such that $\Sigma \cap B$ contains only ordinary points. Then $\Sigma \cap B$ is locally a $C^{1}$ regular curve.

## 5 Euler-Lagrange equation

We will need the equation of first derivative that one can find in [2]. We refer for instance to [1] page 355 for the definition and classical properties of the tangential divergence $\operatorname{div}^{\Sigma} \Phi$.

Proposition 34. [2] For every compact and connected set $\Sigma \subset \Omega$ and for every $\Phi \in C_{0}^{\infty}\left(\mathbb{R}^{2}, \mathbb{R}^{2}\right)$ one has

$$
\begin{equation*}
\left.\frac{\mathrm{d}}{\mathrm{~d} \varepsilon} \mathcal{F}((\operatorname{Id}+\varepsilon \Phi)(\Sigma))\right|_{\varepsilon=0}=\int_{\mathbb{R}^{2}}\left\langle\Phi(k(x)), \frac{k(x)-x}{|k(x)-x|}\right\rangle \mathrm{d} \mu(x) \tag{5.1}
\end{equation*}
$$

As a consequence, for a given $\lambda>0$, if $\Sigma$ is a minimizer for the functional

$$
\begin{equation*}
\mathcal{G}\left(\Sigma^{\prime}\right):=\int_{\Omega} d\left(x, \Sigma^{\prime}\right) \mathrm{d} \mu(x)+\lambda \mathcal{H}^{1}\left(\Sigma^{\prime}\right) \tag{5.2}
\end{equation*}
$$

over all compact and connected sets $\Sigma^{\prime} \subset \Omega$, then for all $\Phi \in C_{0}^{\infty}\left(\mathbb{R}^{2}, \mathbb{R}^{2}\right)$ one has

$$
\begin{equation*}
\int_{\mathbb{R}^{2}}\left\langle\Phi(k(x)), \frac{k(x)-x}{|k(x)-x|}\right\rangle \mathrm{d} \mu(x)+\lambda \int_{\Omega} \operatorname{div}^{\Sigma} \Phi \mathrm{d} \mathcal{H}^{1}=0 \tag{5.3}
\end{equation*}
$$

We would like to apply equation (5.3) to the minimizers of our functional $\mathcal{F}$ defined in (1.1) with length constraint instead of the penalized functional $\mathcal{G}$. The following Proposition was suggested to the Author by F. Santambrogio and says that one can find a $\lambda_{0}$ such that the two first order equations for the two minimizing problems are the same. To get a similar result one could also try to apply the classical Lagrange multipliers theorem on a suitable Banach space of diffeomorphisms to the functional $J(\varphi):=\mathcal{F}(\varphi(\Sigma))$ but the Fréchet differentiability of such functional at $\varphi_{0}:=\mathrm{Id}$ is not clear. Moreover, despite of the technical difficulties of the proof of the next proposition, the idea is very intuitive and perhaps more instructive as well since it gives the explicit value of $\lambda_{0}$ in terms of measure $\psi$ at any endpoint $x_{0}$.

To be more precise, let $x_{0}$ be an endpoint of $\Sigma$ that we will assume, up to a translation, being the origin. Following [10], let us denote by $\nu$ the image measure of $\mu\left\llcorner k^{-1}\left(\left\{x_{0}\right\}\right)\right.$ by the application $x \mapsto \frac{x}{\|x\|}$ and define the vector

$$
\bar{v}:=\int_{S^{1}} v \mathrm{~d} \nu(v) .
$$

By [10] Theorem 3.2. we know that $\Sigma$ admits a tangent line at $x_{0}$ which direction is given by the vector $-\bar{v}$. Now we define the constant

$$
\begin{equation*}
\lambda_{0}:=\int_{S^{1}} v \cdot \frac{\bar{v}}{\|\bar{v}\|} \mathrm{d} \nu(v)=\|\bar{v}\| . \tag{5.4}
\end{equation*}
$$

Proposition 35. Let $\Sigma$ be a minimizer for the problem (1.1) and $x_{0}$ be one of its endpoint. Then Equation (5.3) holds with $\lambda=\lambda_{0}$ defined in (5.4) and for every $\Phi \in C_{0}^{\infty}\left(\mathbb{R}^{2}, \mathbb{R}^{2}\right)$ compactly supported in the complement of $\left\{x_{0}\right\}$.

The idea is to quantify how much one can win or loose in the functional adding a piece of segment of size $r$ starting at the endpoint $x_{0}$ or erasing a piece of curve of size $r$ from the same endpoint. We will prove that the two operations have a cost in $\lambda_{0} r+o(r)$ and this is the purpose of the two next lemmas. Actually one can find similar computations in the proof of Theorem 3.5. of [10] (with a more elliptic redaction) but we would like to re-write here the arguments in full details for the convenience of the reader.

Let $x_{0}$ be an endpoint of $\Sigma$ that we still assume being the origin, and let $\Phi \in C_{0}^{\infty}\left(\mathbb{R}^{2}, \mathbb{R}^{2}\right)$ be a given diffeomorphism supported in a compact $K$ contained in the complement of $\{0\}$. We denote
$C_{K}^{\infty}$ the family of diffeomorphisms $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{2}, \mathbb{R}^{2}\right)$ supported in $K$ satisfying $\varphi(K) \subset K$. Let us define

$$
\varphi_{\varepsilon}:=\operatorname{Id}+\varepsilon \Phi
$$

Notice that if $\varepsilon$ is small enough, then $\varphi_{\varepsilon} \in C_{K}^{\infty}$. For every $\varepsilon$ we denote $k_{\varepsilon}$ a measurable selection of the projection multimap onto $\Sigma_{\varepsilon}:=\varphi_{\varepsilon}(\Sigma)$.

Let us define now $\nu_{\varepsilon}$ the image measure of $\mu\left\llcorner k_{\varepsilon}^{-1}(\{0\})\right.$ by the application $x \mapsto \frac{x}{\|x\|}$ and introduce the constant

$$
\lambda_{\varepsilon}:=\int_{S^{1}} v \cdot \frac{\bar{v}}{\|\bar{v}\|} \mathrm{d} \nu_{\varepsilon}(v)
$$

It is not difficult to see that $\lambda_{\varepsilon} \rightarrow \lambda_{0}$ when $\varepsilon \rightarrow 0$.
Lemma 36. One can find an $r_{0}$ such that for every $r<r_{0}$ there exists a set $\Sigma_{\varepsilon}^{r}$ such that

$$
\begin{gather*}
\Sigma_{\varepsilon}^{r} \cap K=\Sigma_{\varepsilon}, \quad \mathcal{H}^{1}\left(\Sigma_{\varepsilon}^{r}\right)=\mathcal{H}^{1}\left(\Sigma_{\varepsilon}\right)+r \quad \text { and } \\
\mathcal{F}\left(\Sigma_{\varepsilon}\right)-\mathcal{F}\left(\Sigma_{\varepsilon}^{r}\right)=r \lambda_{\varepsilon}+o(r) \tag{5.5}
\end{gather*}
$$

where $o(r)$ depends on $\Phi$ but not on $\varepsilon$.
Proof. Up to a rotation we can assume that $\bar{v}=e_{1}$. Defining the line $L:=\mathbb{R}^{-} . \bar{v}$, by [10] we know that

$$
\frac{1}{r} d_{H}\left(\Sigma \cap B\left(x_{0}, r\right), L \cap B\left(x_{0}, r\right)\right) \rightarrow 0
$$

when $r \rightarrow 0$, and this is the same for $\varphi(\Sigma)$ for all $\varphi \in C_{K}^{\infty}$ since they do not move any points near the origin. Let $P^{+}$be the half space

$$
\begin{equation*}
P^{+}:=\left\{(x, y) \in \mathbb{R}^{2} ; x \geq 0\right\} \tag{5.6}
\end{equation*}
$$

We claim that for all $\varepsilon$,

$$
k_{\varepsilon}^{-1}(\{0\}) \subseteq P^{+}
$$

Indeed, suppose the contrary, namely that there exists a point $x$ such that $k_{\varepsilon}(x)=0$ and $x \notin P^{+}$. Then, since $\{0\}$ admits $\mathbb{R}^{-} e_{1}$ as left-tangent line it would be better for $x$ to be projected onto a point $y \in \Sigma \cap \partial B(0, s)$ for $s$ small enough which is a contradiction.

We define

$$
\Sigma_{\varepsilon}^{r}:=\Sigma_{\varepsilon} \cup L_{r}^{+}
$$

where $L_{r}^{+}:=[0, r] \times\{0\}$. We have to compute the winning in the functional $\mathcal{F}$ in terms of $r$ but independently from $\varepsilon$ small enough, say less than $\varepsilon_{0}$.

Let $D_{r}:=\left(L_{r}^{+} \times \mathbb{R}\right) \cap \Omega$. For every point $x \in P^{+} \backslash D_{r}$ one has $d\left(x, L_{r}^{+}\right)=d\left(x, x_{r}\right)$ where $x_{r}:=(r, 0)$. Then, a simple computation yields, for $r \rightarrow 0$

$$
\begin{equation*}
\left\|x-x_{r}\right\|^{2}=\|x\|^{2}-2\left\langle x, x_{r}\right\rangle+o(r)=\|x\|^{2}\left(1-2\left\langle\frac{x}{\|x\|^{2}}, x_{r}\right\rangle+o(r)\right) \tag{5.7}
\end{equation*}
$$

Therefore, we obtain that for all $x \in k_{\varepsilon}^{-1}(\{0\}) \backslash D_{r}$,

$$
d\left(x, \Sigma_{\varepsilon}\right)-d\left(x, \Sigma_{\varepsilon}^{r}\right)=\|x\|-\left\|x-x_{r}\right\|=r\left\langle\frac{x}{\|x\|}, e_{1}\right\rangle+o(r)
$$

where $o(r)$ does not depend on $\varepsilon$. On the other hand, let us define

$$
A_{r}^{\varepsilon}:=\left\{x \in \Omega \backslash k_{\varepsilon}^{-1}(\{0\}) ; d\left(x, \Sigma_{\varepsilon}^{r}\right)=d\left(x, L_{r}^{+}\right)\right\}
$$

and

$$
A_{r}:=\bigcup_{\varepsilon \leq \varepsilon_{0}} A_{r}^{\varepsilon}
$$

We claim that

$$
\begin{equation*}
\sup _{\varepsilon \leq \varepsilon_{0}} \int_{A_{r}^{\varepsilon}} d\left(x, \Sigma_{\varepsilon}\right)-d\left(x, \Sigma_{\varepsilon}^{r}\right) \mathrm{d} \mu(x)=o(r) . \tag{5.8}
\end{equation*}
$$

To see this, observe that $A_{r}^{\varepsilon} \subset P^{+}$thus, using (5.7), for $x \in A_{r}^{\varepsilon}$ we have

$$
0 \leq d\left(x, \Sigma_{\varepsilon}\right)-d\left(x, \Sigma_{\varepsilon}^{r}\right) \leq\|x\|-d\left(x, \Sigma_{\varepsilon}^{r}\right)=\|x\|-d\left(x, x_{r}\right)=r\left\langle\frac{x}{\|x\|}, e_{1}\right\rangle+o(r)
$$

where $o(r)$ does not depend on $\varepsilon$. Then

$$
\left|\int_{A_{r}^{\varepsilon}} d\left(x, \Sigma_{\varepsilon}\right)-d\left(x, \Sigma_{\varepsilon}^{r}\right) \mathrm{d} \mu(x)\right| \leq r \mu\left(A_{r}^{\varepsilon}\right)+o(r) \leq r \mu\left(A_{r}\right)+o(r)
$$

and we conclude by observing that $\mu\left(A_{r}\right) \rightarrow 0$ thus (5.8) is true.
Finally, since $\int_{D_{r}} d\left(x, \Sigma_{\varepsilon}\right)-d\left(x, \Sigma_{\varepsilon}^{r}\right)=o(r)$ we have

$$
\begin{aligned}
\mathcal{F}\left(\Sigma_{\varepsilon}\right)-\mathcal{F}\left(\Sigma_{\varepsilon}^{r}\right) & =\int_{k_{\varepsilon}^{-1}(\{0\}) \backslash D_{r}} d\left(x, \Sigma_{\varepsilon}\right)-d\left(x, \Sigma_{\varepsilon}^{r}\right) \mathrm{d} \mu(x)+\int_{A_{r}^{\varepsilon}} d\left(x, \Sigma_{\varepsilon}\right)-d\left(x, \Sigma_{\varepsilon}^{r}\right) \mathrm{d} \mu(x)+o(r) \\
& =\lambda_{\varepsilon} r+o(r)
\end{aligned}
$$

which proves the Lemma.

Now we want to do the same while removing this time from $\Sigma_{\varepsilon}$ a piece of size $r$, and estimate the loss in terms of $r$ independently from $\varepsilon$. Compared to Lemma 36 we will this time prove only an inequality which will be enough to prove Proposition 35.

Lemma 37. One can find an $r_{0}$ such that for every $r<r_{0}$ there exists a set $\Sigma_{\varepsilon}^{r}$ such that

$$
\begin{gather*}
\Sigma_{\varepsilon}^{r} \cap K=\Sigma_{\varepsilon}, \quad \mathcal{H}^{1}\left(\Sigma_{\varepsilon}^{r}\right)=\mathcal{H}^{1}\left(\Sigma_{\varepsilon}\right)-r \quad \text { and } \\
F\left(\Sigma_{\varepsilon}^{r}\right)-F\left(\Sigma_{\varepsilon}\right) \leq r \lambda_{\varepsilon}+o(r) \tag{5.9}
\end{gather*}
$$

where $o(r)$ depends on $\Phi$ but not on $\varepsilon$.

Proof. The proof is very similar to the one of Lemma 36. The only difference is that here we don't consider a piece of segment but a piece of curve that converges to a segment with speed $o(r)$.

Let $\gamma:[0, T] \rightarrow \mathbb{R}^{2}$ be a parametrization by arclength of the Lipschitz curve starting at $x_{0}$, such that $\gamma(0)=x_{0}$ and $\gamma(T)$ is a triple point or endpoint. By [10], for $t$ small enough, we know that

$$
\sharp\left\{\partial B\left(x_{0}, t\right) \cap \Sigma\right\}=1 .
$$

We deduce the existence of a radius $t_{r}$ defined by $\Sigma \cap \partial B\left(x_{0}, t_{r}\right)=\gamma(r)$ and satisfying $\gamma([0, r])=$ $\Sigma \cap B\left(x_{0}, t_{r}\right)$. Moreover since the blow up limit at $x_{0}$ is a radius we also know that $r=t_{r}+o(r)$ when $r \rightarrow 0$. We assume $r_{0}$ small enough in such a way that $B\left(x, t_{r}\right) \cap K=\emptyset$ for all $r<r_{0}$ and we define

$$
\Sigma_{\varepsilon}^{r}:=\Sigma_{\varepsilon} \backslash \gamma([0, r]) .
$$

By construction we automatically get $\mathcal{H}^{1}\left(\Sigma_{\varepsilon}^{r}\right)=\mathcal{H}^{1}\left(\Sigma_{\varepsilon}\right)-r$.
Now we want to compute what we have lost in the functional $\mathcal{F}$. We still suppose $x_{0}=\{0\}$ and the tangent line at $x_{0}$ being $\mathbb{R}^{-} . e_{1}$. We denote $P^{+}$the half space defined in (5.6). As before,
we know that for every $\varepsilon$ small enough, $k_{\varepsilon}^{-1}(\{0\}) \subset P^{+}$. Let us denote $x_{r}:=\Sigma \cap \partial B\left(0, t_{r}\right)$ and $\bar{x}_{r}=p_{1}\left(x_{r}\right)$ where $p_{1}$ is the projection on the first axis. We know that $\left\|x_{r}-\bar{x}_{r}\right\|=o(r)$ and $\left\|\bar{x}_{r}\right\|=t_{r}=r-o(r)$. By a computation similar to (5.7) and using that $o(r)=o\left(t_{r}\right)$ we obtain that for all $x \in P^{+}$,

$$
\left\|x-\bar{x}_{r}\right\|^{2}=\|x\|^{2}\left(1-2\left\langle\frac{x}{\|x\|^{2}}, \bar{x}_{r}\right\rangle+o(r)\right)
$$

which implies

$$
\left\|x-\bar{x}_{r}\right\|-\|x\|=r\left\langle\frac{x}{\|x\|}, e_{1}\right\rangle+o(r)
$$

Then, since $\left\|x_{r}-\bar{x}_{r}\right\|=o(r)$ we deduce

$$
\left\|x-x_{r}\right\|-\|x\|=r\left\langle\frac{x}{\|x\|}, e_{1}\right\rangle+o(r)
$$

Now we compute

$$
\begin{aligned}
\mathcal{F}\left(\Sigma_{\varepsilon}^{r}\right)-\mathcal{F}\left(\Sigma_{\varepsilon}\right) & =\int_{k_{\varepsilon}^{-1}\left(B\left(0, t_{r}\right)\right)} d\left(x, \Sigma_{\varepsilon}^{r}\right)-d\left(x, \Sigma_{\varepsilon}\right) \mathrm{d} \mu(x) \\
& \leq \int_{k_{\varepsilon}^{-1}(\{0\})} d\left(x, x_{r}\right)-d(x, 0) \mathrm{d} \mu(x)+r \int_{k_{\varepsilon}^{-1}\left(B\left(0, t_{r}\right) \backslash\{0\}\right)} \mathrm{d} \mu(x) \\
& \leq \int_{k_{\varepsilon}^{-1}(\{0\})}\left\|x-x_{r}\right\|-\|x\| \mathrm{d} \mu(x)+r \psi\left(B\left(0, t_{r}\right) \backslash\{0\}\right) \\
& \leq r \lambda_{\varepsilon}+o(r)
\end{aligned}
$$

which ends the proof.

We are now ready to prove Proposition 35.
Proof of Proposition 35. Let $\Phi$ be given and consider $\Sigma_{\varepsilon}:=\varphi_{\varepsilon}(\Sigma)$ where as before $\varphi_{\varepsilon}=\operatorname{Id}+\varepsilon \Phi$. Assume first that $\mathcal{H}^{1}\left(\Sigma_{\varepsilon}\right)-\mathcal{H}^{1}(\Sigma)=-r_{\varepsilon}<0$. Then, denoting $\Sigma_{\varepsilon}^{+}$the set given by Lemma 36 applied with $r:=r_{\varepsilon}$ and using that $\Sigma$ is a minimizer for $\mathcal{F}$ we obtain that

$$
\begin{aligned}
\mathcal{F}(\Sigma) & \leq \mathcal{F}\left(\Sigma_{\varepsilon}^{+}\right) \\
& =\mathcal{F}\left(\Sigma_{\varepsilon}\right)-\lambda_{\varepsilon} r_{\varepsilon}-o\left(r_{\varepsilon}\right) \\
& =\mathcal{F}\left(\Sigma_{\varepsilon}\right)+\lambda_{\varepsilon}\left[\mathcal{H}^{1}\left(\Sigma_{\varepsilon}\right)-\mathcal{H}^{1}(\Sigma)\right]+o\left(r_{\varepsilon}\right)
\end{aligned}
$$

Now if $\mathcal{H}^{1}\left(\Sigma_{\varepsilon}\right)-\mathcal{H}^{1}(\Sigma)=r_{\varepsilon}>0$ we can use Lemma 37 to find a set $\Sigma_{\varepsilon}^{-}$satisfying the length constraint so by minimality of $\Sigma$,

$$
\begin{aligned}
\mathcal{F}(\Sigma) & \leq \mathcal{F}\left(\Sigma_{\varepsilon}^{-}\right) \\
& \leq \mathcal{F}\left(\Sigma_{\varepsilon}\right)+\lambda_{\varepsilon} r_{\varepsilon}+o\left(r_{\varepsilon}\right) \\
& \leq \mathcal{F}\left(\Sigma_{\varepsilon}\right)+\lambda_{\varepsilon}\left[\mathcal{H}^{1}\left(\Sigma_{\varepsilon}\right)-\mathcal{H}^{1}(\Sigma)\right]+o\left(r_{\varepsilon}\right)
\end{aligned}
$$

In conclusion, using that $r_{\varepsilon}=O(\varepsilon)$ and that $\lambda_{\varepsilon} \rightarrow \lambda_{0}$ we have proved for every $\varepsilon$,

$$
\mathcal{F}(\Sigma)-\mathcal{F}\left(\Sigma_{\varepsilon}\right)+\lambda_{0}\left[\mathcal{H}^{1}(\Sigma)-\mathcal{H}^{1}\left(\Sigma_{\varepsilon}\right)\right] \leq o(\varepsilon)
$$

Now dividing by $\pm \varepsilon$ and passing to the limit, we obtain

$$
\left.\frac{\mathrm{d}}{\mathrm{~d} \varepsilon}\left[\mathcal{F}\left(\Sigma_{\varepsilon}\right)+\lambda_{0} \mathcal{H}^{1}\left(\Sigma_{\varepsilon}\right)\right]\right|_{\varepsilon=0}=0
$$

and we conclude using (5.1) and the classical fact that the derivative of $\mathcal{H}^{1}\left(\Sigma_{\varepsilon}\right)$ is the mean curvature.

Remark 38. The constant $\lambda_{0}$ does not depend on the choice of endpoint $x_{0}$. Indeed, if the constant $\lambda_{1}$ associated to a different endpoint $x_{1} \neq x_{0}$ was greater or lower, one could get a contradiction with the minimality of $\Sigma$ adding or erasing a little piece of curve at one endpoint and do the opposite operation at the other endpoint in order to diminish the functional $\mathcal{F}$.

## 6 Tilt estimate

In this section we control the oscillation of the tangent lines $\pi_{x}$ to $\Sigma$ with respect to a fixed line $\pi$, also called "the tilt". When $\pi_{1}$ and $\pi_{2}$ are two lines in $\mathbb{R}^{2}$, we denote by $\alpha\left(\pi_{1}, \pi_{2}\right) \in\left[0, \frac{\pi}{2}\right]$ the smallest angle between them.

For any $x \in \Sigma \backslash\left(\mathbb{T}_{\Sigma} \cup \mathbb{E}_{\Sigma}\right)$ and $r<r(x)$ we denote by $\pi_{x, r}$ the line that contains the segment $\left[z, z^{\prime}\right]$, where $z$ and $z^{\prime}$ are, as usual, the two points of $\partial B(x, r) \cap \Sigma$. For $\mathcal{H}^{1}$-a.e. $y \in \Sigma$ we also denote by $\pi_{y}$ the approximate tangent line centered at $y$. Finally, we denote $\alpha(y):=\alpha\left(\pi_{y}, \pi_{x, r}\right)$. The definition of $\alpha(y)$ depends in particular on $x$ and $r$ but we do not make it explicit to lighten the notations. A first easy estimate is the following

$$
\begin{equation*}
\int_{\Sigma \cap B(x, r)} 1-\cos (\alpha(y)) \mathrm{d} \mathcal{H}^{1}(y) \leq \operatorname{Cr} \psi(x, r) \beta(x, r) . \tag{6.1}
\end{equation*}
$$

Indeed, let $\gamma:[-T, T]$ be a parametrization of $\Sigma_{r}:=\Sigma \cap B(x, r)$. Assume without loss of generality that the segment $S:=\left[z, z^{\prime}\right]$ is contained in the first axis of $\mathbb{R}^{2}$ and that $\gamma(-T)=z, \gamma(T)=z^{\prime}$ with $z<z^{\prime}$. Then by setting $\gamma(t):=(x(t), y(t))$, using Lemma 11 we have

$$
\begin{aligned}
\int_{-T}^{T} \sqrt{x^{\prime}(t)^{2}+y^{\prime}(t)^{2}}-x^{\prime}(t) d t & =\mathcal{H}^{1}\left(\Sigma_{r}\right)-\left(z^{\prime}-z\right) \\
& =\mathcal{H}^{1}\left(\Sigma_{r}\right)-\mathcal{H}^{1}(S) \\
& \leq \operatorname{C\psi }(x, r) d_{H}\left(\Sigma_{r}, S\right) \\
& \leq \operatorname{Cr} \psi(x, r) \beta(x, r)
\end{aligned}
$$

On the other hand the area formula shows that

$$
\begin{aligned}
\int_{-T}^{T} \sqrt{x^{\prime}(t)^{2}+y^{\prime}(t)^{2}}-x^{\prime}(t) \mathrm{d} t & =\int_{-T}^{T}\left(1-\frac{x^{\prime}(t)}{\sqrt{x^{\prime}(t)^{2}+y^{\prime}(t)^{2}}}\right) \sqrt{x^{\prime}(t)^{2}+y^{\prime}(t)^{2}} \mathrm{~d} t \\
& =\int_{\Sigma_{r}}\left(1-\left\langle\tau(y), e_{1}\right\rangle\right) \mathrm{d} \mathcal{H}^{1}(y) \\
& \geq \int_{\Sigma \cap B(x, r)} 1-\cos (\alpha(y)) \mathrm{d} \mathcal{H}^{1}(y)
\end{aligned}
$$

where $\tau(y)$ is the unit tangent vector at point $x$ (oriented by the parametrization $\gamma$ ) and $e_{1}$ is the first vector of basis, so (6.1) follows.

The next proposition gives a slightly better estimate than (6.1) proved by a variational argument.

Proposition 39. For all $\tau \in(0,1), x \in \Sigma \backslash\left(\mathbb{T}_{\Sigma} \cup \mathbb{E}_{\Sigma}\right)$ and $r<r(x)$ we have

$$
\int_{\Sigma \cap B(x, \tau r)} \sin ^{2}(\alpha(y)) \mathrm{d} \mathcal{H}^{1}(y) \leq C(\tau) r \psi(x, r) \beta(x, r)
$$

where $\alpha(y)$ is the angle between $\pi_{y}$ and $\pi_{x, r}$.

Proof. Without loss of generality we may assume that $\pi:=\pi_{x, r}$ is the first axis. Let us choose $\Phi(z):=\eta(z)^{2}\left(\pi^{\perp}(z)\right)$, where $\pi^{\perp}$ is the projection on the second axis and where $\eta \in C_{c}^{1}(B(x, r))$, $0 \leq \eta \leq 1, \eta=1$ on $B(\tau r)$ and $|\nabla \eta| \leq 2 / r(1-\tau)$.

For every line $\pi^{\prime}$ let $e_{\pi^{\prime}}$ be a unit vector in the direction of $\pi^{\prime}$ and denote by $M_{\pi^{\prime}}$ the orthogonal projection on $\mathbb{R} e_{\pi^{\prime}}$. We maintain that

$$
\begin{equation*}
\left\|M_{\pi}-M_{\pi^{\prime}}\right\|=\sin \left(\alpha\left(\pi^{\prime}, \pi\right)\right) \tag{6.2}
\end{equation*}
$$

where the norm in the left side is the euclidian norm of linear operators and $\alpha\left(\pi^{\prime}, \pi\right) \in\left[0, \frac{\pi}{2}\right]$ is, as usual, the smallest angle between the lines $\bar{\pi}^{\prime}$ and $\pi$. To show (6.2), let $z \in \mathbb{R}^{2}$ be of unit norm and let $(a, b)$ be its coefficients in the orthonormal basis $\left\{e_{\pi}, e_{\pi^{\perp}}\right\}$. Then $\left\|M_{\pi^{\prime}}(z)-M_{\pi}(z)\right\|^{2}=$ $\left\|a\left(M_{\pi^{\prime}}\left(e_{\pi}\right)-e_{\pi}\right)+b M_{\pi^{\prime}}\left(e_{\pi^{\perp}}\right)\right\|^{2}=\left\|b M_{\pi^{\prime}}\left(e_{\pi^{\perp}}\right)-a M_{\pi^{\prime}}\left(e_{\pi}\right)\right\|^{2}=\left(a^{2}+b^{2}\right)\left\|M_{\pi^{\prime}}\left(e_{\pi^{\perp}}\right)\right\|^{2}=\left\langle e_{\pi^{\prime}}, e_{\pi^{\perp}}\right\rangle^{2}=$ $\cos ^{2}\left(\alpha\left(\pi^{\prime}, \pi^{\perp}\right)\right)=\sin ^{2}\left(\alpha\left(\pi^{\prime}, \pi\right)\right)$, so (6.2) holds.

Now let us compute the tangential divergence of $\Phi$. Since the first component of $\Phi$ is 0 and the second is equal to $\eta(z)^{2} z_{2}$ we have

$$
\operatorname{div}^{\pi^{\prime}} \Phi(z)=\left\langle\nabla^{\pi^{\prime}}\left(\eta(z)^{2} z_{2}\right), e_{2}\right\rangle
$$

and

$$
\nabla^{\pi^{\prime}}\left(\eta(z)^{2} z_{2}\right)=\left[2 \eta(z) z_{2}\left\langle\nabla \eta(z), e_{\pi^{\prime}}\right\rangle+\eta(z)^{2}\left\langle e_{2}, e_{\pi^{\prime}}\right\rangle\right] \cdot e_{\pi^{\prime}}
$$

Thus

$$
\begin{aligned}
\operatorname{div}^{\pi^{\prime}} \Phi(z) & =2 \eta(z) z_{2}\left\langle\nabla \eta(z), e_{\pi^{\prime}}\right\rangle\left\langle e_{2}, e_{\pi^{\prime}}\right\rangle+\eta(z)^{2}\left\langle e_{2}, e_{\pi^{\prime}}\right\rangle^{2} \\
& =2 \eta(z)\left\langle M_{\pi^{\prime}}(\nabla \eta(z)), \pi^{\perp}(z)\right\rangle+\eta(z)^{2} \sin ^{2}\left(\alpha\left(\pi, \pi^{\prime}\right)\right) \\
& =2 \eta(z)\left\langle\left(M_{\pi^{\prime}}-M_{\pi}\right)(\nabla \eta(z)), \pi^{\perp}(z)\right\rangle+\eta(z)^{2} \sin ^{2}\left(\alpha\left(\pi, \pi^{\prime}\right)\right) \\
& \geq \eta(z)^{2} \sin ^{2}\left(\alpha\left(\pi, \pi^{\prime}\right)\right)-\left[\frac{1}{t} \eta(z)^{2}\left\|M_{\pi^{\prime}}-M_{\pi}\right\|^{2}\|\nabla \eta(z)\|^{2}+t\left|\pi^{\perp}(z)\right|^{2}\right]
\end{aligned}
$$

hence setting $t:=2\|\nabla \eta(z)\|^{2}$ and using (6.2) we get

$$
\begin{equation*}
\operatorname{div}^{\pi^{\prime}} \Phi(z) \geq \frac{1}{2} \eta(z)^{2} \sin ^{2}\left(\alpha\left(\pi, \pi^{\prime}\right)\right)-\frac{8}{r^{2}(1-\tau)^{2}}\left\|\pi^{\perp}(z)\right\|^{2} \tag{6.3}
\end{equation*}
$$

Therefore, applying the above inequality with $\pi^{\prime}$ the approximate tangent line at point $x$ and recalling (by 2.1) that $\mathcal{H}^{1}(B(x, r) \cap \Sigma) \leq 3 \pi r$ we obtain

$$
\begin{aligned}
\int_{B(x, \tau r)} \sin ^{2}(\alpha(z)) \mathrm{d} \mathcal{H}^{1} & \leq 2 \int_{B(x, r) \cap \Sigma} \operatorname{div}^{\Sigma} \Phi \mathrm{d} \mathcal{H}^{1}+\frac{C}{(1-\tau)^{2}} r \beta(x, r)^{2} \\
& \leq 2 \int_{B(x, r) \cap \Sigma} \operatorname{div}^{\Sigma} \Phi \mathrm{d} \mathcal{H}^{1}+C(\tau) r \beta(x, r) \psi(x, r)
\end{aligned}
$$

by (2.6). On the other hand, since $B(x, r)$ does not contain any endpoint, by Proposition 35 we have that

$$
\begin{aligned}
\int_{\Omega} \operatorname{div}^{\Sigma} \Phi \mathrm{d} \mathcal{H}^{1} & \leq \frac{1}{\lambda_{0}} \int_{\mathbb{R}^{2}}\left|\left\langle\Phi(k(z)), \frac{k(z)-z}{|k(z)-z|}\right\rangle\right| \mathrm{d} \mu(x) \\
& \leq \int_{k^{-1}(B(x, r))} \eta(k(z))^{2}\left\|\pi^{\perp}(k(z))\right\| \mathrm{d} \mu(z) \\
& \leq \operatorname{Cr} \beta(x, r) \psi(x, r)
\end{aligned}
$$

so the proof is complete.

## $7 \quad \Sigma$ is locally a Lipschitz graph

In this last section we prove that away from triple points $\Sigma$ is locally a graph. We begin with some precisions about corner points.

### 7.1 About the aperture of corners

Using the first order equation, one can rely the aperture of any corner point $x_{0}$ in terms of measure $\psi$. Following the notations of Section 39, for any atom $x \in \Sigma$ for the measure $\psi$ (i.e. $x$ is either a corner point of endpoint) we define $\nu_{x}$ the image measure of $\mu\left\llcorner k^{-1}(x)\right.$ by the application $y \mapsto \frac{y-x}{\|y-x\|}$ and the vector

$$
\bar{v}(x):=\int_{S^{1}+x}(v-x) \mathrm{d} \nu_{x}(v) .
$$

Then we denote

$$
\lambda(x):=\|\bar{v}(x)\| .
$$

It is clear that $\lambda(x) \leq \psi(\{x\})$ and recall that $\lambda_{0}:=\lambda\left(x_{0}\right)$ where $x_{0}$ is any endpoint of $\Sigma$. For any corner point $x$ let us denote $\theta(x)$ the smallest angle between the two rays of the bow up limit at point $x$. Then, by the proof of Theorem 3.7. of [10] we have the following very nice identity :

$$
\lambda_{0} \cos \left(\frac{\theta(x)}{2}\right)=\lambda(x)
$$

The next proposition gives a lower bound on the aperture of any corner point and will be needed to find some pieces of graphs. This is probably a well known fact but as far as the author knows, it was never explicitly written before in the literature.

Proposition 40. For any corner point $x$ of $\Sigma$ it holds $\theta(x) \geq \frac{2 \pi}{3}$.
Proof. The proof is fairly simple, relying on the fact that if the aperture is too small, one can replace $\Sigma$ by a suitable Steiner connection to win some length. Indeed, let $x$ be a corner point with aperture $\theta:=\theta(x)<\frac{2 \pi}{3}$. For any $r \in(0, r(x))$ let $z_{r}$ and $z_{r}^{\prime}$ be the two points of $\Sigma \cap \partial B(x, r)$ and let $S_{r}$ be the Steiner minimal set connecting the points $z_{r}, z_{r}^{\prime}$ and $x$.


Since the blow up limit converges to a union of two rays of aperture $\theta<\frac{2 \pi}{3}$, we deduce that

$$
\mathcal{H}^{1}(\Sigma \cap B(x, r))=2 r+o(r)
$$

and

$$
\mathcal{H}^{1}\left(S_{r}\right)=l(\theta) r+o(r)
$$

where $l(\theta)$ is the length of the Steiner connection corresponding to an exact angle of aperture $\theta$ in the unit ball. In particular $l(\theta)<2$, and for $r$ small enough we have that $\mathcal{H}^{1}(\Sigma \cap B(x, r))>\mathcal{H}^{1}\left(S_{r}\right)$. This allows us to take as a competitor for $\Sigma$ the set

$$
\Sigma_{r}:=\Sigma \backslash B(x, r) \cup S_{r} \cup L_{r}^{+}
$$

where $L_{r}^{+}$is a piece of segment added at any endpoint of $\Sigma$ as in the proof of Lemma 36, and satisfying

$$
\mathcal{H}^{1}\left(L_{r}^{+}\right)=\mathcal{H}^{1}(\Sigma \cap B(x, r))-\mathcal{H}^{1}\left(S_{r}\right)=(2-l(\theta)) r+o(r) .
$$

Then it comes

$$
\begin{aligned}
\mathcal{F}(\Sigma) & \leq \mathcal{F}\left(\Sigma_{r}\right) \\
& \leq \mathcal{F}(\Sigma)+r \psi(B(x, r) \backslash\{x\})-\lambda_{0}[2-l(\theta)] r+o(r) \\
\lambda_{0}[2-l(\theta)] r & \leq r \psi(B(x, r) \backslash\{x\})+o(r)
\end{aligned}
$$

which implies a contradiction for $r$ small enough because $\psi(B(x, r) \backslash\{x\})$ tends to 0 .

### 7.2 Construction of the graph

A consequence of Theorem 31, is that $\Sigma$ is locally a graph. We still denote $\mathbb{T}_{\Sigma}$ the set of triple points. For any ordinary point we denote $\pi_{y}$ the tangent line at $y$ (which is defined $\mathcal{H}^{1}$-a.e. on $\Sigma$ ), and when $y$ is a corner point we also denote $\pi_{y}$ the line through $y$ orthogonal to the mediatrice of the corner resulting from taking the blow up limit at $y$.

Proposition 41. For all $x \in \Sigma \backslash\left(\mathbb{T}_{\Sigma} \cup \mathbb{E}_{\Sigma}\right)$ there exists $r$ depending on $x$, and there exists $a$ 5 -Lipschitz function $f: \pi_{x} \rightarrow \mathbb{R}$ with graph denoted by $\Gamma_{f}:=\left\{(t, f(t)) ; t \in \pi_{x}\right\}$ which has the following properties

$$
\begin{align*}
\Sigma \cap B(x, r / 4) & =\Gamma_{f} \cap B(x, r / 4)  \tag{7.1}\\
\int_{\pi_{x} \cap B\left(x, \frac{r}{16}\right)}\left|f^{\prime}(t)\right|^{2} d t & \leq C r \psi(x, r)^{2} \tag{7.2}
\end{align*}
$$

Proof. Let $\gamma:=[-T, T] \rightarrow \mathbb{R}^{2}$ be a parametrization of $\Sigma_{r}:=\Sigma \cap B(x, r)$, where $r<r(x)$ the usual radius given by Lemma 13 . Assume without loss of generality that $\pi_{x}$ is the first axis of $\mathbb{R}^{2} x$ is the origin. We denote $p_{1}$ the orthogonal projection on the first axis, and $\left(\gamma_{1}, \gamma_{2}\right)$ the coordinates of $\gamma$.

For $\mathcal{H}^{1}$-a.e. $y \in \Sigma \cap B(x, r)$ we denote $\alpha(y)$ the smallest non oriented angle between the lines $\pi_{y}$ and $\pi_{x}$. In particular by the area formula one has

$$
\int_{\gamma(a, b)} \sin (\alpha(y))^{2} d \mathcal{H}^{1}(y)=\int_{a}^{b} \frac{\gamma_{2}^{\prime}(t)^{2}}{\sqrt{\gamma_{1}^{\prime}(t)^{2}+\gamma_{2}^{\prime}(t)^{2}}} d t
$$

From Theorem 31 we know that for every $\varepsilon>0$ there exists a radius $r$ such that

$$
\left|\sin ^{2}(\alpha(y))-\sin ^{2}\left(\frac{\pi-\theta(x)}{2}\right)\right| \leq \varepsilon \quad \text { for } \mathcal{H}^{1} \text { a.e. } y \in \Sigma \cap B(x, r)
$$

which implies using Proposition 40 that

$$
\sin ^{2}(\alpha(y)) \leq \frac{3}{4}+\varepsilon \quad \text { for } \mathcal{H}^{1} \text { a.e. } y \in \Sigma \cap B(x, r)
$$

Let us choose $\varepsilon=1 / 400$. Since $\Sigma$ admits two half tangent lines at $x$, up to a smaller choice of $r$ we may assume that $\gamma([-T, 0]) \cap B(x, r) \subset \mathbb{R}_{*}^{-} \times \mathbb{R}, \gamma([0, T]) \cap B(x, r) \subset \mathbb{R}_{*}^{+} \times \mathbb{R}$ and $\gamma([-T, T]) \cap\{0\} \times \mathbb{R}=\{x\}$. Taking if necessary a smaller radius $r$ we may also assume that $C \psi(\gamma([-T, T] \backslash\{0\}))^{2} \leq 1 / 400$ and $d_{H}\left(\gamma([-T, T], L \cap B(x, r)) \leq r / 400\right.$ where $L:=T_{R}(x) \cup T_{L}(x)$ is the blow up limit at point $x$. Then using (2.2), for every $a, b \in[0, T]$ such that $\gamma([a, b]) \subset B(x, r)$ we have

$$
\begin{align*}
\int_{a}^{b} \frac{\gamma_{2}^{\prime}(t)^{2}}{\sqrt{\gamma_{1}^{\prime}(t)^{2}+\gamma_{2}^{\prime}(t)^{2}}} d t & =\int_{\gamma([a, b])} \sin (\alpha(y))^{2} \mathcal{H}^{1}(y) \\
& \leq(3 / 4+1 / 400) \mathcal{H}^{1}(\gamma([a, b])) \\
& \leq(8 / 10)|\gamma(a)-\gamma(b)| \tag{7.3}
\end{align*}
$$

because under our assumptions, $\mathcal{H}^{1}(\gamma([a, b])) \leq\left(1+\frac{1}{400}\right)|\gamma(a)-\gamma(b)|$. Now we denote $F:=$ $\Sigma \cap B(x, r / 4)$. We claim that

$$
\begin{equation*}
\sharp\left\{z^{\prime} \in F ; p_{1}(z)=p_{1}\left(z^{\prime}\right)\right\}=1 \quad \forall z \in F . \tag{7.4}
\end{equation*}
$$

Let us denote $F^{-}:=\gamma([-T, 0]) \cap B(x, r / 4)$ and $F^{+}:=\gamma([0, T]) \cap B(x, r / 4)$. To prove (7.4), it is enough to prove that

$$
\sharp\left\{z^{\prime} \in F^{ \pm} ; p_{1}(z)=p_{1}\left(z^{\prime}\right)\right\}=1 \quad \forall z \in F^{ \pm}
$$

It suffice to consider the case of $F^{+}$(the proof for $F^{-}$will follow by the same way). Assume the contrary, namely that there is $z, z^{\prime} \in F^{+}$such that $p_{1}(z)=p_{1}\left(z^{\prime}\right)$. Let $I \subset[0, T]$ be such that $\gamma(I)$ is the arc that goes from $z$ to $z^{\prime}$ and fix $r_{0}:=\left|z-z^{\prime}\right| \leq r / 2$. We know that $\gamma(I) \cap \partial B\left(z, r_{0}\right)=z^{\prime}$, in particular $\gamma(I)$ is contained in $B\left(z, r_{0}\right)$, and we have

$$
\begin{equation*}
\int_{I}\left|\gamma_{2}^{\prime}(t)\right| d t \geq r_{0} \tag{7.5}
\end{equation*}
$$

On the other hand by (7.3), (2.2)

$$
\begin{align*}
\int_{I}\left|\gamma_{2}^{\prime}(t)\right| d t & \leq\left(\int_{I} \sqrt{\gamma_{1}^{\prime 2}(t)+\gamma_{2}^{\prime}(t)^{2}} d t\right)^{\frac{1}{2}}\left(\int_{I} \frac{\left|\gamma_{2}^{\prime}(t)\right|^{2}}{\sqrt{\gamma_{1}^{\prime 2}(t)+\gamma_{2}^{\prime}(t)^{2}}} d t\right)^{\frac{1}{2}} \\
& \leq \mathcal{H}^{1}(\gamma(I))^{\frac{1}{2}}\left(\int_{\gamma(I)} \sin (\alpha(y))^{2} \mathrm{~d} \mathcal{H}^{1}(y)\right)^{\frac{1}{2}} \\
& \leq r_{0} \sqrt{\frac{401}{400} \cdot \frac{8}{10}} \\
& \leq \frac{9}{10} r_{0} \tag{7.6}
\end{align*}
$$

which gives a contradiction with (7.5). Therefore, one can define the application $f: p_{1}(F) \rightarrow \mathbb{R}$ such that $(t, f(t)) \in F$ for all $t \in p_{1}(F)$.

Further, using a similar argument as before we claim that for all $t$ and $t^{\prime}$ in $p_{1}(F)$ we have that

$$
\begin{equation*}
\left|f(t)-f\left(t^{\prime}\right)\right| \leq 5\left|t-t^{\prime}\right| \tag{7.7}
\end{equation*}
$$

Indeed assume by contradiction that (7.7) is not true, thus there is $t$ and $t^{\prime}$ such that $\left|f(t)-f\left(t^{\prime}\right)\right|>$ $\left|t-t^{\prime}\right|$. It is enough to consider the case when $t, t^{\prime} \leq 0$ or $t, t^{\prime} \geq 0$ (the general case follows from taking 0 as an intermediate point between $t$ and $\left.t^{\prime}\right)$. We denote $z:=(t, f(t)), z^{\prime}:=\left(t^{\prime}, f\left(t^{\prime}\right)\right)$, and $r_{1}:=\left|z-z^{\prime}\right| \geq \sqrt{6}\left|t-t^{\prime}\right|$. As before, let $J \subset[0, T]$ be such that $\gamma(J)$ is the arc that goes from $z$ to $z^{\prime}$. We know that $\gamma(J) \cap \partial B\left(z, r_{1}\right)=z^{\prime}$, in particular $\gamma(J)$ is contained in $B\left(z, r_{1}\right) \subset B(x, 3 r / 4)$, and we have

$$
\begin{equation*}
\int_{J}\left|\gamma_{2}^{\prime}(t)\right| d t \geq \sqrt{r_{1}^{2}-\left|t-t^{\prime}\right|^{2}} \geq \sqrt{\frac{5}{6}} r_{1}>\frac{9}{10} r_{1} \tag{7.8}
\end{equation*}
$$

On the other hand arguing as for (7.6),

$$
\begin{equation*}
\int_{J}\left|\gamma_{2}^{\prime}(t)\right| d t \leq \frac{9}{10} r_{1} \tag{7.9}
\end{equation*}
$$

which gives a contradiction with (7.8) so (7.7) is proved.
Therefore, by a standard extension argument one can find a 5-Lipschitz function $\tilde{f}$ on $\mathbb{R}$ that is equal to $f$ on $p_{1}(F)$, that satisfies (7.1) and that we will still denote by $f$ instead of $\tilde{f}$.

It remains to prove (7.2). Observe that by our assumptions since $x=0, d_{H}(\gamma([-T, T] \cap$ $B(x, r), T \cap B(x, r)) \leq r / 400$, using Proposition 40 and the fact that $\Sigma \cap B(x, r / 4)$ is connected we also have that

$$
p_{1}(\Sigma \cap B(x, r / 4)) \supseteq\left[-\frac{r}{16}, \frac{r}{16}\right] .
$$

On the other hand since

$$
d_{H}(\Sigma \cap B(x, r), L \cap B(x, r)) \leq \operatorname{Cr} \psi(B(x, r) \backslash\{x\}),
$$

we deduce that

$$
\begin{equation*}
\alpha\left(\pi_{x}, \pi_{x, r}\right) \leq C \psi(B(x, r) \backslash\{x\}) \tag{7.10}
\end{equation*}
$$

Now since $f$ is 5 -Lipschitz, applying Proposition 39 with $\tau=\frac{1}{4}$, using (2.6) and (7.10) we get

$$
\begin{aligned}
\int_{\left[-\frac{r}{16}, \frac{r}{16}\right]} f^{\prime}(t)^{2} d t & \leq \sqrt{6} \int_{\left[-\frac{r}{16}, \frac{r}{16}\right]} \frac{f^{\prime}(t)^{2}}{\sqrt{1+f^{\prime}(t)^{2}}} d t \\
& \leq \sqrt{6} \int_{F \cap B\left(x, \frac{1}{4} r\right)} \sin ^{2}(\alpha(y)) \mathrm{d} \mathcal{H}^{1}(y) \\
& \leq \operatorname{Cr} \psi(x, r)^{2}
\end{aligned}
$$

thus (7.2) holds and the proposition is proved.

### 7.3 The equation of curvature

To complete the proof of Theorem 3 we will give some further remarks about the first order equations applied to $f$.

Given $\eta$, let us take $\Phi(x, y):=(0, \eta(x) \chi(y))$ with $\chi \in C_{0}^{1}([-\delta, \delta]), \chi=1$ on $\left(-\frac{\delta}{2}, \frac{\delta}{2}\right)$ and $\delta>0$ is chosen in such a way that $\operatorname{supp}(\Phi) \subset \operatorname{supp}(\eta) \times(-\delta, \delta) \subset B\left(x_{0}, r_{0}\right)$. By applying Proposition 35 with this choice of diffeomorphism $\Phi$ we obtain that

$$
\begin{equation*}
\int_{\Omega} \operatorname{div}^{\Sigma} \Phi \mathrm{d} \mathcal{H}^{1}=\frac{1}{\lambda_{0}} \int_{\mathbb{R}^{2}}\left\langle\Phi(k(y)), \frac{y-k(y)}{|y-k(y)|}\right\rangle \mathrm{d} \mu(y) \tag{7.11}
\end{equation*}
$$

Now for $\mathcal{H}^{1}$ a.e. $x \in \Sigma \cap \Gamma$, a direct computation gives

$$
\operatorname{div}^{\Sigma} \Phi(z)=\frac{\eta^{\prime}(z) f^{\prime}(z)}{1+\left|f^{\prime}(z)\right|^{2}}
$$

thus by the area formula we obtain

$$
\begin{equation*}
\int_{I} \frac{\eta^{\prime}(z) f_{n}^{\prime}(z)}{\sqrt{1+\left|f_{n}^{\prime}(z)\right|^{2}}} \mathrm{~d} \mathcal{H}^{1}=\frac{1}{\lambda_{0}} \int_{\mathbb{R}^{2}} \eta(\pi(k(y)))\left\langle e_{2}, \frac{y-k(y)}{|y-k(y)|}\right\rangle \mathrm{d} \mu(y) \tag{7.12}
\end{equation*}
$$

An immediate consequence of the above equation is that the derivative of $t \mapsto \frac{f^{\prime}(t)}{\sqrt{1+\left|f^{\prime}(t)\right|^{2}}}$ in the distributional sense is a measure. Indeed, we can also write this equation in a more natural form using disintegration. Consider the linear form $T$ that associate for every $\eta \in C_{c}(I)$ the quantity

$$
T(\eta):=\int_{\mathbb{R}^{2}} \eta(\pi(k(y)))\left\langle e_{2}, \frac{y-k(y)}{|y-k(y)|}\right\rangle \mathrm{d} \mu(y)
$$

Since $|T(\eta)| \leq C\|\eta\|_{\infty}$ by the Riesz theorem one can find a measure $\psi_{0}$ on $I$ such that $T(\eta)=$ $\int_{I} \eta(t) \mathrm{d} \psi_{0}(t)$. Then (7.12) becomes

$$
-\frac{d}{d t}\left(\frac{f^{\prime}(t)}{\sqrt{1+\left|f^{\prime}(t)\right|^{2}}}\right)=\psi_{0}
$$

Furthermore it is interesting to $\operatorname{link} \psi_{0}$ with $\psi$. Actually, we easily have that

$$
\left|\psi_{0}\right| \leq \pi \sharp \psi .
$$

In particular, $\frac{f^{\prime}(t)}{\sqrt{1+\left|f^{\prime}(t)\right|^{2}}} \in B V(I)$ and the jump set is concentrated on corner points so that we have

$$
-\frac{d}{d t}\left(\frac{f^{\prime}(t)}{\sqrt{1+\left|f^{\prime}(t)\right|^{2}}}\right)=H(t) d t+\sum_{(t, f(t)) \in \text { Corner }} c_{t} \delta_{t}+H^{\text {Cant }}
$$

where $H^{\text {Cant }}$ is the cantor part, $\|H(t)\|_{L^{1}(I)} \leq \psi(B(x, r))$ and $\left|c_{t}\right| \leq \psi(\{(t, f(t))\})$ for any atom $(t, f(t))$ of $\psi$.

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